



Bordered Floer homology and contact structures

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Abstract

We introduce a contact invariant in the bordered sutured Heegaard Floer homology of a three-manifold with boundary. The input for the invariant is a contact manifold (M, ξ, \mathcal{F}) whose convex boundary is equipped with a signed singular foliation \mathcal{F} closely related to the characteristic foliation. Such a manifold admits a family of foliated open book decompositions classified by a Giroux correspondence, as described in [LV20]. We use a special class of foliated open books to construct admissible bordered sutured Heegaard diagrams and identify well-defined classes c_D and c_A in the corresponding bordered sutured modules.

Foliated open books exhibit user-friendly gluing behavior, and we show that the pairing on invariants induced by gluing compatible foliated open books recovers the Heegaard Floer contact invariant for closed contact manifolds. We also consider a natural map associated to forgetting the foliation \mathcal{F} in favor of the dividing set and show that it maps the bordered sutured invariant to the contact invariant of a sutured manifold defined by Honda–Kazez–Matić.

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1. Introduction

A great deal of interesting and beautiful mathematics has been devoted to understanding the fundamental dichotomy in three-dimensional contact geometry: the subdivision of contact structures into tight and overtwisted. Overtwisted structures are determined by homotopical data and thus may be addressed by tools from algebraic topology. In contrast, tight contact structures do not satisfy an h-principle, and many existence and classification questions for tight contact structures are still open. Tight structures

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are nevertheless extremely natural objects of study, as they include the contact structures arising as the boundary of a complex or symplectic manifold.

Many of the recent advances in classifying tight contact structures were made possible by the advent of Heegaard Floer homology in the early 2000s and the subsequent development of Floer-theoretic contact invariants. Using open books, Ozsváth and Szabó defined an invariant of closed contact threemanifolds [OS05]. Given a closed, contact manifold (M, ξ) , this invariant is a class $c(\xi)$ in the Heegaard Floer homology $\widehat{HF}(-M)$. In [HKM09b], Honda, Kazez and Matić gave an alternative description of $c(\xi)$, again using open books. This 'contact class' was used to show that knot Floer homology detects both genus [OS04] and fiberedness [Ghi08, Ni07]. It gives information about overtwistedness: If ξ is overtwisted, then $c(\xi) = 0$, whereas if ξ is Stein fillable, then $c(\xi) \neq 0$ [OS05]. The contact class was also used to distinguish notions of fillability: Ghiggini used it to construct examples of strongly symplectically fillable contact three-manifolds which do not have Stein fillings [Ghi05].

Contact manifolds with convex boundary can be partitioned by the equivalence class of the dividing set on their boundary. Given a contact manifold M with convex boundary and dividing set Γ , Honda, Kazez and Matić used partial open books to define an invariant $c(M, \Gamma, \xi)$ of the equivalence class in the sutured Floer homology $SFH(-M, -\Gamma)$ [HKM09a]. They also defined a gluing map for sutured Floer homology that respects the contact invariants [HKM08]. This map requires the Heegaard diagrams to satisfy a number of technical conditions, collectively referred to as 'contact-compatibility.' Establishing contactcompatibility for specific examples is difficult, so in practice, computations with the gluing map are rarely possible. As a result, most applications of this gluing map have relied only on its formal properties.

Gluing techniques – and Heegaard Floer theory more broadly – benefited soon after from the introduction of *bordered Floer homology*, a new theory for manifolds with boundary defined by Lipshitz, Ozsváth and Thurston in [LOT18]. Although bordered Floer theory has produced a wide variety of new results, (e.g., [HRRW20, Han17, Lev12, Lev16, Hom13, Pet13, AL19]), applications to contact topology remain mostly uncharted territory.

To a three-manifold with parametrized boundary, bordered Floer homology associates an A_{∞} -module (or *type A structure*) or, equivalently, a *type D structure* over a differential graded algebra associated to the parametrization. When manifolds are glued along compatible parameterized boundaries, the derived tensor product of their bordered invariants recovers the Heegaard Floer homology of the closed three-manifold, up to homotopy equivalence. Zarev introduced a generalization, *bordered sutured Floer homology*, which is an invariant of three-manifolds whose boundary is 'part sutured, part parametrized' [Zar09]. Bordered sutured Floer homology similarly associates to a *bordered sutured manifold* a type A structure and a type D structure such that taking derived tensor products recovers the sutured Floer homology of the manifold formed by gluing along the parameterized parts of the boundary.

1.1. Results

In this paper, we define a contact invariant in the bordered sutured Heegaard Floer homology of a contact three-manifold with boundary. We consider contact manifolds whose convex boundary is equipped with a certain type of singular foliation. As shown in [LV20], to any such contact manifold with foliated boundary, one may associate a topological decomposition known as a *foliated open book*. Intuitively, foliated open books are constructed by cutting ordinary open books along separating convex surfaces. The pages and binding of the resulting pair of foliated open books are simply the restrictions of the pages and binding of the original open book to the corresponding piece. The intersection of the cutting surface with the pages determines an ordered signed singular foliation, here called the boundary foliation. This induced 'open book foliation' is closely related to the characteristic foliation of a supported contact structure and has been extensively studied in the work of Ito–Kawamuro, for example, [IK14a, IK14b]. Under mild technical hypotheses, the topological data of the resulting foliated open book uniquely determine the restriction of the original contact structure to each piece, up to isotopy.

We associate to a foliated contact three-manifold (M, ξ, \mathcal{F}) a bordered sutured manifold (M, Γ, \mathcal{Z}) . We then show that the data of a sorted foliated open book for (M, ξ, \mathcal{F}) give rise to an admissible bordered sutured Heegaard diagram for the manifold (M, Γ, Z) , and so via dualizing, an admissible bordered sutured Heegaard diagram for $(-M, \Gamma, \overline{Z})$, which we will call \mathcal{H} . Moreover, we define preferred generators \mathbf{x}_D and \mathbf{x}_A in $\widehat{BSD}(\mathcal{H})$ and $\widehat{BSA}(\mathcal{H})$, respectively. The structures $\widehat{BSD}(\mathcal{H})$ and $\widehat{BSA}(\mathcal{H})$ give invariants of $(-M, \Gamma, \overline{Z})$ up to homotopy equivalence. (Some further algebraic properties of these elements may be found in Proposition 3.5.) We further define an *equivalence* between elements of two homotopy equivalent type A structures or between elements of two homotopy equivalent type D structures in Section 2.2.2. Our main result is that these preferred generators are invariants of the contact structure up to this equivalence.

Theorem 1. Let (M, ξ, \mathcal{F}) be a foliated contact three-manifold with associated bordered sutured manifold (M, Γ, \mathcal{Z}) . Given admissible bordered sutured Heegaard diagrams \mathcal{H} and \mathcal{H}' for $(-M, \Gamma, \overline{\mathcal{Z}})$ with preferred generators $\mathbf{x}_A \in \widehat{BSA}(\mathcal{H})$ and $\mathbf{x}'_A \in \widehat{BSA}(\mathcal{H}')$, there is a homotopy equivalence between $\widehat{BSA}(\mathcal{H})$ and $\widehat{BSA}(\mathcal{H}')$ induced by Heegaard moves, under which \mathbf{x}_A and \mathbf{x}'_A are equivalent; an analogous statement holds for the preferred generators $\mathbf{x}_D \in \widehat{BSD}(\mathcal{H})$ and $\mathbf{x}'_D \in \widehat{BSD}(\mathcal{H}')$. We refer to these type A and type D equivalence classes as $c_A(M, \xi, \mathcal{F})$ and $c_D(M, \xi, \mathcal{F})$, respectively.

More precisely, we show that varying the choices made in our construction induces homotopy equivalences between the bordered sutured Floer homologies associated to the resulting Heegaard diagrams; these maps carry the preferred generator of one module to the preferred generator of the other module.

An ordered signed singular foliation on the convex boundary of a contact manifold determines a dividing set, but such foliations also induce a finer partition on the set of contact manifolds with convex boundary. These additional data improve the compatibility with cut-and-paste operations, as the ordered signed singular foliation carries data about both the contact structure and the foliated open book near the boundary. Given a pair of foliated contact three-manifolds $(M^L, \xi^L, \mathcal{F}^L)$ and $(M^R, \xi^R, \mathcal{F}^R)$ whose foliated boundaries agree in an appropriate sense, there is a canonical perturbation of the contact structure near the boundary so that the pieces glue to a closed contact three-manifold (M, ξ) . In fact, the foliated open books supporting these manifolds also glue to an open book for the resulting closed contact manifold; see Section 2.3.6. Because our bordered sutured contact invariant is sensitive not only to the dividing set of a convex boundary but also to the singular foliation, it behaves nicely with respect to these cut-and-paste operations.

We prove that the contact invariants of the two foliated contact three-manifolds pair to recover the contact invariant of (M, ξ) .

Theorem 2. The tensor product $c_D(M^L, \xi^L, \mathcal{F}^L) \boxtimes c_A(M^R, \xi^R, \mathcal{F}^R)$ recovers the contact invariant $c(M, \xi)$.

A more precise version of this statement on the level of generators is given in Theorem 5.1.

One may also choose to forget the singular foliation and retain only the data of the dividing set on the convex boundary; this is captured by a natural map from a foliated open book to a partial open book. On the level of Heegaard diagrams, this corresponds to converting a bordered sutured Heegaard diagram to a sutured Heegaard diagram; the procedure to do so was described by Zarev in [Zar10] and induces an isomorphism

$$SFH(-M, -\Gamma(\mathcal{F})) \cong H_*\left(\widehat{BSA}(-M, \Gamma, \overline{\mathcal{Z}})\right) \cdot \iota_+,$$

where ι_+ is an idempotent naturally determined by the foliation data. We show that under Zarev's isomorphism the bordered sutured invariant associated to a foliated open book maps to the contact invariant in the sutured Floer homology associated to the corresponding partial open book.

Theorem 3. Under the above isomorphism, $c_A(M, \xi, \mathcal{F}) \cdot \iota_+$ is identified with the contact invariant $EH(M, \Gamma(\mathcal{F}), \xi)$ from [*HKM09a*].

In particular, $EH(M, \Gamma(\mathcal{F}), \xi)$ vanishes in $SFH(-M, -\Gamma(\mathcal{F}))$ if and only if $c_A(M, \xi, \mathcal{F}) \cdot \iota_+$ is zero in $H_*(\widehat{BSA}(-M, \Gamma, \overline{Z})) \cdot \iota_+$. Since $c_A(M, \xi, \mathcal{F}) = c_A(M, \xi, \mathcal{F}) \cdot \iota_+$ and the differential of $\widehat{BSA}(-M, \Gamma, \overline{Z})$

respects the splitting by the idempotents, the class $c_A(M,\xi,\mathcal{F}) \cdot \iota_+$ being zero in $H_*(\widehat{BSA}(-M,\Gamma,\overline{Z}))$.

 ι_+ is equivalent to the class $c_A(M,\xi,\mathcal{F})$ being zero in $H_*(\widehat{BSA}(-M,\Gamma,\overline{Z}))$, which together with [GHVHM07, Theorem 1] and [HKM09a, Corollary 4.3 and Theorem 4.9] implies the following two corollaries.

Corollary 4. If (M, ξ, \mathcal{F}) is overtwisted or has positive 2π -torsion, then the class $c_A(M, \xi, \mathcal{F})$ is zero in $H_*(\widehat{BSA}(-M, \Gamma, \overline{Z}))$.

Corollary 5. If $c_A(M,\xi,\mathcal{F})$ is zero in $H_*(\widehat{BSA}(-M,\Gamma,\overline{Z}))$, then (M,ξ,\mathcal{F}) does not embed into any closed contact manifold (N,ξ') with nonvanishing contact invariant.

1.2. Further directions

The results in this paper establish a framework for studying foliated open books via Heegaard Floer homology in concert with other combinatorial representations of contact manifolds. This is an essential first step towards developing cut-and-paste technology for the Heegaard Floer contact invariant, and we briefly note further avenues for developing this theory.

The defining data of a contact manifold with foliated boundary includes a choice of a distinguished leaf in the foliation, which plays an essential role in constructing the associated Heegaard diagram. It is natural to ask how the invariant depends on this choice; accordingly, this dependence is the subject of planned future work. We anticipate that the foliation on ∂M may be reparameterized by the addition of a suitable foliated open book for $\partial M \times I$. This is a special case of the more general process of gluing a boundary-parallel layer onto ∂M . We hope to understand the maps induced by such gluings in general and to compare our gluing operation to the sutured Floer homology gluing map from [HKM09a].

Theorems 1 and 2 are phrased terms of equivalences of elements, rather than elements. This subtlety arises because as of this writing there is not a naturality result for the bordered variants of Heegaard Floer homology; hence, the type *D* bordered sutured invariant associated to (M, Γ, Z) is the type *D* homotopy equivalence class of $\widehat{BSD}(M, \Gamma, Z)$, as defined in Section 2.2.2. An analogue of Juhász, Thurston and Zemke's proof of the naturality of the Heegaard Floer homology of closed three-manifolds [JTZ21] for bordered sutured Floer homology would immediately upgrade our invariants.

Organization

Section 2 reviews some necessary background in contact geometry and Heegaard Floer homology. Section 2.1 discusses assumed background in contact geometry while Section 2.2 contains a rapid review of Heegaard Floer homology and bordered sutured Heegaard Floer homology; in particular, Section 2.2.2 introduces a notion of equivalence between elements in bordered sutured Heegaard Floer homology under homotopy equivalences of type *A* and type *D* structures. Finally, Section 2.3 summarizes the relevant material from [LV20] concerning foliated open books. In Section 3, we associate a bordered sutured manifold (M, Γ, Z) to a foliated contact three-manifold. We then show how the data of a sorted foliated open book give rise to an admissible bordered Heegaard diagram \mathcal{H} for $(-M, \Gamma, \overline{Z})$ and we identify preferred generators \mathbf{x}_A and \mathbf{x}_D in the associated bordered Floer homology modules $\widehat{BSA}(\mathcal{H})$ and $\widehat{BSD}(\mathcal{H})$. Section 4 proves Theorem 1, namely invariance of \mathbf{x}_A and \mathbf{x}_D up to the choices made in their definitions. Section 5 proves Theorem 2, showing that we recover the ordinary contact invariants after gluing. Finally, Section 6 discusses the relationship of our invariants to the invariant in sutured Floer homology, proving Theorem 3.

2. Preliminaries

This section provides the background required to read the rest of the paper. We provide references for various classical objects in contact geometry in Section 2.1 and Heegaard Floer theory in Section 2.2,

along with more in-depth summaries of partial open books and the contact invariants in various flavors of Floer homology. Because we are concerned with the relationships between various theories, we pay particular attention to the conventions for bordered, sutured, and bordered sutured versions. Finally, Section 2.3 gives an efficient introduction to foliated open books.

2.1. Assumed background in contact geometry

Throughout this article, we assume familiarity with many standard definitions in three-dimensional contact geometry, including contact structures; characteristic foliations; convex surfaces and dividing sets; open book decompositions for closed three-manifolds, as in, for example, [Gei08] and other standard references. Although we will introduce foliated open books carefully in Section 2.3 below, we briefly first recall the definition of a partial open book supporting a contact structure on a manifold with boundary.

Definition 2.1. A *partial open book* is a triple (S, P, h), where

- 1. *S* is a compact, oriented, connected surface with boundary;
- 2. $P = \bigcup P_i$ is a subsurface of *S* such that the surface *S* is obtained from $\overline{S \setminus P}$ by successively attaching one-handles P_i ; and
- 3. *h*: $P \rightarrow S$ is an embedding which is the identity along $\partial P \cap \partial S$.

To a partial open book, we can associate a sutured manifold (M, Γ) , as follows. (See [HKM09a] or [EO11] for more details.) Let $H = S \times [-1, 0]$ with the identification $(x, t) \sim (x, t')$ for $x \in \partial S$ and $t, t' \in [-1, 0]$. Similarly, let $N = P \times [0, 1]$ with the identification $(x, t) \sim (x, t')$ for $x \in \partial P \cap \partial S$ and $t, t' \in [0, 1]$. Then $M = H \cup N$ where we identify $P \times \{0\} \subset \partial H$ with $P \times \{0\} \subset \partial N$ and $h(P) \times \{-1\} \subset \partial H$ with $P \times \{1\} \subset \partial N$. The suture Γ on ∂M can be given as the union of oriented closed curves obtained by gluing the following arcs, modulo identifications:

$$\Gamma = \overline{\partial S \setminus \partial P} \times \{0\} \cup -\overline{\partial P \setminus \partial S} \times \{1/2\}.$$

Definition 2.2. A contact structure ξ is *compatible* with the partial open book (S, P, h) if for the corresponding sutured manifold $(M = H \cup N, \Gamma)$, the following hold:

- 1. ξ is tight on *H* and *N*;
- 2. ∂H is a convex surface in (M, ξ) with dividing set $\partial S \times \{0\}$;
- 3. ∂N is a convex surface in (M, ξ) with dividing set $\partial P \times \{1/2\}$.

2.2. Heegaard Floer theories

We assume familiarity with the various Heegaard Floer theories and provide only a brief review to establish notation and review details related to the contact invariants defined in [OS05, HKM09a, HKM09b].

2.2.1. Earlier Heegaard Floer theoretic contact invariants

Using open books, Ozsváth and Szabó defined a Heegaard Floer invariant of a closed contact threemanifold [OS05]. For a contact manifold (M, ξ) , this invariant is a class $c(\xi)$ in the Heegaard Floer homology $\widehat{HF}(-M)$. In [HKM09b], Honda, Kazez and Matić gave an alternative description of $c(\xi)$. Their construction again uses open books and goes roughly as follows. An open book (S, h) for (M, ξ) induces a Heegaard splitting of M into $U_1 := S \times [0, 1/2]$ and $U_2 := S \times [1/2, 1]$ with Heegaard surface $\Sigma = (S \times \{1/2\}) \cup_B -(S \times \{0\})$. Let $\{a_i\}$ be a collection of properly embedded arcs on S that cut S into a disk. For all i, let b_i be a small perturbation of a_i that moves the endpoints in the positive direction along ∂S so that b_i intersects a_i in one point. Fix a basepoint z on ∂S away from the thin strips cobounded by the $\{a_i\}$ and $\{b_i\}$. It is clear that $\Sigma = \partial U_1 = -\partial U_2$ and that the $\alpha_i := \partial(a_i \times [0, 1/2])$ bound compressing disks for U_1 and the $\beta_i := \partial(b_i \times [1/2, 1])$ bound compressing disks for U_2 . Thus, $(\Sigma, \alpha, \beta, z)$ is a Heegaard diagram for *M*. One can see the curves as

$$\alpha_i = a_i \cup -a_i \subset (S \times \{1/2\}) \cup_B - (S \times \{0\}),$$

$$\beta_i = b_i \cup -h(b_i) \subset (S \times \{1/2\}) \cup_B - (S \times \{0\}).$$

Then $c(\xi) \in \widehat{HF}(-M)$ is defined as the homotopy equivalence class of the unique generator of $\widehat{CF}(\Sigma, \beta, \alpha, z)$ fully supported on $S \times \{1/2\}$.

Using partial open books, Honda, Kazez and Matić then extended the above construction to define an invariant $EH(M, \Gamma, \xi)$ of contact three-manifolds with convex boundary. In this construction, one begins with a partial open book (S, P, h) for (M, Γ, ξ) , where S is built up from $\overline{S \setminus P}$ by the addition of one-handles P_i , as in Definition 2.1. The roles of U_1 and U_2 are now played by $(P \times [-1/2, 0]) \cup (S \times [0, 1/2])/\sim$ and $(S \times [1/2, 1]) \cup (P \times [-1, -1/2])/\sim$, respectively, and the curves $\{a_i\}$ are the cocores of the one-handles P_i . The rest of the construction is as above, except that the final generator supported on $P \times \{-1/2\}$ defines an element in the sutured Floer homology $SFH(-M, -\Gamma)$. Under certain technical conditions, the authors also defined a gluing map for sutured Floer homology that respects the contact invariants [HKM08].

Before briefly reviewing bordered sutured Floer homology, we discuss a straightforward generalization of the contact invariant to multipointed Heegaard diagrams. We begin by constructing a Heegaard diagram analogous to the one above, except that we allow additional arcs $\{a_i\}$ that cut *S* into *n* disks. We place a basepoint in each of the disks thus obtained. This results in a multipointed Heegaard diagram $(\Sigma, \alpha, \beta, \mathbf{z})$ for *M*. The unique generator \mathbf{x} on $S \times \{1/2\}$ defines an element in $\widetilde{HF}(\Sigma, \beta, \alpha, \mathbf{z}) \cong \widehat{HF}(-M) \otimes H_*(T^{n-1})$. Here, \widetilde{HF} is the homology with respect to the differential that avoids all basepoints, and $H_*(T^{n-1}) \cong H_*(S^1)^{\otimes (n-1)}$ is the ordinary singular homology of T^{n-1} .

