

Invariant densities for random systems of the interval

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Abstract. For random piecewise linear systems T of the interval that are expanding on average we construct explicitly the density functions of absolutely continuous T -invariant measures. If the random system uses only expanding maps our procedure produces all invariant densities of the system. Examples include random tent maps, random W -shaped maps, random β -transformations and random Lüroth maps with a hole.

Key words: absolutely continuous invariant measure, β -expansions, interval map, Lüroth expansions, random dynamics

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1. Introduction

The Perron–Frobenius operator has been used since the seminal paper [LY73] of Lasota and Yorke to establish the existence of absolutely continuous invariant measures for deterministic dynamical systems. The same approach was also successful in the study of random dynamical systems. In the random setting, instead of a single map, a family of maps is considered from which one is selected at each iteration at random. In [Pel84] Pelikan gave sufficient conditions under which a random system using a finite number of piecewise C^2 -transformations on the interval has absolutely continuous invariant measures. He also discussed the possible number of ergodic components. Around the same time a similar result was obtained by Morita in [Mor85], allowing for the possibility to choose from an infinite family of maps as well. In more recent years these results have been generalized in various ways. See [Buz00, GB03, BG05, Ino12], for example.

Finding an explicit formula for the density functions of these absolutely continuous invariant measures, however, is a different matter. Here the Perron–Frobenius operator

can only help if one can make an educated guess. An explicit expression for the invariant density is therefore available only for specific families of maps. In 1957 Rényi gave in [Rén57] an expression for the invariant density of the β -transformation $x \mapsto \beta x \pmod{1}$ for $\beta = (1 + \sqrt{5})/2$, the golden mean. Later Parry and Gel'fond gave a general formula for the invariant density of the β -transformation in [Par60, Gel59]. In [DK10] generalizations of the β -transformation were considered. A more general set-up allowing different slopes was proposed in [Kop90] by Kopf. He introduced a matrix M for any piecewise linear expanding interval map satisfying some minor restraints and associated each absolutely continuous invariant measure of the system to a vector from the null space of M . Some twenty years later, Góra developed in [Gór09] a similar procedure for deterministic piecewise linear eventually expanding interval maps. Unless the map in question has many onto branches, the matrix involved in the procedure from [Gór09] is of higher dimension than the one used in [Kop90].

For random maps not much is known. An exception is the random β -transformation, which was first introduced in [DK03] by Dajani and Kraaikamp and uses random combinations of two piecewise linear maps with constant slope $\beta > 1$. It has a unique absolutely continuous invariant measure, as proved in [DdV07]. In [Kem14] Kempton gave a formula for the invariant density in the case where one chooses the two base maps with equal probability. Recently Suzuki extended these results in [Suz19] to include the non-uniform Bernoulli regime as well.

This paper is concerned with finding explicit expressions for invariant densities of random systems. We consider any finite or countable family $\{T_j : [0, 1] \rightarrow [0, 1]\}$ of piecewise linear maps that are expanding on average. The random system T is given by choosing one of these maps at each step using a probability vector $\mathbf{p} = (p_j)$. The existence of an absolutely continuous invariant measure for such systems is guaranteed by [Pel84] for a finite family and by [Buz00, Ino12] in the countable case. The main result of this paper is that we provide a procedure to construct explicit formulas for invariant probability densities of the random system T . This is the content of Theorem 4.1. The results from Theorem 4.1 cover those from [Kem14, Suz19] regarding the expression for the invariant density as a special case. If we assume that all maps T_j are expanding, we obtain the stronger result that the procedure leading to Theorem 4.1 actually produces all absolutely continuous invariant measures of T . We prove this in Theorem 5.3.

The paper is organized as follows. In the second section we specify our set-up and introduce the necessary assumptions and notation. The third section is devoted to the definition of a matrix M and to the proof that the null space of M is non-trivial. In the fourth section we prove Theorem 4.1, relating each non-trivial vector γ from the null space of M to the density h_γ of an absolutely continuous invariant measure of the system T . In the fifth section we prove Theorem 5.3 concerning when we get all invariant densities. It is in this section that the extra difficulties that we had to overcome for dealing with random systems instead of deterministic ones, are most visible. Finally, we apply the results to some examples. In the sixth section we consider random tent maps, random W -shaped maps and various random β -transformations. In the final section we elaborate on a system related to representations of real numbers: a random Lüroth map with a hole.

2. Preliminaries

Let $\Omega \subseteq \mathbb{N}$ and let $\{T_j : [0, 1] \rightarrow [0, 1]\}_{j \in \Omega}$ be a family of piecewise linear transformations. Consider a positive probability vector $\mathbf{p} = (p_j)_{j \in \Omega}$ (i.e., $p_j > 0$ for all $j \in \Omega$ and $\sum_{j \in \Omega} p_j = 1$). We call the system T a *random system* of the interval $[0, 1]$ of probability \mathbf{p} , if for $x \in [0, 1]$ and $j \in \Omega$,

$$T(x) := T_j(x) \text{ with probability } p_j.$$

A measure $\mu_{\mathbf{p}}$ on $[0, 1]$ is an *absolutely continuous invariant measure* for T and \mathbf{p} if there is a density function h , such that for each Borel set $A \subseteq [0, 1]$ we have

$$\mu_{\mathbf{p}}(A) = \int_A h \, d\lambda = \sum_{j \in \Omega} p_j \mu_{\mathbf{p}}(T_j^{-1}A), \tag{1}$$

where λ denotes the one-dimensional Lebesgue measure.

Such a random system T can also be described by a *pseudo skew-product system*. In that case, let $\sigma : \Omega^{\mathbb{N}} \rightarrow \Omega^{\mathbb{N}}$ be the left shift on sequences and define the map $R : \Omega^{\mathbb{N}} \times [0, 1] \rightarrow \Omega^{\mathbb{N}} \times [0, 1]$ by $R(\omega, x) = (\sigma(\omega), T_{\omega_1}x)$. If $m_{\mathbf{p}}$ is the \mathbf{p} -Bernoulli measure on $\Omega^{\mathbb{N}}$, then $m_{\mathbf{p}} \times \mu_{\mathbf{p}}$ is an invariant measure for R . We call R the pseudo skew-product system associated to T .

We put some assumptions on the systems T we consider.

(A1) Assume that the set of all the critical points of the maps T_j is *finite*. Denote these critical points by $0 = z_0 < z_1 < \dots < z_N = 1$. The points z_i together specify a common partition $\{I_i\}_{1 \leq i \leq N}$ of subintervals of $[0, 1]$, such that all maps T_j are monotone on each of the intervals I_i . Hence, there exist $k_{i,j}, d_{i,j} \in \mathbb{R}$ such that the maps $T_{i,j} := T_j|_{I_i}$ are given by

$$T_{i,j}(x) = k_{i,j}x + d_{i,j}.$$

(A2) Assume that T is *expanding on average* with respect to \mathbf{p} , that is, assume that there is a constant $0 < \rho < 1$, such that for all $x \in [0, 1]$, $\sum_{j \in \Omega} (p_j / |T_j'(x)|) \leq \rho < 1$. This is equivalent to assuming that for each $1 \leq i \leq N$,

$$\sum_{j \in \Omega} \frac{p_j}{|k_{i,j}|} \leq \rho < 1.$$

Under these conditions the random system T satisfies conditions (a) and (b) from [Ino12], which studies the existence of invariant densities h satisfying (1) using the Perron–Frobenius operator. For the deterministic maps $T_j : [0, 1] \rightarrow [0, 1]$, $j \in \Omega$, the Perron–Frobenius operator on $L^1(\lambda)$ is given by

$$P_{T_j} f(x) = \sum_{y \in T_j^{-1}\{x\}} \frac{f(y)}{|T_j'(y)|}.$$

The *random Perron–Frobenius operator* is then defined by

$$P_T f = \sum_{j \in \Omega} p_j P_{T_j} f. \tag{2}$$

The operator P_T is clearly linear and positive. An $L^1(\lambda)$ -function h is called T -invariant for the random system T if it is a fixed point of P_T , that is, if it satisfies $P_T h = h$ λ -almost everywhere (a.e.). A density function h is the density of a measure $\mu_{\mathbf{p}}$ satisfying (1) if and only if it is a fixed point of P_T . From [Ino12, Theorem 5.2] it follows that a T -invariant measure $\mu_{\mathbf{p}}$ of the form (1), and hence a T -invariant function h , exists. Inoue obtained this result by showing that the operator P_T , applied to functions of bounded variation, satisfies a Lasota–Yorke type inequality. From the famous Ionescu-Tulcea and Marinescu theorem one can then deduce much more than mere existence of an absolutely continuous invariant measure; it says that P_T as an operator on the space of functions of bounded variation is quasi-compact. The specific implications of the quasi-compactness of P_T that we use in this paper are the following. The eigenvalue 1 of P_T has a finite-dimensional eigenspace. In other words, the subspace of $L^1(\lambda)$ of T -invariant functions is a finite-dimensional sublattice of the space of functions of bounded variation. As such, it has a finite base $H = \{v_1, \dots, v_r\}$ of T -invariant density functions of bounded variation, each corresponding to an ergodic measure, so that any other T -invariant $L^1(\lambda)$ -function h can be written as a linear combination of the v_i : $h = \sum_{i=1}^r c_i v_i$ for some constants $c_i \in \mathbb{R}$. Furthermore, if we set $U_i := \{x : v_i(x) > 0\}$ for the support of the function v_i , then each U_i is forward invariant under T in the sense that

$$\lambda\left(U_i \Delta \bigcup_{j \in \Omega} T_j(U_i)\right) = 0, \tag{3}$$

where Δ denotes the symmetric difference. Also, the sets U_i are mutually disjoint and none of the sets U_i can properly contain another forward invariant set. We will use these properties in the proofs from §5. An account of these implications on the operator P_T can be found in [Pel84, Mor85, Buz00, Ino12], for example. For more information, we also refer to standard textbooks such as [BG97, LM94].

In this paper we find T -invariant functions $h : [0, 1] \rightarrow \mathbb{R}$ by linking them to the vectors from the null space of a matrix M . To guarantee that this null space is non-trivial, we formulate three additional assumptions that are easy to verify for any given systems. Firstly, we assume that not all the lines $x \mapsto k_{i,j}x + d_{i,j}$, $1 \leq i \leq N$, with respective weights p_j , have a common intersection point with the diagonal. More precisely, consider for each interval I_i the weighted intersection point with the diagonal

$$x = \sum_{j \in \Omega} p_j \left(\frac{x}{k_{i,j}} - \frac{d_{i,j}}{k_{i,j}} \right).$$

Our third assumption states that for each i there is an n , such that these points do not coincide.

(A3) Assume that for each $1 \leq i \leq N$, there is an $1 \leq n \leq N$, such that

$$\frac{\sum_{j \in \Omega} (p_j/k_{i,j})d_{i,j}}{1 - \sum_{j \in \Omega} (p_j/k_{i,j})} \neq \frac{\sum_{j \in \Omega} (p_j/k_{n,j})d_{n,j}}{1 - \sum_{j \in \Omega} (p_j/k_{n,j})}.$$

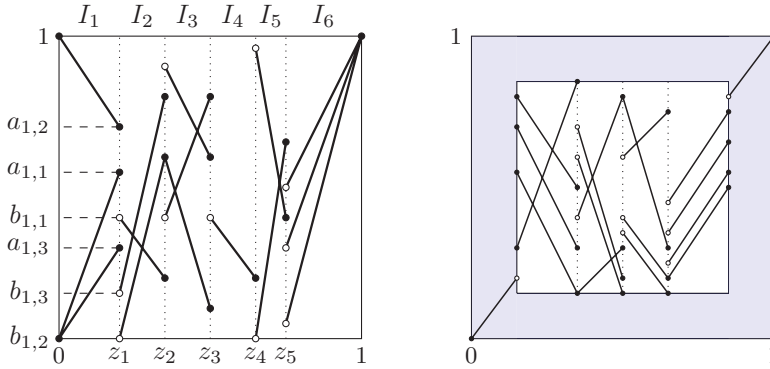


FIGURE 1. On the left is an arbitrary map T satisfying the above conditions. On the right we see a random map T in the white box that does not satisfy (A4). By adding the branches in the grey part and rescaling, we obtain a system that does satisfy these conditions. Note that any point in the grey part (except for 0 and 1) moves to the white part after a finite number of iterations and stays there. Hence, any invariant density will equal 0 on the grey part.

Note that if $d_{i,j} < 0$, then $k_{i,j} > -d_{i,j}$ and if $d_{i,j} > 1$, then $k_{i,j} < 1 - d_{i,j}$. Hence, in all cases $|d_{i,j}| < |k_{i,j}| + 1$ and by (A2),

$$\sum_{j \in \Omega} \frac{p_j}{|k_{i,j}|} |d_{i,j}| \leq 1 + \rho. \tag{4}$$

So, the quantities in (A3) are all finite. Our fourth assumption is on the orbits of the points 0 and 1.

(A4) For each j , assume that

$$d_{1,j} = \begin{cases} 0 & \text{if } k_{1,j} > 0, \\ 1 & \text{if } k_{1,j} < 0, \end{cases} \quad \text{and} \quad d_{N,j} = \begin{cases} 1 - k_{N,j} & \text{if } k_{N,j} > 0, \\ -k_{N,j} & \text{if } k_{N,j} < 0. \end{cases}$$

In other words, the points 0 and 1 are mapped to 0 or 1 under all maps T_j , making the system continuous at the origin, when we consider it as acting on the circle \mathbb{R}/\mathbb{Z} with the points 0 and 1 identified. Since we can deal with finitely many discontinuities, (A4) is not necessary for our results to hold, but it makes computations easier. Any system not satisfying it can be extended to a system that does satisfy this condition and for which no absolutely continuous invariant measure puts weight on the added pieces. See Figure 1 for an illustration and see §6.3 for a concrete example, given by the random (α, β) -transformation.

Finally, we include an assumption stating that the weighted inverse derivative cannot be 0 anywhere.

(A5) Assume that for any $x \in [0, 1]$, the weighted inverse derivative satisfies $\sum_{j \in \Omega} (p_j / T'_j(x)) \neq 0$. This is equivalent to assuming that for each $1 \leq i \leq N$,

$$\sum_{j \in \Omega} \frac{p_j}{k_{i,j}} \neq 0.$$

Conditions (A3) and (A5) are sufficient to get our main results, but probably not necessary. Note that (A5) is automatically fulfilled for any deterministic Lasota–Yorke map (and, in particular, for any deterministic piecewise linear map) and also for any random system for which on each interval I_i the derivatives of all maps T_j have the same sign. The final section contains an example that does not satisfy (A5) for a specific choice of \mathbf{p} . We will see that the procedure which leads to our main results still gives all invariant densities in that case. Moreover, if (A5) is not satisfied for some probability vector \mathbf{p} , then changing \mathbf{p} slightly already lifts this restriction.

