EVALUATING THE TAIL RISK OF MULTIVARIATE AGGREGATE LOSSES

BY

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ABSTRACT

In this paper, we study the tail risk measures for several commonly used multivariate aggregate loss models where the claim frequencies are dependent but the claim sizes are mutually independent and independent of the claim frequencies. We first develop formulas for the moment (or size biased) transforms of the multivariate aggregate losses, showing their relationship with the moment transforms of the claim frequencies and claim sizes. Then, we apply the formulas to compute some popular risk measures such as the tail conditional expectation and tail variance of the multivariate aggregated losses and to perform capital allocation analysis.

KEYWORDS

Compound distribution, dependence modeling, moment transform, risk measures, capital allocation, weighted distributions.

1. INTRODUCTION

Insurance companies typically operate in multiple lines of business and face different types of risks. It is important for them to evaluate the joint distribution of these different losses. Quite commonly, each type of these losses could be described by an aggregated loss model, which usually comprises two important components – loss frequency and loss size. Then, the joint distribution is a function of the interplay between the frequencies and sizes of different types of losses and the dependence among them (Wang, 1998).

In the literature, there are several types of multivariate aggregate loss models. In one type, claim frequencies are dependent but claim sizes are independent. See for example, Hesselager (1996), Cossette et al. (2012), Kim et al. (2019) and references therein. In another type, the claim frequency is one-dimensional, while each claim may cause multiple types of possibly dependent
losses. See for example Sundt (1999). Recently, models that allow dependence between claim frequencies and claim sizes have been developed. For example, in generalized linear model-based insurance pricing models such as Gschlößl and Czado (2007) and Garrido et al. (2016), the regression of claim size includes claim count as a covariate. Alternatively, the expected values of claim frequency and claim size may depend on the same latent variables, as in Oh et al. (2020).

Computing the risk measures for compound random variables, even for univariate cases, is not trivial, because the explicit formulas for the distribution functions usually do not exist. Listed below are some of the recent advances in the actuarial literature. Cossette et al. (2012) derived the capital allocation formulas for multivariate compound distributions under the Tail-Value-at-Risk measure, where the claim frequencies are dependent, the claim sizes are of the mixture Erlang type and mutually independent, and the claim frequency and size are independent. Kim et al. (2019) derived a recursive algorithm to compute the risk measures of multivariate compound Poisson models, where the Poisson-type claim frequencies depend on the same latent variables in a linear fashion. Denuit (2020) derived formulas for the tail conditional expectations (TCE) of some univariate compound distributions. Denuit and Robert (2021) presented some results for the TCE of a compound mixed Poisson model, where both the claim frequencies and sizes depend on several latent variables. Ren (2021) derived the formulas for the TCE and tail variance (TV) of multivariate compound models based on Sundt (1999), where claim frequency is one-dimensional and one claim can yield multiple dependent losses.

The main goal of this paper is to present some easy-to-use formulas for computing the TCE and TV of some multivariate compound loss models, where the claim frequencies are dependent while the sizes are independent. Particularly, we study in detail the important dependence models in Hesselager (1996) and their extensions, which are widely used in the risk theory literature. See, for example, Cummins and Wiltbank (1983), Bermúdez (2009), Cossette et al. (2012) and the references therein. We also discuss a case where the claim frequencies and sizes are dependent through a common mixing variable, following Denuit and Robert (2021).

Methodologically, we apply the moment transform (which is also named as the size-biased transform) technique to our problems. The concept of moment transforms has a long history and is widely used in statistics (see, e.g., Patil and Ord 1976; Arratia and Goldstein 2010, and the references therein). Its relevance to the study of actuarial risk measures has been exploited in the risk theory literature. For example, Furman and Landsman (2005) applied the moment transform technique in computing the TCE of a portfolio of independent risks. Furman and Zitikis (2008) used it in determining TV and many other weighted risk measures. More recently, Denuit (2020) applied this method in analyzing the TCE of univariate compound distributions. The concept of multivariate moment transform was studied in Denuit and Robert
(2021) and applied in analyzing multivariate risks. Ren (2021) applied this technique to study the tail risk of a multivariate compound sum introduced by Sundt (1999), where the claim frequency is one-dimensional while each claim is a multidimensional random vector with dependent components.

The main contributions of this paper are summarized as follows. We first establish the relationship between the moment transform of a multivariate compound loss with those of its claim frequencies and sizes. It is shown that in many cases, the moment-transformed compound distribution can be represented by the convolution of a compound distribution, which is a mixture of some compound distributions that are in the same family of the original one, and the distribution of the moment transformed claim size. Such a representation allows us to evaluate the moment transform of a multivariate compound distribution efficiently by using either the fast Fourier transform (FFT) or recursive method, which are readily available in the literature (e.g., Hesselager 1996). After deriving the moment transforms of multivariate compound distributions, we use them to evaluate the tail risks of multivariate aggregated losses and perform the associated capital allocation. Our main result also shows the effect of the distributions of claim frequencies and sizes on the tail risks of such aggregated losses. Our results generalize those in Denuit (2020) and Kim et al. (2019).

The remaining parts of the paper are organized as follows. Section 2 provides definitions and some preliminary results. Section 3 presents the main result for the moment transform of a general multivariate compound model with dependent claim frequencies and independent claim sizes. Section 4 studies the moment transform of the claim frequency in great detail. The case where claim frequencies and sizes are dependent is also studied. Section 5 provides numerical examples showing the risk capital allocation computation for each of the studied models.

2. Preliminaries and Definitions

Suppose that an insurance company underwrites a portfolio of $K$ types of risks. Let $\mathcal{K} = \{1, \cdots, K\}$ and for $k \in \mathcal{K}$, let $N_k$ denote the number of type $k$ claims. Let $\mathbf{N} = (N_1, \cdots, N_K)$, whose joint probability function is denoted by $p_N(n) = \Pr[(N_1, \cdots, N_K) = (n_1, \cdots, n_K)]$.

For $k \in \mathcal{K}$, let

$$S_{N_k} = \sum_{i=1}^{N_k} X_{k,i},$$

where $X_{k,i}$, $i = 1, 2, \cdots, N_k$, are i.i.d. random variables representing the size of a type $k$ claim. They are assumed to have cumulative distribution function $F_{X_k}$. Loss size variables of different types are mutually independent and independent of $\mathbf{N}$.

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Let
\[ SN = (S_{N_1}, \cdots, S_{N_K}) \]  
(2.1)
denote the multivariate aggregate loss and
\[ S_\bullet = \sum_{k=1}^{K} S_{N_k} \]
denote the total amount of all \( K \) types of claims.

In this paper, we study the following risk measures of \( S_N \):

- The multivariate tail expectation (MTCE) of \( S_N \) at some level \( s_q \), which is defined by (see Landsman et al., 2018)
  \[ \text{MTCE}_{S_N}(s_q) = \mathbb{E}[S_N | S_N > s_q], \]  
  (2.2)
where \( s_q = (s_{q_1}, \cdots, s_{q_K}) \) and the expectation operation is taken to be element-wise.
- The multivariate tail covariance (MTCOV) of \( S_N \) at some level \( s_q \), which is defined by
  \[ \text{MTCOV}_{S_N}(s_q) = \mathbb{E}[(S_N - \text{MTCE}_{S_N}(s_q))(S_N - \text{MTCE}_{S_N}(s_q))^\top | S_N > s_q]. \]  
  (2.3)

MTCE and MTCOV are multivariate extensions of univariate risk measures TCE and TV. They provide important information of the expected values and the variance—covariance dependence structure of the tail of a vector of dependent variables. Their properties are studied in Landsman et al. (2018).

To manage their insolvency risks, insurance companies are required to hold certain amount of capital, which is available to pay the claims arising from the adverse development of one or several types of risks. In order to measure and compare the different types of risks, it is important to determine how much capital should be assigned to each of them. Therefore, a capital allocation methodology is needed (Cummins, 2000). Methods for determining capital requirement and allocation have been studied extensively in the insurance/actuarial science literature. For more detailed discussions of such methods, one could refer to, for example, Cummins (2000), Dhaene et al. (2008), Furman and Landsman (2008) and references therein. Since this paper focuses on tail risk measures such as TCE and TV, we apply the TCE- and TV-based capital allocation methods, which are described briefly in the following.

According to the TCE-based capital allocation rule, the capital required for the type \( k \) risk is given by
\[ \text{TCE}_{S_{N_k} | S_\bullet}(s_q) = \mathbb{E}[S_{N_k} | S_\bullet > s_q], \quad k \in K. \]  
(2.4)
It is straightforward that

\[
\sum_{k=1}^{K} \text{TCE}_{S_{N_k}}(s_q) = \mathbb{E}[S_\bullet | S_\bullet > s_q] = \text{TCE}_{S_\bullet}(s_q),
\]

where \(\text{TCE}_{S_\bullet}(s_q)\) is a commonly used criterion for determining the total capital requirement.

Likewise, according to the TV-based capital allocation rule, the capital required for the type \(k \in \mathcal{K}\) risk is given by

\[
\text{TV}_{S_{N_k}}(s_q) = \text{Cov}[(S_{N_k}, S_\bullet) | S_\bullet > s_q],
\]

which satisfies

\[
\sum_{k=1}^{K} \text{TV}_{S_{N_k}}(s_q) = \text{Var}[S_\bullet | S_\bullet > s_q] = \text{TV}_{S_\bullet}(s_q),
\]

where \(\text{TV}_{S_\bullet}(s_q)\) is another commonly used criterion for determining total capital requirement. It is worth pointing out that \(\text{TV}_{S_{N_k}}(s_q)\) can be computed through the quantities

\[
\text{Cov}[(S_{N_{k_1}}, S_{N_{k_2}}) | S_\bullet > s_q], \quad k_1, k_2 \in \mathcal{K},
\]

for which we will provide formulas in this paper.

Sometimes, the total capital is set exogenously by regulators or internal managers and may not necessarily be the TCE/TV of the sum \(S_\bullet\). The TCE/TV allocation rule can still be applied if tail risk is of the main concern. For example, with TCE allocation rule, the proportion of the total capital allocated to the type \(k\) risk can be determined by

\[
\frac{\mathbb{E}[S_{N_k} | S_\bullet > s_q]}{\mathbb{E}[S_\bullet | S_\bullet > s_q]}.
\]

This ratio is computed in Section 5 for the specific models studied in this paper.

