BREAKING THE COHERENCE BARRIER: A NEW THEORY FOR COMPRESSED SENSING

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Abstract

This paper presents a framework for compressed sensing that bridges a gap between existing theory and the current use of compressed sensing in many real-world applications. In doing so, it also introduces a new sampling method that yields substantially improved recovery over existing techniques. In many applications of compressed sensing, including medical imaging, the standard principles of incoherence and sparsity are lacking. Whilst compressed sensing is often used successfully in such applications, it is done largely without mathematical explanation. The framework introduced in this paper provides such a justification. It does so by replacing these standard principles with three more general concepts: asymptotic sparsity, asymptotic incoherence and multilevel random subsampling. Moreover, not only does this work provide such a theoretical justification, it explains several key phenomena witnessed in practice. In particular, and unlike the standard theory, this work demonstrates the dependence of optimal sampling strategies on both the incoherence structure of the sampling operator and on the structure of the signal to be recovered. Another key consequence of this framework is the introduction of a new structured sampling method that exploits these phenomena to achieve significant improvements over current state-of-the-art techniques.

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1. Introduction

Introduced formally around a decade ago, compressed sensing (CS) [18, 32] has since become a popular area of research in mathematics, computer science and engineering [14, 23, 29, 35, 36, 39–41]. In many real-world problems one is limited by the amount of data that can be collected, making reconstruction via classical techniques impossible. The theory and techniques of CS provide a means to reconstruct from fewer measurements, giving it potential to significantly enhance the recovery step in such applications.

The theory of CS is based on three key concepts: *sparsity*, *incoherence* and *random sampling*. Whilst there are applications where these apply, in many practical problems one or more of these principles may be lacking. This includes most applications in medical imaging—Magnetic Resonance Imaging (MRI), Computerized Tomography (CT) and other versions of tomography such as Thermoacoustic, Photoacoustic or Electrical Impedance Tomography—electron microscopy, as well as seismic tomography, fluorescence microscopy, Hadamard spectroscopy, Helium Atom Scattering (HAS) and radio interferometry. In many of these problems, it is the principle of incoherence that is lacking, rendering the standard theory inapplicable. Yet, despite this issue CS has been, and continues to be, used successfully in many of these areas. To do so, however, it is typically implemented with sampling strategies that differ substantially from the uniform random sampling strategies suggested by the theory. In fact, in many cases the sampling strategies suggested by existing theory yield highly suboptimal numerical results.

The mathematical theory of CS has now reached a mature state. However, as this discussion suggests, there is a substantial, and arguably widening gap between theory and its applications. New developments and sampling strategies are increasingly based on empirical evidence lacking mathematical justification. Furthermore, in the above applications one also witnesses a number of intriguing phenomena that are not explained by the standard theory. For example, in such problems, the optimal sampling strategy depends not just on the overall sparsity of the signal, but also on its structure; a fact that will be documented thoroughly in this paper. This phenomenon is in contradiction with the usual sparsity-based theory of CS. Theorems that explain this observation—that is that reflect how the optimal subsampling strategy depends on the structure of the signal—do not currently exist.

1.1. Contributions. The purpose of this paper is to provide a bridge across this divide. It does so by introducing a theoretical framework for CS based on three more general principles: *asymptotic sparsity*, *asymptotic incoherence*



and *multilevel random sampling*. This new framework shows that CS is also possible under these substantially more general conditions, and moreover, can convey some key advantages. Importantly, it also addresses the issue raised above: namely, the dependence of the subsampling strategy on the structure of the signal.

The significance of this generalization is threefold. First, as will be explained, inverse problems arising from the aforementioned applications are often not incoherent and sparse, but asymptotically incoherent and asymptotically sparse. This paper provides the first comprehensive mathematical explanation for a range of empirical usages of CS in applications such as those listed above. Second, in showing that incoherence is not a requirement for CS, but instead that asymptotic incoherence suffices, the new theory offers markedly greater flexibility in the design of sensing mechanisms. In the future, sensors need only satisfy this significantly more relaxed condition. Third, by using asymptotic incoherence and multilevel sampling to exploit not just sparsity, but also structure, that is asymptotic sparsity, this frameworks paves the way for improved sensing paradigms in CS that achieve better reconstructions in practice than current state-of-the-art CS techniques.

A key aspect of many practical problems, including those listed above, is that they do not offer the freedom to design or choose the sensing operator, but instead impose it (for example, Fourier sampling in MRI). As such, much existing CS work, which relies on random or custom-designed sensing matrices (typically to provide universality), is not applicable. This paper shows that in many such applications the imposed sensing operators are both nonuniversal and highly coherent with popular sparsifying bases. Yet they are often asymptotically incoherent, and thus fall within the remit of the new framework. Spurred by this observation, this paper also raises the question of whether universality and incoherence are actually desirable in practice, even in applications where there is flexibility to design sensing operators with this property (for example, in compressive imaging). Our theorems show that asymptotically incoherent sensing and multilevel sampling allow one to exploit asymptotic, as opposed to just global sparsity. Doing so leads to notable advantages over incoherent sensing, even for problems where the latter are applicable. Moreover, and crucially, this can be done in a computationally efficient manner using fast Fourier or Hadamard transforms (see Section 6.1).

Our framework applies to any CS scenario where both the coherence and sparsity are nonuniform. Of the many applications where this is the case, one of the most important corresponds to the problem of Fourier sampling with multiresolution sparsifying transforms such as wavelets. This model arises in applications such as MRI, CT, radio interferometry, HAS and elsewhere. When applied to this specific problem, this framework yields new and near-optimal



sampling strategies based on multilevel random subsampling, and a new series of recovery guarantees. Specifically, a corollary of our abstract results in the case of Fourier sampling with wavelets taking the following form. If s_k denotes the sparsity of the wavelet coefficients of a given signal or image in the kth wavelet scale, then to recover those coefficients one requires

$$m_k \gtrsim \left(s_k + \sum_{\substack{l=1 \ l \neq k}}^r \beta^{-|k-l|} s_l\right), \quad k = 1, \dots, r.$$
 (1.1)

Fourier measurements (up to log factors) taken uniformly at random from the corresponding kth sampling level (a dyadic band in frequency space), where $\beta > 1$ is a constant depending on the type of wavelet used. See Section 6 for further discussion. As we explain, this guarantee not only confirms the empirically observed recovery properties of CS for such problems, but it also explains some of the key phenomena witnessed; for example, the dependence of the optimal sampling strategy on the sparsity structure.

Another contribution of this paper is that the theorems proved apply in both the finite- and infinite-dimensional settings. Many of the problems listed above are analogue, that is modelled with continuous operators such as the Fourier or Radon transforms. Conversely, the standard CS is based on a finite-dimensional model. Such a *mismatch* between the computational and the physical model can lead to critical errors when CS techniques are applied to real data arising from continuous models, or inverse crimes when the data is inappropriately simulated [22, 46]. To overcome this issue, a theory of CS in infinite dimensions was recently introduced in [3]. This paper extends [3] by presenting the new framework in both the finite-and infinite-dimensional settings. We note in passing that the infinite-dimensional analysis is instrumental for obtaining the Fourier sampling with wavelet sparsity estimate (1.1).

This aside, an additional outcome of this work is that the Restricted Isometry Property (RIP), although a popular tool in CS theory, is of little relevance in many practical inverse problems. As confirmed later via the so-called *flip test*, the standard RIP cannot hold in these types of applications.

The fact that the RIP may be too strong an assumption in practice is well known in the standard CS literature. To overcome this, incoherence-based results, which avoid the RIP, have shown that CS is indeed possible under weaker conditions (see [16, 17] and references therein). We remark that the reasons for the absence of the RIP in the standard CS setting are fundamentally different and arguably less significant to the reasons for its absence in this setting. In particular, as we demonstrate, in many applications only very specific structured sparse vectors can be recovered. This is in stark contrast to the standard understanding that all sparse



vectors can be recovered equally well regardless of their structure. We refer to Section 2.3 for details.

Finally, we remark that this is primarily a mathematical paper. However, as one may expect in light of the above discussion, there are a range of practical implications. We therefore encourage the reader to consult [73] for further elaboration on the practical aspects and more extensive numerical experiments. We also remark that the practical importance of the new concepts of asymptotic sparsity, asymptotic incoherence and multilevel random subsampling has already been verified experimentally in a realistic MRI setting by Siemens [84] (based on an earlier preprint of this paper). Siemens' conclusion from their experiments is: '[...] The image resolution has been greatly improved [...]. Current results practically demonstrated that it is possible to break the coherence barrier by increasing the spatial resolution in MR acquisitions. This likewise implies that the full potential of the CS is unleashed only if asymptotic sparsity and asymptotic incoherence is achieved. Therefore, CS might better be used to increase the spatial resolution rather than accelerating the data acquisition in the context of nondynamic 3D MR imaging.'

Relation to other works. Since the early days of CS, there have been numerous investigations into settings which go beyond classical sparsity and incoherence. So-called structured sparsity has been studied extensively, and there are now a range of generalized sparsity notions in the literature. (Structured sparsity, especially multiscale-type sparsity, also predates CS by some years see, for example, the work of Donoho and Huo [33]—and finds use outside of CS-see, for example, the work of Donoho and Kutyniok on geometric separation [34].) These include group, block, weighted and tree sparsity, amongst others (see [8, 11, 38, 72, 80] and references therein). In most of these works, structured sparsity is exploited by the design of the recovery algorithm (for example, by replacing the thresholding step in an iterative algorithm or the regularization functional in an optimization approach), with the sensing being carried out by a standard, incoherent operator (for example, a Gaussian random matrix). Our framework differs from these works in that it applies directly to the practical, and asymptotically incoherent, sensing operators imposed by many applications and to the way in which CS is typically implemented in practice in these applications. It demonstrates why good recovery is possible in these practical settings via the notion of asymptotic sparsity, and lends crucial insight into the design of optimal sampling strategies.

The observation that many applications of CS result in nonuniform coherence patterns arguably dates back to Lustig *et al.*'s seminal work in CS for MRI [58, 61–63]. For Fourier sampling, numerous empirical sampling strategies have been



proposed to overcome this problem [61, 85], and several other works have followed more principled approaches based on designing sampling strategies to match the underlying coherence pattern (see [10, 55, 70, 71] and references therein). However, these works do not explain the key role played by asymptotic sparsity in the CS recovery. Our work does this, and provides sampling strategies which are provably optimal with respect to *both* the sparsity and the coherence structures.

As mentioned, an important instance of our framework is that case of wavelet sparsifying transforms. The idea of sampling the low-order wavelet coefficients of an image differently goes back to the early days of CS. In particular, Donoho considers a two-level approach for recovering wavelet coefficients in his seminal paper [32], based on acquiring the coarse scales coefficients directly. This was later extended by Tsaig and Donoho to so-called 'multiscale CS' in [82], where distinct subbands were sensed separately. See also [17, 74]. Unlike in our framework, these works normally assume a separation of the wavelet coefficients into distinct bands before sampling, which is largely infeasible in practice (in particular, any application based on Fourier or Hadamard sensing). We note also that similar sampling strategies to those that we introduce here are found in most implementations of CS in MRI [62, 63, 70, 71]. In addition, a so-called 'half-half' scheme (an example of a two-level strategy in our terminology—see Section 3) was used by [77] in an application of CS in fluorescence microscopy, albeit without theoretical recovery guarantees.

The proofs of the main results in this paper have their roots in some existing ideas from CS literature [3, 16, 43], with the two key tools being dual certificates and the golfing scheme. However, in order to account for the sparsity structure and the different sampling patterns used the techniques have some significant differences. In addition, as pointed out in [44, page 26], the original proofs using the golfing scheme assume an independence of certain random variables that will never be satisfied in general. The techniques used in this paper are different and overcome this issue yielding complete generality. Moreover, unlike almost all existing works, our results address both the finite- and infinite-dimensional CS settings. This extends (and improves) a line of work initiated in [3], and calls for a number of more sophisticated mathematical techniques.

REMARK 1.1. Since the initial preprint of this work, there have been several other applications and extensions inspired by the first version which we now mention for the reader's benefit. First, the multilevel sampling strategies we introduced have been extended to block sampling strategies [10, 12, 20, 21], which are more practical for applications such as MRI. A type of multilevel subsampling has also be considered in [49, 50] in the context of practical



compressive imaging architectures, with application to single-pixel [37, 78] and lensless imaging [86]. Our main results in this paper provide a theoretical foundation for these implementations. There have also been several theoretical extensions. First, generalizations of the RIP for the setting of asymptotic sparsity, asymptotic incoherence and multilevel random subsampling have been introduced and analysed in [9, 60, 80]. These complement the results proved in this paper by establishing uniform recovery guarantees. Second, there have been extensions to redundant sparsifying transforms [69] (see also [57] for the case of shearlets) and to total variation minimization [68], respectively.

2. Motivation

In this section, we discuss how the standard theory of CS falls short in explaining its empirical success in many applications. Specifically, even in well-known applications such as MRI (note that MRI was one of the first applications of CS [58, 61–63]), there is a significant gap between theory and practice.

2.1. Compressed sensing. We commence with a short review of aspects of finite-dimensional CS theory (infinite-dimensional CS will be considered in Section 5). Since CS has been the subject of a body of research in the last decade we will not attempt a full survey here, opting instead to focus on aspects most relevant to this paper. For much more comprehensive reviews, including historical context and discussion, we refer to [14, 29, 35, 36, 39–41].

A typical setup in CS, and one which we shall follow in part of this paper, is as follows. Let $\{\psi_j\}_{j=1}^N$ and $\{\varphi_j\}_{j=1}^N$ be two orthonormal bases of \mathbb{C}^N , the *sampling* and *sparsity* bases respectively, and write $U = (u_{ij})_{i,j=1}^N \in \mathbb{C}^{N\times N}$, $u_{ij} = \langle \varphi_j, \psi_i \rangle$. Note that U is an isometry, that is $U^*U = I$.

DEFINITION 2.1. Let $U=(u_{ij})_{i,j=1}^N\in\mathbb{C}^{N\times N}$ be an isometry. The coherence of U is precisely

$$\mu(U) = \max_{i,j=1,\dots,N} |u_{ij}|^2 \in [N^{-1}, 1].$$
(2.1)

We say that U is perfectly incoherent if $\mu(U) = N^{-1}$.

A signal $f \in \mathbb{C}^N$ is said to be s-sparse in the orthonormal basis $\{\varphi_j\}_{j=1}^N$ if at most s of its coefficients in this basis are nonzero. In other words, $f = \sum_{j=1}^N x_j \varphi_j$, and the vector $x \in \mathbb{C}^N$ satisfies $|\operatorname{supp}(x)| \leq s$, where $\operatorname{supp}(x) = \{j : x_j \neq 0\}$. Let $f \in \mathbb{C}^N$ be s-sparse in $\{\varphi_j\}_{j=1}^N$, and suppose we have access to the samples $\hat{f}_j = \langle f, \psi_j \rangle, \ j = 1, \ldots, N$. Let $\Omega \subseteq \{1, \ldots, N\}$ be of cardinality m and chosen



uniformly at random. According to a result of Candès and Plan [16] and Adcock and Hansen [3], f can be recovered exactly with probability exceeding $1 - \epsilon$ from the subset of measurements $\{\hat{f}_i : j \in \Omega\}$, provided

$$m \gtrsim \mu(U) \cdot N \cdot s \cdot (1 + \log(\epsilon^{-1})) \cdot \log(N),$$
 (2.2)

(here and elsewhere in this paper we shall use the notation $a \gtrsim b$ to mean that there exists a constant C > 0 independent of all relevant parameters such that $a \geqslant Cb$). In practice, recovery can be achieved by solving the following convex optimization problem:

$$\min_{\eta \in \mathbb{C}^N} \|\eta\|_{l^1} \text{ subject to } P_{\Omega} U \eta = P_{\Omega} \hat{f}, \tag{2.3}$$

where $\hat{f} = (\hat{f}_1, \dots, \hat{f}_N)^{\top}$ and $P_{\Omega} \in \mathbb{C}^{N \times N}$ is the diagonal projection matrix with jth entry 1 if $j \in \Omega$ and zero otherwise. The key estimate (2.2) shows that the number of measurements m required is, up to a log factor, on the order of the sparsity s, provided the coherence $\mu(U) = \mathcal{O}\left(N^{-1}\right)$. This is the case, for example, when U is the DFT matrix; a problem which was studied in some of the first papers on CS [18].

2.2. Incoherence is often lacking. As mentioned, in a number of important applications, not least MRI, the sampling is carried out in the Fourier domain. Since images are approximately sparse in wavelets, the usual CS setup is to form the matrix $U_N = U_{\rm df} V_{\rm dw}^{-1} \in \mathbb{C}^{N \times N}$, where $U_{\rm df}$ and $V_{\rm dw}$ represent the discrete Fourier and wavelet transforms, respectively.

Unfortunately, in the case the coherence satisfies $\mu(U_N) = \mathcal{O}(1)$ as $N \to \infty$, for any wavelet basis. Thus, this problem has the worst possible coherence, and the standard CS estimate (2.2) states that m = N samples are needed in this case (that is full sampling), even though the object to recover is typically highly sparse. Note that this is not an insufficiency of the theory: as seen in Figure 1, uniform random subsampling in this problem yields an extremely poor reconstruction.

Although the presence of high coherence has been well documented in the MRI context [61–63], the source of it has not been fully explained. As it transpires, the underlying reason for this lack of incoherence can be traced to the fact that this finite-dimensional problem is a discretization of an infinite-dimensional problem. Specifically,

WOT-lim
$$U_{\text{df}}V_{\text{dw}}^{-1} = U,$$
 (2.4)

where $U: l^2(\mathbb{N}) \to l^2(\mathbb{N})$ is the operator represented as the infinite matrix

$$U = \{ \langle \varphi_i, \psi_j \rangle \}_{i,j \in \mathbb{N}}, \tag{2.5}$$



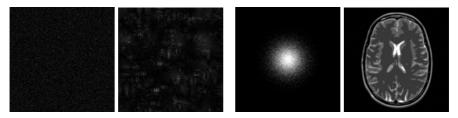


Figure 1. Left to right: (i) 5% uniform random subsampling scheme, (ii) CS reconstruction from uniform subsampling, (iii) 5% multilevel subsampling scheme, (iv) CS reconstruction from multilevel subsampling.

and the functions φ_j are the wavelets used, the ψ_j 's are the standard complex exponentials and WOT denotes the weak operator topology. Since the coherence of the infinite matrix U—that is the supremum of its entries in absolute value—is a fixed number independent of the discretization N, we cannot expect incoherence of the discretization U_N (that is, $U_N = \mathcal{O}(N^{-1})$) for large N. In other words, at some point one will always encounter the so-called *coherence barrier*. To mitigate this problem, one may naturally try to change $\{\varphi_j\}$ or $\{\psi_j\}$. However, this will deliver only marginal benefits: (2.4) demonstrates that the coherence barrier will always occur for large enough N, regardless of the choice of the bases.

Note that this issue is not isolated to this particular example. Informally, any problem that arises as a discretization of an infinite-dimensional problem will suffer from the same phenomenon. The list of applications of this type is long, and includes, for example, MRI, CT, microscopy and seismology.

In view of the coherence barrier, one may wonder how it is possible that CS is applied so successfully to many such problems. The key is so-called *asymptotic* incoherence (see Section 3.1) and the use of variable density subsampling strategies. The success of such a subsampling is well known in the CS MRI community [61–63, 70, 71] and is confirmed numerically in Figure 1. However, it is important to note that this is an empirical solution to the problem. None of the usual CS theory discussed in Section 2.1 explains the effectiveness of CS when implemented in this way.

2.3. Sparsity, the flip test and the absence of RIP. The previous discussion demonstrates that we must dispense with the principles of incoherence and uniform random subsampling in order to develop a new framework. We now claim that sparsity too must also be replaced with a more general concept. This may come as a surprise to the reader, since sparsity is a central pillar of not just CS, but much of modern signal processing. However, this can be confirmed by a simple experiment we refer to as the *flip test*.



Sparsity asserts that an unknown vector x has s important coefficients, where the locations can be arbitrary, and classical CS theory states that such vectors can be recovered by sampling in a way that is independent of the locations of these coefficients. The flip test, described next, allows one to evaluate the validity of this statement for a given problem.

We proceed as follows. Let $x \in \mathbb{C}^N$ and $U \in \mathbb{C}^{N \times N}$. Take samples according to some appropriate subset $\Omega \subseteq \{1, ..., N\}$ with $|\Omega| = m$, and solve:

$$\min_{z \in \mathbb{C}^N} \|z\|_1 \text{ subject to } P_{\Omega} U z = P_{\Omega} U x. \tag{2.6}$$

This gives a reconstruction $z=z_1$. Now we flip the entries of x through the operation $x\mapsto x^{\mathrm{fp}}\in\mathbb{C}^N$, $x_1^{\mathrm{fp}}=x_N$, $x_2^{\mathrm{fp}}=x_{N-1},\ldots,x_N^{\mathrm{fp}}=x_1$, giving a new vector x^{fp} with reversed entries. We next apply the same CS reconstruction to x^{fp} , using the same matrix U and the same subset Ω . That is, we solve (2.6) with x replaced by x^{fp} and denote the solution by z. We perform the flipping operation once more and form the final reconstruction $z_2=z^{\mathrm{fp}}$.

Suppose now that Ω is a good sampling pattern for recovering x using the solution z_1 of (2.6). If sparsity alone is the key structure that determines such reconstruction quality, then we expect roughly the same quality in the approximation z_2 , since $x^{\rm fp}$ is merely a permutation of x. To check whether or not this is true, we consider examples arising from the following applications: fluorescence microscopy, compressive imaging, MRI, CT, electron microscopy and radio interferometry. These examples are all based on either the matrix $U = U_{\rm dft} V_{\rm dwt}^{-1}$ or the matrix $U = U_{\rm Had} V_{\rm dwt}^{-1}$, where $U_{\rm dft}$ is the discrete Fourier transform, $U_{\rm Had}$ is a Hadamard matrix and $V_{\rm dwt}$ is the discrete wavelet transform.

The results are shown in Figure 2. In all cases the flipped reconstructions z_2 are substantially worse than their unflipped counterparts z_1 . We therefore conclude that sparsity alone does not govern the reconstruction quality, and that the successful recovery in the unflipped case must also be due in part to the structure of the signal. Put another way: the best subsampling strategy depends on the signal structure.

The flip test also reveals another interesting phenomenon: the RIP does not hold. Suppose the matrix $P_{\Omega}U$ satisfied an RIP for realistic parameter values (that is problem size N, subsampling percentage m, and sparsity s) found in applications. Then this would imply recovery of all approximately sparse vectors with the same error, in contradiction with the results of the flip test. As was mentioned in Section 1.1, the absence of RIP here is not related to uniform versus nonuniform recovery regimes, but to the key role that the sparsity structure plays in the recovery quality. Indeed, the result of Figure 2 could have been repeated with more measurements and similar disparities in the reconstruction quality would still have been observed.



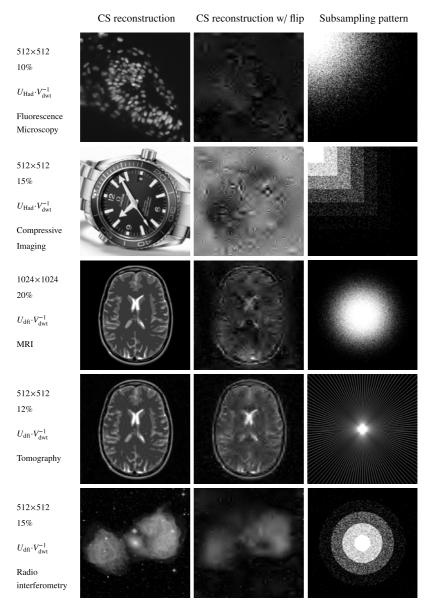


Figure 2. Reconstructions via CS (left column) and the flipped wavelet coefficients (middle column). The right column shows the subsampling map used. The percentage shown is the fraction of Fourier or Hadamard coefficients that were sampled. The reconstruction basis was DB6.



2.4. Signals and images are asymptotically sparse in -lets. Since structure plays a key role, we now address what the structure is that leads to good reconstructions in the unflipped case. Consider a wavelet basis $\{\varphi_n\}_{n\in\mathbb{N}}$. There is a natural decomposition of \mathbb{N} into finite subsets according to the wavelet scales, $\mathbb{N} = \bigcup_{k\in\mathbb{N}} \{M_{k-1}+1,\ldots,M_k\}$, where $0=M_0 < M_1 < M_2 < \ldots$ and $\{M_{k-1}+1,\ldots,M_k\}$ is the set of indices corresponding to the kth scale. Let $x \in l^2(\mathbb{N})$ be the coefficients of a function f in this basis, $\epsilon \in (0,1]$ and define the global sparsity, s, and the sparsity at the kth level, s_k as follows:

$$s = s(\epsilon) = \min \left\{ n : \left\| \sum_{i \in \mathcal{M}_n} x_i \varphi_i \right\| \geqslant \epsilon \left\| \sum_{j=1}^{\infty} x_j \varphi_j \right\| \right\},$$

$$s_k = s_k(\epsilon) = \left| \mathcal{M}_{s(\epsilon)} \cap \{ M_{k-1} + 1, \dots, M_k \} \right|,$$
(2.7)

where \mathcal{M}_n is the set of indices of the largest n coefficients in absolute value and $|\cdot|$ is the set cardinality. A well-known result in nonlinear approximation, and one which significantly predates the development of CS, is that typical images and signals are sparse in wavelets [30, 64]. However, it is also well known that their coefficients exhibit far more structure than sparsity alone. Indeed, the relative perlevel sparsity

$$s_k/(M_k - M_{k-1}) \longrightarrow 0, \tag{2.8}$$

rapidly as $k \to \infty$ for any fixed $\epsilon \in (0, 1]$. Thus typical signals and images have a distinct *asymptotic* sparsity structure: they are much sparser at fine scales (large k) than at coarse scales (small k). This is shown numerically in Figure 3. Note that this holds for most related approximation systems, such as curvelets [13, 15], contourlets [31, 66] or shearlets [25, 26, 56].

3. New principles

Having argued why they are needed, we now formally introduce the main concepts of the paper: namely, asymptotic incoherence, asymptotic sparsity and multilevel sampling.

3.1. Asymptotic incoherence. Recall from Section 2.2 that Fourier sampling with wavelets as the sparsity basis is a standard example of a coherent problem. Similarly, Fourier sampling with Legendre polynomials is also coherent, as is the case of Hadamard sampling with wavelets. In Figure 4 we plot the absolute values of the entries of the matrix U for these three examples. As is evident, whilst U does indeed have large entries in all three case (since it is coherent), these are isolated to a leading submatrix (note that we enumerate over \mathbb{Z} for the Fourier



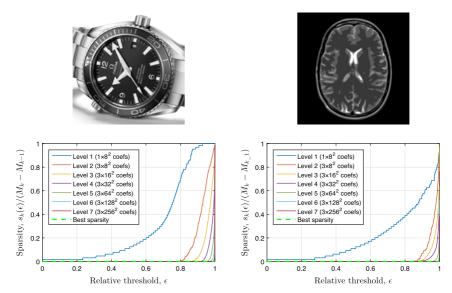


Figure 3. Relative per-level sparsities of the Daubechies-4 wavelet coefficients of two images. Here the levels correspond to wavelet scales and $s_k(\epsilon)$ is given by (2.7). The decreasing nature of the curves for increasing k confirms (2.8).



Figure 4. The absolute values of the matrix U in (2.5): (left): Daubechies-4 wavelets with Fourier sampling. (middle): Legendre polynomials with Fourier sampling. (right): Haar wavelets with Hadamard sampling. Light regions correspond to large values and dark regions to small values.

sampling basis and $\mathbb N$ for the wavelet/Legendre sparsity bases). As one moves away from this region the values get progressively smaller, that is more incoherent. This motivates the following definition:



DEFINITION 3.1 (Asymptotic incoherence). Let be $\{U_N\}$ be a sequence of isometries with $U_N \in \mathbb{C}^{N \times N}$. Then $\{U_N\}$ is asymptotically incoherent if

$$\mu(P_K^\perp U_N), \ \mu(U_N P_K^\perp) \longrightarrow 0, \quad K \to \infty,$$

with N/K = c, for all $c \ge 1$. Conversely, if $U \in \mathcal{B}(l^2(\mathbb{N}))$ then we say that U is asymptotically incoherent if $\mu(P_K^{\perp}U)$, $\mu(UP_K^{\perp}) \to 0$ when $K \to \infty$.

Note that in this definition we use the notation P_K for the projection onto $\operatorname{span}\{e_j: j=1,\ldots,K\}$, where $\{e_j\}$ is the canonical basis of either \mathbb{C}^N or $l^2(\mathbb{N})$, and P_K^{\perp} is its orthogonal complement.

In other words, U (or U_N) is asymptotically incoherent if the coherences of the matrices formed by replacing either the first K rows or columns of U are small. As it transpires, the Fourier-wavelets, Fourier-Legendre and Hadamard-wavelets problems are all asymptotically incoherent. In particular, for wavelets one has $\mu(P_K^\perp U), \ \mu(UP_K^\perp) = \mathcal{O}\left(K^{-1}\right)$ as $K \to \infty$ for the former (see Section 6, see also [54] for the Legendre case).

3.2. Multilevel sampling. Asymptotic incoherence suggests a different subsampling strategy should be used instead of uniform random sampling. High coherence in the first few rows of U means that important information about the signal to be recovered may well be contained in its corresponding measurements. Hence to ensure good recovery we should fully sample these rows. Conversely, once outside of this region, when the coherence starts to decrease, we can begin to subsample. Let $N_1, N, m \in \mathbb{N}$ be given. This now leads us to consider an index set Ω of the form $\Omega = \Omega_1 \cup \Omega_2$, where $\Omega_1 = \{1, \ldots, N_1\}$, and $\Omega_2 \subseteq \{N_1 + 1, \ldots, N\}$ is chosen uniformly at random with $|\Omega_2| = m$. We refer to this as a *two-level* sampling scheme. As we shall prove later, the amount of subsampling possible (that is the parameter m) in the region corresponding to Ω_2 will depend solely on the sparsity of the signal and coherence $\mu(P_N^{\perp}, U)$.

A two-level scheme represents the simplest type of nonuniform density sampling. There is no reason, however, to restrict our attention to just two levels, full and subsampled. In general, we shall consider *multilevel* schemes, defined as follows:

DEFINITION 3.2 (Multilevel random sampling). Let $r \in \mathbb{N}$, $\mathbf{N} = (N_1, \dots, N_r)$ $\in \mathbb{N}^r$ with $1 \leq N_1 < \dots < N_r$, $\mathbf{m} = (m_1, \dots, m_r) \in \mathbb{N}^r$, with $m_k \leq N_k - N_{k-1}$, $k = 1, \dots, r$, and suppose that $\Omega_k \subseteq \{N_{k-1} + 1, \dots, N_k\}, |\Omega_k| = m_k$, $k = 1, \dots, r$, are chosen uniformly at random, where $N_0 = 0$. We refer to the set $\Omega = \Omega_{\mathbf{N},\mathbf{m}} = \Omega_1 \cup \dots \cup \Omega_r$ as an (\mathbf{N},\mathbf{m}) -multilevel sampling scheme.



As discussed earlier, two-level [32, 63, 74, 77] and multilevel [17, 82] schemes have been considered previously in the context of the recovery of wavelet coefficients, and often for specific applications (for example, MRI in [63] and fluorescence microscopy in [77]). We refer to Section 1.2 for further details. On the other hand, although motivated by wavelets, this definition is completely general and allows for other types of structured coefficients. Moreover, it is accompanied by full theoretical recovery guarantees (see Sections 4 and 5).

3.3. Asymptotic sparsity in levels. The flip test, the discussion in Section 2.4 and Figure 3 suggest that we need a different concept to sparsity. Given the structure of function systems such as wavelets and their generalizations, we now propose the following:

DEFINITION 3.3 (Sparsity in levels). Let x be an element of either \mathbb{C}^N or $l^2(\mathbb{N})$. For $r \in \mathbb{N}$ let $\mathbf{M} = (M_1, \dots, M_r) \in \mathbb{N}^r$ with $1 \leqslant M_1 < \dots < M_r$ and $\mathbf{s} = (s_1, \dots, s_r) \in \mathbb{N}^r$, with $s_k \leqslant M_k - M_{k-1}, k = 1, \dots, r$, where $M_0 = 0$. We say that x is (\mathbf{s}, \mathbf{M}) -sparse if, for each $k = 1, \dots, r$, $\Delta_k := \operatorname{supp}(x) \cap \{M_{k-1} + 1, \dots, M_k\}$, satisfies $|\Delta_k| \leqslant s_k$. We denote the set of (\mathbf{s}, \mathbf{M}) -sparse vectors by $\Sigma_{\mathbf{s}, \mathbf{M}}$.

