## COMPLETELY CONTINUOUS MOVEMENTS IN TOPOLOGICAL VECTOR SPACES

## by J. H. MICHAEL

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1. Introduction. Let A be a closed subset of a topological space X and f a continuous mapping of A into X with the following two properties :

1.1.  $f\{ Fr(A) \}$  and  $f\{ Int(A) \}$  are disjoint.

1.2. The mapping  $f_* = f \mid Fr(A)$  is 1-1.

It is proved in [5], that if X is the euclidean n-sphere  $S^n = \{x ; x \in \mathbb{R}^{n+1} \text{ and } ||x|| = 1\}$ , then

1.3.  $f{Fr(A)} = Fr{f(A)}.$ 

[Hence  $f{\text{Int}(A)} = \text{Int}{f(A)}]$ .

The purpose of the present paper is to prove (Theorem 4.4.) that 1.3 is true when X is a real convex topological vector space with a Hausdorff topology and f satisfies the additional requirement of being a completely continuous movement. The proof of this theorem makes use of the degree of completely continuous movements.

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2. Notation. We shall assume henceforth that E denotes a real convex topological vector space with a Hausdorff topology.  $\mathscr{U}$  is the collection of all convex symmetrical open neighbourhoods of the origin. In the usual way, a mapping f of a subset A of E into E is defined to be *completely continuous* on A if it is continuous and there exists a compact subset K of E with  $f(A) \subseteq K$ . Following Nagumo [6], we define a *completely continuous movement* of a subset A of E to be a mapping f of A into E, such that the function

$$\phi(x) \equiv f(x) - x$$

is completely continuous on A. Set complementation is denoted by  $\sim$ ; i.e., if  $B \subseteq A$ , then  $A \sim B$  denotes the complement of B in A.

#### 3. The degree of a completely continuous movement.

3.1. We first of all observe that completely continuous movements have the following properties. These are proved in [6].

3.1.1. If A is a closed subset of E and f is a completely continuous movement of A, then f(A) is closed.

3.1.2. If f, g are completely continuous movements of A, f(A), respectively, then gf is a completely continuous movement of A.

3.1.3. If f is a 1-1 completely continuous movement of A and A is closed, then  $f^{-1}$  is a completely continuous movement of f(A).

3.2. Consider the triple (f, A, b), where A is a subset of E, f is a completely continuous movement of Fr (A) and b is a point of  $E \sim f\{Fr(A)\}$ . With each such triple there is associated an integer

called its degree.<sup>†</sup> This degree has the following properties.

3.2.1. If f is the identity mapping of Fr (A), then

$$d(f, A, x) = 1 \quad \text{when } x \in \text{Int} (A),$$
  
= 0 when  $x \in E \sim \overline{A}.$ 

3.2.2. If f is a completely continuous movement of  $\overline{A}$  and  $b \notin f(\overline{A})$ , then

$$d(f, A, b) = 0.$$

3.2.3. Let  $\mathscr{G}$  be a collection of mutually disjoint open subsets of Int (A). Put

$$U = \bigcup_{G \in \mathscr{G}} G.$$

If f is a completely continuous movement of  $\overline{A} \sim U$  and  $b \in E \sim f(\overline{A} \sim U)$ , then d(f, G, b) = 0 for all but a finite number of  $G \in \mathcal{G}$  and

$$d(f, A, b) = \sum_{G \in \mathscr{G}} d(f, G, b).$$

3.2.4. If f is a completely continuous movement of Fr (A) and  $b_1$ ,  $b_2$  are points of the same component of  $E \sim f\{Fr(A)\}$ , then

$$d(f, A, b_1) = d(f, A, b_2).$$

3.2.5. If f is a completely continuous movement of Fr (A),  $b \in E \sim f\{Fr(A)\}, U \in \mathcal{U}$  and U is such that b + U does not intersect  $f\{Fr(A)\}$  and if  $f_1$  is a completely continuous movement of Fr (A) such that

