Diagonal Plus Tridiagonal Representatives for Symplectic Congruence Classes of Symmetric Matrices

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Abstract. Let n = 2m be even and denote by $\text{Sp}_n(F)$ the symplectic group of rank m over an infinite field F of characteristic different from 2. We show that any $n \times n$ symmetric matrix A is equivalent under symplectic congruence transformations to the direct sum of $m \times m$ matrices B and C, with B diagonal and C tridiagonal. Since the $\text{Sp}_n(F)$ -module of symmetric $n \times n$ matrices over F is isomorphic to the adjoint module $\mathfrak{sp}_n(F)$, we infer that any adjoint orbit of $\text{Sp}_n(F)$ has a representative in the sum of 3m - 1 root spaces, which we explicitly determine.

1 Introduction

A *bilinear space* over a field *F* is an ordered pair (V, φ) consisting of a finite-dimensional *F*-vector space *V* and a bilinear form $\varphi: V \times V \to F$. In this context the first basic question is to decide when two bilinear spaces, say (V, φ) and (W, ψ) , are *equivalent*, *i.e.*, they admit a linear isomorphism $f: V \to W$ satisfying $\psi(f(x), f(y)) = \varphi(x, y)$ for all $x, y \in V$. P. Gabriel [7] showed how to reduce this problem to the non-degenerate case. Work by J. Williamson [12] and C. Riehm [9] reduces the latter to the equivalence of quadratic and hermitian forms and the similarity of matrices. The equivalence problem of sesquilinear forms and its relationship to the determination of conjugacy classes in the classical linear groups is considered by G. E. Wall in [11].

Let us mention one interesting application of the structure theory of bilinear spaces. If (V, φ) is a bilinear space, define its *transpose* to be the bilinear space (V, φ') where φ' is defined by $\varphi'(x, y) = \varphi(y, x)$ for all $x, y \in V$. It is a rather non-trivial fact that the bilinear spaces (V, φ) and (V, φ') are equivalent. Moreover, the corresponding form-preserving linear isomorphism can be chosen to be an involution. This was first proved by R. Gow [8] under the restriction that φ is non-degenerate, but the extension to the general case follows at once from Gabriel's work. An alternative proof is given in [3]. An algorithm to compute the aforementioned involutory isomorphism is presented in [6].

From now on we shall assume that the characteristic of F is not 2. Let (V, φ) be a bilinear space. Given a basis \mathfrak{B} of V, we write $M_{\mathfrak{B}}(\varphi)$ for the Gram matrix of φ

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relative to \mathfrak{B} . We define the symmetric and alternating parts of φ to be the forms

$$\varphi^+ = (\varphi + \varphi')/2$$
 and $\varphi^- = (\varphi - \varphi')/2$.

In this paper we shall deal exclusively with bilinear spaces whose associated alternating form is non-degenerate. This implies that the dimension of our bilinear spaces is even, say n = 2m. Let (V, φ) and (W, ψ) be such bilinear spaces. Let us write J_m , or simply J, for the matrix

$$\begin{pmatrix} 0 & I_m \\ -I_m & 0 \end{pmatrix}$$

The symplectic group $\text{Sp}_n(F)$ is the stabilizer of *J* under the action of $\text{GL}_n(F)$ by congruence transformations, *i.e.*,

$$\operatorname{Sp}_n(F) = \{ X \in \operatorname{GL}_n(F) : X'JX = J \}.$$

(Here X' denotes the transpose of X.) It is well known that V and W admit bases \mathfrak{B} and \mathfrak{C} such that

$$M_{\mathfrak{B}}(\varphi^{-}) = J = M_{\mathfrak{C}}(\psi^{-}).$$

It follows that (V, φ) and (W, ψ) are equivalent if and only if the symmetric matrices $M_{\mathfrak{V}}(\varphi^+)$ and $M_{\mathfrak{C}}(\psi^+)$ are equivalent under the congruence action of $\operatorname{Sp}_n(F)$.