An adaptation of the argument of part (5) of [BVVV13, Theorem 3.1] shows the following.

Proposition 2.3. Let (S, h) and (S', h') be two open book decompositions compatible with (M, ξ) . Let $\{a_i\}$ and $\{a'_i\}$ be sets of cutting arcs that cut up S and S' into n and n' disks, respectively, with n < n'. The graded isomorphism between the Heegaard Floer homologies induced by Heegaard moves, including index 0 and 3 stabilizations,

$$\widetilde{\mathrm{HF}}(\Sigma',\boldsymbol{\beta}',\boldsymbol{\alpha}',\mathbf{z}')\otimes H_*(T^{n'-n})\to \widetilde{\mathrm{HF}}(\Sigma,\boldsymbol{\beta},\boldsymbol{\alpha},\mathbf{z})$$

maps the homology class to $[\mathbf{x}'] \otimes \theta^{\otimes (n'-n)}$ to $[\mathbf{x}]$, where θ corresponds to the lower-degree generator of $H_*(S^1)$.

This means that up to homotopy equivalence, the multipointed contact invariant is simply $c(\xi) \otimes \theta^{\otimes (n-1)}$, where *n* is the number of basepoints.

We will also make use of the fact that the multipointed Heegaard Floer homology for a closed three-manifold M can be interpreted as the sutured Floer homology of M with balls removed, as follows. Let $(\Sigma, \alpha, \beta, \mathbf{z})$ be a multipointed Heegaard diagram for M with n basepoints, and for each basepoint $z \in \mathbf{z}$, let D_z^2 be a disk neighborhood of z. Then $(\Sigma \setminus \bigcup_{\mathbf{z}} D_z^2, \alpha, \beta)$ is a sutured Heegaard diagram for $M(n) = (M \setminus \bigcup_{z \in \mathbf{z}} B_z^3, \bigcup_{z \in \mathbf{z}} \partial D_z^2)$. As the two Heegaard diagrams are identical outside the basepointed/sutured regions, the chain complex $\widetilde{CF}(\Sigma, \alpha, \beta, \mathbf{z})$ is isomorphic to the chain complex $SFC(\Sigma \setminus \bigcup_{\mathbf{z}} D_z^2, \alpha, \beta)$. Thus, we can compute the multipointed Heegaard Floer homology $\widetilde{HF}(\Sigma, \beta, \alpha, \mathbf{z})$ as the sutured Floer homology $SFH(\Sigma \setminus \bigcup_{\mathbf{z}} D_z^2, \alpha, \beta)$. See also [Juh06, Proposition 9.14].

2.2.2. Bordered sutured Floer homology

Lipshitz, Oszváth and Thurston refine Heegaard Floer homology to a bordered variant associated to a three-manifold with parametrized boundary [LOT18, LOT11], and Zarev [Zar09, Zar10] further refines the invariant to an invariant of sutured manifolds with partially parameterized boundary. We briefly

discuss Zarev's constructions [Zar10, Section 3]. Note that the following description is indicative, rather than complete; for a review of the algebraic definitions involved, see [LOT18, Section 2].

Recall that an *arc diagram* Z = (Z, a, m) consists of a finite collection of oriented line segments Z, commonly called arcs in the literature, a collection of points $a = (a_1, \dots, a_{2k})$ on Z, a matching m of the points in a into pairs and a 'type,' α or β . To every arc diagram Z one associates an A_{∞} -algebra A(Z) generated by tuples of oriented arcs in $[0, 1] \times Z$ such that each arc connects some $(0, a_i)$ to some $(1, a_j)$ with $a_j \ge a_i$, up to an equivalence relation imposed by the matching. The ground ring of idempotents $\mathcal{I}(Z)$ of this algebra consists of elements ι corresponding to tuples of horizontal strands $[0, 1] \times \{a_k\}$ in $[0, 1] \times Z$. One further associates to Z a graph G(Z) and a surface F(Z). The graph is constructed by beginning with Z and adding an edge between each pair of matched points, while F(Z) is constructed from $Z \times [0, 1]$ by attaching one-handles to neighborhoods of the matched points on $Z \times \{0\}$.

A bordered sutured manifold (M, Γ, \mathcal{Z}) consists of the following:

- \circ a three-manifold *M* whose boundary decomposes as a *bordered* part *F* and a *sutured* part *T*;
- an arc diagram $\mathcal{Z} = (Z, a, m)$ and an identification of *F* with $F(\mathcal{Z})$;
- a dividing set Γ which is a properly embedded, oriented one-manifold in T with boundary $\partial \Gamma$ =
- $-\partial(Z \times \{\frac{1}{2}\})$ so that Γ decomposes T into the union of $R_+(\Gamma)$ and $R_-(\Gamma)$ with $\partial R_{\pm}(\Gamma) \setminus \partial F = \pm \Gamma$.

The components of the dividing set are also referred to as sutures.

A β -bordered Heegaard diagram $\mathcal{H} = (\Sigma, \alpha, \beta, \mathcal{Z})$ consists of a compact surface Σ with no closed components; a collection of pairwise disjoint, properly embedded circles α ; a collection of pairwise disjoint, properly embedded circles α ; a collection of pairwise disjoint, properly embedded circles β^c and of properly embedded arcs β^a , with $\beta = \beta^a \cup \beta^c$ and an arc diagram \mathcal{Z} of β -type, together with an embedding $G(\mathcal{Z}) \to \Sigma$ which maps Z to a subset of $\partial\Sigma$ and the edges of $G(\mathcal{Z})$ connecting matched points to the arcs β^c . One also requires that the maps $\pi_0(\partial\Sigma \setminus Z) \to \pi_0(\Sigma \setminus \alpha)$ and $\pi_0(\partial\Sigma \setminus Z) \to \pi_0(\Sigma \setminus \beta)$ be surjective. (An α -bordered diagram is defined similarly, mutatis mutandis.) One constructs a bordered sutured manifold (M, Γ, \mathcal{Z}) from \mathcal{H} as follows. The three-manifold M is obtained by attaching two-handles to $\Sigma \times [0, 1]$ along $\alpha \times \{1\}$ and $\beta^c \times \{0\}$ circles; the dividing set Γ appears as $\Gamma = (\partial\Sigma \setminus Z) \times \{\frac{1}{2}\}$, and $F(\mathcal{Z})$ is a neighborhood of $(Z \times [0, 1]) \cup (\beta^a \times \{0\})$. Another way to view (M, Γ, \mathcal{Z}) as coming from \mathcal{H} , which fits better with Morse theory, is to also attach 'halves of two-handles' along $\beta^a \times \{0\}$ and see $F(\mathcal{Z})$ as $Z \times [0, 1]$ together with the intersection of the thickened cores of the partial two-handles with ∂M .

Let **x** and **y** denote tuples of intersection points between the α and β such that each α -circle is used exactly once, each β -circle is used exactly once, and each β -arc is used no more than once; these will ultimately be the generators of the bordered sutured modules. We recall that the set of homology classes $\pi_2(\mathbf{x}, \mathbf{y})$ connecting **x** to **y** is defined as follows. We let $I_s = [0, 1]$ and $I_t = [-\infty, \infty]$ be intervals and consider the relative homology group

$$H_2(\Sigma \times I_s \times I_t, ((\boldsymbol{\alpha} \times \{1\}) \cup (\boldsymbol{\beta} \times \{0\}) \cup (Z \times I_s)) \times I_t), (\mathbf{x} \times I_s \times \{-\infty\}) \cup (\mathbf{y} \times I_s \times \{\infty\})).$$

The set $\pi_2(\mathbf{x}, \mathbf{y})$ denotes elements of this group which are sent to the fundamental class of $(\mathbf{x} \times I_s) \cup (\mathbf{y} \times I_s)$ by the map which applies the boundary homomorphism and then collapses the remainder of the boundary. Any homology class has a unique corresponding *domain*, that is, a linear combination of the components of $\Sigma \setminus (\alpha \cup \beta)$ obtained by projection. A domain is *provincial* if its boundary has no intersection with *Z*.

The set $\pi_2(\mathbf{x}, \mathbf{x})$ is the set of *periodic domains*. We recall that \mathcal{H} is said to be *provincially admissible* if every provincial periodic domain has both positive and negative coefficients and *admissible* if every periodic domain has both positive and negative coefficients.

To a provincially admissible β -bordered Heegaard diagram $\mathcal{H} = (\Sigma, \alpha, \beta, \mathcal{Z})$ equipped with an admissible almost complex structure, Zarev associates a left type D module $\widehat{BSD}(\mathcal{H})$ over $\mathcal{A}(-\mathcal{Z})$ and right type A module $\widehat{BSA}(\mathcal{H})$ over $\mathcal{A}(\mathcal{Z})$. In both cases, the generators are tuples of intersection points as described above.¹ The type A chain homotopy equivalence class of $\widehat{BSA}(\mathcal{H})$ is an invariant of the associated bordered sutured manifold (M, Γ, \mathcal{Z}) , written $\widehat{BSA}(M, \Gamma, \mathcal{Z})$. More precisely, given bordered

¹We assume we are in the nondegenerate case of having a nonempty set of generators. In particular, $|\alpha| \ge |\beta^c|$.

sutured Heegaard diagrams \mathcal{H} and \mathcal{H}' for (M, Γ, \mathcal{Z}) , there is a sequence of Heegaard moves connecting them as in [Zar09, Proposition 4.5], which induce a type *A* homotopy equivalence *f* from $\widehat{BSA}(\mathcal{H})$ to $\widehat{BSA}(\mathcal{H}')$. This type *A* homotopy equivalence is a collection of maps

$$f_i:\widehat{BSA}(\mathcal{H})\otimes\mathcal{A}(\mathcal{Z})^{\otimes(i-1)}\to\widehat{BSA}(\mathcal{H}')$$

indexed by $i \ge 1$, satisfying certain conditions (see [LOT18, Section 2]). Consider $\mathbf{x} \in \widehat{BSA}(\mathcal{H})$ and $\mathbf{x}' \in \widehat{BSA}(\mathcal{H}')$ so that

$$m_{i+1}(\mathbf{x}, a_1, \cdots, a_i) = 0$$
 and $m_{i+1}(\mathbf{x}', a_1, \cdots, a_i) = 0$

for all $i \ge 0$ and $a_i \in \mathcal{A}(\mathcal{Z})$. We say **x** and **x**' are *equivalent* if there exists a homotopy equivalence f from $\widehat{BSA}(\mathcal{H})$ to $\widehat{BSA}(\mathcal{H}')$ so that $f_1(\mathbf{x}) = \mathbf{x}'$ and $f_{i+1}(\mathbf{x}, a_1, \dots, a_i) = 0$ for all i > 0 and $a_i \in \mathcal{A}(\mathcal{Z})$. Similarly, there is a type D homotopy equivalence from $\widehat{BSD}(\mathcal{H})$ to $\widehat{BSD}(\mathcal{H}')$. If $\mathbf{x} \in \widehat{BSD}(\mathcal{H})$ and $\mathbf{x}' \in \widehat{BSD}(\mathcal{H}')$ are both closed elements (meaning that $\delta^1(\mathbf{x}) = \delta^1(\mathbf{x}') = 0$), we say **x** and **x**' are *equivalent* if there is a homotopy equivalence from $\widehat{BSD}(\mathcal{H})$ to $\widehat{BSD}(\mathcal{H}')$ that maps **x** to **x**'.

Given two bordered sutured manifolds (M_1, Γ_1, Z) and $(M_2, \Gamma_2, -Z)$, we may glue along Z to obtain a sutured manifold (M, Γ) . Given β -bordered sutured Heegaard diagrams $\mathcal{H}_1 = (\Sigma_1, \alpha_1, \beta_1, Z)$ for (M_1, Γ_1, Z) and $\mathcal{H}_2 = (\Sigma_2, \alpha_2, \beta_2, -Z)$ for $(M_1, \Gamma_1, -Z)$, there is a glued Heegaard diagram $\mathcal{H} = (\Sigma, \alpha, \beta)$, where $\Sigma = \Sigma_1 \bigcup_Z \Sigma_2$; the set α is the union of α_1 and α_2 and the set β is the union of β_1 and β_2 , together with the circles formed by gluing the arcs in β_1^a and β_2^a along their endpoints on Z.

When at least one of the two diagrams is admissible, there is a gluing map

$$\bar{BSA}(\mathcal{H}_1) \boxtimes_{\mathcal{A}(\mathcal{Z})} \bar{BSD}(\mathcal{H}_2) \to SFC(\mathcal{H})$$

which induces a chain homotopy equivalence of vector spaces. Chain homotopy equivalences of type A and type D modules induce chain homotopy equivalences of the box tensor product, so there is a well-defined equivalence class of \mathbb{F}_2 vector spaces $\widehat{BSA}(M_1, \Gamma_1, \mathcal{Z}) \boxtimes_{\mathcal{A}(\mathcal{Z})} \widehat{BSD}(M_2, \Gamma_2, -\mathcal{Z})$ and an equivalence of chain homotopy equivalence classes of vector spaces

$$\overline{BSA}(M_1, \Gamma_1, \mathcal{Z}) \boxtimes_{\mathcal{A}(\mathcal{Z})} \overline{BSD}(M_2, \Gamma_2, -\mathcal{Z}) \to SFC(M, \Gamma).$$

2.3. Abstract foliated open books

In this section, we provide an overview of the essential definitions and properties of foliated open books that we will rely on in the remainder of this article. Readers are encouraged to see [LV20] for more detail.

Definition 2.4. [LV20, Definition 3.14] An *abstract foliated open book* is a tuple $(\{S_i\}_{i=0}^{2k}, h)$, where S_i is a surface with boundary $\partial S_i = B \cup A_i^2$ and corners at $E = B \cap A_i$ such that

- 1. for all i, A_i is a union of intervals;
- 2. with the boundary orientation, each component *I* of A_i is oriented from a corner labeled $e_+ = e_+(I) \in E_+$ to a corner labeled $e_- = e_-(I) \in E_-$, and $E = E_+ \cup E_-$;
- 3. the surface S_i is obtained from S_{i-1} by either
 - (add): attaching a one-handle along two points $\{p_{i-1}, q_{i-1}\} \in A_{i-1}$, or
 - (cut): cutting S_{i-1} along a properly embedded arc γ_i with endpoints in A_{i-1} and then smoothing.³

Furthermore, $h: S_{2k} \to S_0$ is a diffeomorphism between cornered surfaces that preserves *B* pointwise.

We denote by H_+ (resp. H_-) the set of indices *i* for which S_i is obtained from S_{i-1} by cutting (resp. adding) so that we have a partition $[2k] = H_+ \cup H_-$. (Here [n] denotes the set $\{1, \ldots, n\}$.)

²By a slight abuse of notation we denote the "constant" part of the boundary of S_i by B for all i.

³The indices of γ_i in this paper are shifted compared to [LV20], where the cutting arcs were denoted by γ_{i-1} .



Figure 2.2. Left: a hyperbolic singularity. Center: a positive elliptic singularity. Right: a regular foliation on an open set.

Note that the operations (add) and (cut) are inverses of each other. Let γ denote the cocore of a handle attached along points *p* and *q*. Then cutting along γ cancels the handle attachment and vice versa. We will use the following notation to describe this:

$$S \xrightarrow{\text{add}} P, q S' \text{ and } S' \xrightarrow{\text{cut}} S.$$

Example 2.5. Figure 2.1 shows a first example of a foliated open book. The complete set of labels is shown for the indicative page S_0 , while the attaching spheres and cutting arcs are shown on all pages to the right. The binding is shown in bold. The monodromy $h: S_4 \rightarrow S_0$ is the identity, and we have the partition $H_- = \{2, 4\}, H_+ = \{1, 3\}.$

2.3.1. Supported contact structures

The construction of a compact manifold is natural from the data of a foliated open book: Pairs of successive pages define cornered cobordisms. As described in more detail below, we concatenate these to form a manifold with boundary and collapse the resulting components of $B \times I$ to circles and intervals again labeled *B*. The final page glues to the initial page via *h*. The resulting manifold *M* associated to the foliated open book $({S_i}_{i=0}^{2k}, h)$ retains partial information about the sequence of cuts and adds in the abstract data. This information is encoded in the form of boundary decorations on ∂M , and we introduce the kind of foliation we will consider before explaining how it arises.

Definition 2.6. A *signed singular foliation* is an equivalence class of smooth vector fields (up to multiplication by smooth positive functions) that vanish at only finitely many isolated points, called *singular points*. The complement of the singular points has an open cover such that in each ball, the integral curves of the vector field are a product of oriented intervals, while elliptic and four-pronged hyperbolic singularities patch these charts together. Elliptic singularities may be classified as positive (sources) or negative (sinks), and the hyperbolic singularities have signs determined by input external to the defining vector field.

See Figure 2.2 for local models of the integral curves.

As is standard, leaves that enter (or exit) the hyperbolic singularities are called *stable (or unstable) separatrices*.



Figure 2.3. The elementary cobordism associated to cutting S_{i-1} along γ_i , shown before collapsing $B \times I$.

Each elliptic point e induces a cyclic order on the subset of hyperbolic points with separatrices terminating at e. If e is positive (respectively, negative), the order increases as the separatrices are encountered in a counterclockwise (clockwise) path around e.

Definition 2.7. A signed singular foliation is *ordered* if there is a cyclic order on the set of all hyperbolic points which is compatible with the cyclic orders associated to each of its elliptic points.

Beginning with an abstract foliated open book, we now build a manifold whose boundary is naturally equipped with an ordered signed singular foliation. Each pair of successive pages defines an elementary cobordism M_i from S_{i-1} to S_i with vertical boundary $(B \times I) \cup V_i$, where V_i is the union of a single saddle and of the collection of products $A_{i-1} \times I$ for any components A_{i-1} that are left unchanged. More specifically, the saddle connects either the components of A_{i-1} containing the endpoints of γ_i or the component(s) containing p_{i-1} and q_{i-1} with the obtained component(s) of A_i that have the same endpoints. See Figure 2.3.

Concatenating these M_i and gluing the final S_{2k} to the initial S_0 via h yields a manifold with boundary $(B \times S^1) \cup V$, where V is the (circular) union of the V_i . The singular foliation on V has 2k singular points associated to the transitions between topological types of the pages, while the regular leaves may be identified with curves of the form $A_i \times \{t\}$. If $S_{i-1} \xrightarrow{\text{add}} S_i$, then the corresponding hyperbolic point h_i is negative; otherwise, it is positive. We denote the set of hyperbolic points with respect to this partition $H = H_+ \cup H_-$. The signs match the partition of [2k] introduced after Definition 2.4. Collapsing the components $B \times S^1$ to a single copy of B yields a manifold with foliated boundary $(M, \partial M, \mathcal{F})$. (See Definition 2.9, below, for a precise definition of this term.) Each endpoint of B labeled e_+ becomes a positive elliptic point of the foliation, which we again denote by e_+ ; likewise, an endpoint e_- becomes

Example 2.8. We return to the foliated open book introduced in the first example. The associated smooth manifold is the solid torus shown in Figure 2.4. The images of A_1 and A_2 are shown in green and blue, respectively, on both the manifold on the left and in the associated boundary foliation on the right.

In order to define the compatibility between contact structures and foliated open books, we examine the boundary foliation \mathcal{F} more closely. To any smooth manifold constructed as above, we may associate an S^1 -valued Morse function $\pi: M \setminus B \to S^1$ whose level sets are the pages of the open book and which restricts to the boundary as an S^1 -valued Morse function $\tilde{\pi} := \pi|_{\partial M} : \partial M \setminus E \to S^1$ with the same critical points as π . The function π has only index 1 and 2 critical points, and all of these are index 1 critical points for $\tilde{\pi}$. The index with respect to π is visible in the sign of these hyperbolic points: index 2 critical points of π give positive hyperbolic points of the foliation, while index 1 critical points of π give negative hyperbolic points of the foliation. Heuristically, this means that the interesting features of π may all be seen from the foliation on the boundary. One may build a signed singular foliation simply by patching together the local models of Figure 2.2, but in the context of this paper we will only encounter ordered signed singular foliations; equivalently, these are signed singular foliations that can be induced



Figure 2.4. The smooth manifold (a solid torus) associated to the foliated open book from Figure 2.1 together with the foliation \mathcal{F} on ∂M .

by an S^1 -valued Morse function. We therefore consider the map $\tilde{\pi}$ to be an essential part of the data and we write $\mathcal{F} = (\tilde{\pi}, H = H_- \cup H_+, E = E_- \cup E_+)$. We may also assume that 0 is a regular value of $\tilde{\pi}$, and we further require that $\tilde{\pi} = \pm \phi$ on an (r, ϕ) -disk neighborhood of each elliptic point $e \in E$, where the sign depends on the sign of the elliptic point. Here, (r, ϕ) is the standard polar coordinate system on D^2 . By construction, the foliation on a manifold constructed from an abstract foliated open book has only elliptic and four-pronged hyperbolic singularities, with signs inherited from the partitions of E and H.