 $f(x) - f_1(x) \in U$ 

for all  $x \in Fr(A)$ , then

 $d(f, A, b) = d(f_1, A, b).$ 

3.2.6. Let B be a second subset of E, f and g be completely continuous movements of  $\overline{A}$  and  $\overline{B}$  such that  $f(\overline{A}) \subseteq \overline{B}$ , and b be a point of  $E \sim g[\operatorname{Fr}(B) \cup f\{\operatorname{Fr}(A)\}]$  such that d(f, A, y) is constant for  $y \in g^{-1}(b)$ . Then

$$\begin{aligned} d(gf, A, b) = d(g, B, b) \cdot d\{f, A, g^{-1}(b)\} & \text{if } g^{-1}(b) \neq \emptyset, \\ = 0 & \text{if } g^{-1}(b) = \emptyset. \end{aligned}$$

[Here  $d\{f, A, g^{-1}(b)\}$  denotes the constant value of d(f, A, y) for  $y \in g^{-1}(b)$ ].

Further properties of the degree are given by Theorems 3.2.7 and 3.2.9, which appear below. Theorem 3.2.9 is not new (it is used by Leray in [3], for example), but since the proof does not appear to be readily available in the literature, the theorem is proved here.

3.2.7. THEOREM. Let A be a subset of E, f be a completely continuous movement of Fr (A) and b  $\epsilon E \sim f\{Fr(A)\}$ . Let K be a compact subset of E such that

$$f(x) - x \in K$$

for all  $x \in Fr(A)$ . If F is a linear manifold of E which contains b and K, then

$$d(f, A, b) = d(f, F \cap A, b)$$
 in F.

**Proof.** Choose  $U \in \mathcal{U}$  such that b + U does not intersect  $f{Fr(A)}$ . K is evidently compact in F; hence, by Theorem 2 of [6], there exist a finite dimensional linear manifold G of F containing b, and a continuous mapping  $\phi$  of K into G such that

$$\phi(x) - x \in U,$$

† For the definition and properties of the degree, see [3] and [6]. Actually, in [3] and [6] the degree is defined for open A. However, it can easily be defined for arbitrary A by putting  $d(f, A, b) = d\{f, \text{Int } (A), b\}.$ 

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for all  $x \in K$ . Put

for all  $x \in Fr(A)$ . Since

 $f_1(x) - x = \phi\{f(x) - x\} \in \phi(K),$ 

and  $\phi(K)$  is compact,  $f_1(x)$  is a completely continuous movement of Fr (A). Also

$$f(x) - f_1(x) = - [\phi \{f(x) - x\} - \{f(x) - x\}];$$

hence

 $f(x) - f_1(x) \in U,$  .....(2)

for all  $x \in Fr(A)$ . Furthermore, it follows from (1) that

 $f_1(x) - x \in G$ , .....(3)

for all  $x \in Fr(A)$ . Now, by (2) and 3.2.5,

$$d(f, A, b) = d(f_1, A, b),$$

and, by 3.2.3, this is

 $d(f_1, \text{Interior of } A \text{ in } E, b),$ 

which, by (3) and [3], equals

 $\{df_1, G \cap (\text{Interior of } A \text{ in } E), b\} = d\{f_1, F \cap (\text{Interior of } A \text{ in } E), b\};$ hence, by 3.2.3,

 $d(f, A, b) = d(f_1, F \cap A, b),$ 

and, since (Frontier of  $(F \cap A)$  in  $F \subseteq ($ Frontier of A in  $E \cap F$ , we have, by (2) and 3.2.5,

 $d(f, A, b) = d(f, F \cap A, b).$ 

3.2.8. LEMMA. If F is a linear manifold of E and K is a compact subset of F which spans F, then the relative topology of F is normal.

**Proof.** The relative topology of F is regular and Lemma 1 on p. 113 of [1] shows that a regular Lindelöf space is normal. Hence we have only to prove that F is a Lindelöf space, i.e. that each covering of F by open sets of F has a countable subcovering.

