UNION CURVES IN A SUBSPACE V_n OF A RIEMANNIAN V_m

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1. Introduction. A union curve on a surface in a euclidean 3-space, relative to a given congruence is characterized by the property that its osculating plane at each point contains the ray of the congruence through that point. Springer (2) and Pan (1) have studied union curves in a hypersurface V_n of a Riemannian V_{n+1} . In the present paper we proceed to obtain the equations of union curves in a subspace V_n of a Riemannian V_m .

2. Subspaces of V_m . Consider a subspace V_n of co-ordinates x^i , $i = 1, 2, \ldots, n$ and positive-definite metric

$$ds^2 = g_{ij} \, dx^i dx^j$$

imbedded in a V_m of co-ordinates y^{α} , $\alpha = 1, 2, ..., m$ and positive-definite metric

(2.2)
$$ds^2 = a_{\alpha\beta} dy^{\alpha} dy^{\beta}.$$

For points of V_n , the y's are expressible as functions of the x's, the matrix

 $\frac{\partial y^{\alpha}}{\partial x^{i}}$

being of order n. The coefficients of the fundamental forms of V_m and V_n are connected by the relations

(2.3)
$$g_{ij} = a_{\alpha\beta} y^{\alpha}_{,i} y^{\beta}_{,j}$$

where (,) followed by an index indicates the covariant derivative with respect to the x with that index.

In V_m there are (m - n) mutually orthogonal independent unit vectors normal to V_n . If $N_{\nu_1}^{\alpha}$ be the contravariant components in the y's of any such system of unit normals to V_n , they must satisfy the relations

(2.4)
$$a_{\alpha\beta}N^{\alpha}_{\nu 1}N^{\beta}_{\nu 1} = 1,$$

(2.5)
$$a_{\alpha\beta}N^{\alpha}_{\nu 1}N^{\beta}_{\mu 1} = 0 \quad (\mu \neq \nu),$$

and

(2.6)
$$a_{\alpha\beta}N^{\alpha}_{\nu_{1}}y^{\beta}_{i} = 0 \quad (\nu = n+1,\ldots,m),$$

since $y^{\alpha}_{,i}$ are the components of a vector tangential to the curve of parameter x^{i} .

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3. Tensor derivatives. Let

$$T^{\alpha_1\ldots i_1\ldots}_{\beta_1\ldots j_1\ldots}$$

be a set of quantities over V_n having twofold tensor character indicated by the two types of indices, and let

$$\begin{cases} \alpha \\ \beta \nu \end{cases} \quad \text{and} \quad \begin{cases} i \\ jk \end{cases}$$

be the Christoffel symbols formed with the tensors $a_{\alpha\beta}$ and g_{ij} respectively. Then

$$T^{\alpha_{1}\dots i_{1}\dots j_{1}\dots j_{k}}_{\beta_{1}\dots j_{1}\dots j_{k}} = \frac{\partial T^{\dots}}{\partial x^{k}} + \sum_{\tau} \left\{ \begin{array}{c} \alpha_{\tau} \\ \lambda\gamma \end{array} \right\} \begin{pmatrix} \lambda \\ \alpha_{\tau} \end{pmatrix} T^{\dots}_{\dots} y^{\gamma}_{,k} \\ - \sum_{\tau} \left\{ \begin{array}{c} \lambda \\ \beta_{\tau}\gamma \end{array} \right\} \begin{pmatrix} \beta_{\tau} \\ \lambda \end{pmatrix} T^{\dots}_{,k} \\ - \sum_{i} \left\{ \begin{array}{c} l \\ lk \end{array} \right\} \begin{pmatrix} l \\ l \end{pmatrix} T^{\dots}_{,m} \\ - \sum_{i} \left\{ \begin{array}{c} l \\ j_{i} k \end{array} \right\} \begin{pmatrix} j_{i} \\ l \end{pmatrix} T^{\dots}_{,m} \end{cases}$$

are the components of a tensor, called the tensor derivative of the tensor $T_{:::}$. Here $\binom{\lambda}{\alpha_{\tau}}T$ denotes that the suffix α_{τ} of $T_{:::}$ is to be replaced by λ .

Throughout the present paper we shall use (;) followed by an index to indicate the tensor-derivative with respect to the x with that index.

