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A SIMPLE PROOF OF INTEGRATION BY PARTS FOR THE PERRON INTEGRAL

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P. S. BULLEN

ABSTRACT. This note presents a very simple proof for the integration by parts formula for the Perron integral.

1. Introduction. It is a remarkable fact that the proof of such an elementary result as the integration by parts formula for an integral with such a simple definition was not given until fifty years after the integral was introduced. To this day the proofs are far from simple. The most elegant, due to Mařík [7], requires a non-standard, but reasonable, form for the definition of the integral; the most direct, that of Gordon and Lasher, [5], needs a special treatment for the case when 'the function to be differentiated' is not continuous; the earliest, McShane's proof, ([8], [9]), is cumbersome in its use of sixteen major and minor functions. The present note combines McShane's approach with some preliminary simplifications to give a short direct proof. A detailed history of this theorem has been given in Bullen [2].

2. The integral and some simple properties.

DEFINITION 1. If $f: [a, b] \rightarrow \overline{R}$ then f is Perron integrable (on [a, b]), $f \in P(a, b)$ or just $f \in P$ if there is no ambiguity, iff:

- (I) $\exists m, M: [a, b] \rightarrow R$ such that
- (a) m, M are continuous;
- (b) m(a) = M(a) = 0;
- (c) $\ell DM \ge f \ge uDm$, n.e.;
- (d) $\ell DM > -\infty$, $uDm < \infty$ n.e.;

(ℓD denotes the lower derivative, uD the upper derivative; n.e. means nearly everywhere, that is, except on a countable set);

(II) inf $M(b) = \sup m(b)$, where the inf is over all M in (I), and the sup over all m.

Then the common value in (I) is written $P - \int_a^b f$, the Perron integral of f over [a, b].

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LEMMA 2. (a) If M, m are as in (I) then M - m increasing and non-negative. (b) If $f \in P(a, b)$ then $f \in P(a, x)$, $a \le x \le b$, and if $F(x) = P - \int_a^x f$, $a \le x \le b$, then M - F and F - m are increasing and non-negative; (M, m as in (I)). (c) $f \in P(a, b)$ iff $\forall \epsilon > 0 \exists M$, m as in (I) such that $0 \le M(b) - m(b) < \epsilon$.

The proof of Lemma 2 is almost immediate, but see, for instance Bruckner ([1], p. 174).

The functions M, m of (I) are called respectively major and minor functions of f. If in Definition 1 we had used unilateral derivatives we could have defined left, and right, major and minor functions of f. If now M a major function of f of any type, and m a minor function of f of any type, Lemma 2(a) still holds; the proof when M and m are of opposite types, one left and the other right, is a little deeper (see McShane [9], p. 313).

The following generalisation of Lemma 2(c) is due to McShane, ([8], [9]); but the fact that it is elementary to prove is due to Ridder [10].

LEMMA 3. $f \in P(a, b)$ iff $\forall \epsilon > 0 \exists \mu_1, \mu_2, \mu_3, \mu_4$ being left major, right major, left minor, right minor functions of f respectively, such that $|\mu_i(b) - \mu_j(b)| < \epsilon, 1 \le i$, $j \le 4$; and then

$$P - \int_{a}^{b} f = \inf \{t; t = \mu_{i}(b) \ i = 1 \text{ or } 2\}.$$
$$= \sup \{t; t = \mu_{i}(b), i = 3 \text{ or } 4\}.$$

3. The main result.

THEOREM 4. If $f \in P(a, b)$, $F = P - \int f$, G of bounded variation then $fG \in P(a, b)$ and

(1)
$$P - \int_{a}^{b} fG = F(b)G(b) - F(a)G(a) - \int_{a}^{b} FdG,$$

(The right-hand side of (1) is to be interpreted as follows:

$$G(a) = G(a+); \quad G(b) = G(b-); \quad \int_{a}^{b} F dG = \lim_{\alpha \to a^{+}, \beta \to b^{-}} \int_{a}^{b} F dG$$

the integrals being Riemann-Stieltjes' integrals.)

We remark that Theorem 4 is trivial if G is constant; further if Theorem 4 holds for G_1 and G_2 then it holds for all $\lambda G_1 + \mu G_2$, λ , $\mu \in R$. Since, if G is of bounded variation, $G = G_1 - G_2$ where G_1 and G_2 are bounded increasing functions, to prove Theorem 4 it is sufficient to prove,

LEMMA 5. If $f \in P(a, b)$, $F = P - \int f$, G a bounded increasing function, G(a) = 0, then $f \in G(a, b)$ and

(2)
$$P - \int_a^b fG = F(b)G(b) - \int_a^b FdG.$$

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PROOF. Let M be a major function of f, (as in (I)), and define

$$R(x) = M(x)G(x) - \int_a^x M dG, \quad a \le x \le b$$

If then x and x + h are in [a, b], there is, by the mean value theorem for the Riemann-Stieljes integral, a y between x and x + h such that

(3)
$$R(x+h) - R(x) = \{M(x+h) - M(y)\}\{G(x+h) - G(x)\} + G(x)\{M(x+h) - M(x)\}$$

hence, since M is continuous, so is R.

