# THE NONEXISTENGE OF CERTAIN FINITE PROJECTIVE PLANES 

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1. Introduction. A projective plane geometry $\pi$ is a mathematical system composed of undefined elements called points and undefined sets of points (at least two in number) called lines, subject to the following three postulates:
$\left(\mathrm{P}_{1}\right)$ Two distinct points are contained in a unique line.
$\left(\mathrm{P}_{2}\right)$ Two distinct lines contain a unique common point.
$\left(\mathrm{P}_{3}\right)$ Each line contains at least three points.
The projective plane $\pi$ is finite if it consists of a finite number of points. If $\pi$ is finite, then there exists a positive integer $N$ such that each line of $\pi$ contains exactly $N+1$ distinct points, and each point is contained in exactly $N+1$ distinct lines. Moreover, $\pi$ has exactly $N^{2}+N+1$ distinct points and $N^{2}+N+1$ distinct lines (see [3], [6], [13]).

In all known finite geometries the integer $N$ is a power of a prime. Indeed, for every prime $p$ and for every positive integer $n$, finite geometries with $N=p^{n}$ have been constructed by means of the Galois fields GF[ $p^{n}$ ] (see [12]). It is still an unsettled question whether or not $N$ must be the power of a prime. In this connection it has been shown that there does not exist a finite geometry for $N=6$ (see [11]). The purpose of our paper is to prove the following more general theorem on the non-existence of finite geometries.

Theorem 1. If $N \equiv 1$ or $2 \bmod 4$ and if the square free part of $N$ contains at least one prime factor of the form $4 k+3$, then there does not exist a finite projective plane geometry with $N+1$ points on a line.

In section 2 finite geometries are studied in connection with matrices whose elements are non-negative integers. The Minkowski-Hasse theory on the equivalence of quadratic forms under rational transformations is discussed in section 3, and the results of sections 2 and 3 are then utilized in section 4 to prove Theorem 1.

It is to be noted that Theorem 1 asserts in particular that a geometry does not exist for $N=2 p$, where $p$ is a prime of the form $4 k+3$. Moreover, a finite plane with $N+1$ points on a line can always be constructed from a given complete set of mutually orthogonal Latin squares of order $N \geqq 3$ (see [1], [8]). Thus for any $N$ of Theorem 1 there does not exist a complete set of mutually orthogonal Latin squares of order $N$.
2. The Incidence Matrix. An $n$-rowed square matrix $A$ each of whose elements is zero or one is an incidence matrix provided it satisfies the following three conditions:

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( $\mathrm{I}_{1}$ ) If $r_{1}$ and $r_{2}$ are two distinct rows of $A$, then there is a unique integer $j$ such that the rows $r_{1}$ and $r_{2}$ each have the integer one in the $j$ th column.
( $\mathrm{I}_{2}$ ) If $c_{1}$ and $c_{2}$ are two distinct columns of $A$, then there is a unique integer $i$ such that the columns $c_{1}$ and $c_{2}$ each have the integer one in the $i$ th row.
( $\mathrm{I}_{3}$ ) Each row of $A$ contains at least three ones.
Theorem 2. If $\pi$ is a finite projective plane geometry with $N+1$ points on a line, then there exists an incidence matrix $A$ of order $n=N^{2}+N+1$. If $A^{\mathrm{T}}$ denotes the transpose of the matrix $A$, then

$$
\begin{equation*}
B=A A^{\mathrm{T}}=A^{\mathrm{T}} A \tag{M}
\end{equation*}
$$

where $B$ is an integral matrix with $N+1$ down the main diagonal and ones in all other positions.

For let the $N^{2}+N+1$ points of $\pi$ be numbered in any convenient order $1,2, \ldots, N^{2}+N+1$ and listed in a row. Let the $N^{2}+N+1$ lines be numbered similarly $1,2, \ldots, N^{2}+N+1$ and listed in a column. Then let a table of $N^{2}+N+1$ rows and $N^{2}+N+1$ columns be formed by inserting a one in row $i$ and column $j$ if line $i$ contains point $j$, and a zero in the contrary case. Then by the properties of the geometry $\pi$ given in section 1, it follows that the table yields an incidence matrix $A$ which satisfies the equation (M).

