# THREE NON-TRIVIAL SOLUTIONS FOR NOT NECESSARILY COERCIVE $p$-LAPLACIAN EQUATIONS 

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(Received 11 June 2008)


#### Abstract

We consider the existence of three non-trivial smooth solutions for nonlinear elliptic problems driven by the $p$-Laplacian. Using variational arguments, coupled with the method of upper and lower solutions, critical groups and suitable truncation techniques, we produce three non-trivial smooth solutions, two of which have constant sign. The hypotheses incorporate both coercive and non-coercive problems in our framework of analysis.


Keywords: non-trivial solutions; truncations; upper and lower solutions; p-Laplacian; nonlinear regularity; critical groups

2000 Mathematics subject classification: Primary 35J65; 35J70

## 1. Introduction

Let $Z \subseteq \mathbb{R}^{N}$ be a bounded domain with a $C^{2}$-boundary $\partial Z$. We study here the existence of multiple non-trivial smooth solutions for the following nonlinear Dirichlet problem:

$$
\left.\begin{array}{rl}
-\Delta_{p} x(z) & =m(z)|x(z)|^{r-2} x(z)+f(z, x(z)) \quad \text { a.e. on } Z  \tag{1.1}\\
\left.x\right|_{\partial Z} & =0 .
\end{array}\right\}
$$

Here $1<r<p<\infty$ and $\Delta_{p} x=\operatorname{div}\left(\|D x\|^{p-2} D x\right)$, the $p$-Laplacian differential operator. Our goal is to prove a 'three-solutions theorem' for problem (1.1). Recently, such theorems were proved by Dancer and Perera [3], Liu [8], Liu and Liu [9], Papageorgiou and Papageorgiou $[\mathbf{1 0}]$ and Zhang and co-workers $[\mathbf{1 2}, \mathbf{1 3}]$. In all these works the Euler functional of the problem is coercive. In addition, in $[\mathbf{3}, \mathbf{1 2}, \mathbf{1 3}]$, the asymptotic limits

$$
a_{ \pm}=\lim _{x \rightarrow 0 \pm} \frac{f(z, x)}{|x|^{p-2} x}
$$

play an important role. Additional multiplicity results (two solutions) for coercive problems, using critical groups, can be found in [4]. Here the Euler functional need not be
coercive. In fact, the hypotheses incorporate both coercive and non-coercive problems in our framework of analysis, since the conditions that we impose on the nonlinearity $f$ concerning its behaviour near infinity are minimal. More precisely, we require only that $x \rightarrow f(z, x)$ has subcritical growth. Also, here we do not assume that the limits $a_{ \pm}=\lim _{x \rightarrow 0 \pm} f(z, x) /\left(|x|^{p-2} x\right)$ exist.

## 2. Preliminaries and hypotheses

In our analysis of problem (1.1), we shall use the Sobolev space $W_{0}^{1, p}(Z)$ and the subspace

$$
C_{0}^{1}(\bar{Z})=\left\{x \in C^{1}(\bar{Z}):\left.x\right|_{\partial Z}=0\right\}
$$

Both $W_{0}^{1, p}(Z)$ and $C_{0}^{1}(\bar{Z})$ are ordered Banach spaces, with order cones given, respectively, by

$$
W_{+}=\left\{x \in W_{0}^{1, p}(Z): x(z) \geqslant 0 \text { a.e. on } Z\right\}
$$

and

$$
C_{+}=\left\{x \in C_{0}^{1}(\bar{Z}): x(z) \geqslant 0 \text { for all } z \in Z\right\}
$$

In fact, $C_{+}$has non-empty interior, given by

$$
\text { Int } C_{+}=\left\{x \in C_{+}: x(z)>0 \text { for all } z \in Z, \frac{\partial x}{\partial n}(z)<0 \text { for all } z \in \partial Z\right\}
$$

Here we denote by $n(z)$ the outward unit normal at $z \in \partial Z$. In an ordered Banach space $X$ with order cone $K$, we write $u \leqslant v$ if and only if $v-u \in K$, and $u<v$ if and only if $u \leqslant v$ and $u \neq v$. Also, if $u \leqslant v$, then we define

$$
[u, v]=\left\{y \in W_{0}^{1, p}(Z): u(z) \leqslant y(z) \leqslant v(z) \text { a.e. on } Z\right\}
$$