3. A homogeneous system with a non-trivial solution

An invariant measure reflects the dynamics of a system. For the maps T_j , $j \in \Omega$, considered in this article, the dynamics is determined by the orbits of the endpoints of the lines $x \mapsto k_{i,j}x + d_{i,j}$, $1 \leq i \leq N$. We start this section by defining some quantities that keep track of the possible orbits of these points.

Let Ω^* be the set of all finite strings of elements from Ω together with the empty string ε . For $t \geq 0$, let $\Omega^t \subseteq \Omega^*$ denote the subset of those strings that have length t . So, in particular, $\Omega^0 = \{\varepsilon\}$. Let $|\omega|$ denote the length of the string ω . For any string $\omega \in \Omega^*$ with $|\omega| \geq t$, we let ω_t^1 denote the starting block of length t . For two strings $\omega, \omega' \in \Omega^*$ we simply write $\omega\omega'$ for their concatenation. Each element $\omega \in \Omega^t$ defines a possible start of an orbit of a point in $[0, 1]$ by composition of maps: for $x \in [0, 1]$ and $\omega = \omega_1 \cdots \omega_t \in \Omega^t$, define

$$T_\omega(x) = T_{\omega_t} \circ T_{\omega_{t-1}} \circ \cdots \circ T_{\omega_1}(x)$$

and set $T_\varepsilon(x) = x$. For $\omega \in \Omega^*$, set $\tau_\omega(y, 0) = 1$, and for $1 \leq t \leq |\omega|$, set

$$\tau_\omega(y, t) := \frac{P_{\omega_t}}{k_{i,\omega_t}} \quad \text{if } T_{\omega_{t-1}}(y) \in I_i.$$

Define

$$\delta_\omega(y, t) := \prod_{n=0}^t \tau_\omega(y, n), \tag{5}$$

so that $\delta_\omega(y, t)$ is the weighted slope of the map $T_{\omega_t^1}$ at the point y . Note that $\tau_\omega(y, t)$ and $\delta_\omega(y, t)$ only depend on the block ω_t^1 and not on what comes after. Moreover, for a concatenation ωj , given by any block ω with $|\omega| = t - 1$ and any $j \in \Omega$, we have that $\tau_{\omega j}(y, t) = \tau_j(T_\omega(y), 1)$ and $\delta_{\omega j}(y, t) = \tau_{\omega j}(y, t)\delta_\omega(y, t - 1)$. By assumption (A2) we have that for any $y \in [0, 1]$,

$$\begin{aligned} \left| \sum_{t \geq 0} \sum_{\omega \in \Omega^t} \delta_\omega(y, t) \right| &\leq 1 + \sum_{t \geq 1} \sum_{\omega \in \Omega^{t-1}} \sum_{j \in \Omega} |\delta_\omega(y, t - 1)| |\tau_{\omega j}(y, t)| \\ &\leq 1 + \sum_{t \geq 1} \sum_{\omega \in \Omega^{t-1}} |\delta_\omega(y, t - 1)| \rho \leq \frac{1}{1 - \rho}. \end{aligned} \tag{6}$$

Let $\mathbf{1}_A$ denote the characteristic function of the set A and set

$$\mathbf{K}\mathbf{I}_n(y) := \sum_{t \geq 1} \sum_{\omega \in \Omega^t} \delta_\omega(y, t) \mathbf{1}_n(T_{\omega_{t-1}}(y)) \quad \text{for } 1 \leq n \leq N.$$

Then $KI_n(y)$ keeps track of all the times the random orbit of y visits I_n and adds the corresponding weighted slopes. For $1 \leq i \leq N - 1$, set $A_i := I_1 \cup \dots \cup I_i$ and $B_i := I_{i+1} \cup \dots \cup I_N$. We define

$$\begin{aligned} KA_i(y) &:= \sum_{t \geq 0} \sum_{\omega \in \Omega^t} \delta_\omega(y, t) \mathbf{1}_{A_i}(T_\omega(y)), \\ KB_i(y) &:= \sum_{t \geq 0} \sum_{\omega \in \Omega^t} \delta_\omega(y, t) \mathbf{1}_{B_i}(T_\omega(y)). \end{aligned} \tag{7}$$

By (6), $|KI_n|$, $|KA_i|$ and $|KB_i|$ are finite for all $y \in [0, 1]$. For each $1 \leq n \leq N$, let S_n be the average inverse of the slope,

$$S_n := \sum_{j \in \Omega} \frac{p_j}{k_{n,j}},$$

which is non-zero by (A5), so that S_n^{-1} is well defined. The next two lemmas give some identities that we will use later.

LEMMA 3.1. *For each $y \in [0, 1]$ and $1 \leq i \leq N - 1$ we have*

$$KA_i(y) = \sum_{n=1}^i S_n^{-1} KI_n(y) \quad \text{and} \quad KB_i(y) = \sum_{n=i+1}^N S_n^{-1} KI_n(y).$$

Proof. For any $1 \leq n \leq N$ we have

$$\begin{aligned} \sum_{t \geq 0} \sum_{\omega \in \Omega^t} \delta_\omega(y, t) \mathbf{1}_{I_n}(T_\omega(y)) &= \sum_{t \geq 0} \sum_{\omega \in \Omega^t} \left(\sum_{j \in \Omega} \frac{p_j}{k_{n,j}} \right)^{-1} \left(\sum_{j \in \Omega} \frac{p_j}{k_{n,j}} \right) \delta_\omega(y, t) \mathbf{1}_{I_n}(T_\omega(y)) \\ &= \sum_{t \geq 0} \sum_{\omega \in \Omega^t} S_n^{-1} \sum_{j \in \Omega} \tau_{\omega j}(y, t + 1) \delta_\omega(y, t) \mathbf{1}_{I_n}(T_\omega(y)) \\ &= S_n^{-1} \sum_{t \geq 0} \sum_{\omega \in \Omega^{t+1}} \delta_\omega(y, t + 1) \mathbf{1}_{I_n}(T_\omega^1(y)) = S_n^{-1} KI_n(y). \end{aligned} \tag{8}$$

Putting this in the definition of $KA_i(y)$ from (7) gives the first part of the lemma. Using (8), we also get that

$$KA_i(y) + KB_i(y) = \sum_{t \geq 0} \sum_{\omega \in \Omega^t} \delta_\omega(y, t) = \sum_{n=1}^N S_n^{-1} KI_n(y). \tag{9}$$

The result for KB_i follows. □

Define

$$K_n := S_n^{-1} - 1 \quad \text{and} \quad D_n := S_n^{-1} \left(\sum_{j \in \Omega} \frac{p_j}{k_{n,j}} d_{n,j} \right).$$

Then

$$\frac{D_n}{K_n} = \frac{\sum_{j \in \Omega} (p_j/k_{n,j}) d_{n,j}}{1 - \sum_{j \in \Omega} (p_j/k_{n,j})},$$

so that we can rephrase assumption (A3) as follows: for each $1 \leq i \leq N$, there is an $1 \leq n \leq N$ such that $D_i/K_i \neq D_n/K_n$. We have the following properties for K_n and D_n .

LEMMA 3.2. *Let $y \in [0, 1]$. Then*

$$\sum_{n=1}^N K_n \text{KI}_n(y) = 1 \quad \text{and} \quad - \sum_{n=1}^N D_n \text{KI}_n(y) = y.$$

Proof. For the first part, note that by (9) we have

$$\sum_{n=1}^N S_n^{-1} \text{KI}_n(y) = 1 + \sum_{t \geq 1} \sum_{\omega \in \Omega^t} \delta_\omega(y, t) = 1 + \sum_{n=1}^N \text{KI}_n(y). \tag{10}$$

For the second part, let $1 \leq i \leq N$ be such that $y \in I_i$. Then for $j \in \Omega$ we get $T_{i,j}(y) = k_{i,j}y + d_{i,j}$, and thus

$$y = \sum_{j \in \Omega} \left(\frac{p_j}{k_{i,j}} T_{i,j}(y) - \frac{p_j}{k_{i,j}} d_{i,j} \right).$$

For $t \geq 1$ and $\omega \in \Omega^*$ with $|\omega| \geq t$, set

$$\theta_\omega(y, t) := -\frac{p_{\omega_t}}{k_{n,\omega_t}} d_{n,\omega_t} \quad \text{if } T_{\omega_1^{t-1}}(y) \in I_n. \tag{11}$$

Then

$$y = \sum_{\omega \in \Omega} \tau_\omega(y, 1) T_\omega(y) + \theta_\omega(y, 1). \tag{12}$$

Since $\tau_j(T_\omega(y), 1) = \tau_{\omega j}(y, 2)$ and $\theta_j(T_\omega(y), 1) = \theta_{\omega j}(y, 2)$, we obtain for $\omega \in \Omega$ that

$$T_\omega(y) = \sum_{j \in \Omega} \tau_{\omega j}(y, 2) T_{\omega j}(y) + \theta_{\omega j}(y, 2). \tag{13}$$

Repeated application of (13) in (12), together with the definition of δ_ω from (5), yields after n steps,

$$y = \sum_{t=1}^{n+1} \sum_{\omega \in \Omega^t} \delta_\omega(y, t-1) \theta_\omega(y, t) + \sum_{\omega \in \Omega^{n+1}} \delta_\omega(y, n+1) T_\omega(y).$$

From (6) we obtain that $\lim_{n \rightarrow \infty} \sum_{\omega \in \Omega^{n+1}} |\delta_\omega(y, n+1) T_\omega(y)| = 0$. Hence, by (A2), (4) and (6),

$$\begin{aligned} y &= \sum_{t \geq 0} \sum_{\omega \in \Omega^{t+1}} \delta_\omega(y, t) \theta_\omega(y, t+1) \\ &= - \sum_{n=1}^N \sum_{t \geq 0} \sum_{\omega \in \Omega^t} \delta_\omega(y, t) \mathbf{1}_{I_n}(T_\omega(y)) \left(\sum_{j \in \Omega} \frac{p_j}{k_{n,j}} d_{n,j} \right) \end{aligned} \tag{14}$$

$$\begin{aligned}
 &= - \sum_{n=1}^N S_n^{-1} \left(\sum_{j \in \Omega} \frac{p_j}{k_{n,j}} d_{n,j} \right) \sum_{t \geq 0} \sum_{\omega \in \Omega^t} \delta_\omega(y, t) \left(\sum_{j \in \Omega} \frac{p_j}{k_{n,j}} \right) \mathbf{1}_{I_n}(T_\omega(y)) \\
 &= - \sum_{n=1}^N D_n \sum_{t \geq 0} \sum_{\omega \in \Omega^t} \delta_\omega(y, t) \left(\sum_{j \in \Omega} \tau_{\omega_j}(y, t + 1) \right) \mathbf{1}_{I_n}(T_\omega(y)) \\
 &= - \sum_{n=1}^N D_n \sum_{t \geq 0} \sum_{\omega \in \Omega^{t+1}} \delta_\omega(y, t + 1) \mathbf{1}_{I_n}(T_{\omega_1^t}(y)) = - \sum_{n=1}^N D_n \text{KI}_n(y).
 \end{aligned}$$

□

For the invariant densities, we need to keep track of the orbits of the limits from the left and from the right of each partition point. Set, for $1 \leq i \leq N - 1$ and $j \in \Omega$,

$$a_{i,j} := k_{i,j} z_i + d_{i,j} = \lim_{x \uparrow z_i} T_j(x), \quad \text{and} \quad b_{i,j} := k_{i+1,j} z_i + d_{i+1,j} = \lim_{x \downarrow z_i} T_j(x).$$

See also Figure 1.

Definition 3.3. The $N \times (N - 1)$ matrix $M = (\mu_{n,i})$ given by

$$\mu_{n,i} := \begin{cases} \left[\sum_{j \in \Omega} \left[\frac{p_j}{k_{i,j}} + \frac{p_j}{k_{i,j}} \text{KI}_n(a_{i,j}) - \frac{p_j}{k_{i+1,j}} \text{KI}_n(b_{i,j}) \right] \right] & \text{for } n = i, \\ \left[\sum_{j \in \Omega} \left[\frac{p_j}{k_{i,j}} \text{KI}_n(a_{i,j}) - \frac{p_j}{k_{i+1,j}} - \frac{p_j}{k_{i+1,j}} \text{KI}_n(b_{i,j}) \right] \right] & \text{for } n = i + 1, \\ \left[\sum_{j \in \Omega} \left[\frac{p_j}{k_{i,j}} \text{KI}_n(a_{i,j}) - \frac{p_j}{k_{i+1,j}} \text{KI}_n(b_{i,j}) \right] \right] & \text{otherwise,} \end{cases}$$

is called the *fundamental matrix* of the random piecewise linear system T .

Note that assumption (A2) together with the fact that $|\text{KI}_n(y)| < \infty$ for all $y \in [0, 1]$ implies that all entries of M are finite. In the next section we associate invariant functions h_γ to vectors $\gamma \in \mathbb{R}^{N-1}$ in the null space of M . Here we prove that the null space of M is non-trivial.