4. Congruences of curves in V_n . Let us consider a set of (m-n) congruences of curves, one curve of each of which passes through each point of the subspace V_n . Let $\lambda_{\tau 1}^{\alpha}$ be the contravariant components in the y's, of a unit vector in the direction of the congruence λ_{τ} . Since the vector λ_{τ} is, in general, not normal to V_n , it may be expressed linearly in terms of $y_{\tau i}^{\alpha}$ and the set of normals $N_{\tau 1}^{\alpha}$. Thus

(4.1)
$$\lambda_{\tau 1}^{\alpha} = t_{\tau 1}^{i} y_{,i}^{\alpha} + \sum_{\nu} c_{\nu \tau} N_{\nu 1}^{\alpha}$$

where the parameters $t_{\tau_1}^i$ and $c_{\nu\tau}$ are such that if $\theta_{\nu\tau_1}$ is the angle between the vectors $N_{\nu_1}^{\alpha}$ and $\lambda_{\tau_1}^{\alpha}$ then

(4.2)
$$c_{\nu\tau} = \cos\theta_{\nu\tau 1} = a_{\alpha\beta}\lambda^{\alpha}_{\tau 1}N^{\beta}_{\nu 1}$$

(4.3)
$$1 - t_{\tau 1}^{i} t_{\tau 1 i} = \sum \cos^{2} \theta_{\nu \tau 1}$$

for

$$a_{\alpha\beta}\lambda_{\tau 1}^{\alpha}\lambda_{\tau 1}^{\beta} = a_{\alpha\beta}\left(t_{\tau 1}^{i}y_{,i}^{\alpha} + \sum_{\nu} c_{\nu\tau}N_{\nu 1}^{\beta}\right)\left(t_{\tau 1}^{j}y_{,j}^{\beta} + \sum_{\nu} c_{\nu\tau}N_{\nu 1}^{\beta}\right)$$

or

$$1 = g_{ij}t_{\tau 1}^{i}t_{\tau 1}^{j} + \sum_{\nu} c_{\nu\tau 1}^{2}.$$

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5. Union curves in V_n . A curve in a subspace V_n of a Riemannian V_m is a union curve relative to a set of (m - n) congruences $\lambda_{\tau 1}$ if $\lambda_{\tau 1}(\tau = n + 1, \ldots, m)$ are tangential to the osculating variety of C (that is, the variety determined by the tangent to C and the first curvature vector of C in V_m) at every point of C, that is, if there exists a linear relation between the vectors $\mathbf{t}, \lambda_{\tau 1}(\tau = n + 1, \ldots, m)$ and \mathbf{q} , where \mathbf{t} is the unit tangent vector to C and \mathbf{q} is the first curvature vector of C relative to V_m .

Let ϕ_{τ_1} be the angle which λ_{τ_1} makes with the tangent to *C*, then, by (4.1) we have

(5.1)
$$\cos \phi_{\tau 1} = a_{\alpha\beta} \lambda^{\alpha}_{\tau 1} y^{\beta}_{,j} \frac{dx^{j}}{ds} = a_{\alpha\beta} \bigg[t^{i}_{\tau 1} y^{\alpha}_{,i} + \sum_{\nu} c_{\nu\tau} N^{\alpha}_{\nu 1} \bigg] y^{\beta}_{,j} \frac{dx^{j}}{ds}$$
$$= g_{ij} t^{i}_{\tau 1} \frac{dx^{j}}{ds},$$

by virtue of (2.3) and (2.6).

Let $\xi_{\tau_1}^{\alpha}$ be the contravariant components of a unit vector at a point P of the curve C in V_n which satisfies the following conditions:

(1) It is linearly dependent on $\lambda_{\tau 1}$ and the unit tangent vector **t**.

(2) It is orthogonal to \mathbf{t} .

We may write

(5.2)
$$\xi_{\tau_1}^{\alpha} = a_{\tau_1} \frac{dy^{\alpha}}{ds} + b_{\tau_1} \lambda_{\tau_1}^{\alpha}.$$

Multiplying (5.2) by

$$a_{\alpha\beta}\frac{dy^{\beta}}{ds}$$

and summing over α , we have

(5.3) $0 = a_{\tau 1} + b_{\tau 1} \cos \phi_{\tau 1}$

because of (5.1) and Condition (2).

Using (5.3), we may write (5.2) as

(5.4)
$$\lambda_{\tau 1}^{\alpha} = \frac{dy^{\alpha}}{ds} \cos \phi_{\tau 1} + \frac{1}{b_{\tau 1}} \xi_{\tau 1}^{\alpha}.$$

Since $\lambda_{\tau_1}^{\alpha}$ and $\xi_{\tau_1}^{\alpha}$ are components of unit vectors, from (5.4) we have

$$1 = a_{\alpha\beta}\lambda_{\tau 1}^{\alpha}\lambda_{\tau 1}^{\beta} = a_{\alpha\beta}\left(\frac{dy^{\alpha}}{ds}\cos\phi_{\tau 1} + \frac{1}{b_{\tau 1}}\xi_{\tau 1}^{\alpha}\right)\left(\frac{dy^{\beta}}{ds}\cos\phi_{\tau 1} + \frac{1}{b}\xi_{\tau 1}^{\beta}\right)$$

or

(5.5)
$$\frac{1}{b_{\tau 1}} = \sin \phi_{\tau 1}.$$

(5.2) may now be written as

(5.6)
$$\xi_{\tau 1}^{\alpha} = \lambda_{\tau 1}^{\alpha} \operatorname{cosec} \phi_{\tau 1} - \frac{dy^{\alpha}}{ds} \operatorname{cot} \phi_{\tau 1}.$$

