

LOCAL ANALYSIS OF FRAME MULTIREOLUTION ANALYSIS
WITH A GENERAL DILATION MATRIX

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A multivariate semi-orthogonal frame multiresolution analysis with a general integer dilation matrix and multiple scaling functions is considered. We first derive the formulas of the lengths of the initial (central) shift-invariant space V_0 and the next dilation space V_1 , and, using these formulas, we then address the problem of the number of the elements of a wavelet set, that is, the length of the shift-invariant space $W_0 := V_1 \ominus V_0$. Finally, we show that there does not exist a ‘genuine’ frame multiresolution analysis for which V_0 and V_1 are quasi-stable spaces satisfying the usual length condition.

1. INTRODUCTION

The orthonormal dyadic multiresolution analysis of $L^2(\mathbb{R})$ with a single scaling function was introduced by Mallat and Meyer in order to construct an orthonormal wavelet basis of $L^2(\mathbb{R})$ [17, 18]. Benedetto and Li considered the dyadic semi-orthogonal frame multiresolution analysis of $L^2(\mathbb{R})$ with a single scaling function, and successfully applied the theory in the analysis of narrow band signals [1]. We refer to [9] for the basic definitions and properties of frames and Riesz bases of a Hilbert space. Unlike the multiresolution analysis of Mallat and Meyer, where there always exists a wavelet set consisting of a single element whose dyadic dilations of the integer translates form an orthonormal basis of $L^2(\mathbb{R})$, the multiresolution analysis of Benedetto and Li has a wavelet set whose cardinality may be one or two [14]. The exact definition of a wavelet set of a multiresolution analysis is found in Section 3. The characterisation of the dyadic semi-orthogonal frame multiresolution analysis with a single scaling function admitting a single frame wavelet whose dyadic dilations of the integer translates form a frame for $L^2(\mathbb{R})$ was obtained, independently, by Benedetto and Treiber by a direct method [2], and by Kim and Lim by using the theory of shift-invariant spaces [14]. The dyadic multivariate generalisation (with a single scaling function) of the multiresolution analysis of Mallat and Meyer were considered by several authors. See [3], for example. Lim, among other things, addressed the problem of the cardinality of a wavelet set in the setting of

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the dyadic multivariate frame multiresolution analysis with a single scaling function [16], and Kim and Lim gave an analysis of dyadic multivariate frame multiresolution analysis with multiple scaling functions [15]. As the theory and applications of wavelets evolve, many authors considered more general dilations other than the dyadic ones (for example, [8]).

In this paper we consider a multivariate frame multiresolution analysis with a general integer dilation matrix and multiple scaling functions by extending the method and results of [15]. We first analyse the local dimension of the initial, that is, central, shift-invariant space V_0 and the next dilation space V_1 of the multiresolution analysis. Using this, we derive the formulas of the lengths of the shift-invariant spaces V_0 and V_1 , and address the problem of the number of the elements of a wavelet set. Finally, we show that there does not exist a 'genuine' frame multiresolution analysis for which V_0 and V_1 are quasi-stable spaces satisfying the usual length condition by applying the local dimension analysis and the ergodicity of the dilation matrix (Theorem 9). This result improves Theorem 3.9 in [15] in the sense that we do not presuppose that the spectrums of V_0 and V_1 coincide.

The organisation of this paper is as follows: Preliminary discussions on the dilation matrix and shift-invariant spaces and the definition of the multiresolution analysis we consider are given in Section 2, and our main results, along with an analysis of the local dimensions of V_0 and V_1 , are given in Section 3.

2. PRELIMINARY DISCUSSION

Suppose that M is a $d \times d$ integer dilation matrix, that is, the entries of M are integers and the moduli of the eigenvalues of M are strictly greater than one. It is known that the order of the quotient group $\mathbb{Z}^d/M\mathbb{Z}^d$ is $|\det M|$ [8, Lemma 2]. Let $\mathbb{T}^d := \mathbb{R}^d/\mathbb{Z}^d$ denote the d -dimensional torus which is identified with $[-1/2, 1/2)^d$. For $x \in \mathbb{R}^d$, let $x \pmod{1}$ denotes the standard representative of $x + \mathbb{Z}^d$ in $[-1/2, 1/2)^d$. Suppose that T is a $d \times d$ invertible matrix with integer entries such that the moduli of the eigenvalues of T are all different from 1. Then the map $\tilde{T} : \mathbb{T}^d \rightarrow \mathbb{T}^d$, defined via $\tilde{T}x := Tx \pmod{1}$, is ergodic [20, Theorem 0.15, Corollary 1.10.1]. We note that $M^t = M^*$, where t and $*$ denote the transpose and the adjoint of a matrix with complex entries, respectively. For notational convenience we let $Q := \mathbb{Z}^d/M\mathbb{Z}^d$ and let $Q^* := \mathbb{Z}^d/M^*\mathbb{Z}^d$. Let $D := D_M : L^2(\mathbb{R}^d) \rightarrow L^2(\mathbb{R}^d)$ denote the unitary dilation operator defined via $Df(x) := |\det M|^{1/2}f(Mx)$. For $y \in \mathbb{R}^d$, $T_y : L^2(\mathbb{R}^d) \rightarrow L^2(\mathbb{R}^d)$ denotes the unitary translation operator such that $T_y f(x) := f(x - y)$. In this paper we adapt the following definition of multiresolution analysis.