Thus we are led to the study of normal forms of symmetric matrices under symplectic congruence. This matrix problem is exactly the one considered and solved by J. Williamson [12]. Although he worked in characteristic 0, his results and proofs remain valid for any field of characteristic different from 2. Explicit normal forms in the case of the real field were computed by D. M. Galin (see [2, Appendix 6]).

The present work aims at further contributing to this theory by exhibiting representatives for the congruence action of $\text{Sp}_n(F)$ on symmetric matrices which are very much unlike any others previously considered.

We point out that the module, $\text{Sym}_n(F)$, of symmetric *n* by *n* matrices over *F* under the congruence action of $\text{Sp}_n(F)$ is isomorphic to the adjoint module

$$\mathfrak{sp}_n(F) = \{ Z \in M_n(F) : Z'J_m + J_m Z = 0 \}.$$

An explicit isomorphism from the former to the latter is given by $A \rightarrow Z = J_m A$. Hence, the problem solved by Williamson is equivalent to the problem of finding normal forms for the adjoint action of $\text{Sp}_n(F)$ on its Lie algebra $\mathfrak{sp}_n(F)$. In the case of the real field, one can consult [4] or [5] for the description of normal forms. The case when Z is nilpotent has been described in detail, for arbitrary F of characteristic different from 2, by Springer and Steinberg [10, Chapter IV].

Let us consider the Z₂-gradation $\mathfrak{g} = \mathfrak{g}_0 \oplus \mathfrak{g}_1$ of $\mathfrak{g} = \mathfrak{sp}_n(F)$, where

$$\mathfrak{g}_0 = \left\{ \begin{pmatrix} X & 0 \\ 0 & -X' \end{pmatrix} : X \in M_m(F) \right\},$$

and

$$\mathfrak{g}_1 = \left\{ \begin{pmatrix} 0 & Y \\ Z & 0 \end{pmatrix} : X, Y \in \operatorname{Sym}_m(F) \right\}.$$

(Here $M_n(F)$ is the algebra of all $n \times n$ matrices over F.)

By generalizing a special case of a theorem of L. V. Antonyan [1, Theorem 2], we obtained the following result in [6] (see Theorem 1.6, part (i)).

Theorem 1.1 Let F be any field of characteristic different from 2 and let n = 2mbe even. Then every adjoint orbit of $\text{Sp}_n(F)$ in $\mathfrak{g} = \mathfrak{sp}_n(F)$ meets the subspace \mathfrak{g}_1 . Equivalently, for any $A \in \text{Sym}_n(F)$, there exists $X \in \text{Sp}_n(F)$ such that

$$X'AX = \left[\begin{array}{cc} B & 0 \\ 0 & C \end{array} \right],$$

where $B, C \in \text{Sym}_m(F)$.

It is obvious that in this theorem we can further require *B* or *C* to be a diagonal matrix. This is a consequence of the fact that every symmetric matrix over *F* is congruent to a diagonal one and the observation that $X \oplus (X')^{-1} \in \text{Sp}_n(F)$ for $X \in \text{GL}_m(F)$. It is not possible to demand that both *B* and *C* above are always diagonal. However, it is pleasantly surprising that, under the further assumption that *F* is infinite, we can make *B* diagonal and *C* tridiagonal.

Theorem 1.2 Let F be an infinite field of characteristic different from 2, and A a symmetric matrix of size n = 2m. Then A is congruent under the symplectic group $\text{Sp}_n(F)$ to the direct sum of a diagonal $m \times m$ matrix B and a tridiagonal $m \times m$ matrix C.