Theorem 3. If a matrix $A$ with non-negative integral elements and of order $n>1$ satisfies the equation (M), where $N \geqq 2$, then $A$ is an incidence matrix and defines a finite projective plane geometry with $N+1$ points on a line.

The matrix $A$ must be composed entirely of zeros and ones. For if $a_{i j}$ were an element of $A$ in row $i$ and column $j$ and if $a_{i j}$ were greater than one, then by equation (M) each element in column $j$ of $A$ except $a_{i j}$ would be zero. Moreover, each element in row $i$ of $A$ except $a_{i j}$ would also be zero. But then the matrix $A A^{\mathrm{T}}$ would contain a zero element, and this is impossible if $A$ is to satisfy (M). Since $A$ is composed of zeros and ones and since $A$ satisfies (M) with $N \geqq 2$, it follows that $A$ is an incidence matrix, and this incidence matrix can be used to define the finite projective plane.
3. Congruence of Matrices. Let $A$ and $B$ be two symmetric matrices of order $n$ with elements in the rational field. The matrices $A$ and $B$ are congruent, written $A \sim B$, provided there exists a non-singular matrix $C$ with rational elements such that

$$
A=C^{\mathrm{T}} B C
$$

It is easy to show that congruence of matrices satisfies the usual requirements of an equals relationship.

Suppose now that $A$ is an integral symmetric matrix of order and rank $n$. It is well known that one can always construct an integral diagonal matrix $D=\left[d_{1}, d_{2}, \ldots, d_{n}\right]$, where $d_{i} \neq 0$ for $i=1,2, \ldots, n$, such that $D \sim A$.

The number of negative terms $\iota$ in this diagonal is called the index of $A$. Sylvester's law of inertia states that $\iota$ is an invariant of $A$ (see [7]).

Let $d=(-1)^{c} \delta$, where $\delta$ is the square free positive part of the determinant $|A|$ of the matrix $A$. From the matric equation $B=C^{\mathrm{T}} A C$, it follows that $|B|=|C|^{2}|A|$. Hence $d$ is a second invariant of $A$.

Minkowski [9] and Hasse [4] have introduced a third invariant $c_{p}$, which with the preceding two completes the system. Before discussing the invariant $c_{p}$, we recall now the essentials of the Hilbert norm-residue symbol $(m, n)_{p}$. The norm-residue symbol is defined for arbitrary non-zero integers $m$ and $n$ and for every prime $p$. Its precise definition as well as complete proofs of the following two theorems can be found in the collected works of Hilbert [5].

Theorem 4. If $m$ and $n$ are integers not divisible by the odd prime $p$, then

$$
\begin{equation*}
(m, n)_{p}=+1 \tag{1}
\end{equation*}
$$

$$
\begin{equation*}
(n, p)_{p}=(p, n)_{p}=(n \mid p) \tag{2}
\end{equation*}
$$

where $(n \mid p)$ is the Legendre symbol. Moreover, if $n \equiv m \neq 0 \bmod p$, then

$$
\begin{equation*}
(m, p)_{p}=(n, p)_{p} \tag{3}
\end{equation*}
$$

Theorem 5. For arbitrary non-zero integers $m, m^{\prime}, n, n^{\prime}$ and for every prime $p$,

$$
\begin{gather*}
(-n, n)_{p}=+1  \tag{4}\\
(m, n)_{p}=(n, m)_{p},  \tag{5}\\
\left(m m^{\prime}, n\right)_{p}=(m, n)_{p}\left(m^{\prime}, n\right)_{p},  \tag{6}\\
\left(n, m m^{\prime}\right)_{p}=(n, m)_{p}\left(n, m^{\prime}\right) p \tag{7}
\end{gather*}
$$

At this point it is convenient to prove a Lemma which is useful for the proof of Theorem 1 in section 4.