LEMMA 3.4. *The system $M\gamma = 0$ admits at least one non-trivial solution.*

Proof. Since M has dimension $N \times (N - 1)$, by the Rouché–Capelli theorem the associated homogeneous system admits a non-trivial solution if and only if the rank of M is at most $N - 2$. Below we will give non-trivial linear dependence relations between all combinations of $N - 1$ out of N rows. It follows that any minor of order $N - 1$ of M is zero and thus that the rank of M is at most $N - 2$. We first show that for every $1 \leq i \leq N - 1$,

$$\sum_{n=1}^N K_n \mu_{n,i} = 0 \quad \text{and} \quad \sum_{n=1}^N D_n \mu_{n,i} = 0. \tag{15}$$

Indeed by Lemma 3.2,

$$\begin{aligned} & \sum_{n=1}^N K_n \mu_{n,i} \\ &= \sum_{j \in \Omega} \left[\frac{p_j}{k_{i,j}} K_i - \frac{p_j}{k_{i+1,j}} K_{i+1} + \frac{p_j}{k_{i,j}} \sum_{n=1}^N K_n \text{KI}_n(a_{i,j}) - \frac{p_j}{k_{i+1,j}} \sum_{n=1}^N K_n \text{KI}_n(b_{i,j}) \right] \\ &= S_i(S_i^{-1} - 1) - S_{i+1}(S_{i+1}^{-1} - 1) + S_i - S_{i+1} = 0. \end{aligned}$$

On the other hand, by the definition of the points $a_{i,j}$ and $b_{i,j}$,

$$\begin{aligned} & \sum_{n=1}^N D_n \mu_{n,i} \\ &= \sum_{j \in \Omega} \left[\frac{p_j}{k_{i,j}} D_i - \frac{p_j}{k_{i+1,j}} D_{i+1} + \frac{p_j}{k_{i,j}} \sum_{n=1}^N D_n \text{KI}_n(a_{i,j}) - \frac{p_j}{k_{i+1,j}} \sum_{n=1}^N D_n \text{KI}_n(b_{i,j}) \right] \\ &= \sum_{j \in \Omega} \left(S_i S_i^{-1} \frac{p_j}{k_{i,j}} d_{i,j} - S_{i+1} S_{i+1}^{-1} \frac{p_j}{k_{i+1,j}} d_{i+1,j} - \frac{p_j}{k_{i,j}} a_{i,j} + \frac{p_j}{k_{i+1,j}} b_{i,j} \right) = 0. \end{aligned}$$

Consequently, for every $1 \leq l \leq N$ and every $1 \leq i \leq N - 1$,

$$\sum_{n=1, n \neq l}^N (D_l K_n - D_n K_l) \mu_{n,i} = 0.$$

By assumption (A3) this gives non-trivial linear dependence relations between all combinations of $N - 1$ out of N rows, giving the result. □

Remark 3.5. Note that if $S_n = 0$ for some $1 \leq n \leq N$, then the quantities K_n and D_n are not well defined. In this case $\mu_{n,i} = \sum_{j \in \Omega} (p_j/k_{i,j}) \text{KI}_n(a_{i,j}) - (p_j/(k_{i+1,j})) \text{KI}_n(b_{i,j})$ for each $1 \leq i \leq N - 1$ and by the definition of KI_n we can write for any $y \in [0, 1]$ that

$$\begin{aligned} \text{KI}_n(y) &= \sum_{t \geq 1} \sum_{\omega \in \Omega^{t-1}} \sum_{j \in \Omega} \delta_{\omega}(y, t - 1) \frac{p_j}{k_{n,j}} 1_{I_n}(T_{\omega_1^{t-1}}(y)) \\ &= \sum_{t \geq 1} \sum_{\omega \in \Omega^{t-1}} \delta_{\omega}(y, t - 1) 1_{I_n}(T_{\omega_1^{t-1}}(y)) S_n = 0. \end{aligned}$$

Hence, $\mu_{n,i} = 0$ for each i . From this, it is clear that if $S_n = 0$ for at least two indices n , then a non-trivial vector γ such that $M\gamma = 0$ still exists. If there is a unique ℓ with $S_{\ell} = 0$, then to obtain a non-trivial solution one still needs to find suitable constants c_n such that $\sum_{n=1, n \neq \ell}^N c_n \mu_{n,i} = 0$ for each i .

Any vector γ from the null space of M satisfies the following orthogonal relations, linking γ to the functions KA_i and KB_i .

LEMMA 3.6. For all $1 \leq i \leq N - 1$ we have the following orthogonal relations:

$$\gamma_i + \sum_{m=1}^{N-1} \gamma_m \sum_{j \in \Omega} \left[\frac{p_j}{k_{m,j}} \text{KA}_i(a_{m,j}) - \frac{p_j}{k_{m+1,j}} \text{KA}_i(b_{m,j}) \right] = 0,$$

and

$$\gamma_i - \sum_{m=1}^{N-1} \gamma_m \sum_{j \in \Omega} \left[\frac{p_j}{k_{m,j}} \text{KB}_i(a_{m,j}) - \frac{p_j}{k_{m+1,j}} \text{KB}_i(b_{m,j}) \right] = 0.$$

Proof. If γ is a solution of the system $M\gamma = 0$, then $\sum_{m=1}^{N-1} \gamma_m \mu_{n,m} = 0$ for all n . Lemma 3.1 gives for $n = 1$,

$$\begin{aligned} 0 &= S_1^{-1} \sum_{m=1}^{N-1} \gamma_m \mu_{1,m} \\ &= S_1^{-1} \gamma_1 \sum_{j \in \Omega} \frac{p_j}{k_{1,j}} + S_1^{-1} \sum_{m=1}^{N-1} \gamma_m \sum_{j \in \Omega} \left(\frac{p_j}{k_{m,j}} \text{KI}_1(a_{m,j}) - \frac{p_j}{k_{m+1,j}} \text{KI}_1(b_{m,j}) \right) \\ &= \gamma_1 + \sum_{m=1}^{N-1} \gamma_m \sum_{j \in \Omega} \left(\frac{p_j}{k_{m,j}} \text{KA}_1(a_{m,j}) - \frac{p_j}{k_{m+1,j}} \text{KA}_1(b_{m,j}) \right). \end{aligned}$$

For $2 \leq n \leq N - 1$ we similarly obtain

$$\begin{aligned} 0 &= S_n^{-1} \sum_{m=1}^{N-1} \gamma_m \mu_{n,m} = S_n^{-1} \sum_{m=1}^{N-1} \gamma_m \sum_{j \in \Omega} \left(\frac{p_j}{k_{m,j}} \text{KI}_n(a_{m,j}) - \frac{p_j}{k_{m+1,j}} \text{KI}_n(b_{m,j}) \right) \\ &\quad + S_n^{-1} \left(\gamma_n \sum_{j \in \Omega} \frac{p_j}{k_{n,j}} - \gamma_{n-1} \sum_{j \in \Omega} \frac{p_j}{k_{n,j}} \right) \\ &= S_n^{-1} \sum_{m=1}^{N-1} \gamma_m \sum_{j \in \Omega} \left(\frac{p_j}{k_{m,j}} \text{KI}_n(a_{m,j}) - \frac{p_j}{k_{m+1,j}} \text{KI}_n(b_{m,j}) \right) \\ &\quad + \gamma_n - \gamma_{n-1}. \end{aligned} \tag{16}$$

Then summing over all $1 \leq n \leq i$ and using (16) and Lemma 3.1 gives

$$\begin{aligned} 0 &= \sum_{n=1}^i S_n^{-1} \sum_{m=1}^{N-1} \gamma_m \mu_{n,m} \\ &= \gamma_i + \sum_{n=1}^i S_n^{-1} \sum_{m=1}^{N-1} \gamma_m \sum_{j \in \Omega} \left(\frac{p_j}{k_{m,j}} \text{KI}_n(a_{m,j}) - \frac{p_j}{k_{m+1,j}} \text{KI}_n(b_{m,j}) \right) \\ &= \gamma_i + \sum_{m=1}^{N-1} \gamma_m \sum_{j \in \Omega} \left(\frac{p_j}{k_{m,j}} \text{KA}_i(a_{m,j}) - \frac{p_j}{k_{m+1,j}} \text{KA}_i(b_{m,j}) \right). \end{aligned}$$

This gives the relations for KA_i .

From $\sum_{m=1}^{N-1} \gamma_m \mu_{n,m} = 0$ for all n it also follows that $\sum_{m=1}^{N-1} \gamma_m \sum_{n=1}^N \mu_{n,m} = 0$. From this we obtain that

$$\sum_{m=1}^{N-1} \gamma_m \sum_{j \in \Omega} \frac{p_j}{k_{m,j}} \left(1 + \sum_{n=1}^N \text{KI}_n(a_{m,j}) \right) = \sum_{m=1}^{N-1} \gamma_m \sum_{j \in \Omega} \frac{p_j}{k_{m+1,j}} \left(1 + \sum_{n=1}^N \text{KI}_n(b_{m,j}) \right).$$

Then (10) from the proof of Lemma 3.2 gives that

$$\sum_{m=1}^{N-1} \gamma_m \sum_{j \in \Omega} \frac{p_j}{k_{m,j}} \sum_{n=1}^N S_n^{-1} \text{KI}_n(a_{m,j}) = \sum_{m=1}^{N-1} \gamma_m \sum_{j \in \Omega} \frac{p_j}{k_{m+1,j}} \sum_{n=1}^N S_n^{-1} \text{KI}_n(b_{m,j}).$$

Hence, by Lemma 3.1 we get for each i that

$$\sum_{m=1}^{N-1} \gamma_m \sum_{j \in \Omega} \frac{p_j}{k_{m,j}} (\text{KA}_i(a_{m,j}) + \text{KB}_i(a_{m,j})) = \sum_{m=1}^{N-1} \gamma_m \sum_{j \in \Omega} \frac{p_j}{k_{m+1,j}} (\text{KA}_i(b_{m,j}) + \text{KB}_i(b_{m,j})).$$

This gives the orthogonal relations for KB_i . □

In the proofs of our main results we only use the second part of Lemma 3.6, that is, the orthogonal relations for KB_i , but since we obtain the orthogonal relations for KA_i and KB_i more or less simultaneously, we have listed them both.

4. Invariant densities for the random system T

We now state our main result. For $y \in [0, 1]$, define the $L^1(\lambda)$ -function $L_y : [0, 1] \rightarrow \mathbb{R}$ by

$$L_y(x) = \sum_{t \geq 0} \sum_{\omega \in \Omega^t} \delta_\omega(y, t) \mathbf{1}_{[0, T_\omega(y))}(x). \tag{17}$$

THEOREM 4.1. *Let T be a random piecewise linear system on the unit interval $[0, 1]$ that satisfies assumptions (A1)–(A5) from §2. Let M be the corresponding fundamental matrix and let $\gamma = (\gamma_1, \dots, \gamma_{N-1})^\top$ be a non-trivial solution of the system $M\gamma = 0$. For each $1 \leq m \leq N - 1$, define the function $h_m : [0, 1] \rightarrow \mathbb{R}$ by*

$$h_m(x) := \sum_{\ell \in \Omega} \left[\frac{p_\ell}{k_{m,\ell}} L_{a_{m,\ell}}(x) - \frac{p_\ell}{k_{m+1,\ell}} L_{b_{m,\ell}}(x) \right]. \tag{18}$$

Then a T -invariant function is given by

$$h_\gamma : [0, 1] \rightarrow \mathbb{R}, \quad x \mapsto \sum_{m=1}^{N-1} \gamma_m h_m(x) \tag{19}$$

and $h_\gamma \neq 0$.

To show that $P_T h_\gamma = h_\gamma$ λ -a.e. we have to determine, for each $x \in [0, 1]$ and each branch $T_{i,j}$, whether or not x has an inverse image in the branch $T_{i,j}$. Let

$$x_{i,j} := \frac{x - d_{i,j}}{k_{i,j}}$$

be the inverse of x under the map $T_{i,j} : \mathbb{R} \rightarrow \mathbb{R}$. By the definitions in (18) and (19), we have to show that

$$\begin{aligned}
 h_\gamma(x) &= \sum_{j \in \Omega} \sum_{i=1}^N \frac{p_j}{|k_{i,j}|} h_\gamma(x_{i,j}) \mathbf{1}_{I_i}(x_{i,j}) \\
 &= \sum_{j \in \Omega} \sum_{i=1}^N \frac{p_j}{|k_{i,j}|} \mathbf{1}_{I_i}(x_{i,j}) \sum_{m=1}^{N-1} \gamma_m \sum_{\ell \in \Omega} \left(\frac{p_\ell}{k_{m,\ell}} L_{a_{m,\ell}}(x_{i,j}) - \frac{p_\ell}{k_{m+1,\ell}} L_{b_{m,\ell}}(x_{i,j}) \right).
 \end{aligned}
 \tag{20}$$

The parts for $L_{a_{m,\ell}}$ and $L_{b_{m,\ell}}$ behave similarly. That is why we first study

$$\sum_{j \in \Omega} \sum_{i=1}^N \frac{p_j}{|k_{i,j}|} \mathbf{1}_{I_i}(x_{i,j}) L_y(x_{i,j})$$

for general $y \in [0, 1]$ through several lemmas. We introduce some notation to manage the long expressions. For $1 \leq i \leq N - 1$, let

$$\eta_i := \sum_{j \in \Omega} \frac{p_j (\mathbf{1}_{(0,\infty)}(k_{i,j}) - a_{i,j})}{k_{i,j}} \quad \text{and} \quad \phi_i := \sum_{j \in \Omega} \frac{p_j (-\mathbf{1}_{(-\infty,0)}(k_{i+1,j}) + b_{i,j})}{k_{i+1,j}}.$$

For $y \in [0, 1]$ let $1 \leq n \leq N$ be the index such that $y \in I_n$ and set

$$C(y) := \sum_{j \in \Omega} \left(\sum_{i=1}^{n-1} \frac{p_j}{|k_{i,j}|} + \frac{p_j}{|k_{n,j}|} \mathbf{1}_{(-\infty,0)}(k_{n,j}) \right).
 \tag{21}$$

LEMMA 4.2. *Let $y \in [0, 1]$. Then*

$$y = \sum_{i \geq 0} \sum_{\omega \in \Omega^i} \delta_\omega(y, t) C(T_\omega(y)) - \sum_{i=1}^{N-1} (\eta_i + \phi_i) \text{KB}_i(y).$$

Proof. Let $y \in [0, 1]$ be given and recall the definition of $\theta_\omega(z, t)$ from (11). If $y \in I_n$, then

$$\begin{aligned}
 C(y) - \sum_{i=1}^{N-1} (\eta_i + \phi_i) \mathbf{1}_{B_i}(y) &= \sum_{j \in \Omega} \frac{p_j}{|k_{n,j}|} \mathbf{1}_{(-\infty,0)}(k_{n,j}) \\
 &\quad + \sum_{j \in \Omega} \sum_{i=1}^{n-1} \left(\frac{p_j}{|k_{i,j}|} - \frac{p_j (\mathbf{1}_{(0,\infty)}(k_{i,j}) - a_{i,j})}{k_{i,j}} - \frac{p_j (-\mathbf{1}_{(-\infty,0)}(k_{i+1,j}) + b_{i,j})}{k_{i+1,j}} \right) \\
 &= \sum_{j \in \Omega} \left(-\frac{p_j}{k_{n,j}} b_{n-1,j} + \frac{p_j}{|k_{1,j}|} - \frac{p_j}{k_{1,j}} \mathbf{1}_{(0,\infty)}(k_{1,j}) + \frac{p_j}{k_{1,j}} a_{1,j} + \sum_{i=2}^{n-1} \frac{p_j}{k_{i,j}} (a_{i,j} - b_{i-1,j}) \right) \\
 &= -\sum_{j \in \Omega} \frac{p_j}{k_{n,j}} d_{n,j} = \sum_{j \in \Omega} \theta_j(y, 1),
 \end{aligned}$$

where we have used the assumptions from (A4) in the second to last step. So for any $t \geq 0$ and $\omega \in \Omega^t$ we get that

$$C(T_\omega(y)) - \sum_{i=1}^{N-1} (\eta_i + \phi_i) \mathbf{1}_{B_i}(T_\omega(y)) = \sum_{j \in \Omega} \theta_{\omega j}(y, t + 1), \tag{22}$$

where ωj denotes the concatenation of ω with $j \in \Omega$. Recall from the first line of (14) that

$$y = \sum_{t \geq 0} \sum_{\omega \in \Omega^t} \delta_\omega(y, t) \sum_{j \in \Omega} \theta_{\omega j}(y, t + 1).$$

Combining this with (22) and the definition of KB_i from (7) then gives the result. □

For each $1 \leq i \leq N - 1$, define the functions $E_i, F_i : [0, 1] \rightarrow \mathbb{R}$ by

$$E_i(x) := \sum_{j \in \Omega} \frac{p_j}{|k_{i,j}|} \left(-\mathbf{1}_{[a_i,j,1]}(x) \mathbf{1}_{(0,\infty)}(k_{i,j}) + \mathbf{1}_{[0,a_i,j]}(x) \mathbf{1}_{(-\infty,0)}(k_{i,j}) \right),$$

$$F_i(x) := \sum_{j \in \Omega} \frac{p_j}{|k_{i+1,j}|} \left(-\mathbf{1}_{[0,b_i,j]}(x) \mathbf{1}_{(0,\infty)}(k_{i+1,j}) + \mathbf{1}_{[b_i,j,1]}(x) \mathbf{1}_{(-\infty,0)}(k_{i+1,j}) \right)$$

and let $E_N, F_0 : [0, 1] \rightarrow \mathbb{R}$ be the zero functions. Then for each $1 \leq i \leq N$ we have that for Lebesgue almost every $x \in [0, 1]$,

$$E_i(x) + F_{i-1}(x) = \sum_{j \in \Omega} \frac{p_j}{|k_{i,j}|} (\mathbf{1}_{I_i}(x_{i,j}) - 1),$$

where we have used (A4) for $i = 1, N$. In fact, equality holds for all but countably many points.

