A Generalization of Minimal Varieties

By J. G. FREEMAN

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1. Formulae for the first variation of the volume integral.

I consider an *n*-dimensional generalized metric space ${}^{1}S_{n}$ with coordinates $x^{i}(h, i, j, k...$ run from 1 to *n* throughout), with each point of which is associated a contravariant vector-density with components u^{i} and weight p, called the *element of support*. The unit vector in the direction of the element of support has components denoted by l^{i} .

Let S_{ν} be a ν -space in S_n with coordinates t^{α} (α , β , γ ... run from 1 to ν throughout), and let $S_{\nu+1}$ be any ($\nu + 1$)-space containing S_{ν} , defined by equations of the form

$$x^i = x^i(t^1, t^2, \ldots, t^\nu, v),$$

at each point of which the element of support is defined by equations of the form

$$u^i = u^i(t^1, t^2, \ldots t^{\nu}, v),$$

the coordinates t^{α} , v in $S_{\nu+1}$ being chosen so that S_{ν} is the surface $v=v_0$. Let $B_{\nu-1}$ be a given closed hypersurface of S_{ν} , bounding a region R. If points of R are displaced in $S_{\nu+1}$ by variation of v from v_0 to $v_0 + \delta v$, the region formed by the displaced points will be denoted by R'.

If the first fundamental form of S_{ν} is denoted by $g_{\alpha\beta}dt^{\alpha}dt^{\beta}$, the volume of R is given by

$$V = \int_{R} \sqrt{g(dt)^{\nu}}$$

where g is the determinant $|g_{\alpha\beta}|$ and $(dt)^{\nu}$ is an abbreviation for $dt^1 dt^2 \dots dt^{\nu}$. The volume of R' is similarly given by

$$V' = \int_{R} \left\{ \sqrt{g} + \delta v \frac{\partial \sqrt{g}}{\partial v} + O(\delta v^{2}) \right\} (dt)^{*}$$
$$V' - V = \delta V + O(\delta v^{2})$$
$$\delta V = \delta v \int_{R} \frac{\partial \sqrt{g}}{\partial v} (dt)^{*},$$

so that where

¹ Of the type treated by Schouten and Haantjes in (3). (See the list of references at the end of the paper.)

the first variation of the volume integral.

For brevity 1 shall put¹

$$\partial x^i/\partial t^a = \lambda_{a}{}^i, \quad \partial x^i/\partial v = \mu^i, \qquad g^{a\beta}\lambda_{a}{}^i = \lambda^{\beta)i}, \quad \sqrt{g}\lambda^{\beta)i} = \zeta^{\beta)i},$$

calling μ^i the displacement vector.

To evaluate δV we have

$$d\sqrt{g} = rac{1}{2\sqrt{g}} dg = rac{\sqrt{g}}{2} g^{aeta} dg_{aeta}.$$

If D indicates absolute differentiation in S_n , $dg_{\alpha\beta} = Dg_{\alpha\beta}$ since the $g_{\alpha\beta} = g_{ij}\lambda_{\alpha}{}^i\lambda_{\beta}{}^j$ are scalar in S_n ; hence

$$d\sqrt{g} = \sqrt{g} g^{\alpha\beta} \lambda_{\beta}{}^{i} D\lambda_{\alpha i},$$

$$d\sqrt{g} = D\lambda_{\alpha}{}^{i} \zeta^{\alpha}{}_{i}.$$
 (1.1)

Defining ν torsion vectors² Ω_{α}^{i} by

$$\frac{D}{\partial v} \left(\frac{\partial x^i}{\partial t^a} \right) - \frac{D}{\partial t^a} \left(\frac{\partial x^i}{\partial v} \right) = \Omega_a)^i$$
(1.2)

so that

. i.e.

