

A rigidity theorem for Lagrangian deformations

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Abstract

We consider deformations of singular Lagrangian varieties in symplectic manifolds. We prove that a Lagrangian deformation of a Lagrangian complete intersection is analytically rigid provided that this is the case infinitesimally. This result is given as a consequence of the coherence of the direct image sheaves of relative infinitesimal Lagrangian deformations.

Introduction

We investigate local deformations of singular Lagrangian complete intersections in a symplectic manifold. These Lagrange varieties appear in microlocal analysis as characteristic varieties of quantum integrable systems (see, e.g., [CP94, CP99, DS99]). Deformations of the ideal generated by micro-differential equations induce deformations of the corresponding Lagrangian varieties and, if we regard as equivalent micro-differential ideals which are conjugated by a Fourier integral operator, then equivalent Lagrangian varieties are Lagrangian varieties which are isomorphic up to a symplectic change of coordinates.

Following previous investigations of Pham (see, e.g., [Pha00]), Colin de Verdière observed that in the semi-classical limit, the map from the versal deformation space of the micro-differential ideal to that of its characteristic variety is an isomorphism [Col03] (see also [Gar05b]). He used this correspondence to prove a formal microlocal versal deformation theorem for one-dimensional microdifferential equations. In the case when the characteristic variety is a monomial deformation of a quasi-homogeneous Lagrangian curve singularity, Colin de Verdière proved that the equivalence could be obtained by convergent series. Then, he posed the problem of the existence of a Lagrangian versal deformation for general Lagrangian curve germs. In [Gar04], we showed that this result was a consequence of a slight modification of Brieskorn's coherence theorem [Bri70], similar results were obtained in [Lan95, KL93].

In this paper, we investigate the higher-dimensional problem. We will use the case of plane curves as a guiding example. Our main result is that infinitesimally Lagrangian versal deformations are rigid, i.e., such a Lagrangian deformation admits only trivial deformations (given by a change of coordinates which preserves the symplectic form). This result is weaker than the statement 'infinitesimal Lagrangian versality' implies versality. Nevertheless, it is very likely that a more refined analysis in the spirit of [Pou74] actually leads to this result. Moreover, our result is sufficient to prove a Mather type result for stable integrable systems [Gar05a].

As a simple application of the rigidity theorem, we consider the Lagrangian variety germ (L, 0) given by the equations $p_i q_i = 0$, i = 1, ..., n. In that case, the rigidity theorem implies that the *n*-parameter deformation $p_i q_i = \varepsilon_i$ is rigid. That infinitesimal rigidity implies rigidity in this example was stated in [NP91] without proof.

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A RIGIDITY THEOREM FOR LAGRANGIAN DEFORMATIONS

Our strategy can be summarized as follows. If the deformation module of some deformation theory is of finite type and if it is compatible with base changes then infinitesimal versal deformations are rigid. If, moreover the sum of deformations is defined then infinitesimally versal deformation are indeed versal. This paper is only a concrete illustration of these facts; it is organized as follows.

We start the first section by adapting to the relative case the deformation theory considered by Sevenheck and van Straten for Lagrangian varieties [SvS03, Sev03]. The resulting Lagrangian versal deformation space was, in fact, already described by Du'c Nguyen and Pham in [NP91]. Then we state the main algebraic result namely the finiteness of the deformation module. We postpone the proof of this statement to § 4 since this is only a variant of the proof given by Sevenheck and van Straten in the absolute case [SvS03]. This result was used in our joint paper [GS03] with van Straten.

In § 2, we state the rigidity theorem. We consider only a naive viewpoint of versality namely versality over a smooth base. In § 3, the proof of the rigidity theorem is given. In § 4, we state and prove the coherence of the direct image sheaves of the relative Lagrange complex.

The results of this paper can easily be adapted for real analytic Lagrangian varieties. The formal aspect of the theory of Lagrangian deformations is treated in Sevenheck's thesis [Sev03]. Deformations of compact complex Lagrangian submanifolds of Kähler manifolds were considered in [Voi92]. An earlier version of this paper was pre-published in [Gar02].

1. Lagrangian deformations

1.1 Deformations of real compact Lagrangian manifolds

Let us consider the vector space $\mathbb{R}^{2n} = \{(x, y)\}$ together with the symplectic structure

$$\omega = \sum_{i=1}^{n} dx_i \wedge dy_i.$$

Recall that a Lagrangian manifold in \mathbb{R}^{2n} is an n-dimensional submanifold of \mathbb{R}^{2n} on which the symplectic form ω vanishes.

To understand the construction of the Lagrange complex, it is useful to investigate the deformations of a smooth compact Lagrangian submanifold $L \subset \mathbb{R}^{2n}$. For such a manifold, the Darboux– Weinstein theorem asserts that there exists a symplectomorphism

$$\varphi: \mathbb{R}^{2n} \longrightarrow T^*L$$

which maps a tubular neighbourhood of $L \subset \mathbb{R}^{2n}$ to a tubular neighbourhood of the zero section in the cotangent bundle T^*L to L (see [Wei73]).

Via the map φ , a small one parameter deformation (L_t) of L is mapped to the family of graphs of a one parameter family of maps

$$\alpha_t: L \longrightarrow T^*L,$$

that is, to a family of differential one forms.