It may be of interest to reformulate this theorem in terms of the adjoint module $\mathfrak{g} = \mathfrak{sp}_n(F)$. The subspace $\mathfrak{h} \subset \mathfrak{g}$ consisting of the diagonal matrices

diag $(\xi_1, \xi_2, \dots, \xi_m, -\xi_1, -\xi_2, \dots, -\xi_m), \quad \xi_1, \xi_2, \dots, \xi_m \in F$

is a Cartan subalgebra of g. Let $\varepsilon_i \colon \mathfrak{h} \to F$ be the linear function which takes the value ξ_i at the above diagonal matrix. The root system of $(\mathfrak{g}, \mathfrak{h})$ consists of the functions $\pm \varepsilon_i \pm \varepsilon_j$ for $1 \le i < j \le m$ and the functions $\pm 2\varepsilon_i$ for $1 \le i \le m$. The roots

$$\alpha_1 = \varepsilon_1 - \varepsilon_2, \ \alpha_2 = \varepsilon_2 - \varepsilon_3, \dots, \ \alpha_{m-1} = \varepsilon_{m-1} - \varepsilon_m, \ \alpha_m = 2\varepsilon_m$$

form a base of this root system (of type C_m).

We denote by g^{α} the (1-dimensional) root space corresponding to the root α :

$$\mathfrak{g}^{\alpha} = \{ Z \in \mathfrak{g} : [H, Z] = \alpha(H)Z, \forall H \in \mathfrak{h} \}.$$

If $A = B \oplus C$ where $B, C \in \text{Sym}_m(F)$, with *B* diagonal and *C* tridiagonal, then the matrix $Z = J_m A \in \mathfrak{g}$ lies in the sum of root spaces corresponding to the roots

$$\pm 2\alpha_1, \pm 2\alpha_2, \ldots, \pm 2\alpha_m$$

and

$$\alpha_1 + \alpha_2, \alpha_2 + \alpha_3, \ldots, \alpha_{m-1} + \alpha_m.$$

Hence, the above theorem can be reformulated as follows.

Theorem 1.3 For any infinite field F of characteristic different from 2, any adjoint orbit of $\text{Sp}_n(F)$ in $\mathfrak{g} = \mathfrak{sp}_n(F)$ meets the sum of the root spaces \mathfrak{g}^{α} where α runs through the 3m - 1 roots listed above.

2 Preliminary Results

This section gathers subsidiary results to our main theorem. Recall that a square matrix over F is said to be indecomposable if it is not congruent to the direct sum of square matrices over F of smaller size. Let * be the involution of F[t] which sends $t \mapsto -t$. Thus if $f \in F[t]$, then $f^*(t) = f(-t)$. A proof for the following theorem may be extracted from [10, Chapter IV]. More precisely, the assertions (a) and (b) are well known (and easy to prove) and for (c) and (d) see [10, 2.19 and Corollary 2.20, p. 259].

Theorem 2.1 Let F be a field of characteristic different from 2, let n = 2m be an even positive integer, and let $A \in \text{Sym}_n(F)$. Assume that J + A is indecomposable (under congruence) and set Z = JA. Then one of the following holds:

- (a) Z is invertible and has only one elementary divisor. This divisor is of the form f^k where f is monic, irreducible, and $f^* = f$.
- (b) Z is invertible and has two elementary divisors. These divisors have the form f^k and $(f^*)^k$, where f is monic, irreducible, and $f^* \neq f$.
- (c) Z is nilpotent and has only one elementary divisor, t^n .
- (d) The integer m is odd and Z is nilpotent with exactly two elementary divisors, t^m and t^m . Moreover, if $B \in \text{Sym}_n(F)$ and the elementary divisors of Y = JB are t^m and t^m then $XYX^{-1} = Z$ for some $X \in \text{Sp}_n(F)$.

Our requirement that char $F \neq 2$ is not needed in the next result.