$$\frac{D\lambda_{a}^{i}}{\delta v} - \frac{D\mu^{i}}{\partial t^{a}} = \left(\lambda_{a}^{j}\frac{\overline{\sigma}^{k}}{\partial v} - \mu^{j}\frac{\overline{\sigma}^{k}}{\partial t^{a}}\right)A_{j}^{i}{}_{k} = \Omega_{a}^{i}, \qquad (1.3)$$

we obtain from (1.1), (1.3)

$$\frac{\partial \sqrt{g}}{\partial v} = \frac{D\lambda_{a}}{\partial v}^{i} \zeta^{a}{}_{i} = \left(\frac{D\mu^{i}}{\partial t^{a}} + \Omega_{a}\right)^{i} \zeta^{a}{}_{i}.$$
(1.4)

$$\delta V = \delta v \int_{R} \left(\frac{D\mu_{i}}{\partial t^{a}} + \Omega_{a} \right)^{i} \zeta^{a}{}_{i} (dt)^{\nu}.$$
(1.5)

Now

Thus

$$\begin{split} \frac{\partial}{\partial t^{a}} \left(\mu^{i} \zeta^{a} \right)_{i}^{i} &= \frac{D}{\partial t^{a}} \left(\mu^{i} \zeta^{a} \right)_{i}^{i} \\ &= \frac{D \mu^{i}}{\partial t^{a}} \zeta^{a} _{i}^{i} + \mu^{i} \frac{D}{\partial t^{a}} \zeta^{a} _{i}^{i}. \end{split}$$

From (1.5) we now obtain

$$\delta V = \delta v \int_{R} \frac{\partial}{\partial t^{a}} \left(\mu^{i} \zeta^{a} \right)_{i} \left(dt \right)^{r} - \delta v \int_{R} \left(\mu^{i} \frac{D \zeta^{a} \right)_{i}}{\partial t^{a}} - \Omega_{a} \right)^{i} \zeta^{a} \left(dt \right)^{r}.$$
(1.6)
On integrating $\frac{\partial}{\partial t^{a}} \left(\mu^{i} \zeta^{a} \right)_{i}$, we obtain from (1.6)

¹ In subspace theory it is customary to write B_a^i for $\partial x^i/\partial t^a$; I have written λ_{a}^i instead, in order to emphasise the similarity between the equations given herein for a minimal variety and those given in (2) for an extremal curve.

² A geometrical interpretation of a torsion vector is given in (2), 2.

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$$\delta V = \delta v \int_{B} \mu^{i} \zeta^{a}{}_{i} (dt)^{\nu}_{a} - \delta v \int_{R} \left(\mu^{i} \frac{D \zeta^{a}{}_{i}}{\partial t^{a}} - \Omega_{a}{}^{i} \zeta^{a}{}_{i} \right) (dt)^{\nu}$$
(1.7)

where $(dt)_a^r$ stands for $(dt)^r$ with the term dt^a omitted.¹

2. Conditions for a minimal variety.

The ν -space S_{ν} will be said to be a minimal variety in S_n if, for any given $B_{\nu-1}$, $\delta V = 0$ for arbitrary displacement of points of S_{ν} and the element of support within $B_{\nu-1}$, and for $\mu^i = 0$ on $B_{\nu-1}$. From (1.3) and (1.7), when $\mu^i = 0$ on $B_{\nu-1}$

$$\delta V = - \delta v \int_{R} \left\{ \mu^{i} \left(\frac{D \zeta^{a}{}^{i}}{\partial t^{a}} + \zeta^{a}{}^{j} \frac{\overline{\omega}^{k}}{\partial t^{a}} A_{ijk} \right) - \frac{\overline{\omega}^{k}}{\partial v} \zeta^{a}{}^{j} \lambda_{a}{}^{j} A_{ijk} \right\} (dt)^{\nu}.$$
(2.1)

The conditions that $\delta V = 0$, for values of μ^i and $\frac{\overline{\omega}^k}{\partial \nu}$ arbitrary save for the latter satisfying $\frac{\overline{\omega}^k}{\partial \nu} l_k = 0$, are given by equating to zero the

coefficients of μ^i , $\frac{\overline{\sigma}^k}{\partial v}$ in (2.1), since $l^k A_{ijk} = 0$. Hence

 S_v is a minimal variety in S_n if and only if

(i)
$$\frac{D\zeta^{a_{i}}}{\partial t^{a}} + \zeta^{a_{j}j} \frac{\overline{\sigma}^{k}}{\partial t^{a}} A_{ijk} = 0$$