In the following sections, we develop methods to compute the MTCE and MTCOV of \(S_N\), and the associated quantities for capital allocation. We do this by utilizing the moment transform of the random vector \(S_N\). For this purpose, we next introduce some definitions and preliminary results for moment transforms (see also Patil and Ord, 1976).

**Definition 2.1.** Let \(X\) be a non-negative random variable with distribution function \(F_X\) and moment \(\mathbb{E}[X^\alpha] < \infty\) for some positive integer \(\alpha\). A random variable \(\tilde{X}^{[\alpha]}\) is said to be a copy of the \(\alpha\)th moment transform of \(X\) if its cumulative distribution function (c.d.f.) is given by

\[
F_{\tilde{X}^{[\alpha]}}(x) = \frac{\mathbb{E}[X^\alpha \mathbb{I}(X \leq x)]}{\mathbb{E}[X^\alpha]}
\]

(2.7)
The first moment transform of $X$ is simply denoted as $\tilde{X}$.

**Definition 2.2.** Let $X = (X_1, \ldots, X_K)$ be a random vector with distribution function $F_X$ and moments $\mathbb{E}[X_k^\alpha] < \infty$ and $\mathbb{E}[X_{k_1}^{\alpha_1} X_{k_2}^{\alpha_2}] < \infty$ for some $k, k_1, k_2 \in \{1, \ldots, K\}$ and positive integers $\alpha, \alpha_1$ and $\alpha_2$.

The $k$th component $\alpha$th moment transform of $X$ is any random vector $\hat{X}_{[k, \alpha]}$ with c.d.f.

$$F_{\hat{X}_{[k, \alpha]}(x)} = \frac{\mathbb{E}[X_k^\alpha I(X \leq x)]}{\mathbb{E}[X_k^\alpha]},$$

(2.8)

where $x = (x_1, \ldots, x_K)$. The $k$th component first moment transform of $X$ is denoted as $\hat{X}_{[k]}$.

The $(k_1, k_2)$th component $(\alpha_1, \alpha_2)$th moment transform of $X$ is any random vector $\hat{X}_{[k_1, \alpha_1], [k_2, \alpha_2]}$ with c.d.f.

$$F_{\hat{X}_{[k_1, \alpha_1], [k_2, \alpha_2]}(x)} = \frac{\mathbb{E}[X_{k_1}^{\alpha_1} X_{k_2}^{\alpha_2} I(X \leq x)]}{\mathbb{E}[X_{k_1}^{\alpha_1} X_{k_2}^{\alpha_2}]}.$$

(2.9)

The $(k_1, k_2)$th component, $(1,1)$th moment transform of $X$ is denoted as $\hat{X}_{[k_1, k_2]}$.

**Remark 2.1.** We have used the symbol $\tilde{X}$ to denote the moment transform of a univariate variable $X$ and $\check{X}$ for the moment transform of a multivariate variable $X$. In the sequel, we denote $\check{X}_{[k, \alpha]} = (\check{X}_1_{[k, \alpha]}, \ldots, \check{X}_K_{[k, \alpha]})$. In particular, $\check{X}_i$ denotes the $i$th element of $\check{X}_{[k]}$, which is the $k$th component first moment transform of the random vector $X$. It is not to be confused with $\tilde{X}_i_{[\alpha]}$, which stands for the $\alpha$th moment transform of a univariate random variable $X_i$. The same convention applies to other components or moment transforms.

For discrete distributions, we work with factorial moment transform (Patil and Ord, 1976). To this end, for some integers $I$ and $\alpha$, we define

$$I^{(\alpha)} = \begin{cases} I(I - 1) \cdots (I - \alpha + 1), & \text{if } \alpha \leq I, \\ 0, & \text{other cases.} \end{cases}$$

**Definition 2.3.** Let $N$ be a discrete random variable having probability mass function $p_N(n)$ for $n \geq 0$. A random variable $\check{N}_{[\alpha]}$ is said to be a copy of the $\alpha$th
factorial moment transform of \( N \) if its probability mass function is given by

\[
p_{\tilde{\mathcal{N}}[\alpha]}(n) = \frac{\mathbb{E}[N([\alpha])I(N = n)]}{\mathbb{E}[N([\alpha])]} = \frac{n^{(\alpha)}p_N(n)}{\mathbb{E}[N([\alpha])]}, \quad n \geq 0. \tag{2.10}
\]

In the sequel, we denote the first factorial moment transform of \( N \) by \( \tilde{\mathcal{N}} \).

**Definition 2.4.** Let \( N = (N_1, \cdots, N_K) \) be a vector of discrete random variables having probability mass function \( p_{N}(n) \). A random vector \( \hat{\mathcal{N}}[k[[\alpha]]] \) is said to be a copy of the \( k \)th component \( \alpha \)th factorial moment transform of \( N \) if its probability mass function is given by

\[
p_{\hat{\mathcal{N}}[k[[\alpha]]]}(n) = \frac{\mathbb{E}[N_k([\alpha])I(N = n)]}{\mathbb{E}[N_k([\alpha])]} = \frac{n^{(\alpha)}p_N(n)}{\mathbb{E}[N_k([\alpha])]}, \quad n \geq 0. \tag{2.11}
\]

The \( k \)th component first moment transform of \( N \) is denoted as \( \hat{\mathcal{N}}[k] \).

A random vector \( \hat{\mathcal{N}}[[\alpha_1]][k_2] \) is said to be a copy of the \( (k_1, k_2) \)th component \( (\alpha_1, \alpha_2) \)th order factorial moment transform of \( N \) if its probability mass function is given by

\[
p_{\hat{\mathcal{N}}[[\alpha_1]][k_2]}(n) = \frac{\mathbb{E}[N_{k_1}([\alpha_1])N_{k_2}([\alpha_2])I(N = n)]}{\mathbb{E}[N_{k_1}([\alpha_1])N_{k_2}([\alpha_2])]} = \frac{n^{(\alpha_1)}n^{(\alpha_2)}p_N(n)}{\mathbb{E}[N_{k_1}([\alpha_1])N_{k_2}([\alpha_2])]}, \quad n \geq 0. \tag{2.12}
\]

The reason why we work with the factorial moment transforms for the discrete distributions is that they have simple representations in many cases. See, for example, Table 2 of Patil and Ord (1976).

The relationship between risk measures such as TCE and TV and the moment transform of random variables has been studied extensively in the literature. In particular, the relationship

\[
\mathbb{E}[X^\alpha|X > x] = \mathbb{E}[X^\alpha] \frac{\Pr(X^\alpha > x)}{\Pr(X > x)} \tag{2.13}
\]

has been introduced and utilized in, for example, Furman and Landsman (2005), Furman and Zitikis (2008), Denuit (2020), and the references therein.

In the multivariate case, the MTCE and MTCOV of a random vector \( X = (X_1, \cdots, X_K) \) are related to its multivariate moment transform. We state the results in the following.

**Lemma 2.1.** Let \( \mathcal{K} = \{1, 2, \cdots, K\} \), \( X = (X_1, \cdots, X_K) \) and \( X_* = \sum_{i=1}^{K} X_i \), we have

(i) For \( k \in \mathcal{K} \) and \( \alpha \geq 1 \),

\[
\mathbb{E}[X_k^\alpha|X > x] = \mathbb{E}[X_k^\alpha] \frac{\Pr(X^\alpha > x)}{\Pr(X > x)}. \tag{2.14}
\]
(ii) For \( k_1, k_2 \in \mathcal{K} \) and \( \alpha_1, \alpha_2 \geq 1 \),

\[
\mathbb{E}[X_{k_1}^{\alpha_1} X_{k_2}^{\alpha_2} | X > x] = \frac{\mathbb{E}[X_{k_1}^{\alpha_1} X_{k_2}^{\alpha_2}]}{\Pr (X > x)}.
\]

(2.15)

(iii) For \( k_1, k_2 \in \mathcal{K} \) and \( \alpha_1, \alpha_2 \geq 1 \),

\[
\mathbb{E}[X_{k_1}^{\alpha_1} X_{k_2}^{\alpha_2} | X_\bullet > x] = \frac{\mathbb{E}[X_{k_1}^{\alpha_1} X_{k_2}^{\alpha_2}]}{\Pr (X_\bullet > x)},
\]

where

\[
\hat{X}_{k_1}^{[\alpha_1]},_{k_2}^{[\alpha_2]} = \sum_{k=1}^{K} \hat{X}_{k}^{[\alpha_1]},_{k}^{[\alpha_2]}
\]

and \( \hat{X}_{k}^{[\alpha_1]},_{k}^{[\alpha_2]} \) is the kth element of \( \hat{X}_{k_1}^{[\alpha_1]},_{k_2}^{[\alpha_2]} \).

**Proof.** Statements (i) and (ii) are the direct results of Definition 2.2 of moment transforms. Statement (iii) is similar to Proposition 3.1 of Denuit and Robert (2021), to which we refer the readers for more details. \( \square \)

With Lemma 2.1, we are ready to study the tail risk measures of the compound sum vector \( S_N \) through its moment transforms.

### 3. Evaluation of the Tail Risk Measures of Multivariate Compound Variables via Moment Transforms

In this section, we derive the explicit formulas for moment transforms of the compound sum vector \( S_N \). These formulas not only unveil the relationships between the moment transforms of \( S_N \) and those of \( N \) and \( X_k \) (for some \( k \in \mathcal{K} \)) but also provide a method to compute the MTCE and MTCOV of \( S_N \) and to perform capital allocations (Equations (2.2)–(2.6)).