Henceforth, by $A: W_{0}^{1, p}(Z) \rightarrow W^{-1, p^{\prime}}(Z)$, where $1 / p+1 / p^{\prime}=1$, we denote the nonlinear operator corresponding to $-\Delta_{p}$ and defined by

$$
\langle A(x), y\rangle=\int_{Z}\|D x\|^{p-2}(D x, D y)_{\mathbb{R}^{N}} \mathrm{~d} z \quad \text { for all } x, y \in W_{0}^{1, p}(Z)
$$

Here, $\langle\cdot, \cdot\rangle$ denotes the duality brackets for the pair $\left(W_{0}^{1, p}(Z), W^{-1, p^{\prime}}(Z)\right)$.
Let $\lambda_{1}>0$ denote the principal eigenvalue of $\left(-\Delta_{p}, W_{0}^{1, p}(Z)\right)$ and let $u_{1}$ denote the $L^{p}$-normalized principal eigenfunction. It is known that $u_{1}$ does not change its sign, and so we may assume that $u_{1} \geqslant 0$. Nonlinear regularity theory implies that $u_{1} \in C_{+}$and the nonlinear strong maximum principle of Vazquez [11] yields that $u_{1} \in \operatorname{Int} C_{+}$.

Let $X$ be a Banach space and $\varphi \in C^{1}(X)$. The critical groups of $\varphi$ at an isolated critical point $x$ with $\varphi(x)=c$ are defined by

$$
C_{k}(\varphi, x)=H_{k}\left(\varphi^{c}, \varphi^{c} \backslash\{x\}\right) \quad \text { for all } k \geqslant 0
$$

where $H_{k}$ is the $k$ th singular relative homology group with coefficients in $\mathbb{Z}$ and $\varphi^{c}=$ $\{x \in X: \varphi(x) \leqslant c\}$.

The hypotheses on the nonlinearity $f$ are the following.

Hypothesis 2.1. $f: Z \times \mathbb{R} \rightarrow \mathbb{R}$ is a function such that $f(z, 0)=0$ a.e. on $Z$ and
(i) for all $x \in \mathbb{R}, z \rightarrow f(z, x)$ is measurable;
(ii) for almost every $z \in Z, x \rightarrow f(z, x)$ is continuous;
(iii) for almost all $z \in Z$ and all $x \in \mathbb{R}$ we have

$$
|f(z, x)| \leqslant a(z)+c|x|^{q-1}
$$

where $a \in L^{\infty}(Z)_{+}, c>0$ and

$$
p<q<p^{*}= \begin{cases}\frac{N p}{N-p} & \text { if } p<N \\ \infty & \text { if } p \geqslant N\end{cases}
$$

(iv) there exists $\tau \in\left(p, p^{*}\right)$ such that

$$
\limsup _{x \rightarrow 0} \frac{f(z, x)}{|x|^{\tau-2} x}<\infty \text { uniformly for almost every } z \in Z
$$

(v) $f(z, x) x>0$ for almost every $z \in Z$ and all $x \neq 0$ (strict sign condition).

Hypothesis 2.2. $m \in L^{\infty}(Z), m \geqslant 0$ and $m \neq 0$.

## 3. Two constant-sign solutions

We consider the truncated functions, $f_{ \pm}: Z \times \mathbb{R} \rightarrow \mathbb{R}$, defined by

$$
f_{+}(z, x)=f\left(z, x^{+}\right) \quad \text { and } \quad f_{-}(z, x)=f\left(z,-x^{-}\right)
$$

We consider the following auxiliary nonlinear Dirichlet problem:

$$
\left.\begin{array}{rl}
-\Delta_{p} x(z) & =m(z) x^{+}(z)^{r-1}+f_{+}(z, x(z)) \quad \text { a.e. on } Z,  \tag{3.1}\\
\left.x\right|_{\partial Z} & =0
\end{array}\right\}
$$

By an upper solution for problem (3.1), we mean a function $\bar{x} \in W^{1, p}(Z)$ such that $\left.\bar{x}\right|_{\partial z} \geqslant 0$ and, for all $y \in W_{+}$,

$$
\int_{Z}\|D \bar{x}\|^{p-2}(D \bar{x}, D y)_{\mathbb{R}^{N}} \mathrm{~d} z \geqslant \int_{Z} m\left(\bar{x}^{+}\right)^{r-1} y \mathrm{~d} z+\int_{Z} f_{+}(z, \bar{x}) y \mathrm{~d} z
$$

We say that $\bar{x}$ is a strict upper solution for (3.1), if it is not a solution of (3.1).
Next we derive a strict upper solution for problem (3.1).
Proposition 3.1. If Hypotheses 2.1 and 2.2 hold, then there exists some $\lambda_{+}^{*}>0$ such that problem (3.1) has a strict upper solution $\bar{x} \in \operatorname{Int} C_{+}$, provided that $0<\|m\|_{\infty}<\lambda_{+}^{*}$.