To this end, let  $\mathscr{V}$  be an open covering of F. For each positive integer n, let  $K_n$  be the set of all points

$$\lambda_1 x_1 + \ldots + \lambda_n x_n$$

of F, where  $x_1, \ldots, x_n \in K$  and  $\lambda_1, \ldots, \lambda_n$  are real numbers such that  $|\lambda_1| \leq n, \ldots, |\lambda_n| \leq n$ . If  $J_n$  denotes the closed interval [-n, n], then  $K_n$  is a continuous image of the compact space  $J_n \times \ldots \times J_n \times K \times \ldots \times K$  (2n factors); hence  $K_n$  is compact. Evidently

$$F = \bigcup_{n=1}^{\infty} K_n$$

For each n we can choose a finite subcollection  $\mathscr{V}'_n$  of  $\mathscr{V}$  which covers  $K_n$ . Let

$$\mathscr{V}' = \bigcup_{n=1}^{\infty} \mathscr{V}'_n.$$

 $\mathscr{V}'$  is countable,  $\mathscr{V}' \subseteq \mathscr{V}$  and  $\mathscr{V}'$  covers F. This completes the proof.

3.2.9. THEOREM. If A and B are subsets of E with Int  $(B) \neq \emptyset$ , f is a completely continuous movement of  $\overline{A}$  into  $\overline{B}$  such that  $f\{\operatorname{Fr}(A)\} \subseteq \operatorname{Fr}(B)$ , g is a completely continuous movement of  $\operatorname{Fr}(B)$ ,  $b \in E \sim g\{\operatorname{Fr}(B)\}$  and d(f, A, y) is constant for  $y \in \operatorname{Int}(B)$ , then

$$d(gf, A, b) = d(g, B, b) \cdot d\{f, A, \text{Int}(B)\}.$$

G.M.A.

*Proof.* Let K and L be compact subsets of E such that

for all  $x \in \overline{A}$  and

$$g(x) - x \in L$$

 $f(x) - x \in K$ 

for all  $x \in Fr(B)$ . Let  $b_1 \in Int(B)$  and F be the linear manifold spanned by the compact set  $K \cup L \cup \{b, b_1\}$ . By 3.2.7,

$$d\{f, A, \text{Int}(B)\} = d\{f, F \cap A, F \cap \text{Int}(B)\}$$
 .....(4)

and

$$d(g, B, b) = d(g, F \cap B, b).$$
(5)

But, since  $K + L \subseteq F$ , K + L is compact and, for all  $x \in Fr(A)$ , we have

$$yf(x) - x = \{f(x) - x\} + [g\{f(x)\} - f(x)] \in K + L_{x}$$

it also follows from 3.2.7 that

Thus, it will be sufficient to prove that

$$d(gf, F \cap A, b) = d(g, F \cap B, b) \cdot d\{f, F \cap A, F \cap \operatorname{Int}(B)\}. \dots (7)$$

By 3.1.1,  $g\{F \cap Fr(B)\}$  is closed in F; hence there exists an open, convex, symmetrical neighbourhood U of the origin in F such that

$$(b+U) \cap g\{F \cap \operatorname{Fr}(B)\} = \emptyset.$$
 (8)

By Theorem 2 of [6], we can find a finite dimensional linear manifold  $F^m$  of F and a continuous mapping  $\theta$  of L into  $F^m$  such that  $\theta(x) - x \in U$ 

for all  $x \in L$ . Put

$$\psi_1(x) = \theta\{g(x) - x\}$$

for all  $x \in F \cap Fr(B)$ . Now  $\theta(L)$  is a compact subset of  $F^m$ ,  $F \cap Fr(B)$  is closed in F,  $\psi_1$  is a continuous mapping of  $F \cap Fr(B)$  into  $\theta(L)$  and, by Lemma 3.2.8, F is normal. Hence one can apply Tietze's Extension Theorem ([2], p. 28) to extend  $\psi_1$  to a continuous mapping of  $F \cap \overline{B}$  into a compact subset  $L_1$  of  $F^m$ . Put

$$g_1(x) = \psi_1(x) + x$$

for all  $x \in F \cap \overline{B}$ . Then  $g_1$  is a completely continuous movement of  $F \cap \overline{B}$  into F and for all  $x \in F \cap Fr(B)$  we have  $g(x) - g_1(x) = \{g(x) - x\} - \theta\{g(x) - x\}$ , and hence

for all  $x \in F \cap Fr(B)$ . Since the frontier of  $F \cap B$  in F is contained in  $F \cap Fr(B)$ , it follows from (8), (9) and 3.2.5 that

$$d(g, F \cap B, b) = d(g_1, F \cap B, b).$$
 ....(10)