It is readily verified that L_t is Lagrangian if the one-form α_t is closed and that L_t is Hamiltonian isotopic to $L_0 = L$ if α_t is exact.

Consequently, the space of C^{∞} -small deformations of L over some base Λ modulo Hamiltonian isotopies is parameterized by the maps from Λ to the first de Rham cohomology group $H^1(L, \mathbb{R})$ of L sending $0 \in \Lambda$ to $0 \in H^1(L, \mathbb{R})$.

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1.2 The relative Lagrange complex

We consider now the complex holomorphic situation, that is, a complex manifold M of dimension 2n together with a holomorphic symplectic two-form $\omega \in \Omega^2_M(M)$.

The Poisson bracket $\{f, g\}$ of two holomorphic functions $f, g \in \mathcal{O}_M(U)$ is defined by the formula

$$\{f,g\}\omega^n = df \wedge dg \wedge \omega^{n-1}$$

Recall that a Lagrangian submanifold of M is an n-dimensional holomorphic manifold on which the symplectic form vanishes. By Lagrangian variety $L \subset M$, we mean a reduced complex space of pure dimension n defined by an ideal sheaf \mathcal{I}_L which is closed under the Poisson bracket. This means that

$$\{f, g\} \in \mathcal{I}_L(U)$$
 whenever $f, g \in \mathcal{I}_L(U)$

for any open subset $U \subset M$. Over the smooth locus of L, it is readily seen that both definitions agree.

We consider now the situation with parameters. Let Λ be a complex manifold (the parameter space) with a marked point, denoted by 0, on it. The Poisson bracket on M lifts to an \mathcal{O}_{Λ} -linear Poisson bracket on $\Lambda \times M$. We shall say that a variety

$$L \subset (\Lambda \times M)$$

is a Lagrange variety if its projects one-to-one to a Lagrange variety of M. Let $Z \subset (\Lambda \times M)$ be a reduced complex subspace with ideal sheaf \mathcal{I} . The sequence

$$Z \xrightarrow{i} \Lambda \times M \xrightarrow{p} \Lambda$$

where *i* is the inclusion and *p* is the projection, is called a *Lagrangian deformation* of $\varphi^{-1}(0)$ if $\varphi = p \circ i$ is a flat deformation and if the fibres of φ are reduced Lagrangian varieties.

For brevity, we will simply write $\varphi: Z \longrightarrow \Lambda$ for a given Lagrangian deformation.

For a given $f = f_1 \wedge \cdots \wedge f_k \in \bigwedge^k \mathcal{I}/\mathcal{I}^2$, we denote by $f^j \in \bigwedge^{k-1} \mathcal{I}/\mathcal{I}^2$ the element

$$f^j = (-1)^j f_1 \wedge \cdots \wedge \hat{f}_j \wedge \cdots \wedge f_k.$$

The element $(f^i)^j \in \bigwedge^{k-2} \mathcal{I}/\mathcal{I}^2$ is denoted by $f^{i,j}$.

DEFINITION. The relative Lagrange complex, denoted $(\mathcal{C}^{\bullet}_{Z/\Lambda}, \delta)$, of the Lagrangian deformation

$$\varphi: Z \longrightarrow \Lambda$$

is the complex of sheaves on Z defined by

$$\mathcal{C}_{Z/\Lambda}^{k} = \mathcal{H}om_{\mathcal{O}_{Z}}\left(\bigwedge^{k} \mathcal{I}/\mathcal{I}^{2}, \mathcal{O}_{Z}\right)$$

and the kth differential $\delta: \mathcal{C}^k_{Z/\Lambda} \longrightarrow \mathcal{C}^{k+1}_{Z/\Lambda}$ is given by

$$\delta[\varphi](f) = \sum_{1 \leq i \leq n} \{f_i, \varphi(f^i)\} - \sum_{1 \leq i < j \leq n} \varphi(\{f_i, f_j\} \wedge f^{i,j}).$$

Analogous definitions can be given for germs of Lagrangian deformations.

Notation. If L is a Lagrange variety then the Lagrange complex of L, denoted by C_L^{\bullet} (which is defined in [SvS03]) is the relative Lagrange complex of the constant deformation $\varphi : L \longrightarrow \{0\}$ (here $Z = L, \Lambda = \{0\}$).

Remark. The differentials of the complex $\mathcal{C}^{\bullet}_{Z/\Lambda}$ are $\varphi^{-1}\mathcal{O}_{\Lambda}$ -linear; therefore its cohomology spaces are $\varphi^{-1}\mathcal{O}_{\Lambda}$ -modules.

Example 1. Denote by X_f the Hamilton vector field of a function $f \in \mathcal{O}_Z$. Assume that the fibres of φ are smooth. Then the evaluation map

$$\Omega^1_Z \longrightarrow \mathcal{C}^1_{Z/\Lambda}, \quad \alpha \mapsto [f \mapsto \alpha. X_f]$$

induces an isomorphism between the relative Lagrange complex $\mathcal{C}^{\bullet}_{Z/\Lambda}$ and the relative de Rham complex $\Omega^{\bullet}_{Z/\Lambda}$.