Proof. By virtue of Hypothesis 2.1 (iii)-(v), we have, for almost every $z \in Z$ and all $x \geqslant 0$,

$$
\begin{equation*}
0 \leqslant m(z) x^{r-1}+f(z, x) \leqslant c_{1}\left(\|m\|_{\infty}^{s}+x^{\vartheta-1}\right) \tag{3.2}
\end{equation*}
$$

where $c_{1}>0,1<s$ and $p<\vartheta<p^{*}$.
Let $e \in \operatorname{Int} C_{+}$be the unique solution of the Dirichlet problem:

$$
-\Delta_{p} e(z)=1 \text { a.e. on } Z \quad \text { and }\left.\quad e\right|_{\partial Z}=0 .
$$

Claim 3.2. There exists $\lambda_{+}^{*}>0$ such that for each $m \in L^{\infty}(Z)_{+}$with $0<\|m\|_{\infty}<\lambda_{+}^{*}$ we can find some $\eta_{1}=\eta_{1}(m)>0$ satisfying

$$
\begin{equation*}
c_{1}\|m\|_{\infty}^{s}+c_{1}\left(\eta_{1}\|e\|_{\infty}\right)^{\vartheta-1}<\eta_{1}^{p-1} . \tag{3.3}
\end{equation*}
$$

We argue by contradiction. So, we suppose that the claim is false. Then, we can find $\left\{m_{n}\right\} \subseteq L^{\infty}(Z)_{+}$such that $\left\|m_{n}\right\|_{\infty} \rightarrow 0$ and, for all $\eta>0$,

$$
\eta^{p-1} \leqslant c_{1}\left\|m_{n}\right\|_{\infty}+c_{1}\left(\eta\|e\|_{\infty}\right)^{\vartheta-1}
$$

Hence, we obtain $1 \leqslant c_{1} \eta^{\vartheta-p}\|e\|_{\infty}^{\vartheta-1}$ for all $\eta>0$.
Since $\vartheta>p$, by letting $\eta \downarrow 0$ we have a contradiction. This proves the claim. Now, set $\bar{x}=\eta_{1} e \in \operatorname{Int} C_{+}$. We have

$$
\begin{array}{rlrl}
-\Delta_{p} \bar{x}(z) & =-\eta_{1}^{p-1} \Delta_{p} e(z) \\
& =\eta_{1}^{p-1} & \\
& >c_{1}\|m\|_{\infty}^{s}+c_{1}\left(\eta_{1}\|e\|_{\infty}\right)^{\vartheta-1} & & \\
& \geqslant m(z) \bar{x}(z)^{r-1}+f_{+}(z, \bar{x}(z)) & \text { a.e. on } Z & (\operatorname{see}(3.3)) \\
(3.2)) .
\end{array}
$$

This implies that $\bar{x} \in \operatorname{Int} C_{+}$is a strict upper solution for problem (3.1).
We also consider the following auxiliary nonlinear Dirichlet problem:

$$
\left.\begin{array}{rl}
-\Delta_{p} v(z) & =-m(z) v^{-}(z)^{r-1}+f_{-}(z, v(z)) \quad \text { a.e. on } Z,  \tag{3.4}\\
\left.v\right|_{\partial Z} & =0
\end{array}\right\}
$$

We say that $\underline{v} \in W^{1, p}(Z)$ is a lower solution for problem (3.4) if $\left.\underline{v}\right|_{\partial Z} \leqslant 0$ and

$$
\int_{Z}\|D \underline{v}\|^{p-2}(D \underline{v}, D y)_{\mathbb{R}^{N}} \mathrm{~d} z \leqslant \int_{Z}-m(\underline{v})^{r-1} y \mathrm{~d} z+\int_{Z} f_{-}(z, \underline{v}) y \mathrm{~d} z
$$

for all $y \in W_{+}$. We say that $\underline{v}$ is a strict lower solution for (3.4) if it is a lower solution but not a solution of (3.4).