Lemma 2.2

Let \langle , \rangle : $V \times V \rightarrow F$ be a symmetric bilinear form. Let v_1, \ldots, v_s be vectors in V. Define the vectors e_1, \ldots, e_s of V by expanding the following "determinants" along the last column:

$$e_1 = v_1, \ e_2 = \begin{vmatrix} \langle v_1, v_1 \rangle & v_1 \\ \langle v_2, v_1 \rangle & v_2 \end{vmatrix}, \dots, e_s = \begin{vmatrix} \langle v_1, v_1 \rangle & \langle v_1, v_2 \rangle & \dots & \langle v_1, v_{s-1} \rangle & v_1 \\ \langle v_2, v_1 \rangle & \langle v_2, v_2 \rangle & \dots & \langle v_2, v_{s-1} \rangle & v_2 \\ \vdots & \vdots & & \vdots \\ \langle v_s, v_1 \rangle & \langle v_s, v_2 \rangle & \dots & \langle v_s, v_{s-1} \rangle & v_s \end{vmatrix}.$$

Then e_1, \ldots, e_s are orthogonal. Moreover, span $\{e_1, \ldots, e_s\} = \text{span}\{v_1, \ldots, v_s\}$ provided each of

$$\langle v_1, v_1 \rangle, \begin{vmatrix} \langle v_1, v_1 \rangle & \langle v_1, v_2 \rangle \\ \langle v_2, v_1 \rangle & \langle v_2, v_2 \rangle \end{vmatrix}, \dots, \begin{vmatrix} \langle v_1, v_1 \rangle & \langle v_1, v_2 \rangle & \dots & \langle v_1, v_{s-1} \rangle \\ \langle v_2, v_1 \rangle & \langle v_2, v_2 \rangle & \dots & \langle v_2, v_{s-1} \rangle \\ \vdots & \vdots & & \vdots \\ \langle v_{s-1}, v_1 \rangle & \langle v_{s-1}, v_2 \rangle & \dots & \langle v_{s-1}, v_{s-1} \rangle \end{vmatrix}$$

is nonzero.

Proof Since span $\{e_1, \ldots, e_i\} \subseteq \text{span}\{v_1, \ldots, v_i\}$ for all $1 \le i \le s$, it suffices to verify $\langle v_1, e_i \rangle = \cdots = \langle v_{i-1}, e_i \rangle = 0$ for all $2 \le i \le s$ in order to show the orthogonality of e_1, \ldots, e_s . If $1 \le j < i \le s$ then $\langle v_j, e_i \rangle$ is the determinant of the $i \times i$ matrix defining e_i , except that its last column must be replaced by column j. Having two equal columns, this determinant is 0. As the last assertion of the lemma is obvious, the proof is complete.

We adopt the following conventions for the remainder of the paper. We fix a matrix $A \in \text{Sym}_n(F)$ and define the symmetric and alternating bilinear forms \langle , \rangle and \langle , \rangle_1 on the column space $V = F^n$, by means of

$$\langle x, y \rangle = x'Ay, \quad \langle x, y \rangle_1 = x'Jy, \quad x, y \in V.$$

Set Z = JA. We view V as module over the polynomial algebra F[t] by letting t act as left multiplication by Z. Observe that

(2.1)
$$AZ = -Z'A \text{ and } JZ = -A,$$

or equivalently

(2.2)
$$\langle x, ty \rangle = -\langle tx, y \rangle, \quad x, y \in V,$$

(2.3)
$$\langle x, ty \rangle_1 = -\langle x, y \rangle, \quad x, y \in V$$

Repeated application of (2.2) yields

(2.4)
$$\langle x, py \rangle = \langle p^*x, y \rangle, \quad x, y \in V, p \in F[t]$$

Observe the following immediate consequence of (2.1) and Theorem 2.1: the characteristic polynomial, say f, of Z is even, *i.e.*, $f^* = f$.

Let us say that $v \in V$ is a generator if it generates V as F[t]-module.

Lemma 2.3 Suppose that the characteristic and minimal polynomials of Z are equal, say to f. Given $v \in V$, let $W = \text{span}\{v, Z^2v, \dots, Z^{2(m-1)}v\}$. Then

- (i) $\langle W, ZW \rangle = 0.$
- (ii) The vector v is a generator if and only if dim W = m and the restriction of \langle , \rangle to W is non-degenerate.
- (iii) If v is a generator, then $V = W \oplus ZW$, $\langle W, ZW \rangle = 0$, $\langle W, W \rangle_1 = 0$ and $\langle ZW, ZW \rangle_1 = 0$.

