

THE FRECHET DIFFERENTIAL OF A PRIMARY MATRIX FUNCTION

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Let X be a given complex matrix of order n . If $f(z)$ is analytic at the eigenvalues of X , one may define the primary matrix function $f(X)$ with stem function $f(z)$ by using any of several well-known methods: for instance, canonical forms, power series, or interpolating polynomials [9]. The Frechet differential of the primary matrix function f at X , evaluated for the "increment" H , is written $df(X; H)$ and is defined [1, p. 143] to be the unique linear function of H which satisfies

$$\|f(X + H) - f(X) - df(X; H)\| = o(\|H\|).$$

If H commutes with X it is known [6] that $df(X; H) = Hf^{(1)}(X)$. (Throughout this paper, $f^{(k)}(X)$ denotes the primary matrix function with stem function $f^{(k)}(z)$.) Several attempts have been made to find a similarly satisfying expression for the differential under less restrictive conditions [7; 11], but these have had only partial success because of the reliance on canonical forms to represent $f(X)$. The results of these investigations and the important role of commutativity motivate the following.

Definition. The successive commutes, or inner derivatives, of H with respect to X are defined by: $H_{(0)} = H$ and $H_{(k)} = H_{(k-1)}X - XH_{(k-1)}$ for $k \geq 1$.

In [12] Roth investigated commutes in detail, and some additional information will be found in [3].

As we shall be dealing with linear functions on matrices, it is convenient to use some notation and results of Neudecker [4]. Let the columns of the $n \times n$ matrix H be h_1, h_2, \dots, h_n . We define an isomorphism between the $n \times n$ matrices and the $n^2 \times 1$ matrices by $\text{vec } H = [h_1^T, h_2^T, \dots, h_n^T]^T$. It can be shown that

$$\text{vec}(XH) = (I \times X) \text{vec } H, \quad \text{vec}(HX) = (X^T \times I) \text{vec } H$$

where \times denotes the Kronecker product. By induction, we find that $\text{vec } H_{(k)} = (X^T \times I - I \times X)^k \text{vec } H$ with the convention that the zeroth power of a square matrix is the identity.

In this notation, it is easy to prove that

$$(1) \quad e^{-X} H e^X = \sum_{n=0}^{\infty} \frac{1}{n!} H_{(n)}.$$

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Proof. $\text{vec}(e^{-X}He^X) = [(e^X)^T \times e^{-X}] \text{vec } H$. But

$$(e^X)^T \times e^{-X} = \exp(X^T \times I - I \times X).$$

(See [4].) Thus,

$$\begin{aligned} \text{vec}(e^{-X}He^X) &= \sum_{n=0}^{\infty} \frac{1}{n!} (X^T \times I - I \times X)^n \text{vec } H \\ &= \sum_{n=0}^{\infty} \frac{1}{n!} \text{vec } H_{(n)}. \end{aligned}$$

A second identity which will be needed is

$$(2) \quad X^{r-1}H + X^{r-2}HX + \dots + HX^{r-1} = \sum_{s=1}^r \binom{r}{s} X^{r-s}H_{(s-1)}$$

The proof of (2) will be found in reference [3].

This latter formula, in fact, is the Frechet differential of the function $f(X) = X^r$. For, if $(X + H)^r - X^r$ is expanded, the terms which are linear in H are precisely the left-hand side of (2). From this point, we may pass to the first representation for a Frechet differential.

THEOREM 1. *Let $f(z) = \sum_{r=0}^{\infty} a_r(z - c)^r$ be analytic in a disk of centre c and radius R . Let $\rho + \sigma < R$, where ρ and σ are respectively the spectral radii of $X - cI$ and $X^T \times I - I \times X$. Then*

$$(3) \quad df(X; H) = \sum_{s=1}^{\infty} \frac{1}{s!} f^{(s)}(X)H_{(s-1)}.$$

Proof. We may safely assume that $c = 0$ and that a norm has been chosen to make $\|X\| = \rho + \epsilon < R - \sigma$. Define $g(x) = \sum_{r=1}^{\infty} |a_r| \xi^r$, and take H so small that this series converges at $\xi_1 = \|X\| + \|H\|$. Then the series for $f(X + H)$ converges absolutely, and

$$\begin{aligned} f(X + H) - f(X) &= \sum_{r=1}^{\infty} a_r[(X + H)^r - X^r] \\ &= \sum_{r=1}^{\infty} a_r[X^{r-1}H + X^{r-2}HX + \dots + HX^{r-1}] + o(\|H\|). \end{aligned}$$