Example 2. Consider a map germ $\varphi : (\mathbb{C}^2, 0) \longrightarrow (\mathbb{C}, 0)$ with an isolated critical point at 0. Then the stalk at the origin of the Lagrange complex has only two terms both isomorphic to $\mathcal{O}_{\mathbb{C}^2,0}$ and the differential is given by $h \mapsto \{h, \varphi\}$. Therefore, the map $\mathcal{O}_{\mathbb{C}^2,0} \longrightarrow \Omega^2_{\mathbb{C}^2,0}$, $m \mapsto m\omega$ maps the module $H^1(\mathcal{C}^{\bullet}_{Z/\Lambda,0})$ to its Brieskorn lattice $\Omega^2_{\mathbb{C}^2,0}/d\varphi \wedge d\mathcal{O}_{\mathbb{C}^2,0}$. (Here and in the following, given a sheaf \mathcal{F} we denote by \mathcal{F}_0 its fibre at 0.)

Example 3. Take n = 2 and assume that the ideal of (L, 0) is generated by two commuting function germs f_1, f_2 . Then the complex has three terms respectively isomorphic to $\mathcal{O}_{L,0}, \mathcal{O}_{L,0}^2, \mathcal{O}_{L,0}$. The differentials are respectively given by $\delta h = (\{h, f_1\}, \{h, f_2\})$ and $\delta(m_1, m_2) = \{m_1, f_2\} + \{f_1, m_2\}$.

1.3 Equivalence of Lagrangian deformations

DEFINITION. A Lagrangian deformation germ $\varphi' : (Z', 0) \longrightarrow (\Lambda', 0)$ is called \mathcal{L} -induced (respectively, \mathcal{L} -equivalent) from (respectively, to) $\varphi : (Z, 0) \longrightarrow (\Lambda, 0)$ if there exists a commutative diagram

$$\begin{array}{ccc} (Z',0) & \stackrel{i'}{\longrightarrow} (\Lambda' \times M',0) & \stackrel{\varphi'}{\longrightarrow} (\Lambda',0) \\ & & & \downarrow^g & & \downarrow \\ (Z,0) & \stackrel{i}{\longrightarrow} (\Lambda \times M,0) & \stackrel{\varphi}{\longrightarrow} (\Lambda,0) \end{array}$$

where i', i denote the inclusions and g is a Poisson mapping germ (respectively, a biholomorphic Poisson mapping germ).

DEFINITION. A Lagrangian deformation germ $\varphi : (Z, 0) \longrightarrow (\Lambda, 0)$ is called *rigid* if any deformation germ $\varphi' : (Z', 0) \longrightarrow (\Lambda \times \mathbb{C}, 0)$ such that the restriction of φ' above $\Lambda \times \{0\}$ equals φ , is induced from φ .

A deformation germ

$$\varphi: (Z,0) \longrightarrow (\Lambda,0),$$

of a Lagrangian variety germ (L, 0) is called \mathcal{L} -versal if any deformation of (L, 0) over any smooth basis is induced from φ .

It is readily verified that the first cohomology space of the complex $\mathcal{C}_{L,0}^{\bullet}$ is equal to the \mathbb{C} -vector space of first-order Lagrangian deformations of (L, 0) modulo infinitesimally trivial deformations, where the coordinate changes have to be symplectic.

The ideal of Z at the origin is generated by holomorphic function germs

$$F_1, \dots, F_p : (\mathbb{C}^k \times \mathbb{C}^{2n}, 0) \longrightarrow (\mathbb{C}, 0), \quad (\Lambda \times M, 0) \approx (\mathbb{C}^k \times \mathbb{C}^{2n}, 0).$$

We sometimes use the notation $F = (F_1, \ldots, F_p)$ for the deformation germ $\varphi : (Z, 0) \longrightarrow (\Lambda, 0)$.

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1.4 The Lagrangian Kodaira–Spencer map

We keep the same notations but we assume now that Z is a complete intersection. In this case, we get isomorphisms

$$\mathcal{C}^k_{Z/\Lambda,0} \longrightarrow \bigwedge^k \mathcal{O}_{Z,0}, \quad \varphi \longmapsto \sum_{i_1 < \cdots < i_k} \varphi(F_{i_1} \wedge \cdots \wedge F_{i_k}) e_{i_1} \wedge \cdots \wedge e_{i_k},$$

where $\{e_1, ..., e_n\}$ is the canonical basis of the vector space \mathbb{C}^n , that is, $e_1 = (1, 0, ..., 0)$, $e_2 = (0, 1, 0, ..., 0), ..., e_n = (0, ..., 0, 1)$.

We define a *Kodaira–Spencer mapping* (or rather the stalk at the origin of a Kodaira–Spencer mapping) by

$$\begin{array}{cccc} \theta_F : & T_0 \Lambda & \longrightarrow & H^1(\mathcal{C}^{\bullet}_{Z/\Lambda,0}) \\ & v & \longmapsto & [(DF.v)] \end{array}, \quad (\Lambda,0) \approx (\mathbb{C}^k,0). \end{array}$$

Here $T_0\Lambda$ denotes the tangent space to Λ at the origin.

For instance, choose local coordinates $\lambda_1, \ldots, \lambda_k$ at the origin in Λ . Then the image of the vector $\partial_{\lambda_i} \in T_0 \Lambda$ is given by

$$\theta_F(\partial_{\lambda_i}) = [(\partial_{\lambda_i}F_1, \dots, \partial_{\lambda_i}F_n)].$$

This Kodaira–Spencer map is well-defined, indeed differentiating the following equality along v

$$\{F_j, F_k\} = \sum_{i=1}^n a_i F_i$$

we get that

$$\{dF_j.v, F_k\} + \{F_j, dF_k.v\} = \sum_{i=1}^n (da_i.v)F_i + \sum_{i=1}^n a_i(dF_i.v).$$

Thus, the cocycle $DF.v \in \mathcal{C}^1_{Z/\Lambda,0}$ is a coboundary.