DEFINITION 1: $\{V_k\}_{k \in \mathbb{Z}}$ is said to be a frame multiresolution analysis if each V_k is a closed subspace of $L^2(\mathbb{R}^d)$ such that:

- (1) $V_k \subset V_{k+1}, \quad k \in \mathbb{Z};$
- (2) $\bigcup_{k \in \mathbb{Z}} \overline{V_k} = L^2(\mathbb{R}^d), \quad \bigcap_{k \in \mathbb{Z}} V_k = \{0\};$
- (3) $D(V_k) = V_{k+1}, \quad k \in \mathbb{Z};$
- (4) There exists a finite set of scaling functions $\Phi \subset V_0$ such that $\{T_\alpha \varphi : \alpha \in \mathbb{Z}^d, \varphi \in \Phi\}$ is a frame for V_0 .

Various examples and applications of multiresolution analyses are found in the references cited in Section 1.

The following form of the Fourier transform is used throughout this paper: for $f \in L^1(\mathbb{R}^d) \cap L^2(\mathbb{R}^d)$ and $t \in \mathbb{R}^d$ $\widehat{f}(t) := \int_{\mathbb{R}^d} f(x)e^{-2\pi i t \cdot x} dx$, where \cdot denotes the d -dimensional real inner product. It is, of course, extended to be a unitary transform from $L^2(\mathbb{R}^d)$ onto $L^2(\mathbb{R}^d)$ via the Plancherel theorem.

Suppose that $\{f_i : 1 \leq i \leq n\}$ is a finite family of elements of a Hilbert space \mathcal{H} with an inner product $\langle \cdot, \cdot \rangle$. We frequently use the following simple observation: $\dim \text{span}\{f_i : 1 \leq i \leq n\} = \text{rank}(\langle f_i, f_j \rangle)_{1 \leq i, j \leq n}$.

Our analysis uses the theory of (multi-integer) shift-invariant spaces developed in [4, 5, 6, 10, 11, 12, 19] and the references therein. We briefly review the theory and uses the existing results freely. A closed subspace S of $L^2(\mathbb{R}^d)$ is said to be *shift-invariant* if $T_\alpha f \in S$ whenever $f \in S$ and $\alpha \in \mathbb{Z}^d$. If $\Phi \subset L^2(\mathbb{R}^d)$, then $S := \mathcal{S}(\Phi) := \overline{\text{span}}\{T_\alpha \varphi : \alpha \in \mathbb{Z}^d\}$ is a shift-invariant space. In this case, Φ is called a *generator* of S . If Φ is finite, then S is called a *finite shift-invariant space*. We write $S = \mathcal{S}(\varphi)$ instead of $\mathcal{S}(\{\varphi\})$ if $\Phi = \{\varphi\}$ is a singleton. In this case, we call S a *principal shift-invariant space*. It is known that any shift-invariant space has a countable generator. The *length* of a shift-invariant space is defined to be

$$\text{len } S := \inf \{ \#\Phi : S = \mathcal{S}(\Phi), \Phi \subset L^2(\mathbb{R}^d) \},$$

where $\#$ denotes the cardinality. Let $\widehat{f}_{\parallel x}$ be the sequence $(\widehat{f}(x+\alpha))_{\alpha \in \mathbb{Z}^d}$ which is in $\ell^2(\mathbb{Z}^d)$ for almost every $x \in \mathbb{T}^d$. If $A \subset L^2(\mathbb{R}^d), x \in \mathbb{T}^d$, then we let $\widehat{A}_{\parallel x} := \{\widehat{f}_{\parallel x} \in \ell^2(\mathbb{Z}^d) : f \in A\}$, which is called the *fibre* of A at x . It is a subspace of $\ell^2(\mathbb{Z}^d)$ if A is a shift-invariant space. The following theorem is used frequently in our discussion.