Definition 2.9. A *manifold with foliated boundary* is a compact oriented three-manifold equipped with an ordered signed singular foliation $\mathcal{F} = (\tilde{\pi}, H = H_- \cup H_+, E = E_- \cup E_+)$ on its boundary. We denote this collection of data by $(M, \partial M, \mathcal{F})$.

We recall that these data include the S^1 -valued Morse function $\tilde{\pi}$, and we require that a diffeomorphism $f: (M_1, \partial M_1, \mathcal{F}_1) \to (M_2, \partial M_2, \mathcal{F}_2)$ between manifolds with foliated boundary must satisfy $\tilde{\pi}_2 \circ f = \tilde{\pi}_1$.

We have seen that an abstract foliated open book gives rise to a diffeomorphism class of manifolds with foliated boundary; we say a manifold with foliated boundary is *compatible* with $(\{S_i\}, h)$ if it is diffeomorphic to an output of this construction. A fixed manifold with foliated boundary will admit many different functions π extending the Morse function $\tilde{\pi}$ on the boundary, but compatibility identifies an equivalence class of such functions whose level sets are diffeomorphic to the pages $\{S_i\}$.

Definition 2.10. Suppose that $\mathcal{F} = (\tilde{\pi}, H = H_- \cup H_+, E = E_- \cup E_+)$ is a signed singular foliation with no S^1 leaves. We define $R_+(\mathcal{F})$ to be a closed neighborhood of the union of the stable separatrices of hyperbolic points in H_+ , and let $R_-(\mathcal{F}) = \overline{M \setminus R_+(\mathcal{F})}$. The *dividing curve* $\Gamma(\mathcal{F})$ of \mathcal{F} is $\partial R_+(\mathcal{F}) = -\partial R_-(\mathcal{F})$.

Note that the serifed symbol Γ used here is distinct from the sans-serif symbol Γ introduced in Section 2.2.2 as part of the defining data of a bordered sutured manifold. The above construction of $\Gamma(\mathcal{F})$ follows the construction of Giroux [Gir00] for dividing curves of characteristic foliations of convex surfaces and in our case too $\Gamma(\mathcal{F})$ indeed divides \mathcal{F} : $\Gamma(\mathcal{F})$ is positively transverse to the leaves of \mathcal{F} and it separates $\partial M \setminus \Gamma(\mathcal{F})$ into two parts, one of which contains all the positive singular points, while the other part contains all the negative singular points.⁴ These properties in fact specify $\Gamma(\mathcal{F})$ up to isotopy transverse to \mathcal{F} , and we will often work with its equivalence class, only specifying the representative

⁴Readers concerned that we have not addressed a third condition for dividing curves, regarding the divergence of the foliation, are referred to Lemma 2.6 of [LV20].



Figure 2.5. Left: A foliation on S^2 with four elliptic points and two hyperbolic points. Right: A foliation on S^2 with two elliptic points. The dividing set for each foliation is a circle.

when needed. The choice of the representative then changes $R_+(\mathcal{F})$ and $R_-(\mathcal{F})$ accordingly, while still preserving the condition that $\Gamma(\mathcal{F}) = \partial R_+(\mathcal{F}) = -\partial R_-(\mathcal{F})$. Note that distinct foliations on ∂M may induce isotopic dividing sets; see Figure 2.5.

Definition 2.11. Two ordered signed singular foliations \mathcal{F}_1 and \mathcal{F}_2 on a surface Σ are *strongly topologically conjugate* if there is an isotopy taking \mathcal{F}_1 to \mathcal{F}_2 which respects the cyclic orders on the hyperbolic points.

The term 'topological' refers to the fact that the above isotopy may not be smooth. In fact, in the next definition, the isotopy cannot be chosen to be smooth.

Definition 2.12. [LV20, Definition 3.8, 3.10] A contact structure ξ_0 on a manifold with foliated boundary $(M, \partial M, \mathcal{F})$ is *strictly supported* by the abstract foliated open book $(\{S_i\}, h)$ if there is a diffeomorphism $f: (M', \partial M', \mathcal{F}') \to (M, \partial M, \mathcal{F})$, where $(M', \partial M', \mathcal{F}')$ is a manifold constructed from $(\{S_i\}, h)$ as above such that the pullback $f^*\xi$ is the kernel of some contact one-form α on M' satisfying the following conditions:

- 1. $\alpha(TB) > 0;$
- 2. for all t, $d\alpha|_{\pi^{-1}(t)}$ is an area form; and
- 3. for each pair of consecutive hyperbolic points at times t_1 and t_2 , there is a time t_* such that $t_1 < t_* < t_2$ with the property that the regular leaf $\tilde{\pi}^{-1}(t_*)$ of \mathcal{F} is Legendrian.

A contact structure ξ_1 is *supported* by $(\{S_i\}, h)$ if there exists a path of contact structures ξ_t such that ξ_0 is strictly supported by $(\{S_i\}, h)$ and for all *t*, the characteristic foliation \mathcal{F}_{ξ_t} is strongly topologically conjugate to the characteristic foliation \mathcal{F}_{ξ_0} .

Definition 2.13. A *foliated contact three-manifold* (M, ξ, \mathcal{F}) is a manifold with foliated boundary together with a contact structure ξ on M such that \mathcal{F} is strongly topologically conjugate to \mathcal{F}_{ξ} .

Theorem 2.14. [LV20, Theorems 3.12, 7.1, 7.2] Any foliated open book with circle-free boundary foliation supports a unique isotopy class of contact structures, and any foliated contact three-manifold (M, ξ, \mathcal{F}) admits a supporting foliated open book.

Remark 2.15. Because the signed singular foliation \mathcal{F} data include a function $\tilde{\pi}$, a foliated contact three-manifold has a distinguished t = 0 leaf, which we always assume to be regular.

Distinct foliations may induce isotopic dividing sets, as illustrated in the following example.

Example 2.16. Let $(B^3, \xi_1, \mathcal{F}_1)$ and $(B^3, \xi_2, \mathcal{F}_2)$ be two foliated contact three-balls with ξ_1 and ξ_2 tight, and with the foliations \mathcal{F}_1 and \mathcal{F}_2 on the boundaries as in Figure 2.5. The two three-balls are equivalent in the sense that there is a contact embedding of one into the other with the property that the image of the embedded boundary is convexly isotopic to the boundary of the target manifold. This notion is an equivalence relation on contact manifolds with boundary, yet the given balls are distinct as foliated contact manifolds.

2.3.2. Stabilization

Although each foliated open book supports a unique isotopy class of contact structures, there are many foliated open books which support the same class. Next, we define an operation which changes a foliated open book while preserving the contactomorphism class of the associated contact manifold.

Definition 2.17. Let $\gamma \subset S_0$ be a properly embedded arc with $\partial \gamma \subset B$. The *stabilization of* $(\{S_i\}, h)$ along γ is the foliated open book $(\{S'_i\}, h')$ defined as follows:

- $S'_i = S_i \cup H$, where *H* is a one-handle attached along $\partial \gamma$; and
- $h' = \tau \circ \overline{h}$, where τ is a positive Dehn twist along the circle formed by γ and the core of H. (Here, \overline{h} denotes the extension of *h* to *H* by the identity.)

In order to define stabilization along some arc in a page besides S_0 , we first describe an operation on foliated open books which preserves the contactomorphism type of the associated manifold.

Definition 2.18. [LV20, Definition 3.16] The 1-shift of an abstract foliated open book $(\{S_i\}_{i=0}^{2k}, h)$ is the foliated open book

$$({S_i[1]}_{i=0}^{2k}, h[1]) = ({S_1, S_2, \dots, S_{2k}, S'_1}, h'),$$

where

- if $S_0 \xrightarrow[\gamma_1]{\gamma_1} S_1$, then S'_1 is defined by the relation $S_{2k} \xrightarrow[h^{-1}(\gamma_1)]{\lambda'_1} S'_1$ and h' is the restriction of h to S'_1 ; if $S_0 \xrightarrow[\rho_0, q_0]{add} S_1$, then S'_1 is defined by the relation $S_{2k} \xrightarrow[h^{-1}(\rho_0), h^{-1}(q_0)]{\lambda'_1}$ and h' is h extended by the
- identity on the added one-handle.

An *r*-fold iteration of the shift operation is called an *r*-shift and denoted by $(\{S_i[r]\}_{i=0}^{2k}, h[r])$. One can analogously define *r*-shifts for r < 0.

Shifts correspond to postcomposing π with a diffeomorphism of S^1 .

Definition 2.19. Let $\gamma \subset S_r$ be a properly embedded arc with $\partial \gamma \subset B$. The stabilization of $(\{S_i\}, h)$ along $\gamma \subset S_r$ is the foliated open book $(\{S'_i\}, h')$ defined as follows:

- 1. first perform an *r*-shift of $(\{S_i\}, h)$ to $(\{S_i[r]\}, h[r])$;
- 2. stabilize as in Definition 2.17 along the image of $\gamma \subset S_0[r]$;
- 3. perform a (-r)-shift to obtain $(\{S'_i\}, h')$, where S'_i is still obtained from S_i by a handle attachment along p and q.

It is easy to see that stabilizing does not change the underlying manifold with foliated boundary.

Theorem 2.20. [LV20, Proposition 6.8, Theorem 6.9] Let $(\{S_i\}, h)$ be a foliated open book and $(\{S'_i\}, h')$ be a positive stabilization of $(\{S_i\}, h)$. Then the corresponding contact three-manifolds are contactomorphic. Furthermore, if two foliated open books support contactomorphic foliated contact three-manifolds, then they admit a common positive stabilization.

2.3.3. Sorted foliated open books

Next, we introduce some additional bookkeeping to record the cutting arcs and cocore arcs on all possible pages of the foliated open book. This additional information corresponds to a choice of a gradient-like vector field for π on the associated smooth manifold, as we will describe in Section 2.3.4.



Figure 2.6. The first three pages of the foliated open book from Example 2.5.

If $S_{i-1} \xrightarrow{\text{add}} S_i$, then for all $j \ge i$, decorate S_j with a cocore of the added handle and label this cocore γ_i^- . If $S_{i-1} \xrightarrow{\text{cut}} S_i$ along $\gamma \subset S_{i-1}$, then for all $j \le i - 1$, decorate S_j with the cutting curve and label it γ_i^+ .

We call the γ_i^{\pm} sorting arcs. Note that by an abuse of notation we use a single label γ_i^{\pm} to refer to distinct copies of the sorting arcs on multiple S_j . In general, sorting arcs may intersect (and consequently some sorting arcs may appear as a union of disconnected intervals on some pages). We will shortly restrict to the subclass of *sorted* foliated open books [LV20, Section 5.3], which are characterized by the requirement that the sorting arcs are disjoint on all pages, together with a prescribed ordering of the intersections between sorting arcs and regular leaves. In the sorted case, we enhance the notation for describing a foliated open book to reflect these additional choices.

Definition 2.21. An abstract foliated open book $(\{S_i\}, h, \{\gamma_i^{\pm}\})$ is *sorted* if the following properties hold:

- 1. On each page S_i and for each component I of A_i with $\partial I = \{e_+, e_-\}$, there exist disjoint subintervals I_+ and I_- such that I_+ contains $e_+ \cup \bigcup_j (\gamma_i^+ \cap I)$ and I_- contains $e_- \cup \bigcup_j (\gamma_i^- \cap I)$.
- 2. For i < j < l, on each component of A_i any endpoint of γ_l^+ is closer to e_+ than any endpoint of γ_i^+ ;
- 3. For $j < l \le i$, on each component of A_i any endpoint of γ_l^- lies closer to e_+ than any endpoint of γ_i^- ;
- 4. On each page, the sorting arcs are connected, properly embedded, and disjoint.

See Figure 2.7 in Example 2.24 for an illustration of the ordering conventions given above. Sorted foliated open books are useful because of their close relation to partial open books, which will be described in Section 2.3.5. Below, we show that a foliated open book need not be sorted.

Example 2.22. The foliated open book from Example 2.5 is not sorted. To see this, we start on the S_0 page and attempt to decorate each successive page with cutting arcs which realize the topological transitions between pages and whose endpoints also satisfy the ordering conditions of Definition 2.21.

Cutting along γ_1^+ on S_0 yields S_1 , while attaching a handle to S_1 gives rise to S_2 , which is decorated with the new cocore γ_2^- . However, any cutting arc associated to h_3 necessarily intersects γ_2^- on S_2 , as the endpoints of γ_3^+ must lie closer to the positive ends of A_2 than the endpoints of γ_2^- . Thus, the foliated open book is not sorted. See Figure 2.6.

We may always stabilize a foliated open book to obtain a sorted one.

Theorem 2.23. Any foliated contact three-manifold (M, ξ, \mathcal{F}) admits a supporting sorted foliated open book. If two sorted foliated open books support the same foliated contact three-manifold, then we can stabilize each through sorted foliated open books to obtain a common sorted foliated open book. Moreover, all of these stabilizations can be assumed to be performed on the S₀ page as in Definition 2.17.

Proof. The first two statements are taken from [LV20, Theorem 3.12, Proposition 8.4, Theorem 8.14]. The final claim that the necessary stabilizations may be assumed to occur on the S_0 page is implicit in [LV20], as explained next; we include the brief argument here, although it relies on the connection between foliated and partial open books described in Section 2.3.5. Specifically, the proof of [LV20,



Figure 2.7. The stabilization arc $\gamma \subset S_0$ is chosen to have one endpoint on each interval of the binding *B* so that it crosses each of of the intersecting sorting arcs in Figure 2.6 exactly once. There is a right-handed Dehn twist identifying the two copies of the S'_2 page, while the monodromy $h': S'_4 \to S'_0$ is translation in the plane of the page. The sorting arcs γ^+ are shown in light blue, and the sorting arcs γ^- are shown in dark blue. Subintervals $I_{\pm} \subset A_0$ are highlighted in green and orange on S_0 and may be chosen analogously on the other pages.

Proposition 8.6] explains why stabilizations on the S_0 page suffice to turn an arbitrary sorted foliated open book into a sufficiently stabilized⁵ foliated open book. The proof that two sufficiently stabilized open books admit a common stabilization relies on Giroux correspondence for the associated partial open books and, hence, leads again to stabilizations on S_0 .

Example 2.24. Figure 2.7 shows that the foliated open book from Example 2.5 may be stabilized to a sorted foliated open book. Starting from index S_0 , the first obstruction to being sorted occurred as an intersection between γ_2^- and γ_3^+ on S_2 . This intersection may be removed by stabilizing 'at' the S_2 page; that is, by shifting twice and then stabilizing at the new S_0 . Each new page is obtained from the corresponding old page by attaching a one-handle with one attaching interval on each binding component. The new final maps to the new initial page by a positive Dehn twist; after shifting back, this becomes a positive Dehn twist identifying the two copies of the S'_2 page, as shown. Thus, γ_2^- changes by a positive Dehn twist as it ascends to higher-index pages, while γ_3^+ changes by a negative Dehn twist as it descends to lower-index pages.

When depicting a sequence of pages, there is an implicit identification by translation in the page unless otherwise noted. In this example, the one nontranslation occurs at S'_2 while the map from S'_4 to S'_0 remains translation in the plane of the page, as seen on Figure 2.7. The result is a sorted foliated open book for the original contact manifold with foliated boundary.

2.3.4. Gradient flows on foliated open books

As in Section 2.3.1, we consider the smooth manifold with foliated boundary $(M, \partial M, \mathcal{F})$ constructed from a foliated open book. The initial abstract data determines an equivalence class of circle-valued Morse functions $\pi: M \setminus B \to S^1$ [LV20, Section 5.2]. The level sets of π are the pages, and the restriction $\tilde{\pi}: \partial M \setminus B \to S^1$ is again a circle-valued Morse function with the same set of critical points. In this setting, one may consider the critical submanifolds of a gradient-like vector field for π parallel to ∂M , which thus restricts to a gradient-like vector field for $\tilde{\pi}$. The intersection of the critical submanifolds with the regular level sets of π determines sorting arcs on the pages of the corresponding abstract foliated open book [LV20, Section 5.3]. Thus, a foliated open book is sorted when a gradient-like vector field on Mwhose critical submanifolds are disjoint.

⁵This subclass consists of the foliated open books which can most easily be related to partial open books, a relationship which we discuss shortly.



Figure 2.8. The tile of \mathcal{F} shows purple flowlines of $\nabla \tilde{\pi}$ which satisfy the sorted ordering conditions.

Any surface with an open book foliation decomposes along regular leaves into square tiles that each contain precisely one hyperbolic singularity. Figure 2.8 shows the flowlines of a preferred $\nabla \tilde{\pi}$ on such a tile; these flowlines satisfy the ordering conditions in Definition 2.21, although ensuring their extension to M yields a sorted foliated open book may require stabilization.

The Morse perspective is useful not only for building geometric intuition but also for relating the boundary decorations to those in the interior of the manifold. For example, a sorting arc γ_i^+ is isotopic through the associated stable critical submanifold of $\nabla \pi$ to the stable submanifold of $\nabla \pi$ on ∂M which passes through the corresponding positive hyperbolic point h_i . Likewise, a sorting arc γ_i^- is isotopic through the associated unstable critical submanifold of $\nabla \pi$ to the unstable submanifold of $\nabla \pi$ on ∂M which passes through the corresponding negative hyperbolic point h_i . Conditions 1, 2 and 3 in Definition 2.21 are chosen so that the graphs formed by the (un)stable separatrices of positive (negative) hyperbolic points with respect to \mathcal{F} and with respect to $\nabla \pi$ are isotopic. See [LV20, Lemma 8.8]. In the next section, this will allow us to define certain subsurfaces as neighborhoods of either graph.

2.3.5. Sufficiently stabilized foliated open books and the associated partial open book

Sorted foliated open books are closely related to partial open books, and [LV20] introduced the technical designation of a 'sufficiently stabilized' foliated open book. In this section, we recall this definition and show that a sufficiently stabilized foliated open book naturally has a companion partial open book. Throughout this section, we will let $(\{S_i\}_{i=0}^{2k}, h, \{\gamma_i^{\pm}\})$ be a sorted foliated open book and (M, ξ, \mathcal{F}) be the supported foliated contact three-manifold. We further assume that either k > 0 or $|\partial M| > 1$; the only foliated open books this excludes are those formed from an honest open book by removing a neighborhood of a single point on the binding.

Set

$$R_i = N_{\lrcorner} (A_i \cup (\bigcup_{i < j} \gamma_j^+) \cup (\bigcup_{i \ge j} \gamma_j^-)) \subset S_i,$$

where N_{\downarrow} denotes a 'cornered' neighborhood of $A_i \cup (\bigcup_{i < j} \gamma_j^+) \cup (\bigcup_{i \ge j} \gamma_j^-)$, with corners at *E* so that R_i meets *B* only at *E*. Furthermore, define

$$P_i = \overline{S_i \setminus R_i},$$

as shown on the left in Figure 2.9. Since only the R_i change with *i*, we can identify all the P_i with each other by the flow of the gradient-like vector field. We denote the composition of these identifications from $P_0 \subset S_0$ onto $P_{2k} \subset S_{2k}$ by ι . Let $\tilde{S} = S_0$, $\tilde{P} = P_0$ and $\tilde{h} = h|_{P_{2k}} \circ \iota$.

Definition 2.25. [LV20, Proof of Proposition 8.6] The sorted foliated open book $(\{S_i\}_{i=0}^{2k}, h, \{\gamma_i\})$ is *sufficiently stabilized* if each component of P_0 intersects the boundary of R_0 in at least two intervals.



Figure 2.9. The shaded regions show the cornered neighborhoods R''_i in each page of the sufficiently stabilized open book. As in Example 2.24, successive pages are identified by translation except for the right-handed Dehn twist τ at S''_2 .

This condition ensures that $(\tilde{S}, \tilde{P}, \tilde{h})$ is a partial open book whose pages embed into the pages of $(\{S_i\}_{i=0}^{2k}, h, \{\gamma_i\})$. As the term suggests, this condition may always be achieved by a sequence of positive stabilizations, and in fact, these may be chosen to occur on the S_0 page.

Theorem 2.26. [LV20, Proposition 8.10] With the notation above, the partial open book $(\tilde{S}, \tilde{P}, \tilde{h})$ is compatible with a contact manifold $(\tilde{M}, \tilde{\xi})$ which is contactomorphic to (M, ξ) . Furthermore, under this contactomorphism, the image of the dividing set of the characteristic foliation of ξ on ∂M divides $\tilde{\mathcal{F}}$.