LEMMA 4.3. *For $y \in [0, 1]$ we have that for Lebesgue almost every $x \in [0, 1]$,*

$$\begin{aligned} & \sum_{j \in \Omega} \sum_{i=1}^N \frac{p_j}{|k_{i,j}|} \mathbf{1}_{I_i}(x_{i,j}) L_y(x_{i,j}) \\ &= \sum_{i=1}^{N-1} (E_i(x) + \eta_i + F_i(x) + \phi_i) \text{KB}_i(y) + y + L_y(x) - \mathbf{1}_{[0,y]}(x). \end{aligned}$$

Proof. For $y \in [0, 1]$, let $1 \leq n \leq N$ be the index such that $y \in I_n$. By Fubini’s theorem, we get

$$\sum_{j \in \Omega} \sum_{i=1}^N \frac{p_j}{|k_{i,j}|} \mathbf{1}_{I_i}(x_{i,j}) L_y(x_{i,j}) = \sum_{t \geq 0} \sum_{\omega \in \Omega^t} \delta_\omega(y, t) \sum_{i=1}^N \sum_{j \in \Omega} \frac{p_j}{|k_{i,j}|} \mathbf{1}_{I_i \cap [0, T_\omega(y)]}(x_{i,j}). \tag{23}$$

For Lebesgue almost every $x \in [0, 1]$ and for $n \neq 1$ we have that

$$\begin{aligned} & \sum_{j \in \Omega} \frac{p_j}{|k_{n,j}|} \mathbf{1}_{(-\infty,0)}(k_{n,j}) + \sum_{j \in \Omega} \frac{p_j}{k_{n,j}} \mathbf{1}_{[0,T_j(y)]}(x) + F_{n-1}(x) \\ &= \sum_{j \in \Omega} \left(\frac{p_j}{|k_{n,j}|} \mathbf{1}_{(-\infty,0)}(k_{n,j}) (1 - \mathbf{1}_{[0,T_j(y)]}(x)) - \mathbf{1}_{[b_{n-1,j},1]}(x) \right) \end{aligned}$$

$$\begin{aligned}
 & + \frac{P_j}{|k_{n,j}|} \mathbf{1}_{(0,\infty)}(k_{n,j}) (\mathbf{1}_{[0,T_j(y))}(x) - \mathbf{1}_{[0,b_{n-1,j})}(x)) \\
 & = \sum_{j \in \Omega} \frac{P_j}{|k_{n,j}|} \mathbf{1}_{I_n \cap [0,y)}(x_{n,j}).
 \end{aligned} \tag{24}$$

Using (A4), we also get that

$$\sum_{j \in \Omega} \frac{P_j}{|k_{1,j}|} \mathbf{1}_{(-\infty,0)}(k_{1,j}) + \sum_{j \in \Omega} \frac{P_j}{k_{1,j}} \mathbf{1}_{[0,T_j(y))}(x) + F_0(x) = \sum_{j \in \Omega} \frac{P_j}{|k_{1,j}|} \mathbf{1}_{I_1 \cap [0,y)}(x_{1,j}),$$

so the statement from (24) holds for all $1 \leq n \leq N$. Since $y \in I_n$ we have for Lebesgue almost every $x \in [0, 1]$ that

$$\sum_{i=1}^{N-1} (E_i(x) + F_i(x)) \mathbf{1}_{B_i}(y) = \sum_{i=1}^{n-1} \sum_{j \in \Omega} \frac{P_j}{|k_{i,j}|} (\mathbf{1}_{I_i}(x_{i,j}) - 1) + F_{n-1}(x).$$

Combining this with (24) and the definition of $C(y)$ from (21), we obtain that for each $y \in [0, 1]$, there is a set of $x \in [0, 1]$ of full Lebesgue measure, for which

$$\begin{aligned}
 & \sum_{j \in \Omega} \sum_{i=1}^N \frac{P_j}{|k_{i,j}|} \mathbf{1}_{I_i \cap [0,y)}(x_{i,j}) \\
 & = \sum_{j \in \Omega} \sum_{i=1}^{n-1} \frac{P_j}{|k_{i,j}|} \mathbf{1}_{I_i}(x_{i,j}) + \sum_{j \in \Omega} \frac{P_j}{|k_{n,j}|} \mathbf{1}_{(-\infty,0)}(k_{n,j}) + \sum_{j \in \Omega} \frac{P_j}{k_{n,j}} \mathbf{1}_{[0,T_j(y))}(x) + F_{n-1}(x) \\
 & = \sum_{i=1}^{N-1} (E_i(x) + F_i(x)) \mathbf{1}_{B_i}(y) + C(y) + \sum_{j \in \Omega} \tau_j(y, 1) \mathbf{1}_{[0,T_j(y))}(x).
 \end{aligned}$$

Hence, by (23) we also have that for Lebesgue almost every $x \in [0, 1]$,

$$\begin{aligned}
 & \sum_{j \in \Omega} \sum_{i=1}^N \frac{P_j}{|k_{i,j}|} \mathbf{1}_{I_i}(x_{i,j}) L_y(x_{i,j}) \\
 & = \sum_{i=1}^{N-1} (E_i(x) + F_i(x)) \sum_{t \geq 0} \sum_{\omega \in \Omega^t} \delta_\omega(y, t) \mathbf{1}_{B_i}(T_\omega(y)) \\
 & \quad + \sum_{t \geq 0} \sum_{\omega \in \Omega^t} \delta_\omega(y, t) C(T_\omega(y)) + \sum_{t \geq 1} \sum_{\omega \in \Omega^t} \delta_\omega(y, t) \mathbf{1}_{[0,T_\omega(y))}(x).
 \end{aligned}$$

The statement now follows from the definition of KB_i from (7) and Lemma 4.2. □

Proof of Theorem 4.1. First note that for all $1 \leq i \leq N - 1$ and all $x \in [0, 1]$,

$$E_i(x) + \eta_i = \sum_{j \in \Omega} \frac{P_j}{k_{i,j}} \left(\mathbf{1}_{[0,a_{i,j})}(x) - a_{i,j} \right)$$

and

$$F_i(x) + \phi_i = \sum_{j \in \Omega} \frac{P_j}{k_{i+1,j}} \left(- \mathbf{1}_{[0,b_{i,j})}(x) + b_{i,j} \right).$$

Together they give that

$$\sum_{\ell \in \Omega} \left(\frac{p_\ell}{k_{m,\ell}} (-\mathbf{1}_{[0,a_{m,\ell})}(x) + a_{m,\ell}) - \frac{p_\ell}{k_{m+1,\ell}} (-\mathbf{1}_{[0,b_{m,\ell})}(x) + b_{m,\ell}) \right) = -(E_m(x) + \eta_m + F_m(x) + \phi_m).$$

Using this together with Lemma 4.3 and Fubini’s theorem, we get by (20) that for Lebesgue almost every $x \in [0, 1]$,

$$\begin{aligned} P_T h_\gamma(x) &= \sum_{m=1}^{N-1} \gamma_m \sum_{i=1}^{N-1} (E_i(x) + \eta_i + F_i(x) + \phi_i) \sum_{\ell \in \Omega} \left(\frac{p_\ell}{k_{m,\ell}} \text{KB}_i(a_{m,\ell}) - \frac{p_\ell}{k_{m+1,\ell}} \text{KB}_i(b_{m,\ell}) \right) \\ &\quad - \sum_{m=1}^{N-1} \gamma_m (E_m(x) + \eta_m + F_m(x) + \phi_m) + h_\gamma(x). \end{aligned}$$

From the second part of Lemma 3.6 we can deduce by multiplying by $E_i(x) + \eta_i + F_i(x) + \phi_i$ and summing over all i that

$$\begin{aligned} &\sum_{i=1}^{N-1} (E_i(x) + \eta_i + F_i(x) + \phi_i) \gamma_i \\ &= \sum_{i=1}^{N-1} (E_i(x) + \eta_i + F_i(x) + \phi_i) \sum_{m=1}^{N-1} \gamma_m \sum_{j \in \Omega} \left(\frac{p_j}{k_{m,j}} \text{KB}_i(a_{m,j}) - \frac{p_j}{k_{m+1,j}} \text{KB}_i(b_{m,j}) \right). \end{aligned}$$

Hence, we have obtained that h_γ is a T -invariant function in $L^1(\lambda)$.

It remains to show that $h_\gamma \neq 0$. Recall from §2 that any T -invariant $L^1(\lambda)$ -function is of bounded variation. So at any point $y \in [0, 1]$ the limits $\lim_{x \uparrow y} h_\gamma(x)$ and $\lim_{x \downarrow y} h_\gamma(x)$ exist. Consider $1 \leq \ell \leq N - 1$ and assume $z_\ell \in I_\ell$. Then for all $y \in [0, 1]$, by (6) and (7), we obtain, by the dominated convergence theorem,

$$\lim_{x \downarrow z_\ell} L_y(x) = \sum_{t \geq 0} \sum_{\omega \in \Omega^t} \delta_\omega(y, t) \lim_{x \downarrow z_\ell} \mathbf{1}_{[0, T_\omega(y))}(x) = \sum_{t \geq 0} \sum_{\omega \in \Omega^t} \delta_\omega(y, t) \mathbf{1}_{B_\ell}(T_\omega(y)) = \text{KB}_\ell(y).$$

From this, Lemma 3.6 and the dominated convergence theorem again we then get

$$\begin{aligned} \lim_{x \downarrow z_\ell} h_\gamma(x) &= \sum_{m=1}^{N-1} \gamma_m \sum_{j \in \Omega} \lim_{x \downarrow z_\ell} \left[\frac{p_j}{k_{m,j}} L_{a_{m,j}}(x) - \frac{p_j}{k_{m+1,j}} L_{b_{m,j}}(x) \right] \\ &= \sum_{m=1}^{N-1} \gamma_m \sum_{j \in \Omega} \left[\frac{p_j}{k_{m,j}} \text{KB}_\ell(a_{m,j}) - \frac{p_j}{k_{m+1,j}} \text{KB}_\ell(b_{m,j}) \right] \\ &= \gamma_\ell. \end{aligned} \tag{25}$$

If, on the other hand, $z_\ell \in I_{\ell+1}$, then we obtain similarly that $\lim_{x \uparrow z_\ell} L_y(x) = \text{KB}_\ell(y)$ and thus that $\lim_{x \uparrow z_\ell} h_\gamma(x) = \gamma_\ell$. Hence, $h_\gamma = 0$ implies $\gamma = 0$. This proves the theorem. \square

Remark 4.4. Theorem 4.1 assigns to each solution $\gamma \neq 0$ of $M\gamma = 0$ a T -invariant $L^1(\lambda)$ -function $h_\gamma \neq 0$. From h_γ we can get invariant densities for T as follows. If h_γ is positive or negative, then we can scale h_γ to an invariant density function. If not, then we can write $h_\gamma = h^+ - h^-$ for two positive functions $h^+ : [0, 1] \rightarrow [0, \infty)$ and $h^- : [0, 1] \rightarrow [0, \infty)$ and by the linearity and positivity of P_T it follows that

$$h^+ - h^- = h_\gamma = P_T h_\gamma = P_T h^+ - P_T h^-.$$

Hence, h^+ and h^- can both be normalized to obtain invariant densities for T .

Remark 4.5. In order to compute h_γ , one needs to compute the fundamental matrix M and a vector γ first. Lemma 3.4 implies that when N is small, the computation of γ is straightforward. Indeed, for $N = 2$, M is the null vector, and we can take $\gamma = 1$. This is illustrated by the example of the random tent maps from §6.1. For $N = 3$, it is enough to compute only one row of M and take $\gamma = \begin{pmatrix} -\mu_{i,2} \\ \mu_{i,1} \end{pmatrix}^\top$. We see an illustration of this fact in §6.3 and §6.4 on random β -transformations. For larger N , the computation of M can still be simplified by using the relations from Lemma 3.2.

To end this section we give a small example to show that condition (A5) is not necessary for Theorem 4.1 to hold. Consider the random system with $\Omega = \{0, 1\}$, $T_0(x) = 2x \pmod{1}$ the doubling map, $T_1(x) = 1 - T_0(x)$ and $p_0 = p_1 = \frac{1}{2}$. Then $N = 2$ and for both $n = 1, 2$ we have $S_n = \frac{1}{2} \cdot \frac{1}{2} - \frac{1}{2} \cdot \frac{1}{2} = 0$. Hence $M = \begin{pmatrix} 0 \\ 0 \end{pmatrix}^\top$ and any $\gamma = \gamma_1 \in \mathbb{R} \setminus \{0\}$ is a non-trivial solution to $M\gamma = 0$. Since all critical points of T_0 and T_1 are mapped to 0 or 1, the function h_1 from (18) will be of the form $c \cdot \mathbf{1}_{[0,1]}$ for some $c \neq 0$ and the function $h_\gamma = \gamma/c \cdot \mathbf{1}_{[0,1]}$ is indeed invariant for T .