Since  $f{F \cap Fr(A)} \subseteq F \cap Fr(B)$ , we obtain from (9)

$$gf(x) - g_1f(x) \in U$$

for all  $x \in F \cap Fr(A)$ ; hence

$$d(qf, F \cap A, b) = d(q, f, F \cap A, b)$$
. ....(11)

Now it follows from (8) and (9) that  $g_1^{-1}(b) \subseteq F \cap \text{Int}(B)$ ; hence, by (4),  $d(f, F \cap A, y)$  is constant for  $y \in g_1^{-1}(b)$ . Therefore, by 3.2.6,

$$d(g_1f, F \cap A, b) = d(g_1, F \cap B, b) \cdot d\{f, F \cap A, F \cap \text{Int}(B)\}.$$
 (12)

Equation (7) now follows immediately from (10), (11) and (12), and the proof is complete.

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4. The main result. In this section we prove the theorem that was discussed in § 1. Throughout the section A denotes a closed subset of E and f a completely continuous movement of A with the properties 1.1 and 1.2. As in 1.2,  $f_* = f | Fr(A)$ .

4.1. LEMMA. If Q is a component of  $E \sim f\{Fr(A)\}$  which intersects f(A) and if  $P = f^{-1}(Q)$ , then

(i) Q does not intersect  $f{Fr (P)}$ , and

$$d(f, P, y) \neq 0$$

for all  $y \in Q$ ;

(ii)  $\operatorname{Fr}(Q) \subseteq f\{\operatorname{Fr}(A)\}, f_{*}^{-1}\{\operatorname{Fr}(Q)\} \text{ does not intersect } P \text{ or } E \sim \overline{P} \text{ and} d(f_{*}^{-1}, Q, x) \neq 0 \text{ for } x \in P,$ 

=0 for 
$$x \in E \sim \overline{P}$$
.

**Proof.** P and Q are evidently open sets of E and

 $Fr(Q) \subseteq f\{Fr(A)\}.$  (13)

If a is an arbitrary point of Fr (P), then  $f(a) \in \overline{Q}$  and  $f(a) \notin Q$ ; for  $f(a) \in Q$  would imply  $a \in P$ . Hence  $f(a) \in Fr(Q)$ . Thus

Hence

 $Q \cap f\{\operatorname{Fr}(P)\} \rightarrow \emptyset.$ 

Also

$$P \cap f_{\ast}^{-1}\{\operatorname{Fr}(Q)\} = \emptyset;$$

for, if  $a' \in P$ , then  $f(a') \in Q$ . Hence  $f(a') \notin \operatorname{Fr}(Q)$ ; i.e.,  $a' \notin f_*^{-1} \{\operatorname{Fr}(Q)\}$ . Now Fr  $(P) \subseteq \operatorname{Fr}(A)$ . ....(15)

For otherwise there would exist a point  $p \in Fr(P)$  with  $p \in Int(A)$ ; then, by 1.1,

$$f(p) \notin f\{\operatorname{Fr}(A)\},\$$

which contradicts (13) and (14). By (14), 3.2.4 and Theorem 3.2.9,

for all  $y \in Q$ ; consequently, since P is not empty,

 $d(f, P, y) \neq 0$  .....(18)

for all  $y \in Q$ . It now follows from (18) and 3.2.2 that  $Q \subseteq f(\overline{P})$ ; hence, since  $f(\overline{P})$  is closed,  $\overline{Q} \subseteq f(\overline{P})$ ; therefore

$$(E \sim \overline{P}) \cap f_{*}^{-1} \{ \operatorname{Fr} (Q) \} = \emptyset.$$
 (19)