From (3) we get on rewriting that

(4)
$$\frac{R(x+h) - R(x)}{h} = G(x+h) \frac{M(x+h) - M(x)}{h} - \frac{G(x+h) - G(x)}{h} \{M(y) - M(x)\}.$$

Since $G \ge 0$, if x is a point at which G'(x) is finite, and so a.e.,

$$\ell DR(x) = G(x)\ell DM(x);$$

hence by (c) of Definition 1

$$\ell DR \geq fG$$
 a.e.

Finally, (4) can be rewritten as

$$\frac{R(x+h) - R(x)}{h} = G(x+h) \left\{ \frac{M(x+h) - (x)}{h} \right\} - \left\{ G(x+h) - G(x) \right\} \left\{ \frac{M(y) - M(x)}{y - x} \right\} \left(\frac{y - x}{h} \right);$$

if then h < 0, and x is a point at which $\ell DM(x) > -\infty$, and so n.e.,

$$\ell D_{-}R(x) > -\infty;$$

(here ℓD_{-} denotes the left lower derivative); hence

$$\ell D_{-}R > -\infty$$
, n.e.

Since obviously R(a) = 0, we have that R in a left major function of fG.

In a similar way, if m is a minor function of f, then

$$r(x) = m(x)G(x) - \int_a^x m dG, \quad a \le x \le b,$$

is a left minor function of fG.

A consideration of the above discussion shows that if G had been a non-positive increasing function, rather than a non-negative one, then R would have been a right

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minor function of fG; similarly r would have been a right major function. If then $\gamma = \sup_{a \le x \le b} G(x)$, $G^*(x) = G(x) - \gamma$ and

$$R^*(x) = M(x)G^*(x) - \int_a^x M dG$$

we have that R^* is a right minor function of fG^* , and so

$$s(x) = \gamma m(x) + R^*(x)$$

is a right minor function of fG: similarly

$$S(x) = \gamma M(x) + r^*(x),$$

where

$$r^*(x) = mG^*(x) - \int_a^x mdG, \quad a \le x \le b,$$

is a right major function of fG.

If then $\epsilon > 0$ and M, m are chosen so that $M(b) - m(b) < \epsilon$, as is possible by Lemma 2(c), then the tetrad R, S, r, s can be taken as the μ_i , $1 \le i \le 4$, of Lemma 3, and so $fG\epsilon P(a, b)$; further, by Lemma 3, $P - \int_a^h f = \inf R(b)$, the inf being over all R defined above; this gives (2) and completes the proof of Lemma 5.

5. In [3] an integration by parts theorem for the Burkill approximately continuous integral, the P_{ap}^* -integral, was promised; this result has been recently proved by Chakrabarti and Mukhopadhyay [4].

THEOREM 6. Let $f \in P_{ap}^*(a, b)$, $F = P_{ap}^* - \int f$, g of bounded variation, $G = \int g$; if then $F \in P(a, b)$ it follows that $f G \in P_{ap}^*$ and

(5)
$$P_{ap}^{*}\int_{a}^{b}fG = F(b)G(b) - F(a)G(a) - P - \int_{a}^{b}Fg.$$

For this result the difficulties that occur in trying to prove Theorem 4 do not occur; in particular a proof along the lines given above requires no appeal to Lemma 3. This is because G' = g n.e. and so the analogously defined R, see the proof of Lemma 5 above, is a P_{ap}^* -major function, not, as in Lemma 5 merely a left major function. The proof following the lines of that of Theorem 4, but now much simpler, is different to that given in [4]. A further proof can be given using the descriptive definition of the P_{ap}^* -integral (see [2]). The right-hand side of (5) is, as a function of b, $[ACG_{ap}^*]$; its a.e. existing approximate derivative is the integrand on the left-hand side of (5).

The condition $F \in P(a, b)$ ensures the existence of the right-hand side of (5), by Theorem 4; and the need for such a hypothesis is demonstrated in [4].

6. Professor K. Garg has brought to my attention that the above proof of Theorem 4 will provide an integration by parts theorem for two generalisations of the P-integral given by Ionescu-Tulcea [6], and Ridder [10]. If in Definition 1 right lower

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derivates are used in the definition of the major functions M, but left upper derivates in the definition of the minor functions m, an integral more general than the P-integral is defined, the P_{\pm} -integral say. In an analogous way another generalisation the P_{\pm} -integral can be defined. While generalizing the P-integral they are not themselves related by one being more general than the other; both can be given descriptive definitions (see [6], [10]). Clearly the proof of Theorem 4 will also give a proof of a Theorem 4_{\pm} , a theorem in which the hypothesis " $f \in P$, $F = P - \int f$ " of Theorem 4 is replaced by " $f \in P_{\pm}$, $F = P_{\pm} - \int f$ " and the conclusion is $f G \in P_{\pm}$, with the integral on the left-hand side of (1) being $P_{\pm} - \int_{a}^{b} f G$; a similar Theorem 4_{\pm} can be obtained in the obvious way.

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UNIVERSITY OF BRITISH COLUMBIA VANCOUVER, B.C.

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