Structure–property relationships for 3D-printed PEEK intervertebral lumbar cages produced using fused filament fabrication

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Recent advances in the additive manufacturing technology now enable fused filament fabrication of polyetheretherketone (PEEK). A standardized lumbar fusion cage design was 3D printed with different speeds of the printhead nozzle to investigate whether 3D-printed PEEK cages exhibit sufficient material properties for lumbar fusion applications. It was observed that the compressive and shear strength of the 3D-printed cages were 63–71% of the machined cages, whereas the torsion strength was 92%. The printing speed is an important printing parameter for 3D-printed PEEK, which resulted in up to 20% porosity at the highest speed of 3000 mm/min, leading to reduced cage strength. Printing speeds below 1500 mm/min can be chosen as the optimal printing speed for this printer to reduce the printing time while maintaining strength. The crystallinity of printed PEEK did not differ significantly from the as-machined PEEK cages from extruded rods, indicating that the processing provides similar microstructure.

I. INTRODUCTION

Additive manufacturing (AM), more commonly known as three-dimensional (3D) printing, has emerged as a new frontier for medical device manufacturing.¹ Although relatively new, AM has already been used to fabricate medical devices and surgical instruments from a range of metallic and polymeric materials.²–⁶ Spinal surgery is one of the therapeutic areas in which there has been early interest in AM. AM techniques, including fused filament fabrication (FFF) and selective laser sintering (SLS), have been successfully used to manufacture spinal implants,⁷,⁸ including spinal cages.⁹–¹¹

Spinal cages are load-bearing surgical implants commonly used to stabilize the spine and to treat back pain resulting from degenerative disc disease and spondylolisthesis.¹²,¹³ Figueroa et al.¹¹ manufactured spinal cages via FFF with acrylonitrile butadiene styrene (ABS) and polycarbonate (PC). Cavazos et al.⁹ also investigated the viability of several design concepts in 3D-printed intervertebral lumbar cages based on PC. Previous studies investigated design concepts for lumbar cages to establish technical feasibility of FFF with PC and ABS. However, these relatively low processing temperature polymers have limited mechanical properties compared to polyetheretherketone (PEEK) and no prior history of clinical use in this application.¹⁴ The recent advances of FFF techniques to include high processing temperature polymers, including PEEK, motivated our research group to examine spinal cages produced with this novel manufacturing technique.

PEEK has been used for intervertebral lumbar cages since the 1990s. PEEK is biocompatible, provides
durability and strength, and has an elastic modulus comparable to cortical bone.\textsuperscript{15} Most importantly, PEEK is radiolucent, enabling surgeons to monitor positioning and bone ingrowth. However, PEEK’s hydrophobicity inhibits direct bone apposition, which may result in unsatisfactory outcomes of fusion.\textsuperscript{16} Furthermore, PEEK biomaterials are costly. Challenging designs of PEEK cages do not allow for traditional manufacturing methods such as injection molding. Hence, they currently need to be machined from bulk PEEK which results in material loss of approximately 64\%. As a result, there has been interest in new technologies such as AM to manufacture PEEK implants, including cages, to improve their integration with bone as well as to minimize the amount of material lost during processing.

Prior to the development of commercially available FFF machines for PEEK, SLS was the primary AM processing route for polyketones such as PEEK.\textsuperscript{17,18} SLS processing of PEEK is complicated by particle morphology and size distribution. In addition to the complexity of powder production and handling, SLS equipment is costly and generates gaseous laser sintering powder material waste.\textsuperscript{19,20} Lastly, residual powder, which is unsintered, is not reusable and is thus considered as waste. These limitations have fueled both commercial and academic interest in FFF of PEEK as an alternative to SLS. Yet, relatively few studies discuss FFF of PEEK.\textsuperscript{19–22} Wu et al.\textsuperscript{19} developed a PEEK 3D printing system and defined optimal heated bed and printhead nozzle temperatures for FFF of PEEK. Vaezi et al.\textsuperscript{20} later compared a syringe-based extrusion system and FFF for PEEK to manufacture porous structures. Rahman et al.,\textsuperscript{21} on the other hand, investigated the mechanical properties of dog-bone PEEK specimen printed via FFF. Finally, Cicala et al.\textsuperscript{22} used FFF in a survey of high-temperature engineering polymers including PEEK.