THEOREM 2. ([4, 6, 10, 11].) *Let S be a closed, not necessarily shift-invariant, subspace of $L^2(\mathbb{R}^d)$ and Φ a countable subset of $L^2(\mathbb{R}^d)$. Then $S = \mathcal{S}(\Phi)$ if and only if $\widehat{f}_{\parallel x} \in \overline{\text{span}}\{\widehat{\varphi}_{\parallel x} : \varphi \in \Phi\}$ for almost every $x \in \mathbb{T}^d$ and for each $f \in S$.*

The *spectrum* of a shift-invariant space is defined to be $\sigma(S) := \{x \in \mathbb{T}^d : \widehat{S}_{\parallel x} \neq \{0\}\}$. A finite subset Φ of $L^2(\mathbb{R}^d)$ is said to be a *quasi-stable generator* for the shift-invariant space $\mathcal{S}(\Phi)$ if, in addition to the condition that the family of the integer translates of Φ is a frame for $\mathcal{S}(\Phi)$, $\dim \text{span}\{\widehat{\varphi}_{\parallel x} : \varphi \in \Phi\} = \#\Phi$ or 0 for almost every $x \in \mathbb{T}^d$. If Φ is a quasi-stable generator, then there is a convenient ‘local’ formula for the orthogonal projection onto $\mathcal{S}(\Phi)$ [4, 19]. The *stable generator* is a quasi-stable generator such that

the spectrum of the shift-invariant space it generates is \mathbb{T}^d . It turns out that if Φ is a stable generator, then the family of the integer translates of Φ is a Riesz basis for $\mathcal{S}(\Phi)$ [4, 19]. We say that a shift-invariant space S is *quasi-stable*, if $\dim \widehat{S}_{\|x} = n$ or 0 for some non-negative integer n almost everywhere. It is said to be *stable* if $\dim \widehat{S}_{\|x} = n$ almost everywhere. It is known that a quasi-stable/stable shift-invariant space has a quasi-stable/stable generator [4, 19].

We need the following results:

THEOREM 3. ([4].) *For a shift-invariant subspace S of $L^2(\mathbb{R}^d)$*

$$\text{len } S = \text{ess-sup}\{\dim \widehat{S}_{\|x} : x \in \mathbb{T}^d\}.$$

THEOREM 4. ([4].) *Let S_1 be a shift-invariant subspace of a shift-invariant space S and let $S_2 := S \ominus S_1$. Then S_2 is also a shift-invariant subspace of S and $\widehat{S}_{\|x} = \widehat{S}_{1\|x} \oplus \widehat{S}_{2\|x}$ for almost every $x \in \mathbb{T}^d$.*

Suppose that $S = \mathcal{S}(\Phi)$ for a finite set $\Phi := \{\varphi_1, \varphi_2, \dots, \varphi_n\}$. Then the $n \times n$ matrix

$$G(x) := G_\Phi(x) := (\langle \widehat{\varphi}_i_{\|x}, \widehat{\varphi}_j_{\|x} \rangle_{\ell^2(\mathbb{Z}^d)})_{1 \leq i, j \leq n}$$

is the *Gramian* of Φ at $x \in \mathbb{T}^d$. Let $\lambda(x)$, $\lambda^+(x)$ and $\Lambda(x)$ denote the smallest eigenvalue, the smallest non-negative eigenvalue and the largest eigenvalue of $G(x)$, respectively.

THEOREM 5. ([4, 6, 19].) *The family of the integer translates of Φ is a frame for S if and only if there exist positive constants A and B such that $A \leq \lambda^+(x) \leq \Lambda(x) \leq B$ for almost every $x \in \sigma(S)$. It is a Riesz basis for S if and only if $A \leq \lambda(x) \leq \Lambda(x) \leq B$ for almost every $x \in \mathbb{T}^d$. Moreover, A and B are a pair of frame (Riesz) bounds of the frame (Riesz basis), respectively.*

3. FRAME MULTIREOLUTION ANALYSIS

Suppose that $\{V_j\}_{j \in \mathbb{Z}}$ is a frame multiresolution analysis. Then there exists a set of scaling functions $\Phi := \{\varphi_i : 1 \leq i \leq n\} \subset L^2(\mathbb{R}^d)$ such that $\{T_\alpha \varphi_i : \alpha \in \mathbb{Z}^d, 1 \leq i \leq n\}$ is a frame for V_0 . We may assume that the length of V_0 is n . Then $V_0 = \mathcal{S}(\Phi)$ and $V_1 := D(V_0)$. Let

$$G(x) := G_\Phi(x) := (\langle \widehat{\varphi}_i_{\|x}, \widehat{\varphi}_j_{\|x} \rangle_{\ell^2(\mathbb{Z}^d)})_{1 \leq i, j \leq n}$$

be the Gramian of Φ at $x \in \mathbb{T}^d$.