Arguing as in the proof of Proposition 3.1, we obtain the following.
Proposition 3.3. If Hypotheses 2.1 and 2.2 hold, then there exists $\lambda_{-}^{*}>0$ such that problem (3.4) has a strict lower solution $\underline{v} \in \operatorname{Int} C_{+}$, provided that $\|m\|_{\infty}<\lambda_{-}^{*}$.

Next we introduce an additional truncation. So, let

$$
\hat{f}_{+}(z, x)= \begin{cases}0 & \text { if } x<0 \\ m(z) x^{r-1}+f_{+}(z, x) & \text { if } 0 \leqslant x \leqslant \bar{x}(z) \\ m(z) \bar{x}(z)^{r-1}+f_{+}(z, \bar{x}(z)) & \text { if } \bar{x}(z)<x\end{cases}
$$

Clearly, $\hat{f}_{+}$is a Carathéodory function. We further set

$$
\hat{F}_{+}(z, x)=\int_{0}^{x} \hat{f}_{+}(z, s) \mathrm{d} s
$$

for all $x \in \mathbb{R}$.
Also, we introduce the functional $\hat{\varphi}_{+}: W_{0}^{1, p}(Z) \rightarrow \mathbb{R}$, defined by

$$
\hat{\varphi}_{+}(x)=\frac{1}{p}\|D x\|_{p}^{p}-\int_{Z} \hat{F}_{+}(z, x(z)) \mathrm{d} z .
$$

Clearly, we have $\hat{\varphi}_{+} \in C^{1}\left(W_{0}^{1, p}(Z)\right)$.
Proposition 3.4. If Hypotheses 2.1 and 2.2 hold and $0<\|m\|_{\infty}<\lambda_{+}^{*}$, then problem (1.1) has a solution $x_{0} \in \operatorname{Int} C_{+}$.

Proof. Clearly, $\hat{\varphi}_{+}$is coercive and sequentially $w$-lower semicontinuous. So, by the Weierstrass theorem we can find $x_{0} \in W_{0}^{1, p}(Z)$ such that

$$
\hat{\varphi}_{+}\left(x_{0}\right)=\hat{m}_{+}=\inf \left[\hat{\varphi}_{+}(x): x \in W_{0}^{1, p}(Z)\right] ;
$$

hence, $\hat{\varphi}_{+}^{\prime}\left(x_{0}\right)=0$ and consequently

$$
\begin{equation*}
A\left(x_{0}\right)=\hat{N}_{+}\left(x_{0}\right) \tag{3.5}
\end{equation*}
$$

where $\hat{N}_{+}(x)(\cdot)=\hat{f}_{+}(\cdot, x(\cdot))$ for all $x \in W_{0}^{1, p}(Z)$. Since $\bar{x} \in \operatorname{Int} C_{+}$is a strict upper solution for problem (3.1), we have

$$
\begin{equation*}
A(\bar{x})>m\left(\bar{x}^{+}\right)^{r-1}+N_{+}(\bar{x}) \quad \text { in } W^{-1, p^{\prime}}(Z) \tag{3.6}
\end{equation*}
$$

where $N_{+}(x)(\cdot)=f_{+}(\cdot, x(\cdot))$ for all $x \in W_{0}^{1, p}(Z)$. From (3.5) and (3.6), it follows that in $W^{-1, p^{\prime}}(Z)$ we have

$$
\begin{equation*}
A(\bar{x})-A\left(x_{0}\right)>m \bar{x}^{r-1}+N_{+}(\bar{x})-\hat{N}_{+}\left(x_{0}\right) . \tag{3.7}
\end{equation*}
$$

On (3.7) we act with the test function $\left(x_{0}-x\right)^{+} \in W_{0}^{1, p}(Z)$. Notice that $\hat{f}_{+}\left(z, x_{0}(z)\right)=$ $m(z) \bar{x}(z)^{r-1}+f_{+}(z, \bar{x}(z))$ for almost every $z \in\left\{x_{0}(z)>\bar{x}(z)\right\}$. Therefore, we obtain

$$
\begin{aligned}
0 & \leqslant\left\langle A(\bar{x})-A\left(x_{0}\right),\left(x_{0}-\bar{x}\right)^{+}\right\rangle \\
& =\int_{\left\{x_{0}>\bar{x}\right\}}\left(\|D \bar{x}\|^{p-2} D \bar{x}-\left\|D x_{0}\right\|^{p-2} D x_{0}, D x_{0}-D \bar{x}\right)_{\mathbb{R}^{N}} \mathrm{~d} z .
\end{aligned}
$$