Proof By (2.2)

$$\langle p(t^2)v, tq(t^2)v \rangle = -\langle tp(t^2)v, q(t^2)v \rangle$$

for all $p, q \in F[t]$. On the other hand, the symmetry of \langle , \rangle and (2.4) give

$$\langle p(t^2)v, tq(t^2)v \rangle = \langle tq(t^2)v, p(t^2)v \rangle = \langle tp(t^2)v, q(t^2)v \rangle.$$

Since the characteristic of *F* is not 2, (i) is established.

We next turn our attention to (ii). If v is a generator, then $V = W \oplus ZW$, which by (i) is an orthogonal decomposition of (V, \langle , \rangle) . Hence dim(W) = m and ker $(Z) \cap W = 0$. As ker(Z) coincides with the radical of \langle , \rangle , the restriction of this form to W is non-degenerate.

Suppose conversely that dim W = m and the restriction of \langle , \rangle to W is nondegenerate. Then $W \cap ZW = 0$ by (i). If $w \in W$ and Zw = 0 then $\langle W, w \rangle = 0$, so w = 0. Thus dim ZW = m, whence $V = W \oplus ZW$, *i.e.*, v is a generator.

To prove (iii), suppose that v is a generator. By (i) and (ii), we know that $V = W \oplus ZW$ is an orthogonal decomposition of (V, \langle , \rangle) . Since f is even, W and ZW are Z^2 -invariant. Let i, j be non-negative integers, with j > 0. Then by (2.3), (2.4) and (i),

$$\langle t^{2i}v, t^{2j}v \rangle_1 = -\langle t^{2i}v, t^{2j-1}v \rangle = 0.$$

It follows that $\langle W, W \rangle_1 = 0$. We may now use (2.3) to infer that $\langle ZW, ZW \rangle_1 = 0$, as well.

Proposition 2.4 Let $A \in \text{Sym}_n(F)$ and suppose the characteristic and minimal polynomials of Z = JA coincide. Denote the field of rational functions on algebraically independent variables x_1, \ldots, x_n over F by $K = F(x_1, \ldots, x_n)$. Write also \langle , \rangle for the bilinear form on the column space K^n , defined by

$$\langle y, z \rangle = y' A z, \quad y, z \in K^n.$$

Let $x = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} \in K^n$. Then \langle , \rangle has non-degenerate restriction to the subspaces $\operatorname{span}\{x\}, \operatorname{span}\{x, Z^2x\}, \ldots, \operatorname{span}\{x, Z^2x, \ldots, Z^{2(m-1)}x\}$. In other words, denoting by $P_k \in F[x_1, \ldots, x_n]$ the determinant of the $k \times k$ left upper corner of

$$M = \begin{pmatrix} \langle x, x \rangle & \langle x, Z^2 x \rangle & \cdots & \langle x, Z^{2(m-1)} x \rangle \\ \langle Z^2 x, x \rangle & \langle Z^2 x, Z^2 x \rangle & \cdots & \langle Z^2 x, Z^{2(m-1)} x \rangle \\ \vdots & \vdots & & \vdots \\ \langle Z^{2(m-1)} x, x \rangle & \langle Z^{2(m-1)} x, Z^2 x \rangle & \cdots & \langle Z^{2(m-1)} x, Z^{2(m-1)} x \rangle \end{pmatrix},$$

then P_k is not zero for all k, $1 \le k \le m$.

Proof By hypothesis there exists v in V which generates V as an F[Z]-module. Thus by Lemma 2.3, the matrix obtained from M by making the substitution $x \rightarrow v$ is invertible. Therefore det $M = P_m$ is not zero. Clearly P_1 is not zero either.