The remainder on the right, containing terms of order two or higher in H , is bounded in norm by $\|H\|^2 g''(\xi_1)$. The differential is transformed formally, using (2), as follows:

$$\begin{aligned} df(X; H) &= \sum_{r=1}^{\infty} a_r[X^{r-1}H + X^{r-2}HX + \dots + HX^{r-1}] \\ &= \sum_{r=1}^{\infty} a_r \sum_{s=1}^r \binom{r}{s} X^{r-s}H_{(s-1)} \\ (*) \quad &= \sum_{s=1}^{\infty} \sum_{r=s}^{\infty} a_r \binom{r}{s} X^{r-s}H_{(s-1)} \\ &= \sum_{s=1}^{\infty} \frac{1}{s!} f^{(s)}(X)H_{(s-1)}. \end{aligned}$$

The rearrangement of the series is justified because, in the starred line, the inner sum is bounded in norm by $(s!)^{-1}g^{(s)}(\rho + \epsilon)$, and

$$\limsup |||H_{(\nu-1)}|||^{1/\nu} \leq \sigma < R - \rho - \epsilon.$$

A special case of (3) was discovered and used by Fer [2] in the iterative solution of the matrix equation: $\dot{U} = H(t)U, U(0) = I$. He sets $U = e^X V$, where

$$X(t) = \int_0^t H(\tau)d\tau.$$

Since

$$(d/dt)f(X) = df(X; (d/dt)X) = df(X, H)$$

(see [1]), the time derivative of e^X is found to be, using (1),

$$\begin{aligned} (d/dt)e^X &= e^X \sum_{s=1}^{\infty} \frac{1}{s!} H_{(s-1)} \\ &= He^X - e^X \sum_{s=1}^{\infty} \frac{s}{(s+1)!} H_{(s)}. \end{aligned}$$

Thus the matrix $V(t)$ satisfies

$$\dot{V} = \left[\sum_{s=1}^{\infty} \frac{s}{(s+1)!} H_{(s)} \right] V, V(0) = I$$

in which the coefficient of V vanishes with t at $t = 0$.

When H is required to satisfy some restriction relative to X , the hypotheses on the function can be relaxed, as follows.

COROLLARY 1 (Roth [12]). *Let P be a nonsingular matrix such that $P^{-1}XP = (\lambda_1 I + N_1) \oplus \dots \oplus (\lambda_m I + N_m)$, where $\lambda_i \neq \lambda_j$ if $i \neq j$, and each N_i is nilpotent. If H is such that $P^{-1}HP = H_1 \oplus \dots \oplus H_m$, where H_i is of the same order as $\lambda_i I + N_i$, then $H_{(k)} = 0$ for some k . If f is analytic at the eigenvalues of X , then*

$$df(X; H) = \sum_{s=1}^k \frac{1}{s!} f^{(s)}(X)H_{(s-1)}.$$

It is easily shown that $k \leq 2\mu - 1$, μ being the greatest of the multiplicities of roots of the minimum equation of X . Thus for a diagonalizable X , $k = 1$ and the assumption is that H commutes with X .

A different sort of restriction on H can also provide a simplified representation for the differential.

LEMMA 1. *Let f be analytic at the eigenvalues of X , and let $H = MX - XM$ for some M . Then*

$$df(X; H) = Mf(X) - f(X)M.$$

Proof. Assume first that M is specified by

$$\text{vec } M = (X^T \times I - I \times X)^+ \text{vec } H$$

where $+$ denotes the Moore-Penrose generalized inverse [5], so that H and M are of the same order as H vanishes. Using the power series expansion for matrix exponentials, we find that

$$\begin{aligned} e^{-M}(X + H)e^M &= (I - M + \dots)(X + H)(I + M + \dots) \\ &= X + H - MX + XM + o(\|H\|) \\ &= X + o(\|H\|). \end{aligned}$$

As $f(X)$ has a Frechet derivative [10], it satisfies a Lipschitz condition at X [1, p. 155]. Hence

$$\begin{aligned} f(X + H) &= e^M f(e^{-M}(X + H)e^M) e^{-M} \\ &= e^M f(X + o(\|H\|)) e^{-M} \\ &= e^M f(X) e^{-M} + o(\|H\|). \end{aligned}$$

Again employing the power series expansion for the exponential, and isolating the first order terms, yields

$$\begin{aligned} f(X + H) - f(X) &= f(X) + Mf(X) - f(X)M - f(X) + o(\|H\|) \\ &= Mf(X) - f(X)M + o(\|H\|). \end{aligned}$$

Thus the lemma is proved for the special choice of M . In general, M may be expressed as $M = M_1 + M_2$, where M_1 is as above and M_2 commutes with X ; but then M_2 also commutes with $f(X)$. Hence the lemma holds in general.

Roth proves a similar theorem under more restrictive hypotheses and by different means [12]. For stem functions analytic in a sufficiently large region, application of (3) gives an alternate proof.