Example 2.27. In this example, we return to the foliated open book of Example 2.24, which is not sufficiently stabilized. Recall that R'_0 is constructed as a cornered neighborhood of the sorting arcs together with A'_0 . Observe that $P'_0 := S'_0 \setminus R'_0$ consists of two bigons, each with an edge on *B* and an edge on the annular $\partial R'_0$. It follows that S'_0 cannot be built up from R'_0 by adding one-handles, which is the topological requirement for the surface/subsurface pair to define a partial open book.

Figure 2.9 shows a sufficiently stabilized foliated open book for the same manifold, built by stabilizing along the dotted arc which connected the two components of the binding. The new monodromy is the composition of the original monodromy with a positive Dehn twist along the circle formed by the core of the added handle and the stabilizing arc.

The new $P_0'' := S_0'' \setminus R_0''$ is a single disk whose boundary intersects $\partial R_0''$ along two intervals; this ensures that $(\tilde{S}'', \tilde{P}'', \tilde{h}'')$ is a partial open book. In order to understand \tilde{h}'' , we first examine the flow of P_0'' through the manifold. Recall from Example 2.24 that the only nontrivial identification between successive pages is a right-handed Dehn twist at the S_2'' page before the cut yielding S_3'' . The twist is along the core of the annular R_2'' , so P_4'' is isotopic, relative to $A_4'' = A_0''$, to P_0'' . Thus, the partial open book monodromy is simply the restriction of the foliated open book monodromy to P_4'' .

As shown in [LV20, Lemma 8.12], the cornered diffeomorphism type of the subsurfaces $R_i \subset S_i$ depends only on the foliation \mathcal{F} , rather than on the pages S_i . Construct the corresponding contact threemanifold (M, ξ, \mathcal{F}) for a sorted abstract foliated open book $(\{S_i\}, h, \{\gamma_i^{\pm}\})$. Recall from Definition 2.10 that the subsurface $R_+(\mathcal{F})$ (respectively $R_-(\mathcal{F})$) of ∂M is a closed neighborhood of the (un)stable separatrices corresponding to positive (negative) hyperbolic points of \mathcal{F} .

As noted in Section 2.3.4, the graph of positive separatrices of $\nabla \tilde{\pi}$ from positive hyperbolic points on ∂M is (nonsmoothly) isotopic to the graph of positive separatrices of \mathcal{F} from positive hyperbolic points on ∂M . On the other hand, the former is isotopic through the stable critical submanifolds to a neighborhood of the sorting arcs $\cup_{H_+} \gamma_i^+$ on S_0 . This yields an identification between $R_+(\mathcal{F}) \subset \partial M$ and $R_0 \subset S_0$. Similarly, studying negative separatrices of negative hyperbolic points and unstable critical submanifolds yields an identification between $R_-(\mathcal{F}) \subset \partial M$ and $R_{2k} \subset S_{2k}$.



Figure 2.10. The blue region on the left-hand picture is the cornered neighborhood $R_i \,\subset S_i$. On the right-hand figure, R_i has been isotoped through M in the direction of the indicated arrows to lie mostly on ∂M . The small arrow indicates the half twist which extends into the interior of M. Note that B has been blown up to $B \times I$ for clarity.

Similarly, all the R_i can be identified with surfaces described only using the foliation \mathcal{F} , independently of the foliated open book, as follows. Recall that R_i is the (cornered) neighborhood of the union of A_i and the intersection of all stable and unstable submanifolds of $\nabla \pi$ with S_i . Each of these intersections can be pushed up (or down) onto ∂M along the corresponding stable (or unstable) submanifolds. While performing these isotopies we push the half-neighborhood of A_i up along I_+ and down along I_- ; the surface obtained after the isotopy is not a submanifold of ∂M , as it has a half twist in the middle of each component I of A_i which extends into the interior of M. See Figure 2.10.

2.3.6. Gluing foliated open books

In order to glue foliated open books, we describe the matching conditions imposed upon their boundary foliations. Recall that a foliation \mathcal{F} on a surface F always refers to the data of a signed foliation together with the function $\tilde{\pi}: F \setminus E \to S^1$ whose level sets are the leaves of \mathcal{F} .

Definition 2.28. The *reverse of a foliation* \mathcal{F} on F is the foliation on -F which is equal to \mathcal{F} pointwise but with the leaf orientations and signs of singular points reversed.

The main advantage of foliated open books is that they are well suited for gluing. Suppose that $(M^L, \xi^L, \mathcal{F}^L)$ and $(M^R, \xi^R, \mathcal{F}^R)$ are foliated contact three-manifolds such that there exists an orientation-reversing diffeomorphism $\psi : \partial M^L \to \partial M^R$ that maps the reverse of the foliation \mathcal{F}^L onto \mathcal{F}^R .

Recall that by hypothesis, the boundary foliations are divided, so the boundaries ∂M^{\bullet} are convex with respect to ξ^{\bullet} . (Here, and throughout this section, \bullet will be an element of the set $\{R, L\}$.) Since the contact structures are *I*-invariant near the boundaries, ψ determines a closed contact three-manifold

$$(M,\xi) = (M^L \cup_{\psi} M^R, \xi^L \cup_{\psi} \xi^R).$$

If the initial contact manifolds were supported by foliated open books $(\{S_i^L\}, h^L)$ and $(\{S_i^R\}, h^R)$, respectively, then (M, ξ) naturally inherits a supporting open book whose pages and binding are built by gluing the pages and bindings of the constituent pieces. More precisely, recall that $\partial S_i^{\bullet} = A_i^{\bullet} \cup B^{\bullet}$, where all the B^{\bullet} are identified when forming the manifolds M^{\bullet} . The map ψ identifies the intervals A_i^L and $-A_i^R$ for all *i*, forming the surfaces

$$S_i = S_i^L \bigcup_{A_i^L \xrightarrow{\psi} - A_i^R} S_i^R$$

with boundary $B = B^L \cup B^R$. Observe that a cut to S_i^R pairs with a handle addition to S_i^L , and vice versa, so the surfaces S_i are diffeomorphic for all *i*. This allows us to identify $S_0 \cong S_1 \cong \cdots \cong S_{2k}$, and we denote the composition of these identifications by $\iota: S_0 \to S_{2k}$. Note that ι fixes *B*, and it restricts to P_0^{\bullet} as the identification $\iota^{\bullet}: P_0^{\bullet} \to P_{2k}^{\bullet}$ defined in Section 2.3.5. Letting $S := S_0$, the monodromy $h: S \to S$ for the glued-up open book can be obtained as the composition of ι with $h^L \cup h^R: S_{2k} = S_{2k}^L \cup S_{2k}^R \to S_0^L \cup S_0^R = S_0$. By construction, *h* fixes *B*, as required.

Theorem 2.29. [LV20, Theorem 6.2] Suppose that the foliated open books $(\{S_i^L\}, h^L)$ and $(\{S_i^R\}, h^R)$ define the three-manifolds with foliated boundary (M^L, \mathcal{F}^L) and (M^R, \mathcal{F}^R) , and assume that there is an orientation-reversing diffeomorphism $\varphi \colon \partial M^L \to \partial M^R$ that takes the reverse of the foliation \mathcal{F}^L onto \mathcal{F}^R .

Then there are contact structures ξ^L and ξ^R supported by $(\{S_i^L\}, h^L)$ and $(\{S_i^R\}, h^R)$, respectively, so that $\xi = \xi^L \cup_{\varphi} \xi^R$ is a contact structure ξ on the manifold $M = M^L \cup_{\varphi} M^R$ that is supported by the honest open book (S, h) constructed by pagewise gluing, as defined above.

Since $\iota: S_0 \to S_{2k}$ is given as a sequence of identifications, the monodromy h may be difficult to reconstruct in a complicated case, and the above construction does not automatically give a factorization in terms of Dehn twists. For sorted open books, however, there is a straightforward way to describe ι (and thus h) as follows. Suppose now, that $(\{S_i^L\}, h^L, \{\gamma_i^{\pm, L}\})$ and $(\{S_i^R\}, h^R, \{\gamma_i^{\pm, R}\})$ are sorted foliated open books compatible with $(M^L, \xi^L, \mathcal{F}^L)$ and $(M^R, \xi^R, \mathcal{F}^R)$, respectively. Recall that each page S_i^{\bullet} decomposes as the union of a 'constant' part P_i^{\bullet} and an *i*-dependent part R_i^{\bullet} which is determined by the foliation \mathcal{F}^{\bullet} . By construction, $P_0^{\bullet} \cong P_1^{\bullet} \cong \cdots \cong P_{2k}^{\bullet}$. These diffeomorphisms are explicit in the construction of the pages S_i^{\bullet} , and together they determine $\iota|_{P_L^{\circ} \cup P_0^{\circ}} = \iota^L \cup \iota^R : P_0^{\circ} \cup P_0^R \to P_{2k}^L \cup P_{2k}^R$.

As described earlier, sorted foliated open books have the property that R_0^L is isotopic in M^L to $R_+(\mathcal{F}^L)$. This surface is mapped by ψ onto $R_-(\mathcal{F}^R)$, which in turn is isotopic in M^R to R_{2k}^R . The composition of these three maps gives $\iota|_{R_0^L} : R_0^L \to R_{2k}^R$, and we can similarly obtain $\iota|_{R_0^R} : R_0^R \to R_{2k}^L$. This yields a concrete description of the entire map ι on the remaining parts $R_{2k}^L \cup R_{2k}^L$. Together, the above maps determine h everywhere.

3. Construction of the contact invariant

3.1. Bordered manifold associated to a triple

Let (M, ξ, \mathcal{F}) be a foliated contact three-manifold with signed singular foliation $\mathcal{F} = (\tilde{\pi}, H = H_- \cup H_+, E = E_- \cup E_+)$. Set $\Gamma := \tilde{\pi}^{-1}(0)$ so that Γ is a disjoint union of oriented leaves connecting positive to negative elliptic points. For each leaf *I*, let $e_+(I)$ and $e_-(I)$ be the corresponding positive and negative elliptic points, respectively. Choose $\epsilon > 0$ small enough so that $\tilde{\pi}^{-1}[-\epsilon, \epsilon]$ contains no critical points of $\tilde{\pi}$. Note that then $\tilde{\pi}^{-1}[0, \epsilon]$ is a union of disks, one disk containing each leaf $I \subset \Gamma$ and denoted by $R_+(I)$. Similarly, denote the connected component of $\tilde{\pi}^{-1}[-\epsilon, 0]$ containing *I* by $R_-(I)$. Write $R_+(\Gamma) = \bigcup_{I \subset \Gamma} R_+(I)$ and $R_-(\Gamma) = \bigcup_{I \subset \Gamma} R_-(I)$. Set $F = \partial M \setminus (R_+(\Gamma) \cup R_-(\Gamma))$.

Next, we use the foliation to define a natural parametrization of F via an arc diagram $\mathcal{Z} = (Z, a, m)$. For each hyperbolic point h_i , let δ_i be the union of the two stable separatrices at h_i if h_i is positive or the union of the two unstable separatrices at h_i if h_i is negative. Let Z(I) be a pushoff of $\tilde{\pi}^{-1}(-\epsilon) \cap R_-(I) \subset \partial F$ into F satisfying the following:

- $\circ \ \partial Z(I) = (-e_{-}(I)) \cup e_{+}(I).$
- If δ_i has an endpoint at $e_{\pm}(I)$, then Z(I) intersects δ_i in a unique point; otherwise, δ_i and Z(I) are disjoint.

Let $Z = \bigsqcup_{I \subset \Gamma} Z(I)$. Define *a* to be the set of all intersection points of *Z* with the union of the δ_i , and let *m* be the pairing induced on the points in *a* by δ_i . See Figure 3.1. Observe that *Z* divides *F* into two subsurfaces: a surface containing all hyperbolic points (shown in white on Figure 3.1) and a union of disks (shown in dark red on Figure 3.1). Let e_i be the curve that is the intersection of δ_i with the white



Figure 3.1. In this picture, $R_+(\Gamma)$ and $R_-(\Gamma)$ are colored in light blue and light red, respectively. Thus, F is the union of the dark red and white regions. The green curves are Γ , the blue curves are the δ_i so that their intersections with the white surface are the e_i . Furthermore, dark red may be identified with $Z \times [0, 1/2]$ under the identification of F with F(Z), and the e_i may be identified with the parametrizing arcs for Z.

surface. Note that after removing the disks bounded by the circles $I \cup Z(I)$ from F, and decomposing the resulting surface along the union of e_i , we get a disjoint union of disks so that each one of them contains exactly one of the leaves in $\pi^{-1}(\epsilon)$ on its boundary. Thus, $\mathcal{Z} = (Z, a, m)$ parametrizes F as a β -type arc diagram as defined in [Zar10, Definition 3.2]; that is, F can be identified with $F(\mathcal{Z})$.

Definition 3.1. The triple (M, Γ, \mathcal{Z}) described above is the *bordered sutured manifold associated to the foliated contact three-manifold* (M, ξ, \mathcal{F}) .

3.2. Adapted bordered Heegaard diagram

Let $(\{S_i\}_{i=0}^{2k}, h, \{\gamma_i^{\pm}\})$ be an abstract sorted foliated open book compatible with the foliated contact three-manifold (M, ξ, \mathcal{F}) . In what follows, we will describe a generator in a bordered sutured Heegaard diagram $\mathcal{H} = (\Sigma, \beta, \alpha, \mathcal{Z})$ constructed from the data of $(\{S_i\}, h, \{\gamma_i^{\pm}\})$. Let g_i be the genus of S_i , and let n_i be the number of boundary components of S_i . Recall that the boundary of the cornered surface S_i is $B \cup A_i$, where B is a union of circles and arcs, and A_i is a union of intervals only.

We let $\Sigma = S_0 \cup_B -S_0$. In order to distinguish the two copies, we will write

$$\Sigma = S_{\epsilon} \cup_B -S_0,$$

but we emphasize that S_{ϵ} can be identified with S_0 . The surface Σ has genus $2g_0 + n_0 - 1$ and $|A_0|$ boundary components. For $i \in H_+$, let γ_i^+ be the S_{ϵ} copy of the associated sorting arc. The endpoints of γ_i^+ lie near the E_+ end of intervals of A_{ϵ} . Isotope the arcs $\{\gamma_i^+\}$ (simultaneously, to preserve disjointness) near the endpoints by pushing them along $\partial \Sigma$ in the direction opposite the orientation of the boundary until the endpoints all lie in $I_+ \subset A_0$; the isotopy stops after crossing E_+ and before encountering $\cup_{j \in H_-} h(\gamma_i^-) \subset S_0$. Call the resulting arcs β_i^a . For $i \in H_-$, consider the S_{2k} copies of the sorting arcs γ_i^- , and let $\beta_i^a = h(\gamma_i^-)$ on S_0 . Write $\beta^a = \{\beta_1^a, \dots, \beta_{2k}^a\}$. For convenience, instead of β_i^a we will sometimes write β_i^{\pm} if $i \in H_{\pm}$.

For $i \in H_+$, let $b_i^+ = \beta_i^a \cap S_{\epsilon}$. That is, b_i^+ is the arc β_i^a with the two end segments that lie on $-S_0$ removed so that ∂b_i^+ lies on *B*. We claim that after cutting S_{ϵ} along the arcs b_i^+ , each connected component contains at least one interval of A_{ϵ} .

Lemma 3.2. Each component of $S_{\epsilon} \setminus \bigcup_{i \in H_{+}} b_{i}^{+}$ contains an interval component of A_{ϵ} , and hence at least one point in E_{+} , and, equivalently, at least one point in E_{-} .

Proof. Recall that moving along any given interval of A_{ϵ} , we encounter curves γ_i^+ indexed in decreasing order. Thus, after the isotopy, moving along any given interval of B, we encounter curves b_i^+ indexed in decreasing order as well. Now, suppose there is a component C of $S_{\epsilon} \setminus \bigcup_{i \in H_+} b_i^+$ that does not intersect A_{ϵ} . Then the boundary of C consists of possibly some complete binding circles and at least one circle that alternates between intervals of B and entire arcs b_i^+ . Since C is a subsurface of S_{ϵ} , the orientation on B agrees with the orientation on ∂C . When traversing this circle of ∂C , it follows that each interval of B starts at an intersection point with some b_i^+ and ends at an intersection point with some b_j^+ , where j < i, thus inducing a circular < ordering on integral indices, which is a contradiction.

Let $\boldsymbol{b} = \{b_1, \ldots, b_{2g_0+n_0+|A_0|-k-2}\}$ be a set of cutting arcs for $P_{\epsilon} \subset S_{\epsilon}$ disjoint from $\boldsymbol{\beta}^a$ and with endpoints on B so that each connected component of $S_{\epsilon} \setminus (\boldsymbol{b} \cup \boldsymbol{\beta}^a) = S_{\epsilon} \setminus (\boldsymbol{b} \cup \{b_i^+\}_{i \in H_+})$ is a disk with exactly one interval of A_{ϵ} on its boundary. Note that Lemma 3.2 guarantees this can be achieved. In other words, \boldsymbol{b} is a basis for $H_1(P_{\epsilon}, B)$. Recalling the identification $S_{\epsilon} = S_0$, we may push $b_i \subset S_0$ through M to lie on S_0 again and define

$$\beta_i = b_i \cup -h \circ \iota(b_i) \subset S_{\epsilon} \cup_B -S_0,$$

where ι is the identification of P_0 with P_{2k} from Section 2.3.5. Write $\beta^c = \{\beta_1, \ldots, \beta_{2g_0+n_0+|A_0|-k-2}\}$.

Note that by modifying the isotopy that transforms $\{\gamma_i^+\}$ into $\{\beta_i^+\}$, possibly forcing it to happen in a smaller neighborhood of E_+ , we may assume that all curves in $\beta^a \cup \beta^c$ are pairwise disjoint.

For each cutting arc $b_i \in \mathbf{b}$ on S_{ϵ} , let a_i be an isotopic curve formed by pushing the endpoints negatively along the boundary so that a_i and b_i intersect once transversely. Similarly, for each arc b_j^+ , let \tilde{a}_j be an isotopic curve formed by pushing the endpoints negatively along the boundary so that \tilde{a}_j and b_j^+ intersect once transversely. We 'double' each of these arcs to form the α -circles which define the handlebody $S_0 \times [0, \epsilon]$. Namely, define

$$\alpha_i = a_i \cup -a_i \subset S_{\epsilon} \cup_B -S_0$$

$$\widetilde{\alpha}_j = \widetilde{a}_j \cup -\widetilde{a}_j \subset S_{\epsilon} \cup_B -S_0,$$

and write $\alpha = {\widetilde{\alpha}_i}_{i \in H_+} \cup {\alpha_1, \ldots, \alpha_{2g_0+n_0+|A_0|-k-2}}$. Finally, let

$$Z = \left(\bigcup_{I \subset A_{\epsilon}} (I_{+} \cup I_{-})\right) \cup -A_{0} \subset \partial(S_{\epsilon} \cup_{B} -S_{0}) = \partial\Sigma.$$

We obtain $\mathcal{Z} = (Z, \partial \beta, m)$, where *m* matches a pair of points if they belong to the same β -arc, and we get an identification of $G(\mathcal{Z})$ with $Z \cup \beta^a \subset \Sigma$.

We say that a bordered sutured Heegaard diagram constructed as above is *adapted* to the sorted abstract foliated open book $(\{S_i\}, h, \{\gamma_i^{\pm}\})$.

Let $\mathcal{H} = (\Sigma, \alpha, \beta, \mathbb{Z})$ be a bordered sutured Heegaard diagram adapted to $(\{S_i\}, h, \{\gamma_i^{\pm}\})$. Using the notation introduced above, define the set

$$\mathbf{x} = \{x_1, \dots, x_{2g_0 + n_0 + |A_0| - k - 2}\} \cup \{x_i^+ \mid i \in H_+\}$$



Figure 3.2. The sorting arcs γ_i^+ (on the left) and their images β_i^+ (on the right) after the isotopy taking their endpoints to the highlighted subintervals $I_+ \subset A_0$. The parts of β_i^+ lying on S_{ϵ} are b_i^+ .



Figure 3.3. The sorting arcs γ_i^- and their images $\beta_i^- = -h(\gamma_i^-)$ on $-S_0$.



Figure 3.4. Cutting S_{ϵ} along b_i^+ yields two disks, each with exactly one interval of A_{ϵ} on its boundary. *Therefore, we do not need any more cutting arcs.*

as the unique intersection points

$$x_i = a_i \cap b_i \in S_{\epsilon} \subset \Sigma$$

$$x_i^+ = \tilde{a}_i \cap b_i^+ \in S_{\epsilon} \quad \text{if } i \in H_+$$

Example 3.3. We show the step-by-step construction of the bordered sutured Heegaard diagram adapted to the sorted foliated open book from Example 2.24. To simplify notation, we write S_i and h instead of the S'_i and h' labels used in Example 2.24.