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Using (4.1), (5.6) may be written in the form

(5.7)
$$\xi_{\tau_1}^{\alpha} = \left(t_{\tau_1}^i \operatorname{cosec} \phi_{\tau_1} - \frac{dx^i}{ds} \operatorname{cot} \phi_{\tau_1}\right) y_{,i}^{\alpha} + \sum_{\nu} c_{\nu\tau_1} N_{\nu_1}^{\alpha} \operatorname{cosec} \phi_{\tau_1}.$$

The set of (m - n) linear equations (5.7) in the quantities $N_{\nu_1}^{\alpha}$, when solved, yield,

(5.8)
$$N_{\sigma 1}^{\alpha} = \sum_{\tau} \left[\xi_{\tau 1}^{\alpha} \sin \phi_{\tau 1} - \left(t_{\tau 1}^{i} - \frac{dx^{i}}{ds} \cos \phi_{\tau 1} \right) y_{,i}^{\alpha} \right] C_{\sigma \tau}$$

where $C_{\sigma\tau}$ is the normalized cofactor of $c_{\sigma\tau}$ in the determinant $|c_{\sigma\tau}|$.

Also, we have

(5.9)
$$q^{\alpha} = y^{\alpha}_{,i} p^{i} + \sum_{\nu} \Omega_{\nu|ij} \frac{dx^{i}}{ds} \frac{dx^{j}}{ds} N^{\alpha}_{\nu 1}$$

where p^i and q^{α} are the contravariant components of the first curvature vectors **p** and **q** of C in V_n and V_m respectively (3).

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Using (5.8), (5.9) may be written as

(5.10)
$$q^{\alpha} = y^{\alpha}_{,i} \left[p^{i} - \sum_{\nu,\tau} \Omega_{\nu|lj} \frac{dx^{i}}{ds} \frac{dx^{j}}{ds} \left(t^{i}_{\tau 1} - \frac{dx^{i}}{ds} \cos \phi_{\tau 1} \right) C_{\nu\tau} \right] + \sum_{\nu,\tau} \xi^{\alpha}_{\tau 1} \sin \phi_{\tau 1} C_{\nu\tau} \Omega_{\nu|lj} \frac{dx^{i}}{ds} \frac{dx^{j}}{ds}.$$

Since each λ_{τ} is linearly dependent on **t** and $\xi_{\tau 1}$, by the definition of a union curve, **t**, ξ_{τ} and **q** must be linearly dependent; $\tau = n + 1, \ldots, m$. Again, since **t** is orthogonal to $\xi_{\tau 1}$ and **q**, it follows that $\xi_{\tau 1}$ and **q** must be linearly connected ($\tau = n + 1, \ldots, m$). Therefore, from (5.10) we find that the equations of a union curve are

(5.11)
$$p^{i} - \sum_{\nu,\tau} \Omega_{\nu|lj} \frac{dx^{l}}{ds} \frac{dx^{j}}{ds} \left(t_{\tau 1}^{i} - \frac{dx^{i}}{ds} \cos \phi_{\tau 1} \right) C_{\nu \tau} = 0.$$

The quantities

(5.12)
$$\eta^{i} = p^{i} - \sum_{\tau,\nu} \Omega_{\nu \iota j} \frac{dx^{i}}{ds} \frac{dx^{j}}{ds} \left(t^{i}_{\tau 1} - \frac{dx^{i}}{ds} \cos \phi_{\tau 1} \right) C_{\nu \tau}$$

are the components of a vector in V_n , which may be called the *union curvature* vector in analogy with the corresponding result for a curve in a hypersurface V_n of a V_{n+1} (2).

The magnitude of this vector is called the union curvature of the curve whose unit tangent vector has components in $(dx^i)/(ds)$ in the x's. The union curvature vector is a null vector for a union curve, and consequently the union curvature of a union curve is zero.

6. A particular case. If m = n + 1, $N^{\alpha}_{\nu 1} = N^{\alpha}$, $\theta_{\nu \tau} = \theta$,

$$\phi_{\tau 1} = \phi, \qquad C_{\sigma \tau 1} = \frac{1}{\cos \theta},$$

and equations (5.1) reduce to

(6.1)
$$p^{i} - \Omega_{IJ} \frac{dx^{i}}{ds} \frac{dx^{j}}{ds} \left(t^{i} - \frac{dx^{i}}{ds} \cos \phi \right) \sec \theta = 0$$

which are the equations of a union curve in a hypersurface V_n of a Riemannian V_{n+1} . Also (5.12) reduces to

(6.2)
$$\eta^{i} \equiv p^{i} - \Omega_{lj} \frac{dx^{i}}{ds} \frac{dx^{i}}{ds} \left(t^{i} - \frac{dx^{i}}{ds} \cos \phi \right) \sec \theta,$$

which are the components of the union curvature vector of a curve in V_n (2).

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