Since $\varphi_i \in V_1$ for each $1 \leq i \leq n$, and since $\{DT_\alpha \varphi_i : \alpha \in \mathbb{Z}^d, 1 \leq i \leq n\}$ is a frame for V_1 , there exist $a_{ij} \in \ell^2(\mathbb{Z}^d)$, $1 \leq i, j \leq n$, such that $\varphi_i = \sum_{j=1}^n \sum_{\alpha \in \mathbb{Z}^d} a_{ij}(\alpha) DT_\alpha \varphi_j$. Hence

$$\begin{aligned} \widehat{\varphi}_i(x) &= \sum_{j=1}^n \sum_{\alpha \in \mathbb{Z}^d} a_{ij}(\alpha) |\det M|^{-1/2} e^{-2\pi i \alpha \cdot (M^{*-1}x)} \widehat{\varphi}_j(M^{*-1}x) \\ &= \sum_{j=1}^n m_{ij}(M^{*-1}x) \widehat{\varphi}_j(M^{*-1}x), \end{aligned}$$

where

$$m_{ij}(x) := \sum_{\alpha \in \mathbb{Z}^d} |\det M|^{-1/2} a_{ij}(\alpha) e^{-2\pi i \alpha \cdot x} \in L^2(\mathbb{T}^d).$$

For $x \in \mathbb{T}^d$, let

$$m(x) := (m_{ij}(x))_{1 \leq i, j \leq n}$$

and

$$\widehat{\Phi}(x) := (\widehat{\varphi}_1(x), \widehat{\varphi}_2(x), \dots, \widehat{\varphi}_n(x))^t.$$

Then

$$(1) \quad \widehat{\Phi}(x) = m(M^{*-1}x) \widehat{\Phi}(M^{*-1}x).$$

This m , called a *mask* of the multiresolution analysis, may not be unique since $\{DT_\alpha \varphi_i : \alpha \in \mathbb{Z}^d, 1 \leq i \leq n\}$ is only assumed to be a frame, not necessarily a Riesz basis. Note that $DT_{My} = T_y D$ for $y \in \mathbb{R}^d$. Since each $\gamma \in \mathbb{Z}^d$ can be written uniquely as $\gamma = M\alpha + \beta$ for some $\alpha \in \mathbb{Z}^d$ and $\beta \in Q$,

$$\{DT_\gamma \varphi_i : \gamma \in \mathbb{Z}^d, 1 \leq i \leq n\} = \{T_\alpha DT_\beta \varphi_i : \alpha \in \mathbb{Z}^d, \beta \in Q, 1 \leq i \leq n\}.$$

Hence $V_1 = \mathcal{S}(\Pi)$, where

$$(2) \quad \Pi := \{DT_\beta \varphi_i : \beta \in Q, 1 \leq i \leq n\}.$$

This implies that the length of the shift-invariant space V_1 is less than or equal to $n|\det M|$. Since V_0 is a shift-invariant subspace of V_1 , $\text{len } V_1 \geq \text{len } V_0 = n$. There is an example of a frame multiresolution analysis in which the length of V_1 is that of V_0 . See Example 6 below. Let W_0 denote $V_1 \ominus V_0$, and let $W_j := D^j(W_0), j \in \mathbb{Z}$. Then Definition 1 implies that $L^2(\mathbb{R}^d) = \bigoplus_{j \in \mathbb{Z}} W_j$. W_0 is a shift-invariant space by Theorem 4.

Since W_0 is a subspace of V_1 , the length of W_0 is also less than or equal to $n|\det M|$. It cannot be zero. If it were zero, then $W_0 = \{0\}$; hence $V_0 = V_1$. Definition 1 implies that $L^2(\mathbb{R}^d) = V_0 = \mathcal{S}(\Phi)$. This contradicts a result in [7] which states roughly that there are no frames of $L^2(\mathbb{R}^d)$ consisting of the translates of a finite number of functions. Since W_0 is a finite shift-invariant space, there is a finite set Ψ , called a *wavelet set*, such that $W_0 = \mathcal{S}(\Psi)$. We may assume that the integer translates of the elements of Ψ form a frame for W_0 [5, 19]. Then, obviously, $\{D^j T_\alpha \psi : j \in \mathbb{Z}, \alpha \in \mathbb{Z}^d, \psi \in \Psi\}$ is a frame for $L^2(\mathbb{R}^d)$. Since the minimal cardinality of such Ψ is $\text{len } W_0$, the (minimal) number of the elements of a wavelet set is $\text{len } W_0$.

Note that, for $\beta \in \mathbb{Z}^d$ and $x \in \mathbb{T}^d$,

$$\begin{aligned} (DT_\beta \varphi_i)^\wedge(x) &= |\det M|^{-1/2} e^{-2\pi i \beta \cdot (M^{*-1}x)} \widehat{\varphi}_i(M^{*-1}x), \\ (DT_\beta \varphi_i)^\wedge|_x &= |\det M|^{-1/2} e^{-2\pi i \beta \cdot (M^{*-1}x)} \left(e^{-2\pi i \beta \cdot (M^{*-1}\alpha)} \widehat{\varphi}_i(M^{*-1}(x + \alpha)) \right)_{\alpha \in \mathbb{Z}^d}. \end{aligned}$$