5. All possible absolutely continuous invariant measures

The aim of this section is twofold. Firstly, we prove that the way T is defined on the partition points z_ℓ does not influence the final result. In other words, the set of invariant functions we obtain from Theorem 4.1 if $z_\ell \in I_\ell$ is equal to the set of invariant functions we obtain if we choose $z_\ell \in I_{\ell+1}$. This is the content of Proposition 5.1. The amount of work it takes to compute the matrix M and the invariant functions h_γ depends on whether $z_\ell \in I_\ell$ or $z_\ell \in I_{\ell+1}$. Proposition 5.1 tells us that we are free to choose the most convenient option. We shall see several examples below. Next we will use Proposition 5.1 to prove that, under the additional assumption that all maps T_j are expanding, Theorem 4.1 actually produces all absolutely continuous invariant measures of T . We do this by proving in Theorem 5.3 that the map $\gamma \mapsto h_\gamma$ is a bijection between the null space of M and the subspace of $L^1(\lambda)$ of all T -invariant functions.

PROPOSITION 5.1. *Let T be a random system with partition $\{I_i\}_{1 \leq i \leq N}$ and corresponding partition points z_0, \dots, z_N . Let $\{\hat{I}_i\}_{1 \leq i \leq N}$ be another partition of $[0, 1]$ given by z_0, \dots, z_N and differing from $\{I_i\}_{1 \leq i \leq N}$ only in one or more of the points z_1, \dots, z_{N-1} . Let \hat{T} be the corresponding random system, that is, $\hat{T}(x) = T(x)$ for all $x \neq z_i$, $1 \leq i \leq N - 1$. Let \hat{M} be the fundamental matrix of \hat{T} . There is a one-to-one correspondence between the solutions γ of $M\gamma = 0$ and the solutions $\hat{\gamma}$ of $\hat{M}\hat{\gamma} = 0$. Moreover, the functions h_γ and $\hat{h}_{\hat{\gamma}}$ coincide.*

Proof. First assume that there is only one point z_ℓ on which $\{I_i\}_{1 \leq i \leq N}$ and $\{\hat{I}_i\}_{1 \leq i \leq N}$ differ. We show that any column of \hat{M} is a linear combination of columns of M . More precisely, we show that the i th column of \hat{M} is a linear combination of the i th and the ℓ th columns of M . Assume without loss of generality that $z_\ell \in I_\ell$ and therefore $z_\ell \in \hat{I}_{\ell+1}$. This implies that $T_j(z_\ell) = a_{\ell,j}$, whereas $\hat{T}_j(z_\ell) = b_{\ell,j}$. This difference is reflected in the values of the quantities $\text{KI}_n(a_{i,s})$ and $\text{KI}_n(b_{i,s})$ appearing in the matrix M if $a_{i,s}$ or $b_{i,s}$ enters z_ℓ under some iteration of T . We will describe these changes, but first we define some quantities.

For any $y \in \{a_{i,j}, b_{i,j} : 1 \leq i \leq N - 1, j \in \Omega\}$ let $\Omega_y \subseteq \Omega^*$ be the collection of paths that lead y to z_ℓ , that is, $\omega \in \Omega_y$ if and only if there is a $0 \leq t < |\omega|$, such that $T_{\omega_1^t}(y) = z_\ell$. Let

$$\Omega_y^t := \{\omega \in \Omega^* \mid \exists \eta \in \Omega_y : \omega = \eta_1^t, T_\omega(y) = z_\ell \text{ and } T_{\omega_1^s}(y) \neq z_\ell \text{ for } s < t\}.$$

Then Ω_y^t is the collection of words of length t that lead y to z_ℓ via a path that does not lead y to z_ℓ before time t . We are interested in the difference between the quantities $\text{KI}_n(y)$ and $\hat{\text{KI}}_n(y)$ and we let C_n^y denote the part that they have in common, that is, set

$$C_n^y := \sum_{t \geq 1} \sum_{\omega \in \Omega_y^t \cup \Omega^t \setminus \Omega_y} \delta_\omega(y, t) \mathbf{1}_{I_n}(T_{\omega_1^{t-1}}(y)).$$

Then for $n \neq \ell$, we get

$$\begin{aligned} \text{KI}_n(y) &= C_n^y + \sum_{t \geq 0} \sum_{\omega \in \Omega_y^t} \sum_{u \geq 1} \sum_{\eta \in \Omega^u} \delta_\omega(y, t) \delta_\eta(z_\ell, u) \mathbf{1}_{I_n}(T_{\eta_1^{u-1}}(z_\ell)) \\ &= C_n^y + \sum_{t \geq 0} \sum_{\omega \in \Omega_y^t} \sum_{u \geq 1} \sum_{\eta \in \Omega^u} \sum_{j \in \Omega} \delta_\omega(y, t) \frac{p_j}{k_{\ell,j}} \delta_\eta(a_{\ell,j}, u) \mathbf{1}_{I_n}(T_{\eta_1^{u-1}}(a_{\ell,j})) \\ &= C_n^y + \sum_{t \geq 0} \sum_{\omega \in \Omega_y^t} \delta_\omega(y, t) \sum_{j \in \Omega} \frac{p_j}{k_{\ell,j}} \text{KI}_n(a_{\ell,j}), \end{aligned}$$

and similarly, for $n = \ell$ we obtain

$$\text{KI}_\ell(y) = C_\ell^y + \sum_{t \geq 0} \sum_{\omega \in \Omega_y^t} \delta_\omega(y, t) \sum_{j \in \Omega} \frac{p_j}{k_{\ell,j}} (1 + \text{KI}_\ell(a_{\ell,j})).$$

If we set $Q(y) = \sum_{t \geq 0} \sum_{\omega \in \Omega_y^t} \delta_\omega(y, t)$ as the constant that keeps track of all the paths that lead y to z_ℓ for the first time, then we can write

$$\begin{aligned} \text{KI}_n(y) &= C_n^y + Q(y) \sum_{j \in \Omega} \frac{p_j}{k_{\ell,j}} \text{KI}_n(a_{\ell,j}) \quad \text{for } n \neq \ell, \\ \text{KI}_\ell(y) &= C_\ell^y + Q(y) \sum_{j \in \Omega} \frac{p_j}{k_{\ell,j}} (1 + \text{KI}_\ell(a_{\ell,j})). \end{aligned} \tag{86}$$

On the other hand, for $\hat{K}I_n(y)$ we get

$$\begin{aligned} \hat{K}I_n(y) &= C_n^y + Q(y) \sum_{j \in \Omega} \frac{P_j}{k_{\ell+1,j}} \hat{K}I_n(b_{\ell,j}) \quad \text{for } n \neq \ell + 1, \\ \hat{K}I_{\ell+1}(y) &= C_{\ell+1}^y + Q(y) \sum_{j \in \Omega} \frac{P_j}{k_{\ell+1,j}} (1 + \hat{K}I_{\ell+1}(b_{\ell,j})). \end{aligned} \tag{27}$$

If $b_{\ell,j}$ does not return to z_ℓ , then $KI_n(b_{\ell,j}) = \hat{K}I_n(b_{\ell,j})$. Set

$$B := \{j \in \Omega : \Omega_{b_{\ell,j}} \neq \emptyset\}.$$

Then

$$\begin{aligned} \hat{K}I_n(y) &= C_n^y + Q(y) \sum_{j \notin B} \frac{P_j}{k_{\ell+1,j}} KI_n(b_{\ell,j}) \\ &\quad + Q(y) \sum_{j \in B} \frac{P_j}{k_{\ell+1,j}} \hat{K}I_n(b_{\ell,j}) \quad \text{for } n \neq \ell + 1, \\ \hat{K}I_{\ell+1}(y) &= C_{\ell+1}^y + Q(y) \sum_{j \notin B} \frac{P_j}{k_{\ell+1,j}} (1 + KI_{\ell+1}(b_{\ell,j})) \\ &\quad + Q(y) \sum_{j \in B} \frac{P_j}{k_{\ell+1,j}} (1 + \hat{K}I_{\ell+1}(b_{\ell,j})). \end{aligned}$$

To determine the difference between $KI_n(y)$ and $\hat{K}I_n(y)$, we would like an expression for $\hat{K}I_n(b_{\ell,j})$ in terms of $KI_n(b_{\ell,j})$ for $j \in B$. Fix $n \neq \ell + 1$ for a moment and set, for each $j \in B$,

$$A_j = C_n^{b_{\ell,j}} + Q(b_{\ell,j}) \sum_{i \notin B} \frac{P_i}{k_{\ell+1,i}} KI_n(b_{\ell,i}).$$

Then we can find expressions for $\hat{K}I_n(b_{\ell,j})$ in terms of the values $KI_n(b_{\ell,i})$ by solving the following system of linear equations:

$$\hat{K}I_n(b_{\ell,j}) = A_j + Q(b_{\ell,j}) \sum_{i \in B} \frac{P_i}{k_{\ell+1,i}} \hat{K}I_n(b_{\ell,i}), \quad j \in B.$$

A solution is easily computed through Cramer’s method, which gives, for $j \in B$,

$$\hat{K}I_n(b_{\ell,j}) = \frac{A_j (1 - \sum_{u \in B \setminus \{j\}} Q(b_{\ell,u}) (P_u / k_{\ell+1,u})) + Q(b_{\ell,j}) \sum_{u \in B \setminus \{j\}} (P_u / k_{\ell+1,u}) A_u}{1 - \sum_{i \in B} Q(b_{\ell,i}) (P_i / k_{\ell+1,i})}. \tag{28}$$

Set

$$B_\ell := 1 - \sum_{j \in \Omega} Q(b_{\ell,j}) \frac{P_j}{k_{\ell+1,j}}.$$

Below we will use B_ℓ^{-1} . If $|Q(b_{\ell,j})| \leq 1$, then

$$\left| \sum_{j \in \Omega} Q(b_{\ell,j}) \frac{P_j}{k_{\ell+1,j}} \right| \leq \sum_{j \in \Omega} |Q(b_{\ell,j})| \frac{P_j}{|k_{\ell+1,j}|} \leq \sum_{j \in \Omega} \frac{P_j}{|k_{\ell+1,j}|} \leq \rho < 1,$$

so in this case $B_\ell \neq 0$ and B_ℓ^{-1} is well defined. We now show that $|Q(b_{\ell,j})| \leq 1$. If $b_{\ell,j} = z_\ell$, then $\Omega_{b_{\ell,j}}^t = \emptyset$ for any $t \geq 1$, and so $Q(b_{\ell,j}) = 1$. If $b_{\ell,j} \neq z_\ell$, then $Q(b_{\ell,j}) = \sum_{t \geq 1} \sum_{\omega \in \Omega_{b_{\ell,j}}^t} \delta_\omega(b_{\ell,j}, t)$. By the expanding on average property (A2), for any $y \in I$, any $t \geq 0$ and any $\omega \in \Omega^\mathbb{N}$,

$$|\delta_\omega(y, t)| > \sum_{j \in \Omega} |\delta_\omega(y, t) \tau_j(T_{\omega_1^t}(y), 1)| = \sum_{j \in \Omega} |\delta_{\omega_j}(y, t + 1)|. \tag{29}$$

Note that by the definition of $Q(b_{\ell,j})$ the union

$$\bigcup_{t \geq 1} \bigcup_{\omega \in \Omega_{b_{\ell,j}}^t} [\omega] \subseteq \Omega^\mathbb{N} \tag{30}$$

is a disjoint union of cylinder sets. Hence, by repeated application of (29) we obtain for each $n \geq 1$ that

$$\begin{aligned} 1 = |\delta_\epsilon(b_{\ell,j}, 0)| &> \sum_{i_1 \in \Omega} |\delta_{i_1}(b_{\ell,j}, 1)| = \sum_{i_1 \in \Omega_{b_{\ell,j}}} |\delta_{i_1}(b_{\ell,j}, 1)| + \sum_{i_1 \in \Omega_{b_{\ell,j}}^c} |\delta_{i_1}(b_{\ell,j}, 1)| \\ &> \sum_{i_1 \in \Omega_{b_{\ell,j}}} |\delta_{i_1}(b_{\ell,j}, 1)| + \sum_{i_1 \in \Omega_{b_{\ell,j}}^c} \sum_{i_2 \in \Omega} |\delta_{i_1 i_2}(b_{\ell,j}, 2)| \\ &= \sum_{t=1}^2 \sum_{\omega \in \Omega_{b_{\ell,j}}^t} |\delta_\omega(b_{\ell,j}, t)| + \sum_{\omega \in (\Omega_{b_{\ell,j}} \cup \Omega_{b_{\ell,j}}^2)^c} |\delta_\omega(b_{\ell,j}, 2)| \\ &> \dots > \sum_{t=1}^n \sum_{\omega \in \Omega_{b_{\ell,j}}^t} |\delta_\omega(b_{\ell,j}, t)| + \sum_{\omega \in (\cup_{t=1}^n \Omega_{b_{\ell,j}}^t)^c} |\delta_\omega(b_{\ell,j}, n)|. \end{aligned}$$

Since this holds for each n , we get $|Q(b_{\ell,j})| \leq 1$ and $B_\ell \neq 0$.