DEFINITION. The map $\theta_F : T_0 \Lambda \longrightarrow H^1(\mathcal{C}^{\bullet}_{Z/\Lambda,0})$ defined above is called the *relative Lagrangian* Kodaira–Spencer map of F.

As Z is a complete intersection, the restriction to $\lambda = 0$ gives a surjective mapping from $\mathcal{C}_{Z/\Lambda}^k$ to \mathcal{C}_L^k . Thus, we get an *absolute Kodaira–Spencer mapping*:

$$\begin{array}{cccc} \bar{\theta}_F : & T_0 \Lambda & \longrightarrow & H^1(\mathcal{C}^{\bullet}_{L,0}) \\ & v & \longmapsto & \left[(DF.v)_{|\lambda=0} \right] \end{array}$$

and the following commutative diagram.

$$H^{1}(\mathcal{C}^{\bullet}_{Z/\Lambda,0})$$

$$\downarrow^{\theta_{F}} \qquad \qquad \downarrow^{r}$$

$$T_{0}\Lambda \xrightarrow{\overline{\theta}_{F}} H^{1}(\mathcal{C}^{\bullet}_{L,0})$$

Here r is the restriction to $\lambda = 0$. To get a clear picture of this diagram, let us denote by \mathcal{M} the maximal ideal of the local ring $\mathcal{O}_{\Lambda,0}$ and by $\mathcal{M}H^1(\mathcal{C}^{\bullet}_{Z/\Lambda,0})$ the image of the multiplication mapping

$$\mathcal{M} \otimes_{\mathcal{O}_{\Lambda,0}} H^1(\mathcal{C}^{\bullet}_{Z/\Lambda,0}) \longrightarrow H^1(\mathcal{C}^{\bullet}_{Z/\Lambda,0}).$$

PROPOSITION 1. The kernel of the map r defined above is equal to $\mathcal{M}H^1(\mathcal{C}^{\bullet}_{Z/\Lambda,0})$.

Proof. The vector space $\mathcal{M}H^1(\mathcal{C}^{\bullet}_{Z/\Lambda,0})$ is obviously contained in the kernel of r. We show that the induced map

$$\bar{r}: H^1(\mathcal{C}^{\bullet}_{Z/\Lambda,0})/\mathcal{M}H^1(\mathcal{C}^{\bullet}_{Z/\Lambda,0}) \longrightarrow H^1(\mathcal{C}^{\bullet}_{L,0})$$

is injective. Let us denote by

$$\varphi_p: Z_p \longrightarrow \Lambda_p, \quad p = 0, \dots, k$$

the restriction of $\varphi: Z \longrightarrow \Lambda$ above the \mathbb{C} -vector subspace

$$\Lambda_p = \{\lambda \in \Lambda : \lambda_1 = \dots = \lambda_p = 0\}, \quad \Lambda_0 = \Lambda,$$

where $\lambda_1, \ldots, \lambda_k$ denote local coordinates at the origin in Λ . We have exact sequences of complexes

$$) \longrightarrow \mathcal{C}^{\bullet}_{Z_p/\Lambda_p,0} \longrightarrow \mathcal{C}^{\bullet}_{Z_p/\Lambda_p,0} \longrightarrow \mathcal{C}^{\bullet}_{Z_{p+1}/\Lambda_{p+1},0} \longrightarrow 0$$

where $0 \leq p < k$.

These exact sequences induce long exact sequences in cohomology.

$$\cdots \longrightarrow H^k(\mathcal{C}^{\bullet}_{Z_p/\Lambda_p,0}) \longrightarrow H^k(\mathcal{C}^{\bullet}_{Z_{p+1}/\Lambda_{p+1},0}) \longrightarrow H^{k+1}(\mathcal{C}^{\bullet}_{Z_p/\Lambda_p,0}) \longrightarrow \cdots$$

It is readily seen that the $\mathcal{O}_{\Lambda_p,0}$ -module $H^0(\mathcal{C}^{\bullet}_{Z_p/\Lambda_p,0})$ can be identified with the module $\varphi_p^{-1}(\mathcal{O}_{\Lambda_p,0})$. Thus, in the exact sequence the map

$$H^0(\mathcal{C}^{\bullet}_{Z_p/\Lambda_p,0}) \longrightarrow H^0(\mathcal{C}^{\bullet}_{Z_{p+1}/\Lambda_{p+1},0})$$

is surjective and, therefore, the exact sequence splits. This shows that the induced maps

$$\frac{H^1(\mathcal{C}^{\bullet}_{Z_p/\Lambda_p,0})}{\lambda_{p+1}H^1(\mathcal{C}^{\bullet}_{Z_p/\Lambda_p,0})} \longrightarrow H^1(\mathcal{C}^{\bullet}_{Z_{p+1}/\Lambda_{p+1},0})$$

are injective. Finally, the injectivity of these maps implies in turn that the map \bar{r} is injective. This proves the proposition.

