#### PROBLEMS FOR SOLUTION

- P. 146. (i) Let  $n_1 < n_2 < \ldots$  be an infinite sequence of integers such that  $\sigma(n_i) n_i$  is a constant, where  $\sigma(n)$  is the sum of the divisors of n. Prove that each  $n_i$  is prime.
- (ii) For each  $k \ge 1$ , show that there exist integers  $n_1 < n_2 < \ldots < n_k$ , none of which is a prime, such that  $\sigma(n_i) n_i$  is constant.

P. Erdős

<u>P. 147</u>. Let p be a prime with  $p \equiv 1 \pmod{3}$ . Prove that  $(x+1)^p - x^p - 1 \equiv 0 \pmod{p^3}$  has at least two solutions in the range  $1 \le x \le p - 1$ .

H.A. Heilbronn, University of Toronto

 $\underline{P. 148}$ . Let X be a locally separable connected metric space. Prove that X is separable. Is this true if X is not metric?

J. Marsden, University of California, Berkeley

#### SOLUTIONS

 $\underline{P.~136}$ . Find a topological space X which is  $T_o$  and such that Y' fails to be closed for at least one subset Y of X. (Here Y' denotes the set of all accumulation points of Y.)

P.A. Pittas, Dalhousie University

### Solution by J. Marsden, University of California, Berkeley

Let  $X = \{x_1, x_2, \ldots\} \cup \{x\}$  with topology  $\{U_n = \{x_k : k \ge n\} \cup \{x\}\}$ . This space is  $T_0$  but not  $T_1$ . Let  $Y = \{x\}$ . Then  $Y' = \{x_1, x_2, \ldots\}$  which is not a closed set.

Also solved by J.B. Wilker and the proposer. Both Marsden and the proposer pointed out that such an X is necessarily infinite.

 $\underline{P.\ 137}$ . If X is a complete metric space and T is a contraction in X, then T has a unique fixed point. This fails to hold if T has only the property d(Tx, Ty) < d(x, y).

K.L., Singh, Memorial University

# Solution by P. Ewer, St. Mary's University, Halifax

The subspace  $X=[1,\infty)$  of the real line is complete. Let T be defined by  $T_x=x+\frac{1}{x}$ . Then certainly T leaves no point of X fixed. Suppose  $x, y \in X$  and x < y. Then

$$d(T_x, T_y) = (y - x) - (\frac{1}{x} - \frac{1}{y}) < d(x, y)$$
.

Also solved by S. Aalto, J.A. Baker, D. Lind, J. Marsden, J.B. Wilker and the proposer.

In general it is clear that such a T has at most one fixed point, and J. Marsden points out that a fixed point does exist when one assumes that X is compact. For a new proof that a contractive T has a fixed point see the note, Another Proof of the Contraction Mapping Principle by Boyd and Wong to appear in this section of the Bulletin.

P. 138. Prove that the set S is finite if and only if there is a permutation  $\pi$  of S such that no proper non-empty subset S' has the property  $\pi(S') \not\subseteq S'$ .

J. Marcia, University of Calgary

#### Solution by D. Lind, Cambridge University

If S is finite, a cyclic permutation  $\pi$  of S has the property that  $\pi(S')\subset S'$  for all non-empty proper subsets S' of S. Conversely, suppose S is infinite, and let  $X\in S$ . For a permutation  $\pi$  of S, put  $S'=\bigcup_{n=0}^{\infty} \pi^n(\chi). \text{ Then } \pi(S')\subset S'. \text{ If } S'=S, \text{ then } \pi^{-1}(\chi)=\pi^k(\chi)$ 

for some  $k \ge 0$ , so S is finite, a contradiction. Hence S' is a non-empty proper subset of S.

Also solved by W.D. Jackson, J. Schaer, J.B. Wilker and the proposer.

P. 139. Prove  $S(a, b) = (a - b)^{n-1}$  [aS(1, 0) - bS(0, -1)] where S(a, b) = determinant of a matrix of order n in which each element is either a or b.

K. Schmidt, University of Manitoba

### Solution by S. Spital, California State College

Let the subtraction of the first row of S(a, b) from the remaining rows be indicated by

$$S(a, b) = T$$
  $\begin{pmatrix} a, b \\ a-b, 0, b-a \end{pmatrix}$ 

where the upper two arguments identify the entries in the first row, and the lower three the entries in the remaining n-1 by n block. The required result now follows from well known properties of determinants:

$$T\begin{pmatrix} a, b \\ a-b, 0, b-a \end{pmatrix} = (a-b)^{n-1} T\begin{pmatrix} a, b \\ 1, 0, -1 \end{pmatrix}$$

a S (1,0) - b S(0, -1) = T 
$$\begin{pmatrix} a, 0 \\ 1, 0, -1 \end{pmatrix}$$
 + T  $\begin{pmatrix} 0, b \\ 1, 0, -1 \end{pmatrix}$  = T  $\begin{pmatrix} a, b \\ 1, 0, -1 \end{pmatrix}$ .

Also solved by L. Carlitz, R.C. Mullin and E. Nemeth (jointly), J.B. Wilker and the proposer.