Hence, $\left|\left\{x_{0}>\bar{x}\right\}\right|_{N}=0$, i.e. $x_{0} \leqslant \bar{x}$. Here $|\cdot|_{N}$ denotes the Lebesgue measure on $\mathbb{R}^{N}$. Also, if on (3.5) we act with the test function $-x_{0}^{-} \in W_{0}^{1, p}(Z)$, then

$$
\left\|D x_{0}^{-}\right\|_{p}^{p}=0, \text { i.e. } 0 \leqslant x_{0}
$$

It follows that $\hat{N}_{+}\left(x_{0}\right)=m x_{0}^{r-1}+N_{+}\left(x_{0}\right)$, which implies that $(3.5)$ becomes $A\left(x_{0}\right)=$ $m x_{0}^{r-1}+N_{+}\left(x_{0}\right)$ and, consequently,

$$
\begin{equation*}
-\Delta_{p} x_{0}(z)=m x_{0}(z)^{r-1}+f_{+}\left(z, x_{0}(z)\right) \text { a.e. on } Z \quad \text { and }\left.\quad x_{0}\right|_{\partial Z}=0 . \tag{3.8}
\end{equation*}
$$

Next we show that $x_{0} \neq 0$. To this end, for $t>0$ small we have

$$
\begin{aligned}
\hat{\varphi}_{+}\left(t u_{1}\right) & =\frac{t^{p}}{p}\left\|D u_{1}\right\|_{p}^{p}-\frac{t^{r}}{r} \int_{E} m u_{1}^{r} \mathrm{~d} z-\int_{Z} F\left(z, t u_{1}\right) \mathrm{d} z \\
& \leqslant \frac{t^{p}}{p} \lambda_{1}-\frac{t^{r}}{r} \int_{Z} m u_{1}^{r} \mathrm{~d} z
\end{aligned}
$$

Since $r<p$, if we make $t \in(0,1)$ small enough, then we infer that $\hat{\varphi}_{+}\left(t u_{1}\right)<0$, and hence

$$
\hat{\varphi}_{+}\left(x_{0}\right)=\hat{m}_{+}<0=\hat{\varphi}_{+}(0), \quad \text { i.e. } x_{0} \neq 0
$$

From (3.8) and the nonlinear regularity theory (see, for example, [6, pp. 737-738]), we have $x_{0} \in C_{+} \backslash\{0\}$. Invoking the nonlinear strong maximum principle of [11], we conclude that $x_{0} \in \operatorname{Int} C_{0}$. Moreover,

$$
-\Delta_{p} x_{0}(z)=m(z) x_{0}(z)^{r-1}+f\left(z, x_{0}(z)\right) \quad \text { a.e. on } Z ;
$$

hence, $x_{0} \in \operatorname{Int} C_{+}$is a solution of problem (1.1).
Now we execute an analogous process on the negative semi-axis, for which we define

$$
\hat{f}_{-}(z, x)= \begin{cases}m(z) \underline{v}(z)^{r-1}+f_{-}(z, \underline{v}(z)) & \text { if } x<\underline{v}(z) \\ m x^{r-1}+f_{-}(z, x) & \text { if } \underline{v}(z) \leqslant x \leqslant 0 \\ 0 & \text { if } 0<x\end{cases}
$$

Set

$$
\hat{F}_{-}(z, x)=\int_{0}^{x} \hat{f}_{-}(z, s) \mathrm{d} s
$$

Also, we consider the $C^{1}$-functional $\hat{\varphi}_{-}: W_{0}^{1, p}(Z) \rightarrow \mathbb{R}$, defined by

$$
\hat{\varphi}_{-}(x)=\frac{1}{p}\|D x\|_{p}^{p}-\int_{Z} \hat{F}_{-}(z, x(z)) \mathrm{d} z
$$

Arguing as in the proof of Proposition 3.4, we obtain the following.
Proposition 3.5. If Hypotheses 2.1 and 2.2 hold and $0<\|m\|_{\infty}<\lambda_{-}^{*}$, then problem (1.1) has a solution $v_{0} \in-\operatorname{Int} C_{+}$.