DEFINITION 3.4 ((**s**, **M**)-term approximation). Let $f = \sum_j x_j \varphi_j$, where $\{\varphi_j\}$ is some orthonormal basis of a Hilbert space and $x = (x_j)$ is an element of either \mathbb{C}^N or $l^2(\mathbb{N})$. We define the (**s**, **M**)-term approximation

$$\sigma_{\mathbf{s},\mathbf{M}}(f) = \min_{\eta \in \Sigma_{\mathbf{s},\mathbf{M}}} \|x - \eta\|_{l^1}. \tag{3.1}$$

Typically, it is the case that $s_k/(M_k-M_{k-1})\to 0$ as $k\to\infty$, in which case we say that x is asymptotically sparse in levels. However, our main results do not explicitly require such decay. As discussed in Section 1.2, sparsity in levels is a type of structured sparsity. We note in passing that it is quite different to the notions of block sparsity [8], weighted sparsity [72] or tree-structured sparsity [8], the latter of which has been used previously in the context of model-based CS for the recovery of wavelet coefficients. For further discussion on different structured sparsity models in CS, we refer to [11, 80].

4. Main theorems I: the finite-dimensional case

We now present our main theorems in the finite-dimensional setting. In Section 5 we address the infinite-dimensional case. To avoid pathological examples we assume throughout that the total sparsity $s = s_1 + \cdots + s_r \ge 3$. This is simply to ensure that $\log(s) \ge 1$, which is convenient in the proofs.



4.1. Two-level sampling schemes. We commence with the case of two-level sampling schemes. Recall that in practice, signals are never exactly sparse (or sparse in levels), and their measurements are always contaminated by noise. Let $f = \sum_j x_j \varphi_j$ be a fixed signal, and write $y = P_\Omega \hat{f} + z = P_\Omega Ux + z$, for its noisy measurements, where $z \in \text{ran}(P_\Omega)$ is a noise vector satisfying $||z|| \le \delta$ for some $\delta \ge 0$. If δ is known, we now consider the following problem:

$$\min_{\eta \in \mathbb{C}^N} \|\eta\|_{l^1} \text{ subject to } \|P_{\Omega}U\eta - y\| \leqslant \delta. \tag{4.1}$$

Our aim now is to recover x up to an error proportional to δ and the best approximation error $\sigma_{s,M}(f)$.

Before stating our theorem, it is useful to make the following definition. For $K \in \mathbb{N}$, we write $\mu_K = \mu(P_K^{\perp}U)$. We now have the following:

THEOREM 4.1. Let $U \in \mathbb{C}^{N \times N}$ be an isometry and $x \in \mathbb{C}^N$. Suppose that $\Omega = \Omega_{\mathbf{N},\mathbf{m}}$ is a two-level sampling scheme, where $\mathbf{N} = (N_1, N_2)$, $N_2 = N$, and $\mathbf{m} = (N_1, m_2)$. Let (\mathbf{s}, \mathbf{M}) , where $\mathbf{M} = (M_1, M_2) \in \mathbb{N}^2$, $M_1 < M_2$, $M_2 = N$, and $\mathbf{s} = (M_1, s_2) \in \mathbb{N}^2$, $s_2 \leq M_2 - M_1$, be any pair such that the following holds:

(i) we have

$$\|P_{N_1}^{\perp} U P_{M_1}\| \leqslant \frac{\gamma}{\sqrt{M_1}}$$
 (4.2)

and $\gamma \leqslant s_2 \sqrt{\mu_{N_1}}$ for some $\gamma \in (0, 2/5]$;

(ii) for $\epsilon \in (0, e^{-1}]$, let

$$m_2 \gtrsim (N - N_1) \cdot \log(\epsilon^{-1}) \cdot \mu_{N_1} \cdot s_2 \cdot \log(N)$$
.

Suppose that $\xi \in \mathbb{C}^N$ is a minimizer of (4.1) with $\delta = \tilde{\delta}\sqrt{K^{-1}}$ and $K = (N_2 - N_1)/m_2$. Then, with probability exceeding $1 - s\epsilon$, we have

$$\|\xi - x\| \leqslant C \cdot \left(\tilde{\delta} \cdot \left(1 + L \cdot \sqrt{s}\right) + \sigma_{s,\mathbf{M}}(f)\right),\tag{4.3}$$

for some constant C, where $\sigma_{s,M}(f)$ is as in (3.1), $L = 1 + \left(\sqrt{\log_2(6\epsilon^{-1})}/\log_2(4KM\sqrt{s})\right)$. If $m_2 = N - N_1$ then this holds with probability 1.

To interpret Theorem 4.1, and in particular, to show how it overcomes the coherence barrier, we note the following:

(i) The condition $||P_{N_1}^{\perp}UP_{M_1}|| \le 2/(5\sqrt{M_1})$ (which is always satisfied for some N_1) implies that fully sampling the first N_1 measurements allows one to recover the first M_1 coefficients of f.



(ii) To recover the remaining s_2 coefficients we require, up to log factors, an additional $m_2 \gtrsim (N-N_1) \cdot \mu_{N_1} \cdot s_2$, measurements, taken randomly from the range M_1+1,\ldots,M_2 . In particular, if N_1 is a fixed fraction of N, and if $\mu_{N_1}=\mathcal{O}\left(N_1^{-1}\right)$, such as for wavelets with Fourier measurements (Theorem 6.1), then one requires only $m_2 \gtrsim s_2$ additional measurements to recover the sparse part of the signal.

Thus, in the case where x is asymptotically sparse, we require a fixed number N_1 measurements to recover the nonsparse part of x, and then a number m_2 depending on s_2 and the asymptotic coherence μ_{N_1} to recover the sparse part.

REMARK 4.2. It is not necessary to know the sparsity structure, that is the values \mathbf{s} and \mathbf{M} , of the signal f in order to implement the two-level sampling technique (the same also applies to the multilevel technique discussed in the next section). Given a two-level scheme $\Omega = \Omega_{\mathrm{N,m}}$, Theorem 4.1 demonstrates that f will be recovered exactly up to an error on the order of $\sigma_{\mathrm{s,M}}(f)$, where \mathbf{s} and \mathbf{M} are determined implicitly by \mathbf{N} , \mathbf{m} and the conditions (i) and (ii) of the theorem. Of course, some a priori knowledge of \mathbf{s} and \mathbf{M} will greatly assist in selecting the parameters \mathbf{N} and \mathbf{m} so as to get the best recovery results. However, this is not strictly necessary for implementation.

4.2. Multilevel sampling schemes. We now consider the case of multilevel sampling schemes. Before presenting this case, we need several definitions. The first is key concept in this paper, namely, *the local coherence*.

DEFINITION 4.3 (Local coherence). Let U be an isometry of either \mathbb{C}^N or $l^2(\mathbb{N})$. If $\mathbf{N} = (N_1, \dots, N_r) \in \mathbb{N}^r$ and $\mathbf{M} = (M_1, \dots, M_r) \in \mathbb{N}^r$ with $1 \leq N_1 < \dots < N_r$ and $1 \leq M_1 < \dots < M_r$ the (k, l)th local coherence of U with respect to \mathbf{N} and \mathbf{M} is given by

$$\mu_{\mathbf{N},\mathbf{M}}(k,l) = \sqrt{\mu(P_{N_k}^{N_{k-1}}UP_{M_l}^{M_{l-1}}) \cdot \mu(P_{N_k}^{N_{k-1}}U)}, \quad k,l = 1,\ldots,r,$$

where $N_0 = M_0 = 0$ and P_b^a denotes the projection matrix corresponding to indices $\{a+1,\ldots,b\}$. In the case where $U \in \mathcal{B}(l^2(\mathbb{N}))$ (that is U belongs to the space of bounded operators on $l^2(\mathbb{N})$), we also define

$$\mu_{\mathbf{N},\mathbf{M}}(k,\infty) = \sqrt{\mu(P_{N_k}^{N_{k-1}}UP_{M_{r-1}}^{\perp}) \cdot \mu(P_{N_k}^{N_{k-1}}U)}, \quad k = 1,\ldots,r.$$

Besides the local sparsities s_k , we shall also require the notion of a relative sparsity:



DEFINITION 4.4 (Relative sparsity). Let U be an isometry of either \mathbb{C}^N or $l^2(\mathbb{N})$. For $\mathbf{N} = (N_1, \dots, N_r) \in \mathbb{N}^r$, $\mathbf{M} = (M_1, \dots, M_r) \in \mathbb{N}^r$ with $1 \leqslant N_1 < \dots < N_r$ and $1 \leqslant M_1 < \dots < M_r$, $\mathbf{s} = (s_1, \dots, s_r) \in \mathbb{N}^r$ and $1 \leqslant k \leqslant r$, the kth relative sparsity is given by $S_k = S_k(\mathbf{N}, \mathbf{M}, \mathbf{s}) = \max_{\eta \in \Theta} \|P_{N_k}^{N_{k-1}} U \eta\|^2$, where $N_0 = M_0 = 0$ and Θ is the set

$$\Theta = \{ \eta : \|\eta\|_{l^{\infty}} \leqslant 1, |\text{supp}(P_{M_l}^{M_{l-1}}\eta)| = s_l, \ l = 1, \dots, r \}.$$

We can now present our main theorem:

THEOREM 4.5. Let $U \in \mathbb{C}^{N \times N}$ be an isometry and $x \in \mathbb{C}^N$. Suppose that $\Omega = \Omega_{\mathbf{N},\mathbf{m}}$ is a multilevel sampling scheme, where $\mathbf{N} = (N_1, \ldots, N_r) \in \mathbb{N}^r$, $N_r = N$, and $\mathbf{m} = (m_1, \ldots, m_r) \in \mathbb{N}^r$. Let (\mathbf{s}, \mathbf{M}) , where $\mathbf{M} = (M_1, \ldots, M_r) \in \mathbb{N}^r$, $M_r = N$, and $\mathbf{s} = (s_1, \ldots, s_r) \in \mathbb{N}^r$, be any pair such that the following holds: for $\epsilon \in (0, e^{-1}]$ and $1 \leq k \leq r$,

$$1 \gtrsim \frac{N_k - N_{k-1}}{m_k} \cdot \log(\epsilon^{-1}) \cdot \left(\sum_{l=1}^r \mu_{\mathbf{N},\mathbf{M}}(k,l) \cdot s_l\right) \cdot \log(N), \qquad (4.4)$$

where $m_k \gtrsim \hat{m}_k \cdot \log(\epsilon^{-1}) \cdot \log(N)$, and \hat{m}_k is such that

$$1 \gtrsim \sum_{k=1}^{r} \left(\frac{N_k - N_{k-1}}{\hat{m}_k} - 1 \right) \cdot \mu_{\mathbf{N},\mathbf{M}}(k,l) \cdot \tilde{s}_k, \tag{4.5}$$

for all l = 1, ..., r and all $\tilde{s}_1, ..., \tilde{s}_r \in (0, \infty)$ satisfying

$$\tilde{s}_1 + \cdots + \tilde{s}_r \leqslant s_1 + \cdots + s_r, \quad \tilde{s}_k \leqslant S_k(\mathbf{N}, \mathbf{M}, \mathbf{s}).$$

Suppose that $\xi \in \mathbb{C}^N$ is a minimizer of (4.1) with $\delta = \tilde{\delta}\sqrt{K^{-1}}$ and $K = \max_{1 \leq k \leq r} \{(N_k - N_{k-1})/m_k\}$. Then, with probability exceeding $1 - s\epsilon$, where $s = s_1 + \cdots + s_r$, we have that

$$\|\xi - x\| \leqslant C \cdot \left(\tilde{\delta} \cdot \left(1 + L \cdot \sqrt{s}\right) + \sigma_{s,M}(f)\right),$$

for some constant C, where $\sigma_{s,M}(f)$ is as in (3.1), $L = 1 + \left(\sqrt{\log_2(6\epsilon^{-1})}/\log_2(4KM\sqrt{s})\right)$. If $m_k = N_k - N_{k-1}$, $1 \le k \le r$, then this holds with probability 1.

The key component of this theorem is the bounds (4.4) and (4.5). Whereas the standard CS estimate (2.2) relates the total number of samples m to the global coherence and the global sparsity, these bounds now relate the local sampling



 m_k to the local coherences $\mu_{N,M}(k,l)$ and local and relative sparsities s_k and s_k . In particular, by relating these local quantities this theorem conforms with the conclusions of the flip test in Section 2.3: namely, that the optimal sampling strategy must depend on the signal structure. This is exactly what is described in (4.4) and (4.5).

On the face of it, the bounds (4.4) and (4.5) may appear somewhat complicated, not least because they involve the relative sparsities S_k . As we next show, however, they are indeed sharp in the sense that they reduce to the correct information-theoretic limits in several important cases. Furthermore, in the important case of wavelet sparsity with Fourier sampling, they can be used to provide near-optimal recovery guarantees. We discuss this in Section 6. Note, however, that to do this it is first necessary to generalize Theorem 4.5 to the infinite-dimensional setting, which we do in Section 5.

4.2.1. Sharpness of the estimates—the block-diagonal case. Suppose that $\Omega = \Omega_{\mathbf{N},\mathbf{m}}$ is a multilevel sampling scheme, where $\mathbf{N} = (N_1, \dots, N_r) \in \mathbb{N}^r$ and $\mathbf{m} = (m_1, \dots, m_r) \in \mathbb{N}^r$. Let (\mathbf{s}, \mathbf{M}) , where $\mathbf{M} = (M_1, \dots, M_r) \in \mathbb{N}^r$, and suppose for simplicity that $\mathbf{M} = \mathbf{N}$. Consider the block-diagonal matrix

$$A = A_1 \oplus \cdots \oplus A_r \in \mathbb{C}^{N \times N}, \quad A_k \in \mathbb{C}^{(N_k - N_{k-1}) \times (N_k - N_{k-1})}, \quad A_k^* A_k = I,$$

where $N_0 = 0$. Note that in this setting we have $S_k = s_k$, $\mu_{N,M}(k, l) = 0$, $k \neq l$. Also, since $\mu(N, M)(k, k) = \mu(A_k)$, equations (4.4) and (4.5) reduce to

$$1 \gtrsim rac{N_k - N_{k-1}}{m_k} \cdot \log(\epsilon^{-1}) \cdot \mu(A_k) \cdot s_k \cdot \log(N),$$

$$1 \gtrsim \left(rac{N_k - N_{k-1}}{\hat{m}_k} - 1
ight) \cdot \mu(A_k) \cdot s_k.$$

In particular, it suffices to take

$$m_k \gtrsim (N_k - N_{k-1}) \cdot \log(\epsilon^{-1}) \cdot \mu(A_k) \cdot s_k \cdot \log(N), \quad 1 \leqslant k \leqslant r.$$
 (4.6)

This is exactly as one expects: the number of measurements in the kth level depends on the size of the level multiplied by the local coherence and the sparsity in that level. Note that this result recovers the standard one-level results in finite dimensions [3, 16] up to a slight deterioration in the probability bound to $1 - s\epsilon$. Specifically, the usual bound would be $1 - \epsilon$. The question as to whether or not this s can be removed in the multilevel setting is open, although such a result would be more of a cosmetic improvement.



4.2.2. Sharpness of the estimates—the nonblock-diagonal case. The previous argument demonstrated that Theorem 4.5 is sharp, up to the probability term, in the sense that it reduces to the usual estimate (4.6) for block-diagonal matrices, $S_k = s_k$. This is not true in the general setting. Clearly, $S_k \le s = s_1 + \cdots + s_r$. However, in general there is usually *interference* between different sparsity levels, which means that S_k need not have anything to do with s_k , or can indeed be proportional to the total sparsity s_k . This may seem an undesirable aspect of the theorems, since S_k may be significantly larger than s_k , and thus the estimate on the number of measurements s_k required in the s_k are an unfortunate artefact of the proof? As we now show by example, this is not the case.

Let N = rn for some $n \in \mathbb{N}$ and $\mathbf{N} = \mathbf{M} = (n, 2n, ..., rn)$. Let $W \in \mathbb{C}^{n \times n}$ and $V \in \mathbb{C}^{r \times r}$ be isometries and consider the matrix

$$A = V \otimes W$$
.

where \otimes is the usual Kronecker product. Note that $A \in \mathbb{C}^{N \times N}$ is also an isometry. Now suppose that $x = (x_1, \dots, x_r) \in \mathbb{C}^N$ is an (\mathbf{s}, \mathbf{M}) -sparse vector, where each $x_k \in \mathbb{C}^n$ is s_k -sparse. Then $Ax = y, y = (y_1, \dots, y_r), y_k = Wz_k, z_k = \sum_{l=1}^r v_{kl}x_l$. Hence the problem of recovering x from measurements y with an (\mathbf{N}, \mathbf{m}) -multilevel strategy decouples into r problems of recovering the vector z_k from the measurements $y_k = Wz_k, k = 1, \dots, r$. Let \hat{s}_k denote the sparsity of z_k . Since the coherence provides an information-theoretic limit [16], one requires at least

$$m_k \gtrsim n \cdot \mu(W) \cdot \hat{s}_k \cdot \log(n), \quad 1 \leqslant k \leqslant r$$
 (4.7)

measurements at level k in order to recover each z_k , and therefore recover x, regardless of the reconstruction method used. We now consider two examples of this setup:

EXAMPLE 4.6. Let $\pi: \{1, \ldots, r\} \to \{1, \ldots, r\}$ be a permutation and let V be the matrix with entries $v_{kl} = \delta_{l,\pi(k)}$. Since $z_k = x_{\pi(k)}$ in this case, the lower bound (4.7) reads

$$m_k \gtrsim n \cdot \mu(W) \cdot s_{\pi(k)} \cdot \log(n), \quad 1 \leqslant k \leqslant r.$$
 (4.8)

Now consider Theorem 4.5 for this matrix. First, we note that $S_k = s_{\pi(k)}$. In particular, S_k is completely unrelated to s_k . Substituting this into Theorem 4.5 and noting that $\mu_{\mathbf{N},\mathbf{M}}(k,l) = \mu(W)\delta_{l,\pi(k)}$ in this case, we arrive at the condition $m_k \gtrsim n \cdot \mu(W) \cdot s_{\pi(k)} \cdot (\log(\epsilon^{-1}) + 1) \cdot \log(nr)$, which is equivalent to (4.8) provided $r \lesssim n$.



EXAMPLE 4.7. Now suppose that V is the $r \times r$ DFT matrix. Suppose also that $s \leqslant n/r$ and that the x_k 's have disjoint support sets, that is $\operatorname{supp}(x_k) \cap \operatorname{supp}(x_l) = \emptyset$, $k \neq l$. Then by construction, each z_k is s-sparse, and therefore the lower bound (4.7) reads $m_k \gtrsim n \cdot \mu(W) \cdot s \cdot \log n$, for $1 \leqslant k \leqslant r$. After a short argument, one finds that $s/r \leqslant S_k \leqslant s$ in this case. Hence, S_k is typically much larger than s_k . Moreover, after noting that $\mu_{N,M}(k,l) = (1/r)\mu(W)$, we find that Theorem 4.5 gives the condition $m_k \gtrsim n \cdot \mu(W) \cdot s \cdot (\log(\epsilon^{-1}) + 1) \cdot \log(nr)$. Thus, Theorem 4.5 obtains the lower bound in this case as well.

4.2.3. Sparsity leads to pessimistic reconstruction guarantees. The flip test demonstrates that any sparsity-based theory of CS cannot describe the quality of the reconstructions seen in practice. To conclude this section, we now use the block-diagonal case to further emphasize the need for theorems that go beyond sparsity, such as Theorems 4.1 and 4.5. To see this, consider the block-diagonal matrix

$$U = U_1 \oplus \cdots \oplus U_r, \quad U_k \in \mathbb{C}^{(N_k - N_{k-1}) \times (N_k - N_{k-1})},$$

where each U_k is perfectly incoherent, that is $\mu(U_k) = (N_k - N_{k-1})^{-1}$, and suppose we take m_k measurements within each block U_k . Let $x \in \mathbb{C}^N$ be the signal we wish to recover, where $N = N_r$. The question is, how many samples $m = m_1 + \cdots + m_r$ do we require?

Suppose we assume that x is s-sparse, where $s ext{ } ext{ } ext{min}_{k=1,\dots,r}\{N_k-N_{k-1}\}$. Given no further information about the sparsity structure, it is necessary to take $m_k \geq s \log(N)$ measurements in each block, giving $m \geq rs \log(N)$ in total. However, suppose now that x is known to be s_k -sparse within each level, that is $|\sup(x) \cap \{N_{k-1}+1,\dots,N_k\}| = s_k$. Then we now require only $m_k \geq s_k \log(N)$, and therefore $m \geq s \log(N)$ total measurements. Thus, structured sparsity leads to a significant saving by a factor of r in the total number of measurements required. Although a cosmetic example, we note in passing that the Fourier-wavelets matrix is approximately block diagonal with incoherent blocks, and that the number of levels r in this case is proportional to the log of the signal size.

5. Main theorems II: the infinite-dimensional case

Finite-dimensional CS is suitable in many cases. However, there are some important problems where it can lead to significant problems, since the underlying problem is continuous/analogue. Discretization of the problem in order to produce a finite-dimensional, vector-space model can lead to substantial errors [3, 7, 22, 76], due to the phenomenon of model mismatch.

To address this issue, a theory of infinite-dimensional CS was introduced by two of the authors in [3], based on a novel approach to classical sampling known



as *generalized sampling* [1, 2, 4–6, 52]. We describe this theory next. Note that this infinite-dimensional CS model has also been advocated for and implemented in MRI by Guerquin-Kern, Häberlin, Pruessmann and Unser [45]. See also [53] for a practical implementation of infinite-dimensional CS in surface scattering.

5.1. Infinite-dimensional CS. Suppose that \mathcal{H} is a separable Hilbert space over \mathbb{C} , and let $\{\psi_j\}_{j\in\mathbb{N}}$ be an orthonormal basis on \mathcal{H} (the sampling basis). Let $\{\varphi_j\}_{j\in\mathbb{N}}$ be an orthonormal system in \mathcal{H} (the sparsity system), and suppose that

$$U = (u_{ij})_{i,j \in \mathbb{N}}, \quad u_{ij} = \langle \varphi_j, \psi_i \rangle, \tag{5.1}$$

is an infinite matrix. We may consider U as an element of $\mathcal{B}(l^2(\mathbb{N}))$; the space of bounded operators on $l^2(\mathbb{N})$. As in the finite-dimensional case, U is an isometry, and we may define its coherence $\mu(U) \in (0,1]$ analogously to (2.1). We want to recover $f = \sum_{j \in \mathbb{N}} x_j \varphi_j \in \mathcal{H}$ from a small number of the measurements $\hat{f} = \{\hat{f}_j\}_{j \in \mathbb{N}}$, where $\hat{f}_j = \langle f, \psi_j \rangle$. To do this, we introduce a second parameter $N \in \mathbb{N}$, and let Ω be a randomly chosen subset of indices $1, \ldots, N$ of size m. Unlike in finite dimensions, we now consider two cases. Suppose first that $P_M^\perp x = 0$, that is x has no tail. Then we solve

$$\inf_{\eta \in l^1(\mathbb{N})} \|\eta\|_{l^1} \text{ subject to } \|P_{\Omega}UP_M\eta - y\| \leqslant \delta, \tag{5.2}$$

where $y = P_{\Omega} \hat{f} + z$ and $z \in \operatorname{ran}(P_{\Omega})$ is a noise vector satisfying $||z|| \leq \delta$, and P_{Ω} is the projection operator corresponding to the index set Ω . In [3] it was proved that any solution to (5.2) recovers f exactly up to an error determined by $\sigma_{s,M}(f)$, provided N and m satisfy the so-called *weak balancing property* with respect to M and s (see Definition 5.1, as well as Remark 5.4 for a discussion), and provided

$$m \gtrsim \mu(U) \cdot N \cdot s \cdot (1 + \log(\epsilon^{-1})) \cdot \log(m^{-1}MN\sqrt{s}).$$
 (5.3)

As in the finite-dimensional case, which turns out to be a corollary of this result, we find that m is on the order of the sparsity s whenever $\mu(U)$ is sufficiently small.

In practice, the condition $P_M^{\perp}x = 0$ is unrealistic. In the more general case, $P_M^{\perp}x \neq 0$, we solve the following problem:

$$\inf_{\eta \in l^1(\mathbb{N})} \|\eta\|_{l^1} \text{ subject to } \|P_{\Omega}U\eta - y\| \leqslant \delta. \tag{5.4}$$

In [3] it was shown that any solution of (5.4) recovers f exactly up to an error determined by $\sigma_{s,M}(f)$, provided N and m satisfy the so-called *strong balancing property* with respect to M and s (see Definition 5.1), and provided



a bound similar to (5.3) holds, where the M is replaced by a slightly larger constant (we give the details in the next section in the more general setting of multilevel sampling). Note that (5.4) cannot be solved numerically, since it is infinite-dimensional. Therefore, in practice we replace (5.4) by

$$\inf_{\eta \in l^1(\mathbb{N})} \|\eta\|_{l^1} \text{ subject to } \|P_{\Omega} U P_R \eta - y\| \leqslant \delta, \tag{5.5}$$

where R is taken sufficiently large. See [3] for more information.

5.2. Main theorems. We first require the definition of the so-called *balancing property* [3]:

DEFINITION 5.1 (Balancing property). Let $U \in \mathcal{B}(l^2(\mathbb{N}))$ be an isometry. Then $N \in \mathbb{N}$ and $K \geqslant 1$ satisfy the weak balancing property with respect to $U, M \in \mathbb{N}$ and $s \in \mathbb{N}$ if

$$\|P_M U^* P_N U P_M - P_M\|_{l^{\infty} \to l^{\infty}} \le \frac{1}{8} \left(\log_2^{1/2} \left(4\sqrt{s} K M \right) \right)^{-1},$$
 (5.6)

where $\|\cdot\|_{l^{\infty}\to l^{\infty}}$ is the norm on $\mathcal{B}(l^{\infty}(\mathbb{N}))$. We say that N and K satisfy the strong balancing property with respect to U, M and s if (5.6) holds, as well as

$$\|P_M^{\perp}U^*P_NUP_M\|_{l^{\infty}\to l^{\infty}} \leqslant \frac{1}{8}.$$
 (5.7)

As in the previous section, we commence with the two-level case. Furthermore, to illustrate the differences between the weak/strong balancing property, we first consider the setting of (5.2):

THEOREM 5.2. Let $U \in \mathcal{B}(l^2(\mathbb{N}))$ be an isometry and $x \in l^1(\mathbb{N})$. Suppose that $\Omega = \Omega_{\mathbf{N},\mathbf{m}}$ is a two-level sampling scheme, where $\mathbf{N} = (N_1, N_2)$ and $\mathbf{m} = (N_1, m_2)$. Let (\mathbf{s}, \mathbf{M}) , where $\mathbf{M} = (M_1, M_2) \in \mathbb{N}^2$, $M_1 < M_2$, and $\mathbf{s} = (M_1, s_2) \in \mathbb{N}^2$, be any pair such that the following holds:

- (i) we have $||P_{N_1}^{\perp}UP_{M_1}|| \leq \gamma/\sqrt{M_1}$ and $\gamma \leq s_2\sqrt{\mu_{N_1}}$ for some $\gamma \in (0, 2/5]$;
- (ii) the parameters $N = N_2$, $K = (N_2 N_1)/m_2$ satisfy the weak balancing property with respect to U, $M := M_2$ and $s := M_1 + s_2$;
- (iii) for $\epsilon \in (0, e^{-1}]$, let

$$m_2 \gtrsim (N - N_1) \cdot \log(\epsilon^{-1}) \cdot \mu_{N_1} \cdot s_2 \cdot \log(KM\sqrt{s})$$
.



Suppose that $P_{M_2}^{\perp}x = 0$ and let $\xi \in l^1(\mathbb{N})$ be a minimizer of (5.2) with $\delta = \tilde{\delta}\sqrt{K^{-1}}$. Then, with probability exceeding $1 - s\epsilon$, we have

$$\|\xi - x\| \le C \cdot \left(\tilde{\delta} \cdot \left(1 + L \cdot \sqrt{s}\right) + \sigma_{s,\mathbf{M}}(f)\right),$$
 (5.8)

for some constant C, where $\sigma_{s,M}(f)$ is as in (3.1), and $L = 1 + \left(\sqrt{\log_2\left(6\epsilon^{-1}\right)}/\log_2(4KM\sqrt{s})\right)$. If $m_2 = N - N_1$ then this holds with probability 1.

We next state a result for multilevel sampling in the more general setting of (5.4). For this, we require the following notation: $\tilde{M} = \min\{i \in \mathbb{N} : \max_{k \ge i} \|P_N U e_k\| \le 1/(32K\sqrt{s})\}$, where N, s and K are as defined below.

THEOREM 5.3. Let $U \in \mathcal{B}(l^2(\mathbb{N}))$ be an isometry and $x \in l^1(\mathbb{N})$. Suppose that $\Omega = \Omega_{\mathbf{N},\mathbf{m}}$ is a multilevel sampling scheme, where $\mathbf{N} = (N_1, \ldots, N_r) \in \mathbb{N}^r$ and $\mathbf{m} = (m_1, \ldots, m_r) \in \mathbb{N}^r$. Let (\mathbf{s}, \mathbf{M}) , where $\mathbf{M} = (M_1, \ldots, M_r) \in \mathbb{N}^r$, $M_1 < \cdots < M_r$, and $\mathbf{s} = (s_1, \ldots, s_r) \in \mathbb{N}^r$, be any pair such that the following holds:

- (i) the parameters $N = N_r$, $K = \max_{k=1,\dots,r} \{(N_k N_{k-1})/m_k\}$, satisfy the strong balancing property with respect to U, $M := M_r$ and $s := s_1 + \dots + s_r$;
- (ii) for $\epsilon \in (0, e^{-1}]$ and $1 \le k \le r$,

$$1 \gtrsim \frac{N_k - N_{k-1}}{m_k} \cdot \log(\epsilon^{-1}) \cdot \left(\sum_{l=1}^r \mu_{\mathbf{N},\mathbf{M}}(k,l) \cdot s_l \right) \cdot \log\left(K \tilde{M} \sqrt{s}\right),$$

(with $\mu_{N,M}(k,r)$ replaced by $\mu_{N,M}(k,\infty)$) and

$$m_k \gtrsim \hat{m}_k \cdot \log(\epsilon^{-1}) \cdot \log\left(K\tilde{M}\sqrt{s}\right),$$

where \hat{m}_k satisfies (4.5).

Suppose that $\xi \in l^1(\mathbb{N})$ is a minimizer of (5.4) with $\delta = \tilde{\delta}\sqrt{K^{-1}}$. Then, with probability exceeding $1 - s\epsilon$,

$$\|\xi - x\| \le C \cdot \left(\tilde{\delta} \cdot \left(1 + L \cdot \sqrt{s}\right) + \sigma_{s,\mathbf{M}}(f)\right),$$

for some constant C, where $\sigma_{s,M}(f)$ is as in (3.1), and $L = C \cdot (1 + (\sqrt{\log_2(6\epsilon^{-1})}/\log_2(4KM\sqrt{s})))$. If $m_k = N_k - N_{k-1}$ for $1 \le k \le r$ then this holds with probability 1.



This theorem removes the condition in Theorem 5.2 that x has zero tail. Note that the price to pay is the \tilde{M} in the logarithmic term rather than M ($\tilde{M} \ge M$) because of the balancing property). Observe that \tilde{M} is finite, and in the case of Fourier sampling with wavelets, we have that $\tilde{M} = \mathcal{O}(KN)$ (see Section 6). Note that Theorem 5.2 has a strong form analogous to Theorem 5.3 which removes the tail condition. The only difference is the requirement of the strong, as opposed to the weak, balancing property, and the replacement of M by \tilde{M} in the log factor. Similarly, Theorem 5.3 has a weak form involving a tail condition. For succinctness we do not state these.

REMARK 5.4. The balancing property is the main difference between the finite-and infinite-dimensional theorems. Its role is to ensure that the truncated matrix P_NUP_M is close to an isometry. In reconstruction problems, the presence of an isometry ensures stability in the mapping between measurements and coefficients [1], which explains the need for a such a property in our theorems. As explained in [3], without the balancing property the lack of stability in this mapping leads to numerically useless reconstructions. Note that the balancing property is usually not satisfied for N = M, and in general one requires N > M for it to hold. However, there is always a finite value of N for which it is satisfied, since the infinite matrix U is an isometry. For details we refer to [3]. We provide specific estimates in Section 6 for the required magnitude of N in the case of Fourier sampling with wavelet sparsity.