Thus far, spinal cages have been 3D printed via FFF out of several low-temperature polymers, such as PC and ABS, but not PEEK. Although FFF has been shown to be feasible for PEEK, previous research has not focused on specific clinical applications with structural load-bearing demands. Accordingly, we sought to address the following research questions: (i) How much of the machined PEEK cages’ strength can be achieved with 3D-printed PEEK cages via FFF? (ii) What is the optimum printing speed for PEEK spinal cages and how does it affect the strength of printed cages? (iii) How are the microstructure and crystallinity affected by FFF compared to machined PEEK cages?

II. MATERIALS AND METHODS

A. Materials & FFF process

Medical grade PEEK used in this study was obtained in two forms: 25 mm diameter extruded rod and an experimental 1.75 mm diameter filament developed from PEEK OPTIMA™ LT1 (Invibio Biomaterial Solutions Ltd., Thornton Cleveleys, U.K.). LT1 is the most widely used grade of PEEK for implant applications, with a melt flow index of 3.4 and molecular weight of 115,000.\textsuperscript{23} It has a reported melting temperature of ~343 °C and glass transition temperature of ~145 °C with a crystallization peak of ~160 °C.\textsuperscript{24}

The lumbar cage design used in this study was developed as a reference for ASTM interlaboratory studies [Fig. 1(a)].\textsuperscript{25} The STL file of the cage was created from a 3D model drafted using commercially available software (SolidWorks 2016; Dassault Systèmes, Villacoublay, France). Simplify3D software (available commercially) was used to digitally slice the samples and create the g-code. A batch of six cages was printed on the heated bed. Temporary support structures of 3 mm were generated in the holes of both sides of the cages to ensure that the horizontal cage struts did not collapse during printing [Fig. 1(b)]. In addition, to increase the adhesion between the print object and the print bed, brims were added to the cages [Fig. 1(c)]. These support structures were subsequently trimmed from the cages after printing and before any mechanical or physical property testing.

The professional 3D printer used in this study was Indmatec HPP 155/Gen 2, (Apium Additive Technologies GmbH, Karlsruhe, Germany), which was designed specifically for PEEK FFF AM [Fig. 2(a)]. It has a print volume of 155 × 155 × 155 mm and the printing environment is thermally isolated inside an insulated build chamber. The nozzle diameter for the extruder was 0.4 mm. To increase the adhesion between the cages and the heated bed further, one layer of Dimafix® (DIMA 3D Printers, Valladolid, Spain) solution was applied onto the heated bed prior to printing.

Printing conditions were kept same for all the cohorts (Table I), except for the printhead (extruder) nozzle X/Y axis movement speed, also referred as “printing speed.” Four printed cohorts were fabricated with 1000, 1500, 2000, and 3000 mm/min printing speeds using the PEEK OPTIMA™ LT1 filament [Fig. 2(b)]. The printing time and the filament usage for FFF cohorts were recorded (Table II). In addition to the printed cohorts, control samples were machined from the PEEK OPTIMA™ LT1 extruded rod [Fig. 2(b)].

B. Mechanical testing

Five samples from each cohort were tested under compression, compression–shear, and torsion according to the ASTM F2077\textsuperscript{26} and in accordance with ISO 17025 quality system requirements.\textsuperscript{27} Tests were conducted on a MTS Mini Bionix 858 system (MTS Systems Corporation, Eden Prairie, Minnesota) equipped with calibrated load and displacement sensors. The load cell capacity was 15 kN for compression and shear tests, and the strain rate was chosen as 25 mm/min (as per ASTM F2077\textsuperscript{26}).
The cell capacity for torque was 100 N m and torsion tests were conducted at 60°/min. Load–displacement and torque–angle curves were plotted from the data. Stiffness, ultimate displacement/angle, and ultimate load/torque values were calculated from the curves using a custom script in MATLAB 2016b (The MathWorks, Inc., Natick, Massachusetts), using the recommendations in ASTM F207726 as a guide.