We first assume that \( N \) is a non-random vector, that is \( N = n = (n_1, \cdots, n_K) \). For \( k \in \mathcal{K} \), let

\[
S_{k,n_k} = \sum_{i=1}^{n_k} X_{k,i}
\]

and

\[
S_n = (S_{1,n_1}, S_{2,n_2}, \cdots, S_{K,n_K}).
\]

Then by the results in Furman and Landsman (2005) or Lemmas 2.1 and 2.2 of Ren (2021), for a positive integer \( \alpha \) such that \( \mathbb{E}[X_k^\alpha] < \infty \), we have for
\(i \in \{1, \ldots, n_k\}\) that

\[
\mathbb{E}[X_{k,i}^\alpha \mathbb{I}(S_k, n_k \leq s_k)] = \mathbb{E}[X_{k,i}^\alpha] \Pr \left( X_{k,1}^\alpha + \sum_{j=1}^{n_k} X_{k,j} \leq s_k \right),
\]

(3.1)

where all the variables in the parenthesis are mutually independent. Because \(X_{k,i}\)'s are assumed to be i.i.d., we have

\[
\mathbb{E}[S_k, n_k \mathbb{I}(S_k, n_k \leq s_k)] = n_k \mathbb{E}[X_{k,1}] \Pr \left( X_{k,1}^\alpha + \sum_{j=2}^{n_k} X_{k,j} \leq s_k \right),
\]

(3.2)

and

\[
\mathbb{E}[S_k, n_k^2 \mathbb{I}(S_k, n_k \leq s_k)] = n_k(n_k - 1)(\mathbb{E}[X_{k,1}])^2 
\Pr(S_k, n_k - X_{k,1} + X_{k,2} \leq s_k) 
+ n_k \mathbb{E}[X_{k,1}^2] \Pr(S_k, n_k - X_{k,1} + X_{k,2}^2 \leq s_k),
\]

(3.3)

where all the variables in the parenthesis are mutually independent.

Since \(\{S_k, n_k\}_{k=1, \ldots, K}\) are mutually independent, we have

\[
\mathbb{E}[S_k, n_k \mathbb{I}(S_n \leq s)] = \mathbb{E}[S_k, n_k \mathbb{I}(S_k, n_k \leq s_k)] \prod_{\xi \in K^c \setminus \{k\}} \Pr(S_{\xi, n_{\xi}} \leq s_{\xi}) 
= n_k \mathbb{E}[X_{k,1}] \Pr \left( X_{k,1}^\alpha + \sum_{j=2}^{n_k} X_{k,j} \leq s_k \right) \prod_{\xi \in K^c \setminus \{k\}} \Pr(S_{\xi, n_{\xi}} \leq s_{\xi}),
\]

(3.4)

and

\[
\mathbb{E}[S_k, n_k^2 \mathbb{I}(S_n \leq s)] = \mathbb{E}[S_k, n_k^2 \mathbb{I}(S_k, n_k \leq s_k)] \prod_{\xi \in K^c \setminus \{k\}} \Pr(S_{\xi, n_{\xi}} \leq s_{\xi}),
\]

(3.5)

where the first term on the right side is given in (3.3).

Further, for \(k_i, k_j \in K\),

\[
\mathbb{E}[S_{k_i, n_{k_i}} S_{k_j, n_{k_j}} \mathbb{I}(S_n \leq s)] 
= \mathbb{E}[S_{k_i, n_{k_i}} \mathbb{I}(S_{k_i, n_{k_i}} \leq s_{k_i})] \mathbb{E}[S_{k_j, n_{k_j}} \mathbb{I}(S_{k_j, n_{k_j}} \leq s_{k_j})] \prod_{\xi \in K^c \setminus \{k_i, k_j\}} \Pr(S_{\xi, n_{\xi}} \leq s_{\xi})
\]

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\[ = n_k n_j \mathbb{E}[X_{ki,1}] \mathbb{E}[X_{kj,1}] \prod_{\xi \in \{ki, kj\}} \Pr \left( \bar{X}_{\xi,1} + \sum_{j=2}^{n_\xi} X_{\xi,j} \leq s_\xi \right) \prod_{\xi \in \mathcal{K} - \{ki, kj\}} \Pr [S_\xi n_\xi \leq s_\xi] , \]

(3.6)

where all the variables in the parenthesis are mutually independent.

Now we are ready to present the results for the moment transforms of the compound sum vector \( \mathbf{SN} \).

**Theorem 3.1.** For \( k \in \mathcal{K} \), let \( \mathbf{1}^{[k]} \) denote a \( K \) dimensional vector with \( k \)th element being one and all others are zero. Let

\[ \mathbf{L}^{[k]} = \hat{\mathbf{N}}^{[k]} - \mathbf{1}^{[k]}, \]

whose \( i \)th element is denoted by \( L_i^{[k]} \) and

\[ \mathbf{S}_{\mathbf{L}^{[k]}} = \left( \sum_{j=1}^{L_i^{[k]}} X_{i,j}, i \in \mathcal{K} \right), \]

then

\[ \hat{\mathbf{S}}_{\mathbf{N}}^{[k]} \overset{d}{=} \mathbf{S}_{\mathbf{L}^{[k]}} + \bar{X}_{k,1} \times \mathbf{1}^{[k]} . \]

(3.7)

Further, let

\[ \mathbf{L}^{[k(2)]} = \hat{\mathbf{N}}^{[k(2)]} - 2 \times \mathbf{1}^{[k]}, \]

(3.8)

then

\[ \Pr (\hat{\mathbf{S}}_{\mathbf{N}}^{[k(2)]} \leq s) = \frac{\mathbb{E} [N_k^{(2)}] (\mathbb{E} [X_k])^2}{\mathbb{E} [S_{N_k}^2]} \Pr \left( \mathbf{S}_{\mathbf{L}^{[k(2)]}} + (\bar{X}_{k,1} + \bar{X}_{k,2}) \times \mathbf{1}^{[k]} \leq s \right) + \frac{\mathbb{E} [N_k] (\mathbb{E} [X_k^2])}{\mathbb{E} [S_{N_k}^2]} \Pr \left( \mathbf{S}_{\mathbf{L}^{[k]}} + \bar{X}_{k,1}^{[2]} \times \mathbf{1}^{[k]} \leq s \right) , \]

(3.9)

where \( \bar{X}_{k,1} \) and \( \bar{X}_{k,2} \) are two independent copies of the first moment transform of \( X_k \) and \( \bar{X}_{k,1}^{[2]} \) is a copy of the second moment transform of \( X_k \). All random variables in the above are mutually independent.

In addition, for \( k_1 \neq k_2 \in \mathcal{K} \) let

\[ \mathbf{L}^{[k_1, k_2]} = \hat{\mathbf{N}}^{[k_1, k_2]} - \mathbf{1}^{[k_1]} - \mathbf{1}^{[k_2]} , \]

(3.10)

then

\[ \hat{\mathbf{S}}_{\mathbf{N}}^{[k_1, k_2]} \overset{d}{=} \mathbf{S}_{\mathbf{L}^{[k_1, k_2]}} + \bar{X}_{k_1,1} \times \mathbf{1}^{[k_1]} + \bar{X}_{k_2,1} \times \mathbf{1}^{[k_2]} . \]

(3.11)
Proof. The proof of the above three statements is similar. We next prove statement (3.9).

Firstly, by the law of total probability,

\[
\mathbb{E}[S_{N_k}^2 \mathbb{I}(S_N \leq s)] = \sum_{n \in (\mathbb{Z}^+)^K} p_N(n) \mathbb{E}[S_{k,n_k}^2 \mathbb{I}(S_N \leq s)],
\]

which after applying (3.5) becomes

\[
\mathbb{E}[S_{N_k}^2 \mathbb{I}(S_N \leq s)] = \sum_{n \in (\mathbb{Z}^+)^K} p_N(n) \left( n_k(n_k - 1)(\mathbb{E}[X_{k,1}])^2 \Pr \left( \widetilde{X}_{k,1} + \widetilde{X}_{k,2} + \sum_{j=3}^{n_k} X_{k,j} \leq s_k, \sum_{j=1}^{n_m} X_{m,j} \leq s_m, m \in \mathcal{K} - \{k\} \right) \right)
\]

\[
+ n_k \mathbb{E}[X_{k,1}^2] \Pr \left( \sum_{j=2}^{n_k} X_{k,j} \leq s_k, \sum_{j=1}^{n_m} X_{m,j} \leq s_m, m \in \mathcal{K} - \{k\} \right) \mathbb{E}[N_k^2](\mathbb{E}[X_{k,1}])^2 \Pr \left( \widetilde{X}_{k,1} + \sum_{j=1}^{N_k^2} X_{k,j} \leq s_k, \sum_{j=1}^{N_m^2} X_{m,j} \leq s_m, m \in \mathcal{K} - \{k\} \right) \right)
\]

Dividing both sides of the above by \(\mathbb{E}[S_{N_k}^2]\) and making use the definitions of \(L^{[k]}\) and \(L^{[k,2]}\) leads to (3.9).

Similarly, applying the law of total probability to Equations (3.4) and (3.6) respectively yields

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\[ \mathbb{E}[S_{N_k} \mathbb{I}(SN \leq s)] = \mathbb{E}[N_k] \mathbb{E}[X_k] \text{Pr} \left( \tilde{X}_{k,1} + \sum_{j=1}^{\tilde{N}_k^{[k]} - 1} X_{k,j} \right. \\
\left. \leq s_k , \sum_{j=1}^{\tilde{N}_m^{[k]}} X_{m,j} \leq s_m, m \in \mathcal{K} - \{k\} \right) , \]

(3.12)

and

\[ \mathbb{E}[S_{N_{k_1}} S_{N_{k_2}} \mathbb{I}(SN \leq s)] = \mathbb{E}[N_{k_1} N_{k_2}] \mathbb{E}[X_{k_1}] \mathbb{E}[X_{k_2}] \times \text{Pr} \left( \tilde{X}_{k_1,1} + \sum_{j=1}^{\tilde{N}_{k_1}^{[k_1,k_2]} - 1} X_{k_1,j} \leq s_{k_1}, \tilde{X}_{k_2,1} + \sum_{j=1}^{\tilde{N}_{k_2}^{[k_1,k_2]} - 1} X_{k_2,j} \right. \\
\left. \leq s_{k_2} , \sum_{j=1}^{\tilde{N}_m^{[k_1,k_2]}} X_{m,j} \leq s_m, m \in \mathcal{K} - \{k_1, k_2\} \right) , \]

(3.13)

which leads to statements (3.7) and (3.11), respectively.

\[ \square \]

**Remark 3.1.** Theorem 3.1 generalizes Proposition 1 in Denuit (2020) and Theorem 2 of Ren (2021), which gave formulas for the moment transforms of univariate compound distributions. In particular, with \( K = 1 \) and denoting \( S_N = \sum_{i=1}^N X_i \), Equation (3.9) becomes

\[ \text{Pr} (\tilde{S}_N^{[2]} \leq s) = \frac{\mathbb{E}[N^{[2]}] \mathbb{E}[X^2]}{\mathbb{E}[S_N^2]} \text{Pr} (S_{\tilde{N}_{N-2}} + \tilde{X}_1 + \tilde{X}_2 \leq s) \]

\[ + \frac{\mathbb{E}[N] \mathbb{E}[X^2]}{\mathbb{E}[S_N^2]} \text{Pr} (S_{\tilde{N}_{N-1}} + \tilde{X}_1^{[2]} \leq s) , \]

(3.14)

which is the result in Theorem 2 of Ren (2021).