(ii) $\lambda^{a_{j}i}\lambda_{a_{j}}^{j}A_{ijk} = 0$ (2.2)

In the particular case in which $\nu = 1$, these equations reduce to those defining an extremal curve.² As a further special case we may consider that in which S_n is a Finsler space, $\nu = 2$, and the element of support is tangential to S_{ν} . If m^i are the components of the unit vector orthogonal to the element of support and tangential to S_{ν} , the $\lambda_{\alpha}{}^i$ are of the form $\lambda_{\alpha}{}^i = a_{\alpha}{}^{li} + b_{\alpha}{}^{mi}$. Then condition (2.2) (ii) becomes

$$g^{a\beta}b_a b_\beta m^i m^j A_{ijk} = 0. ag{2.3}$$

Now $g^{a\beta}b_ab_\beta$ does not vanish unless the b_a all vanish, and in this case the two vectors λ_{a}^{i} are in the same direction. In general, however, they are not, and (2.3) leads to

$$m^i m^j A_{ijk} = 0. (2.4)$$

Now ³ equations of the form $\xi^i \xi^j A_{ijk} = 0$, where ξ^i is a unit vector,

¹ Equations (1.5), (1.7) are similar to those for the first variation of the length integral; see (2), (3.5), (3.6).

² See (2), (4.2).

³ See (2), \S 4 for proof.

are satisfied only by $\xi^i = \pm l^i$, unless a restriction is placed on the A_{ijk} . Hence

A Finsler S_n can possess a two-dimensional minimal THEOREM 1. variety S2 with tangential element of support only in the restricted case in which the equations $\xi^i \xi^j A_{ijk} = 0$ have a solution other than $\xi^i = \pm l^i$ at points of S₂.

Returning to the general conditions (2.2) and putting

$$\lambda^{a}{}^{i}{}_{i}\lambda_{a}{}^{j}=B^{j}_{i},$$

we may write condition (2.2) (ii)

$$B_{j}^{'}A_{i}{}^{j}{}_{k}=0. (2.6)$$

To evaluate $\frac{D}{\partial t^a} \left(\sqrt{g \lambda^a}_i \right)$ in (2.2) (i) we have

$$\frac{D}{\partial t^{a}}g^{a\beta} = -g^{a\rho}g^{\beta\sigma}\frac{D}{\partial t^{a}}g_{\rho\sigma} = -g^{a\rho}g^{\beta\sigma}\Big(\lambda_{\rho}_{\rho}_{i}\frac{D\lambda_{\sigma}_{i}}{\partial t^{a}} + \lambda_{\sigma}_{i}\frac{D\lambda_{\rho}_{i}}{\partial t^{a}}\Big).$$

Therefore
$$\frac{D}{\partial t^{a}}g^{a\beta} = -g^{\beta\sigma}\lambda^{a}{}_{h}\frac{D\lambda_{\sigma}{}_{\rho}{}^{h}}{\partial t^{a}} - g^{a\rho}\lambda^{\beta}{}_{h}\frac{D\lambda_{\rho}{}_{\rho}{}^{h}}{\partial t^{a}}.$$
 (2.7)

Thus from (1.1) and (2.7)

$$\begin{split} \frac{D}{\partial t^{a}} \left(\sqrt{g} g^{a\beta} \lambda_{\beta \rangle i} \right) \\ &= \frac{D \sqrt{g}}{\partial t^{a}} g^{a\beta} \lambda_{\beta \rangle i} + \sqrt{g} \frac{D g^{a\beta}}{\partial t^{a}} \lambda_{\beta \rangle i} + \sqrt{g} g^{a\beta} \frac{D \lambda_{\beta \rangle i}}{\partial t^{a}} \\ &= \sqrt{g} \lambda^{\gamma \rangle_{j}} \frac{D \lambda_{\gamma \rangle}^{j}}{\partial t^{a}} g^{a\beta} \lambda_{\beta \rangle i} - \sqrt{g} \left\{ \lambda^{\sigma \rangle}_{i} \lambda^{a \rangle_{h}} \frac{D \lambda_{\sigma \rangle}^{h}}{\partial t^{a}} + g^{a\rho} B^{h}_{i} \frac{D \lambda_{\rho \rangle h}}{\partial t^{a}} \right\} + \sqrt{g} g^{a\beta} \frac{D \lambda_{\beta \rangle i}}{\partial t^{a}} \\ &= \sqrt{g} g^{a\beta} C^{h}_{i} \frac{D \lambda_{\beta \rangle h}}{\partial t^{a}} + \sqrt{g} \lambda^{a \rangle_{i}} \lambda^{\beta \rangle}_{\cdot h} \left(\lambda_{\beta \rangle}^{j} \frac{\overline{\varpi}^{k}}{\partial t^{a}} - \lambda_{a \rangle}^{j} \frac{\overline{\varpi}^{k}}{\partial t^{\beta}} \right) A_{j}^{h}_{k}, \end{split}$$