The need for infinite-dimensional CS. As mentioned above, infinitedimensional CS is needed to avoid artefacts that are introduced when one applies finite-dimensional CS techniques to analogue problems. To illustrate this, we consider the problem of recovering a smooth phantom, that is a C^{∞} bivariate function, from its Fourier data. Note that this scenario arises in both electron microscopy and spectroscopy. In Figure 5, we compare finite-dimensional CS, based on solving (4.1) with $U = U_{dft}V_{dwt}^{-1}$ (discrete Fourier and wavelet transform respectively) with infinite-dimensional CS, which solves (5.5) with the Fourier basis $\{\psi_i\}_{i\in\mathbb{N}}$ and boundary wavelet basis $\{\varphi_i\}_{i\in\mathbb{N}}$. The test function in this case is $f(x, y) = \cos^2(17\pi x/2)\cos^2(17\pi y/2)\exp(-x - y)$. The improvement one gets is due to that fact that the error in infinite-dimensional case is dominated by the wavelet approximation error, whereas in the finite-dimensional case (due mismatch between the continuous Fourier samples and the discrete Fourier transform) the error is dominated by the Fourier approximation error. As is well known [64], wavelet approximation is superior to Fourier approximation and depends on the number of vanishing moments of the wavelet used (DB4 in this case).



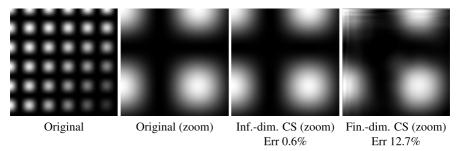


Figure 5. Subsampling 6.15%. Both reconstructions are based on identical sampling information.

6. Recovery of wavelet coefficients from Fourier samples

As noted, Fourier sampling with wavelet sparsity is an important reconstruction problem in CS, with numerous applications ranging from medical imaging to seismology and interferometry. Here we consider the Fourier sampling basis $\{\psi_j\}_{j\in\mathbb{N}}$ and wavelet reconstruction basis $\{\varphi_j\}_{j\in\mathbb{N}}$ (see Section 7.4.1 for a formal definition) with the infinite matrix U as in (5.1). Its global incoherence properties are summarized as follows:

THEOREM 6.1. Let $U \in \mathcal{B}(l^2(\mathbb{N}))$ be the matrix from (7.107) corresponding to the Fourier-wavelets system described in Section 7.4. Then $\mu(U) \geqslant \omega$, where ω is the sampling density, whereas $\mu(P_N^{\perp}U)$, $\mu(UP_N^{\perp}) = \mathcal{O}(N^{-1})$.

Thus, Fourier sampling with wavelet sparsity is indeed globally coherent, yet asymptotically incoherent. This result holds for essentially any wavelet basis in one dimension (see [54] for the multidimensional case). To recover wavelet coefficients, we shall therefore seek to apply a multilevel sampling strategy, which raises the questions: how do we design this strategy, and how many measurements are required? If the levels $\mathbf{M} = (M_1, \ldots, M_r)$ correspond to the wavelet scales, and $\mathbf{s} = (s_1, \ldots, s_r)$ to the sparsities within them, then the best one could hope to achieve is that the number of measurements m_k in the kth sampling level is proportional to the sparsity s_k in the corresponding sparsity level. Our main theorem below shows that multilevel sampling can achieve this, up to an exponentially localized factor and the usual log terms.

THEOREM 6.2. Consider an orthonormal basis of compactly supported wavelets with a multiresolution analysis (MRA). Let Φ and Ψ denote the scaling function and mother wavelet respectively satisfying (7.100) with $\alpha \geqslant 1$. Suppose that Ψ



has $v \ge 1$ vanishing moments, that the Fourier sampling density ω satisfies (7.105) and that the wavelets $\{\varphi_j\}$ are ordered according to (7.102). Let $f = \sum_{j=1}^{\infty} x_j \varphi_j$. Suppose that $\mathbf{M} = (M_1, \dots, M_r)$ corresponds to wavelet scales with $M_k = \mathcal{O}\left(2^{R_k}\right)$ with $R_k \in \mathbb{N}$, $R_{k+1} = a + R_k$, $a \ge 1$, $k = 1, \dots, r$ and $\mathbf{s} = (s_1, \dots, s_r)$ corresponds to the sparsities within them. Let $\epsilon \in (0, e^{-1}]$ and let $\Omega = \Omega_{\mathbf{N},\mathbf{m}}$ be a multilevel sampling scheme such that the following holds:

- (i) The parameters $N=N_r$, $K=\max_{k=1,\ldots,r}$, $\{(N_k-N_{k-1})/m_k\}$, $M=M_r$, $s=s_1+\cdots+s_r$ satisfy $N\gtrsim M^{1+1/(2\alpha-1)}\cdot \left(\log_2(4MK\sqrt{s})\right)^{1/(2\alpha-1)}$. Alternatively, if Φ and Ψ satisfy the slightly stronger Fourier decay property (7.101), then $N\gtrsim M\cdot \left(\log_2(4KM\sqrt{s})\right)^{1/(4\alpha-2)}$.
- (ii) For each k = 1, ..., r 1, $N_k = 2^{R_k} \omega^{-1}$ and for each k = 1, ..., r,

$$m_{k} \gtrsim \log(\epsilon^{-1}) \cdot \log(\tilde{N}) \cdot \frac{N_{k} - N_{k-1}}{N_{k-1}} \times \left(\hat{s}_{k} + \sum_{l=1}^{k-2} s_{l} \cdot 2^{-(\alpha - 1/2)A_{k,l}} + \sum_{l=k+2}^{r} s_{l} \cdot 2^{-vB_{k,l}}\right), \tag{6.1}$$

where $A_{k,l} = R_{k-1} - R_l$, $B_{k,l} = R_{l-1} - R_k$, $\tilde{N} = (K\sqrt{s})^{1+1/v}N$ and $\hat{s}_k = \max\{s_{k-1}, s_k, s_{k+1}\}$ (see Remark 6.3).

Then, with probability exceeding $1 - s\epsilon$, any minimizer $\xi \in l^1(\mathbb{N})$ of (5.4) with $\delta = \tilde{\delta}\sqrt{K^{-1}}$ satisfies

$$\|\xi - x\| \le C \cdot \left(\tilde{\delta} \cdot \left(1 + L \cdot \sqrt{s}\right) + \sigma_{s,\mathbf{M}}(f)\right),$$
 (6.2)

for some constant C, where $\sigma_{s,M}(f)$ is as in (3.1), and $L = C \cdot (1 + (\sqrt{\log_2(6\epsilon^{-1})}/\log_2(4KM\sqrt{s})))$. If $m_k = N_k - N_{k-1}$ for $1 \le k \le r$ then this holds with probability 1.

REMARK 6.3. To avoid cluttered notation we have abused notation slightly in (ii) of Theorem 6.2. In particular, we interpret $s_0 = 0$, $(N_k - N_{k-1})/N_{k-1} = N_1$ for k = 1, and $\sum_{l=1}^{k-2} s_l \cdot 2^{-(\alpha-1/2)A_{k,l}} = 0$ when $k \le 2$.

Given that one can never solve (5.4) exactly, but rather the truncated version (5.5), the following proposition provides the guidance on how the truncation needs to be carried out in order to obtain the same error bound as in Theorem 6.2.



PROPOSITION 6.4. Given the setup in Theorem 6.2 with $\xi \in l^1(\mathbb{N})$ being a minimizer of (5.4), thus satisfying the error bound (6.2). Let J be the number of wavelets up to dilation

$$R = \log_2 \left(2\pi \omega N \left(\frac{\left\| P_K^{\perp} x \right\|_2 \cdot C_{\Psi}}{\delta} \right)^{1/v} \right),\,$$

where C_{Ψ} is a constant depending only on the underlying wavelet Ψ . If one instead solves

$$\min_{\eta \in \mathbb{C}^J} \|\eta\|_{l^1} \text{ subject to } \|P_{\Omega}UP_J\eta - y\| \leqslant 2\delta, \tag{6.3}$$

then any minimizer $\tilde{\xi}$ of (6.3) satisfies the same error bound (6.2) as ξ with a potentially different constant C.

Theorem 6.2 provides the first comprehensive explanation for the observed success of CS in applications based on the Fourier-wavelets model. The key estimate (6.1) shows that m_k need only scale as a linear combination of the local sparsities s_l , $1 \le l \le r$, and critically, the dependence of the sparsities s_l for $l \ne k$ is exponentially diminishing in |k-l|. Note that the presence of the off-diagonal terms is due to the previously discussed phenomenon of interference, which occurs since the Fourier-wavelets system is not exactly block diagonal. Nonetheless, the system is nearly block diagonal, and this results in the near optimality seen in (6.1).

Observe that (6.1) is in agreement with the flip test: if the local sparsities s_k change, then the subsampling factors m_k must also change to ensure the same quality reconstruction. Having said that, it is straightforward to deduce from (6.1) the following global sparsity bound:

$$m \gtrsim s \cdot \log(\epsilon^{-1}) \cdot \log(\tilde{N}),$$

where $m = m_1 + \cdots + m_r$ is the total number of measurements and $s = s_1 + \cdots + s_r$ is the total sparsity. Note in particular the optimal exponent in the log factor.

REMARK 6.5. The Fourier/wavelets recovery problem was studied by Candès and Romberg in [17]. Their result shows that if, in an ideal setting, an image can be first separated into separate wavelet subbands before sampling, then it can be recovered using approximately s_k measurements (up to a log factor) in each sampling band. Unfortunately, such separation into separate wavelet subbands before sampling is infeasible in most practical situations. Theorem 6.2 improves on this result by removing this substantial restriction, with the sole penalty being the slightly worse bound (6.1).



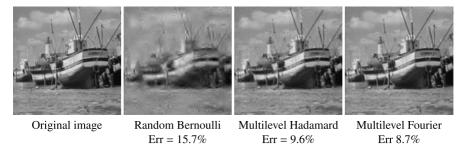


Figure 6. 12.5% subsampling at 256×256 resolution using DB4 wavelets and various different measurements.

Note also that a recovery result for bivariate Haar wavelets, as well as the related technique of TV minimization, was given in [55]. Similarly [10] analyzes block sampling strategies with application to MRI. However, these results are based on sparsity, and therefore they do not explain the conclusions of the flip test regarding how the sampling strategy will depend on the signal structure.

6.1. Universality and RIP or structure? Theorem 6.2 explains the success of CS when one is constrained to acquire Fourier measurements. Yet, due primarily to the their high global coherence with wavelets, Fourier measurements are often viewed as suboptimal for CS. If one had complete freedom to choose the measurements, and no physical constraints (such as are always present in MRI, for example), then standard CS intuition would suggest random Gaussian or Bernoulli measurements, since they are universal and satisfy the RIP.

However, in reality such measurements are actually highly suboptimal in the presence of structured sparsity. This is demonstrated in Figure 6, where an image is recovered from m=8192 measurements taken either as random Bernoulli or multilevel Hadamard or Fourier type. As is evident, the latter gives an error that is almost 50% smaller. The reason for this improvement is that whilst Fourier or Hadamard measurements are highly coherent with wavelets, they are asymptotically incoherent, and, as explained in our theoretical results, this can be exploited through multilevel random subsampling to recover the structured (that is asymptotica) sparsity of wavelet coefficients. Random Gaussian/Bernoulli measurements on the other hand do take advantage of this structure since, in satisfying an RIP, they are guaranteed to recover all sparse vectors equally well.

This observation is an important consequence of our framework. Specifically, whenever structured sparsity is present (such is the case in the majority of



imaging applications, for example) there are substantial improvements to be gained by designing the measurements according to not just the sparsity, but also the additional structure. For a more comprehensive discussion see [73], as well as [19, 83].

7. Proofs

The proofs rely on some key propositions from which one can deduce the main theorems. The main work is to prove these proposition, and that will be done subsequently.

7.1. Key results.

PROPOSITION 7.1. Let $U \in \mathcal{B}(l^2(\mathbb{N}))$ and suppose that Δ and $\Omega = \Omega_1 \cup \cdots \cup \Omega_r$ (where the union is disjoint) are subsets of \mathbb{N} . Let $x_0 \in \mathcal{H}$ and $z \in \operatorname{ran}(P_\Omega U)$ be such that $\|z\| \leq \delta$ for $\delta \geq 0$. Let $M \in \mathbb{N}$ and $y = P_\Omega U x_0 + z$ and $y_M = P_\Omega U P_M x_0 + z$. Suppose that $\xi \in \mathcal{H}$ and $\xi_M \in \mathcal{H}$ satisfy

$$\|\xi\|_{l^1} = \inf_{\eta \in \mathcal{H}} \{ \|\eta\|_{l^1} : \|P_{\Omega}U\eta - y\| \leqslant \delta \},\tag{7.1}$$

$$\|\xi_M\|_{l^1} = \inf_{\eta \in \mathbb{C}^M} \{ \|\eta\|_{l^1} : \|P_{\Omega}UP_M\eta - y_M\| \leqslant \delta \}.$$
 (7.2)

If there exists a vector $\rho = U^* P_{\Omega} w$ such that

(i)
$$\|P_{\Delta}U^*\left(q_1^{-1}P_{\Omega_1}\oplus\cdots\oplus q_r^{-1}P_{\Omega_r}\right)UP_{\Delta}-I_{\Delta}\|\leqslant \frac{1}{4}$$

(ii)
$$\max_{i \in \Delta^c} \left\| \left(q_1^{-1/2} P_{\Omega_1} \oplus \cdots \oplus q_r^{-1/2} P_{\Omega_r} \right) U e_i \right\| \leqslant \sqrt{\frac{5}{4}}$$

(iii)
$$||P_{\Delta}\rho - \operatorname{sgn}(P_{\Delta}x_0)|| \leq q/8$$

(iv)
$$\|P_{\Delta}^{\perp}\rho\|_{l^{\infty}} \leqslant \frac{1}{2}$$

(v)
$$||w|| \leqslant L \cdot \sqrt{|\Delta|}$$

for some L > 0 and $0 < q_k \le 1$, k = 1, ..., r, then we have that

$$\|\xi - x_0\| \leqslant C \cdot \left(\delta \cdot \left(\frac{1}{\sqrt{q}} + L\sqrt{s}\right) + \|P_{\Delta}^{\perp}x_0\|_{l^1}\right),$$

for some constant C, where $s = |\Delta|$ and $q = \min\{q_k\}_{k=1}^r$. Also, if (ii) is replaced by

$$\max_{i \in \{1, \dots, M\} \cap \Delta^c} \left\| \left(q_1^{-1/2} P_{\Omega_1} \oplus \dots \oplus q_r^{-1/2} P_{\Omega_r} \right) U e_i \right\| \leqslant \sqrt{\frac{5}{4}}$$



and (iv) is replaced by $\|P_M P_{\Delta}^{\perp} \rho\|_{l^{\infty}} \leqslant \frac{1}{2}$ then

$$\|\xi_M - x_0\| \le C \cdot \left(\delta \cdot \left(\frac{1}{\sqrt{q}} + L\sqrt{s}\right) + \|P_M P_\Delta^{\perp} x_0\|_{l^1}\right).$$
 (7.3)

Proof. First observe that (i) implies that

$$\left(P_{\Delta}U^*\left(q_1^{-1}P_{\Omega_1}\oplus\cdots\oplus q_r^{-1}P_{\Omega_r}\right)UP_{\Delta}|_{P_{\Delta}(\mathcal{H})}\right)^{-1}$$

exists and

$$\left\| \left(P_{\Delta} U^* \left(q_1^{-1} P_{\Omega_1} \oplus \cdots \oplus q_r^{-1} P_{\Omega_r} \right) U P_{\Delta} |_{P_{\Delta}(\mathcal{H})} \right)^{-1} \right\| \leqslant \frac{4}{3}. \tag{7.4}$$

Also, (i) implies that

$$\left\| \left(q_1^{-1/2} P_{\Omega_1} \oplus \cdots \oplus q_r^{-1/2} P_{\Omega_r} \right) U P_{\Delta} \right\|^2$$

$$= \left\| P_{\Delta} U^* \left(q_1^{-1} P_{\Omega_1} \oplus \cdots \oplus q_r^{-1} P_{\Omega_r} \right) U P_{\Delta} \right\| \leqslant \frac{5}{4}, \tag{7.5}$$

and

$$\|P_{\Delta}U^{*}\left(q_{1}^{-1}P_{\Omega_{1}}\oplus\cdots\oplus q_{r}^{-1}P_{\Omega_{r}}\right)\|^{2} = \|\left(q_{1}^{-1}P_{\Omega_{1}}\oplus\cdots\oplus q_{r}^{-1}P_{\Omega_{r}}\right)UP_{\Delta}\|^{2}$$

$$= \sup_{\|\eta\|=1} \|\left(q_{1}^{-1}P_{\Omega_{1}}\oplus\cdots\oplus q_{r}^{-1}P_{\Omega_{r}}\right)UP_{\Delta}\eta\|^{2}$$

$$= \sup_{\|\eta\|=1} \sum_{k=1}^{r} \|q_{k}^{-1}P_{\Omega_{k}}UP_{\Delta}\eta\|^{2} \leqslant \frac{1}{q} \sup_{\|\eta\|=1} \sum_{k=1}^{r} q_{k}^{-1} \|P_{\Omega_{k}}UP_{\Delta}\eta\|^{2},$$

$$= \frac{1}{q} \sup_{\|\eta\|=1} \left\langle P_{\Delta}U^{*}\left(\sum_{k=1}^{r} q_{k}^{-1}P_{\Omega_{k}}\right)UP_{\Delta}\eta, \eta\right\rangle$$

$$\leqslant \frac{1}{q} \|P_{\Delta}U^{*}\left(q_{1}^{-1}P_{\Omega_{1}}\oplus\cdots\oplus q_{r}^{-1}P_{\Omega_{r}}\right)UP_{\Delta}\|, \tag{7.6}$$

where $1/q = \max_{1 \le k \le r} \{1/q_k\}$. Thus, (7.5) and (7.6) imply

$$\left\| P_{\Delta} U^* \left(q_1^{-1} P_{\Omega_1} \oplus \cdots \oplus q_r^{-1} P_{\Omega_r} \right) \right\| \leqslant \sqrt{\frac{5}{4q}}. \tag{7.7}$$

Suppose that there exists a vector ρ , constructed with $y_0 = P_{\Delta}x_0$, satisfying (iii)–(v). Let ξ be a solution to (7.1) and let $h = \xi - x_0$. Let

$$A_{\Delta} = P_{\Delta} U^* \left(q_1^{-1} P_{\Omega_1} \oplus \cdots \oplus q_r^{-1} P_{\Omega_r} \right) U P_{\Delta} \Big|_{P_{\Delta}(\mathcal{H})}.$$



Then, it follows from (ii) and observations (7.4), (7.5), (7.7) that

$$\|P_{\Delta}h\| = \|A_{\Delta}^{-1}A_{\Delta}P_{\Delta}h\|$$

$$\leq \|A_{\Delta}^{-1}\| \|P_{\Delta}U^{*}\left(q_{1}^{-1}P_{\Omega_{1}}\oplus\cdots\oplus q_{r}^{-1}P_{\Omega_{r}}\right)U(I-P_{\Delta}^{\perp})h\|$$

$$\leq \frac{4}{3} \|P_{\Delta}U^{*}\left(q_{1}^{-1}P_{\Omega_{1}}\oplus\cdots\oplus q_{r}^{-1}P_{\Omega_{r}}\right)\| \|P_{\Omega}Uh\|$$

$$+ \frac{4}{3} \max_{i\in\Delta^{c}} \|P_{\Delta}U^{*}\left(q_{1}^{-1}P_{\Omega_{1}}\oplus\cdots\oplus q_{r}^{-1}P_{\Omega_{r}}\right)Ue_{i}\| \|P_{\Delta}^{\perp}h\|_{l^{1}}$$

$$\leq \frac{4}{3} \|P_{\Delta}U^{*}\left(q_{1}^{-1}P_{\Omega_{1}}\oplus\cdots\oplus q_{r}^{-1}P_{\Omega_{r}}\right)\| \|P_{\Omega}Uh\|$$

$$+ \frac{4}{3} \|P_{\Delta}U^{*}\left(q_{1}^{-1/2}P_{\Omega_{1}}\oplus\cdots\oplus q_{r}^{-1/2}P_{\Omega_{r}}\right)\|$$

$$\times \max_{i\in\Delta^{c}} \|\left(q_{1}^{-1/2}P_{\Omega_{1}}\oplus\cdots\oplus q_{r}^{-1/2}P_{\Omega_{r}}\right)Ue_{i}\| \|P_{\Delta}^{\perp}h\|_{l^{1}}$$

$$\leq \frac{4\sqrt{5}}{3\sqrt{q}}\delta + \frac{5}{3} \|P_{\Delta}^{\perp}h\|_{l^{1}}, \tag{7.8}$$

where in the final step we use $||P_{\Omega}Uh|| \leq ||P_{\Omega}U\zeta - y|| + ||z|| \leq 2\delta$. We now obtain a bound for $||P_{\Delta}^{\perp}h||_{l^{1}}$. First note that

$$||h + x_0||_{l^1} = ||P_{\Delta}h + P_{\Delta}x_0||_{l^1} + ||P_{\Delta}^{\perp}(h + x_0)||_{l^1}$$

$$\geqslant \operatorname{Re} \langle P_{\Delta}h, \operatorname{sgn}(P_{\Delta}x_0) \rangle + ||P_{\Delta}x_0||_{l^1} + ||P_{\Delta}^{\perp}h||_{l^1} - ||P_{\Delta}^{\perp}x_0||_{l^1}$$

$$\geqslant \operatorname{Re} \langle P_{\Delta}h, \operatorname{sgn}(P_{\Delta}x_0) \rangle + ||x_0||_{l^1} + ||P_{\Delta}^{\perp}h||_{l^1} - 2||P_{\Delta}^{\perp}x_0||_{l^1}. (7.9)$$

Since $||x_0||_{l^1} \ge ||h + x_0||_{l^1}$, we have that

$$||P_{\Delta}^{\perp}h||_{l^{1}} \le |\langle P_{\Delta}h, \operatorname{sgn}(P_{\Delta}x_{0})\rangle| + 2||P_{\Delta}^{\perp}x_{0}||_{l^{1}}.$$
 (7.10)

We use this equation later on in the proof, but before we do that observe that some basic adding and subtracting yields

$$\begin{aligned} |\langle P_{\Delta}h, \operatorname{sgn}(x_{0})\rangle| \\ &\leq |\langle P_{\Delta}h, \operatorname{sgn}(P_{\Delta}x_{0}) - P_{\Delta}\rho\rangle| + |\langle h, \rho\rangle| + \left|\langle P_{\Delta}^{\perp}h, P_{\Delta}^{\perp}\rho\rangle\right| \\ &\leq \|P_{\Delta}h\| \|\operatorname{sgn}(P_{\Delta}x_{0}) - P_{\Delta}\rho\| + |\langle P_{\Omega}Uh, w\rangle| + \|P_{\Delta}^{\perp}h\|_{l^{1}} \|P_{\Delta}^{\perp}\rho\|_{l^{\infty}} \\ &\leq \frac{q}{8} \|P_{\Delta}h\| + 2L\delta\sqrt{s} + \frac{1}{2} \|P_{\Delta}^{\perp}h\|_{l^{1}} \\ &\leq \frac{\sqrt{5q}}{6}\delta + \frac{5q}{24} \|P_{\Delta}^{\perp}h\|_{l^{1}} + 2L\delta\sqrt{s} + \frac{1}{2} \|P_{\Delta}^{\perp}h\|_{l^{1}} \end{aligned}$$
(7.11)

where the last inequality utilizes (7.8) and the penultimate inequality follows from properties (iii), (iv) and (v) of the dual vector ρ . Combining this with (7.10) and



the fact that $q \leq 1$ gives that

$$\|P_{\Delta}^{\perp}h\|_{l^{1}} \leqslant \delta\left(\frac{4\sqrt{5q}}{3} + 8L\sqrt{s}\right) + 8\|P_{\Delta}^{\perp}x_{0}\|_{l^{1}}.$$
 (7.12)

Thus, (7.8) and (7.12) yields:

$$||h|| \leqslant ||P_{\Delta}h|| + ||P_{\Delta}^{\perp}h|| \leqslant \frac{8}{3} ||P_{\Delta}^{\perp}h||_{l^{1}} + \frac{4\sqrt{5}}{3\sqrt{q}}\delta$$

$$\leqslant \left(8\sqrt{q} + 22L\sqrt{s} + \frac{3}{\sqrt{q}}\right) \cdot \delta + 22||P_{\Delta}^{\perp}x_{0}||_{l^{1}}. (7.13)$$

The proof of the second part of this proposition follows the proof as outlined above and we omit the details. \Box

The next two propositions give sufficient conditions for Proposition 7.1 to be true. But before we state them we need to define the following.

DEFINITION 7.2. Let U be an isometry of either $\mathbb{C}^{N\times N}$ or $\mathcal{B}(l^2(\mathbb{N}))$. For $\mathbf{N}=(N_1,\ldots,N_r)\in\mathbb{N}^r$, $\mathbf{M}=(M_1,\ldots,M_r)\in\mathbb{N}^r$ with $1\leqslant N_1<\cdots< N_r$ and $1\leqslant M_1<\cdots< M_r$, $\mathbf{s}=(s_1,\ldots,s_r)\in\mathbb{N}^r$ and $1\leqslant k\leqslant r$, let

$$\kappa_{\mathbf{N},\mathbf{M}}(k,l) = \max_{\eta \in \Theta} \|P_{N_k}^{N_{k-1}} U P_{M_l}^{M_{l-1}} \eta\|_{l^{\infty}} \cdot \sqrt{\mu(P_{N_k}^{N_{k-1}} U)}.$$

where

$$\Theta = \{ \eta : \|\eta\|_{l^{\infty}} \leqslant 1, |\operatorname{supp}(P_{M_{l}}^{M_{l-1}}\eta)| = s_{l}, l = 1, \dots, r-1, |\operatorname{supp}(P_{M_{r-1}}^{\perp}\eta)| = s_{r}, \},$$

and $N_0 = M_0 = 0$. We also define

$$\kappa_{\mathbf{N},\mathbf{M}}(k,\infty) = \max_{n \in \Theta} \|P_{N_k}^{N_{k-1}} U P_{M_{r-1}}^{\perp} \eta\|_{l^{\infty}} \cdot \sqrt{\mu(P_{N_k}^{N_{k-1}} U)}.$$

PROPOSITION 7.3. Let $U \in \mathcal{B}(l^2(\mathbb{N}))$ be an isometry and $x \in l^1(\mathbb{N})$. Suppose that $\Omega = \Omega_{\mathbf{N},\mathbf{m}}$ is a multilevel sampling scheme, where $\mathbf{N} = (N_1, \dots, N_r) \in \mathbb{N}^r$ and $\mathbf{m} = (m_1, \dots, m_r) \in \mathbb{N}^r$. Let (\mathbf{s}, \mathbf{M}) , where $\mathbf{M} = (M_1, \dots, M_r) \in \mathbb{N}^r$, $M_1 < \dots < M_r$, and $\mathbf{s} = (s_1, \dots, s_r) \in \mathbb{N}^r$, be any pair such that the following holds:

(i) The parameters $N := N_r$, and $K := \max_{k=1,\dots,r} (N_k - N_{k-1})/m_k$, satisfy the weak balancing property with respect to U, $M := M_r$ and $s := s_1 + \dots + s_r$;



(ii) for $\epsilon > 0$ and $1 \leq k \leq r$,

$$1 \gtrsim (\log(s\epsilon^{-1}) + 1) \cdot \frac{N_k - N_{k-1}}{m_k} \cdot \left(\sum_{l=1}^r \kappa_{\mathbf{N},\mathbf{M}}(k,l)\right) \cdot \log\left(KM\sqrt{s}\right), \quad (7.14)$$

(iii)
$$m_k \gtrsim (\log(s\epsilon^{-1}) + 1) \cdot \hat{m}_k \cdot \log(KM\sqrt{s}), \qquad (7.15)$$

where \hat{m}_k satisfies

$$1 \gtrsim \sum_{k=1}^{r} \left(\frac{N_k - N_{k-1}}{\hat{m}_k} - 1 \right) \cdot \mu_{\mathbf{N},\mathbf{M}}(k,l) \cdot \tilde{s}_k, \quad \forall l = 1, \dots, r,$$

where $\tilde{s}_1 + \cdots + \tilde{s}_r \leqslant s_1 + \cdots + s_r$, $\tilde{s}_k \leqslant S_k(s_1, \ldots, s_r)$ and S_k is defined in (4.4).

Then (i)–(v) in Proposition 7.1 follow with probability exceeding $1 - \epsilon$, with (ii) replaced by

$$\max_{i \in \{1, \dots, M\} \cap \Delta^{c}} \left\| \left(q_{1}^{-1/2} P_{\Omega_{1}} \oplus \dots \oplus q_{r}^{-1/2} P_{\Omega_{r}} \right) U e_{i} \right\| \leqslant \sqrt{\frac{5}{4}}, \tag{7.16}$$

(iv) replaced by $\|P_M P_{\Delta}^{\perp} \rho\|_{l^{\infty}} \leqslant \frac{1}{2}$ and L in (v) is given by

$$L = C \cdot \sqrt{K} \cdot \left(1 + \frac{\sqrt{\log_2(6\epsilon^{-1})}}{\log_2(4KM\sqrt{s})} \right). \tag{7.17}$$

If $m_k = N_k - N_{k-1}$ for all $1 \le k \le r$ then (i)–(v) follow with probability one (with the alterations suggested above).

PROPOSITION 7.4. Let $U \in \mathcal{B}(l^2(\mathbb{N}))$ be an isometry and $x \in l^1(\mathbb{N})$. Suppose that $\Omega = \Omega_{\mathbf{N},\mathbf{m}}$ is a multilevel sampling scheme, where $\mathbf{N} = (N_1, \dots, N_r) \in \mathbb{N}^r$ and $\mathbf{m} = (m_1, \dots, m_r) \in \mathbb{N}^r$. Let (\mathbf{s}, \mathbf{M}) , where $\mathbf{M} = (M_1, \dots, M_r) \in \mathbb{N}^r$, $M_1 < \dots < M_r$, and $\mathbf{s} = (s_1, \dots, s_r) \in \mathbb{N}^r$, be any pair such that the following holds:

(i) The parameters N and K (as in Proposition 7.3) satisfy the strong balancing property with respect to U, $M = M_r$ and $s := s_1 + \cdots + s_r$;



(ii) for $\epsilon > 0$ and $1 \leq k \leq r$,

$$1 \gtrsim (\log(s\epsilon^{-1}) + 1) \cdot \frac{N_k - N_{k-1}}{m_k} \times \left(\kappa_{\mathbf{N},\mathbf{M}}(k,\infty) + \sum_{l=1}^{r-1} \kappa_{\mathbf{N},\mathbf{M}}(k,l)\right) \cdot \log\left(K\tilde{M}\sqrt{s}\right), \quad (7.18)$$

(iii)

$$m_k \gtrsim (\log(s\epsilon^{-1}) + 1) \cdot \hat{m}_k \cdot \log(K\tilde{M}\sqrt{s}),$$
 (7.19)

where $\tilde{M} = \min\{i \in \mathbb{N} : \|\max_{j \geqslant i} P_N U P_{\{j\}}\| \leqslant 1/(K32\sqrt{s})\}$, and \hat{m}_k is as in Proposition 7.3.

Then (i)–(v) in Proposition 7.1 follow with probability exceeding $1 - \epsilon$ with L as in (7.17). If $m_k = N_k - N_{k-1}$ for all $1 \le k \le r$ then (i)–(v) follow with probability one.

LEMMA 7.5 (Bounds for $\kappa_{N,M}(k, l)$). For k, l = 1, ..., r

$$\kappa_{\mathbf{N},\mathbf{M}}(k,l) \leqslant \min \left\{ \mu_{\mathbf{N},\mathbf{M}}(k,l) \cdot s_l, \sqrt{s_l \cdot \mu(P_{N_k}^{N_{k-1}}U)} \cdot \left\| P_{N_k}^{N_{k-1}}UP_{M_l}^{M_{l-1}} \right\| \right\}. (7.20)$$

Also, for $k = 1, \ldots, r$

$$\kappa_{\mathbf{N},\mathbf{M}}(k,\infty) \leqslant \min \left\{ \mu_{\mathbf{N},\mathbf{M}}(k,\infty) \cdot s_r, \sqrt{s_r \cdot \mu(P_{N_k}^{N_{k-1}}U)} \cdot \left\| P_{N_k}^{N_{k-1}}UP_{M_{r-1}}^{\perp} \right\| \right\}. \tag{7.21}$$

Proof. For $k, l = 1, \ldots, r$

$$\begin{split} \kappa_{\mathbf{N},\mathbf{M}}(k,l) &= \max_{\eta \in \Theta} \|P_{N_k}^{N_{k-1}} U P_{M_l}^{M_{l-1}} \eta\|_{l^{\infty}} \cdot \sqrt{\mu(P_{N_k}^{N_{k-1}} U)} \\ &= \max_{\eta \in \Theta} \max_{N_{k-1} < i \leqslant N_k} \left| \sum_{M_{l-1} < j \leqslant M_l} \eta_j u_{ij} \right| \cdot \sqrt{\mu(P_{N_k}^{N_{k-1}} U)} \\ &\leqslant s_l \cdot \sqrt{\mu(P_{N_k}^{N_{k-1}} U P_{M_l}^{M_{l-1}})} \cdot \sqrt{\mu(P_{N_k}^{N_{k-1}} U)} \leqslant s_l \cdot \mu_{\mathbf{N},\mathbf{M}}(k,l) \end{split}$$



since $|u_{ij}| \leq 1$, and similarly,

$$\begin{split} \kappa_{\mathbf{N},\mathbf{M}}(k,\infty) &= \max_{\eta \in \Theta} \|P_{N_k}^{N_{k-1}} U P_{M_{r-1}}^{\perp} \eta\|_{l^{\infty}} \cdot \sqrt{\mu(P_{N_k}^{N_{k-1}} U)} \\ &= \max_{\eta \in \Theta} \max_{N_{k-1} < i \leqslant N_k} \left| \sum_{M_{r-1} < j} \eta_j u_{ij} \right| \cdot \sqrt{\mu(P_{N_k}^{N_{k-1}} U)} \leqslant s_r \cdot \mu_{\mathbf{N},\mathbf{M}}(k,\infty). \end{split}$$

Finally, it is straightforward to show that for k, l = 1, ..., r,

$$\kappa_{\mathbf{N},\mathbf{M}}(k,l) \leqslant \sqrt{s_l} \cdot \left\| P_{N_k}^{N_{k-1}} U P_{M_l}^{M_{l-1}} \right\| \sqrt{\mu(P_{N_k}^{N_{k-1}} U)}$$

and

$$\kappa_{\mathbf{N},\mathbf{M}}(k,\infty)\leqslant \sqrt{s_r}\cdot \left\|P_{N_k}^{N_{k-1}}UP_{M_{r-1}}^{\perp}\right\|\sqrt{\mu(P_{N_k}^{N_{k-1}}U)}.$$

We are now ready to prove the main theorems.