In Figure 3.2, we see the sorting arcs γ_i^+ and their images β_i^+ after the isotopy taking their endpoints to $I_+ \subset A_0$. The arcs b_i^+ are the intersections $\beta_i^+ \cap S_{\epsilon}$.

Figure 3.3 shows the sorting arcs γ_i^- on S_0 and, after mirroring, their images $\beta_i^- = -h(\gamma_i^-)$ on $-S_0$; recall that in this example *h* is the identity. Recall that $\beta^a = \{\beta_i^+ \mid i \in H_+\} \cup \{\beta_i^- \mid i \in H_-\}$.

Observe that in this example we do not need any cutting arcs **b** because $S_{\epsilon} \setminus \{b_i^+\}_{i=1,3}$ consists of two disks, each with exactly one interval of A_{ϵ} on its boundary; see Figure 3.4. Therefore, β^c is empty, and we have no a_i arcs, either.



Figure 3.5. The $\tilde{\alpha}_i$ curves obtained from the b_i^+ arcs.



Figure 3.6. The bordered sutured Heegaard diagram adapted to the sorted foliated open book of Example 2.24. The intersection points $x_i^+ = \tilde{a}_i \cap b_i^+ \in S_{\epsilon}$ for $i \in H_+$ are marked as black dots. The black portion of the resulting boundary is Z, while the green is $\partial \Sigma \setminus Z$.

We next define \tilde{a}_i by pushing the endpoints of b_i^+ negatively along the boundary so that \tilde{a}_i and b_i^+ intersect once transversely. Figure 3.5 shows the arcs \tilde{a}_i on S_{ϵ} and their mirror images on $-S_0$. Glued together, they form $\tilde{\alpha}_i$. Since this example has no α_i curves, we have $\alpha = {\tilde{\alpha}_i}_{i \in H_+}$.

Finally, Figure 3.6 illustrates the bordered sutured Heegaard diagram adapted to the sorted foliated open book of Example 2.24. In this example, the set of intersection points **x** consists only of $x_i^+ = \tilde{a}_i \cap b_i^+ \in S_{\epsilon}$ for $i \in H_+$.

We will use **x** to define two contact invariants in bordered sutured Floer homology. In order to do that, we first show that \mathcal{H} is an admissible diagram for the bordered sutured manifold associated to (M, ξ, \mathcal{F}) .

Proposition 3.4. Let $(\{S_i\}, h, \{\gamma_i^{\pm}\})$ be a sorted abstract foliated open book supporting a foliated contact three-manifold (M, ξ, \mathcal{F}) . Suppose $\mathcal{H} = (\Sigma, \alpha, \beta, \mathcal{Z})$ is a bordered sutured Heegaard diagram adapted to $(\{S_i\}, h, \{\gamma_i^{\pm}\})$. Then \mathcal{H} gives an admissible bordered Heegaard diagram for the bordered sutured manifold (M, Γ, \mathcal{Z}) associated to (M, ξ, \mathcal{F}) .

Proof. Starting from a sorted foliated open book ($\{S_i\}$, h, { γ_i^{\pm} }), we may either first construct a foliated contact manifold (M, ξ, \mathcal{F}) as in Section 2.3.1 and an associated bordered sutured manifold (M, Γ, \mathcal{Z}) as in Section 3.1, or we may start by constructing a bordered sutured Heegaard diagram $\mathcal{H} = (\Sigma, \alpha, \beta, \mathcal{Z})$ as above. To temporarily distinguish between the two constructions of the set of matched arcs, we will in fact temporarily replace this notation with $\mathcal{H} = (\Sigma, \alpha, \beta, \mathcal{Z}')$, with Z' the set of arcs in \mathcal{Z}' . We may then use the construction of Section 2.2.2 to produce a bordered sutured manifold. We wish to verify that the bordered sutured manifold arising this way is (M, Γ, \mathcal{Z}) .

Recall that the foliated contact manifold (M, ξ, \mathcal{F}) is built via saddle cobordisms specified by the sorting arcs. We intend for the α curves to specify the handlebody from S_0 to S_{ϵ} and for the β curves to specify the handlebody from S_0 to S_{ϵ} and for the β curves to specify the handlebody from S_{ϵ} to S_0 . We will start by modifying the graph $G(\mathcal{Z}') \subset \Sigma$ and the bordered sutured structure on ∂M via isotopy, allowing us to identify the Heegaard surface Σ with the

surface $S_{\epsilon} \cup_B -S_0$ in M in such a way that $\partial \Sigma \setminus Z'$ is identified with Γ . (This is equivalent to recovering Γ as $(\partial \Sigma \setminus Z') \times \{\frac{1}{2}\}$ in a thickened copy of the surface $\Sigma \times [0, 1]$.) Recall that we chose Z' to be the union of A_0 with the arcs $\bigcup_{I \subset A_{\epsilon}} (I_+ \cup I_-)$; the purpose of this choice is to enable a simple discussion of gluing in Section 5. However, we may isotope Z' inward along the arcs I_{\pm} to A_0 . On ∂M , we may isotope Z (resp. Γ) through the disks bounded between Z and A_0 (resp. A_0 and A_{ϵ}) and identify it with A_0 (resp. A_{ϵ}). This isotopy can be chosen so that it carries the matched points on Z to the matched points on Z' (as identified with A_0). Note that under this isotopy the edges e_i of the graph G(Z) will twist near their endpoints around the elliptic points.

Next, $\{\tilde{a}_i\}_{i \in H_+} \cup \{a_1, \dots, a_{2g_0+n_0+|A_0|-k-2}\}$ is a cut system for S_{ϵ} . At each time $0 \le t \le \epsilon$, we may consider the image of each of these arcs on $\pi^{-1}(t)$ coming from applying the flow of π ; for each arc, the union of these images is a disk with boundary the corresponding α -circle. (We say that these arcs *trace out* disks in time $[0, \epsilon]$ whose boundaries are the α -circles.) So, α specifies the handlebody from S_0 to S_{ϵ} . Similarly, the cutting arcs $\{b_1, \dots, b_{2g_0+n_0+|A_0|-k-2}\}$ for P_{ϵ} will trace out disks in time $[\epsilon, 2\pi]$, whose boundaries under the identification of $S_{2\pi}$ with S_0 using monodromy h are the β -circles on Σ .

Finally, for each $i \in H_-$, flowing backward from time $t = i\pi/k$ to $t = \epsilon$, the sorting arc γ_i^- traces out a disk corresponding to the cocore of the handle addition. The boundary of this disk is the arc $\beta_i^$ together with the twisted and truncated copy of the separatrix δ_i , that is, with the twisted arc e_i . These are the disks attached along the arcs β_i^- . Likewise, for $i \in H_+$, flowing forward from $t = i\pi/k$ to $t = 2\pi$, the sorting arc γ_i^+ traces out a disk corresponding to the cutting arc for the handle subtraction, whose boundary under the identification of $S_{2\pi}$ with S_0 via the monodromy h is the arc β_i^+ together with the twisted and truncated copy of the separatrix δ_i . These are the disks attached along the arcs β_i^+ .

As for admissibility, we notice that just as in the closed or sutured cases, admissibility is automatic: Every periodic domain with an α -circle on its boundary crosses the only intersection of that circle with β curves or circles on S_{ϵ} , at which point the sign of the connected component of $\Sigma \setminus (\alpha \cup \beta)$ must change.

If \mathcal{H} is a bordered sutured Heegaard diagram adapted to a sorted abstract foliated open book $(\{S_i\}, h, \{\gamma_i^{\pm}\})$ and $(\{S_i\}, h, \{\gamma_i^{\pm}\})$ is compatible with the foliated contact three-manifold (M, ξ, \mathcal{F}) , we say that \mathcal{H} is *adapted* to (M, ξ, \mathcal{F}) .

By Proposition 3.4 and [Zar10, Section 3.4], the diagram $\overline{\mathcal{H}} = (\Sigma, \beta, \alpha, \overline{Z})$ obtained by exchanging the roles of the two sets of curves and formally replacing the arc diagram Z of β -type (which is to say, parametrized by arcs which are part of the second set of curves) with the identical arc diagram \overline{Z} of α -type (parametrized by arcs which are part of the first set of curves) is a bordered sutured diagram for $(-M, \Gamma, \overline{Z})$. Write $\overline{Z} = (Z, a, m)$. We have the following proposition.

Proposition 3.5. The above **x** gives a well-defined generator

$$\mathbf{x}_D := \mathbf{x} \in \widehat{BSD}(\overline{\mathcal{H}})$$

with $I_D(\mathbf{x}) = I(H_-)$ and $\delta^1(\mathbf{x}_D) = 0$, and a well-defined generator

$$\mathbf{x}_A := \mathbf{x} \in \widehat{BSA}(\overline{\mathcal{H}})$$

with $I_A(\mathbf{x}_A) = I(H_+)$ and $m_{i+1}(\mathbf{x}_A, a(\rho_1), \dots, a(\rho_i)) = 0$ for all $i \ge 0$ and all sets of Reeb chords ρ_j in (Z, a).

Proof. Since each of the intersections in the definition of **x** is unique, the two generators are well defined. The idempotents are as stated since the β -arcs occupied by **x** are indexed by H_+ , whereas the unoccupied β -arcs are indexed by H_- . Last, consider regions of $\Sigma \setminus (\alpha \cup \beta)$ that have a point $x \in \mathbf{x}$ as a corner vertex. Each such region either has an interval of $\partial \Sigma \setminus Z$ on its boundary or it has some corner near which it agrees with one of the thin strips obtained by perturbing the b_i and b_j^+ arcs to a_i and \tilde{a}_j arcs. The positively oriented boundary of such a thin strip near *x* has a segment of a β curve ending at *x*,

and a segment of an α curve starting at *x*. Such a region cannot be in the projection $\pi_{\Sigma} \circ u$ of an index 1 holomorphic map

$$u: (S, \partial S) \to (\operatorname{Int}(\Sigma) \times \mathbb{D} \times \mathbb{R}, (\boldsymbol{\beta} \times \{1\} \times \mathbb{R}) \cup (\boldsymbol{\alpha} \times \{0\} \times \mathbb{R}))$$

satisfying [Zar10, Section 5.2, Conditions (1)-(11)] and asymptotic to $\mathbf{x} \times [0, 1]$ at $-\infty$. Thus, $\delta^1(\mathbf{x}_D) = 0$, and $m_{i+1}(\mathbf{x}_A, a_1, \dots, a_i) = 0$ for all $i \ge 0$ and all $a_j \in \mathcal{A}(\partial \overline{\mathcal{H}})$.

4. Invariance

In this section, we complete the proof of Theorem 1. Specifically, we show that given two different sets of choices made in constructing a bordered sutured Heegaard diagram for the bordered sutured threemanifold $(-M, \Gamma, \overline{Z})$ associated to a foliated contact three-manifold (M, ξ, \mathcal{F}) resulting in Heegaard diagrams \mathcal{H} and \mathcal{H}' with associated type *A* bordered sutured Floer homologies $\widehat{BSA}(\mathcal{H})$ and $\widehat{BSA}(\mathcal{H}')$, the contact elements \mathbf{x}_A and \mathbf{x}'_A are equivalent in the sense of Section 2.2.2 and likewise for \mathbf{x}_D and \mathbf{x}'_D . We prove equivalence of these classes under

- 1. isotopy of the monodromy *h* of the foliated open book $(\{S_i\}, h, \{\gamma_i^{\pm}\})$ for (M, ξ, \mathcal{F}) ;
- 2. the choice of complex structure;
- 3. stabilizations of the foliated open book $(\{S_i\}, h, \{\gamma_i^{\pm}\})$ on the S_0 page; and
- 4. the choice of the cutting arcs made when constructing the bordered Heegaard diagram in Section 3.2.

Note that we do not have to prove invariance under time shift since the definition of a triple (M, ξ, \mathcal{F}) has an implicit choice of initial time t = 0; see Remark 2.15. Invariance under the choice of complex structure follows from [Zar09, Theorem 7.8] and the observation that since there are no nontrivial topological domains beginning at the generator **x** on the bordered sutured Heegaard diagram \mathcal{H} , the type A and type D chain homotopy equivalences between bordered sutured complexes associated to pairs (\mathcal{H}, J_1) and (\mathcal{H}, J_2) count a single pseudoholomorphic strip constant in the Σ coordinate beginning at **x**_D or **x**_A, and thus in each case carry the special generator to itself. It is a consequence of Theorem 2.23 that stabilizations on the S_0 page are sufficient.

We thus focus on the remaining three choices made in the construction of the contact invariants. For invariance under the isotopy class of h and choice of the cutting arcs, our proofs heavily parallel those of [HKM09b, Section 3] and [HKM09a, Section 3]; our proof of stabilization invariance has a slightly different structure.

Proposition 4.1. Suppose we choose two representatives for the isotopy class of h, resulting in bordered sutured Heegaard diagrams \mathcal{H} and \mathcal{H}' . The resulting contact elements $\mathbf{x}_A \in \widehat{BSA}(\mathcal{H})$ and $\mathbf{x}'_A \in \widehat{BSA}(\mathcal{H}')$ are equivalent in the sense of Section 2.2.2 and likewise for \mathbf{x}_D and \mathbf{x}'_D .

Proof. The proof given in [HKM09b, Lemma 3.3] carries over to the bordered sutured case essentially verbatim. As previously, the point is that there are no holomorphic curves beginning at the generators \mathbf{x}_A and \mathbf{x}_D .

We now turn our attention to equivalence under choice of the cutting arcs in the case that we start with a sufficiently stabilized foliated open book. (Subsequently, in Proposition 4.5, we will prove stabilization invariance, thus showing invariance of the choice of cutting arcs for all sorted foliated open books.)

First, we show that two different choices of cutting arcs b and \overline{b} for $P_{\epsilon} \subset S_{\epsilon}$ are related by arcslides on P_{ϵ} .

Proposition 4.2. Suppose that $(\{S_i\}, h, \{\gamma_i\})$ is a sufficiently stabilized foliated open book. Then any two sets of cutting arcs $\mathbf{b} = \{b_1, \ldots, b_{2g_0+n_0+|A_0|-k-2}\}$ and $\tilde{\mathbf{b}} = \{\tilde{b}_1, \ldots, \tilde{b}_{2g_0+n_0+|A_0|-k-2}\}$ for P_{ϵ} are related by a sequence of arcslides.

Proof. The proof is modeled on [HKM09a, Lemma 3.3] and [HKM09b, Lemma 3.6]. Let $r = 2g_0 + n_0 + |A_0| - k - 2$.

First, we will show that $\bigcup_{i=1}^{r} b_i$ and $\bigcup_{i=1}^{r} \tilde{b}_i$ can be made disjoint from each other by performing a sequence of arcslides. Then we verify the statement of the proposition for the case of two disjoint sets of cutting arcs. Suppose that $(\bigcup_{i=1}^{r} b_i) \cap (\bigcup_{i=1}^{r} \tilde{b}_i) \neq \emptyset$. We may assume the curves intersect efficiently. We can decrease the number of intersections as follows.

Cut P_{ϵ} along the arcs in **b** to obtain a set of polygons. For each cutting arc b_i , label the two resulting boundary segments on $\partial(P_{\epsilon} \setminus \mathbf{b})$ by b_i and b_i^{-1} and call these two segments *partners*.

First, we show that every connected component of $P_{\epsilon} \setminus b$ intersects R_{ϵ} in exactly one interval. To see that each connected component of $P_{\epsilon} \setminus b$ intersects R_{ϵ} , observe that otherwise the boundary of the component would only contain arcs in B and in b. But the connected components of $P_{\epsilon} \setminus b$ are naturally identified with the connected components of $S_{\epsilon} \setminus (b \cup \beta^a)$ and by the definition of cutting arcs, each connected component of $S_{\epsilon} \setminus (b \cup \beta^a)$ is a disk with exactly one interval of A_{ϵ} on its boundary. Moreover, $P_{\epsilon} \setminus b$ cannot intersect R_{ϵ} in more intervals. Assume it intersects R_{ϵ} in at least two intervals. There are two types of such a segment of R_{ϵ} : Either it corresponds only to an arc in A_{ϵ} or also to an arc of type γ_i^{\pm} whose both endpoints connect to arcs in A_{ϵ} . In this latter case, the isotopy of γ_i^{\pm} resulting in β_i^{\pm} leaves at least one of these arcs in A_{ϵ} on the boundary of the connected component of $S_{\epsilon} \setminus (b \cup \beta^a)$. In the former case, the only arc in A_{ϵ} is also on the boundary of the corresponding connected component of $S_{\epsilon} \setminus (b \cup \beta^a)$. In both cases, the segment of R_{ϵ} corresponds to an arc in A_{ϵ} on $\partial S_{\epsilon} \setminus (b \cup \beta^a)$. Therefore, our assumption contradicts the fact that $S_{\epsilon} \setminus (b \cup \beta^a)$ contains exactly one interval of A_{ϵ} on its boundary.

Consider a connected component *C* of $P_{\epsilon} \setminus \boldsymbol{b}$ containing an intersection point of $\bigcup_{i=1}^{r} b_i$ and $\bigcup_{i=1}^{r} \widetilde{b}_i$. Then *C* is a polygon with some number of edges in \boldsymbol{b} (of types b_j and b_j^{-1}), some number of edges in *B* and exactly one edge in R_{ϵ} .

After possibly reordering the elements of \boldsymbol{b} , we may assume that $b_1 \cap \tilde{b}_1 \neq \emptyset$ and that we can find a subarc $\tilde{b}_1^0 \subset \tilde{b}_1$ in C such that \tilde{b}_1^0 starts from a segment B_1 of the binding B, ends on b_1 and has interior disjoint from $\bigcup_{i=1}^r b_i$, as in Figure 4.1. We may also assume that b_1 and B_1 are not adjacent, as we could otherwise isotope \tilde{b}_1^0 to decrease the number of intersection points between \tilde{b}_1^0 and b_1 .

Now, \tilde{b}_1^0 cuts *C* into two polygons C_1 and C_2 , at least one of which does not contain b_1^{-1} . Suppose first that C_1 does not contain b_1^{-1} and also that $\partial C_1 \cap \partial R_{\epsilon} = \emptyset$. In this case, we may slide b_1 over the remaining arcs in ∂C_1 until we obtain b'_1 . Note that b'_1 has a subarc which lies on b_1 , while the rest of b'_1 lies in a small neighborhood of \tilde{b}_1 . This means that no new intersection points are created, while we cancel the one we started with. Therefore, $b'_1 \cup b_2 \cup ... \cup b_r$ has fewer intersection points with $\bigcup_{i=1}^r \tilde{b}_i$. We proceed similarly in the case when $\partial C_1 \cap \partial R_{\epsilon} \neq \emptyset$ but b_1^{-1} is not contained in ∂C_2 because then we may slide b_1 over the remaining arcs in ∂C_2 to get b'_1 . The case when ∂C_1 intersects ∂R_{ϵ} in an arc γ and C_2 contains b_1^{-1} on its boundary is handled as follows. Since the foliated open book is sufficiently stabilized, any connected component of P_{ϵ} intersects ∂R_{ϵ} in at least two intervals. Therefore, there is an arc $c \subset \partial C$ which is of type b_i or b_i^{-1} such that c^{-1} is not in ∂C ; otherwise, *C* would glue up to a



Figure 4.1. The polygon C, with the subarc \tilde{b}_1^0 crossing between the nonadjacent arcs b_1 and B_1 .

connected component of P_{ϵ} intersecting ∂R_{ϵ} in only one interval. Sliding *c* over all other arcs in ∂C except γ gives us *c'* parallel to γ . After this, we may slide b_1 over the arcs in ∂C_1 since now we only need to slide it over *c'* instead of γ . Finally, we get b'_1 which has a subarc lying on b_1 , while the rest lie in a small neighborhood of \tilde{b}_1 as before. This means that no new intersection points are created, while we cancel the one we started with. Therefore, $\{b'_1, b_2, ..., b_r\}$ has fewer intersection points with $\cup_{i=1}^r \tilde{b}_i$ than $\cup_{i=1}^r b_i$ did. Iterating this procedure a finite number of times, we obtain a new set of cutting arcs which are disjoint from the arcs \tilde{b} .