Theorem 3.1 is different from Theorem 3 of Ren (2021), which is valid for cases with one dimensional claim frequency and multidimensional claim sizes.

**Remark 3.2.** Theorem 3.1 relates the moment transform of \( S_N \) with those of \( N \) and \( X \). For example, Equation (3.9) shows that the distribution of \( \tilde{S}_N^{[k^{[2]}]} \) is a mixture of

\[ W_1 = : S_{L^{[k^{[2]}]}} + (\tilde{X}_{k,1} + \tilde{X}_{k,2}) \times 1^{[k]} \]

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and

\[ W_2 = S_{\tilde{N}^{[k]}_{[2]}} + \tilde{X}_{k,1}^{[2]} \times 1^{[k]} \].

Loosely speaking, to obtain \( W_1 \), we first obtain \( \tilde{N}^{[k(2)]}_{[2]} \), which is the second factorial moment transform of \( N \). Then, we replace two type \( k \) claims from \( S_{\tilde{N}^{[k(2)]}_{[2]}} \) with their independent moment transformed versions \( \tilde{X}_{k,1} \) and \( \tilde{X}_{k,2} \). To obtain \( W_2 \), we replace a type \( k \) claim from \( S_{\tilde{N}^{[k]}} \) with its independent second moment transformed version, \( \tilde{X}_{k,1}^{[2]} \).

**Remark 3.3.** Theorem 3.1 provides an approach to calculate the distributions of the moment transformed \( SN \). For example, to compute the distribution of \( \tilde{S}_{N}^{[k(2)]} \), we do the following.

1. **Determine the distribution functions of** \( L^{[k]} \) **and** \( L^{[k(2)]} \). This is studied in great detail in Section 4 of this paper, where we show that for several commonly used models \( N \) studied in Hesselager (1996) and Kim et al. (2019), the distribution of the \( L \)’s are in fact mixture of some distributions in the same family as \( N \) and can be conveniently computed.

2. **Determine the distribution functions of** \( S_{L^{[k(2)]}}^{[k]} \) **and** \( S_{L^{[k]}}^{[k]} \). This can be done by either (a) applying the recursive methods introduced in Hesselager (1996) and Kim et al. (2019) or (b) applying the FFT method if the characteristic functions of \( N \) (therefore \( L \)’s) and \( X \) are known. For details of the FFT method, see for example, Wang (1998) and Embrechts and Frei (2009).

3. **Determine the distribution functions of** \( W_1 \) **and** \( W_2 \). Since the elements in \( W_1 \) and \( W_2 \) are independent, this can be done by applying direct (multivariate) convolution or FFT.

4. **Mixing the distribution functions of** \( W_1 \) **and** \( W_2 \) **using the weights in** Equation (3.9).

With Theorem 3.1, the MTCE and MTCOV of \( SN \), defined in (2.2) and (2.3) respectively, can be computed by applying items (i) and (ii) of Lemma 2.1. We summarize the results as follows.

\[
E[S_{N_k} | S_N > s_q] = E[S_{N_k}] \frac{Pr(\tilde{S}_{N}^{[k]} > s_q)}{Pr(S_N > s_q)}, \quad k \in \mathcal{K} \tag{3.15}
\]

\[
E[S_{N_k}^2 | S_N > s_q] = E[S_{N_k}^2] \frac{Pr(\tilde{S}_{N}^{[k(2)]} > s_q)}{Pr(S_N > s_q)}, \quad k \in \mathcal{K} \tag{3.16}
\]

and

\[
E[S_{N_{k_1}N_{k_2}} | S_N > s_q] = E[S_{N_{k_1}N_{k_2}}] \frac{Pr(\tilde{S}_{N}^{[k_1,k_2]} > s_q)}{Pr(S_N > s_q)}, \quad k_1, k_2 \in \mathcal{K}. \tag{3.17}
\]
To determine the quantities defined in (2.4) and (2.6) related to the capital allocation problem, we make use of item (iii) of Lemma 2.1. This yields

\[ \mathbb{E}[S_{N_k} | S_\bullet > s] = \mathbb{E}[S_{N_k}] \frac{\Pr [\hat{S}_k > s]}{\Pr [S_\bullet > s]}, \]  

(3.18)

where \( \hat{S}_k = \sum_{j=1}^{K} \hat{S}_{N_j}^{[k]} \), and \( \hat{S}_{N_j}^{[k]} \) is the \( j \)th element of \( \hat{S}_{N}^{[k]} \), whose (joint) distribution can be computed using (3.7). Then, the probability \( \Pr [S_\bullet > s] \) can be calculated. For example, in the bivariate case, if the FFT method is used for \( \hat{S}_N^{[k]} \), then the distribution of \( \hat{S}_k \) can be obtained by the inverse fast Fourier transform of the diagonal terms of the array of the FFT of \( \hat{S}_N^{[k]} \).

In addition, for \( k_1, k_2 \in \mathcal{K} \)

\[ \mathbb{E}[S_{N_{k_1}} S_{N_{k_2}} | (S_\bullet > s)] = \mathbb{E}[S_{N_{k_1}} S_{N_{k_2}}] \frac{\Pr [\hat{S}_{k_1,k_2} > s]}{\Pr [S_\bullet > s]}, \]  

(3.19)

where

\[ \hat{S}_{k_1,k_2} = \sum_{j=1}^{K} \hat{S}_{N_j}^{[k_1,k_2]}. \]

These quantities can be computed by applying Equations (3.9) and (3.11).

From Equations (3.15) to (3.19), it is seen that we essentially change the problem of computing tail moments to the problem of computing the tail probabilities of the moment transformed distributions. All the required quantities for computing the risk measures and performing the capital allocations can be determined if the moment transformed distributions of \( S_N \) can be computed.

By Theorem 3.1, it is seen that the distribution functions of the moment transforms of \( S_N \) rely on the distribution functions of \( L^{[k]} \), \( L^{[k_1,k_2]} \) and \( L^{[k_2]} \). Therefore, in the next section, we derive formulas for determining them when \( N \) follows some commonly used multivariate discrete distributions, as introduced in Hesselager (1996) and Kim et al. (2019).

4. MULTIVARIATE FACTORIAL MOMENT TRANSFORM OF SOME COMMONLY USED DISCRETE DISTRIBUTIONS

As discussed in Section 4.2 of Denuit and Robert (2021), common mixture is a very flexible and useful method for constructing dependence models. It plays a fundamental role in the following derivations. Therefore, we first present a general result on moment transform of a random vector with common mixing variables.

Let \( X = (X_1, \ldots, X_K) \). An external environment, described by a random variable \( \Lambda \), affects each element of \( X \) such that \( X \overset{d}{=} X(\Lambda) \) and \( X_i \overset{d}{=} X_i(\Lambda) \). Let
Let \( X(\lambda) \) be the random vector with the conditional distribution of \( X \) given \( \Lambda = \lambda \), and then, we have the following result for the moment transform of \( X \).

**Proposition 4.1.** The distribution function of the \((k_1, k_2)\)th component \((\alpha_1, \alpha_2)\)th order moment transform of \( X = X(\Lambda) \) is given by

\[
F_{\hat{X}^{(k_1, k_2)}_{(\alpha_1, \alpha_2)}}(x) = \int F_{\hat{X}^{(k_1, k_2)}_{(\alpha_1, \alpha_2)}}(x) \, dF_{\Lambda^\ast}(\lambda),
\]

where

\[
dF_{\Lambda^\ast}(\lambda) = \frac{\mathbb{E}[X_{k_1}(\lambda)^{\alpha_1} X_{k_2}(\lambda)^{\alpha_2}]}{\mathbb{E}[X_{k_1}(\Lambda)^{\alpha_1} X_{k_2}(\Lambda)^{\alpha_2}]} \, dF(\lambda).
\]

**Proof.**

\[
F_{\hat{X}^{(k_1, k_2)}_{(\alpha_1, \alpha_2)}}(x) = \frac{\mathbb{E}[X_{k_1}(\lambda)^{\alpha_1} X_{k_2}(\lambda)^{\alpha_2} \mathbb{I}(X \leq x)]}{\mathbb{E}[X_{k_1}(\Lambda)^{\alpha_1} X_{k_2}(\Lambda)^{\alpha_2}]} = \int \mathbb{E}[X_{k_1}(\lambda)^{\alpha_1} X_{k_2}(\lambda)^{\alpha_2} \mathbb{I}(X(\lambda) \leq x)] \, dF_{\Lambda^\ast}(\lambda)
\]

\[
= \int \mathbb{E}[X_{k_1}(\lambda)^{\alpha_1} X_{k_2}(\lambda)^{\alpha_2} \mathbb{I}(\hat{X}(\lambda)^{[k_1, k_2]} \leq x)] \, dF_{\Lambda^\ast}(\lambda)
\]

\[
= \int \mathbb{E}[\hat{X}(\lambda)^{[k_1, k_2]} \leq x] \, dF_{\Lambda^\ast}(\lambda).
\]

\[\square\]

This proposition is used in several settings in the sequel, where the moment transforms of several commonly used multivariate models for claim frequency are studied.