Proof of Theorems 4.1 and 5.2. It is clear that Theorem 4.1 follows from Theorem 5.2, thus it remains to prove the latter. We apply Proposition 7.3 to a two-level sampling scheme $\Omega = \Omega_{\mathbf{N},\mathbf{m}}$, where $\mathbf{N} = (N_1, N_2)$ and $\mathbf{m} = (m_1, m_2)$ with $m_1 = N_1$ and $m_2 = m$. Also, consider (\mathbf{s}, \mathbf{M}) , where $\mathbf{s} = (M_1, s_2)$, $\mathbf{M} = (M_1, M_2)$. Thus, if $N_1, N_2, m_1, m_2 \in \mathbb{N}$ are such that

$$N = N_2$$
, $K = \max \left\{ \frac{N_2 - N_1}{m_2}, \frac{N_1}{m_1} \right\}$

satisfy the weak balancing property with respect to U, $M = M_2$ and $s = M_1 + s_2$, we have that (i)–(v) in Proposition 7.1 follow with probability exceeding $1 - s\epsilon$, with (ii) replaced by

$$\max_{i \in \{1, \dots, M\} \cap \Delta^c} \| \left(P_{N_1} \oplus \frac{N_2 - N_1}{m_2} P_{\Omega_2} \right) U e_i \| \leqslant \sqrt{\frac{5}{4}},$$

(iv) replaced by $\|P_M P_{\Delta}^{\perp} \rho\|_{l^{\infty}} \leqslant \frac{1}{2}$ and L in (v) is given by (7.17), if

$$1 \gtrsim (\log(s\epsilon^{-1}) + 1) \cdot \frac{N - N_1}{m_2} \cdot (\kappa_{\mathbf{N},\mathbf{M}}(2,1) + \kappa_{\mathbf{N},\mathbf{M}}(2,2)) \cdot \log(KM\sqrt{s}),$$

$$(7.22)$$

$$m_2 \gtrsim (\log(s\epsilon^{-1}) + 1) \cdot \hat{m}_2 \cdot \log(KM\sqrt{s}),$$
 (7.23)

where \hat{m}_2 satisfies $1 \gtrsim ((N_2 - N_1)/\hat{m}_2 - 1) \cdot \mu_{N_1} \cdot \tilde{s}_2$, and $\tilde{s}_2 \leqslant S_2$ (recall S_2 from Definition 4.4). Recall from (7.20) that

$$\kappa_{\mathbf{N},\mathbf{M}}(2,1) \leqslant \sqrt{s_1 \cdot \mu_{N_1}} \cdot \|P_{N_1}^{\perp} U P_{M_1}\|, \quad \kappa_{\mathbf{N},\mathbf{M}}(2,2) \leqslant s_2 \cdot \mu_{N_1}.$$



Also, it follows directly from Definition 4.4 that

$$S_2 \leqslant \left(\|P_{N_1}^{\perp} U P_{M_1}\| \cdot \sqrt{M_1} + \sqrt{s_2} \right)^2.$$

Thus, provided that $\|P_{N_1}^{\perp}UP_{M_1}\| \le \gamma/\sqrt{M_1}$ where γ is as in (i) of Theorem 5.2, we observe that (iii) of Theorem 5.2 implies (7.22) and (7.23). Thus, the theorem now follows from Proposition 7.1.

Proof of Theorems 4.5 and 5.3. It is straightforward that Theorem 4.5 follows from Theorem 5.3. Now, recall from Lemma 7.20 that

$$\kappa_{\mathbf{N},\mathbf{M}}(k,l) \leqslant s_l \cdot \mu_{\mathbf{N},\mathbf{M}}(k,l), \quad \kappa_{\mathbf{N},\mathbf{M}}(k,\infty) \leqslant s_r \cdot \mu_{\mathbf{N},\mathbf{M}}(k,\infty), \quad k,l = 1,\ldots,r.$$

Thus, a direct application of Propositions 7.4 and 7.1 completes the proof. \Box

It remains now to prove Propositions 7.3 and 7.4. This is the content of the next sections.

7.2. Preliminaries. Before we commence on the rather length proof of these propositions, let us recall one of the monumental results in probability theory that will be of greater use later on.

THEOREM 7.6 (Talagrand [59, 79]). There exists a number K with the following property. Consider n independent random variables X_i valued in a measurable space Ω and let \mathcal{F} be a (countable) class of measurable functions on Ω . Let Z be the random variable $Z = \sup_{f \in \mathcal{F}} \sum_{i \leq n} f(X_i)$ and define

$$S = \sup_{f \in \mathcal{F}} \|f\|_{\infty}, \quad V = \sup_{f \in \mathcal{F}} \mathbb{E} \left(\sum_{i \le n} f(X_i)^2 \right).$$

If $\mathbb{E}(f(X_i)) = 0$ for all $f \in \mathcal{F}$ and $i \leq n$, then, for each t > 0, we have

$$\mathbb{P}(|Z - \mathbb{E}(Z)| \ge t) \le 3 \exp\left(-\frac{1}{K} \frac{t}{S} \log\left(1 + \frac{tS}{V + S\mathbb{E}(\overline{Z})}\right)\right),$$

where $\overline{Z} = \sup_{f \in \mathcal{F}} \left| \sum_{i \leqslant n} f(X_i) \right|$.

Note that this version of Talagrand's theorem is found in [59, Corollary 7.8]. We next present a theorem and several technical propositions that will serve as the main tools in our proofs of Propositions 7.3 and 7.4. A crucial tool herein is the Bernoulli sampling model. We use the notation $\{a, \ldots, b\} \supset \Omega \sim \text{Ber}(q)$, where a < b $a, b \in \mathbb{N}$, when Ω is given by $\Omega = \{k : \delta_k = 1\}$ and $\{\delta_k\}_{k=1}^N$ is a sequence of Bernoulli variables with $\mathbb{P}(\delta_k = 1) = q$.



DEFINITION 7.7. Let $r \in \mathbb{N}$, $\mathbf{N} = (N_1, \dots, N_r) \in \mathbb{N}^r$ with $1 \leqslant N_1 < \dots < N_r$, $\mathbf{m} = (m_1, \dots, m_r) \in \mathbb{N}^r$, with $m_k \leqslant N_k - N_{k-1}, k = 1, \dots, r$, and suppose that

$$\Omega_k \subseteq \{N_{k-1}+1,\ldots,N_k\}, \quad \Omega_k \sim \operatorname{Ber}\left(\frac{m_k}{N_k-N_{k-1}}\right), \quad k=1,\ldots,r,$$

where $N_0 = 0$. We refer to the set $\Omega = \Omega_{N,m} := \Omega_1 \cup \cdots \cup \Omega_r$. as an (N, m)-multilevel Bernoulli sampling scheme.

THEOREM 7.8. Let $U \in \mathcal{B}(l^2(\mathbb{N}))$ be an isometry. Suppose that $\Omega = \Omega_{\mathbf{N},\mathbf{m}}$ is a multilevel Bernoulli sampling scheme, where $\mathbf{N} = (N_1, \dots, N_r) \in \mathbb{N}^r$ and $\mathbf{m} = (m_1, \dots, m_r) \in \mathbb{N}^r$. Consider (\mathbf{s}, \mathbf{M}) , where $\mathbf{M} = (M_1, \dots, M_r) \in \mathbb{N}^r$, $M_1 < \dots < M_r$, and $\mathbf{s} = (s_1, \dots, s_r) \in \mathbb{N}^r$, and let

$$\Delta = \Delta_1 \cup \cdots \cup \Delta_r, \quad \Delta_k \subset \{M_{k-1} + 1, \ldots, M_k\}, \quad |\Delta_k| = s_k$$

where $M_0 = 0$. If $||P_{M_r}U^*P_{N_r}UP_{M_r} - P_{M_r}|| \le 1/8$ then, for $\gamma \in (0, 1)$,

$$\mathbb{P}(\|P_{\Delta}U^*(q_1^{-1}P_{\Omega_1}\oplus\cdots\oplus q_r^{-1}P_{\Omega_r})UP_{\Delta}-P_{\Delta}\|\geqslant 1/4)\leqslant \gamma,\tag{7.24}$$

where $q_k = m_k/(N_k - N_{k-1})$, provided that

$$1 \gtrsim \frac{N_k - N_{k-1}}{m_k} \cdot \left(\sum_{l=1}^r \kappa_{\mathbf{N},\mathbf{M}}(k,l)\right) \cdot \left(\log\left(\gamma^{-1}s\right) + 1\right). \tag{7.25}$$

In addition, if $q = \min\{q_k\}_{k=1}^r = 1$ then

$$\mathbb{P}(\|P_{\Delta}U^*(q_1^{-1}P_{\Omega_1}\oplus\cdots\oplus q_r^{-1}P_{\Omega_r})UP_{\Delta}-P_{\Delta}\|\geqslant 1/4)=0.$$

In proving this theorem we deliberately avoid the use of the Matrix Bernstein inequality [43], as Talagrand's theorem is more convenient for our infinite-dimensional setting. Before we can prove this theorem, we need the following technical lemma.

LEMMA 7.9. Let $U \in \mathcal{B}(l^2(\mathbb{N}))$ with $||U|| \leq 1$, and consider the setup in Theorem 7.8. Let $N = N_r$ and let $\{\delta_j\}_{j=1}^N$ be independent random Bernoulli variables with $\mathbb{P}(\delta_j = 1) = \tilde{q}_j, \ \tilde{q}_j = m_k/(N_k - N_{k-1}) \ and \ j \in \{N_{k-1} + 1, \dots, N_k\}, \ and \ define$ $Z = \sum_{j=1}^N Z_j, \ Z_j = (\tilde{q}_j^{-1} \delta_j - 1) \ \eta_j \otimes \bar{\eta}_j \ and \ \eta_j = P_\Delta U^* e_j.$ Then

$$\mathbb{E}\left(\|Z\|\right)^2 \leqslant 48 \max\{\log(|\Delta|), 1\} \max_{1 \leqslant j \leqslant N} \left\{ \tilde{q}_j^{-1} \|\eta_j\|^2 \right\},$$

when $(\max\{\log(|\Delta|), 1\})^{-1} \ge 18 \max_{1 \le j \le N} \{\tilde{q}_j^{-1} \|\eta_j\|^2\}.$



The proof of this lemma involves essentially reworking an argument due to Rudelson [75], and is similar to arguments given previously in [3] (see also [17]). We include it here for completeness as the setup deviates slightly. We shall also require the following result:

LEMMA 7.10 (Rudelson). Let $\eta_1, \ldots, \eta_M \in \mathbb{C}^n$ and let $\varepsilon_1, \ldots, \varepsilon_M$ be independent Bernoulli variables taking values 1, -1 with probability 1/2. Then

$$\mathbb{E}\left(\left\|\sum_{i=1}^{M} \varepsilon_{i} \bar{\eta}_{i} \otimes \eta_{i}\right\|\right) \leqslant \frac{3}{2} \sqrt{p} \max_{i \leqslant M} \|\eta_{i}\| \sqrt{\left\|\sum_{i=1}^{M} \bar{\eta}_{i} \otimes \eta_{i}\right\|},$$

where $p = \max\{2, 2\log(n)\}.$

Lemma 7.10 is often referred to as Rudelson's Lemma [75]. However, we use the above complex version that was proven by Tropp [81, Lemma 22].

Proof of Lemma 7.9. We commence by letting $\tilde{\delta} = {\{\tilde{\delta}_j\}_{j=1}^N}$ be independent copies of $\delta = {\{\delta_j\}_{j=1}^N}$. Then, since $\mathbb{E}(Z) = 0$,

$$\mathbb{E}_{\delta} (\|Z\|) = \mathbb{E}_{\delta} \left(\left\| Z - \mathbb{E}_{\tilde{\delta}} \left(\sum_{j=1}^{N} \left(\tilde{q}_{j}^{-1} \tilde{\delta}_{j} - 1 \right) \eta_{j} \otimes \bar{\eta}_{j} \right) \right\| \right)$$

$$\leq \mathbb{E}_{\delta} \left(\mathbb{E}_{\tilde{\delta}} \left(\left\| Z - \sum_{j=1}^{N} \left(\tilde{q}_{j}^{-1} \tilde{\delta}_{j} - 1 \right) \eta_{j} \otimes \bar{\eta}_{j} \right\| \right) \right), \quad (7.26)$$

by Jensen's inequality. Let $\varepsilon = \{\varepsilon_j\}_{j=1}^N$ be a sequence of Bernoulli variables taking values ± 1 with probability 1/2. Then, by (7.26), symmetry, Fubini's theorem and the triangle inequality, it follows that

$$\mathbb{E}_{\delta} (\|Z\|) \leqslant \mathbb{E}_{\varepsilon} \left(\mathbb{E}_{\delta} \left(\mathbb{E}_{\bar{\delta}} \left(\left\| \sum_{j=1}^{N} \varepsilon_{j} \left(\tilde{q}_{j}^{-1} \delta_{j} - \tilde{q}_{j}^{-1} \tilde{\delta}_{j} \right) \eta_{j} \otimes \bar{\eta}_{j} \right\| \right) \right) \right)$$

$$\leqslant 2\mathbb{E}_{\delta} \left(\mathbb{E}_{\varepsilon} \left(\left\| \sum_{j=1}^{N} \varepsilon_{j} \tilde{q}_{j}^{-1} \delta_{j} \eta_{j} \otimes \bar{\eta}_{j} \right\| \right) \right). \tag{7.27}$$

We are now able to apply Rudelson's lemma (Lemma 7.10). However, as specified before, it is the complex version that is crucial here. By Lemma 7.10 we get that



$$\mathbb{E}_{\varepsilon} \left(\left\| \sum_{j=1}^{N} \varepsilon_{j} \tilde{q}_{j}^{-1} \delta_{j} \eta_{j} \otimes \bar{\eta}_{j} \right\| \right) \leqslant \frac{3}{2} \sqrt{\max\{2 \log(s), 2\}}$$

$$\times \max_{1 \leqslant j \leqslant N} \tilde{q}_{j}^{-1/2} \| \eta_{j} \| \sqrt{\left\| \sum_{j=1}^{N} q_{j}^{-1} \tilde{q}_{j}^{-1} \delta_{j} \eta_{j} \otimes \bar{\eta}_{j} \right\|},$$

$$(7.28)$$

where $s = |\Delta|$. And hence, by using (7.27) and (7.28), it follows that

$$\mathbb{E}_{\delta}\left(\|Z\|\right) \leqslant 3\sqrt{\max\{2\log(s),2\}} \max_{1\leqslant j\leqslant N} \tilde{q}_{j}^{-1/2} \|\eta_{j}\| \sqrt{\mathbb{E}_{\delta}\left(\left\|Z + \sum_{j=1}^{N} \eta_{j} \otimes \bar{\eta}_{j}\right\|\right)}.$$

Note that $\left\|\sum_{j=1}^{N} \eta_{j} \otimes \bar{\eta}_{j}\right\| \leq 1$, since U is an isometry. The result now follows from the straightforward calculus fact that if r > 0, $c \leq 1$ and $r \leq c\sqrt{r+1}$ then we have that $r \leq c(1+\sqrt{5})/2$.

Proof of Theorem 7.8. Let $N=N_r$ just to be clear here. Let $\{\delta_j\}_{j=1}^N$ be random Bernoulli variables as defined in Lemma 7.9 and define $Z=\sum_{j=1}^N Z_j$, $Z_j=\left(\tilde{q}_j^{-1}\delta_j-1\right)\eta_j\otimes\bar{\eta}_j$ with $\eta_j=P_{\Delta}U^*e_j$. Now observe that

$$P_{\Delta}U^{*}(q_{1}^{-1}P_{\Omega_{1}}\oplus\cdots\oplus q_{r}^{-1}P_{\Omega_{r}})UP_{\Delta} = \sum_{j=1}^{N}\tilde{q}_{j}^{-1}\delta_{j}\eta_{j}\otimes\bar{\eta}_{j},$$

$$P_{\Delta}U^{*}P_{N}UP_{\Delta} = \sum_{j=1}^{N}\eta_{j}\otimes\bar{\eta}_{j}.$$

$$(7.29)$$

Thus, it follows that

$$||P_{\Delta}U^{*}(q_{1}^{-1}P_{\Omega_{1}} \oplus \cdots \oplus q_{r}^{-1}P_{\Omega_{r}})UP_{\Delta} - P_{\Delta}||$$

$$\leq ||Z|| + ||(P_{\Delta}U^{*}P_{N}UP_{\Delta} - P_{\Delta})|| \leq ||Z|| + \frac{1}{9},$$
(7.30)

by the assumption that $\|P_{M_r}U^*P_{N_r}UP_{M_r} - P_{M_r}\| \le 1/8$. Thus, to prove the assertion we need to estimate $\|Z\|$, and Talagrand's theorem (Theorem 7.6) will be our main tool. Note that clearly, since Z is self-adjoint, we have that $\|Z\| = \sup_{\zeta \in \mathcal{G}} |\langle Z\zeta, \zeta \rangle|$, where \mathcal{G} is a countable set of vectors in the unit ball of $P_{\Lambda}(\mathcal{H})$. For $\zeta \in \mathcal{G}$ define the mappings

$$\hat{\zeta}_1(T) = \langle T\zeta, \zeta \rangle, \quad \hat{\zeta}_2(T) = -\langle T\zeta, \zeta \rangle, \quad T \in \mathcal{B}(\mathcal{H}).$$



In order to use Talagrand's Theorem 7.6 we restrict the domain \mathcal{D} of the mappings ζ_i to

$$\mathcal{D} = \left\{ T \in \mathcal{B}(\mathcal{H}) : \|T\| \leqslant \max_{1 \leqslant j \leqslant N} \{ \tilde{q}_j^{-1} \|\eta_j\|^2 \} \right\}.$$

Let \mathcal{F} denote the family of mappings $\hat{\zeta}_1$, $\hat{\zeta}_2$ for $\zeta \in \mathcal{G}$. Then $||Z|| = \sup_{\hat{\zeta} \in \mathcal{F}} \hat{\zeta}(Z)$, and for i = 1, 2 we have

$$|\hat{\zeta}_i(Z_j)| = \left| \left(\tilde{q}_j^{-1} \delta_j - 1 \right) \right| \left| \left\langle \left(\eta_j \otimes \bar{\eta}_j \right) \zeta, \zeta \right\rangle \right| \leqslant \max_{1 \leqslant j \leqslant N} \{ \tilde{q}_j^{-1} \| \eta_j \|^2 \}.$$

Thus, $Z_j \in \mathcal{D}$ for $1 \leqslant j \leqslant N$ and $S := \sup_{\zeta \in \mathcal{F}} \|\hat{\zeta}\|_{\infty} = \max_{1 \leqslant j \leqslant N} \{\tilde{q}_j^{-1} \|\eta_j\|^2\}$. Note that

$$\|\eta_j\|^2 = \langle P_{\Delta}U^*e_j, P_{\Delta}U^*e_j \rangle = \sum_{k=1}^r \langle P_{\Delta_k}U^*e_j, P_{\Delta_k}U^*e_j \rangle.$$

Also, note that an easy application of Holder's inequality gives the following (note that the l^1 and l^{∞} bounds are finite because all the projections have finite rank),

$$\begin{split} |\langle P_{\Delta_k} U^* e_j, \, P_{\Delta_k} U^* e_j \rangle| &\leqslant \| P_{\Delta_k} U^* e_j \|_{l^1} \| P_{\Delta_k} U^* e_j \|_{l^{\infty}} \\ &\leqslant \| P_{\Delta_k} U^* P_{N_l}^{N_{l-1}} \|_{l^1 \to l^1} \| P_{\Delta_k} U^* e_j \|_{l^{\infty}} \\ &\leqslant \| P_{N_l}^{N_{l-1}} U P_{\Delta_k} \|_{l^{\infty} \to l^{\infty}} \cdot \sqrt{\mu(P_{N_l}^{N_{l-1}} U)} \leqslant \kappa_{\mathbf{N}, \mathbf{M}}(l, k), \end{split}$$

for $j \in \{N_{l-1} + 1, \dots, N_l\}$ and $l \in \{1, \dots, r\}$. Hence, it follows that

$$\|\eta_j\|^2 \leqslant \max_{1 \leqslant k \leqslant r} (\kappa_{\mathbf{N},\mathbf{M}}(k,1) + \dots + \kappa_{\mathbf{N},\mathbf{M}}(k,r)),$$
 (7.31)

and therefore $S \leq \max_{1 \leq k \leq r} \left(q_k^{-1} \sum_{j=1}^r \kappa_{N,M}(k,j)\right)$. Finally, note that by (7.31) and the reasoning above, it follows that

$$V := \sup_{\hat{\zeta}_{i} \in \mathcal{F}} \mathbb{E} \left(\sum_{j=1}^{N} \hat{\zeta}_{i}(Z_{j})^{2} \right) = \sup_{\zeta \in \mathcal{G}} \mathbb{E} \left(\sum_{j=1}^{N} \left(\tilde{q}_{j}^{-1} \delta_{j} - 1 \right)^{2} |\langle P_{\Delta} U^{*} e_{j}, \zeta \rangle|^{4} \right)$$

$$\leqslant \max_{1 \leqslant k \leqslant r} \|\eta_{k}\|^{2} \left(\frac{N_{k} - N_{k-1}}{m_{k}} - 1 \right) \sup_{\zeta \in \mathcal{G}} \sum_{j=1}^{N} |\langle e_{j}, U P_{\Delta} \zeta \rangle|^{2},$$

$$\leqslant \max_{1 \leqslant k \leqslant r} \frac{N_{k} - N_{k-1}}{m_{k}} \left(\sum_{l=1}^{r} \kappa_{\mathbf{N}, \mathbf{M}}(k, l) \right) \sup_{\zeta \in \mathcal{G}} \|U \zeta\|^{2}$$

$$= \max_{1 \leqslant k \leqslant r} \frac{N_{k} - N_{k-1}}{m_{k}} \left(\sum_{l=1}^{r} \kappa_{\mathbf{N}, \mathbf{M}}(k, l) \right), \tag{7.32}$$



where we used the fact that U is an isometry to deduce that ||U|| = 1. Also, by Lemma 7.9 and (7.31), it follows that

$$\mathbb{E}(\|Z\|)^{2} \leqslant 48 \max_{1 \leqslant k \leqslant r} \frac{N_{k} - N_{k-1}}{m_{k}} \left(\sum_{l=1}^{r} \kappa_{\mathbf{N}, \mathbf{M}}(k, l) \right) \cdot \log(s)$$
 (7.33)

when

$$1 \ge 18 \max_{1 \le k \le r} \frac{N_k - N_{k-1}}{m_k} \left(\sum_{l=1}^r \kappa_{\mathbf{N}, \mathbf{M}}(k, l) \right) \cdot \log(s), \tag{7.34}$$

(recall that we have assumed $s \ge 3$). Thus, by (7.30) and Talagrand's Theorem 7.6, it follows that

$$\mathbb{P}\left(\|P_{\Delta}U^{*}(q_{1}^{-1}P_{\Omega_{1}}\oplus\cdots\oplus q_{r}^{-1}P_{\Omega_{r}})UP_{\Delta}-P_{\Delta}\|\geqslant 1/4\right)
\leqslant \mathbb{P}\left(\|Z\|\geqslant \frac{1}{16}+\sqrt{24\max_{1\leqslant k\leqslant r}\frac{N_{k}-N_{k-1}}{m_{k}}\left(\sum_{l=1}^{r}\kappa_{\mathbf{N},\mathbf{M}}(k,l)\right)\cdot\log(s)}\right)
\leqslant 3\exp\left(-\frac{1}{16K}\left(\max_{1\leqslant k\leqslant r}\frac{N_{k}-N_{k-1}}{m_{k}}\left(\sum_{l=1}^{r}\kappa_{\mathbf{N},\mathbf{M}}(k,l)\right)\right)^{-1}\log(1+1/32)\right),$$
(7.35)

when m_k 's are chosen such that the right hand side of (7.33) is less than or equal to 1. Thus, by (7.30) and Talagrand's Theorem 7.6, it follows that

$$\mathbb{P}\left(\|P_{\Delta}U^{*}(q_{1}^{-1}P_{\Omega_{1}}\oplus\cdots\oplus q_{r}^{-1}P_{\Omega_{r}})UP_{\Delta}-P_{\Delta}\|\geqslant 1/4\right)
\leqslant \mathbb{P}\left(\|Z\|\geqslant 1/8\right) \leqslant \mathbb{P}\left(\|Z\|\geqslant \frac{1}{16}+\mathbb{E}\|Z\|\right) \leqslant \mathbb{P}\left(\|Z\|-\mathbb{E}\|Z\|\|\geqslant \frac{1}{16}\right)
\leqslant 3\exp\left(-\frac{1}{16K}\left(\max_{1\leqslant k\leqslant r}\frac{N_{k}-N_{k-1}}{m_{k}}\left(\sum_{l=1}^{r}\kappa_{\mathbf{N},\mathbf{M}}(k,l)\right)\right)^{-1}\log\left(1+1/32\right)\right),$$
(7.36)

when m_k 's are chosen such that the right hand side of (7.33) is less than or equal to $1/16^2$. Note that this condition is implied by the assumptions of the theorem as is (7.34). This yields the first part of the theorem. The second claim of this theorem follows from the assumption that $||P_{M_r}U^*P_{N_r}UP_{M_r} - P_{M_r}|| \le 1/8$.

PROPOSITION 7.11. Let $U \in \mathcal{B}(l^2(\mathbb{N}))$ be an isometry. Suppose that $\Omega = \Omega_{N,m}$ is a multilevel Bernoulli sampling scheme, where $\mathbf{N} = (N_1, \dots, N_r) \in \mathbb{N}^r$ and



 $\mathbf{m} = (m_1, \dots, m_r) \in \mathbb{N}^r$. Consider (\mathbf{s}, \mathbf{M}) , where $\mathbf{M} = (M_1, \dots, M_r) \in \mathbb{N}^r$, $M_1 < \dots < M_r$, and $\mathbf{s} = (s_1, \dots, s_r) \in \mathbb{N}^r$, and let $\Delta = \Delta_1 \cup \dots \cup \Delta_r$, $\Delta_k \subset \{M_{k-1}, \dots, M_k\}$, $|\Delta_k| = s_k$, where $M_0 = 0$. Let $\beta \ge 1/4$.

(i) If

$$N := N_r, \quad K := \max_{k=1,\dots,r} \left\{ \frac{N_k - N_{k-1}}{m_k} \right\},$$

satisfy the weak balancing property with respect to U, $M := M_r$ and $s := s_1 + \cdots + s_r$, then, for $\xi \in \mathcal{H}$ and $\beta, \gamma > 0$, we have that

$$\mathbb{P}\left(\|P_M P_\Delta^\perp U^*(q_1^{-1} P_{\Omega_1} \oplus \cdots \oplus q_r^{-1} P_{\Omega_r}) U P_\Delta \xi\|_{l^\infty} > \beta \|\xi\|_{l^\infty}\right) \leqslant \gamma, \quad (7.37)$$

provided that

$$\frac{\beta}{\log\left(\frac{4}{\gamma}(M-s)\right)} \geqslant C \Lambda, \quad \frac{\beta^2}{\log\left(\frac{4}{\gamma}(M-s)\right)} \geqslant C \Upsilon, \tag{7.38}$$

for some constant C > 0, where $q_k = m_k/(N_k - N_{k-1})$ for k = 1, ..., r,

$$\Lambda = \max_{1 \le k \le r} \left\{ \frac{N_k - N_{k-1}}{m_k} \cdot \left(\sum_{l=1}^r \kappa_{\mathbf{N}, \mathbf{M}}(k, l) \right) \right\},\tag{7.39}$$

$$\Upsilon = \max_{1 \leqslant l \leqslant r} \sum_{k=1}^{r} \left(\frac{N_k - N_{k-1}}{m_k} - 1 \right) \cdot \mu_{\mathbf{N}, \mathbf{M}}(k, l) \cdot \tilde{s}_k, \tag{7.40}$$

for all $\{\tilde{s}_k\}_{k=1}^r$ such that $\tilde{s}_1 + \dots + \tilde{s}_r \leqslant s_1 + \dots + s_r$ and $\tilde{s}_k \leqslant S_k(s_1, \dots, s_r)$. Moreover, if $q_k = 1$ for all $k = 1, \dots, r$, then (7.38) is trivially satisfied for any $\gamma > 0$ and the left-hand side of (7.37) is equal to zero.

(ii) If N satisfies the strong Balancing Property with respect to U, M and s, then, for $\xi \in \mathcal{H}$ and $\beta, \gamma > 0$, we have that

$$\mathbb{P}\left(\|P_{\Delta}^{\perp}U^{*}(q_{1}^{-1}P_{\Omega_{1}}\oplus\cdots\oplus q_{r}^{-1}P_{\Omega_{r}})UP_{\Delta}\xi\|_{l^{\infty}}>\beta\|\xi\|_{l^{\infty}}\right)\leqslant\gamma,\quad (7.41)$$

provided that

$$\frac{\beta}{\log\left(4/\gamma(\tilde{\theta}-s)\right)} \geqslant C \Lambda, \quad \frac{\beta^2}{\log\left(4/\gamma(\tilde{\theta}-s)\right)} \geqslant C \Upsilon, \tag{7.42}$$

for some constant C > 0, $\tilde{\theta} = \tilde{\theta}(\{q_k\}_{k=1}^r, 1/8, \{N_k\}_{k=1}^r, s, M)$ and Υ , Λ as defined in (i) and



$$\widetilde{\theta}(\{q_k\}_{k=1}^r, t, \{N_k\}_{k=1}^r, s, M)
= \left| \left\{ i \in \mathbb{N} : \max_{\substack{\Gamma_1 \subset \{1, \dots, M\}, \\ \Gamma_{2,j} \subset \{N_{j-1}+1, \dots, N_j\}, \\ j=1, \dots, r}} |\Gamma_1| = s
\|P_{\Gamma_1} U^*(q_1^{-1} P_{\Gamma_{2,1}} \oplus \cdots \oplus q_r^{-1} P_{\Gamma_{2,r}}) U e_i \| > \frac{t}{\sqrt{s}} \right\} \right|.$$

Moreover, if $q_k = 1$ for all k = 1, ..., r, then (7.42) is trivially satisfied for any $\gamma > 0$ and the left-hand side of (7.41) is equal to zero.