Remark 1. If the absolute Kodaira–Spencer mapping $\bar{\theta}_F$ is surjective, then the proposition implies the exact sequence

$$0 \longrightarrow \mathcal{M}H^1(\mathcal{C}^{\bullet}_{Z/\Lambda,0}) \xrightarrow{i} H^1(\mathcal{C}^{\bullet}_{Z/\Lambda,0}) \xrightarrow{r} H^1(\mathcal{C}^{\bullet}_{L,0}) \longrightarrow 0$$

where i denotes the inclusion.

1.5 The finiteness theorem

Following [SvS03], we introduce a class of singularities which plays the role of isolated singularities in symplectic geometry. On the total space Z of the deformation

$$\rho: Z \longrightarrow \Lambda$$

of a Lagrangian variety $L \subset M$ a stratification is defined as follows. Let f_1, \ldots, f_k be generators of the ideal of Z at a point x. Denote by V_x the \mathbb{C} -vector space generated by Hamilton vectorfields of f_1, \ldots, f_k evaluated at x. For each j, the stratum Z_j is defined by the condition

$$x \in Z_j \iff \dim V_x = j.$$

We have $Z = \bigcup_{j=0}^{n} Z_j$ where $2n = \dim(M)$.

The following notion was introduced in [SvS03] in the absolute case where it is called 'condition (P)'.

DEFINITION. A Lagrangian deformation $\varphi : Z \longrightarrow \Lambda$ is called *pyramidal* if for any k the variety Z_k is of relative dimension at most k.

PROPOSITION 2. The germ of a pyramidal deformation $\varphi : Z \longrightarrow \Lambda$ at a point $x \in Z_k$ is \mathcal{L} -equivalent to a deformation germ of the type

 $\varphi': (Z' \times \mathbb{C}^k, 0) \longrightarrow (\Lambda, 0), \ Z' \subset \mathbb{C}^{2n-2k}, \quad \mathbb{C}^k \subset \mathbb{C}^{2k}$

which is constant on the second factor. Moreover, this decomposition induces a quasi-isomorphism between the complexes $C^{\bullet}_{Z/\Lambda,x}$ and $C^{\bullet}_{Z'/\Lambda,0}$.

The proof of this proposition is straightforward, it is based on a simple symplectic reduction argument (in the absolute case see, e.g., [SvS03]).

THEOREM 1 [SvS03]. If (L, 0) is the germ of a pyramidal Lagrangian variety then the cohomology spaces $H^k(\mathcal{C}_{L,0}^{\bullet})$ are finite-dimensional vector spaces.

On the basis of examples, we conjecture that the converse to this theorem holds.

CONJECTURE. If $H^1(\mathcal{C}_{L,0}^{\bullet})$ is a finite-dimensional vector space and if (L,0) is a complete intersection then (L,0) is pyramidal.

We will prove the following generalisation of the previous theorem.

THEOREM 2. If $\varphi : (Z, 0) \longrightarrow (\Lambda, 0)$ is the germ of a pyramidal Lagrangian deformation then the cohomology spaces $H^k(\mathcal{C}^{\bullet}_{Z/\Lambda, 0})$ are $\mathcal{O}_{\Lambda, 0}$ -modules of finite type.

In the case dim L = 1, the theorem is a slight generalisation of a result due to Brieskorn ([Bri70, Satz 1.1], see also [Gre75] for a more general statement).

The proof of this theorem repeats that of Sevenheck and van Straten in the absolute case. We postpone it until § 4. This result was used in [GS03] in order to prove that $H^1(\mathcal{C}^{\bullet}_{Z/\Lambda,0})$ is actually a free $\mathcal{O}_{\Lambda,0}$ module provided that φ is an infinitesimally versal Lagrangian deformation.

2. The rigidity theorem

THEOREM 3. Let $F : (\mathbb{C}^k \times \mathbb{C}^{2n}, 0) \longrightarrow (\mathbb{C}^n, 0)$ be a Lagrangian deformation of a Lagrangian complete intersection germ $(L, 0) \subset (\mathbb{C}^{2n}, 0)$. Assume that:

- (1) (L,0) is pyramidal;
- (2) the absolute Kodaira–Spencer map

$$\bar{\theta}_F: T_0\mathbb{C}^k \longrightarrow H^1(\mathcal{C}^{\bullet}_{L,0})$$

associated to F is surjective.

Then, the Lagrangian deformation F is rigid.

Example 4. Consider the germ at the origin of the Lagrangian variety

$$L = \{(q, p) \in \mathbb{C}^{2n} : q_1 p_1 = q_2 p_2 = \dots = q_n p_n = 0\}$$

and let $F = (F_1, \ldots, F_n)$ be the *n*-parameter deformation defined by

$$F_i = q_i p_i + \lambda_i.$$

The Lagrangian Kodaira–Spencer mapping maps $\partial_{\lambda_1}, \ldots, \partial_{\lambda_n}$ to the cohomology classes

 $[(1, 0, \dots, 0)], \dots, [(0, \dots, 0, 1)].$

A straightforward computation shows that they generate $H^1(\mathcal{C}_{L,0}^{\bullet})$.

Thus, the Lagrangian deformation F is rigid. That infinitesimal Lagrangian versality implies Lagrangian rigidity in this example was assumed without proof in [NP91, § 1.2] (compare [Rus64, Vey78]).