Next, we show that for $\bigcup_{i=1}^{r} b_i$ and $\bigcup_{i=1}^{r} \tilde{b}_i$ disjoint, **b** can be turned into \tilde{b} via a finite sequence of arcslides. Let *C* denote a connected component of $P_{\epsilon} \setminus b$ as before. If each arc \tilde{b}_i in *C* is parallel to some b_j or b_j^{-1} , we are done with *C*. Suppose that there is an arc, say \tilde{b}_1 , which is not parallel to any b_j or b_j^{-1} . Then \tilde{b}_1 cuts *C* into two pieces C_1 and C_2 , with the property that each ∂C_i contains more than one arc of type b_j or b_j^{-1} . Choose the labeling such that $C \cap R_{\epsilon}$ is in C_1 . Moreover, we can find a pair of arcs b_j and b_j^{-1} such that $b_j \subset \partial C_2$ and $b_j^{-1} \notin \partial C_2$ (or vice versa); otherwise, every segment of ∂C_2 has its partner in ∂C_2 , implying that some part of C_2 glues up to a connected component of $P_{\epsilon} \setminus b$ which does not intersect R_{ϵ} . If each such b_j were parallel to an arc \tilde{b}_j , then $\bigcup_{i=1}^{r} \tilde{b}_i$ would again cut off a subsurface which does not intersect R_{ϵ} . Therefore, we may assume that there exists a b_j which is not parallel to any \tilde{b}_l . Now, we can slide b_j over all the arcs b_l and b_i^{-1} in C_1 until it becomes parallel to \tilde{b}_1 . This way we associated an arc which was not parallel to any \tilde{b}_l before to \tilde{b}_1 not parallel to any b_j

Proposition 4.3. Let $\mathbf{b} = \{b_1, b_2, \dots, b_r\} \rightarrow \{b_1 + b_2, b_2, \dots, b_r\} = \mathbf{b'}$ be an arcslide among the cutting arcs on P_{ϵ} . If \mathcal{H} and $\mathcal{H'}$ are the resulting bordered sutured Heegaard diagams, then the resulting contact elements $\mathbf{x}_A \in \widehat{BSA}(\mathcal{H})$ and $\mathbf{x}'_A \in \widehat{BSA}(\mathcal{H'})$ are equivalent in the sense of Section 2.2.2, and likewise for \mathbf{x}_D and \mathbf{x}'_D .

Proof. An arcslide induces a pair of handleslides, one among the α -circles followed by one among their pushoffs, that is, the β -circles. The induced maps on \widehat{BSD} and on \widehat{BSA} count holomorphic triangles that do not interact with the boundary of the Heegaard diagram. Thus, the proof is a straightforward adaptation of [HKM09b, Lemma 3.5].

We conclude the following.

Proposition 4.4. Let $\mathbf{b} = \{b_1, \ldots, b_r\}$ and $\widetilde{\mathbf{b}} = \{\widetilde{b}_1, \ldots, \widetilde{b}_r\}$ be two possible choices of cutting arcs made in the construction of the bordered Heegaard diagram associated to the sufficiently stabilized open book $(\{S_i\}, h, \{\gamma_i\})$, and let \mathcal{H} and $\widetilde{\mathcal{H}}$ be the resulting bordered sutured Heegaard diagrams. Then the resulting contact elements $\mathbf{x}_A \in \widehat{BSA}(\mathcal{H})$ and $\mathbf{x}'_A \in \widehat{BSA}(\mathcal{H}')$ are equivalent in the sense of Section 2.2.2 and likewise for \mathbf{x}_D and \mathbf{x}'_D .

Proof. This follows immediately from Propositions 4.2 and 4.3.

Proposition 4.5. Let $(\{S'_i\}, h', \{\gamma'^{\pm}\})$ be the open book resulting from stabilization of the open book $(\{S_i\}, h, \{\gamma^{\pm}_i\})$ on the S_0 page, and let \mathcal{H} and \mathcal{H}' be the resulting bordered sutured Heegaard diagrams. The resulting contact elements $\mathbf{x}_A \in \widehat{BSA}(\mathcal{H})$ and $\mathbf{x}'_A \in \widehat{BSA}(\mathcal{H}')$ are equivalent in the sense of Section 2.2.2 and likewise for type D.

Proof. Let $\mathcal{H} = (\Sigma, \alpha, \beta, \mathbb{Z})$ be a bordered sutured Heegaard diagram adapted to $(\{S_i\}, h, \{\gamma_i^{\pm}\})$. We take $(\{S_i'\}, h', \{\gamma_i'^{\pm}\})$ to be the result of stabilizing $(\{S_i\}, h, \{\gamma_i^{\pm}\})$ along a curve $\gamma \subset S_0$. Recall that if we denote by \overline{h} the extension of h to the added one-handle by the identity, then $h' = \tau \circ \overline{h}$, where τ is a positive Dehn twist along the circle c formed by γ and the core of the attached one-handle. This means that we can obtain from \mathcal{H} a diagram $\mathcal{H}' = (\Sigma', \alpha', \beta', \mathbb{Z})$ adapted to $(\{S_i'\}, h', \{\gamma_i'^{\pm}\})$ as follows. Add a one-handle to the two pages S_{ϵ} and $-S_0$ that form the Heegaard surface in order to obtain $\Sigma' = S'_{\epsilon} \cup -S'_0$.



Figure 4.2. (a) The two neighborhoods on S_{ϵ} and S_0 of the stabilization arc, viewed on the Heegaard diagram \mathcal{H} . The stabilization arc is drawn as a grey dashed arc on S_0 . The red and blue vertical lines on each neighborhood represent a (possibly) more general sequence of α and β curves. (b) The Heegaard diagram \mathcal{H}' corresponding to the stabilized open book, where the same choice of cutting arcs is used away from the stabilization region and the cocore of the stabilizing one-handle is used as the final cutting arc; the diagram \mathcal{H}' has one new α circle denoted α' and one new β circle, denoted β' . In this and all subsequent figure in this section, black lines are identified via translation in the plane, being part of the binding. Green stars mark regions that intersect $\partial \Sigma \setminus Z$; to see why the marked regions indeed intersect the $\partial \Sigma \setminus Z$ part of $\partial \Sigma$ nontrivially, simply note that the stabilization arc has endpoints on $\partial \Sigma \setminus Z$.

Let b' be the cocore of the one-handle on S'_{ϵ} , and let a' be a perturbation of the new cutting arc b' to the left. Let

$$\beta' = b' \cup -h' \circ \iota(b') \subset S'_{\epsilon} \cup_B -S'_0,$$

and let

$$\alpha' = a' \cup -a' \subset S'_{\epsilon} \cup_B -S'_0.$$

Last, modify all β curves that intersect γ by applying to them a positive Dehn twist along *c*; see Figure 4.2(b). Clearly \mathcal{H}' is adapted to the stabilized open book $(\{S'_i\}, h', \{\gamma'^{\pm}_i\})$.

Figures 4.2–4.4 demonstrate a sequence of Heegaard moves that transforms \mathcal{H}' into a diagram \mathcal{H}'' adapted to a foliated open book ({ S_i }, h'', { γ_i^{\pm} }) whose monodromy h'' is isotopic to h.

In particular, in Figure 4.2(a) we see the original neighborhood of \mathcal{H}' where we intend to stabilize, with the stabilization arc drawn in (dashed) grey, and in Figure 4.2(b) we see the result of the stabilization, with new curves α' and β' . Observe that each of α' and β' may intersect some number of α and β curves on S_0 . We handleslide every β curve other than β' that intersects α' over β' to obtain Figure 4.3(a), in which we have eliminated all intersection points between α' and any β curve other than β' . After a small isotopy of the diagram to Figure 4.3(b), we then handleslide all α circles other than α' which intersect β' over the curve α' . The result of these handleslides, shown in Figure 4.3(c), is a diagram in which α' and β' intersect once and there is a punctured torus neighborhood of $\alpha' \cup \beta'$ which intersects no other α or β curves. We excise this punctured torus, obtaining Figure 4.4(a), after which we may isotope the surface to obtain Figure 4.4(b); trading two bigons between S_0 and S_{ϵ} produces the diagram \mathcal{H}'' shown in Figure 4.4(c), whose monodromy h'' is isotopic to h'.



Figure 4.3. (a) The diagram after sliding all β curves that intersect α' over β' to eliminate the intersection points. (b) An isotopy of the previous figure. (c) The result of sliding all α circles that intersect β' over α' , so that the new neighborhood of $\alpha' \cup \beta'$ is a punctured torus with a single intersection point of $\alpha' \cap \beta'$.



Figure 4.4. (a) The result of excising the punctured torus, along with an isotopy of the curve that represents the binding 'trading' two bigons from S_{ϵ} to S_0 ; the grey lines are the boundary of the punctured torus; the new binding is marked in purple. (b) An isotopy of the previous figure, again with the grey lines as the boundary of a puncture. (c) An isotopy of the previous figure, divided by page according to the new binding.

We will show that there is a type D (resp. type A) homotopy equivalence induced by the sequence of moves which carries the contact class from \mathcal{H}' to the contact class from \mathcal{H}'' .

Let $\mathbf{x}_D \in \widehat{BSD}(\widehat{\mathcal{H}})$ be the generator corresponding to the set of intersection points \mathbf{x} , as defined in Section 3.2. Let x' be the unique intersection point in $\alpha' \cap \beta'$ on \mathcal{H}' . Observe that the diagram \mathcal{H}' was obtained by modifying \mathcal{H} away from \mathbf{x} , and that $\mathbf{x}' := \mathbf{x} \cup \{x'\}$ is the special generator for \mathcal{H}' coming from the construction in Section 3.2. Let \mathbf{x}'_D be the generator in $\widehat{BSD}(\overline{\mathcal{H}'})$ corresponding to \mathbf{x}' . Last, let \mathbf{x}'' be the special generator on \mathcal{H}'' and \mathbf{x}''_D be the corresponding generator in $\widehat{BSD}(\overline{\mathcal{H}'})$.



Figure 4.5. Top: The case of sliding a curve that does not contain an intersection point in **x**, that is, some β_i^- . Bottom: The case of sliding a curve that contains an intersection point in **x**.

Let $\mathbf{x}_0 = \mathbf{x}'_D$, and let $\boldsymbol{\beta}_0 = \boldsymbol{\beta}'$. Consider the bordered Heegaard triple $\mathcal{H}_i = (\Sigma, \boldsymbol{\beta}_{i-1}, \boldsymbol{\beta}_i, \boldsymbol{\alpha}', \mathcal{Z})$ corresponding to the *i*th handleslide in the sequence of handleslides making $\boldsymbol{\alpha}'$ disjoint from every $\boldsymbol{\beta}$ curve except $\boldsymbol{\beta}'$. Figure 4.5 illustrates the diagram in a neighborhood of the union of $\boldsymbol{\alpha}', \boldsymbol{\beta}'$ and the $\boldsymbol{\beta}$ -circles that intersect $\boldsymbol{\alpha}'$. Let F_i be the map associated to the *i*th handleslide defined by counting holomorphic triangles with Maslov index zero. Then, the chain map associated with the handleslides is

$$f_i := F_i(\cdot, \Theta) : \widehat{BSD}(\Sigma, \beta_{i-1}, \alpha', \mathcal{Z}) \to \widehat{BSD}(\Sigma, \beta_i, \alpha', \mathcal{Z})$$

where Θ represents the top generator in $(\Sigma, \beta_{i-1}, \beta_i, \mathbb{Z})$. We will argue that f_1 carries \mathbf{x}_0 to a single generator \mathbf{x}_1 in $\widehat{BSD}(\Sigma, \beta_1, \alpha', \mathbb{Z})$ and inductively, that each map f_i carries the generator \mathbf{x}_{i-1} to a generator \mathbf{x}_i .

Assume $\Delta \in \pi_2(\mathbf{x}_{i-1}, \Theta, \mathbf{y})$ is a Whitney triangle that contributes nontrivially to $f_i(\mathbf{x}_{i-1})$. Let n_j denote the coefficient of Δ in the region labelled with j, and recall that $n_j \ge 0$ for all j.

First, consider a neighborhood of an intersection point in \mathbf{x}_{i-1} on one of the β curves other than β' . This situation is illustrated in the top left rectangle in the bottom image of Figure 4.5. Because the black and pink intersection points must both appear as corners in the projection of Δ to \mathcal{H}_i , we have

$$n_1 + n_3 + 1 = n_4$$
 $n_4 + n_5 = n_3 + 1$,

so taking the sum of the two equations and cancelling terms, we see that $n_1 + n_5 = 0$, implying that $n_1 = n_5 = 0$. Thus, we see $n_4 = n_3 + 1$, so in particular $n_4 \ge 1$. But the multiplicity of the intersection point marked in turquoise in **y** is $n_4 + n_2 - n_1 = n_4 + n_2 \le 1$, so $n_4 = 1$ and $n_2 = 0$.

For the central rectangle, we first observe that $n_7 = n_{11}$ and $n_6 = n_{17}$; otherwise, some corner of the projection of Δ to \mathcal{H}_i lies on the intersection of β' with an α curve other than α' , which cannot occur since \mathbf{x}_{i-1} contains an intersection point between β' and α' . Next, $n_{d_0} = 0$ since the region marked with d_0 intersects $\partial \Sigma \setminus Z$ nontrivially. We claim that if $n_{d_{j-1}} = 0$, then $n_{d_j} = 0$. Consider the green or blue curve separating d_{j-1} or d_j . If it is part of a pair of green and blue curves containing an intersection point of a generator that moves under the cobordism map, then either $n_5 = 0$ or $n_{18} = 0$ (because the region labelled 18 intersects $\partial \Sigma \setminus Z$ nontrivially) can be used to deduce that if $n_{d_{j-1}} = 0$, then so is n_{d_j} . If, however, the curve separating d_{j-1} or d_j is part of a pair of green and blue curves without an intersection point of a generator that moves under the cobordism map, then the fact that $n_{13} = n_{14} = n_{15} = n_{16}$ shows that if $n_{d_{j-1}} = 0$, then $n_{d_j} = 0$. So all $n_{d_j} = 0$, and by the same logic $n_7 = n_{11} = 0$.

Now, we see that

$$n_{10} = n_9 + 1$$
 $n_{10} + n_6 = 1$ $n_9 + n_6 = 0$,

implying that $n_6 = n_9 = 0$ and $n_{10} = 1$. Hence, the domain of Δ is the disjoint union of the small yellow triangles, and **y** is the intersection point \mathbf{x}_i shown in turquoise in Figure 4.5. Consequently, for an appropriate choice of the complex structure $f_i(\mathbf{x}_{i-1}) = \mathbf{x}_i$. So the map induced by the *i*th handleslide among the β curves takes each intersection point between β_{i-1} and α in \mathbf{x}_{i-1} to the nearest intersection point between β_i and α' .

The argument for handleslides among the α curves is analogous. Let \mathbf{z} be the generator that \mathbf{x}' is carried to by the sequence of β and α handleslides. Next, destabilizing along a neighborhood of $\alpha' \cup \beta'$ results in a Heegaard diagram \mathcal{H}'' adapted to a foliated open book $(\{S_i\}, h'', \{\gamma_i^{\pm}\})$ whose monodromy h'' is isotopic to h, as in Figure 4.4(c). It is clear that the destabilization map sends \mathbf{z} to \mathbf{x}''_D . By Proposition 4.1, \mathbf{x}''_D is equivalent to \mathbf{x}_D , the generator for the original Heegaard diagram.

The argument for type A is similar. The *i*th handleslide induces maps

$$(f_i)_j \colon \widehat{BSA}(\Sigma, \beta_{i-1}, \alpha', \overline{Z}) \otimes \mathcal{A}(\overline{Z})^{\otimes (j-1)} \to \widehat{BSA}(\Sigma, \beta_i, \alpha', \overline{Z})$$

indexed by *j*; each map $(f_i)_1$ carries the generator \mathbf{x}_{i-1} to the generator \mathbf{x}_i , and whenever j > 1, we have $(f_i)_j(\mathbf{x}_{i-1}, a_1, \dots, a_{j-1}) = 0$ for any $a_1, \dots, a_j \in A(\overline{Z})$.

Proof of Theorem 1. Proposition 4.1 shows that isotopy of the monodromy *h* induces maps of bordered sutured Floer modules carrying the distinguished generator to the distinguished generator, and therefore that isotopy of the monodromy preserves the homotopy equivalence class of \mathbf{x}_D in $\widehat{BSD}(-M, \Gamma, \overline{Z})$. Similarly, the discussion at the start of this section shows that changing the choice of almost complex structure induces maps of bordered sutured Floer modules which are identity on the special generators, hence preserve the distinguished generator \mathbf{x}_D . Proposition 4.5 shows that stabilization on the S_0 page of the open book ($\{S_i\}, h, \{\gamma_i\}$) induces maps of bordered sutured Floer modules carrying the distinguished generator. By Theorem 2.23, these stabilizations suffice. Proposition 4.4 shows that for a sufficiently stabilized open book, varying the choice of cutting arcs also induces maps of bordered scarrying the distinguished generator.

The argument for type A proceeds similarly.

Thus, we may finally define our contact invariants.

Definition 4.6. Let $c_D(M, \xi, \mathcal{F})$ be the type *D* homotopy equivalence class (in the sense of Section 2.2.2) of \mathbf{x}_D in $\widehat{BSD}(-M, \Gamma, \overline{Z})$. Similarly, let $c_A(M, \xi, \mathcal{F})$ be the type *A* homotopy equivalence class of \mathbf{x}_A in $\widehat{BSA}(-M, \Gamma, \overline{Z})$.

5. Gluing

In this section, we show that after gluing, the tensor product of the classes from Definition 4.6 recovers the Ozsváth–Szabó contact class.

Suppose that $(M^L, \xi^L, \mathcal{F}^L)$ and $(M^R, \xi^R, \mathcal{F}^R)$ are two foliated contact three-manifolds and that $\psi : \partial M^L \to \partial M^R$ is an orientation-reversing diffeomorphism that takes the reverse of \mathcal{F}^L to \mathcal{F}^R . Let $(M, \xi) = (M^L \cup_{\psi} M^R, \xi^L \cup_{\psi} \xi^R)$. If we glue the corresponding bordered sutured three-manifolds $(M^L, \Gamma^L, \mathcal{F}^L)$ and $(M^R, \Gamma^R, \mathcal{F}^R)$, then we obtain a sutured three-manifold $(M(|\Gamma|), \Gamma) = (M^L \cup_{F(\mathcal{Z})} M^R, \Gamma^L \cup \Gamma^R)$, where $M(|\Gamma|)$ denotes M with $|\Gamma|$ balls removed. The associated chain complex computes multipointed Heegaard Floer homology. It follows that $SFH(-M(|\Gamma|), \Gamma) \cong \widehat{HF}(-M) \otimes H_*(T^{|\Gamma|-1})$. The gluing statement is approximately the following: Under the map

$$\widehat{BSA}(-M^L, \Gamma^L, \overline{\mathcal{Z}}) \boxtimes_{\mathcal{A}(\overline{\mathcal{Z}})} \widehat{BSD}(-M^R, \Gamma^R, -\overline{\mathcal{Z}}) \to SFC(-M(|\Gamma|), \Gamma),$$

the box tensor product of the bordered contact invariants (M^L, ξ^L) and (M^R, ξ_R) maps to the generator corresponding to the multipointed contact invariant of (M, ξ) . In order to state the theorem precisely, we must fix the respective Heegaard diagrams, as we describe next.

We begin with sorted abstract foliated open books for the two foliated contact three-manifolds. We will show that gluing two bordered sutured Heegaard diagrams adapted to these open books yields a multipointed Heegaard diagram adapted to an open book that supports (M, ξ) .

In fact, we can do two different constructions. In the first construction, we glue the two foliated open books as described in Section 2.3.6 to obtain an open book (S, h) for (M, ξ) . We then construct an adapted (multipointed) Heegaard diagram \mathcal{H} with a distinguished generator \mathbf{x} for $c(\xi) \otimes \theta^{|\Gamma|-1}$. In the second construction, we begin with bordered sutured Heegaard diagrams adapted to the foliated contact three-manifolds constructed as in Section 3.2; these have distinguished generators \mathbf{x}^L and \mathbf{x}^R which give $c_D(\xi^L)$ and $c_A(\xi^R)$, respectively. We then glue the diagrams together to obtain a sutured Heegaard diagram \mathcal{H}' for $(-\mathcal{M}(|\Gamma|), \Gamma)$ with the distinguished generator $\mathbf{x}' := \mathbf{x}^L \boxtimes \mathbf{x}^R$ representing $c_D(\xi^L) \boxtimes c_A(\xi^R)$. Each of these constructions involves some choice of cutting arcs. We will start with the latter construction and show that the obtained sutured Heegaard diagram for $(-\mathcal{M}(|\Gamma|), \Gamma)$ – interpreted as a multipointed Heegaard diagram for M, as in the end of Section 2.2.1 – is the Heegaard diagram coming from the former construction.