For $i \notin B$ we have that $\text{KI}_n(b_{\ell,i}) = C_n^{b_{\ell,i}}$. Then, by the definition of B_ℓ , we get

$$\begin{aligned} \sum_{j \in B} \frac{p_j}{k_{\ell+1,j}} \text{KI}_n(b_{\ell,j}) &= B_\ell^{-1} \sum_{j \in B} \frac{p_j}{k_{\ell+1,j}} A_j \\ &= B_\ell^{-1} \sum_{j \in B} \frac{p_j}{k_{\ell+1,j}} \left(C_n^{b_{\ell,j}} + Q(b_{\ell,j}) \sum_{i \notin B} \frac{p_i}{k_{\ell+1,i}} C_n^{b_{\ell,i}} \right) \\ &= B_\ell^{-1} \sum_{j \in B} \frac{p_j}{k_{\ell+1,j}} C_n^{b_{\ell,j}} + B_\ell^{-1} (1 - B_\ell) \sum_{i \notin B} \frac{p_i}{k_{\ell+1,i}} C_n^{b_{\ell,i}} \\ &= B_\ell^{-1} \sum_{j \in \Omega} \frac{p_j}{k_{\ell+1,j}} C_n^{b_{\ell,j}} - \sum_{i \notin B} \frac{p_i}{k_{\ell+1,i}} C_n^{b_{\ell,i}}. \end{aligned} \tag{31}$$

We obtain similar expressions for $n = \ell + 1$. For each $1 \leq i \leq N - 1$, let

$$Q_i := \sum_{j \in \Omega} \left(\frac{p_j}{k_{i,j}} Q(a_{i,j}) - \frac{p_j}{k_{i+1,j}} Q(b_{i,j}) \right).$$

We show that for each $1 \leq n \leq N$ and $1 \leq i \leq N - 1$ we have

$$\hat{\mu}_{n,i} = \mu_{n,i} - Q_i B_\ell^{-1} \mu_{n,\ell},$$

that is, the i th column of \hat{M} is a linear combination of the i th and ℓ th columns of M . We give the proof only for $n \notin \{\ell, \ell + 1, i, i + 1\}$, since the other cases are very similar. To prove this, we first rewrite $\mu_{n,i} - Q_i B_\ell^{-1} \mu_{n,\ell}$. Therefore, note that

$$\begin{aligned} & \sum_{j \in \Omega} \frac{P_j}{k_{\ell,j}} \text{KI}_n(a_{\ell,j}) - B_\ell^{-1} \left(\sum_{j \in \Omega} \frac{P_j}{k_{\ell,j}} \text{KI}_n(a_{\ell,j}) - \sum_{j \in B} \frac{P_j}{k_{\ell+1,j}} Q(b_{\ell,j}) \sum_{i \in \Omega} \frac{P_i}{k_{\ell,i}} \text{KI}_n(a_{\ell,i}) \right) \\ &= \sum_{j \in \Omega} \frac{P_j}{k_{\ell,j}} \text{KI}_n(a_{\ell,j}) (1 - B_\ell^{-1} B_\ell) = 0. \end{aligned}$$

Then we obtain from the definition of M , (26) and the above equation that

$$\begin{aligned} \mu_{n,i} - Q_i B_\ell^{-1} \mu_{n,\ell} &= \sum_{j \in \Omega} \left(\frac{P_j}{k_{i,j}} C_n^{a_{i,j}} - \frac{P_j}{k_{i+1,j}} C_n^{b_{i,j}} \right) + Q_i \sum_{j \in \Omega} \frac{P_j}{k_{\ell,j}} \text{KI}_n(a_{\ell,j}) \\ &\quad - Q_i B_\ell^{-1} \sum_{j \in \Omega} \frac{P_j}{k_{\ell,j}} \text{KI}_n(a_{\ell,j}) + Q_i B_\ell^{-1} \sum_{j \notin B} \frac{P_j}{k_{\ell+1,j}} \text{KI}_n(b_{\ell,j}) \\ &\quad + Q_i B_\ell^{-1} \sum_{j \in B} \frac{P_j}{k_{\ell+1,j}} \left(C_n^{b_{\ell,j}} + Q(b_{\ell,j}) \sum_{u \in \Omega} \frac{P_u}{k_{\ell,u}} \text{KI}_n(a_{\ell,u}) \right) \\ &= \sum_{j \in \Omega} \left(\frac{P_j}{k_{i,j}} C_n^{a_{i,j}} - \frac{P_j}{k_{i+1,j}} C_n^{b_{i,j}} \right) + Q_i B_\ell^{-1} \sum_{j \in \Omega} \frac{P_j}{k_{\ell+1,j}} C_n^{b_{\ell,j}}. \end{aligned}$$

For $\hat{\mu}_{n,i}$ we get by combining (27) and (31) that

$$\begin{aligned} \hat{\mu}_{n,i} &= \sum_{j \in \Omega} \left(\frac{P_j}{k_{i,j}} C_n^{a_{i,j}} + \frac{P_j}{k_{i+1,j}} C_n^{b_{i,j}} \right) + Q_i \sum_{j \notin B} \frac{P_j}{k_{\ell+1,j}} \text{KI}_n(b_{\ell,j}) \\ &\quad + Q_i B_\ell^{-1} \sum_{j \in \Omega} \frac{P_j}{k_{\ell+1,j}} C_n^{b_{\ell,j}} - Q_i \sum_{j \notin B} \frac{P_j}{k_{\ell+1,j}} C_n^{b_{\ell,j}} = \mu_{n,i} - Q_i B_\ell^{-1} \mu_{n,\ell}. \end{aligned}$$

One can now easily check that if $\gamma = (\gamma_1, \dots, \gamma_{N-1})^\top$ is a solution of $M\gamma = 0$, then the vector $\hat{\gamma} = (\hat{\gamma}_1, \dots, \hat{\gamma}_{N-1})^\top$ given by

$$\hat{\gamma}_\ell = \gamma_\ell + \sum_{i=1}^{N-1} \frac{Q_i}{B_\ell - Q_\ell} \gamma_i, \tag{32}$$

and $\hat{\gamma}_i = \gamma_i$ if $i \neq \ell$, satisfies $\hat{M}\hat{\gamma} = 0$. The fact that $B_\ell - Q_\ell \neq 0$ follows in the same way as that $B_\ell \neq 0$. Hence, there is a one-to-one relation between the solutions γ of $M\gamma = 0$ and $\hat{\gamma}$ of $\hat{M}\hat{\gamma} = 0$.

It remains to prove that the functions h_γ and $\hat{h}_{\hat{\gamma}}$ coincide. For that we need to consider the functions L_γ . As we did for KI_n , let L^γ denote the parts that L_γ and \hat{L}_γ have in common, that is, set

$$L^\gamma = \sum_{t \geq 0} \sum_{\omega \in \Omega'_y \cup \Omega'_t \setminus \Omega_y} \delta_\omega(y, t) \mathbf{1}_{[0, T_\omega(y))}.$$

Set $A := \{j \in \Omega : \Omega_{a_{\ell,j}} \neq \emptyset\}$. Then

$$\begin{aligned} L_y &= L^y + Q(y) \sum_{t \geq 1} \sum_{\omega \in \Omega^t} \delta_\omega(z_\ell, t) \mathbf{1}_{[0, \hat{T}_\omega(z_\ell)]} \\ &= L^y + Q(y) \left(\sum_{j \in \Omega} \mathbf{1}_{[0, a_{\ell,j}]} + \sum_{t \geq 1} \sum_{\omega \in \Omega^t} \frac{p_j}{k_{\ell,j}} \delta_\omega(b_{\ell,j}, u) \mathbf{1}_{[0, \hat{T}_\omega(a_{\ell,j})]} \right) \\ &= L^y + Q(y) \sum_{j \notin A} \frac{p_j}{k_{\ell,j}} L_{a_{\ell,j}} + Q(y) \sum_{j \in A} \frac{p_j}{k_{\ell,j}} L_{a_{\ell,j}}. \end{aligned}$$

By Cramer’s rule we obtain for each $j \in A$, that (compare (31))

$$\sum_{j \in A} \frac{p_j}{k_{\ell,j}} L_{a_{\ell,j}} = (B_\ell - Q_\ell)^{-1} \sum_{j \in \Omega} \frac{p_j}{k_{\ell,j}} L^{a_{\ell,j}} - \sum_{j \notin A} \frac{p_j}{k_{\ell,j}} L_{a_{\ell,j}}. \tag{33}$$

Similarly, we obtain that

$$\hat{L}_y = L^y + Q(y) \sum_{j \notin B} \frac{p_j}{k_{\ell+1,j}} L_{b_{\ell,j}} + Q(y) \sum_{j \in B} \frac{p_j}{k_{\ell+1,j}} \hat{L}_{b_{\ell,j}} \tag{34}$$

and

$$\sum_{j \in B} \frac{p_j}{k_{\ell+1,j}} \hat{L}_{b_{\ell,j}} = B_\ell^{-1} \sum_{j \in \Omega} \frac{p_j}{k_{\ell+1,j}} L^{b_{\ell,j}} - \sum_{j \notin B} \frac{p_j}{k_{\ell+1,j}} L^{b_{\ell,j}}. \tag{35}$$

To prove that $h_\gamma = \hat{h}_\gamma$, note that, on the one hand,

$$h_\gamma = \sum_{m=1}^{N-1} \gamma_m \sum_{j \in \Omega} \left(\frac{p_j}{k_{m,j}} L^{a_{m,j}} - \frac{p_j}{k_{m+1,j}} L^{b_{m,j}} \right) + \sum_{m=1}^{N-1} \gamma_m Q_m \sum_{j \in \Omega} \frac{p_j}{k_{\ell,j}} L_{a_{\ell,j}}.$$

On the other hand, using equations (32), (34) and (35), we obtain for \hat{h}_γ that

$$\begin{aligned} \hat{h}_\gamma &= \sum_{m=1}^{N-1} \gamma_m \sum_{s \in \Omega} \left(\frac{p_s}{k_{m,s}} L^{a_{m,s}} - \frac{p_s}{k_{m+1,s}} L^{b_{m,s}} \right) + \sum_{m=1}^{N-1} \gamma_m Q_m \left(1 + \frac{Q_\ell}{B_\ell - Q_\ell} \right) \sum_{s \in \Omega} \frac{p_s}{k_{\ell+1,s}} \hat{L}_{b_{\ell,s}} \\ &\quad + \sum_{m=1}^{N-1} \gamma_m \frac{Q_m}{B_\ell - Q_\ell} \sum_{s \in \Omega} \left(\frac{p_s}{k_{\ell,s}} L^{a_{\ell,s}} - \frac{p_s}{k_{\ell+1,s}} L^{b_{\ell,s}} \right) \\ &= \sum_{m=1}^{N-1} \gamma_m \sum_{s \in \Omega} \left(\frac{p_s}{k_{m,s}} L^{a_{m,s}} - \frac{p_s}{k_{m+1,s}} L^{b_{m,s}} \right) + \sum_{m=1}^{N-1} \gamma_m Q_m \frac{B_\ell}{B_\ell - Q_\ell} B_\ell^{-1} \sum_{s \in \Omega} \frac{p_s}{k_{\ell+1,s}} L^{b_{\ell,s}} \\ &\quad + \sum_{m=1}^{N-1} \gamma_m \frac{Q_m}{B_\ell - Q_\ell} \sum_{s \in \Omega} \left(\frac{p_s}{k_{\ell,s}} L^{a_{\ell,s}} - \frac{p_s}{k_{\ell+1,s}} L^{b_{\ell,s}} \right) \\ &= \sum_{m=1}^{N-1} \gamma_m \sum_{s \in \Omega} \left(\frac{p_s}{k_{m,s}} L^{a_{m,s}} - \frac{p_s}{k_{m+1,s}} L^{b_{m,s}} \right) + \sum_{m=1}^{N-1} \gamma_m \frac{Q_m}{B_\ell - Q_\ell} \sum_{s \in \Omega} \frac{p_s}{k_{\ell,s}} L^{a_{\ell,s}}. \end{aligned}$$

By (33) this implies that $h_\gamma = \hat{h}_\gamma$.

If the partitions $\{I_n\}_{1 \leq n \leq N}$ and $\{\hat{I}_n\}_{1 \leq n \leq N}$ differ in more than one partition point z_ℓ , we can obtain the results from the above by changing one partition point at a time. \square

The next lemma states that adding extra points to the set z_0, \dots, z_N does not influence the set of densities obtained from Theorem 4.1. This lemma is one of the ingredients of the proof of Theorem 5.3 below.

LEMMA 5.2. *Let T be a random system with partition $\{I_i\}_{1 \leq i \leq N}$ and corresponding partition points z_0, \dots, z_N . Consider a refinement of the partition, given by adding extra points $z_1^\dagger, \dots, z_s^\dagger$, for some $s \in \mathbb{N}$. Let T^\dagger be the corresponding random system, that is, $T^\dagger(x) = T(x)$ for all $x \in [0, 1]$, and let M^\dagger be the fundamental matrix of T^\dagger . There is a one-to-one correspondence between the solutions γ of $M\gamma = 0$ and the solutions γ^\dagger of $M^\dagger\gamma^\dagger = 0$. Moreover, the functions h_γ and h_{γ^\dagger} coincide.*

Proof. Let $Z^\dagger := \{z_1^\dagger, \dots, z_s^\dagger\}$. By introducing these extra points the fundamental matrix M^\dagger of T^\dagger becomes an $(N + s) \times (N + s - 1)$ matrix. It is possible to construct this matrix from M in s ,

$$M \rightarrow M_1^\dagger \rightarrow M_2^\dagger \rightarrow \dots \rightarrow M_s^\dagger = M^\dagger,$$

by adding one of the points from Z^\dagger to the partition of T at a time. All of these steps work in exactly the same way, so it is enough to prove the result for $s = 1$. Therefore, assume $Z^\dagger = \{z^\dagger\}$. There is an $1 \leq i \leq N$ such that z^\dagger splits the interval I_i into two subintervals, say I_i^L and I_i^R . By Proposition 5.1, it is irrelevant whether $z^\dagger \in I_i^L$ or $z^\dagger \in I_i^R$. By construction, z^\dagger is a continuity point of $T^\dagger = T$, so

$$a_{i,j}^\dagger = b_{i,j}^\dagger = k_{i,j}z^\dagger + d_{i,j},$$

and for each n we have

$$\sum_{j \in \Omega} \left[\frac{p_j}{k_{i,j}} \text{KI}_n(a_{i,j}^\dagger) - \frac{p_j}{k_{i,j}} \text{KI}_n(b_{i,j}^\dagger) \right] = 0.$$

Therefore M^\dagger has, with respect to M , an extra column at the i th position, whose entries are all zeros except for the diagonal and subdiagonal entries, which are given by $\sum_{j \in \Omega} (p_j/k_{i,j})$ and $-\sum_{j \in \Omega} (p_j/k_{i,j})$, respectively. Moreover, the i th and $(i + 1)$ th rows of M^\dagger are obtained by splitting the i th row of M into two, such that $\text{KI}_i(a_{n,j}) = \text{KI}_i^\dagger(a_{n,j}) + \text{KI}_{i+1}^\dagger(a_{n,j})$ for all n , and analogously for $b_{n,j}$.

The null space of M^\dagger equals the null space of the $(N + 1) \times N$ matrix A obtained from M^\dagger by replacing the $(i + 1)$ th row by the sum of the i th and $(i + 1)$ th rows. Then all the entries of the i th column of A are 0 except for the diagonal entry, and the matrix M appears as a submatrix of A , by deleting the i th column and the i th row. Hence, any solution γ of $M\gamma = 0$ can be transformed into a solution γ^\dagger of $M^\dagger\gamma^\dagger = 0$ by setting $\gamma_j^\dagger = \gamma_j$ for $j \neq i$ and by using the relation $\sum_{j=1}^N A_{i,j}\gamma_j^\dagger = 0$ for γ_i^\dagger . This gives the first part of the lemma.

Finally, for corresponding solutions γ and γ^\dagger the associated densities h_γ and h_{γ^\dagger} coincide, since

$$\sum_{j \in \Omega} \left[\frac{p_j}{k_{i,j}} L_{a_{i,j}^\dagger}(x) - \frac{p_j}{k_{i,j}} L_{b_{i,j}^\dagger}(x) \right] = 0. \quad \square$$

The next theorem says that in the case where all maps T_j are expanding, Theorem 4.1 in fact produces all absolutely continuous invariant measures for the system T .