### 4.1. Multinomial – \((a,b,0)\) mixture.

This is model A of Hesselager (1996). Let \( M \) be a counting random variable whose probability mass function \( p_M \) is in the \((a,b,0)\) class with parameters \( a \) and \( b \). That is,

\[
p_M(k) = \left( a + \frac{b}{k} \right) p_M(k - 1), \quad k = 1, 2, 3, \ldots.
\]

Assume that conditional on \( M = m \), \( N = (N_1, \ldots, N_K) \) follows a multinomial (MN) distribution with parameters \((m, q_1, \ldots, q_K)\). That is
\[ \Pr(N = n \mid M = m) = \frac{m!}{n_1! n_2! \cdots n_K!} q_1^{n_1} \cdots q_K^{n_K}, \] when \( n_1 + n_2 + \cdots + n_K = m \)

for non-negative \( n_1, \ldots, n_K \). It is understood that \( N = 0 \) when \( m = 0 \).

As illustrated in Hesselager (1996), this model has a natural application in claim reserving where \( M \) is the total number of claims incurred in a fixed period and \( n_1 \sim n_K \) are the number of claims in different stages of settlement (reported, not-reported, paid, and so on).

In the following, we refer to the unconditional distribution of \( N \) as the HMN distribution and write \( N \sim \text{HMN}(M, q_1, \ldots, q_K) \). To obtain the moment transforms of \( N \), we observe that \( M \) can be regarded as a common mixing variable for \((N_1, \ldots, N_K)\). Thus, we write \( N(d) = N(M) \) and let \( N(m) = (N_1(m), \ldots, N_K(m)) \) denote the random vector with distribution \( \text{MN}(m, q_1, \ldots, q_K) \).

By simple substitution, it is easy to verify that

- for \( k \in \mathcal{K} \) and \( m \geq 1 \),

\[ L[k](m) = \hat{N}(m)^{[k]} - 1^{[k]} \sim \text{MN}(m - 1, q_1, \ldots, q_K), \quad (4.3) \]

- for \( k_1 \neq k_2 \in \mathcal{K} \) and \( m \geq 2 \)

\[ L[k_1, k_2](m) = \hat{N}(m)^{[k_1, k_2]} - 1^{[k_1]} - 1^{[k_2]} \sim \text{MN}(m - 2, q_1, \ldots, q_K), \quad (4.4) \]

- for \( k \in \mathcal{K} \) and \( m \geq 2 \),

\[ L[k^{[2]}](m) = \left( \hat{N}(m)^{[k^{[2]}]} - 2 \times 1^{[k]} \right) \sim \text{MN}(m - 2, q_1, \ldots, q_K) \quad (4.5) \]

Combining Proposition 4.1 and the above three points yields the following results.

**Theorem 4.1.** Let \( N \sim \text{HMN}(M, q_1, \ldots, q_K) \), then

\[ L[k] = \hat{N}[k] - 1^{[k]} \sim \text{HMN}(\hat{M} - 1, q_1, \ldots, q_K), \quad (4.6) \]

\[ L[k^{[2]}] = \hat{N}[k^{[2]}] - 2 \times 1^{[k]} \sim \text{HMN}(\hat{M}^{[2]} - 2, q_1, \ldots, q_K), \quad (4.7) \]

\[ L[k_1, k_2] = \hat{N}[k_1, k_2] - 1^{[k_1]} - 1^{[k_2]} \sim \text{HMN}(\hat{M}^{[2]} - 2, q_1, \ldots, q_K). \quad (4.8) \]

**Proof.** By Proposition 4.1,

\[ p_{\hat{N}[k]}(n) = \sum_m p_{\hat{N}(m)^{[k]}(n)} p_{M_k}(m), \]
where
\[
\begin{align*}
p_{M^*_k}(m) &= \frac{\mathbb{E}[N_k(m)]}{\mathbb{E}[N_k(M)]} p_M(m) \\
&= \frac{mq_k}{\mathbb{E}[M]q_k} p_M(m) \\
&= p_{\tilde{M}}(m).
\end{align*}
\]
Therefore,
\[
\begin{align*}
p_{L^{[k]}(n)} &= \sum_m p_{L^{[k]}(n)}(m)p_{M^*_k}(m),
\end{align*}
\]
which by (4.3) indicates (4.6).

Similarly,
\[
\begin{align*}
L^{[k_1,k_2]} &\sim HMN(M^*_k - 2, q_1, \cdots, q_K),
\end{align*}
\]
where
\[
\begin{align*}
p_{M^*_{k_1,k_2}}(m) &= \frac{\mathbb{E}[N_{k_1}(m)N_{k_2}(m)]}{\mathbb{E}[N_{k_1}(M)N_{k_2}(M)]} p_M(m) \\
&= \frac{m(m-1)q_{k_1}q_{k_2}}{\mathbb{E}[M(M-1)]q_{k_1}q_{k_2}} p_M(m) \\
&= p_{\tilde{M}^{[2]}}(m),
\end{align*}
\]
which leads to (4.7). In addition,
\[
\begin{align*}
L^{[k^{[2]}]} &\sim HMN(M^*_{k^{[2]}} - 2, q_1, \cdots, q_K)
\end{align*}
\]
where
\[
\begin{align*}
p_{M^*_{k^{[2]}}}(m) &= \frac{\mathbb{E}[N_k(m)(N_k(m) - 1)]}{\mathbb{E}[N_k(M)(N_k(M) - 1)]} p_M(m) \\
&= \frac{m(m-1)q^2_k}{\mathbb{E}[M(M-1)]q_k^2} p_M(m) \\
&= p_{\tilde{M}^{[2]}}(m),
\end{align*}
\]
which leads to (4.8).

It was shown in Ren (2021) that if \(M\) is in \((a,b,0)\) class with parameter \((a,b)\), then \(\tilde{M} - 1\) is in the \((a,b,0)\) class with parameter \((a, a+b)\), and \(M^{[2]} - 2\) is in the \((a,b,0)\) class with parameter \((a, 2a + b)\). Therefore, the distributions of \(L^{[k]}, L^{[k^{[2]}]}, L^{[k_1,k_2]}, \) and the original \(N\) are all in the same HMN family of Binomial-(a,b,0) mixture distributions. Thus, all the nice properties discussed in Hesselager (1996) are preserved. A particular important fact is that the
corresponding compound distributions of $S_{L[k]}$, $S_{L[k^{(2)]}}$, $S_{L^{(k_1,k_2)}}$ can be evaluated recursively by using Theorem 2.2 of Hesselager (1996). Alternatively, the characteristic functions of $S_{L[k]}$, $S_{L[k^{(2)]}}$, $S_{L^{(k_1,k_2)}}$ can be found easily, and their distribution functions can be computed using the FFT method. Consequently, Theorem 3.1 can be applied to compute the distributions of $\hat{S}_N^{[k]}$, $\hat{S}_N^{[k^{(2)]}}$ and $\hat{S}_N^{[k_1,k_2]}$.

4.2. Additive common shock

For $k \in \{0\} \cup \mathcal{K}$, let $\{M_k\}$ be independent non-negative discrete random variables with distribution functions in the $(a, b, 0)$ class with parameters $\{(a_k, b_k)\}$. For $k \in \mathcal{K}$, let $N_k = M_0 + M_k$. We consider the vector $\mathbf{N} = (N_1, \ldots, N_K)$.

The moment transforms of $\mathbf{N}$ could be derived by treating $M_0$ as a common mixing random variable. However, we next take a seemingly more direct approach.

**Theorem 4.2.** The $k$th component first moment transform of $\mathbf{N}$ is given by

$$
\Pr\left(\hat{N}^{[k]} = n\right) = \frac{\mathbb{E}[M_0]}{\mathbb{E}[N_k]} \Pr\left[\hat{M}_0 + M_{\xi} = n_{\xi} \text{ for all } \xi \in \mathcal{K}\right]
+ \frac{\mathbb{E}[M_k]}{\mathbb{E}[N_k]} \Pr\left[M_0 + \hat{M}_k = n_k, M_0 + M_{\xi} = n_{\xi} \text{ for all } \xi \in \mathcal{K} - \{k\}\right].
$$

(4.9)

The $k$th component second factorial moment transform of $\mathbf{N}$ is given by

$$
\Pr\left(\hat{N}^{[k^{(2)]}} = n\right) = \frac{\mathbb{E}[M_0^{(2)}]}{\mathbb{E}[N_k^{(2)}]} \Pr\left[\hat{M}_0^{(2)} + M_{\xi} = n_{\xi} \text{ for all } \xi \in \mathcal{K}\right]
+ \frac{\mathbb{E}[M_k^{(2)}]}{\mathbb{E}[N_k^{(2)}]} \Pr\left[M_0 + \hat{M}_k^{(2)} = n_k, M_0 + M_{\xi} = n_{\xi} \text{ for all } \xi \in \mathcal{K} - \{k\}\right]
+ 2\frac{\mathbb{E}[M_0]\mathbb{E}[M_k]}{\mathbb{E}[N_k^{(2)}]} \Pr\left[\hat{M}_0 + \hat{M}_k = n_k, M_0 + M_{\xi} = n_{\xi} \text{ for all } \xi \in \mathcal{K} - \{k\}\right].
$$

(4.10)

For $k_1 \neq k_2 \in \mathcal{K}$, the $(k_1, k_2)$th component first-order moment transform of $\mathbf{N}$ is given by

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\[
\Pr \left( \hat{N}^{[k_1,k_2]} = n \right) = \frac{\mathbb{E}[M_0^{(2)}]}{\mathbb{E}[N_{k_1}N_{k_2}]} \Pr \left[ \hat{M}_0^{[(2)]} + M_\xi = n_\xi \text{ for all } \xi \in \mathcal{K} \right] \\
+ \frac{\mathbb{E}[M_0]}{\mathbb{E}[N_{k_1}N_{k_2}]} \Pr \left[ \hat{M}_0 + M_\xi = n_\xi \text{ for all } \xi \in \mathcal{K} \right] \\
+ \frac{\mathbb{E}[M_0M_{k_1}]}{\mathbb{E}[N_{k_1}N_{k_2}]} \Pr \left[ \hat{M}_0 + \hat{M}_{k_1} = n_{k_1} \right] \\
\hat{M}_0 + M_\xi = n_\xi \text{ for all } \xi \in \mathcal{K} - \{k_1\} \\
+ \frac{\mathbb{E}[M_0M_{k_2}]}{\mathbb{E}[N_{k_1}N_{k_2}]} \Pr \left[ \hat{M}_0 + \hat{M}_{k_2} = n_{k_2} \right] \\
\hat{M}_0 + M_\xi = n_\xi \text{ for all } \xi \in \mathcal{K} - \{k_2\} \\
+ \frac{\mathbb{E}[M_{k_1}M_{k_2}]}{\mathbb{E}[N_{k_1}N_{k_2}]} \Pr \left[ M_0 + \hat{M}_{k_1} = n_{k_1} \right] \Pr \left[ M_0 + \hat{M}_{k_2} = n_{k_2} \right] \\
M_0 + M_\xi = n_\xi \text{ for all } \xi \in \mathcal{K} - \{k_1, k_2\}
\]