Hence, for almost every $x \in \mathbb{T}^d$,

$$\begin{aligned}
 \widehat{V}_{1\|x} &= \text{span} \left\{ \left(e^{-2\pi i \beta \cdot (M^{*-1}\alpha)} \widehat{\varphi}_i(M^{*-1}(x + \alpha)) \right)_{\alpha \in \mathbb{Z}^d} : \beta \in Q, 1 \leq i \leq n \right\}, \\
 (3) \quad \widehat{V}_{0\|x} &= \text{span} \left\{ \left(\widehat{\varphi}_i(x + \alpha) \right)_{\alpha \in \mathbb{Z}^d} : 1 \leq i \leq n \right\} \\
 &= \text{span} \left\{ \sum_{j=1}^n \left(m_{ij}(M^{*-1}(x + \alpha)) \widehat{\varphi}_j(M^{*-1}(x + \alpha)) \right)_{\alpha \in \mathbb{Z}^d} : 1 \leq i \leq n \right\}.
 \end{aligned}$$

For $\beta^* \in Q^*$ define $P_{\beta^*} : \ell^2(\mathbb{Z}^d) \rightarrow \ell^2(\mathbb{Z}^d)$ via

$$(P_{\beta^*} a)(\alpha) := \begin{cases} a(\alpha), & \text{if } \alpha \in \beta^* + M^* \mathbb{Z}^d, \\ 0, & \text{otherwise.} \end{cases}$$

Then $\ell^2(\mathbb{Z}^d) = \bigoplus_{\beta^* \in Q^*} P_{\beta^*}(\ell^2(\mathbb{Z}^d))$. Define, for $x \in \mathbb{T}^d, 1 \leq i \leq n, \beta^* \in Q^*$,

$$a_{x,i,\beta^*} := P_{\beta^*} \left(\left(\widehat{\varphi}_i(M^{*-1}(x + \alpha)) \right)_{\alpha \in \mathbb{Z}^d} \right).$$

Notice that a_{x,i,β^*} is the ‘up-sampled’ version of $\widehat{\varphi}_i\|_{M^{*-1}(x+\beta^*)}$, that is,

$$(4) \quad a_{x,i,\beta^*}(\beta^* + M^* \alpha) = \widehat{\varphi}_i\|_{M^{*-1}(x+\beta^*)}(\alpha), \quad \alpha \in \mathbb{Z}^d,$$

$$(5) \quad a_{x,i,\beta^*}(\gamma^*) = 0, \quad \gamma^* \notin \beta^* + M^* \mathbb{Z}^d.$$

Therefore

$$(6) \quad \|a_{x,i,\beta^*}\|_{\ell^2(\mathbb{Z})} = \|\widehat{\varphi}_i\|_{M^{*-1}(x+\beta^*)}\|_{\ell^2(\mathbb{Z})}.$$

We also have

$$\left(e^{-2\pi i \beta \cdot (M^{*-1}\alpha)} \widehat{\varphi}_i(M^{*-1}(x + \alpha)) \right)_{\alpha \in \mathbb{Z}} = \sum_{\gamma^* \in Q^*} e^{-2\pi i \beta \cdot (M^{*-1}\gamma^*)} a_{x,i,\gamma^*}.$$

Let $b_{x,i,\beta}$ be the right-hand side of the above equation. Then, for a fixed $x \in \mathbb{T}^d, 1, \leq i \leq n$, we have the following matrix relation:

$$(b_{x,i,\beta})_{\beta \in Q}^t = (e^{-2\pi i \beta \cdot (M^{*-1}\gamma^*)})_{\beta \in Q, \gamma^* \in Q^*} (a_{x,i,\gamma^*})_{\gamma^* \in Q^*}^t.$$

Recall that, for any $\beta \in \mathbb{Z}^d$, the map $\gamma^* \rightarrow e^{-2\pi i \beta \cdot (M^{*-1}\gamma^*)}$ is a character of the discrete group G^* . Hence the sum $\sum_{\gamma^* \in Q^*} e^{-2\pi i \beta \cdot (M^{*-1}\gamma^*)}$ is the order of Q^* , which is $|\det M|$, if the map is the identity character, and the sum is 0 if the map is not the identity character since the only discrete multiplicative subgroups of \mathbb{T} are the groups of the p -th roots of unity ([20, Theorem 0.14]). Using this observation, it is easy to see that

$$(e^{-2\pi i \beta \cdot (M^{*-1}\gamma^*)})_{\beta \in Q, \gamma^* \in Q^*} (e^{2\pi i (M^{*-1}\delta^*) \cdot \eta})_{\delta^* \in Q^*, \eta \in Q} = |\det M| I_{|\det M|}.$$

In particular, for each $1 \leq i \leq n$ and $x \in \mathbb{T}^d$, $\text{span}\{b_{x,i,\beta} : \beta \in Q\} = \text{span}\{a_{x,i,\gamma^*} : \gamma^* \in Q^*\}$. This shows that:

$$(7) \quad \widehat{V}_{1\|x} = \text{span}\{a_{x,i,\gamma^*} : 1 \leq i \leq n, \gamma^* \in Q^*\}.$$