Proof. To prove (i) we note that, without loss of generality, we can assume that $\|\xi\|_{l^{\infty}} = 1$. Let $\{\delta_j\}_{j=1}^N$ be random Bernoulli variables with $\mathbb{P}(\delta_j = 1) = \tilde{q}_j = q_k$, for $j \in \{N_{k-1} + 1, \dots, N_k\}$ and $1 \le k \le r$. A key observation that will be crucial below is that

$$P_{\Delta}^{\perp}U^{*}(q_{1}^{-1}P_{\Omega_{1}} \oplus \cdots \oplus q_{r}^{-1}P_{\Omega_{r}})UP_{\Delta}\xi = \sum_{j=1}^{N} P_{\Delta}^{\perp}U^{*}\tilde{q}_{j}^{-1}\delta_{j}(e_{j} \otimes e_{j})UP_{\Delta}\xi$$

$$= \sum_{j=1}^{N} P_{\Delta}^{\perp}U^{*}(\tilde{q}_{j}^{-1}\delta_{j} - 1)(e_{j} \otimes e_{j})UP_{\Delta}\xi + P_{\Delta}^{\perp}U^{*}P_{N}UP_{\Delta}\xi. \tag{7.43}$$

We use this equation at the end of the argument, but first we estimate the size of the individual components of $\sum_{j=1}^{N} P_{\Delta}^{\perp} U^* (\tilde{q}_j^{-1} \delta_j - 1) (e_j \otimes e_j) U P_{\Delta} \xi$. To do that define, for $1 \leq j \leq N$, the random variables

$$X_i^i = \langle U^*(\tilde{q}_i^{-1}\delta_j - 1)(e_j \otimes e_j)UP_{\Delta}\xi, e_i \rangle, \quad i \in \Delta^c.$$

We show using Bernstein's inequality that, for each $i \in \Delta^c$ and t > 0,

$$\mathbb{P}\left(\left|\sum_{j=1}^{N} X_{j}^{i}\right| > t\right) \leqslant 4 \exp\left(-\frac{t^{2}/4}{\Upsilon + \Lambda t/3}\right). \tag{7.44}$$

To prove the claim, we need to estimate $\mathbb{E}(|X_i^i|^2)$ and $|X_i^i|$. First note that,

$$\mathbb{E}\left(|X_j^i|^2\right) = (\tilde{q}_j^{-1} - 1)|\langle e_j, UP_\Delta \xi \rangle|^2 |\langle e_j, Ue_i \rangle|^2,$$

and note that $|\langle e_j, Ue_i \rangle|^2 \le \mu_{N,M}(k, l)$ for $j \in \{N_{k-1} + 1, ..., N_k\}$ and $i \in \{M_{l-1} + 1, ..., M_l\}$. Hence



$$\begin{split} \sum_{j=1}^{N} \mathbb{E}\left(|X_{j}^{i}|^{2}\right) &\leqslant \sum_{k=1}^{r} (q_{k}^{-1} - 1)\mu_{\mathbf{N},\mathbf{M}}(k,l) \|P_{N_{k}}^{N_{k-1}} U P_{\Delta} \xi\|^{2} \\ &\leqslant \sup_{\zeta \in \Theta} \left\{ \sum_{k=1}^{r} (q_{k}^{-1} - 1)\mu_{\mathbf{N},\mathbf{M}}(k,l) \|P_{N_{k}}^{N_{k-1}} U \zeta\|^{2} \right\}, \end{split}$$

where

$$\Theta = \{ \eta : \|\eta\|_{l^{\infty}} \leqslant 1, |\operatorname{supp}(P_{M_l}^{M_{l-1}}\eta)| = s_l, \ l = 1, \dots, r \}.$$

The supremum in the above bound is attained for some $\tilde{\zeta} \in \Theta$. If $\tilde{s}_k = \|P_{N_k}^{N_{k-1}} U \tilde{\zeta}\|^2$, then we have

$$\sum_{i=1}^{N} \mathbb{E}\left(|X_{j}^{i}|^{2}\right) \leqslant \sum_{k=1}^{r} (q_{k}^{-1} - 1) \mu_{\mathbf{N},\mathbf{M}}(k, l) \tilde{s}_{k}. \tag{7.45}$$

Note that it is clear from the definition that $s_k \leqslant S_k(s_1, \ldots, s_r)$ for $1 \leqslant k \leqslant r$. Also, using the fact that $||U|| \leqslant 1$ and the definition of Θ , we note that

$$\tilde{s}_1 + \dots + \tilde{s}_r = \sum_{k=1}^r \|P_{N_k}^{N_{k-1}} U P_{\Delta} \zeta\|^2 \le \|U P_{\Delta} \zeta\|^2 = \|\zeta\|^2 \le s_1 + \dots + s_r.$$

To estimate $|X_j^i|$ we start by observing that, by the triangle inequality, the fact that $\|\xi\|_{l^\infty}=1$ and Holder's inequality, it follows that $|\langle \xi, P_\Delta U^* e_j \rangle| \leq \sum_{k=1}^r |\langle P_{M_k}^{M_{k-1}} \xi, P_\Delta U^* e_j \rangle|$, and

$$|\langle P_{M_k}^{M_{k-1}} \xi, P_{\Delta} U^* e_j \rangle| \leq ||P_{N_l}^{N_{l-1}} U P_{\Delta_k}||_{l^{\infty} \to l^{\infty}},$$

 $j \in \{N_{l-1} + 1, \dots, N_l\}, l \in \{1, \dots, r\}.$

Hence, it follows that for $1 \le j \le N$ and $i \in \Delta^c$,

$$|X_{j}^{i}| = \tilde{q}_{j}^{-1}|(\delta_{j} - \tilde{q}_{j})||\langle \xi, P_{\Delta}U^{*}e_{j}\rangle||\langle e_{j}, Ue_{i}\rangle|,$$

$$\leq \max_{1 \leq k \leq r} \left\{ \frac{N_{k} - N_{k-1}}{m_{k}} \cdot \left(\kappa_{\mathbf{N},\mathbf{M}}(k, 1) + \dots + \kappa_{\mathbf{N},\mathbf{M}}(k, r)\right) \right\}. \tag{7.46}$$

Now, clearly $\mathbb{E}(X_j^i) = 0$ for $1 \le j \le N$ and $i \in \Delta^c$. Thus, by applying Bernstein's inequality to $\text{Re}(X_j^i)$ and $\text{Im}(X_j^i)$ for j = 1, ..., N, via (7.45) and (7.46), the claim (7.44) follows.



Now, by (7.44), (7.43) and the assumed weak Balancing property (wBP), it follows that

$$\mathbb{P}\left(\|P_{M}P_{\Delta}^{\perp}U^{*}(q_{1}^{-1}P_{\Omega_{1}}\oplus\cdots\oplus q_{r}^{-1}P_{\Omega_{r}})UP_{\Delta}\xi\|_{l^{\infty}}>\beta\right)$$

$$\leq \sum_{i\in\Delta^{c}\cap\{1,\dots,M\}}\mathbb{P}\left(\left|\sum_{j=1}^{N}X_{j}^{i}+\langle P_{M}P_{\Delta}^{\perp}U^{*}P_{N}^{\perp}UP_{\Delta}\xi,e_{i}\rangle\right|>\beta\right)$$

$$\leq \sum_{i\in\Delta^{c}\cap\{1,\dots,M\}}\mathbb{P}\left(\left|\sum_{j=1}^{N}X_{j}^{i}\right|>\beta-\|P_{M}P_{\Delta}^{\perp}U^{*}P_{N}UP_{\Delta}\|_{l^{\infty}}\right)$$

$$\leq 4(M-s)\exp\left(-\frac{t^{2}/4}{\Upsilon+\Delta t/3}\right), \quad t=\frac{1}{2}\beta, \quad \text{by (7.44), (wBP)}.$$

Also,

$$4(M-s)\exp\left(-\frac{t^2/4}{\Upsilon+\Lambda t/3}\right) \leqslant \gamma$$

when

$$\log\left(\frac{4}{\gamma}(M-s)\right)^{-1} \geqslant \left(\frac{4\gamma}{t^2} + \frac{4\Lambda}{3t}\right).$$

And this concludes the proof of (i). To prove (ii), for t > 0, suppose that there is a set $\Lambda_t \subset \mathbb{N}$ such that

$$\mathbb{P}\left(\sup_{i\in A_t}|\langle P_{\Delta}^{\perp}U^*(q_1^{-1}P_{\Omega_1}\oplus\cdots\oplus q_r^{-1}P_{\Omega_r})UP_{\Delta}\eta,e_i\rangle|>t\right)=0,\quad |A_t^c|<\infty.$$

Then, as before, by (7.44), (7.43) and the assumed strong Balancing property (sBP), it follows that

$$\mathbb{P}\left(\|P_{\Delta}^{\perp}U^{*}(q_{1}^{-1}P_{\Omega_{1}}\oplus\cdots\oplus q_{r}^{-1}P_{\Omega_{r}})UP_{\Delta}\xi\|_{l^{\infty}}>eta
ight) \ \leqslant \sum_{i\in\Delta^{c}\cap\Delta^{c}_{i}}\mathbb{P}\left(\left|\sum_{j=1}^{N}X_{j}^{i}+\langle P_{\Delta}^{\perp}U^{*}P_{N}^{\perp}UP_{\Delta}\xi,e_{i}
angle
ight|>eta
ight),$$

yielding

$$\begin{split} & \mathbb{P}\left(\|P_{\Delta}^{\perp}U^{*}(q_{1}^{-1}P_{\Omega_{1}}\oplus\cdots\oplus q_{r}^{-1}P_{\Omega_{r}})UP_{\Delta}\xi\|_{l^{\infty}}>\beta\right) \\ & \leqslant \sum_{i\in\Delta^{c}\cap\Lambda_{t}^{c}}\mathbb{P}\left(\left|\sum_{j=1}^{N}X_{j}^{i}\right|>\beta-\|P_{\Delta}^{\perp}U^{*}P_{N}UP_{\Delta}\|_{l^{\infty}}\right) \\ & \leqslant 4\left(\left|\Lambda_{t}^{c}\right|-s\right)\exp\left(-\frac{t^{2}/4}{\Upsilon+\Lambda t/3}\right)<\gamma, \quad t=\frac{1}{2}\beta, \quad \text{by (7.44), (sBP),} \end{split}$$



whenever

$$\log\left(\frac{4}{\gamma}\left(\left|\Lambda_{t}^{c}\right|-s\right)\right)^{-1}\geqslant\left(\frac{4\gamma}{t^{2}}+\frac{4\Lambda}{3t}\right).$$

Hence, it remains to obtain a bound on $|\Lambda_t^c|$. Let

$$\theta(q_{1},...,q_{r},t,s) = \begin{cases} i: \max_{\substack{\Gamma_{1} \subset \{1,...,M\}, \\ \Gamma_{2,j} \subset \{N_{j-1}+1,...,N_{j}\}, \\ \end{cases}} |\Gamma_{1}| = s} \|P_{\Gamma_{1}}U^{*}(q_{1}^{-1}P_{\Gamma_{2,1}} \oplus \cdots \oplus q_{r}^{-1}P_{\Gamma_{2,r}})Ue_{i}\| \\ > \frac{t}{\sqrt{s}} \end{cases}.$$

Clearly, $\Delta_t^c \subset \theta(q_1, \ldots, q_r, t, s)$ and

$$\|P_{\Gamma_1}U^*(q_1^{-1}P_{\Gamma_{2,1}}\oplus\cdots\oplus q_r^{-1}P_{\Gamma_{2,r}})Ue_i\|\leqslant \max_{1\leqslant j\leqslant r}q_j^{-1}\|P_NUP_{i-1}^{\perp}\|\to 0$$

as $i \to \infty$. So, $|\theta(q_1, \dots, q_r, t, s)| < \infty$. Also, since $\tilde{\theta}(\{q_k\}_{k=1}^r, t, \{N_k\}_{k=1}^r, s, M)$ is a decreasing function in t, for all $t \ge \frac{1}{8}$,

$$|\theta(q_1,\ldots,q_r,t,s)| < \tilde{\theta}(\{q_k\}_{k=1}^r,1/8,\{N_k\}_{k=1}^r,s,M)$$

thus, we have proved (ii). The statements at the end of (i) and (ii) are clear from the reasoning above. \Box

PROPOSITION 7.12. Consider the same setup as in Proposition 7.11. If N and K satisfy the weak Balancing Property with respect to U, M and s, then, for $\xi \in \mathcal{H}$ and $\gamma > 0$, we have

$$\mathbb{P}(\|P_{\Delta}U^*(q_1^{-1}P_{\Omega_1}\oplus\cdots\oplus q_r^{-1}P_{\Omega_r})UP_{\Delta}-P_{\Delta})\xi\|_{l^{\infty}}>\tilde{\alpha}\|\xi\|_{l^{\infty}})\leqslant \gamma,\quad (7.47)$$

with $\tilde{\alpha} = \left(2\log_2^{1/2}\left(4\sqrt{s}KM\right)\right)^{-1}$, provided that

$$1 \gtrsim \Lambda \cdot (\log(s\gamma^{-1}) + 1) \cdot \log(\sqrt{s}KM)$$
,

$$1 \gtrsim \Upsilon \cdot (\log(s\gamma^{-1}) + 1) \cdot \log(\sqrt{s}KM)$$
,

where Λ and Υ are defined in (7.39) and (7.40). Also,

$$\mathbb{P}(\|P_{\Delta}U^{*}(q_{1}^{-1}P_{\Omega_{1}}\oplus\cdots\oplus q_{r}^{-1}P_{\Omega_{r}})UP_{\Delta}-P_{\Delta})\xi\|_{l^{\infty}}>\frac{1}{2}\|\xi\|_{l^{\infty}})\leqslant\gamma \qquad (7.48)$$

provided that

$$1 \gtrsim \Lambda \cdot (\log(s\gamma^{-1}) + 1), \quad 1 \gtrsim \Upsilon \cdot (\log(s\gamma^{-1}) + 1).$$



Moreover, if $q_k = 1$ for all k = 1, ..., r, then the left-hand sides of (7.47) and (7.48) are equal to zero.

Proof. Without loss of generality we may assume that $\|\xi\|_{l^{\infty}} = 1$. Let $\{\delta_j\}_{j=1}^N$ be random Bernoulli variables with $\mathbb{P}(\delta_j = 1) = \tilde{q}_j := q_k$, with $j \in \{N_{k-1} + 1, \ldots, N_k\}$ and $1 \leq k \leq r$. Let also, for $j \in \mathbb{N}$, $\eta_j = (UP_{\Delta})^*e_j$. Then, after observing that

$$P_{\Delta}U^*(q_1^{-1}P_{\Omega_1} \oplus \cdots \oplus q_r^{-1}P_{\Omega_r})UP_{\Delta} = \sum_{j=1}^N q_j^{-1}\delta_j\eta_j \otimes \bar{\eta}_j, \ P_{\Delta}U^*P_NUP_{\Delta}$$
$$= \sum_{j=1}^N \eta_j \otimes \bar{\eta}_j,$$

it follows immediately that

$$P_{\Delta}U^{*}(q_{1}^{-1}P_{\Omega_{1}} \oplus \cdots \oplus q_{r}^{-1}P_{\Omega_{r}})UP_{\Delta} - P_{\Delta}$$

$$= \sum_{j=1}^{N} (\tilde{q}_{j}^{-1}\delta_{j} - 1)\eta_{j} \otimes \bar{\eta}_{j} - (P_{\Delta}U^{*}P_{N}UP_{\Delta} - P_{\Delta}). \tag{7.49}$$

As in the proof of Proposition 7.11 our goal is to eventually use Bernstein's inequality and the following is therefore a setup for that. Define, for $1 \le j \le N$, the random variables $Z_j^i = \langle (\tilde{q}_j^{-1}\delta_j - 1)(\eta_j \otimes \bar{\eta}_j)\xi, e_i \rangle$, for $i \in \Delta$. We claim that, for t > 0,

$$\mathbb{P}\left(\left|\sum_{j=1}^{N} Z_{j}^{i}\right| > t\right) \leqslant 4 \exp\left(-\frac{t^{2}/4}{\gamma + \Lambda t/3}\right), \quad i \in \Delta.$$
 (7.50)

Now, clearly $\mathbb{E}(Z_j^i) = 0$, so we may use Bernstein's inequality. Thus, we need to estimate $\mathbb{E}(|Z_i^i|^2)$ and $|Z_i^i|$. We start with $\mathbb{E}(|Z_i^i|^2)$. Note that

$$\mathbb{E}\left(|Z_{j}^{i}|^{2}\right) = (\tilde{q}_{j}^{-1} - 1)|\langle e_{j}, UP_{\Delta}\xi\rangle|^{2}|\langle e_{j}, Ue_{i}\rangle|^{2}. \tag{7.51}$$

Thus, we can argue exactly as in the proof of Proposition 7.11 and deduce that

$$\sum_{i=1}^{N} \mathbb{E}\left(|Z_{j}^{i}|^{2}\right) \leqslant \sum_{k=1}^{r} (q_{k}^{-1} - 1)\mu_{N_{k-1}}\tilde{s}_{k},\tag{7.52}$$

where $s_k \leqslant S_k(s_1, \ldots, s_r)$ for $1 \leqslant k \leqslant r$ and $\tilde{s}_1 + \cdots + \tilde{s}_r \leqslant s_1 + \cdots + s_r$. To estimate $|Z_i^i|$ we argue as in the proof of Proposition 7.11 and obtain

$$|Z_j^i| \le \max_{1 \le k \le r} \left\{ \frac{N_k - N_{k-1}}{m_k} \cdot (\kappa_{\mathbf{N},\mathbf{M}}(k,1) + \dots + \kappa_{\mathbf{N},\mathbf{M}}(k,r)) \right\}.$$
 (7.53)



Thus, by applying Bernstein's inequality to $Re(Z_1^i), \ldots, Re(Z_N^i)$ and the imaginary part $Im(Z_1^i), \ldots, Im(Z_N^i)$ we obtain, via (7.52) and (7.53) the estimate (7.50), and we have proved the claim.

Now armed with (7.50) we can deduce that, by (7.43) and the assumed weak Balancing property (wBP), it follows that

$$\mathbb{P}\left(\|P_{\Delta}U^{*}(q_{1}^{-1}P_{\Omega_{1}}\oplus\cdots\oplus q_{r}^{-1}P_{\Omega_{r}})UP_{\Delta}-P_{\Delta})\xi\|_{l^{\infty}}>\tilde{\alpha}\right)$$

$$\leq \sum_{i\in\Delta}\mathbb{P}\left(\left|\sum_{j=1}^{N}Z_{j}^{i}+\langle(P_{\Delta}U^{*}P_{N}UP_{\Delta}-P_{\Delta})\xi,e_{i}\rangle\right|>\tilde{\alpha}\right)$$

$$\leq \sum_{i\in\Delta}\mathbb{P}\left(\left|\sum_{j=1}^{N}Z_{j}^{i}\right|>\tilde{\alpha}-\|P_{M}U^{*}P_{N}UP_{M}-P_{M}\|_{l^{1}}\right),$$

$$\leq 4s\exp\left(-\frac{t^{2}/4}{\Upsilon+\Lambda t/3}\right), \quad t=\tilde{\alpha}, \quad \text{by (7.50), (wBP)}.$$
(7.54)

Also,

$$4s \exp\left(-\frac{t^2/4}{\gamma + \Lambda t/3}\right) \leqslant \gamma,\tag{7.55}$$

when

$$1 \geqslant \left(\frac{4\Upsilon}{t^2} + \frac{4}{3t}\Lambda\right) \cdot \log\left(\frac{4s}{\gamma}\right).$$

And this gives the first part of the proposition. Also, the fact that the left-hand side of (7.47) is zero when $q_k = 1$ for $1 \le k \le r$ is clear from (7.55). Note that (ii) follows by arguing exactly as above and replacing $\tilde{\alpha}$ by $\frac{1}{4}$.

PROPOSITION 7.13. Let $U \in \mathcal{B}(l^2(\mathbb{N}))$ such that $||U|| \leq 1$. Suppose that $\Omega = \Omega_{\mathbf{N},\mathbf{m}}$ is a multilevel Bernoulli sampling scheme, where $\mathbf{N} = (N_1, \dots, N_r) \in \mathbb{N}^r$ and $\mathbf{m} = (m_1, \dots, m_r) \in \mathbb{N}^r$. Consider (\mathbf{s}, \mathbf{M}) , where $\mathbf{M} = (M_1, \dots, M_r) \in \mathbb{N}^r$, $M_1 < \dots < M_r$, and $\mathbf{s} = (s_1, \dots, s_r) \in \mathbb{N}^r$, and let $\Delta = \Delta_1 \cup \dots \cup \Delta_r$, where $\Delta_k \subset \{M_{k-1} + 1, \dots, M_k\}$, $|\Delta_k| = s_k$, and $M_0 = 0$. Then, for any $t \in (0, 1)$ and $\gamma \in (0, 1)$,

$$\mathbb{P}\left(\max_{i\in\{1,\ldots,M\}\cap\Delta^c}\|P_{\{i\}}U^*(q_1^{-1}P_{\Omega_1}\oplus\cdots\oplus q_r^{-1}P_{\Omega_r})UP_{\{i\}}\|\geqslant 1+t\right)\leqslant\gamma$$

provided that

$$\frac{t^2}{4} \geqslant \log\left(\frac{2M}{\gamma}\right) \cdot \max_{1 \leqslant k \leqslant r} \left\{ \left(\frac{N_k - N_{k-1}}{m_k} - 1\right) \cdot \mu_{\mathbf{N},\mathbf{M}}(k,l) \right\} \tag{7.56}$$



for all $l=1,\ldots,r$ when $M=M_r$ and for all $l=1,\ldots,r-1,\infty$ when $M>M_r$. In addition, if $m_k=N_k-N_{k-1}$ for each $k=1,\ldots,r$, then

$$\mathbb{P}(\|P_{\{i\}}U^*(q_1^{-1}P_{\Omega_1}\oplus\cdots\oplus q_r^{-1}P_{\Omega_r})UP_{\{i\}}\|\geqslant 1+t)=0, \quad \forall i\in\mathbb{N}. \quad (7.57)$$

Proof. Fix $i \in \{1, ..., M\}$. Let $\{\delta_j\}_{j=1}^N$ be random independent Bernoulli variables with $\mathbb{P}(\delta_j = 1) = \tilde{q}_j := q_k$ for $j \in \{N_{k-1} + 1, ..., N_k\}$. Define $Z = \sum_{j=1}^N Z_j$ and $Z_j = (\tilde{q}_j^{-1}\delta_j - 1) |u_{ji}|^2$. Now observe that

$$P_{\{i\}}U^*(q_1^{-1}P_{\Omega_1}\oplus\cdots\oplus q_r^{-1}P_{\Omega_r})UP_{\{i\}}=\sum_{j=1}^N\tilde{q}_j^{-1}\delta_j\left|u_{ji}\right|^2=\sum_{j=1}^NZ_j+\sum_{j=1}^N\left|u_{ji}\right|^2,$$

where we interpret U as the infinite matrix $U = \{u_{ij}\}_{i,j \in \mathbb{N}}$. Thus, since $||U|| \leq 1$,

$$||P_{\{i\}}U^*(q_1^{-1}P_{\Omega_1} \oplus \cdots \oplus q_r^{-1}P_{\Omega_r})UP_{\{i\}}|| \le \left|\sum_{j=1}^N Z_j\right| + 1$$
 (7.58)

and it is clear that (7.57) is true. For the case where $q_k < 1$ for some $k \in \{1, ..., r\}$, observe that for $i \in \{M_{l-1} + 1, ..., M_l\}$ (recall that Z_j depend on i), we have that $\mathbb{E}(Z_j) = 0$. Also,

$$\left| Z_{j} \right| \leqslant \begin{cases} \max_{1 \leqslant k \leqslant r} \{ \max\{q_{k}^{-1} - 1, 1\} \cdot \mu_{\mathbf{N}, \mathbf{M}}(k, l) \} := B_{i} \\ i \in \{ M_{l-1} + 1, \dots, M_{l} \}, \\ \max_{1 \leqslant k \leqslant r} \{ \max\{q_{k}^{-1} - 1, 1\} \cdot \mu_{\mathbf{N}, \mathbf{M}}(k, \infty) \} := B_{\infty} \quad i > M_{r}, \end{cases}$$

and, by again using the assumption that $||U|| \le 1$,

$$\sum_{j=1}^{N} \mathbb{E}\left(\left|Z_{j}\right|^{2}\right) = \sum_{j=1}^{N} (\tilde{q}_{j}^{-1} - 1) \left|u_{ji}\right|^{4}$$

$$\leq \begin{cases} \max_{1 \leq k \leq r} \{(q_{k}^{-1} - 1) \mu_{\mathbf{N},\mathbf{M}}(k, l)\} =: \sigma_{i}^{2} & i \in \{M_{l-1} + 1, \dots, M_{l}\}, \\ \max_{1 \leq k \leq r} \{(q_{k}^{-1} - 1) \mu_{\mathbf{N},\mathbf{M}}(k, \infty)\} =: \sigma_{\infty}^{2} & i > M_{r}. \end{cases}$$

Thus, by Bernstein's inequality and (7.58),

$$\mathbb{P}(\|P_{\{i\}}U^*(q_1^{-1}P_{\Omega_1}\oplus\cdots\oplus q_r^{-1}P_{\Omega_r})UP_{\{i\}}\|\geqslant 1+t)$$

$$\leqslant \mathbb{P}\left(\left|\sum_{j=1}^N Z_j\right|\geqslant t\right)\leqslant 2\exp\left(-\frac{t^2/2}{\sigma^2+Bt/3}\right),$$



$$B = \begin{cases} \max_{1 \leqslant i \leqslant r} B_i & M = M_r, \\ \max_{i \in \{1, \dots, r-1, \infty\}} B_i & M > M_r, \end{cases} \quad \sigma^2 = \begin{cases} \max_{1 \leqslant i \leqslant r} \sigma_i^2 & M = M_r, \\ \max_{i \in \{1, \dots, r-1, \infty\}} \sigma_1^2 & M > M_r. \end{cases}$$

Applying the union bound yields

$$\mathbb{P}\left(\max_{i\in\{1,...,M\}}\|P_{\{i\}}U^*(q_1^{-1}P_{\Omega_1}\oplus\cdots\oplus q_r^{-1}P_{\Omega_r})UP_{\{i\}}\|\geqslant 1+t\right)\leqslant\gamma$$

whenever (7.56) holds.

7.3. Proofs of Propositions 7.3 and 7.4. The proof of the propositions relies on an idea that originated in a paper by Gross [43], namely, the golfing scheme. The variant we are using here is based on an idea from [3] as well as uneven section techniques from [47, 48], see also [42]. However, the informed reader will recognize that the setup here differs substantially from both [43] and [3]. See also [16] for other examples of the use of the golfing scheme. Before we embark on the proof, we state and prove a useful lemma.

LEMMA 7.14. Let \tilde{X}_k be independent binary variables taking values 0 and 1, such that $\tilde{X}_k = 1$ with probability P. Then,

$$\mathbb{P}\left(\sum_{i=1}^{N} \tilde{X}_{i} \geqslant k\right) \geqslant \left(\frac{N \cdot e}{k}\right)^{-k} \binom{N}{k} P^{k}. \tag{7.59}$$

Proof. First observe that

$$\mathbb{P}\left(\sum_{i=1}^{N} \tilde{X}_{i} \geqslant k\right) = \sum_{i=k}^{N} \binom{N}{i} P^{i} (1-P)^{N-i} = \sum_{i=0}^{N-k} \binom{N}{i+k} P^{i+k} (1-P)^{N-k-i} \\
= \binom{N}{k} P^{k} \sum_{i=0}^{N-k} \frac{(N-k)!k!}{(N-i-k)!(i+k)!} P^{i} (1-P)^{N-k-i} \\
= \binom{N}{k} P^{k} \sum_{i=0}^{N-k} \binom{N-k}{i} P^{i} (1-P)^{N-k-i} \left[\binom{i+k}{k} \right]^{-1}.$$

The result now follows because $\sum_{i=0}^{N-k} {N-k \choose i} P^i (1-P)^{N-k-i} = 1$ and for $i=0,\ldots,N-k$, we have that

$$\binom{i+k}{k} \leqslant \left(\frac{(i+k)\cdot e}{k}\right)^k \leqslant \left(\frac{N\cdot e}{k}\right)^k,$$

where the first inequality follows from Stirling's approximation (see [24], page 1186).



Proof of Proposition 7.3. We start by mentioning that converting from the Bernoulli sampling model and uniform sampling model has become standard in the literature. In particular, one can do this by showing that the Bernoulli model implies (up to a constant) the uniform sampling model in each of the conditions in Proposition 7.1. This is straightforward and the reader may consult [17, 18, 41] for details. We therefore consider (without loss of generality) only the multilevel Bernoulli sampling scheme.

Recall that we are using the following Bernoulli sampling model: given $N_0 = 0$, $N_1, \ldots, N_r \in \mathbb{N}$ we let

$$\{N_{k-1}+1,\ldots,N_k\}\supset \Omega_k \sim \text{Ber}(q_k), \quad q_k = \frac{m_k}{N_k - N_{k-1}}.$$

Note that we may replace this Bernoulli sampling model with the following equivalent sampling model (see [3]):

$$\Omega_k = \Omega_k^1 \cup \Omega_k^2 \cup \cdots \cup \Omega_k^u, \quad \Omega_k^j \sim \operatorname{Ber}(q_k^j), \quad 1 \leqslant k \leqslant r,$$

for some $u \in \mathbb{N}$ with

$$(1 - q_k^1)(1 - q_k^2) \cdots (1 - q_k^u) = (1 - q_k). \tag{7.60}$$

The latter model is the one we use throughout the proof and the specific value of u will be chosen later. Note also that because of overlaps we have

$$q_k^1 + q_k^2 + \dots + q_k^u \geqslant q_k, \quad 1 \leqslant k \leqslant r.$$
 (7.61)

The strategy of the proof is to show the validity of (i) and (ii), and the existence of a $\rho \in \text{ran}(U^*(P_{\Omega_1} \oplus \cdots \oplus P_{\Omega_r}))$ that satisfies (iii)–(v) in Proposition 7.1 with probability exceeding $1 - \epsilon$, where (iii) is replaced by (7.16), (iv) is replaced by $\|P_M P_{\Lambda}^{\perp} \rho\|_{l^{\infty}} \leqslant \frac{1}{2}$ and L in (v) is given by (7.17).

Step I. The construction of ρ : we start by defining $\gamma = \epsilon/6$ (the reason for this particular choice will become clear later). We also define a number of quantities (and the reason for these choices will become clear later in the proof):

$$u = 8\lceil 3v + \log(\gamma^{-1}) \rceil, \quad v = \lceil \log_2(8KM\sqrt{s}) \rceil, \tag{7.62}$$

as well as

$$\{q_k^i: 1 \leq k \leq r, 1 \leq i \leq u\}, \{\alpha_i\}_{i=1}^u, \{\beta_i\}_{i=1}^u$$

by

$$q_k^1 = q_k^2 = \frac{1}{4}q_k, \quad \tilde{q}_k = q_k^3 = \dots = q_k^u, \quad q_k = (N_k - N_{k-1})m_k^{-1}, \quad 1 \leqslant k \leqslant r,$$
(7.63)



with

$$(1-q_k^1)(1-q_k^2)\cdots(1-q_k^u)=(1-q_k)$$

and

$$\alpha_1 = \alpha_2 = (2\log_2^{1/2}(4KM\sqrt{s}))^{-1}, \quad \alpha_i = 1/2, \quad 3 \le i \le u,$$
 (7.64)

as well as

$$\beta_1 = \beta_2 = \frac{1}{4}, \quad \beta_i = \frac{1}{4} \log_2(4KM\sqrt{s}), \quad 3 \leqslant i \leqslant u.$$
 (7.65)

Consider now the following construction of ρ . We define recursively the sequences $\{Z_i\}_{i=0}^u \subset \mathcal{H}$, $\{Y_i\}_{i=1}^u \subset \mathcal{H}$ and $\{\omega_i\}_{i=0}^u \subset \mathbb{N}$ as follows: first let $\omega_0 = \{0\}$, $\omega_1 = \{0, 1\}$ and $\omega_2 = \{0, 1, 2\}$. Then define recursively, for $i \geqslant 3$, the following:

$$\omega_{i} = \begin{cases}
\omega_{i-1} \cup \{i\} & \text{if } \left\| \left(P_{\Delta} - P_{\Delta} U^{*} \left(\frac{1}{q_{1}^{i}} P_{\Omega_{1}^{i}} \oplus \cdots \oplus \frac{1}{q_{r}^{i}} P_{\Omega_{r}^{i}} \right) U P_{\Delta} \right) Z_{i-1} \right\|_{l^{\infty}} \\
\leqslant \alpha_{i} \| P_{\Delta_{k}} Z_{i-1} \|_{l^{\infty}}, \\
\text{and } \left\| P_{M} P_{\Delta}^{\perp} U^{*} \left(\frac{1}{q_{1}^{i}} P_{\Omega_{1}^{i}} \oplus \cdots \oplus \frac{1}{q_{r}^{i}} P_{\Omega_{r}^{i}} \right) U P_{\Delta} Z_{i-1} \right\|_{l^{\infty}} (7.66) \\
\leqslant \beta_{i} \| Z_{i-1} \|_{l^{\infty}}, \\
\omega_{i-1} & \text{otherwise}, \end{cases}$$

$$Y_{i} = \begin{cases}
\sum_{j \in \omega_{i}} U^{*} \left(\frac{1}{q_{1}^{j}} P_{\Omega_{1}^{j}} \oplus \cdots \oplus \frac{1}{q_{r}^{j}} P_{\Omega_{r}^{j}} \right) U Z_{j-1} & \text{if } i \in \omega_{i}, \\
Y_{i-1} & \text{otherwise}, \end{cases}$$

$$Z_{i} = \begin{cases}
\operatorname{sgn}(x_{0}) - P_{\Delta} Y_{i} & \text{if } i \in \omega_{i}, \\
Z_{i-1} & \text{otherwise}, \end{cases}$$

$$i \geqslant 1, Z_{0} = \operatorname{sgn}(x_{0}).$$

Now, let $\{A_i\}_{i=1}^2$ and $\{B_i\}_{i=1}^5$ denote the following events

$$\begin{split} A_i: & \left\| \left(P_{\Delta} - U^* \left(\frac{1}{q_1^i} P_{\Omega_1^i} \oplus \cdots \oplus \frac{1}{q_r^i} P_{\Omega_r^i} \right) U P_{\Delta} \right) Z_{i-1} \right\|_{l^{\infty}} \leqslant \alpha_i \, \| Z_{i-1} \|_{l^{\infty}} \,, \\ & i = 1, 2, \\ B_i: & \left\| P_M P_{\Delta}^{\perp} U^* \left(\frac{1}{q_1^i} P_{\Omega_1^i} \oplus \cdots \oplus \frac{1}{q_r^i} P_{\Omega_r^i} \right) U P_{\Delta} Z_{i-1} \right\|_{l^{\infty}} \leqslant \beta_i \| Z_{i-1} \|_{l^{\infty}}, \\ & i = 1, 2. \end{split}$$



$$B_3: \quad \left\| P_{\Delta} U^* \left(\frac{1}{q_1} P_{\Omega_1} \oplus \cdots \oplus \frac{1}{q_r} P_{\Omega_r} \right) U P_{\Delta} - P_{\Delta} \right\| \leqslant 1/4,$$

$$\max_{i \in \Delta^c \cap \{1, \dots, M\}} \left\| \left(q_1^{-1/2} P_{\Omega_1} \oplus \cdots \oplus q_r^{-1/2} P_{\Omega_r} \right) U e_i \right\| \leqslant \sqrt{5/4}$$

 $B_4: |\omega_u| \geqslant v$,

 $B_5: (\bigcap_{i=1}^2 A_i) \cap (\bigcap_{i=1}^4 B_i).$

(7.67)

Also, let $\tau(j)$ denote the jth element in ω_u (for example, $\tau(0) = 0$, $\tau(1) = 1$, $\tau(2) = 2$) and finally define ρ by

$$\rho = \begin{cases} Y_{\tau(v)} & \text{if } B_5 \text{ occurs,} \\ 0 & \text{otherwise.} \end{cases}$$

Note that, clearly, $\rho \in \text{ran}(U^*P_{\Omega})$, and we just need to show that when the event B_5 occurs, then (i)–(v) in Proposition 7.1 will follow.