Lemma. For $p$ an odd prime and for every positive integer $n$,

$$
\begin{gather*}
(n, n+1)_{p}=(-1, n+1)_{p}  \tag{8}\\
\left(n, n^{2}+n+1\right)_{p}=+1  \tag{9}\\
\prod_{i=1}^{n}(i, i+1)_{p}=((n+1)!,-1)_{p} \tag{10}
\end{gather*}
$$

If $p$ does not divide $n$ or $n+1$, then (8) is trivial. If $p$ divides $n$, then $n+1 \equiv 1 \bmod p$ and if $p$ divides $n+1$, then $n \equiv-1 \bmod p . \quad$ By (3) of Theorem 4 equation (8) is established. If $p$ divides $n$, then $n^{2}+n+1 \equiv$ $(n+1)^{2} \not \equiv 0 \bmod p$ and if $p$ divides $n^{2}+n+1$, then $n \equiv(n+1)^{2} \neq 0$ $\bmod p$. This establishes (9). Equation (10) is a consequence of (8) and Theorem 5.

Now let $A$ be a non-singular and symmetric integral matrix of order $n$. Let $D_{r}$ denote the leading principal minor determinant of order $r$, and suppose that $D_{r} \neq 0$ for $r=1,2, \ldots, n$. The invariant $c_{p}$ is then defined for every odd prime $p$ by the equation

$$
c_{p}=c_{p}(A)=\left(-1,-D_{n}\right)_{p} \prod_{i=1}^{n-1}\left(D_{i},-D_{i+1}\right)_{p}
$$

By (1) of Theorem 4, evidently $c_{p}=-1$ for only a finite number of $p$.

We are now in a position to state the fundamental Minkowski-Hasse theorem, a proof of which can be found in the original paper of Hasse [4]. More recent developments of the theory are discussed in [2] and [10].

Theorem 6. Let $A$ and $B$ be two integral symmetric matrices of order and rank $n$. Suppose further that the leading principal minor determinants of $A$ and $B$ are different from zero. Then $A \sim B$ if and only if $A$ and $B$ have the same invariants $\iota, d$, and $c_{p}$ for every odd prime $p$.
4. Proof of Theorem 1. Let $N$ be a positive integer and let $B_{n}$ denote the integral matrix of order $n$ with $N+1$ down the main diagonal and ones in all other positions. If we subtract column one of $B_{n}$ from each of the other columns, and then add to row one each of the other rows, we obtain

$$
\left|B_{n}\right|=N^{n-1}(N+n)
$$

In particular if $n=N^{2}+N+1$, then $B_{n}$ is the matrix $B$ of equation (M) and $|B|$ is the square of an integer.

If row $n$ of $B_{n}$ is subtracted from each of the other rows, and if column $n$ is then subtracted from each of the other columns, the resulting matrix is

$$
Q_{n}=\left[\begin{array}{ccccc}
2 N & N & N & \cdots & -N \\
N & 2 N & N & \cdots & -N \\
N & N & 2 N & \cdots & -N \\
\cdot & \cdot & \cdot & & \cdot \\
\cdot & \cdot & \cdot & & \cdot \\
\cdot & \cdot & \cdot & & \cdot \\
-N & -N & -N & \cdots & N+1
\end{array}\right]
$$

and this matrix is congruent to $B_{n}$. Hence for every odd prime $p, c_{p}\left(B_{n}\right)=$ $c_{p}\left(Q_{n}\right)$. Moreover, if $E_{i}$ denotes the determinant of order $i$ with $2 N$ down the main diagonal and $N$ in all other positions, then $E_{i}=N^{i}(i+1)$. Thus if $n=N^{2}+N+1$ and if $p$ is an odd prime, then the invariant $c_{p}(B)=$ $c_{p}\left(Q_{n}\right)$ of the matrix $B$ of equation (M) is given by

$$
c_{p}(B)=\left(E_{n-1},-1\right)_{p} \prod_{i=1}^{n-2}\left(E_{i},-E_{i+1}\right)_{p}
$$