Let $(\{S_i^L\}_{i=0}^{2k}, h^L, \{\gamma_i^{\pm,L}\})$ and $(\{S_i^R\}_{i=0}^{2k}, h^R, \{\gamma_i^{\pm,R}\})$ be sorted abstract foliated open books for the triples $(M^L, \xi^L, \mathcal{F}^L)$ and $(M^R, \xi^R, \mathcal{F}^R)$, respectively. Let $\mathcal{H}^L = (\Sigma^L, \beta^L, \alpha^L, \mathcal{Z}^L)$ and $\mathcal{H}^R = (\Sigma^R, \beta^R, \alpha^R, \mathcal{Z}^R)$ be Heegaard diagrams adapted to these foliated open books. Since \mathcal{F}^L is the reverse of \mathcal{F}^R , we can identify \mathcal{Z}^L with $-\mathcal{Z}^R$.⁶ We can therefore glue the two diagrams along $\mathcal{Z}^L = -\mathcal{Z}^R$ to obtain a sutured diagram $\mathcal{H}' = \mathcal{H}^L \cup \mathcal{H}^R$. More precisely, since $E_{\pm}^L = E_{\mp}^R$ and $H_{\pm}^L = H_{\mp}^R$, the endpoints of the two arcs $\beta_i^{a,L}$ and $\beta_i^{a,R}$ may be isotoped to match up on $A_{\epsilon}^L = -A_{\epsilon}^R$ for each $i \in \mathcal{H}_{\pm}^L = \mathcal{H}_{\mp}^R$. This yields the curves $\beta_i^a = \beta_i^{a,L} \cup \beta_i^{a,R}$ on the surface $\Sigma' = \Sigma^L \cup_{\mathcal{Z}_L} = -\mathcal{Z}_R$. See Figure 5.1.

As a next step, we cap all boundary components of Σ' with disks and place a basepoint in the middle of each disk. We thus obtain a multipointed Heegaard diagram \mathcal{H} for M. We could equivalently have obtained \mathcal{H} from \mathcal{H}^L and \mathcal{H}^R by gluing Σ^L to Σ^R along the entire A_{ϵ}^L and A_{ϵ}^R and placing a basepoint in the middle of each component of $A_{\epsilon}^L = -A_{\epsilon}^R$. Now, we are ready to state the precise gluing statement.

Theorem 5.1 (Gluing). As above, let (M, ξ) denote the manifold constructed by gluing foliated open books along their compatible boundaries, and let \mathcal{H} be the multipointed Heegaard diagram formed by capping the discs on the resulting sutured Heegaard diagram \mathcal{H}' . Then \mathcal{H} is adapted to an open book (S, h) for (M, ξ) and the box tensor product $\mathbf{x}_A \boxtimes \mathbf{x}_D$ agrees with the generator \mathbf{x} representing the multipointed contact invariant for (M, ξ) .

⁶For ease of exposition, we assume that the intervals I_{\pm}^L on A_{ϵ}^L and I_{\mp}^R on A_{ϵ}^R are chosen so that they match up after gluing, which can always be obtained up to isotopy.



Figure 5.1. Top: Two bordered sutured Heegaard diagrams with compatible boundary, glued together. We have $i_1 < \cdots < i_s$ and $\{i_1, \ldots, i_s\} \in H^L_+ = H^R_-$; similarly, $j_1 < \cdots < j_t$ and $\{j_1, \ldots, j_t\} \in H^L_- = H^R_+$. Recall that a β -arc $\beta_i^{a,\bullet}$ corresponding to a hyperbolic point in H^{\bullet}_{\pm} is also denoted by $\beta_i^{\pm,\bullet}$, to help read the diagram. Cutting arcs b_j^L and b_j^R , as well as their perturbations a_j^L and a_j^R , are labelled without subscripts, again for ease for reading. Bottom: The corresponding foliation on the left boundary. Only an interval of A_0 and the relevant nearby separatrices are shown.

Since our goal is to show that \mathcal{H} is a multipointed Heegaard diagram compatible with an open book for (M, ξ) , we will continue to keep track of the union $B = B^L \cup B^R \subset \Sigma = \Sigma^L \cup_{A^L = -A^R} \Sigma^R$ of the two original bindings. Observe that B splits Σ into two 'pages', namely $S' := S^L_{\epsilon} \cup_{A^L_{\epsilon} = -A^{\epsilon}_R} S^R_{\epsilon}$, and $S'' := S^L_0 \cup_{A^L_{\epsilon} = -A^0_{\epsilon}} S^R_0$. We will break the argument relating \mathcal{H} to an open book for (M, ξ) into three propositions. Consider the collections of arcs obtained by restricting the β and α curves to S', and denote these by $\mathbf{b}' = \{b'_i\}$ and $\mathbf{a}' = \{a'_i\}$, respectively. Denote the remaining parts of the β and α curves by $\mathbf{b}'' = \{b''_i\}$ and $\mathbf{a}'' = \{a''_i\}$.

Proposition 5.2. The set of arcs b' cuts S' into $\frac{|E^L|}{2} = \frac{|E^R|}{2}$ disks, each of which contains exactly one basepoint.

Proof. Following the notation in Section 3.2, we will write $b_i^{+,\bullet}$ for $\beta_i^{a,\bullet} \cap S_{\epsilon}^{\bullet}$ whenever $i \in H_+^{\bullet}$. Thus, the collection \boldsymbol{b}' is exactly the union of the collections $\boldsymbol{b}^{+,L} = \{b_i^{+,L}\}_{i \in H_+^L}, \boldsymbol{b}^L = \{b_i^L\}, \boldsymbol{b}^{+,R} = \{b_i^{+,R}\}_{i \in H_+^R}$ and $\boldsymbol{b}^R = \{b_i^R\}$.

Observe that

$$S' \setminus \boldsymbol{b}' = (S_{\boldsymbol{\epsilon}}^L \setminus (\boldsymbol{b}^L \cup \boldsymbol{b}^{+,L})) \cup_{A_{\boldsymbol{\epsilon}}^L = -A_{\boldsymbol{\epsilon}}^R} (S_{\boldsymbol{\epsilon}}^R \setminus (\boldsymbol{b}^R \cup \boldsymbol{b}^{+,R})),$$

so to prove the proposition, we need to understand how the pieces in the right- and left-hand sides glue together.

Recall from Section 3.2 that each connected component of $S_{\epsilon}^{\bullet} \setminus (b^{\bullet} \cup b^{+,\bullet})$ is a disk with exactly one interval of A_{ϵ}^{\bullet} on its boundary; the rest of the disk's boundary consists of copies of arcs in $b^{\bullet} \cup b^{+,\bullet}$ and intervals on the binding B^{\bullet} . The intersection with A_{ϵ}^{\bullet} must contain a basepoint, and thus we have exactly one basepoint in each component of $S_{\epsilon}^{\bullet} \setminus (b^{\bullet} \cup b^{+,\bullet})$. Thus, restricting the gluing of \mathcal{H}^{L} and \mathcal{H}^{R} to these disks results in a pairing – each disk in $S_{\epsilon}^{L} \setminus (b^{L} \cup b^{+,L})$ is glued to a disk in $S_{\epsilon}^{R} \setminus (b^{R} \cup b^{+,R})$ along an interval of $A_{\epsilon}^{L} = -A_{\epsilon}^{R}$. Thus, $S' \setminus b'$ consists of $|E_{+}^{L}| = \frac{|E^{L}|}{2}$ disks, each containing exactly one basepoint.

Next, we observe the following.

Proposition 5.3. The arcs in b' are the standard perturbations (i.e., perturbations 'to the right', as in [*HKM09a*]) of the arcs in a'.

Proof. This follows immediately from the construction in Section 3.2, as each arc \tilde{a}_i^{\bullet} is a perturbation to the left of the arc $b_i^{+,\bullet}$, and each arc a_i^{\bullet} is a perturbation to the left of b_i^{\bullet} .

Note that this implies that we can replace b' with a' in the statement of Proposition 5.2.

Recall from Section 2.3.6 the definition of the monodromy associated to the open book (S, h) built by gluing a pair of compatible foliated open books: The abstract map $h : S \to S$ is defined by flowing S_0 through the manifold in the positive *t*-direction to S_{2k} , a map denoted by ι and then applying the left and right monodromies to the appropriate subsurfaces.

Proposition 5.4. With the above definitions, $a''_i = a'_i$ (via the trivial identification of the ϵ and 0 pages). Furthermore, up to isotopy fixing the boundary, $h: S' \to S''$ maps the arcs b'_i onto b''_i .

Proof. The first statement follows immediately from the above discussion. To prove the second assertion, consider the identifications

$$R_{\epsilon}^{L} \cong R_{+}(M^{L}) \cong R_{-}(M^{R}) \cong R_{2k}^{R}$$
 and $R_{\epsilon}^{R} \cong R_{+}(M^{R}) \cong R_{-}(M^{L}) \cong R_{2k}^{L}$

in the definition of ι .

Each of the surfaces is defined as a neighborhood of a graph, and we note that away from a collar neighborhood of $A_{\epsilon}^{L} = -A_{\epsilon}^{R}$ and $A_{2k}^{R} = -A_{2k}^{L}$ the identifications may be chosen to induce isotopies

$$\gamma_i^{+,L} \cong \delta_i^L \cong \delta_i^R \cong \gamma_i^{-,R}$$
 and $\gamma_i^{+,R} \cong \delta_i^R \cong \delta_i^L \cong \gamma_i^{-,L}$

(Recall that δ_i are the (un)stable separatrices of the foliation connecting h_i to the elliptic points.)

Away from $A_{\epsilon}^{L} = -A_{\epsilon}^{R}$, the **b**' agree with $\gamma^{+,\bullet}$ curves, which are carried by ι to $\gamma^{-,\bullet}$ curves before being sent by h^{R} and h^{L} to the **b**'' curves on S''. As the collar neighborhood of $-A_{0}^{L} \cup A_{\epsilon}^{L} = A_{0}^{R} \cup -A_{\epsilon}^{R}$ is a union of disks, the statement follows.

Proof of Theorem 5.1. The above propositions demonstrate that the multipointed Heegaard diagram \mathcal{H} constructed above corresponds to the open book (S, h) obtained by gluing the sorted foliated open books $(\{S_i^L\}, h^L)$ and $(\{S_i^R\}, h^R)$. Indeed, first, *S* is diffeomorphic to *S'* and *S''*, and by Proposition 5.2 the page *S'* is cut by a' into $|\Gamma|$ disks, each containing a basepoint. Furthermore, by Proposition 5.3, the arcs in b' are obtained by the usual perturbation of the a' arcs. Lastly, by Proposition 5.4, the arcs of a'' are the image of the arcs of a' under the identification of *S'* with *S''*, while the arcs in b'' are the image of the arcs of a' under the identification of *S'* with *S''*, while the arcs in b'' are the image of the arcs of b' under a diffeomorphism in the mapping class of *h*. There is only one generator in the page *S'*, which by definition represents the multipointed contact invariant of ξ , while by construction it is also the box tensor of the bordered contact invariants for ξ^L and ξ^R . This completes the proof.

6. Relationship to the HKM contact element

In this section, we relate the invariants defined in this paper to the HKM contact invariant, that is, the contact invariant for sutured manifolds from [HKM09a]. Let $\mathcal{Z} = (Z, a, m)$ be an arc diagram and $F = F(\mathcal{Z})$ be the corresponding surface. The union of Z and the parametrizing arcs $\coprod_{i=1}^{2k} e_i$ on F is an embedded graph, denoted by $G(\mathcal{Z}) \subset F$. For any subset r of parametrizing arcs, Zarev defines a bordered sutured manifold W_r , called a *cap*, in [Zar10, Definitions 2.5 and 6.1]. We recall the definition for a β -type arc diagram \mathcal{Z} .

First, W_r consists of the three-manifold $W = F \times [0, 1]/\sim$, where $(x, t) \sim (x, t')$ whenever $x \in \partial F$. Thus, $\partial W = (-F \times \{0\}) \cup (F \times \{1\})$, and the bordered and sutured parts of ∂W are $-F \times \{0\}$ and $F \times \{1\}$, respectively. Second, each component of Z is a pushoff of an arc in ∂F into the interior of F; denote the union of these arcs in ∂F by S_- . Let R be the union of the disk regions enclosed by Z and S_- . Then, the sutures $\Gamma_r \subset F \times \{1\}$ are defined as $\partial(R \cup N(r)) \setminus S_-$, where $N(r) = \coprod_{e_i \in r} N(e_i)$. Furthermore, $R_-(\Gamma_r) = R \cup N(r)$. Finally, $-F \times \{0\}$ is parametrized by -Z.

Zarev constructs a bordered sutured Heegaard diagram $\mathcal{H}^r = (\Sigma^r, \alpha^r, \beta^r, -\mathcal{Z})$ for any cap \mathcal{W}_r as follows. Let $D = (-Z) \times [0, 1]$. The endpoints of any parametrizing arc e_i is a pair of matched points in $a \subset -Z$. To construct Σ^r , first for every $e_i \notin r$, do 0-surgery on D along the surface framed 0-sphere obtained by slightly pushing $(\partial e_i) \times \{0\}$ into $\operatorname{Int}(D)$. Then, for any $e_i \in r$ attach a band to D along a small neighborhood in $-Z \times \{1\}$ of the 0-sphere $(\partial e_i) \times \{1\}$ so the resulting surface remains oriented. This diagram has no β -circles. However, associated to each e_i there is a β arc $\beta_i^r \subset \Sigma^r$ which connects the points $(\partial e_i) \times \{0\}$. If $e_i \in r$, β_i^r is the union of $(\partial e_i) \times [0, 1]$ and the core of the corresponding band. If $e_i \notin r$, β_i^r goes over the tube on the boundary of the corresponding one-handle once. Write $\beta^r = \{\beta_1^r, \ldots, \beta_{2k}^r\}$. Next, for any $e_i \notin r$ let $\alpha_i^r \subset \Sigma^r$ be the dual circle to β_i^r , that is, the belt sphere of the associated one-handle. This circle intersects β_i^r in a single point denoted by x_i^r and is disjoint from β_j^r for any $j \neq i$. Then, let $\alpha^r = \{\alpha_i^r \mid e_i \notin r\}$. Finally, $G(-\mathcal{Z})$ is embedded in Σ^r such that -Zis identified with $(-Z) \times \{0\}$ and any edge e_i is identified with β_i^r . Clearly, this diagram has a unique generator $\mathbf{x}^r = \{x_i^r \mid e_i \notin r\}$. See Figure 6.1.

We now consider a particular cap that arises naturally in the context of the bordered sutured manifold (M, Γ, \mathcal{Z}) associated to a foliated contact three-manifold (M, ξ, \mathcal{F}) . As in Section 3.1, let $\mathcal{Z} = (Z, a, m)$



Figure 6.1. Left: The arc diagram for the torus example in Figure 3.1; note that the arc e_i corresponding to δ_i is labelled with i. Right: The bordered sutured diagram \mathcal{H}^r for $r = \{e_2, e_4\}$.

be the arc diagram which parametrizes the bordered part $F = F(\mathcal{Z})$ in ∂M and let $\Gamma(\mathcal{F})$ denote the dividing set associated to the foliation \mathcal{F} . Let k be the number of elements in H_{\pm} , so |a| = 4k. Each matched pair of points in a corresponds to a hyperbolic point and to a parameterizing arc $e_i \subset \delta_i$, where $i \in [2k]$ is the index of the point. From now on, fix $r = \coprod_{i \in H_+} e_i$ and define the associated cap $\mathcal{W} := \mathcal{W}_r$ with suture Γ_r .

Correspondingly, we define the sutured manifold $(M, \widetilde{\Gamma}) := (M, \Gamma, \mathcal{Z}) \cup_F \mathcal{W}$. We will show here that the sutures $\widetilde{\Gamma}$ may in fact be identified with $-\Gamma(\mathcal{F})$. Recall that $\widetilde{\Gamma}$ separates ∂M into regions $R_{\pm}(\widetilde{\Gamma})$. It is straightforward from the definition that

$$R_{-}(\widetilde{\Gamma}) = R_{-}(\Gamma) \cup R_{-}(\Gamma_{r}) = R_{-}(\Gamma) \bigcup (R \cup N(r)).$$

Observe that $R_{-}(\Gamma) \bigcup (R \cup N(r))$ is a neighborhood of the stable separatrices of points in H_{+} . Thus, we can identify it with $R_{+}(\mathcal{F})$, and as a consequence, $\widetilde{\Gamma} = -\partial R_{+}(\mathcal{F})$ and is isotopic to $-\Gamma(\mathcal{F})$. To avoid a proliferation of notation, we will henceforth denote the sutured manifold obtained by gluing the cap as $(M, \Gamma) := (M, -\Gamma(\mathcal{F}))$.

Consequently, if we define $\overline{W} = (-W, \Gamma, -\overline{Z})$, then

$$(-M, -\Gamma(\mathcal{F})) = (-M, \Gamma, \overline{\mathcal{Z}}) \cup_{\overline{F}} \overline{\mathcal{W}}.$$

The gluing formula gives the following:

$$SFC(-M, -\Gamma(\mathcal{F})) \simeq \widehat{BSA}(-M, \Gamma, \overline{\mathcal{Z}}) \boxtimes_{\mathcal{A}(\overline{\mathcal{Z}})} \widehat{BSD}(\overline{\mathcal{W}}).$$

Let $\iota_r \in \mathcal{A}(\overline{Z})$ be the idempotent corresponding to the horizontal arcs for the points in *a* that lie on the boundary of *r*. It follows from the special structure of the Heegaard diagram for \mathcal{W} that $\widehat{BSD}(\overline{\mathcal{W}})$ is an elementary type *D* module generated by ι_r ; see [Zar10, Proposition 6.2]. Thus,

$$SFH(-M, -\Gamma(\mathcal{F})) \cong H_*\left(\widehat{BSA}(-M, \Gamma, \overline{\mathcal{Z}})\right) \cdot \iota_r$$

See [Zar10, Theorem 6.5].

We now prove Theorem 3 for ι_+ given by ι_r .

Proof of Theorem 3. Suppose $(\{S_i\}_{i=0}^{2k}, h, \{\gamma_i^{\pm}\})$ is a sorted foliated open book compatible with the triple (M, ξ, \mathcal{F}) . Let $\mathcal{H} = (\Sigma, \alpha, \beta = \beta^a \cup \beta^c, \mathcal{Z})$ be the bordered sutured Heegaard diagram constructed in Section 3.2 for (M, Γ, \mathcal{Z}) . We begin with a brief sketch of the argument before presenting it in detail. First, we will construct a sutured Heegaard diagram for $(M, -\Gamma(\mathcal{F}))$ by gluing \mathcal{H} to the diagram \mathcal{H}^r , where \mathcal{H}^r denotes the diagram for the cap \mathcal{W} described above. Then, we show that after possibly performing some handleslides and 2k-times destabilizing this diagram, one recovers the sutured Heegaard diagram corresponding to the partial open book $(S' = S_0, P' = P_0, h' = h|_{P_{2k}} \circ \iota)$ compatible with the contact sutured manifold $(M, \Gamma(\mathcal{F}), \xi)$, following the conventions in [HKM09a, Section 2]. Note that this is a diagram for $(M, -\Gamma(\mathcal{F}))$. Letting $\mathbf{x}^r = \{x_i^r \mid i \in H_-\}$ denote the generator of \mathcal{H}^r , we additionally prove that the map induced by the Heegaard moves sends the generator $\mathbf{x} \otimes \mathbf{x}^r$ in $SFC(\overline{\mathcal{H}} \cup \overline{\mathcal{H}^r})$ to the generator which represents the contact invariant $EH(M, \Gamma(\mathcal{F}), \xi) \in SFH(-M, -\Gamma(\mathcal{F}))$.

After gluing \mathcal{H} and \mathcal{H}^r along Z, for every $i \in [2k]$, the arc β_i^r in Σ^r will be paired with the arc β_i^a in Σ , producing a circle $\tilde{\beta}_i$. For any $i \in H_+$, there exists a circle $\tilde{\alpha}_i$ in α , and for any $i \in H_-$, we define $\tilde{\alpha}_i = \alpha_i^r$. We write $\alpha^r = \{\tilde{\alpha}_i \mid i \in H_-\}$. Then

$$\mathcal{H}' = \mathcal{H} \cup \mathcal{H}^r = \left(\Sigma' = \Sigma \cup_Z \Sigma^r, \alpha' = \alpha \cup \alpha^r, \beta' = \beta^c \cup \{\widetilde{\beta}_i\}_{i \in [2k]} \right)$$

is a Heegaard diagram for $(M, -\Gamma(\mathcal{F}))$. In this diagram, we see that $\widetilde{\alpha}_i \cap \widetilde{\beta}_i = \{x_i^+\}$ for $i \in H_+$, while $\widetilde{\alpha}_i \cap \widetilde{\beta}_i = \{x_i^r\}$ for $i \in H_-$. Furthermore, for $i \in H_-$, the α -circle $\widetilde{\alpha}_i$ is disjoint from all circles in

 β' aside from $\tilde{\beta}_i$. On the other hand, since \mathcal{H} is defined using an abstract sorted foliated open book decomposition, Condition (2) of Definition 2.21 implies that, for any $i, j \in H_+$, the arc $\beta_i^a \subset \Sigma$ is disjoint from the circle $\tilde{\alpha}_j \subset \Sigma$ if and only if j > i. Thus, for $i \in H_+$, the β -circle $\tilde{\beta}_i$ is disjoint from the subset

$$\{\alpha_1,\ldots,\alpha_{2g_0+n_0+|A_0|-k-2}\}\cup\{\widetilde{\alpha}_j\mid j\in H_+\text{ and }j>i\}\cup\alpha^r\subset\alpha'.$$

Suppose $i \in H_-$. Since $\tilde{\alpha}_i$ intersects $\tilde{\beta}_i$ once, the curves in α can be made disjoint from $\tilde{\beta}_i$ by sliding each curve in α that intersects $\tilde{\beta}_i$ over $\tilde{\alpha}_i$. Then we may destabilize \mathcal{H}' using the pair $\tilde{\alpha}_i$ and $\tilde{\beta}_i$. Repeating this procedure for each $i \in H_-$ yields a Heegaard diagram $\mathcal{H}'' = (\Sigma'', \alpha'', \beta'')$ for $(\mathcal{M}, -\Gamma(\mathcal{F}))$, where $\alpha'' = \alpha, \beta'' = \beta^c \cup {\{\tilde{\beta}_i\}_{i \in H_+}}$, and Σ'' is obtained from Σ by attaching bands along $\partial \beta_i^a$ for each $i \in H_+$.