The 1-periodicity of the mask m and (4) imply that:

$$\widehat{V}_{0\|x} = \text{span}\left\{ \sum_{j=1}^n \sum_{\alpha^* \in Q^*} m_{ij}(M^{*-1}(x + \alpha^*)) a_{x,j,\alpha^*} : 1 \leq i \leq n \right\}.$$

Note that, for almost every $x \in \mathbb{T}^d$, $\dim \widehat{V}_{1\|x}$ equals the rank of the following $n|\det M| \times n|\det M|$ matrix

$$\left(\langle a_{x,i,\alpha^*}, a_{x,j,\beta^*} \rangle_{\mathbb{C}^{2^d}} \right)_{(i,\alpha^*), (j,\beta^*)}.$$

If we order the indices suitably, then (4) and (5) imply that the matrix is the block diagonal matrix

$$\text{diag}\left(G(M^{*-1}(x + \alpha^*)) \right)_{\alpha^* \in Q^*}.$$

Recall that $\text{rank } G(M^{*-1}(x + \alpha^*)) = \dim \widehat{V}_{0\|M^{*-1}(x+\alpha^*)}$ for each $\alpha^* \in Q^*$. Hence, for almost every $x \in \mathbb{T}^d$,

$$(8) \quad \dim \widehat{V}_{1\|x} = \sum_{\alpha^* \in Q^*} \text{rank } G(M^{*-1}(x + \alpha^*)) = \sum_{\alpha^* \in Q^*} \dim \widehat{V}_{0\|M^{*-1}(x+\alpha^*)}.$$

A direct calculation shows that

$$G(x) = \sum_{\alpha^* \in Q^*} m(M^{*-1}(x + \alpha^*)) G(M^{*-1}(x + \alpha^*)) m(M^{*-1}(x + \alpha^*))^*.$$

Hence, for almost every $x \in \mathbb{T}^d$,

$$(9) \quad \dim \widehat{V}_{0\|x} = \text{rank} \sum_{\alpha^* \in Q^*} m(M^{*-1}(x + \alpha^*)) G(M^{*-1}(x + \alpha^*)) m(M^{*-1}(x + \alpha^*))^*.$$

EXAMPLE 6. Let us first consider a dyadic univariate frame multiresolution analysis with a single scaling function, that is, $d = n = 1$ and $Q = \mathbb{Z}/2\mathbb{Z} = \{0, 1\}$. Therefore $Df(x) = 2^{1/2}f(2x)$. Let V_0 be a Paley–Wiener space such that $\{f \in L^2(\mathbb{R}) : \text{supp}(f) \subset [-a, a]\}$ with $0 < a < 1/4$, and let $V_j := D^j(V_0)$, $j \in \mathbb{Z}$. Then it is easy to see that $\{V_j\}_{j \in \mathbb{Z}}$ is a frame multiresolution analysis ([14]). Obviously, $V_0 = \mathcal{S}(\check{\chi}_{[-a,a]})$, where $\check{\chi}$ denotes the inverse Fourier transform. Hence, $V_1 = \mathcal{S}(\check{\chi}_{[-2a,2a]})$ is a shift-invariant space of length 1. This can be proved by using (8). Note that $G(x) = \chi_{[-a,a]+z}(x)$ for $x \in \mathbb{T}$. Hence, $\widehat{V}_{1\|x} = \chi_{[-a,a]+z}(x/2) + \chi_{[-a,a]+z}(x/2 + 1/2)$ for $x \in \mathbb{T}$. Hence $\dim \widehat{V}_{1\|x} = 1$ for $x \in [-2a, 2a]$, and $\dim \widehat{V}_{1\|x} = 0$ for $x \in \mathbb{T} \setminus [-2a, 2a]$. Therefore $\text{len } V_1 = 1$ by Theorem 3. Recall that $\text{len } V_1$ is less than or equal to $n2^d = 2$. In this example, the length of V_1 is

that of V_0 . Notice, however, that V_0 is a strict subspace of V_1 . It is now easy to see that $\text{len } V_2 = 2$.

The above example can be directly extended to the case where $d > 1$, $n = 1$ and $M = 2I_d$. Then $Q = Q^* = \{(\varepsilon_1, \varepsilon_2, \dots, \varepsilon_d) : \varepsilon_i = 0 \text{ or } 1\}$. For the sake of simplicity, define $\widehat{\varphi} := \chi_{(-1/4, 1/4)^d}$, $V_0^d := \mathcal{S}(\varphi)$ and $V_j^d := D^j(V_0^d)$. Then $\{V_j^d\}_{j \in \mathbb{Z}}$ is a frame multiresolution analysis. We show that $\text{len } V_1^d = 1$. (8) implies that, for almost every $x \in \mathbb{T}^d = [-1/2, 1/2]^d$, $\dim \widehat{V}_1^d|_x$ is the number of the sets $2\sigma(V_0^d) - \beta^* + 2\mathbb{Z}^d$, $\beta^* \in Q^*$, to which x belongs. A direct calculation shows that x belongs only to $2\sigma(V_0^d) + 2\mathbb{Z}^d$ since $\sigma(V_0^d) = (-1/4, 1/4)^d$. Therefore $\text{len } V_1^d = 1$ by Theorem 3. Since V_0^d is a strict subset of V_1^d , $\text{len } W_0 = 1$.