THEOREM 5.3. *Let $\Omega \subseteq \mathbb{N}$ and let T be a random piecewise linear system satisfying assumptions (A1), (A3), (A4) and (A5). Furthermore, assume that $|k_{i,j}| > 1$ for each $j \in \Omega$ and $1 \leq i \leq N$. An $L^1(\lambda)$ -function h is an invariant function for the random system T if and only if $h = h_\gamma$ for some solution γ of the system $M\gamma = 0$.*

An essential ingredient in the proof of this theorem is the extension of a result by Boyarksy, Góra and Islam from [GBI06] given in the next lemma. [GBI06, Theorem 3.6] states that if we have a random system consisting of two maps that are both expanding, the supports of the invariant densities of T are a finite union of intervals. As the next lemma shows, this result in fact goes through for any finite or countable number of maps with only a small change in the proof. In the case of piecewise linear maps, some small steps can be slightly simplified. We have included the proof for the convenience of the reader.

LEMMA 5.4. (cf. Lemma 3.4 and Theorem 3.6 from [GBI06]) *Let $\Omega \subseteq \mathbb{N}$ and let T be a random system of piecewise linear maps satisfying (A1) and such that for each $j \in \Omega$ the map T_j is expanding, that is, it satisfies $|k_{i,j}| > 1$ for all $1 \leq i \leq N$. If h is a T -invariant density, then the support of h is a finite union of open intervals.*

Proof. Let $H = \{v_1, \dots, v_r\}$ be the base of the subspace of $L^1(\lambda)$ of T -invariant functions, consisting of density functions of bounded variation, mentioned in §2. Since any invariant function h for T can be written as $h = \sum_{n=1}^r c_n v_n$ for some constants $c_n \in \mathbb{R}$, it is enough to prove the result for elements in H . Therefore, let $h \in H$ and let $U := \text{supp}(h)$ denote the support of h . Since h is a function of bounded variation, we can take h to be lower semicontinuous and U can be written as a countable union of open intervals, each separated by an interval of positive length: $U = \bigcup_{k \geq 1} U_k$. Assume without loss of generality that $\lambda(U_{k+1}) \leq \lambda(U_k)$ for each $k \geq 1$. Let $Z := \{z_1, \dots, z_{N-1}\}$ and let \mathcal{D} be the set of indices k , such that U_k contains one of the points $z \in Z$, that is,

$$\mathcal{D} = \{k \geq 1 \mid \exists z \in Z : z \in U_k\}.$$

We first show that $\mathcal{D} \neq \emptyset$ by proving that $Z \cap U_1 \neq \emptyset$. Suppose to the contrary that U_1 does not contain a point z . Then for each $j \in \Omega$, $T_j(U_1)$ is an interval and since each T_j is expanding, we have $\lambda(T_j(U_1)) > \lambda(U_1)$. By the property from (3) that U is forward invariant, we know that $T_j(U_1) \subseteq U$ for each j , so it must be contained in one of the intervals U_k . This gives a contradiction.

Now, let J be the smallest interval in the set

$$\{U_k \cap I_n : k \in \mathcal{D}, 1 \leq n \leq N\}.$$

Note that this is a finite set, since Z and \mathcal{D} are both finite. Moreover, by the above this set is not empty, so J exists. Since each U_k is an open interval, we have $\lambda(J) > 0$. Let $\mathcal{F} = \{k \geq 1 : \lambda(U_k) \geq \lambda(J)\}$, where k is not necessarily in J , and let $S = \bigcup_{k \in \mathcal{F}} U_k$. Since any connected component U_k of S has Lebesgue measure bigger than $\lambda(J)$, S is a finite union of open intervals. We first prove that $T_j(S) \subseteq S$ for any $j \in \Omega$. Let $U_k \subseteq S$ and suppose

first that $k \notin \mathcal{D}$. Then, for each $j \in \Omega$, as above $T_j(U_k)$ is an interval with $\lambda(T_j(U_k)) > \lambda(U_k) \geq \lambda(J)$. So, $T_j(U_k)$ is contained in another interval U_i that satisfies $\lambda(U_i) > \lambda(J)$ and thus satisfies $U_i \subseteq S$. Hence, $T_j(U_k) \subseteq S$. If, on the other hand, $k \in \mathcal{D}$, then $T_j(U_k)$ consists of a finite union of intervals and since T_j is expanding, the Lebesgue measure of each of these intervals exceeds $\lambda(J)$. Hence, each of the connected components of $T_j(U_k)$ is contained in some interval U_i that satisfies $\lambda(U_i) > \lambda(J)$ and therefore $U_i \subseteq S$. Hence, also in this case $T_j(U_k) \subseteq S$, implying that $T_j(S) \subseteq S$ for all $j \in \Omega$.

Obviously, $S \subseteq U$. Using the fact that $T_j(S) \subseteq S$ for all $j \in \Omega$, we will now show that $U \subseteq S$. Suppose this is not the case and let U_s be the largest interval in $U \setminus S$. Since $U_k \subseteq S$ for any $k \in \mathcal{D}$, we have $s \notin \mathcal{D}$. So, again, for each $j \in \Omega$ the set $T_j(U_s)$ is an interval with $\lambda(T_j(U_s)) > \lambda(U_s)$ and hence, $T_j(U_s) \subseteq S$. Thus $U_s \subseteq T_j^{-1}(S)$ and since $U_s \not\subseteq S$, we have $U_s \subseteq T_j^{-1}(S) \setminus S$. Let $\mu_{\mathbf{p}}$ be the absolutely continuous T -invariant measure with density h . We show that $\mu_{\mathbf{p}}(T_j^{-1}(S) \setminus S) = 0$. Since for each $j \in \Omega$ we have

$$S \subseteq T_j^{-1}(T_j(S)) \subseteq T_j^{-1}(S),$$

we obtain from (1) that

$$\begin{aligned} 0 &= \mu_{\mathbf{p}}(S) - \mu_{\mathbf{p}}(S) = \sum_{j \in \Omega} p_j \mu_{\mathbf{p}}(T_j^{-1}(S)) - \sum_{j \in \Omega} p_j \mu_{\mathbf{p}}(S) \\ &= \sum_{j \in \Omega} p_j (\mu_{\mathbf{p}}(T_j^{-1}(S)) - \mu_{\mathbf{p}}(S)) = \sum_{j \in \Omega} p_j \mu_{\mathbf{p}}(T_j^{-1}(S) \setminus S). \end{aligned}$$

Since $p_j > 0$ for all j , we have that $\mu_{\mathbf{p}}(T_j^{-1}(S) \setminus S) = 0$ for each j . Hence, $\mu_{\mathbf{p}}(U_s) = 0$, which contradicts the fact that $U_s \subseteq U$. □

Remark 5.5. The paper [GBI06] contains an example that shows that the previous lemma is not necessarily true if we drop the assumption that all maps T_j are expanding. In [GBI06, Example 3.7] the authors describe a random system T using an expanding and a non-expanding map, of which for a certain probability vector \mathbf{p} the support of the invariant density is a countable union of intervals. The fact that the supports of the elements from H are finite unions of open intervals plays an essential role in the proof of Theorem 5.3, as we will now show.

Proof of Theorem 5.3. We will show that the linear mapping from the null space of M to the subspace of $L^1(\lambda)$ of all T -invariant functions is a linear isomorphism. Let $H = \{v_1, \dots, v_r\}$ again be the basis of density functions of bounded variation, whose corresponding measures are ergodic, for the subspace of T -invariant $L^1(\lambda)$ -functions mentioned in §2. Recall that any invariant function h for T can be written as $h = \sum_{n=1}^r c_n v_n$ for some constants $c_n \in \mathbb{R}$.

The injectivity follows from the proof of Theorem 4.1, where we showed that $h_{\gamma} = 0$ implies $\gamma = 0$. We prove surjectivity by providing for each $h \in H$ a vector γ such that $h_{\gamma} = h$. We will do this by altering T in several steps (see Figure 2), so that we finally obtain a system T_U that has a vector γ_U associated to it for which the corresponding density $h_{\gamma_U}^U$ vanishes outside the support U of h . Then, using Proposition 5.1 and Lemma 5.2, we transform the solution γ_U to a solution γ for T that produces the original density h .

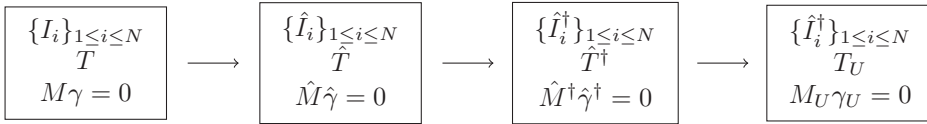


FIGURE 2. The steps we take in transforming T to T_U .

Fix $h \in H$, and let $U := \text{supp}(h)$. Let $Z = \{z_1, \dots, z_{N-1}\}$ again be the set of critical points of the system. Following [Kop90, Theorem 2], we classify the points in Z as follows:

- $Z_1 := \{z_i \in Z \mid z_i \text{ is in the interior of } U\}$,
- $Z_2 := \{z_i \in Z \mid z_i \text{ is a left (right) endpoint of a subinterval of } U \text{ and } z_i \in I_{i+1} (z_i \in I_i)\}$,
- $Z_3 := \{z_i \in Z \mid z_i \text{ is a left (right) endpoint of a subinterval of } U \text{ and } z_i \in I_i (z_i \in I_{i+1})\}$,
- $Z_4 := \{z_i \in Z \mid z_i \text{ is an exterior point for } U\}$.

We now modify the partition $\{I_i\}_{1 \leq i \leq N}$ on the points in Z_3 , so that it corresponds better to the set U . Let $\{\hat{I}_i\}_{1 \leq i \leq N}$ be a partition of $[0, 1]$ given by z_0, \dots, z_N and differing from $\{I_i\}_{1 \leq i \leq N}$ only for $z_i \in Z_3$, that is, $z_i \in \hat{I}_i$ if and only if $z_i \notin I_i$. Let \hat{T} be the corresponding random system, that is, $\hat{T}(x) = T(x)$ for all $x \notin Z_3$. By Proposition 5.1, the corresponding matrices M and \hat{M} have vectors in their null spaces that differ only on the entries i for which $z_i \in Z_3$, but such that they define the same density.

There might be boundary points of U that are not in Z . Let Z^\dagger be the set of such points. From Lemma 5.4 it follows that U is a finite union of open intervals, so the set Z^\dagger is finite. Consider the partition $\{\hat{I}_i^\dagger\}$ given by the points in $Z \cup Z^\dagger$ and let \hat{T}^\dagger be the system with this partition and given by $\hat{T}^\dagger(x) = \hat{T}(x)$ for all x . By Lemma 5.2, the corresponding matrices \hat{M} and \hat{M}^\dagger have vectors in their null spaces that differ only on the extra entries corresponding to points $z^\dagger \in Z^\dagger$, but such that they define the same density.

Define a new piecewise linear random system T_U by modifying \hat{T}^\dagger outside of U . To be more precise, we let $T_U(x) = \hat{T}^\dagger(x)$ for all $x \in U$ and on each connected component of $[0, 1] \setminus U$ we assume all maps $T_{U,j}$ to be equal and onto, that is, mapping the interval onto $[0, 1]$. Recall from (3) that the set U is forward invariant under T . Then any invariant function of T_U vanishes on $[0, 1] \setminus U$ λ -a.e., since the set of points $x \in [0, 1] \setminus U$, such that $T^n(x) \in [0, 1] \setminus U$ for all $n \geq 0$ is a self-similar set of Hausdorff dimension less than 1. From Theorem 4.1 we get a non-trivial solution γ_U of $M_U\gamma_U = 0$ with a corresponding function h_U that vanishes on $[0, 1] \setminus U$. Since \hat{T} and T_U coincide on U , the function h_U is also invariant for \hat{T} and hence for T . From the fact that U is the support of one of the densities in the basis H and $\text{supp}(h_U) \subseteq U$, we then conclude that $h_U = h$, up to possibly a set of Lebesgue measure 0.

It remains to show that γ_U can be transformed into a vector from the null space of M , leading to the same density h_U . We first show that $\hat{M}^\dagger\gamma_U = 0$. Note that for $z_i \in Z_4$, since h_U is of bounded variation,

$$\lim_{x \uparrow z_i} h_U(x) = 0 = \lim_{x \downarrow z_i} h_U(x).$$

Hence, by the calculations in (25), $\gamma_{U,i} = 0$. Similarly, for $z_i \in Z_2 \cup Z_3$ we have that either $\lim_{x \uparrow z_i} h_U(x) = 0$ or $\lim_{x \downarrow z_i} h_U(x) = 0$, which again by the calculations in (25) gives $\gamma_{U,i} = 0$. Hence, $\gamma_{U,i} = 0$ for each i such that $z_i \in Z_2 \cup Z_3 \cup Z_4$. Similarly, $\gamma_{U,i} = 0$ for each i such that $z_i \in Z^\dagger$. In the multiplication $\hat{M}^\dagger \gamma_U$ the orbits of the points $a_{i,j}$ and $b_{i,j}$ which are different under \hat{T}^\dagger and T_U are multiplied by 0. Since U is forward invariant, all orbits of points $a_{i,j}$ and $b_{i,j}$ corresponding to i such that $z_i \in Z_1$ will stay in U and will thus be equal under \hat{T}^\dagger and T_U . These facts imply that also $\hat{M}^\dagger \gamma_U = 0$ and that the corresponding invariant density for \hat{T}^\dagger is again h_U .

From Lemma 5.2 it follows that there is a vector $\hat{\gamma}$ in the null space of \hat{M} with $\hat{h}_{\hat{\gamma}} = h_U$. Finally, Proposition 5.1 then tells us how we can modify $\hat{\gamma}$ to get a vector γ in the null space of M with $h_\gamma = \hat{h}_{\hat{\gamma}} = h_U = h$. □

6. Examples

In this section we apply Theorems 4.1 and 5.3 to various examples.

6.1. *Random tent maps.* For any countable set of slopes $\{k_j\}_{j \in \Omega}$ with $k_j \in (0, 2)$ for each j , consider the family $T := \{T_j\}_{j \in \Omega}$, where each T_j is a tent map of slope k_j , that is, $T_j : [0, 1] \rightarrow [0, 1]$ is given by

$$T_j(x) = \begin{cases} k_j x & \text{if } x \in [0, 1/2], \\ k_j - k_j x & \text{if } x \in (1/2, 1] \end{cases}$$

(see Figure 3(a)). So, (A1) and (A4) hold.