Step II. $B_5 \Rightarrow (i)$, (ii). To see that the assertion is true, note that if B_5 occurs then B_3 occurs, which immediately (i) and (ii).

Step III. $B_5 \Rightarrow (iii)$, (iv). To show the assertion, we start by making the following observations: by the construction of $Z_{\tau(i)}$ and the fact that $Z_0 = \operatorname{sgn}(x_0)$, it follows that

$$\begin{split} Z_{\tau(i)} &= Z_0 - \left(P_{\Delta} U^* \left(\frac{1}{q_1^{\tau(1)}} P_{\Omega_1^{\tau(1)}} \oplus \cdots \oplus \frac{1}{q_r^{\tau(1)}} P_{\Omega_r^{\tau(i)}} \right) U P_{\Delta} \right) Z_0 \\ &+ \cdots + \left(P_{\Delta} U^* \left(\frac{1}{q_1^{\tau(i)}} P_{\Omega_1^{\tau(i)}} \oplus \cdots \oplus \frac{1}{q_r^{\tau(i)}} P_{\Omega_r^{\tau(i)}} \right) U P_{\Delta} \right) Z_{\tau(i-1)} \\ &= Z_{\tau(i-1)} - \left(P_{\Delta} U^* \left(\frac{1}{q_1^{\tau(i)}} P_{\Omega_1^{\tau(i)}} \oplus \cdots \oplus \frac{1}{q_r^{\tau(i)}} P_{\Omega_r^{\tau(i)}} \right) U P_{\Delta} \right) Z_{\tau(i-1)} \\ &i \leq |\omega_r|, \end{split}$$

so we immediately get that

$$Z_{\tau(i)} = \left(P_{\Delta} - P_{\Delta}U^* \left(\frac{1}{q_1^{\tau(i)}} P_{\Omega_1^{\tau(i)}} \oplus \cdots \oplus \frac{1}{q_r^{\tau(i)}} P_{\Omega_r^{\tau(i)}}\right) U P_{\Delta}\right) Z_{\tau(i-1)}, \quad i \leqslant |\omega_u|.$$

Hence, if the event B_5 occurs, we have, by the choices in (7.64) and (7.65)

$$\|\rho - \operatorname{sgn}(x_0)\| = \|Z_{\tau(v)}\| \leqslant \sqrt{s} \|Z_{\tau(v)}\|_{l^{\infty}} \leqslant \sqrt{s} \prod_{i=1}^{v} \alpha_{\tau(i)} \leqslant \frac{\sqrt{s}}{2^{v}} \leqslant \frac{1}{8K}, \quad (7.68)$$



since we have chosen $v = \lceil \log_2(8KM\sqrt{s}) \rceil$. Also,

$$\|P_{M}P_{\Delta}^{\perp}\rho\|_{l^{\infty}} \leqslant \sum_{i=1}^{v} \|P_{M}P_{\Delta}^{\perp}U^{*}\left(\frac{1}{q_{1}^{\tau(i)}}P_{\Omega_{1}^{\tau(i)}}\oplus\cdots\oplus\frac{1}{q_{r}^{\tau(i)}}P_{\Omega_{r}^{\tau(i)}}\right)UP_{\Delta}Z_{\tau(i-1)}\|_{l^{\infty}}$$

$$\leqslant \sum_{i=1}^{v} \beta_{\tau(i)}\|Z_{\tau(i-1)}\|_{l^{\infty}} \leqslant \sum_{i=1}^{v} \beta_{\tau(i)}\prod_{j=1}^{i-1} \alpha_{\tau(j)}$$

$$\leqslant \frac{1}{4}\left(1+\frac{1}{2\log_{2}^{1/2}(a)}+\frac{\log_{2}(a)}{2^{3}\log_{2}(a)}+\cdots+\frac{1}{2^{v-1}}\right) \leqslant \frac{1}{2}, \quad (7.69)$$

where $a = 4KM\sqrt{s}$. In particular, (7.68) and (7.69) imply (iii) and (iv) in Proposition 7.1.

Step IV. $B_5 \Rightarrow (v)$. To show that, note that we may write the already constructed ρ as $\rho = U^* P_{\Omega} w$ where

$$w = \sum_{i=1}^{v} w_i, \quad w_i = \left(\frac{1}{q_1^{\tau(i)}} P_{\Omega_1} \oplus \cdots \oplus \frac{1}{q_r^{\tau(i)}} P_{\Omega_r}\right) U P_{\Delta} Z_{\tau(i-1)}.$$

To estimate ||w|| we simply compute

$$\|w_{i}\|^{2} = \left\langle \left(\frac{1}{q_{1}^{\tau(i)}} P_{\Omega_{1}^{\tau(i)}} \oplus \cdots \oplus \frac{1}{q_{r}^{\tau(i)}} P_{\Omega_{r}^{\tau(i)}} \right) U P_{\Delta} Z_{\tau(i-1)}, \right.$$

$$\left(\frac{1}{q_{1}^{\tau(i)}} P_{\Omega_{1}^{\tau(i)}} \oplus \cdots \oplus \frac{1}{q_{r}^{\tau(i)}} P_{\Omega_{r}^{\tau(i)}} \right) U P_{\Delta} Z_{\tau(i-1)} \right\rangle$$

$$= \sum_{k=1}^{r} \left(\frac{1}{q_{k}^{\tau(i)}} \right)^{2} \|P_{\Omega_{k}^{\tau(i)}} U Z_{\tau(i-1)}\|^{2},$$

and then use the assumption that the event B_5 holds to deduce that

$$\begin{split} & \sum_{k=1}^{r} \left(\frac{1}{q_{k}^{\tau(i)}}\right)^{2} \|P_{\mathcal{Q}_{k}^{\tau(i)}} U Z_{\tau(i-1)}\|^{2} \\ & \leqslant \max_{1 \leqslant k \leqslant r} \left\{\frac{1}{q_{k}^{\tau(i)}}\right\} \left\langle \sum_{k=1}^{r} \frac{1}{q_{k}^{\tau(i)}} P_{\Delta} U^{*} P_{\Omega_{k}^{\tau(i)}} U Z_{\tau(i-1)}, Z_{\tau(i-1)} \right\rangle \\ & = \max_{1 \leqslant k \leqslant r} \left\{\frac{1}{q_{k}^{\tau(i)}}\right\} \left\langle \left(\sum_{k=1}^{r} \frac{1}{q_{k}^{\tau(i)}} P_{\Delta} U^{*} P_{\Omega_{k}^{\tau(i)}} U - P_{\Delta} \right) Z_{\tau(i-1)}, Z_{\tau(i-1)} \right\rangle \end{split}$$



$$\begin{split} & + \|Z_{\tau(i-1)}\|^2 \\ & \leqslant \max_{1 \leqslant k \leqslant r} \left\{ \frac{1}{q_k^{\tau(i)}} \right\} \left(\|Z_{\tau(i-1)}\| \|Z_{\tau(i)}\| + \|Z_{\tau(i-1)}\|^2 \right) \\ & \leqslant \max_{1 \leqslant k \leqslant r} \left\{ \frac{1}{q_k^{\tau(i)}} \right\} s \left(\|Z_{\tau(i-1)}\|_{l^{\infty}} \|Z_{\tau(i)}\|_{l^{\infty}} + \|Z_{\tau(i-1)}\|_{l^{\infty}}^2 \right) \\ & \leqslant \max_{1 \leqslant k \leqslant r} \left\{ \frac{1}{q_k^{\tau(i)}} \right\} s(\alpha_i + 1) \left(\prod_{j=1}^{i-1} \alpha_j \right)^2, \end{split}$$

where the last inequality follows from the assumption that the event B_5 holds. Hence

$$\|w\| \leqslant \sqrt{s} \sum_{i=1}^{\nu} \left(\max_{1 \leqslant k \leqslant r} \left\{ \frac{1}{\sqrt{q_k^{\tau(i)}}} \right\} \sqrt{\alpha_i + 1} \prod_{j=1}^{i-1} \alpha_j \right). \tag{7.70}$$

Note that, due to the fact that $q_k^1 + \cdots + q_k^u \ge q_k$, we have that

$$\tilde{q}_k \geqslant \frac{m_k}{2(N_k - N_{k-1})} \frac{1}{8 \lceil \log(\gamma^{-1}) + 3 \lceil \log_2(8KM\sqrt{s}) \rceil \rceil - 2}.$$

This gives, in combination with the chosen values of $\{\alpha_i\}$ and (7.70) that

$$\begin{split} \|w\| &\leqslant 2\sqrt{s} \max_{1 \leqslant k \leqslant r} \sqrt{\frac{N_k - N_{k-1}}{m_k}} \left(1 + \frac{1}{2\log_2^{1/2} \left(4KM\sqrt{s}\right)}\right)^{3/2} \\ &+ \sqrt{s} \max_{1 \leqslant k \leqslant r} \sqrt{\frac{N_k - N_{k-1}}{m_k}} \cdot \frac{\sqrt{3}}{2} \\ &\times \frac{\sqrt{8 \left\lceil \log(\gamma^{-1}) + 3 \left\lceil \log_2(8KM\sqrt{s}) \right\rceil \right\rceil - 2}}{\log_2 \left(4KM\sqrt{s}\right)} \cdot \sum_{i=3}^v \frac{1}{2^{i-3}} \\ &\leqslant 2\sqrt{s} \max_{1 \leqslant k \leqslant r} \sqrt{\frac{N_k - N_{k-1}}{m_k}} \\ &\times \left(\left(\frac{3}{2}\right)^{3/2} + \sqrt{\frac{6}{\log_2(4KM\sqrt{s})}} \sqrt{1 + \frac{\log_2\left(\gamma^{-1}\right) + 6}{\log_2(4KM\sqrt{s})}}\right) \end{split}$$



$$\leq \sqrt{s} \max_{1 \leq k \leq r} \sqrt{\frac{N_k - N_{k-1}}{m_k}} \times \left(\frac{3\sqrt{3}}{\sqrt{2}} + \frac{2\sqrt{6}}{\sqrt{\log_2(4KM\sqrt{s})}} \sqrt{1 + \frac{\log_2(\gamma^{-1}) + 6}{\log_2(4KM\sqrt{s})}} \right). \tag{7.71}$$

Step V. The weak balancing property, (7.14) and (7.15) $\Rightarrow \mathbb{P}(A_1^c \cup A_2^c \cup B_1^c \cup B_2^c \cup B_3^c) \leqslant 5\gamma$. To see this, note that by Proposition 7.12 we immediately get (recall that $q_k^1 = q_k^2 = 1/4q_k$) that $\mathbb{P}(A_1^c) \leqslant \gamma$ and $\mathbb{P}(A_2^c) \leqslant \gamma$ as long as the weak balancing property and

$$1 \gtrsim \Lambda \cdot (\log(s\gamma^{-1}) + 1) \cdot \log(\sqrt{s}KM), 1 \gtrsim \gamma \cdot (\log(s\gamma^{-1}) + 1) \cdot \log(\sqrt{s}KM),$$

$$(7.72)$$

are satisfied, where $K = \max_{1 \le k \le r} (N_k - N_{k-1})/m_k$,

$$\Lambda = \max_{1 \leqslant k \leqslant r} \left\{ \frac{N_k - N_{k-1}}{m_k} \cdot \left(\sum_{l=1}^r \kappa_{\mathbf{N}, \mathbf{M}}(k, l) \right) \right\}, \tag{7.73}$$

$$\Upsilon = \max_{1 \leqslant l \leqslant r} \sum_{k=1}^{r} \left(\frac{N_k - N_{k-1}}{m_k} - 1 \right) \cdot \mu_{\mathbf{N}, \mathbf{M}}(k, l) \cdot \tilde{s}_k, \tag{7.74}$$

and where $\tilde{s}_1 + \cdots + \tilde{s}_r \leqslant s_1 + \cdots + s_r$ and $\tilde{s}_k \leqslant S_k(s_1, \ldots, s_r)$. However, clearly, (7.14) and (7.15) imply (7.72). Also, Proposition 7.11 yields that $\mathbb{P}(B_1^c) \leqslant \gamma$ and $\mathbb{P}(B_2^c) \leqslant \gamma$ as long as the weak balancing property and

$$1 \gtrsim \Lambda \cdot \log\left(\frac{4}{\gamma}(M-s)\right), \quad 1 \gtrsim \Upsilon \cdot \log\left(\frac{4}{\gamma}(M-s)\right),$$
 (7.75)

are satisfied. However, again, (7.14) and (7.15) imply (7.75). Finally, it remains to bound $\mathbb{P}(B_3^c)$. First note that by Theorem 7.8, we may deduce that

$$\mathbb{P}\left(\|P_{\Delta}U^*\left(\frac{1}{q_1}P_{\Omega_1}\oplus\cdots\oplus\frac{1}{q_r}P_{\Omega_r}\right)UP_{\Delta}-P_{\Delta}\|>1/4,\right)\leqslant\gamma/2,$$

when the weak balancing property and

$$1 \gtrsim \Lambda \cdot \left(\log\left(\gamma^{-1}s\right) + 1\right) \tag{7.76}$$

holds and (7.14) implies (7.76).

For the second part of B_3 , we may deduce from Proposition 7.13 that

$$\mathbb{P}\left(\max_{i\in\Delta^{c}\cap\{1,\dots,M\}}\left\|\left(q_{1}^{-1/2}P_{\Omega_{1}}\oplus\cdots\oplus q_{r}^{-1/2}P_{\Omega_{r}}\right)Ue_{i}\right\|>\sqrt{5/4}\right)\leqslant\frac{\gamma}{2},$$



whenever

$$1 \gtrsim \log\left(\frac{2M}{\gamma}\right) \cdot \max_{1 \leqslant k \leqslant r} \left\{ \left(\frac{N_k - N_{k-1}}{m_k} - 1\right) \cdot \mu_{\mathbf{N},\mathbf{M}}(k,l) \right\}, \quad l = 1, \dots, r$$

$$(7.77)$$

which is true whenever (7.14) holds. Indeed, recalling the definition of $\kappa_{N,M}(k,j)$ and Θ in Definition 7.2, observe that

$$\max_{\eta \in \Theta, \|\eta\|_{\infty} = 1} \sum_{l=1}^{r} \left\| P_{N_{k}}^{N_{k-1}} U P_{M_{l}}^{M_{l-1}} \eta \right\|_{\infty} \geqslant \max_{\eta \in \Theta, \|\eta\|_{\infty} = 1} \left\| P_{N_{k}}^{N_{k-1}} U \eta \right\|_{\infty} \geqslant \sqrt{\mu (P_{N_{k}}^{N_{k-1}} U P_{M_{l}}^{M_{l-1}})}$$

$$(7.78)$$

for each $l=1,\ldots,r$ which implies that $\sum_{j=1}^r \kappa_{\mathbf{N},\mathbf{M}}(k,j) \geqslant \mu_{\mathbf{N},\mathbf{M}}(k,l)$, for $l=1,\ldots,r$. Consequently, (7.77) follows from (7.14). Thus, $\mathbb{P}(B_3^c) \leqslant \gamma$.

Step VI. The weak balancing property, (7.14) and (7.15) $\Rightarrow \mathbb{P}(B_4^c) \leqslant \gamma$. To see this, define the random variables X_1, \ldots, X_{u-2} by

$$X_{j} = \begin{cases} 0 & \omega_{j+2} \neq \omega_{j+1}, \\ 1 & \omega_{j+2} = \omega_{j+1}. \end{cases}$$
 (7.79)

We immediately observe that

$$\mathbb{P}(B_4^c) = \mathbb{P}(|\omega_u| < v) = \mathbb{P}(X_1 + \dots + X_{u-2} > u - v). \tag{7.80}$$

However, the random variables X_1, \ldots, X_{u-2} are not independent, and we therefore cannot directly apply the standard Chernoff bound. In particular, we must adapt the setup slightly. Note that

$$\mathbb{P}(X_{1} + \dots + X_{u-2} > u - v)
\leq \sum_{l=1}^{\binom{u-2}{u-v}} \mathbb{P}(X_{\pi(l)_{1}} = 1, X_{\pi(l)_{2}} = 1, \dots, X_{\pi(l)_{u-v}} = 1)
= \sum_{l=1}^{\binom{u-2}{u-v}} \mathbb{P}(X_{\pi(l)_{u-v}} = 1 \mid X_{\pi(l)_{1}} = 1, \dots, X_{\pi(l)_{u-v-1}} = 1)
\times \mathbb{P}(X_{\pi(l)_{1}} = 1, \dots, X_{\pi(l)_{u-v-1}} = 1)
= \sum_{l=1}^{\binom{u-2}{u-v}} \mathbb{P}(X_{\pi(l)_{u-v}} = 1 \mid X_{\pi(l)_{1}} = 1, \dots, X_{\pi(l)_{u-v-1}} = 1)
\times \mathbb{P}(X_{\pi(l)_{u-v-1}} = 1 \mid X_{\pi(l)_{1}} = 1, \dots, X_{\pi(l)_{u-v-2}} = 1) \dots \mathbb{P}(X_{\pi(l)_{1}} = 1)$$

$$(7.81)$$



where $\pi:\{1,\ldots,\binom{u-2}{u-v}\}\to\mathbb{N}^{u-v}$ ranges over all $\binom{u-2}{u-v}$ ordered subsets of $\{1,\ldots,u-2\}$ of size u-v. Thus, if we can provide a bound P such that

$$P \geqslant \mathbb{P}(X_{\pi(l)_{u-v-j}} = 1 \mid X_{\pi(l)_1} = 1, \dots, X_{\pi(l)_{u-v-(j+1)}} = 1),$$

$$P \geqslant \mathbb{P}(X_{\pi(l)_1} = 1)$$

$$l = 1, \dots, \binom{u-2}{u-v}, \quad j = 0, \dots, u-v-2,$$

$$(7.82)$$

then, by (7.81),

$$\mathbb{P}(X_1 + \dots + X_{u-2} > u - v) \leqslant \binom{u-2}{u-v} P^{u-v}.$$
 (7.83)

We continue assuming that (7.82) is true, and then return to this inequality below. Let $\{\tilde{X}_k\}_{k=1}^{u-2}$ be independent binary variables taking values 0 and 1, such that $\tilde{X}_k = 1$ with probability P. Then, by Lemma 7.14, (7.83) and (7.80) it follows that

$$\mathbb{P}(B_4^c) \leqslant \mathbb{P}\left(\tilde{X}_1 + \dots + \tilde{X}_{u-2} \geqslant u - v\right) \left(\frac{(u-2) \cdot e}{u-v}\right)^{u-v}. \tag{7.84}$$

Then, by the standard Chernoff bound [65, Theorem 2.1, equation 2], it follows that, for t > 0,

$$\mathbb{P}\left(\tilde{X}_1 + \dots + \tilde{X}_{u-2} \geqslant (u-2)(t+P)\right) \leqslant e^{-2(u-2)t^2}.$$
 (7.85)

Hence, if we let t = (u - v)/(u - 2) - P, it follows from (7.84) and (7.85) that

$$\mathbb{P}(B_{\scriptscriptstyle A}^{c}) \leqslant e^{-2(u-2)t^2 + (u-v)(\log((u-2)/(u-v)) + 1)} \leqslant e^{-2(u-2)t^2 + u - 2}$$

Thus, by choosing P = 1/4 we get that $\mathbb{P}(B_4^c) \leq \gamma$ whenever $u \geq x$ and x is the largest root satisfying

$$(x-u)\left(\frac{x-v}{u-2} - \frac{1}{4}\right) - \log(\gamma^{-1/2}) - \frac{x-2}{2} = 0,$$

and this yields $u \ge 8\lceil 3v + \log(\gamma^{-1/2}) \rceil$ which is satisfied by the choice of u in (7.62). Thus, we would have been done with Step VI if we could verify (7.82) with P = 1/4, and this is the theme in the following claim.

Claim. The weak balancing property, (7.14) and $(7.15) \Rightarrow (7.82)$ with P = 1/4. To prove the claim we first observe that $X_i = 0$ when

$$\left\| \left(P_{\Delta} - P_{\Delta} U^* \left(\frac{1}{q_1^i} P_{\Omega_1^i} \oplus \cdots \oplus \frac{1}{q_r^i} P_{\Omega_r^i} \right) U P_{\Delta} \right) Z_{i-1} \right\|_{l^{\infty}} \leqslant \frac{1}{2} \| Z_{i-1} \|_{l^{\infty}}$$



$$\left\| P_{M} P_{\Delta}^{\perp} U^{*} \left(\frac{1}{q_{1}^{i}} P_{\Omega_{1}^{i}} \oplus \cdots \oplus \frac{1}{q_{r}^{i}} P_{\Omega_{r}^{i}} \right) U P_{\Delta} Z_{i-1} \right\|_{l^{\infty}} \leqslant \frac{1}{4} \log_{2}(4KM\sqrt{s}) \| Z_{i-1} \|_{l^{\infty}},$$

$$i = j+2,$$

where we recall from (7.63) that

$$q_k^3 = q_k^4 = \dots = q_k^u = \tilde{q}_k, \quad 1 \leqslant k \leqslant r.$$

Thus, by choosing $\gamma = 1/8$ in (7.48) in Proposition 7.12 and $\gamma = 1/8$ in (i) in Proposition 7.11, it follows that $\frac{1}{4} \geqslant \mathbb{P}(X_j = 1)$, for $j = 1, \ldots, u - 2$, when the weak balancing property is satisfied and

$$(\log(8s) + 1)^{-1} \gtrsim \tilde{q}_k^{-1} \cdot \sum_{l=1}^r \kappa_{N,M}(k,l), \quad 1 \leqslant k \leqslant r$$
 (7.86)

$$(\log(8s) + 1)^{-1} \gtrsim \left(\sum_{k=1}^{r} \left(\tilde{q}_k^{-1} - 1\right) \cdot \mu_{\mathbf{N},\mathbf{M}}(k,l) \cdot \tilde{s}_k\right), \quad 1 \leqslant l \leqslant r, \quad (7.87)$$

as well as

$$\frac{\log_2(4KM\sqrt{s})}{\log(32(M-s))} \gtrsim \tilde{q}_k^{-1} \cdot \sum_{l=1}^r \kappa_{\mathbf{N},\mathbf{M}}(k,l), \quad 1 \leqslant k \leqslant r$$
 (7.88)

$$\frac{\log_2(4KM\sqrt{s})}{\log\left(32(M-s)\right)} \gtrsim \left(\sum_{k=1}^r \left(\tilde{q}_k^{-1} - 1\right) \cdot \mu_{\mathbf{N},\mathbf{M}}(k,l) \cdot \tilde{s}_k\right), \quad 1 \leqslant l \leqslant r, \quad (7.89)$$

with $K = \max_{1 \le k \le r} (N_k - N_{k-1})/m_k$. Thus, to prove the claim we must demonstrate that (7.14) and $(7.15) \Rightarrow (7.86)$, (7.87), (7.88) and (7.89). We split this into two stages:

Stage 1. (7.15) \Rightarrow (7.89) and (7.87). To show the assertion we must demonstrate that if, for $1 \le k \le r$,

$$m_k \gtrsim (\log(s\epsilon^{-1}) + 1) \cdot \hat{m}_k \cdot \log(KM\sqrt{s}),$$
 (7.90)

where \hat{m}_k satisfies

$$1 \gtrsim \sum_{k=1}^{r} \left(\frac{N_k - N_{k-1}}{\hat{m}_k} - 1 \right) \cdot \mu_{\mathbf{N}, \mathbf{M}}(k, l) \cdot \tilde{s}_k, \quad l = 1, \dots, r,$$
 (7.91)

we get (7.89) and (7.87). To see this, note that by (7.61) we have that

$$q_k^1 + q_k^2 + (u - 2)\tilde{q}_k \geqslant q_k, \quad 1 \leqslant k \leqslant r,$$
 (7.92)



so since $q_k^1 = q_k^2 = \frac{1}{4}q_k$, and by (7.92), (7.90) and the choice of u in (7.62), it follows that

$$\begin{split} 2(8(\lceil \log(\gamma^{-1}) + 3\lceil \log_2(8KM\sqrt{s})\rceil \rceil) - 2)\tilde{q}_k \geqslant q_k &= \frac{m_k}{N_k - N_{k-1}} \\ \geqslant C \frac{\hat{m}_k}{N_k - N_{k-1}} (\log(s\epsilon^{-1}) + 1) \log\left(KM\sqrt{s}\right) \\ \geqslant C \frac{\hat{m}_k}{N_k - N_{k-1}} (\log(s) + 1) (\log\left(KM\sqrt{s}\right) + \log(\epsilon^{-1})), \end{split}$$

for some constant C (recall that we have assumed that $\log(s) \ge 1$). And this gives (by recalling that $\gamma = \epsilon/6$) that $\tilde{q}_k \ge \hat{C}(\hat{m}_k/(N_k - N_{k-1}))(\log(s) + 1)$, for some constant \hat{C} . Thus, (7.15) implies that for $1 \le l \le r$,

$$1 \gtrsim (\log(s) + 1) \left(\sum_{k=1}^{r} \left(\frac{N_k - N_{k-1}}{m_k (\log(s) + 1)} - \frac{1}{\log(s) + 1} \right) \cdot \mu_{\mathbf{N}, \mathbf{M}}(k, l) \cdot \tilde{s}_k \right)$$
$$\gtrsim (\log(s) + 1) \left(\sum_{k=1}^{r} \left(\tilde{q}_k^{-1} - 1 \right) \cdot \mu_{\mathbf{N}, \mathbf{M}}(k, l) \cdot \tilde{s}_k \right),$$

and this implies (7.89) and (7.87), given an appropriate choice of the constant C. Stage 2. (7.14) \Rightarrow (7.88) and (7.86). To show the assertion we must demonstrate that if, for $1 \le k \le r$,

$$1 \gtrsim (\log(s\epsilon^{-1}) + 1) \cdot \frac{N_k - N_{k-1}}{m_k} \cdot \left(\sum_{l=1}^r \kappa_{\mathbf{N},\mathbf{M}}(k,l)\right) \cdot \log\left(KM\sqrt{s}\right), \quad (7.93)$$

we obtain (7.88) and (7.86). To see this, note that by arguing as above via the fact that $q_k^1 = q_k^2 = \frac{1}{4}q_k$, and by (7.92), (7.93) and the choice of u in (7.62) we have that

$$2(8(\lceil \log(\gamma^{-1}) + 3\lceil \log_2(8KM\sqrt{s})\rceil \rceil) - 2)\tilde{q}_k \geqslant q_k = \frac{m_k}{N_k - N_{k-1}}$$

$$\geqslant C \cdot \left(\sum_{l=1}^r \kappa_{\mathbf{N},\mathbf{M}}(k,l)\right) \cdot (\log(s\epsilon^{-1}) + 1) \cdot \log\left(KM\sqrt{s}\right)$$

$$\geqslant C \cdot \left(\sum_{l=1}^r \kappa_{\mathbf{N},\mathbf{M}}(k,l)\right) \cdot (\log(s) + 1) \left(\log(\epsilon^{-1}) + \log\left(KM\sqrt{s}\right)\right),$$

for some constant C. Thus, we have that for some appropriately chosen constant \hat{C} , $\tilde{q}_k \geqslant \hat{C} \cdot (\log(s) + 1) \cdot \sum_{l=1}^r \kappa_{N,M}(k,l)$. So, (7.88) and (7.86) holds given an appropriately chosen C. This yields the last puzzle of the proof, and we are done.



Proof of Proposition 7.4. The proof is very close to the proof of Proposition 7.3 and we simply point out the differences. The strategy of the proof is to show the validity of (i) and (ii), and the existence of a $\rho \in \text{ran}(U^*(P_{\Omega_1} \oplus \cdots \oplus P_{\Omega_r}))$ that satisfies (iii)–(v) in Proposition 7.1 with probability exceeding $1 - \epsilon$.

Step I. The construction of ρ : the construction is almost identical to the construction in the proof of Proposition 7.3, except that

$$u = 8\lceil \log(\gamma^{-1}) + 3v \rceil, \quad v = \lceil \log_2(8K\tilde{M}\sqrt{s}) \rceil,$$

$$\alpha_1 = \alpha_2 = (2\log_2^{1/2}(4K\tilde{M}\sqrt{s}))^{-1}, \quad \alpha_i = 1/2, \quad 3 \le i \le u,$$
(7.94)

as well as

$$\beta_1 = \beta_2 = \frac{1}{4}, \quad \beta_i = \frac{1}{4} \log_2(4K\tilde{M}\sqrt{s}), \quad 3 \leqslant i \leqslant u,$$

and (7.66) gets changed to

$$\omega_{i} = \begin{cases} \omega_{i-1} \cup \{i\} & \text{if } \left\| \left(P_{\Delta} - P_{\Delta} U^{*} \left(\frac{1}{q_{1}^{i}} P_{\Omega_{1}^{i}} \oplus \cdots \oplus \frac{1}{q_{r}^{i}} P_{\Omega_{r}^{i}} \right) U P_{\Delta} \right) Z_{i-1} \right\|_{l^{\infty}} \\ \leqslant \alpha_{i} \| P_{\Delta_{k}} Z_{i-1} \|_{l^{\infty}}, \\ & \text{and } \left\| P_{\Delta}^{\perp} U^{*} \left(\frac{1}{q_{1}^{i}} P_{\Omega_{1}^{i}} \oplus \cdots \oplus \frac{1}{q_{r}^{i}} P_{\Omega_{r}^{i}} \right) U P_{\Delta} Z_{i-1} \right\|_{l^{\infty}} \\ \leqslant \beta_{i} \| Z_{i-1} \|_{l^{\infty}}, \\ \omega_{i-1} & \text{otherwise}, \end{cases}$$

the events B_i , i = 1, 2 in (7.67) get replaced by

$$\widetilde{B}_i: \quad \left\| P_{\Delta}^{\perp} U^* \left(\frac{1}{q_1^i} P_{\Omega_1^i} \oplus \cdots \oplus \frac{1}{q_r^i} P_{\Omega_r^i} \right) U P_{\Delta} Z_{i-1} \right\|_{l^{\infty}} \leqslant \beta_i \| Z_{i-1} \|_{l^{\infty}}, \quad i = 1, 2,$$

and the second part of B_3 becomes

$$\max_{i \in \Delta^c} \left\| \left(q_1^{-1/2} P_{\Omega_1} \oplus \cdots \oplus q_r^{-1/2} P_{\Omega_r} \right) U e_i \right\| \leqslant \sqrt{5/4}.$$

Step II. $B_5 \Rightarrow (i), (ii)$. This step is identical to Step II in the proof of Proposition 7.3.