In order to show the other P_k are not zero, it will be convenient to replace M by a similar matrix. Consider the matrix $N \in M_m(F[x_1, ..., x_n])$, defined by

$$N = \begin{pmatrix} \langle x, x \rangle & \langle Zx, Zx \rangle & \cdots & \langle Z^{m-1}x, Z^{m-1}x \rangle \\ \langle Zx, Zx \rangle & \langle Z^2x, Z^2x \rangle & \cdots & \langle Z^mx, Z^mx \rangle \\ \vdots & \vdots & & \vdots \\ \langle Z^{m-1}x, Z^{m-1}x \rangle & \langle Z^mx, Z^mx \rangle & \cdots & \langle Z^{2(m-1)}x, Z^{2(m-1)}x \rangle \end{pmatrix}.$$

Denote by M(k) and N(k) the $k \times k$ left upper corners of M and N, respectively. Let D(k) be the $k \times k$ diagonal matrix with alternating diagonal entries 1 and -1, in this order. Since AZ = -Z'A, we have as before,

$$\langle y, Zz \rangle = -\langle Zy, z \rangle, \quad y, z \in K^n.$$

It follows easily that

$$D(k)M(k)D(k) = N(k), \quad 1 \le k \le m.$$

Thus it suffices to show the polynomials $R_k = \det N(k)$ are non-zero.

Given $k, 1 \le k \le m$, and $l, 1 \le l \le m - k + 1$, let N(k, l) be the $k \times k$ submatrix of N in the intersection of rows $1, \ldots, k$ and columns $l, \ldots, l + k - 1$. Write $R_{k,l} \in F[x_1, \ldots, x_n]$ for the determinant of N(k, l). Thus $R_{k,1}$ is nothing but R_k . In fact, the very definition of N yields the following fundamental relation:

(2.5)
$$R_{k,l}(x) = R_k(Z^{l-1}x).$$

Suppose our result is false and choose k as small as possible satisfying $R_k = 0$. We know that k > 1. As R_{k-1} is not zero, it follows that the first k - 1 rows of N(k) are linearly independent over K and row k is a linear combination of the preceding rows. Thus, by subtracting from row k a suitable linear combination of rows $1, \ldots, k - 1$ we may transform the first k entries on row k of N to zero.

Denote this new matrix by P. Since N is invertible and P is row equivalent to N, some entry along row k of P must be non-zero. Suppose this entry, say a, occurs in the position s, where s is as small as possible.

For l = s - k + 1, consider the submatrix *T* of *P* in the intersections of rows $1, \ldots, k$ and columns $l, \ldots, l + k - 1 = s$. Its last row is $0, \ldots, 0, a$ and the intersection of its first k - 1 rows and columns constitute the matrix N(k - 1, l). Since R_{k-1} is not zero, it follows from (2.5) that the determinant of N(k - 1, l) is not zero. Hence *T* is invertible. But *T* is row equivalent to N(k, l), which by (2.5) is singular. This contradiction completes the proof.

3 Main Result

We are ready to prove our main result.

Theorem 3.1 Let F be an infinite field of characteristic different from 2, let n = 2m be an even integer, and $A \in \text{Sym}_n(F)$. Then there exists $X \in \text{Sp}_n(F)$ and $B, C \in \text{Sym}_m(F)$ such that B is diagonal, C is tridiagonal, and

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Proof Clearly, without any loss of generality, we may assume that $J_m + A$ is indecomposable. Let $V = F^n$ be the space of column vectors. We make V into an F[t]-module by letting t act as the matrix $Z = J_m A$. By Theorem 2.1, there are four possibilities, (a)–(d), for the matrix Z.

We assume first that V is cyclic as an F[t]-module, *i.e.*, we exclude case (d).

Let P_1, \ldots, P_m be the non-zero polynomials defined in Proposition 2.4. Consider their product $P = P_1 \cdots P_m$. Since *F* is infinite and *P* is not zero, there exists $v \in F^n$ such that $P(v) \neq 0$, that is, none of P_1, \ldots, P_m vanish on *v*.