**C. Imaging**

Prior to testing, three cages from each cohort were micro-CT scanned at 10 μm isotropic resolution using a Scanco μCT 80 (Scanco Medical, Brüttisellen, Switzerland). Both ends of the cage design, where it was solid cuboid, were defined as the regions of interest to obtain porosity measurements per cage. A control volume
was created for the porosity calculations. Two control volume measurements were taken from the designated regions per cage to compare the average porosity and the pore size between the cohorts \( (n = 6 \) per cohort). The histogram of the grayscale values (which correspond with densities) resulting from the micro-CT scans appeared as two clear peaks \( [(\text{one for the PEEK cages and the other for empty space (i.e., air)})]. The threshold chosen for the segmentation threshold was the halfway point between the two peaks. Evaluations were conducted via Scanco software (Scanco Medical, Switzerland) on the control volumes. The evaluation for porosity percentage provided \[ \frac{\text{solid volume}}{\text{total volume}} \] values. The porosity percentage of the control volumes were calculated using Eq. (1).

\[ 1 - \frac{\text{volume}_{\text{solid}}}{\text{volume}_{\text{total}}} \]  

\[ \left( 1 \right) \]

Moreover, the outcome from the evaluations for average pore size is a volume-based thickness. The software uses a volume-based local thickness algorithm which was introduced by Hildebrand and Rüegsegger. After mechanical testing, the fracture surfaces of printed cohorts were imaged using light microscopy to view the crack morphology of different cohorts under the same loading condition. Crack and layer width were also calculated from the light microscopy images of the compression samples. Furthermore, detailed surface micrographs of printed cohorts were taken to analyze the porosity and the structure of the surface via scanning electron microscopy (SEM). Prior to SEM, cages were sputtered with platinum and palladium to achieve a conductive surface.

### D. Level of crystallinity

X-ray diffraction (XRD) and Fourier transmission infrared spectroscopy (FTIR) were used to determine the degree of crystallinity of PEEK cages. Wide-angle X-ray scattering (WAXS) was determined as the scattering technique for XRD. For WAXS, two cohorts were created as top and bottom from printed cages according to the location where the samples were obtained. Three samples per cohort were evaluated. 1 mm thick samples were used for WAXS analysis. An internal plate was used to collect diffracted X-ray at a distance of 82 mm from the sample for 60 min. The internal plate was then read using RAXIA software to determine the diffraction pattern by plotting 2 theta (2\( \theta \)) versus intensity. MagicPlot software (Magicplot Systems, LLC, Saint Petersburg, Russia) was used to fit Gaussian distributions and determine the area of the curve to each crystalline peak. The degree of crystallinity was calculated using Eq. (2).

\[ \frac{\text{Area}_{\text{crystalline}}}{\text{Area}_{\text{amorphous}} + \text{Area}_{\text{crystalline}}} \]  

\[ \left( 2 \right) \]

FTIR samples for printed cohorts were prepared from the body of the cages after dividing the cages into two to avoid any contamination of printing bed-PEEK adhesion material, whereas the surface was used for machined cohort \( (n = 9–14) \). FTIR measurements were collected with a Nicolet Continuum (Thermo Electron Corporation, Waltham, Massachusetts) and the parameters used were based on ASTM

<table>
<thead>
<tr>
<th>Cohorts</th>
<th>Cage Weight (g)</th>
<th>Time per Cage (min)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Mean Standard deviation</td>
<td></td>
</tr>
<tr>
<td>1000</td>
<td>1.56 0.008</td>
<td>62.8</td>
</tr>
<tr>
<td>1500</td>
<td>1.50 0.009</td>
<td>40.3</td>
</tr>
<tr>
<td>2000</td>
<td>1.49 0.011</td>
<td>33.7</td>
</tr>
<tr>
<td>3000</td>
<td>1.27 0.022</td>
<td>29.4</td>
</tr>
<tr>
<td>Machined</td>
<td>1.44 0.018</td>
<td>17</td>
</tr>
</tbody>
</table>

(5 \( \times \) 5 \( \times \) 2 mm\(^3\)); limited by the standardized cage design) was created for the porosity calculations. Two control volume measurements were taken from the designated regions per cage to compare the average porosity and the pore size between the cohorts \( (n = 6 \) per cohort). The histogram of the grayscale values (which correspond with densities) resulting from the micro-CT scans appeared as two clear peaks \( [(\text{one for the PEEK cages and the other for empty space (i.e., air)})]. The threshold chosen for the segmentation threshold was the halfway point between the two peaks. Evaluations were conducted via Scanco software (Scanco Medical, Switzerland) on the control volumes. The evaluation for porosity percentage provided \[ \frac{\text{solid volume}}{\text{total volume}} \] values. The porosity percentage of the control volumes were calculated using Eq. (1).
Crystallinity from FTIR data was also calculated using the crystallinity index and the equation provided in ASTM F2778\textsuperscript{28} using a custom script in MATLAB 2016b.