In the subsequent computation we prove

$$
\begin{equation*}
c_{p}(B)=(-1, N)_{p}^{\frac{N(N+1)}{2}} \tag{E}
\end{equation*}
$$

By Theorem 5 and (10), and omitting for convenience the subscript $p$,

$$
\begin{aligned}
& \prod_{i=1}^{n-2}\left(E_{i},-E_{i+1}\right)=\prod_{i=1}^{n-2}\left(N^{i}(i+1),-N^{i+1}(i+2)\right) \\
& \quad=\prod_{i=1}^{n-2}\left(N^{i},-N^{i+1}\right)(i+1,-(i+2)) S \\
& =(N,-1)^{\frac{(n-1)(n-2)}{2}}((n-1)!,-1)(n!,-1) S,
\end{aligned}
$$

where

$$
S=\prod_{i=1}^{n-2}\left(N^{i}, i+2\right)\left(N^{i+1}, i+1\right)
$$

Moreover, by (9)

$$
\begin{gathered}
S=\prod_{i=1}^{n-2}\left(N^{i}, i+2\right) \prod_{i=0}^{n-3}\left(N^{i}, i+2\right) \\
=(N, n)^{n-2}=+1
\end{gathered}
$$

Thus

$$
\begin{aligned}
& c_{p}(B)=\left(N^{n-1} n,-1\right)(N,-1)^{\frac{(n-1)(n-2)}{2}}(n,-1) \\
& =(N,-1)^{n-1}(N,-1)^{\frac{(n-1)(n-2)}{2}}=(N,-1)^{\frac{N(N+1)}{2}},
\end{aligned}
$$

and this establishes equation (E).
Suppose now that $\pi$ is a finite projective plane with $N+1$ points on a line. Then by equation (M) of section 2 , the matrix $B$ is congruent to the identity matrix $I$. Since $c_{p}(I)=+1$ for every odd prime $p$, it follows that if $\pi$ exists, then for every odd prime $p$,

$$
c_{p}(B)=(-1, N)^{\frac{N(N+1)}{2}}=+1
$$

If now $N \equiv 1$ or $2 \bmod 4$, then the exponent $\frac{N(N+1)}{2}$ is odd. Moreover, if a prime $p$ of the form $4 k+3$ divides the square free part of $N$, then $(-1, N)_{p}=-1$. This is a contradiction and completes the proof of Theorem 1.

Postscript (November 13, 1948)
(a) In a letter to one of the authors, dated May 11, 1948, Marshall Hall pointed out that the $n$-rowed symmetric matrix $B$ of section $4\left(n=N^{2}+N+1\right)$ is the matrix of a quadratic form which can be written as

$$
\left(x_{2}+\ldots+x_{n}\right)^{2}+N\left(x_{2}+\frac{x_{1}}{N}\right)^{2}+\ldots+N\left(x_{n}+\frac{x_{1}}{N}\right)^{2}
$$

Hall's remark demonstrates concretely that $B$ is rationally congruent to the diagonal matrix $D=(1, N, N, \ldots, N)$ and thus permits a simpler derivation of equation ( E ).
(b) In 1782 Euler conjectured that a pair of orthogonal latin squares (or a graeco-latin square) of order $N$ cannot exist if $N$ has the form $4 k+2$. The truth of Euler's conjecture would ensure (see [1], [8]) the non-existence of projective planes with $N \equiv 2 \bmod 4$ and hence would both imply and improve
one half of Theorem 1. For this reason the authors have decided to add to the bibliography a paper by H. F. MacNeish [14] containing a "proof" of Euler's conjecture. The correctness of this proof, however, has been questioned by F. W. Levi. In this connection see [6] (Second Lecture); Jahrbuch der Math., vol. 48 (1921), 71; Jahrbuch der Math., vol. 49 (1923), 41-42.

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