exitting
$$\delta^{h}_{i} - B^{h}_{i} = C^{h}_{i} \qquad [(2.8)$$

wr

and

using
$$\frac{D\lambda_{\beta}}{\partial t^{a}} - \frac{D\lambda_{a}}{\partial t^{\beta}} = \left(\lambda_{\beta}\right)^{j} \frac{\overline{\sigma}^{k}}{\partial t^{a}} - \lambda_{a}^{j} \frac{\overline{\sigma}^{k}}{\partial t^{\beta}} A_{j}^{h}_{jk}.$$
 (2.9)

Now (2.2) (i) may be written

$$\sqrt{g}g^{a\beta}C_{i}^{h}\frac{D\lambda_{\beta)h}}{\partial t^{a}} + \sqrt{g}\lambda^{a}{}_{i}B_{h}^{j}\frac{\varpi^{k}}{\partial t^{a}}A_{j}{}^{h}{}_{k} + \sqrt{g}\lambda^{\beta}{}_{h}C_{i}^{j}\frac{\varpi^{k}}{\partial t^{k}}A_{j}{}^{h}{}_{k} = 0,$$

in which the middle term vanishes on account of (2.6). Finally (2.2)becomes

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THEOREM 2. S, is a minimal variety in S_n if and only if

(i)
$$g^{\alpha\beta}C_{i}^{h}\left(\frac{D\lambda_{\beta)h}}{\partial t^{\alpha}} + \lambda_{\alpha)j}\frac{\sigma^{k}}{\partial t^{\beta}}A_{h}^{j}_{k}\right) = 0$$

(ii) $B_{i}^{h}A_{h}^{i}_{k} = 0$ over S_{r}

3. Mean curvature of a minimal variety.

Let C be a curve on any subspace S_{ν} (not necessarily a minimal variety of S_n), with unit tangent vector at a given point P having S_n , S_{ν} components $dx^i/ds = \xi^i$, $dx^a/ds = \xi^a$ respectively, s being the arc-length of C.

If ρ is the radius of first curvature of C in S_n at P, $\rho D\xi^i/ds$ is the unit vector in the direction of its principal normal in S_n ; hence if θ is the angle between this principal normal and any unit vector X^i normal to S_r at P,

$$\cos\,\theta = \rho\,\frac{D\xi^i}{ds}\,X_i\,.$$

Writing 1/R for $(\cos \theta)/\rho$, we have

$$\frac{1}{R} = \frac{D\xi^i}{ds} X_i.$$

I call 1/R the normal curvature of S, for the normal Xⁱ corresponding to the curve C. Now since $\xi^i = \lambda_{aj}^i \xi^a$,

$$rac{D\xi^i}{ds}= \ rac{D\lambda_{a}{}^i}{ds}\xi^a+\lambda_{a}{}^irac{d\xi^a}{ds}$$

$$\frac{ds}{R} = \frac{D\lambda_{a}{}^{i}}{ds} X^{i} \xi^{a} \quad \text{for} \quad \lambda_{a}{}^{i} X_{i} = 0.$$