(4.11)

Proof. The proof of three statements is similar. We only prove (4.11) in the following.

\[
\Pr \left( \hat{N}^{[k_1,k_2]} = n \right) = \frac{\mathbb{E}[N_{k_1}N_{k_2}] \mathbb{1}(N = n)}{\mathbb{E}[N_{k_1}N_{k_2}]}
= \frac{\mathbb{E}\left[ (M_0^{(2)} + M_0 + M_0M_{k_1} + M_0M_{k_2} + M_{k_1}M_{k_2}) \mathbb{1}(N = n) \right]}{\mathbb{E}[N_{k_1}N_{k_2}]}
\]

Now, because \( M_0, M_1, \ldots, M_K \) are mutually independent, we have for the first multiplication in the above
\[
\mathbb{E}[M_0^{(2)} \mathbb{1}(N = n)] = \mathbb{E}[M_0^{(2)}] \Pr \left( \hat{M}_0^{[(2)]} + M_\xi = n_\xi \text{ for all } \xi \in \mathcal{K} \right),
\]
which results in the first line of (4.11). Other terms can be obtained similarly. \(\square\)

Remark 4.1. Some insights can be gleaned from the results. Firstly, (4.9) indicates that the distribution of \( \hat{N}^{[k]} \) is a mixture of those of \( N_A = (M_0 + M_1, \ldots, M_0 + M_{k_1}, \ldots, M_0 + M_K) \) and \( N_B = (M_0 + M_1, \ldots, M_0 + M_{k}, \ldots, M_0 + M_K) \).

The Poisson case is especially interesting. Suppose that \( M_\xi \sim \text{Poisson}(\lambda_\xi) \) for \( \xi \in \{0\} \cup \mathcal{K} \). Then, \( \hat{M}_\xi = M_\xi + 1 \) for all \( \xi \). As a result, the distribution of \( \hat{N}^{[k]} \) is a mixture of those of \( N_A = N + 1 \), where \( 1 \) is a \( K \) dimensional vector of ones, and \( N_B = N + 1^{[k]} \), with weights \( \frac{\lambda_0}{\lambda_0 + \lambda_k} \) and \( \frac{\lambda_k}{\lambda_0 + \lambda_k} \) respectively. It is obvious that
\( \hat{N}^{[k]} \) is larger than \( N \) in the sense of multivariate first-order stochastic dominance. For a general result about the stochastic order of a multivariate random variable and its moment transform, please refer to Property 2.1 of Denuit and Robert (2021). In addition, note that more weights are given to \((N + 1)\) when \( \mathbb{E}[M_0] \) is large.

Having obtained the distributions of \( \hat{N}^{[k]}, \hat{N}^{[k_1,k_2]} \) and \( \hat{N}^{[k_2]} \), the distributions of \( L^{[k]}, L^{[k_1,k_2]} \) and \( L^{[k_2]} \) can be computed. For example, for the Poisson case in Remark 4.1, \( L^{[k]} = \hat{N}^{[k]} - 1^{[k]} \) is a mixture of \( N + 1 - 1^{[k]} \) and \( N \). Therefore, the corresponding compound distributions required in Theorem 3.1 can be evaluated using either the FFT method or the recursive formulas in Theorem 3.2 of Hesselager (1996).

### 4.3. Common Poisson mixture

We consider the mixture model studied in Kim et al. (2019), which is more general than Model B of Hesselager (1996).

Let \( \Lambda \) be a random variable defined on \((0, \infty)\). Conditional on \( \Lambda = \lambda \), the claim frequencies \( \{N_k\}_{k \in K} \) are independent Poisson random variables, where the type \( k \) frequency has mean \( a_k \lambda + b_k \) for some non-negative constants \( a_k \) and \( b_k \). Without loss of generality, we assume that \( \mathbb{E}[\Lambda] = 1 \).

We have the following result.

**Theorem 4.3.**

\[
\text{Pr}\left(L^{[k]} = n\right) = \int \prod_{k \in K} \text{Pr}\left(N_k(\lambda) = n_k\right) \ dF_{\Lambda_k}^*(\lambda),
\]

where

\[
F_{\Lambda_k}^*(\lambda) = \frac{a_k F_{\Lambda}^*(\lambda) + b_k F_{\Lambda}(\lambda)}{a_k + b_k}.
\] (4.12)

\[
\text{Pr}\left(L^{[k_1,k_2]} = n\right) = \int \prod_{k \in K} \text{Pr}\left(N_k(\lambda) = n_k\right) \ dF_{\Lambda_{k_1,k_2}}^*(\lambda),
\]

where

\[
F_{\Lambda_{k_1,k_2}}^*(\lambda) = \frac{a_{k_1} a_{k_2} \mathbb{E}[\Lambda^2] F_{\Lambda}^{[2]}(\lambda) + (a_{k_1} b_{k_2} + a_{k_2} b_{k_1}) F_{\Lambda}^{[1]}(\lambda) + b_{k_1} b_{k_2} F_{\Lambda}(\lambda)}{a_{k_1} a_{k_2} \mathbb{E}[\Lambda^2] + a_{k_1} b_{k_2} + a_{k_2} b_{k_1} + b_{k_1} b_{k_2}}.
\] (4.13)

\[
\text{Pr}\left(L^{[k_2]} = n\right) = \int \prod_{k \in K} \text{Pr}\left(N_k(\lambda) = n_k\right) \ dF_{\Lambda_{k_2}}^*(\lambda),
\]

where

\[
F_{\Lambda_{k_2}}^*(\lambda) = \frac{a_k^2 \mathbb{E}[\Lambda^2] F_{\Lambda}^{[2]}(\lambda) + 2 a_k b_k F_{\Lambda}^{[1]}(\lambda) + b_k^2 F_{\Lambda}(\lambda)}{a_k^2 \mathbb{E}[\Lambda^2] + 2 a_k b_k + b_k^2}.
\] (4.15)
Proof. The proof of the three statements is similar. We only present the proof of (4.14) in the following.

First, due to Proposition 4.1, we have
\[ \Pr \left( \hat{N}^{[k]} = n \right) = \int \Pr \left( \tilde{N}(\lambda)^{[k]} = n \right) \ dF*_{\Lambda^{[k]}}, \]

where
\[ dF*_{\Lambda^{[k]}}(\lambda) = \frac{\mathbb{E}[N_k(\lambda)^{[2]}]}{\mathbb{E}[\tilde{N}_k(\Lambda)^{[2]}]} \ dF(\lambda) \]
\[ = \frac{(a_k \lambda + b_k)^2}{\mathbb{E}(a_k \lambda + b_k)^2} \ dF(\lambda) \]
\[ = \frac{a^2_k \lambda^2 \ dF(\lambda) + 2a_k b_k \lambda \ dF(\lambda) + b^2_k \ dF(\lambda)}{a^2_k \mathbb{E}[\lambda^2] + 2a_k b_k \mathbb{E}[\lambda] + b^2_k} \]
\[ = \frac{a^2_k \mathbb{E}[\lambda^2] dF(\lambda) + 2a_k b_k \ dF(\lambda) + b^2_k \ dF(\lambda)}{a^2_k \mathbb{E}[\lambda^2] + 2a_k b_k \mathbb{E}[\lambda] + b^2_k}, \]

which is (4.15). Notice that we have used \( \mathbb{E}[\lambda] = 1 \).

Next, since \( L^{[k]} = \hat{N}^{[k]} - 2 \times 1^*[k] \),

we have
\[ \Pr \left( L^{[k]} = n \right) = \int \Pr \left( L^{[k]}(\lambda) = n \right) \ dF*_{\Lambda^{[k]}}, \] (4.16)

However, because \( N_k(\lambda), k \in K \) are independent Poisson random variables,
\[ L^{[k]}(\lambda) = \tilde{N}(\lambda)^{[k]} \overset{d}{=} N(\lambda), \]

and
\[ L^{[k]}(\lambda) = \tilde{N}(\lambda)^{[k]} - 2 \times 1^*[k] \overset{d}{=} N(\lambda) \] (4.17)

Combining (4.16) and (4.17) leads to the desired result. \( \square \)

Remark 4.2. It is seen from Theorem 4.3 that the distributions of \( L^{[k]}, L^{[k]} \) and \( L^{[k_1,k_2]} \) are similar to that of \( N \), with mixing parameters given by \( \Lambda^*_{[k]}, \Lambda^*_{[k]} \), and \( \Lambda^*_{[k_1,k_2]} \), respectively. In addition, the distributions of \( \Lambda^*_{[k]}, \Lambda^*_{[k_2]} \) and \( \Lambda^*_{[k_1,k_2]} \) are the mixtures of those of \( \tilde{\Lambda}^{[1]}, \tilde{\Lambda}^{[2]} \), and \( \Lambda \). Therefore, they can be evaluated if the distributions of \( \tilde{\Lambda}^{[1]} \) and \( \tilde{\Lambda}^{[2]} \) can be determined. In fact, this is true for many choices of the distribution of \( \Lambda \) (Patil and Ord, 1976). For example, if \( \Lambda \) has a

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gamma ($\alpha$, $\beta$) distribution with p.d.f
\[ f_\Lambda(\lambda) = \frac{\beta^\alpha}{\Gamma(\alpha)} \lambda^{\alpha-1} e^{-\beta \lambda} \]
then $\tilde{\Lambda}^{[1]}$ and $\tilde{\Lambda}^{[2]}$ follow gamma distributions with parameters $(\alpha + 1, \beta)$ and $(\alpha + 2, \beta)$, respectively. In such a case, the distributions of $L$'s are the finite mixtures of some Poisson-gamma mixtures. Consequently, the distribution of the compound sum $S_L$ can be computed using the recursive methods derived in Hesselager (1996) or the FFT method.