Step III. $B_5 \Rightarrow (iii), (iv)$. Equation (7.69) gets changed to

$$\begin{split} \|P_{\Delta}^{\perp}\rho\|_{l^{\infty}} &\leqslant \sum_{i=1}^{v} \left\| P_{\Delta}^{\perp}U^{*}\left(\frac{1}{q_{1}^{\tau(i)}}P_{\Omega_{1}^{\tau(i)}} \oplus \cdots \oplus \frac{1}{q_{r}^{\tau(i)}}P_{\Omega_{r}^{\tau(i)}}\right) U P_{\Delta}Z_{\tau(i-1)} \right\|_{l^{\infty}} \\ &\leqslant \sum_{i=1}^{v} \beta_{\tau(i)} \|Z_{\tau(i-1)}\|_{l^{\infty}} \leqslant \sum_{i=1}^{v} \beta_{\tau(i)} \prod_{j=1}^{i-1} \alpha_{\tau(j)} \\ &\leqslant \frac{1}{4} \left(1 + \frac{1}{2 \log_{2}^{1/2}(a)} + \frac{\log_{2}(a)}{2^{3} \log_{2}(a)} + \cdots + \frac{1}{2^{v-1}}\right) \leqslant \frac{1}{2}, \\ a &= 4\tilde{M}K\sqrt{s}. \end{split}$$

Step IV. $B_5 \Rightarrow (v)$. This step is identical to Step IV in the proof of Proposition 7.3.

Step V. The strong balancing property, (7.18) and (7.19) $\Rightarrow \mathbb{P}(A_1^c \cup A_2^c \cup \widetilde{B}_1^c \cup \widetilde{B}_2^c \cup B_3^c) \leqslant 5\gamma$. We start by bounding $\mathbb{P}(\widetilde{B}_1^c)$ and $\mathbb{P}(\widetilde{B}_2^c)$. Note that by Proposition 7.11(ii) it follows that $\mathbb{P}(\widetilde{B}_1^c) \leqslant \gamma$ and $\mathbb{P}(\widetilde{B}_2^c) \leqslant \gamma$ as long as the strong balancing property is satisfied and

$$1 \gtrsim \Lambda \cdot \log \left(\frac{4}{\gamma} (\tilde{\theta} - s) \right), \quad 1 \gtrsim \Upsilon \cdot \log \left(\frac{4}{\gamma} (\tilde{\theta} - s) \right), \tag{7.95}$$

where $\tilde{\theta} = \tilde{\theta}(\{q_k^i\}_{k=1}^r, 1/8, \{N_k\}_{k=1}^r, s, M)$ for i = 1, 2 and where $\tilde{\theta}$ is defined in Proposition 7.11(ii) and Λ and Υ are defined in (7.73) and (7.74). Note that it is easy to see that we have

$$\left| \left\{ j \in \mathbb{N} : \max_{\substack{\Gamma_{1} \subset \{1, \dots, M\}, \\ \Gamma_{2,j} \subset \{N_{j-1}+1, \dots, N_{j}\}, \\ ||P_{\Gamma_{1}}U^{*}((q_{1}^{i})^{-1}P_{\Gamma_{2,1}} \oplus \dots \oplus (q_{r}^{i})^{-1}P_{\Gamma_{2,r}}) U e_{j} || > \frac{1}{8\sqrt{s}} \right\} \right| \leqslant \tilde{M},$$

where

$$\tilde{M} = \min\{i \in \mathbb{N} : \max_{j \ge i} ||P_N U P_{\{j\}}|| \le 1/(K32\sqrt{s})\},$$

and this follows from the choice in (7.63) where $q_k^1 = q_k^2 = \frac{1}{4}q_k$ for $1 \le k \le r$. Thus, it immediately follows that (7.18) and (7.19) imply (7.95). To bound $\mathbb{P}(B_3^c)$, we first deduce as in Step V of the proof of Proposition 7.3 that

$$\mathbb{P}\left(\left\|P_{\Delta}U^*\left(\frac{1}{q_1}P_{\Omega_1}\oplus\cdots\oplus\frac{1}{q_r}P_{\Omega_r}\right)UP_{\Delta}-P_{\Delta}\right\|>1/4,\right)\leqslant\gamma/2$$



when the strong balancing property and (7.18) holds. For the second part of B_3 , we know from the choice of \tilde{M} that

$$\max_{i\geqslant \tilde{M}}\left\|\left(q_1^{-1/2}P_{\Omega_1}\oplus\cdots\oplus q_r^{-1/2}P_{\Omega_r}\right)Ue_i\right\|\leqslant \sqrt{\frac{5}{4}}$$

and we may deduce from Proposition 7.13 that

$$\mathbb{P}\left(\max_{i\in\Delta^{c}\cap\{1,\ldots,\tilde{M}\}}\left\|\left(q_{1}^{-1/2}P_{\Omega_{1}}\oplus\cdots\oplus q_{r}^{-1/2}P_{\Omega_{r}}\right)Ue_{i}\right\|>\sqrt{5/4}\right)\leqslant\frac{\gamma}{2},$$

whenever

$$1 \gtrsim \log\left(\frac{2\tilde{M}}{\gamma}\right) \cdot \max_{1 \leqslant k \leqslant r} \left\{ \left(\frac{N_k - N_{k-1}}{m_k} - 1\right) \mu_{\mathbf{N},\mathbf{M}}(k,l) \right\}, \quad l = 1, \ldots, r-1, \infty,$$

which is true whenever (7.18) holds, since by a similar argument to (7.78),

$$\kappa_{\mathbf{N},\mathbf{M}}(k,\infty) + \sum_{j=1}^{r-1} \kappa_{\mathbf{N},\mathbf{M}}(k,j) \geqslant \mu_{\mathbf{N},\mathbf{M}}(k,l), \quad l=1,\ldots,r-1,\infty.$$

Thus, $\mathbb{P}(B_3^c) \leq \gamma$. As for bounding $\mathbb{P}(A_1^c)$ and $\mathbb{P}(A_2^c)$, observe that by the strong balancing property $\tilde{M} \geq M$, thus this is done exactly as in Step V of the proof of Proposition 7.3.

Step VI. The strong balancing property, (7.18) and (7.19) $\Rightarrow \mathbb{P}(B_4^c) \leqslant \gamma$. To see this, define the random variables X_1, \ldots, X_{u-2} as in (7.79). Let π be defined as in Step VI of the proof of Proposition 7.3. Then it suffices to show that (7.18) and (7.19) imply that for $l=1,\ldots,\binom{u-2}{u-v}$ and $j=0,\ldots,u-v-2$, we have

$$\frac{1}{4} \geqslant \mathbb{P}(X_{\pi(l)_{u-v-j}} = 1 \mid X_{\pi(l)_1} = 1, \dots, X_{\pi(l)_{u-v-(j+1)}} = 1),
\frac{1}{4} \geqslant \mathbb{P}(X_{\pi(l)_1} = 1).$$
(7.96)

Claim. The strong balancing property, (7.18) and $(7.19) \Rightarrow (7.96)$. To prove the claim we first observe that $X_i = 0$ when

$$\begin{split} & \left\| \left(P_{\Delta} - P_{\Delta} U^* \left(\frac{1}{q_1^i} P_{\Omega_1^i} \oplus \cdots \oplus \frac{1}{q_r^i} P_{\Omega_r^i} \right) U P_{\Delta} \right) Z_{i-1} \right\|_{l^{\infty}} \leqslant \frac{1}{2} \| Z_{i-1} \|_{l^{\infty}} \\ & \left\| P_{\Delta}^{\perp} U^* \left(\frac{1}{q_1^i} P_{\Omega_1^i} \oplus \cdots \oplus \frac{1}{q_r^i} P_{\Omega_r^i} \right) U P_{\Delta} Z_{i-1} \right\|_{l^{\infty}} \leqslant \frac{1}{4} \log_2(4K \tilde{M} \sqrt{s}) \| Z_{i-1} \|_{l^{\infty}}, \\ & i = j+2. \end{split}$$



Thus, by again recalling from (7.63) that $q_k^3 = q_k^4 = \cdots = q_k^u = \tilde{q}_k$, $1 \le k \le r$, and by choosing $\tilde{\gamma} = 1/4$ in (7.48) in Proposition 7.12 and $\tilde{\gamma} = 1/4$ in (ii) in Proposition 7.11, we conclude that (7.96) follows when the strong balancing property is satisfied as well as (7.86) and (7.87). and

$$\frac{\log_2(4K\tilde{M}\sqrt{s})}{\log\left(16(\tilde{M}-s)\right)} \geqslant C_2 \cdot \tilde{q}_k^{-1} \cdot \left(\sum_{l=1}^{r-1} \kappa_{\mathbf{N},\mathbf{M}}(k,l) + \kappa_{\mathbf{N},\mathbf{M}}(k,\infty)\right),\tag{7.97}$$

$$\frac{\log_2(4K\tilde{M}\sqrt{s})}{\log\left(16(\tilde{M}-s)\right)} \geqslant C_2 \cdot \left(\sum_{l=1}^r \left(\tilde{q}_k^{-1}-1\right) \cdot \mu_{\mathbf{N},\mathbf{M}}(k,l) \cdot \tilde{s}_k\right),\tag{7.98}$$

where k = 1, ..., r and $l = 1, ..., r - 1, \infty$ and for $K = \max_{1 \le k \le r} (N_k - N_{k-1})/m_k$. for some constants C_1 and C_2 . Thus, to prove the claim we must demonstrate that (7.18) and (7.19) \Rightarrow (7.86), (7.87), (7.97) and (7.98). This is done by repeating Stage 1 and Stage 2 in Step VI of the proof of Proposition 7.3 almost verbatim, except replacing M by \tilde{M} .

7.4. Proofs of Theorem 6.2 and Proposition 6.4. Throughout this section, we use the notation

$$\hat{f}(\xi) = \int_{\mathbb{R}} f(x)e^{-ix\xi}dx,\tag{7.99}$$

to denote the Fourier transform of a function $f \in L^1(\mathbb{R})$.

- 7.4.1. Setup. We first introduce the wavelet sparsity and Fourier sampling bases that we consider, and in particular, their orderings. Consider an orthonormal basis of compactly supported wavelets with an MRA [27, 28]. For simplicity, suppose that $\sup(\Psi) = \sup(\Phi) = [0, a]$ for some $a \ge 1$, where Ψ and Φ are the mother wavelet and scaling function respectively. For later use, we recall the following three properties of any such wavelet basis:
- (1) There exist $\alpha \geqslant 1$, C_{Ψ} and $C_{\Phi} > 0$, such that

$$\left|\hat{\Phi}(\xi)\right| \leqslant \frac{C_{\Phi}}{(1+|\xi|)^{\alpha}}, \quad \left|\hat{\Psi}(\xi)\right| \leqslant \frac{C_{\Psi}}{(1+|\xi|)^{\alpha}}.$$
 (7.100)

See [28, Equation (7.1.4)]. We denote $\max\{C_{\Psi}, C_{\Phi}\}$ by $C_{\Phi, \Psi}$.

- (2) Ψ has $v \ge 1$ vanishing moments and $\hat{\Psi}(z) = (-iz)^v \theta_{\Psi}(z)$ for some bounded function θ_{Ψ} (see [64, pages 208 and 284]).
- (3) $\|\hat{\Phi}\|_{L^{\infty}}, \|\hat{\Psi}\|_{L^{\infty}} \leq 1.$



REMARK 7.15. The three properties above are based on the standard setup for an MRA, however, we also consider a stronger assumption on the decay of the Fourier transform of derivatives of the scaling function and the mother wavelet. In particular, in addition, we sometimes assume that for C > 0 and $\alpha \ge 1.5$,

$$\left|\hat{\Phi}^{(k)}(\xi)\right| \leqslant \frac{C}{(1+|\xi|)^{\alpha}}, \quad \left|\hat{\Psi}^{(k)}(\xi)\right| \leqslant \frac{C}{(1+|\xi|)^{\alpha}}, \quad \xi \in \mathbb{R}, \ k = 0, 1, 2,$$
(7.101)

where $\hat{\Phi}^{(k)}$ and $\hat{\Psi}^{(k)}$ denotes the kth derivative of the Fourier transform of Φ and Ψ respectively. As is evident from Theorem 6.2, the faster decay, the closer the relationship between N and M in the balancing property gets to linear. Also, faster decay and more vanishing moments yield a closer to block-diagonal structure of the matrix U.

We now wish to construct a wavelet basis for the compact interval [0, a]. The most standard approach is to consider the following collection of functions

$$\Lambda_a = \{ \Phi_k, \Psi_{j,k} : \operatorname{supp}(\Phi_k)^o \cap [0, a] \neq \emptyset, \operatorname{supp}(\Psi_{j,k})^o \cap [0, a] \neq \emptyset,$$

$$j \in \mathbb{Z}_+, k \in \mathbb{Z} \}$$

where $\Phi_k = \Phi(\cdot - k)$, and $\Psi_{j,k} = 2^{j/2}\Psi(2^j \cdot -k)$. (the notation K^o denotes the interior of a set $K \subseteq \mathbb{R}$). This gives

$$\left\{ f \in \mathrm{L}^2(\mathbb{R}) : \mathrm{supp}(f) \subseteq [0, a] \right\} \subseteq \overline{\mathrm{span}\{\varphi : \varphi \in \Lambda_a\}}$$

$$\subseteq \left\{ f \in \mathrm{L}^2(\mathbb{R}) : \mathrm{supp}(f) \subseteq [-T_1, T_2] \right\},$$

where T_1 , $T_2 > 0$ are such that $[-T_1, T_2]$ contains the support of all functions in Λ_a . Note that the inclusions may be proper (but not always, as is the case with the Haar wavelet). It is easy to see that

$$\Psi_{j,k} \notin \Lambda_a \Longleftrightarrow \frac{a+k}{2^j} \le 0, \quad a \le \frac{k}{2^j},$$

$$\Phi_k \notin \Lambda_a \Longleftrightarrow a+k \le 0, \quad a \le k.$$

and therefore

$$\Lambda_a = {\{\Phi_k : |k| = 0, \dots, \lceil a \rceil - 1\}} \cup {\{\Psi_{j,k} : j \in \mathbb{Z}_+, k \in \mathbb{Z}, -\lceil a \rceil < k < 2^j \lceil a \rceil\}}.$$

We order Λ_a in increasing order of wavelet resolution as follows:

$$\{\Phi_{-\lceil a\rceil+1}, \dots, \Phi_{-1}, \Phi_0, \Phi_1, \dots, \Phi_{\lceil a\rceil-1}, \Psi_{0,-\lceil a\rceil+1}, \dots, \Psi_{0,-\lceil a\rceil+1}, \dots, \Psi_{0,-\lceil a\rceil+1}, \dots, \Psi_{0,-\lceil a\rceil+1}, \dots, \Psi_{0,-\lceil a\rceil+1}, \dots\},$$

$$(7.102)$$



and then we finally denote the functions according to this ordering by $\{\varphi_j\}_{j\in\mathbb{N}}$. By the definition of Λ_a , we let $T_1 = \lceil a \rceil - 1$ and $T_2 = 2\lceil a \rceil - 1$. Finally, for $R \in \mathbb{N}$, let $\Lambda_{R,a}$ contain all wavelets in Λ_a with resolution less than R, so that

$$\Lambda_{R,a} = \{ \varphi \in \Lambda_a : \varphi = \Psi_{j,k}, \ 0 \leqslant j < R, \text{ or } \varphi = \Phi_k \}. \tag{7.103}$$

We also denote the size of $\Lambda_{R,a}$ by W_R . It is easy to verify that

$$W_R = 2^R \lceil a \rceil + (R+1)(\lceil a \rceil - 1).$$
 (7.104)

Having constructed an orthonormal wavelet system for [0, a], we now introduce the appropriate Fourier sampling basis. We must sample at a rate that is at least that of the Nyquist rate. Hence we let $\omega \leq 1/(T_1 + T_2)$ be the sampling density (note that $1/(T_1 + T_2)$ is the Nyquist criterion for functions supported on $[-T_1, T_2]$). For simplicity, we assume throughout that

$$\omega \in (0, 1/(T_1 + T_2)), \quad \omega^{-1} \in \mathbb{N},$$
 (7.105)

and remark that this assumption is an artefact of our proofs and is not necessary in practice. The Fourier sampling vectors are now defined as follows.

$$\psi_j(x) = \sqrt{\omega} e^{-2\pi i j \omega x} \chi_{[-T_1/(\omega(T_1 + T_2)), T_2/(\omega(T_1 + T_2))]}(x), \quad j \in \mathbb{Z}.$$
 (7.106)

This gives an orthonormal sampling basis for the space $\{f \in L^2(\mathbb{R}) : \operatorname{supp}(f) \subseteq [-T_1, T_2]\}$. Since Λ_a is an orthonormal system for this space, it follows that the infinite matrix

$$U = \begin{pmatrix} u_{11} & u_{12} & u_{13} & \cdots \\ u_{21} & u_{22} & u_{23} & \cdots \\ u_{31} & u_{32} & u_{33} & \cdots \\ \vdots & \vdots & \vdots & \ddots \end{pmatrix}, \quad u_{ij} = \langle \varphi_j, \tilde{\psi}_i \rangle, \tag{7.107}$$

is an isometry, where $\{\varphi_j\}_{j\in\mathbb{N}}$ represents the wavelets ordered according to (7.102) and $\{\tilde{\psi}_j\}_{j\in\mathbb{N}}$ is the standard ordering of the Fourier basis (7.106) over \mathbb{N} ($\tilde{\psi}_1 = \psi_0$, $\tilde{\psi}_{2n} = \psi_n$ and $\tilde{\psi}_{2n+1} = \psi_{-n}$). With slight abuse of notation it is this ordering that we are using in Theorem 6.2.

7.4.2. Some preliminary estimates. Throughout this section, we assume the setup and notation introduced above.

THEOREM 7.16. Let U be the matrix of the Fourier/wavelets pair introduced in (7.107) with sampling density ω as in (7.105). Suppose that Φ and Ψ satisfy the decay estimate (7.100) with $\alpha \geqslant 1$ and that Ψ has $v \geqslant 1$ vanishing moments. Then the following holds.



- (i) We have $\mu(U) \geqslant \omega$.
- (ii) We have that

$$\begin{split} &\mu(P_N^\perp U)\leqslant \frac{C_{\phi,\psi}^2}{\pi\,N(2\alpha-1)(1+1/(2\alpha-1))^{2\alpha}},\quad N\in\mathbb{N},\\ &\mu(U\,P_N^\perp)\leqslant \|\Psi\|_{L^\infty}^2\frac{4\omega\lceil a\rceil}{N},\quad N\geqslant 2\lceil a\rceil+2(\lceil a\rceil-1), \end{split}$$

and consequently $\mu(P_N^{\perp}U)$, $\mu(UP_N^{\perp}) = \mathcal{O}(N^{-1})$.

(iii) If the wavelet and scaling function satisfy the decay estimate (7.100) with $\alpha > 1/2$, then, for R and N such that $\omega^{-1}2^R \leq N$ and $M = |\Lambda_{R,a}|$ (recall the definition of $\Lambda_{R,a}$ from (7.103)),

$$\mu(P_N^{\perp}UP_M) \leqslant \frac{C_{\Phi,\Psi}^2}{\pi^{2\alpha}\omega^{2\alpha-1}} (2^{R-1}N^{-1})^{2\alpha-1}N^{-1}.$$

(iv) If the wavelet has $v \ge 1$ vanishing moments, $\omega^{-1}2^R \ge N$ and $M = |\Lambda_{R,a}|$ with $R \ge 1$, then

$$\mu(P_N U P_M^{\perp}) \leqslant \frac{\omega}{2^R} \cdot \left(\frac{\pi \omega N}{2^R}\right)^{2v} \cdot \|\theta_{\Psi}\|_{L^{\infty}}^2,$$

where θ_{Ψ} is the function such that $\hat{\Psi}(z) = (-iz)^{v}\theta_{\Psi}(z)$ (see above).

Proof. Note that $\mu(U) \geqslant |\langle \Phi, \psi_0 \rangle|^2 = \omega \left| \hat{\Phi}(0) \right|^2$, moreover, it is known that $\hat{\Phi}(0) = 1$ [51, Ch. 2, Theorem 1.7]. Thus, (i) follows.

To show (ii), let $R \in \mathbb{N}$, $-\lceil a \rceil < j < 2^R \lceil a \rceil$ and $k \in \mathbb{Z}$. Then, by the choice of j, we have that $\Psi_{R,j}$ is supported on $[-T_1, T_2]$. Also, $\psi_k(x) = \sqrt{\omega}e^{-2\pi ik\omega x}\chi_{[-T_1/(\omega(T_1+T_2)),T_2/(\omega(T_1+T_2))]}(x)$. Thus, since by (7.105) we have $\omega \in (0, 1/(T_1+T_2))$, it follows that

$$\langle \Psi_{R,j}, \psi_k \rangle = \sqrt{\omega} \int_{-T_1/(\omega(T_1 + T_2))}^{T_2/(\omega(T_1 + T_2))} \Psi_{R,j}(x) e^{2\pi i \omega k x} dx$$

$$= \sqrt{\omega} \hat{\Psi}_{R,j}(-2\pi \omega k) = \sqrt{\frac{\omega}{2^R}} \hat{\Psi}\left(\frac{-2\pi k \omega}{2^R}\right) e^{2\pi i \omega k j/2^R}. (7.108)$$

Also, similarly, it follows that

$$\langle \Phi_j, \psi_k \rangle = \sqrt{\omega} \int_{-T_1/(\omega(T_1 + T_2))}^{T_2/(\omega(T_1 + T_2))} \Phi_j(x) e^{2\pi i \omega k x} dx = \sqrt{\omega} \hat{\Phi}_j(-2\pi k \omega)$$
$$= \sqrt{\omega} \hat{\Phi}(-2\pi k \omega) e^{2\pi i \omega k j}. (7.109)$$



Thus, the decay estimate in (7.100) yields

$$\begin{split} &\mu(P_N^\perp U)\leqslant \sup_{|k|\geqslant N/2}\max_{\varphi\in A_a}|\langle\varphi,\,\psi_k\rangle|^2\\ &=\max\left\{\sup_{|k|\geqslant N/2}\max_{R\in\mathbb{Z}_+}\frac{\omega}{2^R}\left|\hat{\Psi}\left(\frac{-2\pi\,\omega k}{2^R}\right)\right|^2,\omega\sup_{|k|\geqslant N/2}\left|\hat{\varPhi}\left(-2\pi\,\omega k\right)\right|^2\right\}\\ &\leqslant \max_{|k|\geqslant N/2}\max_{R\in\mathbb{Z}_+}\frac{\omega}{2^R}\frac{C_{\varPhi,\psi}^2}{(1+|2\pi\,\omega k2^{-R}|)^{2\alpha}}\leqslant \max_{R\in\mathbb{Z}_+}\frac{\omega}{2^R}\frac{C_{\varPhi,\psi}^2}{(1+|\pi\,\omega N2^{-R}|)^{2\alpha}}. \end{split}$$

The function $f(x) = x^{-1}(1+\pi\omega N/x)^{-2\alpha}$ on $[1,\infty)$ satisfies $f'(\pi\omega N(2\alpha-1)) = 0$. Hence

$$\mu(P_N^{\perp}U) \leqslant \frac{C_{\Phi,\Psi}^2}{\pi N(2\alpha - 1)(1 + 1/(2\alpha - 1))^{2\alpha}},$$

which gives the first part of (ii). For the second part, we first recall the definition of W_R for $R \in \mathbb{N}$ from (7.104). Then, given any $N \in \mathbb{N}$ such that $N \geqslant W_1 = 2\lceil a\rceil + 2(\lceil a\rceil - 1)$, let R be such that $W_R \leqslant N < W_{R+1}$. Then, for each $n \geqslant N$, there exists some $j \geqslant R$ and $l \in \mathbb{Z}$ such that the n^{th} element via the ordering (7.102) is $\varphi_n = \Psi_{j,l}$ (note that we only need $\Psi_{j,l}$ here and not Φ_j as we have chosen $N \geqslant W_1$). Hence, by using (7.108),

$$\mu(UP_N^{\perp}) = \max_{n \geqslant N} \max_{k \in \mathbb{Z}} |\langle \varphi_n, \psi_k \rangle|^2 = \max_{j \geqslant R} \max_{k \in \mathbb{Z}} \frac{\omega}{2^j} \left| \hat{\Psi} \left(\frac{-2\pi \omega k}{2^j} \right) \right|^2$$
$$\leq \|\hat{\Psi}\|_{L^{\infty}}^2 \frac{\omega}{2^R} \leq 4 \|\hat{\Psi}\|_{L^{\infty}}^2 \frac{\omega \lceil a \rceil}{N},$$

where the last line follows because $N < W_{R+1} = 2^{R+1} \lceil a \rceil + (R+2)(\lceil a \rceil - 1)$ implies that

$$2^{-R} < \frac{1}{N} \left(2\lceil a \rceil + (R+2)(\lceil a \rceil - 1)2^{-R} \right) \leqslant \frac{4\lceil a \rceil}{N}.$$

This concludes the proof of (ii).

To show (iii), let R and N be such that $\omega^{-1}2^R \leq N$ and $M = |\Lambda_{R,a}|$. Observe that (7.108) and (7.109) together with the decay estimate in (7.100) yield

$$\mu(P_N^{\perp}UP_{W_R}) \leqslant \max_{|k| \geqslant N/2} \max_{\varphi \in A_{R,a}} |\langle \varphi, \psi_k \rangle|^2$$

$$= \max \left\{ \max_{|k| \geqslant N/2} \max_{j < R} \frac{\omega}{2^j} \left| \hat{\Psi} \left(\frac{-2\pi\omega k}{2^j} \right) \right|^2, \max_{|k| \geqslant N/2} \left| \hat{\Phi} \left(-2\pi\omega k \right) \right|^2 \right\}$$



$$\leq \max_{|k| \geqslant N/2} \max_{j < R} \frac{\omega}{2^{j}} \frac{C_{\phi, \psi}^{2}}{(1 + |2\pi\omega k 2^{-j}|)^{2\alpha}} \leq \max_{k \geqslant N/2} \max_{j < R} \frac{C_{\phi, \psi}^{2}}{\pi^{2\alpha}\omega^{2\alpha - 1}} \frac{2^{j(2\alpha - 1)}}{(2k)^{2\alpha}}$$

$$= \frac{C_{\phi, \psi}^{2}}{\pi^{2\alpha}\omega^{2\alpha - 1}} (2^{R-1}N^{-1})^{2\alpha - 1}N^{-1},$$

and this colludes the proof of (iii).

To show (iv), first note that because $R \ge 1$, for all $n > W_R$, $\varphi_n = \Psi_{j,k}$ for some $j \ge 0$ and $k \in \mathbb{Z}$. Then, recalling the properties of Daubechies wavelets with v vanishing moments, and by using (7.108) we get that

$$\mu(P_N U P_{W_R}^{\perp}) = \max_{n > W_R} \max_{|k| \leqslant N/2} |\langle \varphi_n, \psi_k \rangle|^2 = \max_{j \geqslant R} \max_{|k| \leqslant N/2} \frac{\omega}{2^j} \left| \hat{\Psi} \left(\frac{-2\pi\omega k}{2^j} \right) \right|^2$$

$$\leqslant \frac{\omega}{2^R} \cdot \left(\frac{\pi\omega N}{2^R} \right)^{2v} \cdot \|\theta_{\Psi}\|_{L^{\infty}}^2,$$

as required. \Box

COROLLARY 7.17. Let **N** and **M** be as in Theorem 6.2 and recall the definition of $\mu_{N,M}(k, j)$ in (4.3). Suppose that Φ and Ψ satisfy the decay estimate (7.100) with $\alpha \geqslant 1$ and that Ψ has $v \geqslant 1$ vanishing moments. Then,

$$for \ k \geqslant 2, \quad \mu_{N,M}(k,j) \leqslant B_{\Phi,\Psi} \cdot \begin{cases} \frac{\sqrt{\omega}}{\sqrt{N_{k-1}2^{R_{j-1}}}} \cdot \left(\frac{\omega N_{k}}{2^{R_{j-1}}}\right)^{v} & j \geqslant k+1, \\ \frac{1}{N_{k-1}} \left(\frac{2^{R_{j-1}}}{\omega N_{k-1}}\right)^{\alpha-1/2} & j \leqslant k-1, (7.110) \\ \frac{1}{N_{k-1}} & j = k, \end{cases}$$

$$for \ k \geqslant 2, \quad \mu_{N,M}(k,\infty) \leqslant B_{\Phi,\Psi} \cdot \begin{cases} \frac{\sqrt{\omega}}{\sqrt{N_{k-1}2^{R_{r-1}}}} \cdot \left(\frac{\omega N_{k}}{2^{R_{r-1}}}\right)^{v} & k \leqslant r-1, \\ \frac{1}{N_{r-1}} & k = r, \end{cases}$$

$$\mu_{N,M}(1,j) \leqslant B_{\Phi,\Psi} \cdot \begin{cases} \frac{\sqrt{\omega}}{\sqrt{2^{R_{j-1}}}} \cdot \left(\frac{\omega N_{1}}{2^{R_{j-1}}}\right)^{v} & j \geqslant 2, \\ 1 & j = 1, \end{cases}$$

$$(7.111)$$

$$\mu_{\mathbf{N},\mathbf{M}}(1,\infty) \leqslant B_{\phi,\psi} \cdot \frac{\sqrt{\omega}}{\sqrt{2^{R_{r-1}}}} \cdot \left(\frac{\omega N_1}{2^{R_{r-1}}}\right)^{v},$$
(7.113)

where $B_{\Phi,\Psi}$ is a constant which depends only on Φ and Ψ and $R_0 = 0$.



Proof. Throughout this proof, $B_{\Phi,\Psi}$ is a constant which depends only on Φ and Ψ , although its value may change from instance to instance. Note that

$$\mu_{\mathbf{N},\mathbf{M}}(k,j) = \sqrt{\mu(P_{N_k}^{N_{k-1}}UP_{M_j}^{M_{j-1}}) \cdot \mu(P_{N_k}^{N_{k-1}}U)}$$

$$\leq B_{\Phi,\Psi}N_{k-1}^{-1/2}\sqrt{\mu(P_{N_k}^{N_{k-1}}UP_{M_j}^{M_{j-1}})}, \quad k \geq 2, \ j \in \{1,\dots,r\}, (7.114)$$

since we have $\mu(P_{N_{k-1}}^{\perp}U) \leqslant B_{\Phi,\Psi}N_{k-1}^{-1}$ by (ii) of Theorem 7.16. Also, clearly

$$\mu_{\mathbf{N},\mathbf{M}}(1,j) = \sqrt{\mu(P_{N_1}^{N_0}UP_{M_j}^{M_{j-1}}) \cdot \mu(P_{N_1}^{N_0}U)} \leqslant B_{\boldsymbol{\Phi},\boldsymbol{\psi}} \sqrt{\mu(P_{N_1}^{N_0}UP_{M_j}^{M_{j-1}})}, \quad (7.115)$$

for $j \in \{1, ..., r\}$. Thus, for $k \ge 2$, it follows that $\mu_{N,M}(k, k) \le \mu(P_{N_{k-1}}^{\perp} U) \le B_{\phi,\psi}(1/N_{k-1})$, yielding the last part of (7.110). Also, the last part of (7.112) is clear from (7.115).

As for the middle part of (7.110), note that for $k \ge 2$, and with $j \le k - 1$, we may use (iii) of Theorem 7.16 to obtain

$$\sqrt{\mu(P_{N_k}^{N_{k-1}}UP_{M_j}^{M_{j-1}})} \leqslant \sqrt{\mu(P_{N_{k-1}}^{\perp}UP_{M_j})} \leqslant B_{\Phi,\Psi} \cdot \frac{1}{\sqrt{N_{k-1}}} \left(\frac{2^{R_{j-1}}}{\omega N_{k-1}}\right)^{\alpha-1/2},$$

and thus, in combination with (7.114), we obtain the $j \le k-1$ part of (7.110). Observe that if $k \in \{1, ..., r\}$ and $j \ge k+1$, then by applying (iv) of Theorem 7.16, we obtain

$$\sqrt{\mu(P_{N_k}^{N_{k-1}}UP_{M_j}^{M_{j-1}})} \leqslant \sqrt{\mu(P_{N_k}UP_{M_{j-1}}^{\perp})} \leqslant B_{\phi,\psi} \cdot \frac{\sqrt{\omega}}{\sqrt{2^{R_{j-1}}}} \cdot \left(\frac{\omega N_k}{2^{R_{j-1}}}\right)^{v}. \quad (7.116)$$

Thus, by combining (7.116) with (7.114), we obtain the $j \ge k+1$ part of (7.110). Also, by combining (7.116) with (7.114) we get the $j \ge 2$ part of (7.112). Finally, recall that

$$\mu_{\mathbf{N},\mathbf{M}}(k,\infty) = \sqrt{\mu(P_{N_k}^{N_{k-1}}UP_{M_{r-1}}^{\perp}) \cdot \mu(P_{N_{k-1}}^{\perp}U)}$$

and similarly to the above, (7.111) and (7.113) are direct consequences of parts (ii) and (iv) of Theorem 7.16.