E. Statistics

Distributions of data were first inspected for normality using the Shapiro–Wilk W test. Normal data sets were analyzed via ANOVA with a post hoc Dunnett’s test [pairwise ranking with a control (machined cages)]. The Kruskal Wallis test with a post hoc steel test [pairwise ranking with a control (machined cages)] was conducted for comparisons with non-normal data sets. The control group was designated as machined cage cohort. In addition, bivariate correlation analysis was performed using the Pearson correlation on the normal data sets, and with Spearman’s correlation on the non-normal data sets. Since the cracks were analyzed only on the printed cages, there was not a control group. For crack and layer width measurements, Kruskal Wallis test with a post hoc Dunn correction was conducted for comparisons. Statistical analyses were performed using commercially available statistical software (JMP 11.0; SAS Institute Inc., Cary, North Carolina) with $\alpha = 0.05$.

III. RESULTS

A. Mechanical testing

The stiffness of the printed cages achieved between 74 and 92% of the machined cages’ stiffness depending on the loading condition (Table III). Under compressive loading, cages printed with the slowest speed (1000 mm/min) were able to provide 91.6% of machined cage stiffness, and we did not observe a difference between the stiffnesses of the printed cages ($P = 0.25$). The bivariate analysis of speed versus stiffness showed that stiffness decreased significantly when the printing speed increased [Pearson correlation coefficient (PCC) = $-0.58$, $P < 0.01$]. Finally, machined cages were significantly stiffer than printed cohorts with 1500, 2000, and 3000 mm/min ($P < 0.001, 0.002$, and $<0.001$; mean difference = 2486, 1935, and 2643 N, respectively).

Under compressive–shear loading, we did not detect a difference in stiffness between printed cohorts and the machined cohort ($P = 0.37$). Printed cages showed similar stiffness compared to the machined cages and they were able to provide up to 87% stiffness of the machined cages. Printing speed did not significantly affect the stiffness of printed cohorts when compressive–shear loading was applied (PCC = $-0.18$; $P = 0.47$).

Under torsional loading, the printed cohort with 1500 mm/min was able to reach 67% of machined cages’ stiffness. However, machined cages were significantly stiffer than all printed cohorts ($P = 0.04$ for all tests; mean difference = 888, 757, 1103, and 1114 N mm\textsuperscript{-}, for the cohorts printed with 1000, 1500, 2000, and 3000 mm/min, respectively). The decrement in printed cohorts’ torsional stiffness due to printing speed increment was not significant (Rho = $-0.37$; $P = 0.11$).

<table>
<thead>
<tr>
<th>Cohorts</th>
<th>Printed with speeds (mm/min)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Machined</td>
</tr>
<tr>
<td>Compression</td>
<td></td>
</tr>
<tr>
<td>Stiffness (N/mm)</td>
<td>10,184</td>
</tr>
<tr>
<td>Ultimate force (N)</td>
<td>14,229</td>
</tr>
<tr>
<td>Ultimate displacement (mm)</td>
<td>3.12</td>
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<tr>
<td>Compression-shear</td>
<td></td>
</tr>
<tr>
<td>Stiffness (N/mm)</td>
<td>1123</td>
</tr>
<tr>
<td>Ultimate force (N)</td>
<td>2140</td>
</tr>
<tr>
<td>Ultimate displacement (mm)</td>
<td>3.06</td>
</tr>
<tr>
<td>Torsion</td>
<td></td>
</tr>
<tr>
<td>Stiffness (N m/deg)</td>
<td>2.26</td>
</tr>
<tr>
<td>Ultimate moment (N m)</td>
<td>11.7</td>
</tr>
<tr>
<td>Ultimate displacement (deg)</td>
<td>18.8</td>
</tr>
<tr>
<td>LM Measurements</td>
<td></td>
</tr>
<tr>
<td>Crack width (microns)</td>
<td>N/A</td>
</tr>
<tr>
<td>Layer width (microns)</td>
<td>N/A</td>
</tr>
<tr>
<td>Porosity</td>
<td></td>
</tr>
<tr>
<td>Porosity percentage (%)</td>
<td>0</td>
</tr>
<tr>
<td>Average pore size (microns)</td>
<td>0</td>
</tr>
<tr>
<td>Crystallinity</td>
<td></td>
</tr>
<tr>
<td>XRD (%)</td>
<td>48.5</td>
</tr>
<tr>
<td>FTIR (%)</td>
<td>20.0</td>
</tr>
</tbody>
</table>