4.4. Dependent claim frequency and size

As briefly discussed in Section 4.3 of Denuit and Robert (2021), the general mixing method we used in this section can be applied to calculate the risk measures of the aggregate loss when the claim frequency and size are dependent through some common mixing variables. To illustrate the method, we use the setup of Section 4.3 of this paper, but now assume that the distributions of claim sizes also depend on the background parameter $\Lambda$.

**Theorem 4.4.** Let $\Lambda$ be a random variable defined on $(0, \infty)$. Conditional on $\Lambda = \lambda$, let the claim frequencies $N_k$ for $k \in K$ be independent Poisson random variables with mean $a_k \lambda + b_k$; let the corresponding claim sizes have distribution function $F_{X_k|\lambda}$ with mean $c_k \lambda + d_k$. Then,

\[(i)\]
\[
\Pr \left( S_N^{[k]} \leq s \right) = \int \Pr \left( S_{N_1}(\lambda) \leq s_1, \cdots, S_{N_k}(\lambda) + \tilde{X}_k(\lambda) \leq s_k, \cdots, S_{N_K}(\lambda) \leq s_K \right) dF_{\Lambda,d,k^*}(\lambda)
\]

where
\[
dF_{\Lambda,d,k^*}(\lambda) = \frac{E\left[S_{N_k}(\lambda)\right]}{E\left[S_{N_k}(\Lambda)\right]} dF_\Lambda(\lambda)
\]
\[
= \frac{(a_k \lambda + b_k)(c_k \lambda + d_k)}{E[(a_k \Lambda + b_k)(c_k \Lambda + d_k)]} dF_\Lambda(\lambda)
\]
\[
= \frac{a_k c_k E[\Lambda^2] dF_{\Lambda^{[2]}_k}(\lambda) + (a_k d_k + b_k c_k)E[\Lambda] dF_{\Lambda^{[1]}_k}(\lambda) + b_k d_k dF_\Lambda(\lambda)}{a_k c_k E[\Lambda^2] + (a_k d_k + b_k c_k)E[\Lambda] + b_k d_k}.
\]
(ii) \[
\Pr \left( \tilde{S}_N^{[k]} \leq s \right) = \int \Pr \left( S_{N_1}(\lambda) \leq s, \ldots, \tilde{S}_{N_k}(\lambda) \leq s_k \right) dF_{\Lambda^*[d;k]}^*(\lambda)
\]
where
\[
dF_{\Lambda^*[d;k]}^*(\lambda) = \frac{\mathbb{E} \left[ \tilde{S}_{N_k}^2(\lambda) \right]}{\mathbb{E} \left[ \tilde{S}_{N_k}^2(\Lambda) \right]} dF(\lambda)
\]
and
\[
\Pr \left( \tilde{S}_{N_k}(\lambda) \leq s \right) = \frac{\mathbb{E} \left[ \tilde{N}_{k}^2(\lambda) \right] (\mathbb{E} \left[ \tilde{X}_k(\lambda) \right])^2}{\mathbb{E} \left[ \tilde{S}_{N_k}^2(\lambda) \right]} \Pr \left( S_{N_k}(\lambda) \leq s \right) + \tilde{X}_{k,1}(\lambda) + \tilde{X}_{k,2}(\lambda) \leq s
\]
\[
+ \frac{\mathbb{E} \left[ \tilde{N}_{k}(\lambda) \right] (\mathbb{E} \left[ \tilde{X}_k(\lambda) \right]^2)}{\mathbb{E} \left[ \tilde{S}_{N_k}^2(\lambda) \right]} \Pr \left( S_{N_k}(\lambda) + \tilde{X}_{k,1}(\lambda) \leq s \right),
\]

(iii) \[
\Pr \left( \tilde{S}_N^{[k_1,k_2]} \leq s \right) = \int \Pr \left( S_{N_1}(\lambda) \leq s_1, \ldots, \tilde{S}_{N_{k_1}}(\lambda) \leq s_{k_1}, \ldots, \tilde{S}_{N_{k_2}}(\lambda) \leq s_{k_2}, \ldots, S_{N_k}(\lambda) \leq s_k \right) dF_{\Lambda^*[d_{k_1,k_2}]}^*(\lambda)
\]
with
\[
dF_{\Lambda^*[d_{k_1,k_2}]}^*(\lambda) = \frac{\mathbb{E} \left[ S_{N_{k_1}}(\lambda) S_{N_{k_2}}(\lambda) \right]}{\mathbb{E} \left[ S_{N_{k_1}}(\Lambda) S_{N_{k_2}}(\Lambda) \right]} dF(\lambda).
\]

**Proof.** Since all variables in $S_N$ are independent conditional on $\Lambda$, we have
\[
\tilde{S}_N^{[k_1,k_2]} \overset{d}{=} \left( S_{N_1}(\lambda) \ldots, \tilde{S}_{N_{k_1}}(\lambda)^{[k_1]} \ldots, \tilde{S}_{N_{k_2}}(\lambda)^{[k_2]} \ldots, S_{N_k}(\lambda) \right).
\]
Then, the three statements can be proved by applying Proposition 4.1.

Equation (4.22) for $\tilde{S}_{N_k}(\lambda)^{[2]}$ is due to (3.14).
Remark 4.3. When both the distributions of claim frequency and size depend on $\lambda$, the distribution of $S_{N_k}$ cannot be computed using the recursive methods. However, its characteristic function can still be calculated. Thus, the FFT method is still applicable.

5. Numerical examples

In this section, we provide numerical examples carrying out the capital allocation computation for each of the three models introduced in the previous section. In all the examples, we suppose that an insurer underwrites auto insurance policies that cover two types of claims: bodily injury (BI) and property damage (PD). Let the numbers of the two types of claims incurred in a time period be $N = (N_1, N_2)$ and their sizes be $X_1$ and $X_2$, respectively.

The distributions of claim frequencies and sizes and their parameters are selected hypothetically. However, they reflect the fact that the BI claims have relatively low frequencies and high severities. Our main goal is to illustrate the application of the formulas derived in this paper to compute the risk measures and capital allocations for multivariate aggregate loss models. Our results illustrate how low (or high) frequencies and high (or low) severities contribute to the tail risks.

To compare these two types of risks, in all the examples we report the following ratios.

- The proportions of risk capital allocated to the two types of risks according to the TCE criterion

$$\frac{\mathbb{E}[S_{N_k}|S_\bullet > s_q]}{\mathbb{E}[S_\bullet|S_\bullet > s_q]} \quad k = 1, 2. \quad (5.1)$$

- The proportions of risk capital allocated to the two types of risks according to the TV criterion

$$\frac{\text{Cov}[(S_k, S_\bullet)|S_\bullet > s_q]}{\text{Var}[S_\bullet|S_\bullet > s_q]} \quad k = 1, 2. \quad (5.2)$$

The computations are carried out using the following procedure.

Computation Procedure 5.1

(i) Determine the distributions of $L^{[k]}$ and $L^{[k]}$ for $k = 1, 2$, and $L^{[1,2]}$ using Theorems 4.1, 4.2, or 4.3.

(ii) Determine the distributions of $S_{L^{[k]}}$ and $S_{L^{[k]}[2]}$, for $k = 1, 2$, and $S_{L^{[1,2]}}$. For the three models we discussed, this can be implemented by using the FFT or the recursive method proposed in Hesselager (1996). We choose to use the FFT method because of the simplicity of computer programming.
(iii) Determine the distributions of $\tilde{S}_N^{[k]}$, $\tilde{S}_N^{[k,2]}$ for $k = 1, 2$ and $\tilde{S}_N^{[1,2]}$. This is implemented by using Theorem 3.1. The required convolutions are computed using the FFT method.

(iv) Determine the MTCE and MTCOV of $S_N$ using Equations (3.15), (3.16), and (3.17).

(v) Determine the TCE- and TV-based capital allocations by using Equations (3.18) and (3.19).

A flowchart for computing $\frac{E[S_N|S_N > s_q]}{E[S_N|S_N > s_q]}$ is shown in Figure 1. The steps for computing $\frac{Cov\left[S_k,S_N|S_N > s_q\right]}{Var\left[S_N|S_N > s_q\right]}$ are similar and thus omitted.

Since in all the three models studied, the claim frequencies are dependent but the claim sizes are independent, we have

$$E[S_k^2] = E[N_k]E[X_k^2] + E[N_k^2](E[X_k])^2, \quad k = 1, 2$$

and

$$E[S_1S_2] = E[N_1N_2]E[X_1]E[X_2].$$

These quantities will be used in the calculations.

5.1. An example of the HMN model

Assume that $N$ follows the HMN $(M, q_1, q_2)$ distribution with $M \sim NB(r, \beta)$ whose probability mass function is given by (the parameterization in Klugman et al., 2019 is adopted)

$$p_M(n) = \binom{r+n-1}{n} \left(\frac{\beta}{1+\beta}\right)^n \left(\frac{1}{1+\beta}\right)^r, \quad n \geq 0.$$
It is easy to check that
\[ E[N_k] = E[M] q_k, \quad k = 1, 2, \]
\[ E[N_k^{(2)}] = E[M^{(2)}] q_k^2, \quad k = 1, 2, \]
and
\[ E[N_1 N_2] = E[M^{(2)}] q_1 q_2, \]
and
\[ \text{Cov}[N_1, N_2] = (\text{Var}(M) - E[M]) q_1 q_2. \]

One interesting fact that the above equation reveals is that for the HMN model, the sign of the covariance of \( N_1 \) and \( N_2 \) depends on the relative sizes of the variance and mean of \( M \). Clearly, if \( M \) follows a negative binomial distribution, then \( N_1 \) and \( N_2 \) are positively correlated; if \( M \) follows a Poisson distribution, then they are not correlated; if \( M \) is a binomial random variable, then they are negatively correlated.