Consider the subspace *W* of *V* spanned by the vectors $v, Z^2v, \ldots, Z^{2(m-1)}v$. Since $P_m(v) \neq 0$, Lemma 2.3 ensures that

$$V = W \oplus ZW, \quad \langle W, ZW \rangle = 0, \quad \langle W, W \rangle_1 = 0, \quad \langle ZW, ZW \rangle_1 = 0,$$

with the restriction of \langle , \rangle to *W* non-degenerate.

Construct the vectors e_1, \ldots, e_m by applying Lemma 2.2 to the form \langle , \rangle and the vectors $v, Z^2v, \ldots, Z^{2(m-1)}v$. It follows that e_1, \ldots, e_m are orthogonal relative to \langle , \rangle . As the restriction of \langle , \rangle to W is non-degenerate, the vectors e_1, \ldots, e_m are non-isotropic. Since none of P_1, \ldots, P_{m-1} vanish on v, Lemma 2.2 ensures that e_1, \ldots, e_m span W. Note that the matrix B of the restriction of \langle , \rangle to W is diagonal and nonsingular.

Let $f_i = -\langle e_i, e_i \rangle^{-1} Z e_i$, for $1 \le i \le m$. It is not difficult to see at this point that $\{e_1, \ldots, e_m, f_1, \ldots, f_m\}$ must be a symplectic basis of *V*.

We still have to show that the matrix *C* of the restriction of \langle , \rangle to *ZW* is tridiagonal. This means that $\langle Ze_i, Ze_j \rangle = 0$ if j - i > 1. Suppose that j - i > 1. We have

$$\langle Ze_i, Ze_j \rangle = -\langle Z^2e_i, e_j \rangle.$$

Since $e_i \in \text{span}\{v, Z^2v, \dots, Z^{2(i-1)}v\}$, it follows that

$$Z^2 e_i \in \text{span}\{v, Z^2 v, \dots, Z^{2(i-1)}v, Z^{2i}v\}.$$

At this crucial point we recall that none of P_1, \ldots, P_i vanishes at ν . Hence, by Lemma 2.2,

$$\operatorname{span}\{v, Z^2v, \ldots, Z^{2(i-1)}v, Z^{2i}v\} = \operatorname{span}\{e_1, e_2, \ldots, e_i, e_{i+1}\}.$$

But e_j is orthogonal to $e_1, \ldots, e_i, e_{i+1}$ relative to \langle , \rangle , whence $\langle Ze_i, Ze_j \rangle = 0$.

It remains to consider case (d) of Theorem 2.1.

As *m* is odd, we set m = 2s+1. It is well known that there exists a nilpotent matrix $Y_1 \in \mathfrak{sp}_{2s}(F)$ of rank 2s - 1 (a principal nilpotent element of this Lie algebra). For instance, we can take

$$Y_1 = \begin{bmatrix} Y_{11} & Y_{12} \\ 0 & -Y'_{11} \end{bmatrix},$$

where Y_{11} is the upper triangular nilpotent Jordan block of size *s* and all the entries of Y_{12} are 0 except the one in the lower right hand corner which is equal to 1.

Set $A_1 = -J_s Y_1$. Assume that $J_s + A_1$ is decomposable. Then there exists an invertible matrix X such that

$$X'(J_s + A_1)X = (J_p + A_{11}) \oplus (J_q + A_{12})$$

for some positive integers p, q (with p + q = s) and some symmetric matrices A_{11} and A_{12} . We have

$$X'J_sX=J_p\oplus J_q, \quad X'A_1X=A_{11}\oplus A_{12}.$$

We obtain that

$$Y_1 = -J_s^{-1}A_1 = X(J_p \oplus J_q)X'(X')^{-1}(A_{11} \oplus A_{12})X^{-1}$$

giving the contradiction $X^{-1}Y_1X = J_pA_{11} \oplus J_qA_{12}$. We conclude that $J_s + A_1$ is indecomposable.