## 4. The three-solutions theorem

In this section we prove the three-solutions theorem for problem (1.1). For this purpose, we introduce the following truncations of the identity map, of the nonlinearity $f$ and of $m x^{r-1}+f(z, x)$ :

$$
\begin{aligned}
& \bar{f}_{0}(z, x)= \begin{cases}f\left(z, v_{0}(z)\right) & \text { if } x<v_{0}(z), \\
f(z, x) & \text { if } v_{0}(z) \leqslant x \leqslant x_{0}(z), \\
f\left(z, x_{0}(z)\right) & \text { if } x_{0}(z)<x,\end{cases} \\
& \bar{f}_{+}(z, x)= \begin{cases}0 & \text { if } x<0, \\
m(z) x^{r-1}+f(z, x) & \text { if } 0 \leqslant x \leqslant x_{0}(z), \\
m(z) x_{0}(z)^{r-1}+f\left(z, x_{0}(z)\right) & \text { if } x_{0}(z)<x,\end{cases} \\
& \bar{f}_{-}(z, x)= \begin{cases}m(z) v_{0}(z)^{r-1}+f\left(z, v_{0}(z)\right) & \text { if } x<v_{0}(z), \\
m(z) x^{r-1}+f(z, x) & \text { if } v_{0}(z) \leqslant x \leqslant 0, \\
0 & \text { if } 0<x,\end{cases}
\end{aligned}
$$

and

$$
\bar{f}_{0}^{*}(z, x)= \begin{cases}m(z) v_{0}(z)^{r-1}+f\left(z, v_{0}(z)\right) & \text { if } x<v_{0}(z), \\ m(z) x^{r-1}+f(z, x) & \text { if } v_{0}(z) \leqslant x \leqslant x_{0}(z), \\ m(z) x_{0}(z)^{r-1}+f\left(z, x_{0}(z)\right) & \text { if } x_{0}(z)<x .\end{cases}
$$

Also, we define

$$
\bar{F}_{ \pm}(z, x)=\int_{0}^{x} \bar{f}_{ \pm}(z, s) \mathrm{d} s \quad \text { and } \quad \bar{F}_{0}^{*}(z, x)=\int_{0}^{x} \bar{f}_{0}^{*}(z, s) \mathrm{d} s .
$$

Finally, we introduce the $C^{1}$-functionals $\bar{\varphi}_{ \pm}, \bar{\varphi}_{0}: W_{0}^{1, p}(Z) \rightarrow \mathbb{R}$, defined by

$$
\bar{\varphi}_{ \pm}(x)=\frac{1}{p}\|D x\|_{p}^{p}-\int_{Z} \bar{F}_{ \pm}(z, x(z)) \mathrm{d} z
$$

and

$$
\bar{\varphi}_{0}(z)=\frac{1}{p}\|D x\|_{p}^{p}-\int_{Z} \bar{F}_{0}^{*}(z, x(z)) \mathrm{d} z .
$$

In the next proposition we will locate the critical points of these three functionals.
Proposition 4.1. If Hypotheses 2.1 and 2.2 hold and $0<\|m\|_{\infty}<\lambda_{0}^{*}=\min \left\{\lambda_{+}^{*}, \lambda_{-}^{*}\right\}$, then the critical points of $\bar{\varphi}_{+}$are in $\left[0, x_{0}\right]$, the critical points of $\bar{\varphi}_{-}$are in $\left[v_{0}, 0\right]$ and the critical points of $\bar{\varphi}_{0}$ are in $\left[v_{0}, x_{0}\right]$. Furthermore, $v_{0}$ and $x_{0}$ are local minimizers of $\bar{\varphi}_{0}$.
Proof. We prove the case for $\bar{\varphi}_{0}$ (the proof for $\bar{\varphi}_{ \pm}$is similar). So, let $x \in W_{0}^{1, p}(Z)$ be a critical point of $\bar{\varphi}_{0}$. Then we have $\bar{\varphi}_{0}^{\prime}(x)=0$; hence,

$$
\begin{equation*}
A(x)=\hat{\bar{N}}_{0}^{*}(x), \tag{4.1}
\end{equation*}
$$

where $\hat{\bar{N}}_{0}^{*}(x)(\cdot)=\bar{f}_{0}^{*}(\cdot, x(\cdot))$ for all $x \in W_{0}^{1, p}(Z)$. Thus,

$$
\begin{align*}
\left\langle A(x),\left(x-x_{0}\right)^{+}\right\rangle & =\int_{Z} m x_{0}^{r-1}\left(x-x_{0}\right)^{+} \mathrm{d} z+\int_{Z} f\left(z, x_{0}\right)\left(x-x_{0}\right)^{+} \mathrm{d} z \\
& =\left\langle A\left(x_{0}\right),\left(x-x_{0}\right)^{+}\right\rangle \tag{4.2}
\end{align*}
$$