P. 140. Every integral two by two matrix is a sum of three squares; and the number three is best possible.

I. Connell, McGill University

# Solution by L. Carlitz, Duke University

1. Put 
$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$
. Consider
$$A - \begin{bmatrix} x & b \\ c & 1-x \end{bmatrix}^2 = A - \begin{bmatrix} x^2 + bc & b \\ c & (1-x)^2 + bc \end{bmatrix} = \begin{bmatrix} a - x^2 - bc & 0 \\ 0 & d - (1-x)^2 - bc \end{bmatrix}.$$

We can choose x so that

$$a - x^2 - bc = d - (1 - x)^2 - bc$$

that is 2x = a - d + 1, provided  $a \equiv d + 1 \pmod{2}$ . Since

$$\begin{bmatrix} u & 0 \\ 0 & u \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ u & 0 \end{bmatrix}^2 ,$$

it follows that A is a sum of two squares when a - d is odd. If a - d is even, we have

$$\mathbf{A} = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}^2 + \begin{bmatrix} \mathbf{a} - 1 & \mathbf{b} \\ \mathbf{c} & \mathbf{d} \end{bmatrix},$$

which is evidently a sum of three squares. Thus every A is a sum of at most three squares.

#### 2. We show now that if

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \equiv \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \pmod{2}$$

and  $a \equiv d + 2 \pmod{4}$ , A is not a sum of two squares. Assume

(1) 
$$A = \begin{bmatrix} x & y \\ z & x^{1} \end{bmatrix}^{2} + \begin{bmatrix} t & u \\ v & t^{1} \end{bmatrix}^{2},$$

so that

$$x^{2} + yz + t^{2} + uv = a$$
  
 $y(x + x') + u(t + t') = b$   
 $z(x + x') + v(t + t') = c$   
 $x^{2} + yz + t^{2} + uv = d$ .

Subtracting the fourth equation from the first we get

$$x^2 + t^2 = a - d + x'^2 + t'^2$$
.

Since  $a - d = 2 \pmod{4}$  it follows that either

(i) 
$$x \equiv t \equiv 1$$
,  $x' \equiv t' \equiv 0$  or (ii)  $x \equiv t \equiv 0$ ,  $x' \equiv t' \equiv 1 \pmod{2}$ .

In either case we have

$$x + x' \equiv t + t' \equiv 1 \pmod{2}$$
.

It follows that

(2) 
$$y + u \equiv b \equiv 0, z + v \equiv c \equiv 0 \pmod{2}$$
.

On the other hand

$$x^2 + yz + t^2 + uv \equiv yz + uv \equiv a \pmod{2}$$
,

so that

(3) 
$$yz + uv \equiv 1 \pmod{2}$$
.

But, by (2),  $u \equiv y$ ,  $v \equiv z \pmod{2}$ , which contradicts (3). Hence (1) is impossible.

3. We shall now show that in all other cases A is a sum of two squares. We consider first the case

$$a - d \equiv 2 \pmod{4}$$

and either b or c (or both) odd.

Put

(4) 
$$a - d + 2 = 4e$$
.

We show that

(5) 
$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} e & y \\ z & 1 - e \end{bmatrix}^2 + \begin{bmatrix} e & u \\ v & 1 - e \end{bmatrix}^2,$$

that is

$$2e^{2}$$
 + yz + uv = a  
y + u = b  
z + v = c  
 $2(1-e)^{2}$  + yz + uv = d.

Subtracting the fourth equation from the first, we get 4e - 2 = a - d, in agreement with (4). Thus the fourth equation can be ignored. Eliminating u and v, we get

$$yz + (b - y) (c - z) + 2e^2 = a$$

or

$$(2y - b) (2z - c) + bc + 4e^2 = 2a$$
.

Now assume c odd and take z = (c + 1)/2.

Then

$$2y + b(c - 1) + 4e^2 = 2a$$
,

so that y is determined.

4. Finally, we take  $a \equiv d \pmod{4}$ . If  $b \equiv c \equiv 0 \pmod{2}$ , consider

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} - \begin{bmatrix} x & b/2 \\ c/2 & 2-x \end{bmatrix}^2 = \begin{bmatrix} a - x^2 - bc/4 & 0 \\ 0 & d - (2-x)^2 - bc/4 \end{bmatrix}$$

This is of the form

$$\begin{bmatrix} \mathbf{u} & \mathbf{0} \\ \mathbf{0} & \mathbf{u} \end{bmatrix} = \begin{bmatrix} \mathbf{0} & \mathbf{1} \\ \mathbf{u} & \mathbf{0} \end{bmatrix}^2$$

if 4x = a - d + 4.

Hence assume b or c odd. Put a - d = 4e. Take

$$x + x' = t + t' = 1$$
.

Consider

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} e & y \\ z & 1 - e \end{bmatrix}^2 + \begin{bmatrix} e+1 & u \\ v & -e \end{bmatrix}^2,$$

that is

$$e^{2} + (e + 1)^{2} + yz + uv = a$$
 $y + u = b$ 
 $z + v = c$ 
 $e^{2} + (1 - e)^{2} + yz + uv = d$ 

Subtracting the fourth from the first we get 4e = a - d. Eliminating u, v we get

$$e^{2} + (e + 1)^{2} + yz + (b - y) (c - z) = a$$

or

$$(2y - b) (2z - c) + bc + 2e^{2} + 2(e + 1)^{2} = 2a$$
.

If c is odd, take 2z = c + 1, so that

$$2y + b(c - 1) + 2e^{2} + 2(e + 1)^{2} = 2a$$

thus determining y.

To sum up, every  $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$  is a sum of at most three squares.

Two squares will suffice unless

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} \equiv \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \pmod{2}$$

and  $a \equiv d + 2 \pmod{4}$ .

Editor's comment: One case is omitted in the above analysis: each of a, b, c, d is even, say  $a=2a_1$ , etc., and  $a-d\equiv 2 \mod 4$ ; but this can be dealt with as in paragraph 3 above. We arrive at the equation  $(2y-b)(2z-c)+bc+4e^2=2a$ , or,  $(y-b_1)(z-c_1)+b_1c_1+e^2=a_1$ , and we may take  $z=c_1+1$ , thus obtaining y.

Also solved, but not completely as in the above solution, by  $J.\,B.$  Wilker and the proposer.