Write $H_- = \{j_1 < j_2 < \cdots < j_k\}$. Let $\mathcal{H}'_l = (\Sigma'_l, \alpha'_l, \beta'_l)$ be the Heegaard diagram obtained from \mathcal{H}' by applying the aforementioned Heegaard moves for j_1, \ldots, j_{l-1} . Denote by

$$f_{l}^{-}: SFC(\overline{\mathcal{H}'}_{l}) = SFC(\Sigma'_{l}, \beta'_{l}, \alpha'_{l}) \to SFC(\overline{\mathcal{H}'}_{l+1}) = SFC(\Sigma'_{l+1}, \beta'_{l+1}, \alpha'_{l+1})$$

the composition of chain maps corresponding to the *l*th sequence of moves.

Let $f^- = f_k^- \circ \cdots \circ f_l^-$. Note that the intersection points for \mathcal{H} and \mathcal{H}'' are in one-to-one correspondence, and $\mathbf{x} \in SFC(\overline{\mathcal{H}''})$ denotes the generator corresponding to the intersection point \mathbf{x} for \mathcal{H} . Let f_l^h be the composition of chain maps associated with the sequence handleslides, and let f_l^{ds} be the chain map associated with the subsequent destabilization. By an argument analogous to that in the proof of Proposition 4.5, we have that for an appropriate choice of the complex structure $f_l^- = f_l^{ds} \circ f_l^h(\mathbf{x} \otimes \mathbf{x}_l^r) = \mathbf{x} \otimes \mathbf{x}_{l+1}^r$, and so $f^-(\mathbf{x} \otimes \mathbf{x}^r) = \mathbf{x}$. Here, $\mathbf{x}_l^r = \{x_{i_l}^r \mid l \leq i \leq k\}$.

Next, we simplify the diagram \mathcal{H}'' using the pairs $\tilde{\alpha}_i$ and $\tilde{\beta}_i$ for all $i \in H_+$. Suppose $H_+ = \{i_1 < i_2 < \cdots < i_k\}$. Note that $\tilde{\beta}_{i_1} \cap \tilde{\alpha}_{i_1} = x_{i_1}^+$ while $\tilde{\beta}_{i_1}$ is disjoint from the rest of the α -circles. As before, first slide every β -circle that intersects $\tilde{\alpha}_{i_1}$ over $\tilde{\beta}_{i_1}$ to remove the intersection points and then destabilize the diagram using $\tilde{\alpha}_{i_1}$ and $\tilde{\beta}_{i_1}$. In the new diagram, $\tilde{\beta}_{i_2}$ is disjoint from all α -circles except $\tilde{\alpha}_{i_2}$ and $\tilde{\beta}_{i_1} \cap \tilde{\alpha}_{i_1} = x_{i_2}^+$. So we can repeat this simplification for i_2 and in fact continue until $i = i_k$. At the end, we get a surface homeomorphic to $\Sigma \setminus \coprod_{i \in H_+} N(\beta_i^a)$. By definition, $\Sigma = S_{\epsilon} \cup_B (-S_0)$, where S_{ϵ} is a copy of S_0 . Therefore,

$$\Sigma \setminus \coprod_{i \in H_+} N(\beta_i^a) \cong (S_0 \setminus \coprod_{i \in H_+} N(\gamma_i^+)) \cup_B (-S_0) = P_0 \cup_B (-S_0)$$

and this surface is equipped with

$$\{\alpha_1, \ldots, \alpha_{2g_0+n_0+|A_0|-k-2}\}$$
 and $\{\beta_1, \ldots, \beta_{2g_0+n_0+|A_0|-k-2}\}.$

This is exactly the sutured Heegaard diagram defined in [HKM09a] associated to the partial open book (S', P', h').

Let \mathcal{H}''_l be the Heegaard diagram obtained from \mathcal{H}'' after applying the above Heegaard moves for i_1, \ldots, i_{l-1} , and denote the chain map induced by the *l*th sequence of moves by

$$f_l^+: SFC(\overline{\mathcal{H}_l''}) \to SFC(\overline{\mathcal{H}_{l+1}''}).$$

Let $f^+ = f_k^+ \circ \cdots \circ f_1^+$. Once again, by an argument analogous to that in the proof of Proposition 4.5 we have that for an appropriate choice of complex structure, $f^+(\mathbf{x})$ is the generator representing the contact invariant $\text{EH}(M, \Gamma(\mathcal{F}), \xi)$, that is, $\{x_1, \ldots, x_{2g_0+n_0+|A_0|-k-2}\}$.

Hence, $f_*^+ \circ f_*^-(c_A(\xi) \cdot \iota_r) = f_*^+ \circ f_*^-([\mathbf{x} \otimes \mathbf{x}^r]) = \operatorname{EH}(M, \Gamma(\mathcal{F}), \xi).$

7. Examples

Example 7.1. For our first example, consider the foliated open books obtained as follows. Begin with the open book for (S^3, ξ_{std}) whose pages are disks. Embedding a sphere in this open book so that it



Figure 7.1. The sphere shown on the left separates S^3 into two tight balls and induces a foliated open book for each. The elliptic points are labelled with the signs associated to the ball whose first page is connected, as shown on the right.



Figure 7.2. The bordered sutured Heegaard diagram adapted to the sorted foliated open book of *Example 7.1.*

intersects the binding in four points, as in Figure 7.1, produces two tight balls. See Figure 7.3. We first consider the ball whose initial page is a rectangle.

Observe that this ball can also be obtained by cutting the solid torus of Example 2.5 along a meridional disk disjoint from the binding, which has the effect of removing a pair of hyperbolic points from the induced foliated open book. In this example, the first hyperbolic point is positive and the second negative, so the foliated open book is automatically sorted. The associated Heegaard diagram \mathcal{H}_1 is shown in Figure 7.2.

Let *x* be the unique intersection point on the S_{ϵ} part of the diagram, and let *y* be the other intersection point. Let ρ_1 and $\underline{\rho_2}$ be the algebra elements corresponding to the Reeb chords on the inside and outside components of $\partial \overline{\mathcal{H}_1}$, as seen on Figure 7.2. The type *A* structure $\widehat{BSA}(\overline{\mathcal{H}_1})$ is generated by *x* and *y*, and has structure maps

$$m_2(y, \rho_1) = x$$
$$m_2(y, \rho_2) = x.$$

The contact class $c_A(B^3, \xi_1, \mathcal{F}_1)$ is the homotopy equivalence class of x.

Example 7.2. As a second example we consider the ball in (S^3, ξ_{std}) which is the complement of the previous example. See Figure 7.3.



Figure 7.3. The shaded regions represent the pages of the solid ball from Example 7.1, while their unshaded complements are the pages of a foliated open book for the ball of Example 7.2.



Figure 7.4. A sorted foliated open book for the ball of Example 7.2.

Observe that S_0 is disconnected, and the first negative hyperbolic point is followed by a second positive hyperbolic point. The associated foliated open book is not sorted, so we stabilize it before constructing the associated bordered sutured Heegaard diagram \mathcal{H}_2 . The result of the stabilization is shown in Figure 7.4.

By keeping track of the four elliptic points in the embedded open book decomposition of (S^3, ξ_{std}) and their images on the two Heegaard diagrams, we see that the corresponding Heegaard diagram \mathcal{H} for (S^3, ξ_{std}) is obtained by gluing \mathcal{H}_1 to \mathcal{H}_2 by identifying the outside boundary component of one diagram to the inside boundary component of the other, and vice versa. Thus, to have consistent labels (between \mathcal{H}_1 and \mathcal{H}_2) of the algebra generators for the given foliation, we must label the generator for the inside boundary component of $\overline{\mathcal{H}_2}$ by ρ_2 and the other one by ρ_1 . Let *s* be the unique intersection point on the S_{ϵ} part of $\overline{\mathcal{H}_2}$, and let *t* be the other intersection point. The type *D* structure $\overline{BSD}(\overline{\mathcal{H}_2})$ is generated by *s* and *t*, and has structure map

$$\delta^1(t) = (\rho_1 + \rho_2) \otimes s.$$

The contact class $c_D(B^3, \xi_2, \mathcal{F}_2)$ is the homotopy equivalence class of s.

Example 7.3. We take the box tensor product of the type *A* structure from Example 7.1 and the type *D* structure from Example 7.2, to compute the contact class for (S^3, ξ_{std}) . Considering the idempotents, $\widehat{BSA}(\overline{\mathcal{H}_1}) \boxtimes \widehat{BSD}(\overline{\mathcal{H}_2})$ is generated by $y \otimes t$ and $x \otimes s$. The differential $\partial = \partial^{\boxtimes}$ is trivial, so the homology $H_*(\widehat{BSA}(\overline{\mathcal{H}_1}) \boxtimes \widehat{BSD}(\overline{\mathcal{H}_2}))$ is generated by $[y \otimes t]$ and $[x \otimes s]$. Therefore, $[x \otimes s]$ is the contact class of the glued three-sphere (S^3, ξ_{std}) .

Example 7.4. Finally, we return to the the running example used throughout this paper: the solid torus first introduced in Example 2.5. Recall that Example 3.3 constructed the bordered sutured Heegaard diagram adapted to a sorted foliated open book for this manifold. Here, we compute the associated type *A* structure.

For simplicity, we label the intersection points in Heegaard diagram \mathcal{H} by x_1, x_2, x_3, x_4, y_1 , and y_2 as in Figure 7.5. In this diagram, we have six generators

$$\{x_1y_1, x_1y_2, x_2y_2, x_3y_1, x_3y_2, x_4y_2\}$$



Figure 7.5. The Heegaard diagram \mathcal{H} from Example 3.3, with intersection points labelled so that x_1y_1 is the contact class.



Figure 7.6. The portion of the Heegaard diagram \mathcal{H} from Figure 7.5 relevant to the computation of $\overrightarrow{BSA}(\overline{\mathcal{H}})$. The boundary is parametrized by an arc diagram which consists of two arcs with eight points on them. The intervals between points are labeled with $\{1, \ldots, 6\}$ in gray.

where x_1y_1 is the generator $x_1^+x_3^+$ defined in Section 3.2. Then, we simplify our depiction of the Heegaard diagram \mathcal{H} by first removing the domains adjacent to $\partial \Sigma \setminus Z$ and then cutting along the intersection points x_1 , y_1 and y_2 . Moreover, $\overline{\mathcal{H}}$ is obtained from \mathcal{H} by switching α and β , so we draw β arcs in red and α circles in blue. See Figure 7.6.

Every region is adjacent to the boundary, so $m_1 = 0$. We computed m_i for i > 1, by finding the local coefficients of curves and computing their Maslov indices. Then, it is easy to see that the curves with Maslov index one contribute to the maps listed below. Moreover, $m_i = 0$ for i > 3. Note that instead of

$$m_2(x_3y_2, I_{\{2,4\}}a(\{1,5\})) = x_3y_1$$

we write simply

$$m_2(x_3y_2, \{1, 5\}) = x_3y_1,$$

as the appropriate completion of a set of Reeb chords is clear from the context. The nontrivial maps are as follows.

$$m_{2}(x_{3}y_{2}, 5) = x_{4}y_{2}$$

$$m_{2}(x_{3}y_{2}, \{1, 5\}) = x_{3}y_{1}$$

$$m_{2}(x_{3}y_{2}, \{2, 4\}) = x_{3}y_{1}$$

$$m_{2}(x_{3}y_{2}, 2) = x_{2}y_{2}$$

$$m_{2}(x_{3}y_{2}, 23) = x_{1}y_{2}$$

$$m_{2}(x_{3}y_{2}, 56) = x_{1}y_{2}$$

$$m_{2}(x_{3}y_{2}, \{123, 5\}) = x_{1}y_{1}$$

$$m_{2}(x_{3}y_{2}, \{2, 456\}) = x_{1}y_{1}$$

$$m_{2}(x_{4}y_{2}, 1) = x_{3}y_{1}$$

$$m_{2}(x_{4}y_{2}, 1) = x_{3}y_{1}$$

$$m_{2}(x_{4}y_{2}, 0) = x_{1}y_{2}$$

$$m_{2}(x_{2}y_{2}, 456) = x_{1}y_{1}$$

$$m_{2}(x_{2}y_{2}, 456) = x_{1}y_{1}$$

$$m_{2}(x_{2}y_{2}, 456) = x_{1}y_{1}$$

$$m_{2}(x_{3}y_{1}, 23) = x_{1}y_{1}$$

$$m_{2}(x_{3}y_{1}, 23) = x_{1}y_{1}$$

$$m_{3}(x_{4}y_{2}, \{1, 6\}, 5) = x_{1}y_{1}$$

$$m_{3}(x_{4}y_{2}, \{4, 6\}, 2) = x_{1}y_{1}$$

$$m_{3}(x_{4}y_{2}, 4, \{2, 6\}) = x_{1}y_{1}$$

$$m_{3}(x_{4}y_{2}, 4, \{2, 6\}) = x_{1}y_{1}$$

$$m_{3}(x_{2}y_{2}, \{3, 4\}, 2) = x_{1}y_{1}$$

$$m_{3}(x_{2}y_{2}, \{3, 4\}, 2) = x_{1}y_{1}$$

$$m_{3}(x_{3}y_{2}, \{1, 23\}, 5) = x_{1}y_{1}$$

$$m_{3}(x_{3}y_{2}, \{1, 23\}, 5) = x_{1}y_{1}$$

$$m_{3}(x_{3}y_{2}, \{4, 23\}, 2) = x_{1}y_{1}$$

$$m_{3}(x_{3}y_{2}, \{4, 56\}, 5) = x_{1}y_{1}$$

$$m_{3}(x_{3}y_{2}, \{4, 56\}, 5, 6\}) = x_{1}y_{1}$$

$$m_{3}(x_{3}y_{2}, \{1, 56\}, 5, 6\}) = x_{1}y_{1}$$

Example 7.5. Our next example is the solid torus in (S^3, ξ_{std}) which is the complement of the previous example. As in Example 7.2, the embedded foliated open book arising from the disk open book for (S^3, ξ_{std}) is not sorted. A sequence of two stabilizations results in a sorted foliated open book, the first and last page of which are shown in Figure 7.7.

The construction from Section 3.2 yields the Heegaard diagram \mathcal{H}' shown in Figure 7.8.



Figure 7.7. The first and last page of a sorted foliated open book for the solid torus of Example 7.5.



Figure 7.8. The bordered sutured Heegaard diagram \mathcal{H}' adapted to the sorted foliated open book depicted in Figure 7.7.

We label the intersection points in Heegaard diagram \mathcal{H}' by $x'_1, x'_2, x'_3, x'_4, x'_5, x'_6, y'_1$, and y'_2 as in Figure 7.8. We have eight generators

$$\{x_1'y_1', x_1'y_2', x_2'y_2', x_3'y_1', x_4'y_1', x_4'y_2', x_5'y_1', x_6'y_2'\},\$$

where $x'_1y'_1$ is the generator $x_2^+x_4^+$ defined in Section 3.2. By removing the domains adjacent to $\partial \Sigma \setminus Z$ and then cutting along the points x'_1, x'_4, y'_1 and y'_2 we get the planar depiction of the Heegaard diagram \mathcal{H}' shown in Figure 7.9. By matching elliptic points again, as in Example 7.2, we obtain labels $\{1, \ldots, 6\}$ on the intervals of the arc diagram for \mathcal{H}' consistent with those for the diagram \mathcal{H} from Example 7.4.

This time, we have a nice diagram, and the type D structure is straightforward to compute. The type D structure maps are listed below.

$$\begin{split} \delta^{1}(x'_{1}y'_{1}) &= 0 \\ \delta^{1}(x'_{1}y'_{2}) &= 2 \otimes x'_{1}y'_{1} + 5 \otimes x'_{1}y'_{1} \\ \delta^{1}(x'_{2}y'_{2}) &= I \otimes x'_{3}y'_{1} + 1 \otimes x'_{1}y'_{2} \\ \delta^{1}(x'_{3}y'_{1}) &= 12 \otimes x'_{1}y'_{1} \\ \delta^{1}(x'_{4}y'_{1}) &= 123 \otimes x'_{1}y'_{1} + 456 \otimes x'_{1}y'_{1} + 3 \otimes x'_{3}y'_{1} + 6 \otimes x'_{5}y'_{1} \\ \delta^{1}(x'_{4}y'_{2}) &= 123 \otimes x'_{1}y'_{2} + 456 \otimes x'_{1}y'_{2} + 23 \otimes x'_{2}y'_{2} + 2 \otimes x'_{4}y'_{1} + 5 \otimes x'_{4}y'_{1} + 56 \otimes x'_{6}y'_{2} \\ \delta^{1}(x'_{5}y'_{1}) &= 45 \otimes x'_{1}y'_{1} \\ \delta^{1}(x'_{6}y'_{2}) &= 4 \otimes x'_{1}y'_{2} + I \otimes x'_{5}y'_{1} \end{split}$$

Example 7.6. We take the box tensor product of the type *A* structure from Example 7.4 and the type *D* structure from Example 7.5 to compute the contact class for (S^3, ξ_{std}) .



Figure 7.9. The portion of the Heegaard diagram \mathcal{H}' from Figure 7.8 relevant to the computation of $\widehat{BSD}(\mathcal{H}')$.

Considering the idempotents, $\widehat{BSA}(\overline{\mathcal{H}}) \boxtimes \widehat{BSD}(\overline{\mathcal{H}'})$ has 8 generators:

$$\begin{pmatrix} x_1y_1 \otimes x'_1y'_1, \ x_1y_2 \otimes x'_2y'_2, \ x_1y_2 \otimes x'_3y'_1, \ x_1y_2 \otimes x'_5y'_1 \\ x_1y_2 \otimes x'_6y'_2, \ x_2y_2 \otimes x'_4y'_1, \ x_3y_2 \otimes x'_4y'_2, \ x_4y_2 \otimes x'_4y'_1 \end{pmatrix}$$

Moreover, the differential $\partial = \partial^{\boxtimes}$ is given as follows:

$$\begin{aligned} \partial \left(x_3 y_2 \otimes x'_4 y'_2 \right) &= x_2 y_2 \otimes x'_4 y'_1 + x_4 y_2 \otimes x'_4 y'_1 + x_1 y_2 \otimes x'_2 y'_2 + x_1 y_2 \otimes x'_6 y'_2 \\ \partial \left(x_2 y_2 \otimes x'_4 y'_1 \right) &= x_1 y_2 \otimes x'_3 y'_1 + x_1 y_1 \otimes x'_1 y'_1 \\ \partial \left(x_4 y_2 \otimes x'_4 y'_1 \right) &= x_1 y_2 \otimes x'_5 y'_1 + x_1 y_1 \otimes x'_1 y'_1 \\ \partial \left(x_1 y_2 \otimes x'_2 y'_2 \right) &= x_1 y_2 \otimes x'_3 y'_1 + x_1 y_1 \otimes x'_1 y'_1 \\ \partial \left(x_1 y_2 \otimes x'_6 y'_2 \right) &= x_1 y_2 \otimes x'_5 y'_1 + x_1 y_1 \otimes x'_1 y'_1 \end{aligned}$$

It is easy to see that the homology is generated by $[x_1y_1 \otimes x'_1y'_1]$ and $[x_1y_2 \otimes x'_2y'_2 + x_2y_2 \otimes x'_4y'_1]$. Therefore, $[x_1y_1 \otimes x'_1y'_1]$ is the contact class (S^3, ξ_{std}) . Observe that this agrees with the result in Example 7.3.

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