For, if  $c \in f_{*}^{-1}{\{Fr(Q)\}}$ , then  $f(c) \in \overline{Q}$ ,  $f(c) \in f(\overline{P})$ , and, since, by (13), 1.1 and 1.2, c is the only point in  $f^{-1}{\{f(c)\}}$ , we have  $c \in \overline{P}$ . Since Q is not empty, it now follows from (17), (18) and (19) that

$$d(f_{*}^{-1}, Q, x) \neq 0, \text{ for } x \in P,$$
  
=0, for  $x \in E \sim \overline{P}.$ 

4.2. LEMMA. Fr  $\{f(A)\} \subseteq f\{Fr(A)\}$ .

*Proof.* Suppose that the lemma is not true; i.e., that there exists a point  $b \in \operatorname{Fr} \{f(A)\}$  with  $b \notin f\{\operatorname{Fr} (A)\}$ . Let Q be the component of  $E \sim f\{\operatorname{Fr} (A)\}$  containing b and put  $P = f^{-1}(Q)$ . By Lemma 4.1,  $d(f, P, y) \neq 0$  for all  $y \in Q$ . But, since Q is open and  $b \in \operatorname{Fr} \{f(A)\}$ , Q must contain a point y' of  $E \sim f(A)$ ; hence  $y' \notin f(\overline{P})$  and, by 3.2.2, d(f, P, y') = 0. This is a contradiction.

4.3. LEMMA. 
$$d\{f_*^{-1}, f(A), x\} \neq 0$$
, for  $x \in Int(A)$ ,  
=0, for  $x \in E \sim A$ .

**Proof.** Let  $x \in E \sim Fr(A)$ . Denote by  $\mathcal{Q}$  the collection consisting of all those components of  $E \sim f\{Fr(A)\}$  that are contained in f(A). By Lemma 4.2,

 $f(A) \sim f\{ \operatorname{Fr}(A) \} = \bigcup_{Q \in \mathcal{Q}} Q.$ (20)

Hence, by 3.2.3,

(Empty sums are regarded as zero.)

Suppose that  $x \in Int(A)$ . By 1.1 and (20), there is exactly one  $Q \in \mathcal{Q}$ , say Q', such that  $x \in f^{-1}(Q)$ . Therefore, by Lemma 4.1,

$$d(f_{*}^{-1}, Q, x) \neq 0$$
, when  $Q = Q'$ ,  
= 0, when  $Q \neq Q'$ .

Hence by (21),  $d\{f_{*}^{-1}, f(A), x\} \neq 0$ .

If  $x \in E \sim A$ , there is no  $Q \in \mathcal{Q}$  with  $x \in f^{-1}(Q)$ , so that, by (21),  $d\{f_*^{-1}, f(A), x\} = 0$ .

4.4. THEOREM.  $f{Fr}(A) = Fr{f(A)}$ .

Proof. Because of Lemma 4.2, we have only to prove that

 $f{\operatorname{Fr}(A)} \subseteq \operatorname{Fr}{f(A)}.$ 

Suppose that this inequality is not true; i.e., that there exists a point  $b \in f\{Fr(A)\}$  with  $b \notin Fr\{f(A)\}$ . Put  $a = f_*^{-1}(b)$ . Then  $a \in Fr(A)$  and  $b \in Int\{f(A)\}$ .

(i) Let  $a \in \overline{\operatorname{Int}(A)}$ . Let C be the component of  $E \sim f_*^{-1}[\operatorname{Fr}\{f(A)\}]$  which contains a. Then C is open and therefore contains a point a' of Int (A) and a point a'' of  $E \sim A$ . By 3.2.4,

$$d\{f_{*}^{-1}, f(A), a'\} = d\{f_{*}^{-1}, f(A), a''\}$$

and this contradicts Lemma 4.3.