COROLLARY 1. A Lagrangian deformation $F : (\mathbb{C}^k \times \mathbb{C}^2, 0) \longrightarrow (\mathbb{C}, 0)$ of a Lagrangian curve germ $(L, 0) \subset (\mathbb{C}^2, 0)$ with an isolated singular point is \mathcal{L} -versal provided that the absolute Kodaira–Spencer map associated to F is surjective.

Proof. We follow standard arguments due to Martinet for the case of singularity theory of differentiable maps [Mar82].

Put $f = F(0, \cdot)$ and let G be an arbitrary s-parametric Lagrangian deformation of $f = F(0, \cdot)$. We have to prove that G is \mathcal{L} -induced from F. To do this, we define the sum of F and G by the formula

$$(F \oplus G)(\alpha, \lambda, x) = F(\lambda, x) + G(\alpha, x) - f.$$

The restriction of this deformation to $\lambda = 0$ is equal to G. Consequently, it is sufficient to prove that $F \oplus G$ is \mathcal{L} -induced from F. Denote by F_j the restriction of $F \oplus G$ to the vector space $\{\alpha \mid \alpha_k = 0 \ \forall k \ge j\}$. We have $F_1 = F$ and $F_{s+1} = F \oplus G$.

The rigidity theorem implies that F_j is \mathcal{L} -induced from F_{j-1} . By induction, we get that F_j is \mathcal{L} -induced from F_{j-k} . In particular, $F_s = F \oplus G$ is \mathcal{L} -induced from $F_1 = F$.

Remark 2. In the case n > 1, we cannot use Martinet's argument since $F \oplus G$ is not, in general, a Lagrangian deformation.

Remark 3. For Lagrangian curves, there is a complete description of the \mathcal{L} -versal deformation. Let $F = f + \sum_{i=1}^{k} \lambda_i m_i$ be a k-parameter deformation of a reduced germ $\{f = 0\}$. Denote by e_1, \ldots, e_{μ} the restrictions of the m_i to $\lambda = 0$. Then F is \mathcal{L} -versal provided that the function germs $e_1, \ldots, e_{\mu} \in \mathcal{O}_{\mathbb{C}^2,0}$ project to a basis $[e_1], \ldots, [e_{\mu}]$ of the \mathbb{C} -vector space $H^1(\mathcal{C}_{L,0}^{\bullet})$. If f is quasihomogeneous, then according to Brieskorn [Bri70], there is a canonical isomorphism between the Milnor algebra and the fibre at the origin of the Brieskorn lattice of f. As the latter is isomorphic to the Lagrangian versal deformation space (cf. Example 2), we get an isomorphism

$$H^1(\mathcal{C}^{\bullet}_{L,0}) \longrightarrow \mathcal{O}_{\mathbb{C}^2,0}/Jf, \quad [m] \mapsto \bar{m}.$$

Here Jf denotes the Jacobian ideal of f generated by the partial derivatives of f. In this case, we recover the theorem of Colin de Verdière [Col03] similar (and somehow much more refined) results on volume forms are to be found in [Lan95, KL93] and reference therein.

Unlike the case of quasi-homogeneous singularities a set of germs m_1, \ldots, m_{μ} projecting to a basis of the Milnor algebra does not project to a basis of $H^1(\mathcal{C}_{L,0}) \approx \mathcal{O}_{L,0}/\{\mathcal{O}_{L,0}, f\}$. However, for a generic symplectic structure, this is indeed the case [VG82].

3. Proof of the rigidity theorem

3.1 Infinitesimal formulation of the problem

Let

$$G: (\mathbb{C} \times \mathbb{C}^k \times \mathbb{C}^{2n}, 0) \longrightarrow (\mathbb{C}^n, 0), \quad (t, \lambda, x) \mapsto G(t, \lambda, x)$$

be a deformation of

$$F: (\mathbb{C}^k \times \mathbb{C}^{2n}, 0) \longrightarrow (\mathbb{C}^n, 0), \quad (\lambda, x) \mapsto F(\lambda, x)$$

ASSERTION. The deformation G is \mathcal{L} -induced from F provided that there exist function germs $h \in \mathcal{O}_{2n+k+1}, b_1, \ldots, b_k \in \mathcal{O}_{k+1}$ and a matrix $B \in gl(n, \mathcal{O}_{2n+k+1})$ solving the equation

$$\{h,G\} + BG + \sum_{i=1}^{k} b_i \partial_{\lambda_i} G = -\partial_t G.$$
(1)

Proof. We search for a Poisson mapping germ

$$\varphi : (\mathbb{C} \times \mathbb{C}^k \times \mathbb{C}^{2n}, 0) \longrightarrow (\mathbb{C}^{2n}, 0), \quad (t, \lambda, x) \longrightarrow \varphi(t, \lambda, x)$$

and a matrix $A \in GL(n, \mathcal{O}_{2n+k+1})$ such that the following equalities hold

$$\begin{cases} F = A_{\tau}(G_{\tau} \circ \varphi_{\tau}), \\ (A_0, \varphi_0) = (I, Id). \end{cases}$$
(2)

We have used the standard notations $I \in GL(n, \mathcal{O}_{2n+k+1})$ for the identity matrix, Id for the identity mapping in \mathbb{C}^{2n} , A_{τ} for $A(\tau, \cdot, \cdot)$ and so on.