TABLE III. Metrics calculated in this study.
In addition to the stiffness, ultimate load/moment and ultimate displacement were compared among cohorts [compression, shear, or torsion, Fig. 3]. Under compressive loading, slowest printed cages were able to provide 63% ultimate strength of the machined cages [Fig. 3(a)]. However, machined cages’ ultimate load was significantly higher than all printed cohorts \((P = 0.04\) for all the comparisons; mean difference = 5536, 5964, 6351, and 6443 N, for the cohorts printed with 1000, 1500, 2000, and 3000 mm/min, respectively). The bivariate analysis revealed that the printing speed was inversely correlated with the ultimate load \((\text{Rho} = -0.61, P = 0.005)\).

When compressive–shear load was applied to the cages, the cohort printed with 1500 mm/min speed showed 71% ultimate load of the machined cages; however, it was significantly lower \([P = 0.03; \text{mean difference} = 629 N; \text{Fig. 3(b)}]\). Additionally, machined cages showed significantly higher ultimate load than the other printed cohorts \((P < 0.001\) for all tests; mean difference = 1169, 1279, and 1235 N for the cohorts printed with 1000, 2000, and 3000 mm/min, respectively). There was no correlation in ultimate load printing speed under shear \((\text{PCC} = -0.24, P > 0.19)\).

Under torsional loading, cohorts printed with 1000, 1500, and 2000 mm/min showed comparable ultimate moment with the machined cages and with no significant differences \([P = 0.18, 0.27, \text{and} 0.39, \text{respectively}; \text{Fig. 3(c)}]\). The machined cages’ ultimate moment was only higher than the fastest cohort (3000 mm/min) \((P = 0.04\) and mean difference = 1448 N mm). The bivariate analysis verified that the ultimate moment reached under torsional loading was negatively correlated with the printing speed \((\text{Rho} = -0.60; P = 0.005)\).

When ultimate displacement was compared between cohorts under compression, the machined cohort was displaced significantly more until it reached the ultimate load compared to printed cohorts with 1000, 2000, and 3000 mm/min \((P = 0.04\) for all tests; mean difference = 1.69, 1.61, and 1.49 mm). The only significant difference detected was between printed cohort with 1500 mm/min and machined cohort \((P = 0.12\) and mean difference = 1.57 mm). And there was not a significant correlation between the printing speed and ultimate displacement \((\text{Rho} = 0.35\) and \(P = 0.5)\).

Printed cohorts demonstrated similar ultimate displacement under compression–shear force compared to the
machined cages \( (P = 0.08) \). Additionally, the printing speed was not correlated with ultimate displacement under shear force \( (PCC = -0.31; P = 0.199) \). Similarly, the printed cohorts’ angular displacement was not significantly different than machined cages \( (PCC = 0.02; P = 0.94) \). No significant difference was observed between the printed cohorts’ displacement under torsional load \( (P = 0.66) \) and no correlation was detected between the angular displacement of the cohorts and the printing speed \( (P = 0.94) \).

B. Imaging

Based on the micro-CT scans, printed cohorts exhibited, on average, between 2 and 20% porosity [Fig. 4(a)]. There was a strong correlation between the printing speed and the porosity of the printed cages \( (PCC = 0.88; P < 0.001) \). As expected, there were no detectable pores (mean porosity = 0%) for machined cages, which was significantly lower than printed cages \( (P = 0.01 \text{ for all tests}; \text{mean difference} = 1.88\%, 3.82\%, 2.99\%, \text{and} 19.6\%, \text{for printed cohorts with} 1000, 1500, 2000, \text{and} 3000 \text{mm/min, respectively}) \).