where the last equality is due to the fact that $x_{0} \in \operatorname{Int} C_{+}$is a solution of (1.1).
By virtue of the strict monotonicity of the map $A$, from (4.2) we infer that

$$
\left(x-x_{0}\right)^{+}=0
$$

i.e. $x \leqslant x_{0}$. In a similar fashion we also can show that

$$
v_{0} \leqslant x
$$

So, indeed the critical points of $\bar{\varphi}_{0}$ are in the ordered interval $\left[v_{0}, x_{0}\right]$.
Without loss of generality, we may assume that $x_{0} \in \operatorname{Int} C_{+}$is the only non-trivial critical point of $\bar{\varphi}_{+}$and $v_{0}$ is the only non-trivial critical point of $\bar{\varphi}_{-}$. Otherwise, we already have a third non-trivial solution of (1.1), distinct from $x_{0}$ and $v_{0}$, which is in fact of constant sign.

As in the proof of Proposition 3.4, we can show that for $t>0$ small we have $\bar{\varphi}_{+}\left(t u_{1}\right)<$ 0 ; hence,

$$
\bar{m}_{+}=\inf \left[\bar{\varphi}_{+}(x): x \in W_{0}^{1, p}(Z)\right]<0=\bar{\varphi}_{+}(0)
$$

Note that $\bar{\varphi}_{+}$is coercive and sequentially $w$-lower semicontinuous. Therefore, we can find some $\bar{x}_{0} \in W_{0}^{1, p}(Z)$ such that

$$
\bar{\varphi}_{+}\left(\bar{x}_{0}\right)=\bar{m}_{+}<0=\bar{\varphi}_{+}(0)
$$

i.e. $\bar{x}_{0} \neq 0$. It follows that $\bar{x}_{0}=x_{0}$. Because $x_{0} \in \operatorname{Int} C_{+}$, we can find small $r>0$ such that

$$
\left.\bar{\varphi}_{+}\right|_{\bar{B}_{r}^{C}{ }_{0}^{1}(\bar{Z})}\left(x_{0}\right)=\left.\varphi_{0}\right|_{\bar{B}_{r}^{C} C_{0}^{1}(\bar{Z})\left(x_{0}\right)},
$$

where

$$
\bar{B}_{r}^{C_{0}^{1}(\bar{Z})}\left(x_{0}\right)=\left\{x \in C_{0}^{1}(\bar{Z}):\left\|x-x_{0}\right\|_{C_{0}^{1}(\bar{Z})} \leqslant r\right\}
$$

Hence, $x_{0}$ is a local $C_{0}^{1}(\bar{Z})$-minimizer of $\bar{\varphi}_{0}$. From [5], it follows that $x_{0}$ is a local $W_{0}^{1, p}(Z)$ minimizer of $\bar{\varphi}_{0}$. The argument for $v_{0} \in-\operatorname{Int} C_{+}$is similar.

Now we are ready for the multiplicity result.
Theorem 4.2. If Hypotheses 2.1 and 2.2 hold and $0<\|m\|_{\infty}<\lambda_{0}^{*}=\min \left\{\lambda_{+}^{*}, \lambda_{-}^{*}\right\}$, then problem (1.1) has at least three non-trivial distinct solutions $x_{0}, v_{0}$ and $y_{0}$ such that

$$
x_{0} \in \operatorname{Int} C_{0}, \quad v_{0} \in-\operatorname{Int} C_{+}, \quad y_{0} \in C_{0}^{1}(\bar{Z})
$$

and $v_{0}(z) \leqslant y_{0}(z) \leqslant x_{0}(z)$ for all $z \in \bar{Z}$.

Proof. From Propositions 3.4 and 3.5 , we already have two solutions of constant sign: $x_{0} \in \operatorname{Int} C_{+}$and $v_{0} \in-\operatorname{Int} C_{+}$. By Proposition 4.1, we know that both $x_{0}$ and $v_{0}$ are local minimizers of $\bar{\varphi}_{0}$. So, as in [1, Proposition 29], we can find $r>0$ small enough such that

$$
\bar{\varphi}_{0}\left(x_{0}\right)<\inf \left[\bar{\varphi}_{0}(x):\left\|x-x_{0}\right\|=r\right]
$$

and

$$
\bar{\varphi}_{0}\left(v_{0}\right)<\inf \left[\bar{\varphi}_{0}(v):\left\|v-v_{0}\right\|=r\right] .
$$