The following lemmas inform us of the range of Fourier samples required for accurate reconstruction of wavelet coefficients. Specifically, Lemma 7.18 will provide a quantitative understanding of the balancing property, whilst Lemma 7.19 and Lemma 7.20 will be used in bounding the relative sparsity terms.



LEMMA 7.18 [67, Corollary 5.4]. Consider the setup in Section 7.4.1. Let the sampling density ω be such that $\omega^{-1} \in \mathbb{N}$ and suppose that there exists C_{ϕ} , $C_{\Psi} > 0$ and $\alpha \ge 1.5$ such that

$$\left|\hat{\Phi}^{(k)}(\xi)\right| \leqslant \frac{C_{\Phi}}{(1+|\xi|)^{\alpha}}, \quad \left|\hat{\Psi}^{(k)}(\xi)\right| \leqslant \frac{C_{\Psi}}{(1+|\xi|)^{\alpha}}, \quad \xi \in \mathbb{R}, \quad k = 0, 1, 2.$$

Then given $\gamma \in (0, 1)$, we have that $\|P_M U^* P_N U P_M - P_M\|_{l^{\infty} \to l^{\infty}} \leqslant \gamma$ wherever $N \geqslant C \gamma^{-1/(2\alpha-1)} M$ and $\|P_M^{\perp} U^* P_N U P_M\|_{l^{\infty} \to l^{\infty}} \leqslant \gamma$ wherever $N \geqslant C \gamma^{-1/(\alpha-1)} M$ where C is some constant independent of N but dependent on C_{Φ} , C_{Ψ} and ω .

LEMMA 7.19 [67, Lemma 5.1]. Let φ_k denote the kth wavelet via the ordering in (7.102). Let $R \in \mathbb{N}$ and $M \leqslant W_R$ be such that $\{\varphi_j : j \leqslant M\} \subset \Lambda_{R,a}$, where W_R and $\Lambda_{R,a}$ are defined in (7.104) and (7.103), respectively. Also, let the sampling density ω be such that $\omega^{-1} \in \mathbb{N}$. Then for any $\gamma \in (0, 1)$, we have that $\|P_N^{\perp}UP_M\| \leqslant \gamma$, whenever N is such that

$$N \geqslant \omega^{-1} \left(\frac{4C_{\phi}^2}{(2\pi)^{2\alpha} \cdot (2\alpha - 1)} \right)^{1/2\alpha - 1} \cdot 2^{R+1} \cdot \gamma^{-(2/2\alpha - 1)}$$

and C_{Φ} is a constant depending on Φ .

LEMMA 7.20. Let φ_k denote the k^{th} wavelet the ordering in (7.102). Let R_1 , $R_2 \in \mathbb{N}$ with $R_2 > R_1$, and M_1 , $M_2 \in \mathbb{N}$ with $M_2 > M_1$ be such that

$$\{\varphi_j: M_2 \geqslant j > M_1\} \subset \Lambda_{R_2,a} \setminus \Lambda_{R_1,a},$$

where $\Lambda_{R_i,a}$ is defined in (7.103). Then for any $\gamma \in (0, 1)$

$$\|P_N U P_{M_2}^{M_1}\| \leqslant \frac{\pi^2}{4} \|\theta_{\Psi}\|_{L^{\infty}} \cdot (2\pi\gamma)^v \cdot \sqrt{\frac{1 - 2^{2v(R_1 - R_2)}}{1 - 2^{-2v}}}$$

whenever N is such that $N \leq \gamma \omega^{-1} 2^{R_1}$.

Proof. Let $\eta \in l^2(\mathbb{N})$ be such that $\|\eta\| = 1$. Note that, by the definition of U in (7.107), it follows that

$$\|P_N U P_{M_2}^{M_1} \eta\|^2 \leqslant \sum_{|k| \leqslant N/2} \left| \left\langle \psi_k, \sum_{j=M_1+1}^{M_2} \eta_j \varphi_j \right\rangle \right|^2 \leqslant \sum_{|k| \leqslant N/2} \left| \left\langle \psi_k, \sum_{l=R_1}^{R_2-1} \sum_{i \in \Delta_l} \eta_{\rho(l,j)} \Psi_{l,j} \right\rangle \right|^2,$$

where we have defined

$$\Delta_l = \{ j \in \mathbb{Z} : \Psi_{l,j} \in \Lambda_{l+1,a} \setminus \Lambda_{l,a} \}, \quad \rho : \{ (l, \Delta_l) \}_{l \in \mathbb{N}} \to \mathbb{N} \setminus \{1, \dots, |\Lambda_{1,a}| \}$$



to be the bijection such that $\varphi_{\rho(l,j)} = \Psi_{l,j}$. Now, observe that we may argue as in the proof of Theorem 7.16 and use (7.108) to deduce that given $l \in \mathbb{N}$, $-\lceil a \rceil < j < 2^l \lceil a \rceil$ and $k \in \mathbb{Z}$, we have that $\langle \Psi_{l,j}, \psi_k \rangle = \sqrt{\omega/2^l} \hat{\Psi}(-(2\pi\omega k/2^l))e^{2\pi i\omega jk}$. Hence, it follows that

$$\begin{split} & \sum_{|k| \leqslant N/2} \left| \left\langle \psi_k, \sum_{l=R_1}^{R_2 - 1} \sum_{j \in \Delta_l} \eta_{\rho(l,j)} \Psi_{l,j} \right\rangle \right|^2 \\ & = \sum_{|k| \leqslant N/2} \left| \sum_{l=R_1}^{R_2 - 1} \frac{\sqrt{\omega}}{\sqrt{2^l}} \sum_{j \in \Delta_l} \eta_{\rho(l,j)} \hat{\Psi} \left(-\frac{2\pi \omega k}{2^l} \right) e^{2\pi i \omega j k/2^l} \right|^2 \end{split}$$

which again gives us that

$$\|P_{N}UP_{M_{2}}^{M_{1}}\eta\|^{2} \leqslant \sum_{|k| \leqslant N/2} \left| \sum_{l=R_{1}}^{R_{2}-1} \frac{\sqrt{\omega}}{\sqrt{2^{l}}} \hat{\Psi} \left(-\frac{2\pi\omega k}{2^{l}} \right) f^{[l]} \left(\frac{\omega k}{2^{l}} \right) \right|^{2}$$

$$\leqslant \sum_{|k| \leqslant N/2} \sum_{l=R_{1}}^{R_{2}-1} \left| \hat{\Psi} \left(-\frac{2\pi\omega k}{2^{l}} \right) \right|^{2} \cdot \sum_{l=R_{1}}^{R_{2}-1} \left| \frac{\sqrt{\omega}}{\sqrt{2^{l}}} f^{[l]} \left(\frac{\omega k}{2^{l}} \right) \right|^{2}$$

$$\leqslant \sum_{l=R_{1}} \max_{|k| \leqslant N/2} \left| \hat{\Psi} \left(-\frac{2\pi\omega k}{2^{l}} \right) \right|^{2} \cdot \sum_{l=R_{1}}^{R_{2}-1} \sum_{|k| \leqslant N/2} \frac{\omega}{2^{l}} \left| f^{[l]} \left(\frac{\omega k}{2^{l}} \right) \right|^{2},$$
(7.117)

where $f^{[l]}(z) = \sum_{j \in \Delta_l} \eta_{\rho(l,j)} e^{2\pi i z j}$. Let $H = \chi_{[0,1)}$ and, for $l \in \mathbb{N}$, $-\lceil a \rceil < j < 2^j \lceil a \rceil$, define $H_{l,j} = 2^{l/2} H(2^l \cdot -j)$. By the choice of j, we have that $H_{l,j}$ is supported on $[-T_1, T_2]$. Also, since by (7.105) we have $\omega \in (0, 1/(T_1 + T_2))$, we may argue as in (7.108) and find that $\langle H_{l,j}, \psi_k \rangle = \sqrt{\omega/2^l} \hat{H} \left(-2\pi k\omega/2^l\right) e^{2\pi i \omega k j/2^l}$. Thus,

$$\left\langle \sum_{j \in \Delta_l} \eta_{\rho(l,j)} H_{l,j}, \psi_k \right\rangle = \sqrt{\frac{\omega}{2^l}} \sum_{j \in \Delta_l} \eta_{\rho(l,j)} \hat{H} \left(\frac{-2\pi k\omega}{2^l} \right) e^{2\pi i \omega k j/2^l}. \tag{7.118}$$

It is straightforward to show that $\inf_{|x| \leq \pi} |\hat{H}(x)| \geq 2/\pi$, and since $N \leq 2^{R_1}/\omega$, for each $l \geq R_1$, it follows directly from (7.118) and the definition of $f^{[l]}$ that

$$\sum_{|k| \leqslant N/2} \frac{\omega}{2^{l}} \left| f^{[l]} \left(\frac{\omega k}{2^{l}} \right) \right|^{2} \leqslant \left(\inf_{|x| \leqslant \pi} \left| \hat{H}(x) \right|^{2} \right)^{-1} \sum_{|k| \leqslant N/2} \left| \left\langle \sum_{j \in \Delta_{l}} \eta_{\rho(l,j)} H_{l,j}, \psi_{k} \right\rangle \right|^{2}$$

$$\leqslant \frac{\pi^{2}}{4} \left\| \sum_{i \in \Delta_{l}} \eta_{\rho(l,j)} H_{l,j} \right\|^{2} \leqslant \frac{\pi^{2}}{4} \left\| P_{\Delta_{l}} \eta \right\|^{2}.$$



Hence, we immediately get that

$$\sum_{l=R_1}^{R_2-1} \sum_{|k| \leqslant N/2} \frac{\omega}{2^l} \left| f^{[l]} \left(\frac{\omega k}{2^l} \right) \right|^2 \leqslant \frac{\pi^2}{4} \sum_{l=R_1}^{R_2-1} \left\| P_{\Delta_l} \eta \right\|^2 \leqslant \frac{\pi^2}{4} \|\eta\|^2 \leqslant \frac{\pi^2}{4}.$$
 (7.119)

Also, since Ψ has v vanishing moments, we have that $\hat{\Psi}(z) = (-iz)^v \theta_{\Psi}(z)$ for some bounded L^{∞} function θ_{Ψ} . Thus, since $N \leq \gamma \cdot 2^{R_1}/\omega$, we have

$$\begin{split} \sum_{l=R_1}^{R_2-1} \max_{|k| \leqslant N/2} \left| \hat{\Psi} \left(\frac{2\pi \omega k}{2^l} \right) \right|^2 &\leqslant \frac{\pi^2}{4} \|\theta_{\Psi}\|_{L^{\infty}}^2 \sum_{l=R_1}^{R_2-1} \left(2\pi \gamma 2^{R_1-l} \right)^{2v} \\ &\leqslant \frac{\pi^2}{4} (2\pi \gamma)^{2v} \|\theta_{\Psi}\|_{L^{\infty}}^2 \frac{1 - 2^{2v(R_1 - R_2)}}{1 - 2^{-2v}}. \end{split}$$

Thus, by applying (7.117), (7.118) and (7.119), it follows that

$$\|P_N U P_{M_2}^{M_1} \eta\|^2 \leqslant \frac{\pi^2}{4} \|\theta_{\Psi}\|_{L^{\infty}}^2 \cdot (2\pi \gamma)^{2v} \frac{1 - 2^{2v(R_1 - R_2)}}{1 - 2^{-2v}},$$

and we have proved the desired estimate.

7.4.3. The proofs.

Proof of Theorem 6.2. In this proof, we let $B_{\Phi,\Psi}$ be some constant which depends only on Φ and Ψ , although its value may change from instance to instance. The assertions of the theorem will follow if we can show that the conditions in Theorem 5.3 are satisfied. We begin with condition (i). First observe that since U is an isometry we have that $\|P_MU^*P_NUP_M-P_M\|_{l^\infty}=\|P_MU^*P_N^{\perp}UP_M\|_{l^\infty\to l^\infty} \leq \sqrt{M}\|P_N^{\perp}UP_M\|$ and $\|P_M^{\perp}U^*P_NUP_M\|_{l^\infty\to l^\infty}=\|P_M^{\perp}U^*P_N^{\perp}UP_M\|_{l^\infty\to l^\infty} \leq \sqrt{M}\|P_N^{\perp}UP_M\|$. So N, K satisfy the strong balancing property with respect to U, M and S if

$$||P_N^{\perp}UP_M|| \leq \frac{1}{8} (M \log_2(4KM\sqrt{s}))^{-1/2}$$
.

In the case of $\alpha \ge 1$, by applying Lemma 7.19 with

$$\gamma = \frac{1}{8} \left(M \log_2(4KM\sqrt{s}) \right)^{-1/2},$$

it follows that N, K satisfy the strong balancing property with respect to U, M, s whenever

$$N \geqslant C_{\omega,\Phi} \cdot 2^{R+1} \cdot \left(\tfrac{1}{8} \left(M \log_2(4KM\sqrt{s}) \right)^{-1/2} \right)^{-(2/(2\alpha-1))},$$



where R is the smallest integer such that $M \leq W_R$ (where W_R is defined in (7.104)) and $C_{\omega,\Phi}$ is a constant which depends only on the Fourier decay of Φ and ω . By the choice of R, we have that $M = \mathcal{O}(2^R)$ since $W_R = \mathcal{O}(2^R)$ by (7.104). Thus, the strong balancing property holds provided that

$$N \gtrsim M^{1+1/(2\alpha-1)} \cdot \left(\log_2(4MK\sqrt{s})\right)^{1/(2\alpha-1)}$$

where the constant involved depends only on ω and the Fourier decay of Φ . Furthermore, if (7.101) holds, then a direct application of Lemma 7.18 gives that N, K satisfy the strong balancing property with respect to U, M, s whenever $N \gtrsim M \cdot \left(\log_2(4KM\sqrt{s})\right)^{1/(4\alpha-2)}$. So, condition (i) of Theorem 6.2 implies condition (i) of Theorem 5.3.

To show that (ii) in Theorem 5.3 is satisfied, we need to demonstrate that

$$1 \gtrsim \frac{N_k - N_{k-1}}{m_k} \cdot \log(\epsilon^{-1}) \cdot \left(\sum_{l=1}^r \mu_{\mathbf{N},\mathbf{M}}(k,l) \cdot s_l\right) \cdot \log\left(K\tilde{M}\sqrt{s}\right), \quad (7.120)$$

(with $\mu_{N,M}(k,r)$ replaced by $\mu_{N,M}(k,\infty)$, and also recall that $N_0=0$) and

$$m_{k} \gtrsim \hat{m}_{k} \cdot \log(\epsilon^{-1}) \cdot \log\left(K\tilde{M}\sqrt{s}\right),$$

$$1 \gtrsim \sum_{k=1}^{r} \left(\frac{N_{k} - N_{k-1}}{\hat{m}_{k}} - 1\right) \cdot \mu_{\mathbf{N},\mathbf{M}}(k,l) \cdot \tilde{s}_{k}, \quad \forall l = 1, \dots, r,$$

$$(7.121)$$

where

$$\tilde{M} = \min \left\{ i \in \mathbb{N} : \max_{k \geqslant i} \|P_N U e_k\| \leqslant 1/(32K\sqrt{s}) \right\}.$$
 (7.122)

We first consider (7.120). By applying the bounds (7.110) and (7.111) on the local coherences derived in Corollary 7.17, we have that (7.120) is implied by

$$\frac{m_{k}}{(N_{k} - N_{k-1})} \gtrsim B_{\Phi,\Psi} \cdot \left(\sum_{j=1}^{k-1} \frac{s_{j}}{N_{k-1}} \left(\frac{2^{R_{j-1}}}{\omega N_{k-1}}\right)^{\alpha - 1/2} + \frac{s_{k}}{N_{k-1}} + \sum_{j=k+1}^{r} \frac{s_{j} \cdot \sqrt{\omega}}{\sqrt{N_{k-1} 2^{R_{j-1}}}} \cdot \left(\frac{\omega N_{k}}{2^{R_{j-1}}}\right)^{v}\right) \cdot \log(\epsilon^{-1}) \cdot \log\left(K\tilde{M}\sqrt{s}\right), \tag{7.123}$$

where $k = 2, \ldots, r$, and

$$\frac{m_1}{N_1} \gtrsim B_{\phi,\Psi} \cdot \left(s_1 + \sum_{j=2}^r \frac{s_j \cdot \sqrt{\omega}}{\sqrt{2^{R_{j-1}}}} \cdot \left(\frac{\omega N_1}{2^{R_{j-1}}} \right)^v \right) \cdot \log(\epsilon^{-1}) \cdot \log\left(K \tilde{M} \sqrt{s} \right). \tag{7.124}$$



To obtain a bound on the value of \tilde{M} in (7.122), observe that by Lemma 7.20, $\|P_N U P_{\{j\}}\| \leq 1/(32K\sqrt{s})$ whenever $j = |A_{J,a}| = \mathcal{O}\left(2^J\right)$ such that $2^J \geq (32K\sqrt{s})^{1/v} \cdot N \cdot \omega$. Thus, $\tilde{M} \leq \lceil (32K\sqrt{s})^{1/v} \cdot N \cdot \omega \rceil$, and by recalling that $N_k = 2^{R_k} \omega^{-1}$, we have that (7.123) is implied by

$$\frac{m_k \cdot N_{k-1}}{N_k - N_{k-1}} \gtrsim B_{\phi, \psi} \cdot \log(\epsilon^{-1}) \cdot \log\left((K\sqrt{s})^{1+1/\nu}N\right)
\times \left(\sum_{j=1}^{k-1} s_j \cdot \left(2^{\alpha - 1/2}\right)^{-(R_{k-1} - R_{j-1})} + s_k + s_{k+1} \cdot 2^{-(R_k - R_{k-1})/2} \right)
+ \sum_{j=k+2}^{r} s_j \cdot 2^{-(R_{j-1} - R_{k-1})/2} \cdot 2^{-v(R_{j-1} - R_k)}, \quad k \geqslant 2, \quad (7.125)$$

and when k = 1, (7.124) is implied by

$$\frac{m_1}{N_1} \gtrsim B_{\phi,\psi} \cdot \log(\epsilon^{-1}) \cdot \log\left((K\sqrt{s})^{1+1/v}N\right)
\times \left(s_1 + s_2 \cdot 2^{-R_1/2} + \sum_{j=k+2}^r s_j \cdot 2^{-(R_{j-1} - R_{k-1})/2} \cdot 2^{-v(R_{j-1} - R_k)}\right). (7.126)$$

However, the condition (6.1) obviously implies (7.125) and (7.124), hence we have established that condition (6.1) implies (7.120). As for condition (7.121), we first derive upper bounds for the \tilde{s}_k values. Recall that according to Theorem 5.3 we have

$$\tilde{s}_k \leqslant S_k(\mathbf{N}, \mathbf{M}, \mathbf{s})$$

= $\max\{\|P_{N_l}^{N_{k-1}}U\eta\|^2 : \|\eta\|_{l^{\infty}} \leqslant 1, |\operatorname{supp}(P_{M_l}^{M_{l-1}}\eta)| = s_l, \ l = 1, \dots, r\},$

where $N_0 = M_0 = 0$. Thus, we concentrate on bounding S_k . First note that by a direct rearrangement of terms in Lemma 7.19, for any $\gamma \in (0, 1)$ and $R \in \mathbb{N}$ such that $M \leq W_R$, we have that $\|P_N^{\perp}UP_M\| \leq \gamma$ whenever N is such that

$$\gamma \geqslant \left(\frac{2^R}{\omega N}\right)^{2\alpha-1/2} \cdot \sqrt{\frac{2}{2\alpha-1}} \cdot \frac{C_{\phi}}{\pi^{\alpha}}.$$

So for any L>0, by letting $\gamma=\sqrt{2/(2\alpha-1)}\cdot(C_{\Phi}/\pi^{\alpha})\cdot L^{-((2\alpha-1)/2)}$, if $\gamma\in(0,1)$, then $\|P_N^{\perp}UP_M\|\leqslant\gamma$ provided that $N\geqslant\omega^{-1}\cdot L\cdot 2^R$. Also, if $\gamma>1$, then $\|P_N^{\perp}UP_M\|\leqslant\gamma$ is trivially true since $\|U\|=1$. Therefore, for $k\geqslant 2$ we have that

$$\|P_{N_{k-1}}^{\perp}UP_{M_l}\| < \sqrt{\frac{2}{2\alpha-1}} \cdot \frac{C_{\phi}}{\pi^{\alpha}} \cdot \left(\frac{2^{R_l}}{2^{R_{k-1}}}\right)^{\alpha-1/2}, \quad l \leqslant k-1.$$



Also, by Lemma 7.20, it follows that

$$\|P_{N_k}UP_{M_l}^{M_{l-1}}\| < (2\pi)^v \cdot \|\theta_{\Psi}\|_{L^{\infty}} \cdot \left(\frac{2^{R_k}}{2^{R_{l-1}}}\right)^v, \quad l \geqslant k+1.$$

Consequently, for k = 3, ..., r

$$\begin{split} \sqrt{\tilde{s}_k} &\leqslant \sqrt{S_k} = \max_{\eta \in \Theta} \|P_{N_k}^{N_{k-1}} U \eta\| \leqslant \sum_{l=1}^r \|P_{N_k}^{N_{k-1}} U P_{M_l}^{M_{l-1}} \| \sqrt{s_l} \\ &\leqslant B_{\Phi, \Psi} \left(\sum_{l=1}^{k-2} \sqrt{s_l} \cdot \left(\frac{2^{R_l}}{2^{R_{k-1}}} \right)^{\alpha - 1/2} + \sqrt{s_{k-1}} + \sqrt{s_k} + \sqrt{s_{k+1}} \right. \\ &+ \sum_{l=k+2}^r \sqrt{s_l} \cdot \left(\frac{2^{R_k}}{2^{R_{l-1}}} \right)^v \right), \end{split}$$

where

$$\Theta = \{ \eta : \|\eta\|_{l^{\infty}} \leqslant 1, |\text{supp}(P_{M_l}^{M_{l-1}}\eta)| = s_l, \ l = 1, \dots, r \},$$

and for k = 1, 2 we have

$$\sqrt{\tilde{s}_k} \leqslant B_{\Phi,\Psi} \left(\sqrt{s_{k-1}} + \sqrt{s_k} + \sqrt{s_{k+1}} + \sum_{l=k+2}^r \sqrt{s_l} \cdot \left(\frac{2^{R_k}}{2^{R_{l-1}}} \right)^v \right),$$

where we let $s_0 = 0$. Hence, for k = 3, ..., r, $A_{\alpha} = 2^{\alpha - 1/2}$ and $A_{\nu} = 2^{\nu}$

$$ilde{s}_k \leqslant B_{\Phi,\Psi} \left(\sqrt{\hat{s}_k} + \sum_{l=1}^{k-2} \sqrt{s_l} \cdot A_{lpha}^{-(R_{k-1}-R_l)} + \sum_{l=k+2}^r \sqrt{s_l} \cdot A_v^{-(R_{l-1}-R_k)}
ight)^2,$$

where $\hat{s}_k = \max\{s_{k-1}, s_k, s_{k+1}\}$. So, by using the Cauchy–Schwarz inequality, we obtain

$$\begin{split} \tilde{s}_k &\leqslant B_{\Phi,\Psi} \left(1 + \sum_{l=1}^{k-2} A_{\alpha}^{-(R_{k-1} - R_l)} + \sum_{l=k+2}^r A_{\nu}^{-(R_{l-1} - R_k)} \right) \\ &\times \left(\hat{s}_k + \sum_{l=1}^{k-2} s_l \cdot A_{\alpha}^{-(R_{k-1} - R_l)} + \sum_{l=k+2}^r s_l \cdot A_{\nu}^{-(R_{l-1} - R_k)} \right) \\ &\leqslant B_{\Phi,\Psi} \left(\hat{s}_k + \sum_{l=1}^{k-2} s_l \cdot A_{\alpha}^{-(R_{k-1} - R_l)} + \sum_{l=k+2}^r s_l \cdot A_{\nu}^{-(R_{l-1} - R_k)} \right), \end{split}$$

and similarly, for k = 1, 2, it follows that $\tilde{s}_k \leq B_{\Phi,\Psi}(\hat{s}_k + \sum_{l=k+2}^r s_l \cdot A_v^{-(R_{l-1} - R_k)})$. Finally, we use the above results to show that condition (6.1) implies (7.121):



By our coherence estimates in (7.110), (7.111), (7.111) and (7.113), we see that (7.121) holds if $m_k \gtrsim \hat{m}_k \cdot (\log(\epsilon^{-1}) + 1) \cdot \log((K\sqrt{s})^{1+1/v}N)$ and for each $l = 2, \ldots, r$,

$$1 \gtrsim B_{\Phi,\Psi} \left(\left(\frac{N_{1}}{\hat{m}_{1}} - 1 \right) \cdot \tilde{s}_{1} \cdot \sqrt{\frac{\omega}{2^{R_{l-1}}}} \cdot \left(\frac{\omega N_{1}}{2^{R_{l-1}}} \right)^{v} + \sum_{k=2}^{l-1} \left(\frac{N_{k} - N_{k-1}}{\hat{m}_{k}} - 1 \right) \cdot \tilde{s}_{k} \cdot \sqrt{\frac{\omega}{N_{k-1} 2^{R_{l-1}}}} \cdot \left(\frac{\omega N_{k}}{2^{R_{l-1}}} \right)^{v} + \left(\frac{N_{l} - N_{l-1}}{\hat{m}_{l}} - 1 \right) \cdot \tilde{s}_{l} \cdot \frac{1}{N_{l-1}} + \sum_{k=l+1}^{r} \left(\frac{N_{k} - N_{k-1}}{\hat{m}_{k}} - 1 \right) \cdot \tilde{s}_{k} \cdot \frac{1}{N_{k-1}} \left(\frac{2^{R_{l-1}}}{\omega N_{k-1}} \right)^{\alpha - 1/2} \right), \quad (7.127)$$

(where we with slight abuse of notation define

$$\sum_{k=2}^{l-1} \left(\frac{N_k - N_{k-1}}{\hat{m}_k} - 1 \right) \tilde{s}_k \sqrt{\frac{\omega}{N_{k-1} 2^{R_{l-1}}}} \left(\frac{\omega N_k}{2^{R_{l-1}}} \right)^v = 0$$

when l = 2), and for l = 1

$$1 \gtrsim B_{\Phi,\Psi} \left(\left(\frac{N_1}{\hat{m}_1} - 1 \right) \cdot \tilde{s}_1 + \sum_{k=2}^r \left(\frac{N_k - N_{k-1}}{\hat{m}_k} - 1 \right) \cdot \tilde{s}_k \cdot \frac{1}{N_{k-1}} \left(\frac{1}{\omega N_{k-1}} \right)^{\alpha - 1/2} \right). \tag{7.128}$$

Recalling that $N_k = \omega^{-1} 2^{R_k}$, (7.127) becomes, for l = 2, ..., r,

$$\begin{split} &1 \gtrsim B_{\Phi,\Psi} \cdot \left(\left(\frac{N_{1}}{\hat{m}_{1}} - 1 \right) \cdot \frac{\tilde{s}_{k}}{N_{k-1}} \cdot 2^{-v(R_{l-1} - R_{k})} \right. \\ &+ \sum_{k=1}^{l-1} \left(\frac{N_{k} - N_{k-1}}{\hat{m}_{k}} - 1 \right) \cdot \frac{\tilde{s}_{k}}{N_{k-1}} \cdot 2^{-v(R_{l-1} - R_{k})} + \left(\frac{N_{l} - N_{l-1}}{\hat{m}_{l}} - 1 \right) \cdot \frac{\tilde{s}_{l}}{N_{l-1}} \\ &+ \sum_{k=l+1}^{r} \left(\frac{N_{k} - N_{k-1}}{\hat{m}_{k}} - 1 \right) \cdot \frac{\tilde{s}_{k}}{N_{k-1}} \cdot \left(2^{\alpha - 1/2} \right)^{-(R_{k-1} - R_{l-1})} \right), \end{split}$$

and (7.128) becomes

$$1 \gtrsim B_{\varPhi, \psi} \cdot \left(\left(rac{N_1}{\hat{m}_1} - 1
ight) \cdot ilde{s}_1 + \sum_{k=l+1}^r \left(rac{N_k - N_{k-1}}{\hat{m}_k} - 1
ight) \cdot rac{ ilde{s}_k}{N_{k-1}} \cdot \left(2^{lpha - 1/2}
ight)^{-R_{k-1}}
ight).$$

 \Box



Observe that for l = 2, ..., r

$$1 + \sum_{k=1}^{l-1} 2^{-v(R_{l-1} - R_k)} + \sum_{k=l+1}^{r} \left(2^{\alpha - 1/2} \right)^{-(R_{k-1} - R_{l-1})} \leqslant B_{\Phi, \Psi},$$

and that $1 + \sum_{k=l+1}^{r} (2^{\alpha-1/2})^{-(R_{k-1})} \leq B_{\Phi,\Psi}$. Thus, (7.121) holds provided that for each k = 2, ..., r,

$$\hat{m}_k \geqslant B_{\phi,\psi} \cdot \frac{N_k - N_{k-1}}{N_{k-1}} \cdot \tilde{s}_k, \quad \hat{m}_1 \geqslant B_{\phi,\psi} \cdot N_1 \cdot \tilde{s}_1,$$

and combining with our estimates of \tilde{s}_k , we may deduce that (6.1) implies (7.121).

Proof of Proposition 6.4. If $\|P_J^\perp x\| = 0$, there is nothing to prove, thus, we assume that $\|P_J^\perp x\| \neq 0$. Let $f = \sum_{j=1}^\infty x_j \varphi_j$ and $\hat{f} = \{\hat{f}_j\}_{j\in\mathbb{N}}$, where $\hat{f}_j = \langle f, \psi_j \rangle$. Similarly, let $g = \sum_{j=1}^J x_j \varphi_j$ and $\hat{g} = \{\hat{g}_j\}_{j\in\mathbb{N}}$, where $\hat{g}_j = \langle g, \psi_j \rangle$. Let Ω be a multilevel sampling scheme as in Theorem 6.2, and define $y = P_\Omega \hat{f} + z$ where $z \in \operatorname{ran}(P_\Omega)$ is a noise vector satisfying $\|z\| \leqslant \delta$. Now, let $z_1 = P_\Omega U P_J x - y$. Suppose for the moment that $\|P_\Omega U P_J^\perp\| \|P_J^\perp x\| \leqslant \delta$, we show this later. Then we have

$$||z_1|| \le ||P_{\Omega}Ux - y|| + ||P_{\Omega}UP_I^{\perp}x|| \le \delta + ||P_{\Omega}UP_I^{\perp}|| ||P_I^{\perp}x|| \le 2\delta.$$

Define $\tilde{y} = P_{\Omega}\hat{g} - z_1$ and apply Theorem 6.2 to g and the noise vector z_1 . Then, since $\tilde{y} = y$ we get that any minimizer $\tilde{\xi}$ of

$$\min_{\eta \in \mathbb{C}^J} \|\eta\|_{l^1} \text{ subject to } \|P_{\Omega}UP_J\eta - y\| \leqslant 2\delta,$$

satisfies

$$\|\tilde{\xi} - P_J x\| \leqslant C \cdot \left(2\tilde{\delta} \cdot \left(1 + L \cdot \sqrt{s}\right) + \sigma_{s,M}(g)\right).$$

However, $\sigma_{s,M}(g) \leqslant \sigma_{s,M}(f)$ and $||P_J^{\perp}x|| \leqslant \sigma_{s,M}(f)$. Thus,

$$\|\tilde{\xi} - x\| \leqslant 2C \cdot \left(\tilde{\delta} \cdot \left(1 + L \cdot \sqrt{s}\right) + \sigma_{s,M}(f)\right),$$

where we have assumed without loss of generality that $C \geqslant 1$. So, to finish the proof, we only need to show that $\|P_{\Omega}UP_J^{\perp}\|\|P_J^{\perp}x\| \leqslant \delta$. In fact, we show that $\|P_NUP_J^{\perp}\|\|P_J^{\perp}x\| \leqslant \delta$. To see the latter, by choosing $R_1 = R$ and letting $R_2 \to \infty$ in Lemma 7.20, it follows that for any $\gamma \in (0, 1)$

$$\|P_N U P_J^{\perp}\| \leqslant \frac{\pi^2}{4} \|\theta_{\Psi}\|_{L^{\infty}} (2\pi \gamma)^v \sqrt{2}$$



whenever $N \leq \gamma 2^R \omega^{-1}$. Letting

$$\gamma = (2\pi)^{-1} \left(\frac{\delta}{\|P_L^{\perp} x\| \cdot \|\theta_{\Psi}\|_{L^{\infty}} \pi^2} \right)^{1/\nu}$$

we get the desired bound when $2^R \geqslant 2\pi\omega N \cdot \left(((\|P_K^{\perp}x\|_2 \cdot C_{\Psi})/\delta) \right)^{1/v}$, where $C_{\Psi}^{-1} = \|\theta_{\Psi}\|_{L^{\infty}}\pi^2$.

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