Differentiating the first equation of the system (2) with respect to τ at $\tau = t$, we get the equation

$$A_t \frac{d}{d\tau}\Big|_{\tau=t} (G_t \circ \varphi_\tau) + \left(\frac{d}{d\tau}\Big|_{\tau=t} A_\tau\right) (G_t \circ \varphi_t) + A_t \left(\frac{d}{d\tau}\Big|_{\tau=t} G_\tau\right) \circ \varphi_t = 0.$$
(3)

Define the time-dependent vector field germ v_t and the matrix $B \in gl(n, \mathcal{O}_{2n+k+1})$ by the formulae

$$v_t(\varphi_t(\lambda, x)) = \frac{d}{d\tau}|_{\tau=t} \varphi_\tau(\lambda, x),$$
$$(A_t B_t) \circ \varphi_t = \frac{d}{d\tau}|_{\tau=t} A_\tau.$$

Multiplying (3) on the right by φ_t^{-1} and on the left by A_t^{-1} , we get the equation

$$L_{v_t}G_t + B_tG_t + \partial_t G_t = 0. \tag{4}$$

Standard theorems on differential equations imply that $(\varphi_{\tau}, A_{\tau})$ satisfying the system (2) can be found provided that there exists (v_t, B_t) satisfying (4). Up to here our arguments have been standard and hold for most of the versal deformation theorems. We now come to the specificity of our situation. The vector field $v(t, \cdot) = v_t$ comes from a Poisson mapping germ, therefore it is of the type

$$v = \sum_{i=1}^{2n} a_i \partial_{x_i} + \sum_{i=1}^{k} b_i \partial_{\lambda_i}, \quad a_i \in \mathcal{O}_{2n+k+1}, \quad b_i \in \mathcal{O}_{k+1}$$

where the vector field $w = \sum_{i=1}^{2n} a_i \partial_{x_i}$ is the Hamiltonian field of some function germ $h \in \mathcal{O}_{2n+k+1}$. Consequently, (4) can be written in the form

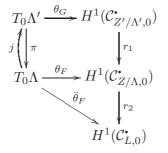
$$\{h,G\} + BG + \sum_{i=1}^{k} b_i \partial_{\lambda_i} G = -\partial_t G.$$
(5)

This proves our assertion.

3.2 Solving the infinitesimal equation

We interpret Equation (1) in cohomological terms.

Let $\varphi : Z \longrightarrow \Lambda$ and $\varphi' : Z' \longrightarrow \Lambda'$ be representatives for the germs F and G. We have the following commutative diagram.



The maps θ_G and θ_F are relative Kodaira–Spencer maps, while $\bar{\theta}_F$ is the absolute map. The maps π, j denote, respectively, the canonical projection and the inclusion induced by the product structure $(\Lambda', 0) \approx (\Lambda \times \mathbb{C}, 0)$. The map r_1 is the restriction to t = 0 and the map r_2 is the restriction to $\lambda = 0$. In this setting, (1) can be rewritten as

$$\sum_{i=1}^{k} b_i \theta_G(\partial_{\lambda_i}) = -\theta_G(\partial_t), \quad b_1, \dots, b_k \in \mathcal{O}_{\Lambda', 0}.$$
 (6)

(We have used the notation $\theta_G(\partial_{\lambda_i})$ rather than $[\partial_{\lambda_i}G]$ to underline in which space we take the cohomology class.)

Equation (6) can be solved provided that the cohomology class $\theta_G(\partial_t)$ belongs to the $\mathcal{O}_{\Lambda',0}$ module generated by the $\theta_G(\partial_{\lambda_i})$.

As $\bar{\theta}_F$ is surjective, we have an exact sequence (Remark 1, § 1.4)

$$0 \longrightarrow \mathcal{M}H^1(\mathcal{C}^{\bullet}_{Z'/\Lambda',0}) \xrightarrow{i} H^1(\mathcal{C}^{\bullet}_{Z'/\Lambda',0}) \xrightarrow{r} H^1(\mathcal{C}^{\bullet}_{L,0}) \longrightarrow 0,$$

where \mathcal{M} denotes the maximal ideal of the local ring $\mathcal{O}_{\Lambda',0}$.

The finiteness theorem (Theorem 2, § 1.5) asserts that the $\mathcal{O}_{\Lambda',0}$ -module $H^1(\mathcal{C}^{\bullet}_{Z'/\Lambda',0})$ is of finite type. Therefore, as the vectors

$$\bar{\theta}_F(\partial_{\lambda_1}),\ldots,\bar{\theta}_F(\partial_{\lambda_k})$$

generate the vector space $H^1(\mathcal{C}_{L,0})$, the Nakayama lemma implies that the elements

$$\theta_G(\partial_{\lambda_1}), \dots, \theta_G(\partial_{\lambda_k})$$

generate the $\mathcal{O}_{\Lambda',0}$ -module $H^1(\mathcal{C}^{\bullet}_{Z'/\Lambda',0})$. This concludes the proof of Theorem 3.

4. The coherence theorem

For the proof of the rigidity theorem to be complete, we need to prove the finiteness of the module of relative infinitesimal Lagrangian deformations.

4.1 Coherence of the higher direct image sheaves of the Lagrange complex

We denote by $D_r \subset \mathbb{C}^{k+2n}$ the polycylinder of polyradius $r \in \mathbb{C}^{k+2n}$ centered at the origin.