By the first part of the proof (covering case (c) of Theorem 2.1), A_1 is symplectically congruent to a matrix $B_1 \oplus C_1$, where $B_1, C_1 \in \text{Sym}_s(F)$ with B_1 diagonal and nonsingular and C_1 tridiagonal and of rank s - 1. As $J_s + A_1$ is indecomposable, all entries of C_1 lying just above the diagonal must be non-zero. In particular, the first s - 1 rows of C_1 are linearly independent. Since $J_s(B_1 \oplus C_1)$ is nilpotent, we have $(B_1C_1)^s = (C_1B_1)^s = 0$.

Let g_1, g_2, \ldots, g_s denote the standard basis of the column space F^s . Let *S* be the $s \times s$ permutation matrix representing the transformation $g_1 \leftrightarrow g_s, g_2 \leftrightarrow g_{s-1}, etc.$ We take *B* to be the diagonal matrix $B = B_1 \oplus [0] \oplus (-SB_1S)$ of size *m* and rank m - 1, and define the tridiagonal matrix $C \in Sym_m(F)$ by

$$C = \begin{bmatrix} C_1 & g_s & 0 \\ g'_s & 0 & g'_1 \\ 0 & g_1 & -SC_1S \end{bmatrix}.$$

We claim that the matrix $Y := J_m(B \oplus C)$ is similar to the direct sum of two nilpotent Jordan blocks, each of size *m*.

First we prove that $Y^m = 0$. Clearly we have

$$Y^m = (-1)^s \begin{bmatrix} 0 & (CB)^s C \\ -(BC)^s B & 0 \end{bmatrix}.$$

As

$$BC = \begin{bmatrix} B_1 C_1 & B_1 g_s & 0\\ 0 & 0 & 0\\ 0 & -S B_1 S g_1 & S B_1 C_1 S \end{bmatrix}$$

and $(B_1C_1)^s = 0$, we have

$$(BC)^{s} = \begin{bmatrix} 0 & (B_{1}C_{1})^{s-1}B_{1}g_{s} & 0\\ 0 & 0 & 0\\ 0 & -S(B_{1}C_{1})^{s-1}B_{1}Sg_{1} & 0 \end{bmatrix}$$

Hence $(BC)^{s}B = 0$. Now B_1 is invertible, so $C_1(B_1C_1)^{s-1} = 0$. This fact together with the last displayed equation and $Sg_1 = g_s$ yield $C(BC)^{s} = 0$, or equivalently $(CB)^{s}C = 0$. This proves that $Y^{m} = 0$.

Next we shall prove that *C* has rank m - 1. Recall that the first s - 1 rows of C_1 are linearly independent. As C_1 is singular, its last row is a linear combination of the first s - 1 rows. Consequently, by subtracting a suitable linear combination of the first s - 1 rows of *C* from its *s*-th row, we obtain a row having all entries 0 except the central entry which is equal to 1. A similar argument is applicable to the last *s* rows of *C*, *i.e.*, by subtracting a suitable linear combination of the s + 2-nd row, we obtain the same row as above. This shows that *C* is singular. On the other hand, by deleting the last row and the first column of *C*, we obtain an invertible lower triangular matrix. We conclude that *C* has rank m - 1.

Since $Y^m = 0$ and Y has rank n - 2, Y has to be similar to the direct sum of two nilpotent Jordan blocks of size *m* each, *i.e.*, our claim is proved.

As we are dealing with case (d) of Theorem 2.1, both *Y* and *Z* belong to $\mathfrak{sp}_n(F)$ and are nilpotent and have exactly two elementary divisors, t^m and t^m . As *m* is odd, we know from Theorem 2.1 that *Y* and *Z* are symplectically similar. Consequently, the matrices *A* and $B \oplus C$ are symplectically congruent.

This completes the proof of the theorem.

Final Comment It would be worthwhile to determine if Theorem 3.1 remains valid for finite fields of characteristic different from 2. Our method yields a positive answer provided the polynomial function associated to $P_1 \cdots P_m$ (as defined in Proposition 2.4) is not identically zero, which is a problem of independent interest.

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