Without loss of generality, we may assume that $\varphi_{0}\left(v_{0}\right) \leqslant \varphi_{0}\left(x_{0}\right)$. Then, the sets $E_{0}=\left\{v_{0}, x_{0}\right\}, E=\left[v_{0}, x_{0}\right]$ and

$$
D=\partial B_{r}\left(x_{0}\right)=\left\{x \in W_{0}^{1, p}(Z):\left\|x-x_{0}\right\|=r\right\}
$$

are linking in $W_{0}^{1, p}(Z)$ (see, for example, [6, p. 642]). Also, $\bar{\varphi}_{0}$ being coercive, we can easily verify that it satisfies the Palais-Smale condition. So, we can apply the linking theorem (see, for example, [6, p. 644]) and obtain some $y_{0} \in W_{0}^{1, p}(Z)$, a critical point of $\bar{\varphi}_{0}$ of mountain-pass type, $y_{0} \neq x_{0}, y_{0} \neq v_{0}$. Hence [2],

$$
\begin{equation*}
C_{1}\left(\bar{\varphi}_{0}, y_{0}\right) \neq 0 \tag{4.3}
\end{equation*}
$$

On the other hand, by Hypothesis 2.1 (iv), we can find some $\beta>0$ and $\delta>0$ such that

$$
0 \leqslant f(z, x) x \leqslant \beta|x|^{\tau}
$$

for all $z \in Z$ and all $|x| \leqslant \delta$. Now, let $|x| \leqslant \delta$. If $x \in\left[v_{0}(z), x_{0}(z)\right]$, then $\bar{f}_{0}(z, x)=f(z, x)$, and so

$$
\begin{equation*}
0 \leqslant \bar{f}_{0}(z, x) x \leqslant \beta|x|^{\tau} \tag{4.4}
\end{equation*}
$$

If $x>x_{0}(z)$ (respectively, $x<v_{0}(z)$ ), then

$$
\bar{f}_{0}(z, x)=f\left(z, x_{0}(z)\right)
$$

(respectively, $\bar{f}_{0}(z, x)=f\left(z, v_{0}(z)\right)$ ).
If $\mu \in(r, p)$, then for almost every $z \in Z$ and all $|x| \leqslant \delta, x \in\left[v_{0}(z), x_{0}(z)\right]$, we have

$$
\begin{equation*}
\left(\frac{\mu}{r}-1\right)|x|^{r}+\mu \bar{F}_{0}(z, x)-\bar{f}_{0}(z, x) x \geqslant\left(\frac{\mu}{r}-1\right)|x|^{r}-\beta|x|^{\tau} \tag{4.5}
\end{equation*}
$$

since $\bar{F}_{0} \geqslant 0$, and due to (4.4).
Since $r<\tau$ and $|x| \leqslant \delta<1$, from (4.5) it follows that

$$
\begin{equation*}
\left(\frac{\mu}{r}-1\right)|x|^{r}+\mu \bar{F}_{0}(z, x)-\bar{f}_{0}(z, x) x \geqslant 0 \tag{4.6}
\end{equation*}
$$

for almost all $z \in Z$ and all $|x| \leqslant \delta, x \in\left[v_{0}(z), x_{0}(z)\right]$.

If $x>x_{0}(z)$, then

$$
\left(\frac{\mu}{r}-1\right) x_{0}(z)^{r}-f\left(z, x_{0}(z)\right) x_{0}(z) \geqslant\left(\frac{\mu}{r}-1\right) x_{0}(z)^{r}-\beta x_{0}(z)^{\tau} \geqslant 0 .
$$

A similar result is obtained if $x<v_{0}(z)$.
Invoking [7, Proposition 2.1], by (4.6) we have

$$
\begin{equation*}
C_{k}\left(\bar{\varphi}_{0}, 0\right)=0 \quad \text { for all } k \geqslant 0 . \tag{4.7}
\end{equation*}
$$

If we compare (4.3) and (4.7), it is clear that $y_{0} \neq 0$. Finally, the nonlinear regularity theory implies that $y_{0} \in C_{0}^{1}(\bar{Z})$. Since $y_{0} \in\left[v_{0}, x_{0}\right]$, we conclude that $y_{0}$ is a non-trivial smooth solution of problem (1.1), distinct from $x_{0}$ and $v_{0}$.

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