An immediate application of the Lemma can be made to the approximation of $f(Z)$ if $Z = [z_{ij}]$ has distinct diagonal entries. Set $X = \text{diag}\{z_{11}, \dots, z_{nn}\}$, so $f(Z) \simeq f(X) + df(X; Z - X) = [\phi_{ij}]$. The elements ϕ_{ij} are given by $\phi_{ii} = f(z_{ii})$ and, for $i \neq j$,

$$\phi_{ij} = z_{ij} \frac{f(z_{ii}) - f(z_{jj})}{z_{ii} - z_{jj}}.$$

This approximation would have been useful in [13] where Z is a Ritz matrix and $f(z) = (z)^{-\frac{1}{2}} \tanh(z^{\frac{1}{2}})$.

We shall now show that the two different restrictions on H mentioned in the Corollary and Lemma 1 are complementary.

LEMMA 2. *For any matrix H of order n , there exist matrices L and M satisfying: $H = L + MX - XM$, and $L_{(k)} = 0$ for some k .*

Proof. Let $P^{-1}XP = (\lambda_1 I + N_1) \oplus \dots \oplus (\lambda_m I + N_m)$ as in Corollary 1. Let $P^{-1}HP = [H_{ij}]$, $P^{-1}LP = [L_{ij}]$, $P^{-1}MP = [M_{ij}]$ be partitioned conformally with $P^{-1}XP$. In order that $L_{(k)} = 0$ for some k , $L_{ij} = 0$ ($i \neq j$) is necessary and sufficient [12]. The equations to be satisfied are thus:

$$(4) \quad M_{ij}(\lambda_j I + N_j) - (\lambda_i I + N_i)M_{ij} = H_{ij} \quad (i \neq j),$$

$$(5) \quad L_{ii} = H_{ii} - M_{ii}N_i + N_iM_{ii}.$$

The submatrices M_{ii} are, in fact, arbitrary but we shall take them to be 0. Equation (4) determines M_{ij} uniquely, since $\lambda_i \neq \lambda_j$ for $i \neq j$ [4]. We also note that M is of the same order as H when H vanishes.

By combining the Lemmas and the Corollary, and using the linearity of the Frechet differential, one easily proves the principal representation below.

THEOREM 2. *Let $f(z)$ be analytic at the eigenvalues of X . Let $H = L + MX - XM$, where $L_{(k)} = 0$ for some k . Then*

$$df(X; H) = Mf(X) - f(X)M + \sum_{s=1}^k \frac{1}{s!} f^{(s)}(X)L_{(s-1)}.$$

Several derivatives for functions of matrices have been defined by limit processes [8; 10]. It is also possible to obtain the Frechet differential via a limit.

THEOREM 3. *For sufficiently small $\epsilon \neq 0$, let $S = S(\epsilon)$ be defined by $SX - XS + \epsilon S = H$, and let $f(z)$ be analytic at the eigenvalues of X . Then*

$$(6) \quad df(X; H) = \lim_{\epsilon \rightarrow 0} \left[Sf(X) - f(X)S + \epsilon \sum_{r=1}^{2n-1} \frac{1}{r!} f^{(r)}(X)S_{(r-1)} \right].$$

Proof. For $\epsilon \neq 0$ and sufficiently small, S exists and is unique. By substitution one verifies that

$$S(\epsilon) = M - \sum_{m=1}^{2n-1} (-\epsilon)^{-m} L_{(m-1)} + O(\epsilon)$$

where L and M are as in Lemma 2, and that the quantity in brackets in (6) is $df(X; H) + O(\epsilon)$. The upper limit in the sums may be reduced if more is known about the matrix X .

The Frechet derivative, that is, the linear function $H \rightarrow df(X; H)$, may be realized as a matrix of order n^2 if H and $df(X; H)$ are replaced by their images under “vec”. We replace $X^T \times I - I \times X$ by Δ for brevity.

THEOREM 4. *Under the conditions of Theorem 1, 2, or 3, the Frechet derivative of f at X is*

$$(Th 1) \quad \sum_{r=1}^{\infty} \frac{1}{r!} [I \times f^{(r)}(X)] \Delta^{r-1},$$

$$(Th 2) \quad [f(X^T) \times I - I \times f(X)] \Gamma + \sum_{r=1}^k \frac{1}{r!} [I \times f^{(r)}(X)] \Delta^{r-1} \Pi$$

where Γ is any matrix having the property that $\Delta^{k+1} \Gamma = \Delta^k$ for some integer k , and $\Pi \equiv I - \Delta \Gamma$, or

$$(Th 3) \quad \lim_{\epsilon \rightarrow 0} \left\{ \left[f(X^T) \times I - I \times f(X) + \epsilon \sum_{r=1}^{2n-1} \frac{1}{r!} (I \times f^{(r)}(X)) \Delta^{r-1} \right] (\Delta + \epsilon I)^{-1} \right\}.$$

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