The average pore sizes ranged between 81 and 135 \( \mu \text{m} \) wide for all printed cohorts [Fig. 4(b)]. We did not observe a correlation between the printing speed and average pore size \( (PCC = 0.37; P = 0.08) \). The average pore size for machined cages was 0 \( \mu \text{m} \) and was significantly lower than all the printed cohorts \( (P = 0.01 \text{ for all tests} \text{; mean difference} = 97, 116, 81, \text{and} 135 \mu \text{m}, \text{for printed cohorts with} 1000, 1500, 2000, \text{and} 3000 \text{mm/min, respectively}) \).

SEM images were used to visualize the pore structures on the cage surface (Fig. 5). It was observed from the
SEM images that the printed cohorts had unfused layers which might be associated with weaker points for crack initiation (Fig. 6). The fracture surface morphology was the same for all printed cohorts under the same loading condition (Fig. 7). Under compression and shear, the cracks were observed parallel with the layers. On the other hand, under torsional loading, the crack started parallel with the layers and then changed the direction and became perpendicular to the layers.

Additionally, the layer and crack width were calculated and analyzed (Fig. 8 and Table III). The bivariate analysis indicated that the layer width increased significantly when the printing speed was increased (Rho = 0.46 and $P < 0.0001$). Fastest printed (3000 mm/min) cohort’s layers were significantly wider than the other printed groups ($P < 0.001$ for all tests; mean difference = 34.2, 19.9, and 18.37 μm, for printed cohorts with 1000, 1500, and 2000 mm/min, respectively). Moreover, the slowest
C. Level of crystallinity

Both FTIR and XRD confirmed that crystallinity did not depend on the manufacturing method in PEEK cages. There was no significant difference detected between the printed cohorts and machined cohort crystallinity calculated via FTIR, (mean crystallinity ~20%; \( P = 0.49 \), 0.98, 0.74, and 0.98 for printed cohorts with 1000, 1500, 2000, and 3000 mm/min, respectively, Table III). Additionally, we did not observe a correlation between the printing speed and the crystallinity measured using XRD (PCC = 0.012 and \( P = 0.46 \)). Similarly, XRD also did not show any significant differences between the printed and machined cohorts (\( P = 0.97 \), 1.0, 1.0, and 1.0 for printed cohorts with 1000, 1500, 2000, and 3000 mm/min, respectively). The average crystallinity calculated via WAXS was approximately 49% (Table III). Similar to FTIR, there was not a correlation detected between the printing speed and the crystallinity measured using XRD (PCC = 0.001 and \( P = 0.996 \)). There was no significant difference in crystallinity detected between the top and bottom locations with reference to the heated bed of the printed cohorts via WAXS (\( P = 0.68 \)).

IV. DISCUSSION

We present here a detailed structure–property investigation of FFF PEEK structural, load-bearing implants developed using a commercially available printer. The 3D-printed PEEK cages via FFF achieved between 63 and 92% strength of machined PEEK cages under different loading conditions. We would like to emphasize that these findings were obtained with the “as-printed” cages, without any subsequent post-processing such as annealing. The results of this study suggest that the optimum printing speed for FFF PEEK cages in the present configuration is between 1000 and 1500 mm/min. Our findings were explained by porosity of the cages, as documented by micro-CT evaluations and SEM images. We did not observe an association between the cage properties and crystallinity as a function of printing speed, further supporting the concept that print defects at the microscale, rather than crystalline morphology, are likely responsible for the differences between the FFF and machined PEEK cages.

Previous studies of FFF PEEK have shown mechanical property differences of FFF compared to other
manufacturing methods. Cicala et al. conducted tensile loading on the PEEK dog-bone specimen 3D printed by FFF and showed that FFF PEEK’s tensile strength was 77% of the injection molded PEEK. Similarly, Rahman et al. provided a range of injection molded PEEK’s tensile strength, where their FFF PEEK results performed from 33 to 97%. As an alternate AM method, PEEK manufactured via SLS was referred to have lower strength than injected molded PEEK as well. Berretta et al. tested the tensile strength of their dog-bone PEEK specimen produced by SLS, which were around 60% of the PEEK’s tensile strength.

