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A review on gait generation of the biped robot on various terrains – CORRIGENDUM

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The authors regret the inclusion of an error in the above article. On page 2, Table 1 contains a mistake in the ZMP equations.

The correct version of the ZMP equation in Table 1 is provided below.

\[ x_{ZMP} = \sum_{i=1}^{n} \left[ -\frac{I_i \dot{\omega}_i + m_i x_i (\ddot{z}_i - g) + m_i \ddot{x}_i z_i}{m_i (\ddot{z}_i - g)} \right] \]

\[ y_{ZMP} = \sum_{i=1}^{n} \left[ -\frac{I_i \dot{\omega}_i + m_i y_i (\ddot{z}_i - g) + m_i \ddot{y}_i z_i}{m_i (\ddot{z}_i - g)} \right] \]

Reference


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