Suppose, temporarily, that $\{T_\alpha \varphi_i : \alpha \in \mathbb{Z}, 1 \leq i \leq n\}$ is a Riesz basis of V_0 . Then $\text{rank } G(x) = n$ for almost every $x \in \mathbb{T}^d$ [4]. Hence $\dim \widehat{V}_1|_x = n|\det M|$ for almost every $x \in \mathbb{T}^d$. Since $\widehat{V}_1|_x = \widehat{V}_0|_x \oplus \widehat{W}_0|_x$ almost everywhere by Theorem 4, $\dim \widehat{W}_0|_x = n(|\det M| - 1)$ almost everywhere. Therefore $\text{len } W_0 = n(|\det M| - 1)$ by Theorem 3. Benedetto and Li [1] introduced the following concept: a frame multiresolution analysis admit a *standard (frame) wavelet set* if $\text{len } W_0 \leq n(|\det M| - 1)$. The characterisations of dyadic frame multiresolution analyses admitting standard wavelet sets were given in [2, 14], independently, for $d = n = 1$, and in [16] for $d > 1$ and $n = 1$. Combining (8) and (9) with Theorems 3 and 4 yield the following general result on the admittance of a standard wavelet set.

THEOREM 7. *The frame multiresolution analysis $\{V_j\}_{j \in \mathbb{Z}}$ admits a standard wavelet set if and only if, for almost every $x \in \mathbb{T}^d$,*

$$\begin{aligned}
 & \sum_{\alpha^* \in Q^*} \text{rank } G(M^{*-1}(x + \alpha^*)) \\
 & \quad - \text{rank} \sum_{\alpha^* \in Q^*} m(M^{*-1}(x + \alpha^*)) G(M^{*-1}(x + \alpha^*)) m(M^{*-1}(x + \alpha^*))^* \\
 (10) \quad & \leq n(|\det M| - 1).
 \end{aligned}$$

We now recover the previous results on the admittance of a standard wavelet set [2, 14, 16]. Suppose that $n = 1$ and $M = 2I_d$. Then $Q = Q^* = \mathbb{Z}^d/2\mathbb{Z}^d = \{(\varepsilon_1, \varepsilon_2, \dots, \varepsilon_d) : \varepsilon_i = 0 \text{ or } 1\}$, $|\det M| = 2^d$, $\Phi = \{\varphi\} \subset L^2(\mathbb{R}^d)$, $G(x) = \|\widehat{\varphi}\|_{\ell^2(\mathbb{Z}^d)}^2$, and $m(x)$ is also a scalar. (10) becomes

$$\sum_{\alpha \in Q} \text{rank} \left\| \widehat{\varphi}|_{(x+\alpha)/2} \right\|_{\ell^2(\mathbb{Z}^d)}^2 - \text{rank} \sum_{\alpha \in Q} \left| m\left(\frac{x+\alpha}{2}\right) \right|^2 \left\| \widehat{\varphi}|_{(x+\alpha)/2} \right\|_{\ell^2(\mathbb{Z}^d)}^2 \leq 2^d - 1,$$

where the rank of a scalar is the rank of the 1×1 matrix with the scalar entry. Notice that the left-hand side of the above inequality is less than or equal to 2^d . Hence the frame multiresolution analysis admits a standard wavelet set if and only if the left-hand side is

not 2^d almost everywhere. The condition, now, is equivalent to the condition that E is of zero Lebesgue measure with

$$E := \left\{ x \in \mathbb{T}^d : \widehat{\varphi}_{\|(x+\alpha)/2} \neq 0 \text{ for each } \alpha \in Q, \sum_{\alpha \in Q} \left| m\left(\frac{x+\alpha}{2}\right) \right|^2 = 0 \right\}.$$

This recovers Theorem 5 of [16] (see also [2, 14] for the univariate case).

We now observe a simple relationship between the spectrums of V_0 and V_1 .

LEMMA 8. $\sigma(V_1) = M^* \sigma(V_0) \pmod{1}$.