While taking the reported decrease caused by FFF from the literature into consideration, it must be noted that our results are applied on the spinal cages tested under compressive loading conditions rather than tension. Mechanical properties of FFF PEEK cages were compared as reference to machined cage results which were within the reproducibility limit of ASTM standards. FFF cages exhibited a compressive strength of ~8 kN, which is less than the machined PEEK cages but in excess of the load expected for cages under in vivo loading. The compressive strength of human thoracolumbar vertebrae ranges from about 2000 N for specimens having low bone density and small cross-sectional areas to about 8000 N for specimens having high bone density and large cross-sectional areas. Similarly, Wilke et al. measured in vivo lumbar disc pressure in common activities which was between 180 and 4140 N. Although the compressive–shear and torsional

FIG. 8. Crack and layer width were measured from printed cohorts after compression testing (a). Increasing the printing speed caused a greater layer width (b); however, crack width was not significantly correlated with the print speed (c).
strength were lower for FFF cages than that for machined cages, they were above the axial compression–shear and rotation limits defined for a spinal unit.\textsuperscript{34}

The difference in mechanical properties between FFF versus machined PEEK cages can be explained, at least in part, both by the layer adhesion and porosity of the printed cages. Crack visualization indicated the importance of the layer adhesion for FFF cages. This strengthens the idea of layer-to-layer intersection line being the stress point since the cracks observed along with the layers.

Micro-CT scanning was previously designated for characterization of porosity in parts printed via FFF.\textsuperscript{35} In our study, the FFF cages’ (printed with slowest speed) average porosity calculated from micro-CT scans of control volume was 2\%. Often the cause of porosity is explained by the entrapped micro-air bubbles in the filament and voids which became pores during the FFF process.\textsuperscript{20} Vaezi et al.\textsuperscript{20} stated that high level of porosity (38\%) played a role in reduction of mechanical properties for their porous PEEK samples and showed that even printing with 100\% infill they encountered 14\% porosity of FFF PEEK samples. Cicala et al.\textsuperscript{22} also emphasized the need of optimization for FFF PEEK by decreasing pore formation during the printing process.

The reason why slower speeds were suggested for FFF of PEEK is the association between printing speed and porosity. The printing speed had a great impact on the printed cages’ porosity such that it increased the porosity from 2 to 4\% (slower speeds) to 20\% (fastest speed).

Considering the fact that the printhead’s movement pattern remains the same regardless of the printing speed, increasing the printhead’s speed redundantly might have caused an imperfect filament-to-filament bonding, which could increase the porosity and cause an overall reduction in mechanical properties. In the same manner, Vaezi et al.\textsuperscript{20} associated the porosity found in PEEK samples with 100\% infill with the formation of air gap between deposited filaments within layers. Additionally, it was emphasized by the previous studies that the influence of filament-to-filament bonding is more crucial than the strength of the filament itself for 3D-printed parts via FFF.\textsuperscript{36,37} Thus, in addition to diminishing entrapped microbubbles in the filament prior to printing, a good filament-to-filament bonding must be considered to reach the optimum structural integrity under load.

Furthermore, it was confirmed that the FFF process did not influence the cages’ crystallinity. It is well known that the crystallinity of PEEK has a sufficient influence in its mechanical properties.\textsuperscript{38} The FFF process did not change the crystallinity of PEEK cages compared to the extruded rod, which were in accordance with the literature.\textsuperscript{39,40}

Several limitations to the current study can be acknowledged here. The printing speeds used in this study are applicable to this printer and extruder configuration, and changes in this configuration may impact the porosity in a different manner than observed here. In the current study, cages were also tested “as-printed”, without any post-processing such as annealing which will be investigated in future research. Finally, the mechanical strength of the cages was evaluated under static loading conditions. Thus, future studies should investigate the fatigue behavior of printed cages compared to machined cages.

\section*{V. CONCLUSIONS}

The results suggest that without any additional influence on 3D printing such as ambient parameter control or post-processing, FFF 3D-printed cages are already able to provide sufficient strength for lumbar cage applications. It also indicates the importance of printing parameters such as printing speed to avoid porosity which may improve the mechanical properties of printed cages. Our findings are important steps toward evaluating this novel 3D printing manufacturing technique for PEEK implants.

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\section*{REFERENCES}


### Supplementary Material

To view supplementary material for this article, please visit https://doi.org/10.1557/jmr.2018.178.