(ii) Let  $a \notin \overline{\operatorname{Int}(A)}$ . We have  $b \notin f\{\overline{\operatorname{Int}(A)}\}$ . Since  $b \in \operatorname{Int}\{f(A)\}$ , there exists a  $U \in \mathscr{U}$  with  $\overline{b+U}$  contained in f(A) but not intersecting  $f\{\overline{\operatorname{Int}(A)}\}$ . Then  $\overline{b+U} \subseteq f\{\operatorname{Fr}(A)\}$  and  $f_{\bullet}^{-1} \mid \overline{b+U}$  is a 1-1 completely continuous movement. Therefore, by Lemma 4.2,

$$\operatorname{Fr}\left\{f_{*}^{-1}(\overline{b+U})\right\} \subseteq f_{*}^{-1}\left\{\operatorname{Fr}\left(\overline{b+U}\right)\right\},$$

so that  $a \notin \operatorname{Fr} \{f_*^{-1}(\overline{b+U})\}\$ , and hence  $a \in \operatorname{Int} \{f_*^{-1}(\overline{b+U})\} \subseteq \operatorname{Int}(A)$ . This is a contradiction.

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# ON CERTAIN RELATIONS BETWEEN PRODUCTS OF BILATERAL HYPERGEOMETRIC SERIES

## by HARISHANKER SHUKLA

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1. Introduction. Darling [3] in 1932 and Bailey [2] in 1933 gave certain theorems on products of hypergeometric series. Again in 1948 Sears [4] used the relation which expresses the  ${}_M \Phi_{M-1}(x)$  series in terms of M other series of the same type to derive transformations between products of both basic and ordinary hypergeometric series. In this paper I give certain general theorems on products of bilateral hypergeometric series together with some of their interesting special cases.

The following notation is used throughout the paper :

$$\begin{array}{l} (a \; ; \; n) = (1-a) \, (1-aq) \, \dots \, (1-aq^{n-1}), \quad (a \; ; \; 0) = 1, \\ (a \; ; \; -n) = (-1)^n q^{\frac{1}{n}(n+1)} / a^n (q/a \; ; \; n), \quad |\; q \; | < 1, \\ (a)_n = a(a+1) \, \dots \, (a+n-1), \; (a)_0 = 1, \quad (a)_{-n} = (-1)^n / (1-a)_n, \\ r \, \Psi_r \begin{bmatrix} a_1, \; a_2, \, \dots, \; a_r \; ; \; z \\ b_1, \; b_2, \, \dots, \; b_r \end{bmatrix} = \sum_{n=-\infty}^{\infty} \frac{(a_1 \; ; \; n) \, (a_2 \; ; \; n) \, \dots \, (a_r \; ; \; n)}{(b_1 \; ; \; n) \, (b_2 \; ; \; n) \, \dots \, (b_r \; ; \; n)} \; z^n, \\ r \, H_r \begin{bmatrix} a_1, \; a_2, \, \dots, \; a_r \; ; \; z \\ b_1, \; b_2, \, \dots, \; b_r \end{bmatrix} = \sum_{n=-\infty}^{\infty} \frac{(a_1)_n (a_2)_n \, \dots \, (a_r)_n}{(b_1)_n (b_2)_n \, \dots \, (b_r)_n} \; z^n, \\ \Pi \begin{bmatrix} a_1, \; a_2, \, \dots, \; a_r \\ b_1, \; b_2 \, \dots, \; b_r \end{bmatrix} = \prod_{n=0}^{\infty} \frac{(1-a_1q^n) \, (1-a_2q^n)}{(1-b_1q^n) \, (1-b_2q^n)} \, \dots \, (1-a_rq^n)}, \\ \Gamma \begin{bmatrix} a_1, \; a_2, \, \dots, \; a_r \\ b_1, \; b_2 \, \dots, \; b_r \end{bmatrix} = \frac{\Gamma(a_1)\Gamma(a_2) \, \dots \, \Gamma(a_r)}{\Gamma(b_1)\Gamma(b_2) \, \dots \, \Gamma(b_n)}, \end{array}$$

and idem (a; b) means that the preceding expression is repeated with a and b interchanged.