Following Hesselager (1996), the joint PGF of \( N \) is
\[ P_N(z_1, z_2) = (1 - \beta(q_1 z_1 + q_2 z_2 - 1))^{-r} \quad (5.3) \]
and the characteristic function of \( S_N \) is
\[ \psi_{S_N}(t_1, t_2) = (1 - \beta(q_1 \psi_{X_1}(t_1) + q_2 \psi_{X_2}(t_2) - 1))^{-r}, \quad (5.4) \]
where \( \psi_{X_1} \) and \( \psi_{X_2} \) are the characteristic functions of \( X_1 \) and \( X_2 \), respectively.

With the above formulas, we may follow Computation Procedure 5.1 to evaluate the risks and perform the capital allocations for the aggregate losses \((S_1, S_2)\). Some results for this model related to steps (i) and (ii) are given in the following. Steps (iii) to (v) are generic and can be followed for all the models.

**Step (i):** By Theorem 4.1,
\[ L^{[k]} \sim (M_1, q_1, q_2), \quad k = 1, 2 \]
and
\[ L^{[1^{(2)}]} \text{ d } L^{[2^{(2)}]} \text{ d } L^{[1,2]} \sim (M_2, q_1, q_2). \]

Since \( M \sim NB(r, \beta) \), we have
\[ M_1 = \tilde{M} - 1 \sim NB(r + 1, \beta) \]
and
\[ M_2 = \tilde{M}^{(2)} - 2 \sim NB(r + 2, \beta). \]

Thus, for this model, all \( L \)'s follow HMN distributions.

**Step (ii):** Because of the above, the characteristic functions of \( S_{L^{[k]}}, S_{L^{[1^{(2)}]}}, S_{L^{[1,2]}} \) for \( k = 1, 2 \) and \( S_{L^{[1,2]}} \) can be derived in a similar way as that for \( S_N \). Specifically,
\[ \psi_{S_{L^{[k]}}}(t_1, t_2) = (1 - \beta(q_1 \psi_{X_1}(t_1) + q_2 \psi_{X_2}(t_2) - 1))^{-(r+1)} \quad (5.5) \]
and

$$\psi_{S_{[1,2]}}(t_1, t_2) = \psi_{S_{[1,2]}}(t_1, t_2) = \left(1 - \beta(q_1 \psi X_1(t_1) + q_2 \psi X_2(t_2) - 1)\right)^{-r+2}.$$  

(5.6)

Therefore, their distributions can also be computed using the FFT method.

The capital allocation computations are performed by assuming that $M \sim NB(r = 10, \beta = 1)$, $q_1 = 0.1$, $q_2 = 0.9$, $X_1 \sim Poisson(5)$ and $X_2 \sim Poisson(1)$. Note that we assumed Poisson distributions with hypothetical parameters for the claim sizes for simplicity. If more realistic continuous distributions are assumed, they need to be discretized in order to use the FFT or recursive methods.

The proportions of capital allocated according to TCE with selected values of $s_q$ are plotted in the upper left panel of Figure 2. It shows that the proportion of risk capital allocated to BI (PD) claims increases (decreases) with $s_q$. More capital is allocated to PD claims when $s_q$ is small, whereas more risk capital is allocated to BI claims when $s_q$ is large. To put the numbers in the plot into context, $S_*$ has mean 14 and standard deviation 8.2.

The proportions of capital allocated according to TV are shown in the upper right panel of Figure 2. We observe that the proportion allocated to BI claims is a decreasing function for small values of $s_q$ (roughly speaking, when $s_q$ is less than the mean value of $S_*$, 14); it is increasing for large values of $s_q$. The opposite pattern is observed for PD claims.
Figure 2 also shows the capital allocation results obtained by using a Monte Carlo simulation with sample size $10^7$. Clearly, the results obtained by the two methods agree. In addition, our elementary simulation results become unstable for large $s_q$. To obtain more stable simulation results, one needs to either increase the sample size or apply certain variance reduction methods.

Note that the amounts of capital allocated to BI and PD risks both increase with $s_q$, as shown in the lower panels of Figure 2.

5.2. An example of the common shock model

Let $N_1 = M_0 + M_1$, $N_2 = M_0 + M_2$, where $M_0$, $M_1$, and $M_2$ are independent Poisson random variables with parameter $\lambda_0$, $\lambda_1$, $\lambda_2$ respectively. Then, we have

$$\mathbb{E}[N_k] = \lambda_0 + \lambda_k, \quad k = 1, 2,$$

$$\mathbb{E}[N_k^{(2)}] = (\lambda_0 + \lambda_k)^2, \quad k = 1, 2,$$

and

$$\mathbb{E}[N_1N_2] = (\lambda_0 + \lambda_1)(\lambda_0 + \lambda_2) + \lambda_0.$$

The characteristic function of $S_N$ is

$$\psi_{S_N}(t_1, t_2) = \exp \left( \lambda_0(\psi_{X_1}(t_1)\psi_{X_2}(t_2) - 1) + \lambda_1(\psi_{X_1}(t_1) - 1) + \lambda_2(\psi_{X_2}(t_2) - 1) \right).$$

(5.7)

Some results for this model related to steps (i) and (ii) of Computation Procedure 5.1 are given in the following.

**Step (i):** By Equation (4.9), we have that $L[1]$ is a mixture of $N + (0, 1)$ and $N$ with weights $\lambda_0/(\lambda_0 + \lambda_1)$ and $\lambda_1/(\lambda_0 + \lambda_1)$, respectively. $L[2]$ is a mixture of $N + (1, 0)$ and $N$ with weights $\lambda_0/(\lambda_0 + \lambda_2)$ and $\lambda_2/(\lambda_0 + \lambda_2)$, respectively. Similarly, the distributions of $L[k^{(2)}], k = 1, 2$ and $L[1,2]$ are some mixtures of $N$, $N + (0, 1)$, $N + (1, 0)$, $N + (0, 2)$, $N + (2, 0)$, and $N + (1, 1)$. Therefore, their distributions can be computed.

**Step (ii):** Since the distributions of $L$’s are the mixtures of the aggregate Poisson random variables and some constants. The characteristic function of the corresponding compound distribution can be obtained straightforwardly.

With these steps, all the quantities needed for the capital allocations can be computed. The computation is carried out with $\lambda_0 = 0.5$, $\lambda_1 = 0.5$, $\lambda_2 = 5$, $X_1 \sim \text{Poisson}(5)$ and $X_2 \sim \text{Poisson}(1)$. Figure 3 illustrates the results.
5.3. An example of the Poisson Mixture model

Let \( \Lambda \) follow a Gamma distribution with parameters \((\alpha, \alpha)\), and thus, its mean is 1. Conditional on \( \Lambda = \lambda \), for \( k \in \{1, 2\} \), \( N_k \)'s are independent Poisson random variables with mean \( a_k \lambda + b_k \).

It is easy to check that for \( k = 1, 2 \)

\[
\mathbb{E}[N_k] = a_k + b_k,
\]

\[
\mathbb{E}[N_k^{(2)}] = (a_k + b_k)^2 + \frac{a_k^2}{\alpha},
\]

and

\[
\mathbb{E}[N_1 N_2] = (a_1 + b_1)(a_2 + b_2) + \frac{a_1 a_2}{\alpha}.
\]

The characteristic function of \( S_N \) is

\[
\psi_{S_N}(t_1, t_2) = \exp \left( b_1(\psi_{X_1}(t_1) - 1) + b_2(\psi_{X_2}(t_2) - 1) \right) + \left( \frac{\alpha}{\alpha - a_1(\psi_{X_1}(t_1) - 1) - a_2(\psi_{X_2}(t_2) - 1)} \right)^\alpha
\]

\[(5.8)\]

Some results for this model related to steps (i) and (ii) of Computation Procedure 5.1 are given in the following.

**Step (i):** By Theorem 4.3, the distributions of \( L^{[1]}, L^{[2]}, L^{[1][2]}, L^{[2][2]}, \) and \( L^{[1,2]} \) are all mixtures of Poisson-gamma mixtures.

**Step (ii):** Because of the above, the characteristic function of \( S_L \) can be determined and the distribution function can be calculated using FFT.

The capital allocation computations are carried out with \( a_1 = 0.2, a_2 = 0.4, b_1 = 1, b_2 = 2, \alpha = 2, X_1 \sim \text{Poisson}(5) \) and \( X_2 \sim \text{Poisson}(1) \). Figure 4 illustrates the results.
5.4. Findings of the numerical examples and other computational issues

In all of the three numerical examples we studied, the parameters are set such that BI claims are less frequent but more severe. The results show that, according to TCE allocation rule, the proportion of risk allocated to BI (PD) claims increases (decreases) with respect to the threshold level \( s_q \). According to TV allocation principle, the proportion allocated to BI claims first decreases and then increases. The opposite pattern is observed for PD claims. For all the cases, the proportions allocated to the two types of risk seem to converge to some constant as \( s_q \) goes to infinity.

We only provide examples that consider two types of risks. Computations are implemented using the software R (R Core Team, 2016). However, the formulas derived in Sections 3 and 4 are valid for compound variables of any finite dimension \( K \). Nevertheless, the distribution of \( S_N \) and its moment transform still need to be evaluated by multivariate recursive or FFT method, which may lead to numerical problems when \( K \) is very large. Exploring the behavior of the computational aspects of our model for the high-dimensional problem may be a good topic for future research.

It is worth pointing out that our Equations (3.15)–(3.19) in fact lead to a novel approach to simulate the tail moments and perform the capital allocations. Particularly, instead of simulating the tail moments directly, one can simulate the ratio between the tail probabilities of the moment transformed distributions.

6. Conclusions

This paper presents the formulas for computing the multivariate TCE and TV for some types of multivariate compound distributions where the claim frequencies are dependent and the claim sizes are independent. We focus on the three important types of dependence models introduced in Hesselager (1996) and their extensions. The formulas are derived based on the moment transform.
of multivariate compound distributions, as discussed in Denuit and Robert (2021) and the references therein.

As shown in Section 4.4, the methodology can be extended to the cases where the claim frequencies and claim sizes are dependent through a common shock. For future research, one could investigate whether such methodology can be applied to compute the risk measures of compound variables with more complicated dependence structures.

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