and

Since

$$egin{aligned} &rac{D\lambda_{a)}{}^{i}}{ds}=rac{d\lambda_{a)}{}^{i}}{ds}+\lambda_{a)}{}^{j}rac{dx^{k}}{ds}\,\Gamma_{j}{}^{i}{}_{k}+\lambda_{a)}{}^{j}rac{du^{k}}{ds}\,C_{j}{}^{i}{}_{k} \ &=\left(rac{\partial\lambda_{a)}{}^{i}}{\partial t^{eta}}+\lambda_{a)}{}^{j}\lambda_{eta}{}^{k}\Gamma_{j}{}^{i}{}_{k}
ight)\xi^{eta}+\lambda_{a)}{}^{j}rac{du^{k}}{ds}\,C_{j}{}^{i}{}_{k} \end{aligned}$$

it follows that 1/R depends not only on ξ^{α} but also on du^k/ds and will therefore, in general, have different values corresponding to different curves having the same tangent at P. If, however, S_{ν} is a minimal variety in S_n , the u^k are supposed functions of the t^{β} and $du^k/ds = \xi^{\beta} \partial u^k/\partial t^{\beta}$; then $D\lambda_{\alpha}{}^i/ds = \xi^{\beta} D\lambda_{\alpha}{}^i/\partial t^{\beta}$ and 1/R is now of the form

$$\frac{1}{R} = X_{\alpha\beta} \xi^{\alpha} \xi^{\beta}, \qquad (3.1)$$

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 $X_{\alpha\beta} = \frac{1}{2} \left(\frac{D\lambda_{\alpha}{}^{i}}{\partial t^{\beta}} + \frac{D\lambda_{\beta}{}^{i}}{\partial t^{\alpha}} \right) X_{i}, \qquad (3.2)$

where

which is symmetrical in α , β .

Defining then the mean curvature of S, for the normal X^i as the sum of the values of 1/R stationary for variation of ξ^a , we have for this mean curvature

$$K_m(X) = g^{\alpha\beta} X_{\alpha\beta}. \tag{3.3}$$

If we multiply equation (i) of THEOREM 2 by X^i , and use

$$X^i C^h_i = X^i (\delta^h_i - B^h_i) = X^h$$

 $K_m(X) + \lambda^{\beta_j} X^h \frac{\varpi^k}{2i^{\beta}} A_h^{j} = 0$

we obtain

Hence the following necessary, but not sufficient, condition for a minimal variety:

THEOREM 3. If S, is a minimal variety in S_n , its mean curvature for , a normal X^i is given by

$$K_m(X) = -X^h \lambda^{\beta_j} \frac{\varpi^k}{\partial t^{\beta}} A_h^{j_k}.$$

When S_n is Riemannian and $A_{hk}^{j} = 0$, this reduces to the well-known theorem: The mean curvature for every normal of a minimal variety in a Riemannian space vanishes. In this case the condition is sufficient as well as necessary.¹

If in particular the element of support of the generalised S_n is normal to S_r ,

$$l^{h}\lambda^{\beta_{j}}\frac{\varpi^{k}}{\partial t^{\beta}}A_{h}^{j}{}_{k}=\lambda^{\beta_{j}}\frac{\varpi^{k}}{\partial t^{\beta}}pl^{j}A_{k}=0$$

since $\lambda^{\beta}_{j} l^{j} = 0$. Hence

THEOREM 4. If S, is a minimal variety to which the element of support is normal, its mean curvature for the element of support vanishes.

4. Conditions for the vanishing of the first variation of the volume integral.

From (1.5) follows

¹ Proved in (1), § 52.

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THEOREM 5. The first variation vanishes if

$$\left(\frac{Du^{i}}{\partial t^{a}}+\Omega_{a}\right)\zeta^{a}_{i}=0 \text{ over } R.$$

Also, from (1.7) we have

THEOREM 6. The first variation vanishes if R is a region of a minimal variety in S_n and the displacement vector is normal to R on its boundary.

For if R is a region of a minimal variety in S_n the second integral in (1.7) vanishes identically. Finally, from (1.7) we have also

THEOREM 7. The first variation vanishes if the displacement vector satisfies $\mu^i D\zeta^{a_i}_i/\partial t^a = \Omega_{a_i}{}^i \zeta^{a_i}_i$ at points of R, and either vanishes or is normal to R on its boundary.

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