DEFINITION. A standard representative $\varphi : Z \longrightarrow \Lambda$ of a deformation germ $F : (\mathbb{C}^k \times \mathbb{C}^{2n}, 0) \longrightarrow (\mathbb{C}^p, 0)$ is a Stein representative of the germ together with a stratification of the fibres of φ such that:

- (1) φ is the restriction to $Z = Y \cap D_s$ of a deformation of the type $\varphi' : Y \longrightarrow \Lambda$, where Y is a subvariety of D_r , r > s;
- (2) there exists a fundamental system (Λ_t) of neighbourhoods of the origin in \mathbb{C}^k with $\Lambda_1 = \Lambda$ such that for any $t \in [0, 1[$, the fibres of φ' above Λ_t are transverse to the boundary of \overline{D}_{ts} (as stratified varieties).

There is a priori no reason for such a representative to exist.

PROPOSITION 3. Any pyramidal Lagrangian deformation germ admits a standard representative.

Proof. First consider the case of a constant deformation $\varphi : L \mapsto \{0\}$. The stratification defined in § 1.5 is obviously a Whitney stratification. In a Whitney stratification the transversality to a stratum (here the origin) implies the transversality to any adjacent strata in a small neighbourhood of it [Whi64, Tei81]. The existence of a standard representative follows.

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Consider now a general deformation $F = (F_1, \ldots, F_p)$ of a Lagrangian germ (L, 0). Choose a standard representative $\varphi : L \mapsto \{0\}, L \subset D_s$ of the constant deformation. That φ is a standard representative implies that for $\lambda = 0$, the vector space generated by hamiltonian vector fields of the $F_i(\lambda, -)$ at any point is transverse to the boundary of the polydisks $D_{ts}, t \in [0, 1]$. The transversality lemma implies that this remains true for $\lambda \in \mathbb{C}^k$ sufficiently close to the origin. This proves the proposition.

THEOREM 4. Let $\varphi : Z \longrightarrow \Lambda$ be a standard representative of a pyramidal Lagrangian deformation. Then, the direct image sheaves $\mathbb{R}^p \varphi_* \mathcal{C}^{\bullet}_{Z/\Lambda}$ are coherent sheaves of \mathcal{O}_{Λ} modules and there is a canonical isomorphism

$$(\mathbb{R}^p \varphi_* \mathcal{C}^{\bullet}_{Z/\Lambda})_0 \approx H^p(\mathcal{C}^{\bullet}_{Z/\Lambda,0}).$$

4.2 Criteria for the existence of a shrinking

Let $\varphi : Z \longrightarrow \Lambda$ be a standard representative of a holomorphic map germ and denote by \mathcal{K}^{\bullet} a complex of coherent sheaves with a $\varphi^{-1}\mathcal{O}_{\Lambda}$ linear differential. We use the notation of the above definition.

DEFINITION [vSt]. A transversal vector field to $(\varphi, \mathcal{K}^{\bullet})$ is a C^{∞} vector field θ defined in $D_{ts} \setminus \{0\}$, t > 1 satisfying the following conditions:

- (1) for any $t \in [0, 1]$, θ is transversal to the boundary of D_{ts} above Λ_t ;
- (2) the integral curves of θ are contained in the fibres of φ ;
- (3) the restriction of the cohomology sheaves $\mathcal{H}^p(\mathcal{K}^{\bullet})$ to the integral curves of θ are constant sheaves.

The following theorem is a consequence of the Kiehl–Verdier theorem [KV71, Dou74] (see also [FK71]).

THEOREM 5 [vSt]. The existence of a transversal vector field to $(\varphi, \mathcal{K}^{\bullet})$ implies that the hypercohomology sheaves $\mathbb{R}^p f_* \mathcal{K}^{\bullet}$ are coherent and that there is a canonical isomorphism

$$(\mathbb{R}^p \varphi_* \mathcal{K})_0 \approx H^p(\mathcal{K}_0^{\bullet}).$$

Remark 4. This theorem is proved only in the case dim S = 1 and X is smooth in [vSt]. These assumptions are nevertheless not used in the proof.

4.3 Proof of the coherence theorem

We construct a transversal vector field θ to $(\varphi, \mathcal{C}_{Z/\Lambda})$. The fact that φ is a standard representative implies that at any point $x \in \partial \overline{D}_{ts}$ there exists a holomorphic function $h \in \mathcal{I}_x$ such that the Hamilton vector field X of h is transverse to $\partial \overline{D}_{ts}$ and points inward D_{ts} , provided that $\varphi(x) \in \Lambda_t$.

Proposition 2 implies that the cohomology sheaves $\mathcal{H}^p(\mathcal{C}^{\bullet}_{Z/\Lambda})$ are constant along the integral lines of X. Consequently, for $t \in [0, 1]$, we can find a covering (V_k) of $D_s \setminus \{0\}$ such that there exists a Hamiltonian vector field X_k in V_k transversal to $(\varphi, \mathcal{C}^{\bullet}_{Z/\Lambda})$.

Take a partition of the unity (ψ_k, V_k) of $D_s \setminus \{0\}$ and define the C^{∞} vector-field

$$\theta = \sum_{k=1}^{s} \psi_k X_k.$$

This vector field is transversal to $(\varphi, \mathcal{C}^{\bullet}_{Z/\Lambda})$. This concludes the proof of Theorem 4.

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