PROOF: Suppose that $x \in \sigma(V_0)$. Then $\widehat{\varphi}_{i\|x} \neq 0$ for some i by (3). There exist $y \in \mathbb{T}^d, \alpha^* \in \mathbb{Z}^d$ such that $M^*x = y + \alpha^*$. Now $\alpha^* = \beta^* + M^*\gamma^*$ for some $\beta^* \in Q^*$ and $\gamma^* \in \mathbb{Z}^d$. (6) implies that

$$\|a_{y,i,\beta^*}\|_{\ell^2(\mathbb{Z}^d)} = \|\widehat{\varphi}_{i\|M^{*-1}(M^*x - \beta^* - M^*\gamma^* + \beta^*)}\|_{\ell^2(\mathbb{Z})} = \|\widehat{\varphi}_{i\|x - \gamma^*}\|_{\ell^2} \neq 0.$$

Therefore, $y = M^*x - \alpha^* \in \sigma(V_1)$ by (7). This shows that $M^*\sigma(V_0) \subset \sigma(V_1)$. Suppose, on the other hand, that $x \in \sigma(V_1)$. Then $a_{x,i,\beta^*} \neq 0$ for some $1 \leq i \leq n$ and $\beta^* \in Q^*$ by (7). Then $\widehat{\varphi}_{i\|M^{*-1}(x+\beta^*)} \neq 0$ by (6). Hence $M^{*-1}(x + \beta^*) \pmod{1} \in \sigma(V_0)$ by (3). This shows that $\sigma(V_1) \subset M^*\sigma(V_0) \pmod{1}$. \square

Recall that a frame is a Riesz basis if it is, in a certain sense, ‘globally’ irredundant, that is, irredundant in the norm topology [9, 13]. Suppose that Φ is a quasi-stable generating set for V_0 . Then the family of the integer translates of Φ , which is a frame for V_0 , is ‘locally’, that is, fibre-wise, irredundant. We now show that: if Φ and Π are quasi-stable generating sets for V_0 and V_1 , respectively, then the integer translates are ‘globally’ redundant. This result improves Theorem 3.9 [15] in the sense that we do not presuppose that $\sigma(V_0) = \sigma(V_1)$. More precisely, we show:

THEOREM 9. *Suppose that $\{V_j\}_{j \in \mathbb{Z}}$ is a frame multiresolution analysis. If V_0 and V_1 are both quasi-stable, and if $\text{len } V_1 = |\det M| \text{len } V_0$, then they are actually stable. In particular, $\sigma(V_0) = \sigma(V_1) = \mathbb{T}^d$.*

PROOF: We may assume that $V_0 = \mathcal{S}(\Phi)$ with $\Phi := \{\varphi_1, \varphi_2, \dots, \varphi_n\}$ a quasi-stable generator for V_0 . Then $V_1 = \mathcal{S}(\Pi)$ with Π as in (2). Since $\#\Pi = \text{len } V_1$, Π is a generator for V_1 with minimal length. Hence Π is actually a quasi-stable generator for V_1 [5, Theorem 3.12]. The length condition on V_1 and (8) show the following fact: If $x \in \sigma(V_1)$, then, for each $\alpha^* \in Q^*$, there exists $\delta_{x,\alpha^*} \in \mathbb{Z}^d$ such that $M^{*-1}(x + \alpha^*) + \delta_{x,\alpha^*} \in \sigma(V_0)$. It is obvious that for a fixed set of coset representatives Q^* the set of ‘folding’ multi-integers $\{\delta_{x,\alpha^*} : x \in \sigma(V_1), \alpha^* \in Q^*\}$ is a finite set. This implies that $\sigma(V_0)$ contains a measurable subset of Lebesgue measure $|M^{*-1}(\sigma(V_1) + \alpha^*)| = |M^{*-1}(\sigma(V_1))|$. We show that these subsets of $\sigma(V_0)$ do not overlap. Suppose that $M^{*-1}(x + \alpha^*) + \gamma = M^{*-1}(y + \beta^*) + \delta \in \mathbb{T}^d$ for $x, y \in \sigma(V_1), \alpha^*, \beta^* \in Q^*, \gamma, \delta \in \mathbb{Z}^d$. Then $x - y = \beta^* - \alpha^* + M^*(\delta - \gamma)$. Since the right-hand side is an integer and since $x, y \in \mathbb{T}^d = [-1/2, 1/2]^d, x - y = 0$. Hence $\alpha^* = \beta^*$ and

$\gamma = \delta$. Therefore $\sigma(V_0)$ contains $\#Q^* = |\det M|$ number of subsets of Lebesgue measure $|M^{*-1}(\sigma(V_1))|$. This shows that $|\sigma(V_0)| \geq |\sigma(V_1)|$. Since $V_0 \subset V_1$, $\sigma(V_0) \subset \sigma(V_1)$. Consequently, $\sigma(V_0) = \sigma(V_1)$. Lemma 8 implies that $\sigma(V_0) = M^*\sigma(V_0) \pmod{1}$. The ergodicity of the map $x \in \mathbb{T}^d \rightarrow M^*x \pmod{1}$ in \mathbb{T}^d implies that $\sigma(V_0)$ is either \mathbb{T}^d or empty. Since it is not empty, it is \mathbb{T}^d . \square

The length condition in Theorem 9 is indispensable by Example 6.

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