Let $\mathbf{p} = (p_j)_{j \geq 0}$ be a probability vector such that T is expanding on average (i.e. $\sum_{j \in \mathbb{N}} (p_j/k_j) < 1$), so (A2) holds. One easily verifies that then conditions (A3) and (A5) hold as well. For $N = 2$ set

$$z_0 = 0, \quad z_1 = \frac{1}{2}, \quad z_2 = 1,$$

and $I_1 = [z_0, z_1]$, $I_2 = [z_1, z_2]$. Since z_1 is the only critical point, the fundamental matrix M is the null vector. As a consequence, we can choose $\gamma = 1$, to obtain the invariant density

$$h_\gamma = c \sum_{j \in \Omega} \frac{2p_j}{k_j} L_{k_j/2},$$

for some normalizing constant c . If, for each $j \in \mathbb{N}$ and $w \in \Omega^t$, $t \geq 0$, we set

$$\ell_{\omega,j} = \#\left\{1 \leq n \leq t : T_{\omega_1^{n-1}}\left(\frac{k_j}{2}\right) \in \left(\frac{1}{2}, 1\right]\right\},$$

then this becomes

$$h_\gamma = c \sum_{j \in \Omega} \frac{2p_j}{k_j} \sum_{t \geq 0} \sum_{\omega \in \Omega^t} (-1)^{\ell_{\omega,j}} \prod_{n=0}^t \frac{p_{\omega_n}}{k_{\omega_n}} \mathbf{1}_{(0, T_\omega(k_j/2))}. \tag{36}$$

If we assume that $k_j > 1$ for all j , then it follows from Theorem 5.3 that the density from (36) is the unique invariant density for (T, \mathbf{p}) . If we do not assume this, then we can still

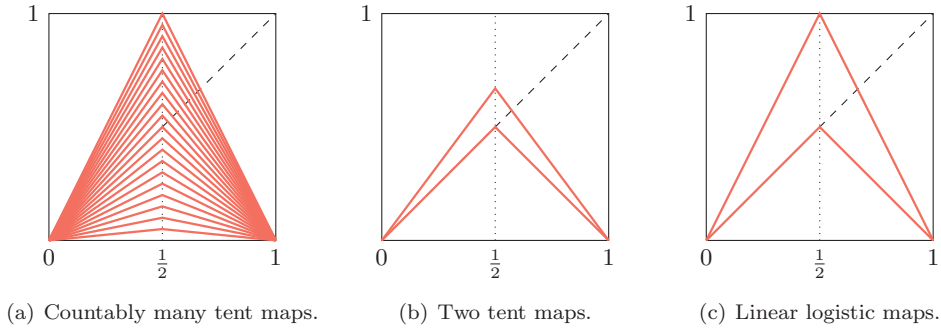


FIGURE 3. Random families of tent maps.

draw the same conclusion if there are only finitely many maps. Namely, to satisfy condition (A2) there has to be at least one j such that $k_j > 1$. The existence and uniqueness of an absolutely continuous invariant measure for the map T_j are then guaranteed by the results from [LY73, LY78]. If the set $\{k_j\}_{j \in \mathbb{N}}$ is finite, it then follows from [Pel84, Corollary 7] that there is only one invariant density for (T, \mathbf{p}) .

In [AGH18] the authors considered random combinations of logistic maps. In [AGH18, Theorem 4.2] they proved that the random system $\{f_0, f_1\}$ with $f_0(x) = 2x(1 - x)$ and $f_1(x) = 4x(1 - x)$ has a σ -finite absolutely continuous invariant measure that is infinite if the map f_0 is chosen with probability $p_0 > \frac{1}{2}$. The linear analogue of this system paints a different picture. Fix $a \in (1, 2]$ and consider the random system with two maps $T_0(x) = \min\{x, 1 - x\}$ and $T_{a,1}(x) = \min\{ax, a - ax\}$. See Figure 3(b) for an example with $a = \frac{4}{3}$. For any $p \in (0, 1)$, set $p_0 = p$ and $p_1 = 1 - p$ and note that $p_0 + p_1/a < 1$. Assumptions (A1)–(A5) are then met and the random system $T = \{T_0, T_{a,1}\}$ has a finite absolutely continuous invariant measure for any such p . A straightforward computation yields $L_{1/2} = (1/(1 - p))\mathbf{1}_{[0,1/2)} + (1/a)L_{a/2}$, so that up to a normalizing constant, the unique absolutely continuous invariant density is then

$$h_{\gamma,a} = \frac{2p}{1 - p} \mathbf{1}_{[0,1/2)} + \frac{2}{a} L_{a/2}. \tag{37}$$

In particular, for $a = 2$ as shown in Figure 3(c) we get

$$h_{\gamma,2} = (1 + p)\mathbf{1}_{[0,1/2)} + (1 - p)\mathbf{1}_{(1/2,1]}.$$

Note that for $p = 1$ we have a deterministic, non-expanding interval map that does not satisfy the requirements from [Kop90]. However, the limit $\lim_{p \rightarrow 1} h_{\gamma,2} = 2 \cdot \mathbf{1}_{[0,1/2)}$ is an invariant density for the system. On the other hand, for a fixed $p \in (0, 1)$ the limit $\lim_{a \rightarrow 1} h_{\gamma,a}$ is not an absolutely continuous measure. To see this, note that $h_{\gamma,a}$ is determined by the random orbits of $a/2$ and that $1 - a/2 \leq T_\omega(a/2) \leq a/2$ for any ω . Hence, by (37) and the definition of the L -functions in (17), it follows that $h_{\gamma,a} = 0$ on $(a/2, 1]$, while on $[0, 1 - a/2)$ we have $h_{\gamma,a} = v$ on $[0, 1 - a/2)$ for some constant $v \in \mathbb{R}$. For any point in $x \in [0, 1 - (a/2))$, the random Perron–Frobenius operator from (2)

now yields

$$v = h_{\gamma,a}(x) = P_T h_{\gamma,a}(x) = pv + (1 - p)\frac{v}{a},$$

which holds if and only if $v = 0$. It follows that for any $a \in (1, 2]$ and any $p \in (0, 1)$, $\text{supp}(h_{\gamma,a}) \subseteq [1 - a/2, a/2]$. As a consequence $\lim_{a \rightarrow 1} h_{\gamma} = \delta_{1/2}$, where $\delta_{1/2}$ is the Dirac delta function at $\frac{1}{2}$.

6.2. *A random family of W-shaped maps.* Keller introduced in [Kel82] a family of piecewise expanding W -maps to study the phenomenon of instability of absolutely continuous invariant measures. Later the stability of W -shaped maps was studied in other papers as well; see, for example, [LGB+13, EM12]. Here we construct a random family of W -shaped maps, where each element of the collection is an expanding on average random map $W_a := \{W_{a,0}, W_{a,1}\}$ defined on the unit interval. We give an absolutely continuous invariant probability measure.

For $a > 2$, let $\Omega = \{0, 1\}$ and $N = 4$. Set

$$z_0 = 0, \quad z_1 = 1/a, \quad z_2 = 1/2, \quad z_3 = (a - 1)/a, \quad z_4 = 1$$

and

$$I_1 = [z_0, z_1], \quad I_2 = (z_1, z_2], \quad I_3 = (z_2, z_3), \quad I_4 = [z_3, z_4].$$

Let

$$W_{a,0}(x) = \begin{cases} 1 - ax & \text{if } x \in I_1, \\ \frac{2}{a-2}x - \frac{2}{(a-2)a} & \text{if } x \in I_2, \\ W_{a,0}(1-x) & \text{otherwise,} \end{cases}$$

and

$$W_{a,1}(x) = \begin{cases} 1 - ax & \text{if } x \in I_1, \\ \frac{2(a-1)}{a-2}x - \frac{2(a-1)}{(a-2)a} & \text{if } x \in I_2, \\ W_{a,1}(1-x) & \text{otherwise.} \end{cases}$$

See Figure 4(a), for some examples of W_a for different values of a .

For $a > 4$ the map $W_{a,0}$ presents two contractive branches. Let $1 > p > ((a - 4)(a - 1))/(a - 2)^2$ be arbitrary, and let $p_{a,0} = 1 - p$ and $p_{a,1} = p$. With this choice of probability vector the random map W_a satisfies (A1)–(A5). The fundamental matrix M is given by

$$M = \begin{pmatrix} \frac{1-a}{a^2} - \frac{C}{a} & \frac{p_{a0}(2-a)(a-1)}{a^2} + \frac{p_{a1}(2-a)}{a^2(a-1)} & -\frac{C}{a} + \frac{1}{a^2} \\ C & -C & 0 \\ 0 & -C & C \\ \frac{1}{a^2(a-1)} - \frac{C}{a(a-1)} & \frac{p_{a0}(2-a)}{a^2(a-1)} - \frac{p_{a1}(2-a)(a^2-a-1)}{a^2(a-1)^2} & -\frac{C}{a(a-1)} + \frac{1+a-a^2}{a^2(a-1)} \end{pmatrix}$$

for some constant C . Its null space consists of all vectors of the form

$$s \begin{pmatrix} 1 & 1 & 1 \end{pmatrix}^T, \quad s \in \mathbb{R}.$$

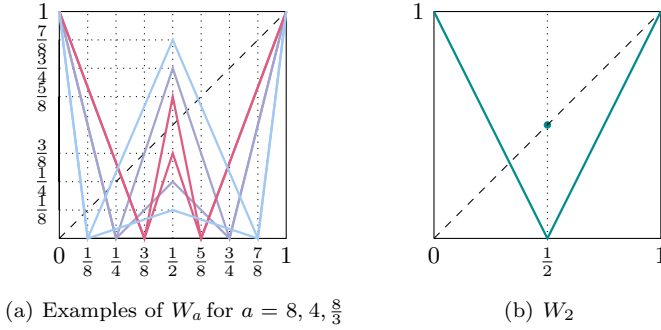


FIGURE 4. Examples of random systems W_a for various values of a .

From

$$L_0 = \frac{1}{1-a}, \quad L_{1/a} = \frac{1}{a(a-1)} + \mathbf{1}_{[0,1/a]} \quad \text{and} \quad L_{(a-1)/a} = -\frac{1}{a(a-1)} + \mathbf{1}_{[0,(a-1)/a]},$$

we get the invariant density

$$h_{a,p} = c \left[((a-1) - p(a-2)) \cdot \mathbf{1}_{[0,1/a]} + \mathbf{1}_{[1/a,(a-1)/a]} + \left(1 - p \frac{a-2}{a-1} \right) \cdot \mathbf{1}_{((a-1)/a,1]} \right],$$

for the normalizing constant

$$c = \frac{a(a-1)}{2(a-1)^2 - pa(a-2)}.$$

Theorem 5.3 implies that if $a < 4$, then this is the unique absolutely continuous invariant density for W_a . Note that

$$\lim_{a \rightarrow 2} h_{a,p}(x) = \frac{1}{2} \mathbf{1}_{[0,1]}(x) + \frac{1}{2} \delta_{1/2}(x).$$

On the other hand, for the limit map W_2 shown in Figure 4(b), Lebesgue measure is the only absolutely continuous invariant measure.

6.3. *Random β -transformations.* Let $\beta > 1$ be a non-integer and use $\lfloor \beta \rfloor$ to denote the largest integer not exceeding β . A β -expansion of a real number $x \in [0, \lfloor \beta \rfloor / (\beta - 1)]$ is an expression of the form $x = \sum_{n=1}^{\infty} b_n \beta^{-n}$, where $b_n \in \{0, 1, \dots, \lfloor \beta \rfloor\}$ for all $n \geq 1$. The properties of β -expansions have been thoroughly studied. One of the more striking results is that Lebesgue almost all $x \in [0, \lfloor \beta \rfloor / (\beta - 1)]$ have uncountably many different β -expansions (see [EJK90, Sid03, DdV07]). In [DK03] Dajani and Kraaikamp introduced a random system that produces for each $x \in [0, \lfloor \beta \rfloor / (\beta - 1)]$ all its possible β -expansions. We will define this system for $1 < \beta < 2$ for simplicity, but everything easily extends to $\beta > 2$. Set

$$z_0 = 0, \quad z_1 = \frac{1}{\beta}, \quad z_2 = \frac{1}{\beta(\beta-1)}, \quad z_3 = \frac{1}{\beta-1},$$

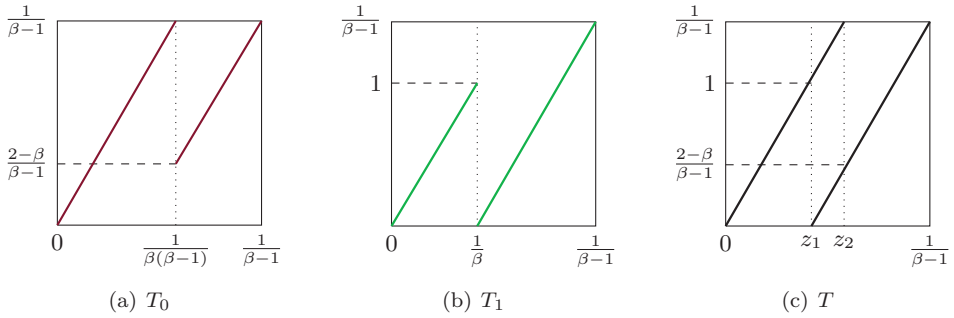


FIGURE 5. In (a) we see the lazy β -transformation T_0 , in (b) the greedy β -transformation T_1 and in (c) we see them combined. Whether or not $1 > (2 - \beta)/(\beta - 1)$ depends on the chosen value of β .

and let

$$T_0(x) = \begin{cases} \beta x & \text{if } x \in [z_0, z_2], \\ \beta x - 1 & \text{if } x \in (z_2, z_3], \end{cases} \quad \text{and} \quad T_1(x) = \begin{cases} \beta x & \text{if } x \in [0, z_1], \\ \beta x - 1 & \text{if } x \in [z_1, z_3] \end{cases}$$

(see Figure 5). The map T_0 is called the *lazy β -transformation* and the map T_1 is the *greedy β -transformation*. We do not bother to rescale the system to the unit interval $[0, 1]$, since this has no effect on the computations.

One of the reasons why people are interested in the random β -transformation is for its relation to the infinite Bernoulli convolution; see [DdV05, DK13, Kem14]. The density of the absolutely continuous invariant measures has been the subject of several papers. For a special class of values β an explicit expression for the density of $\mu_{\mathbf{p}}$ was found in [DdV07] using a Markov chain. In [Kem14] Kempton produced an explicit formula for the invariant density for all $1 < \beta < 2$ when $p_0 = p_1 = \frac{1}{2}$ by constructing a natural extension of the system. He states that there is a straightforward extension of this method to $\beta > 2$. Recently Suzuki obtained a formula for the density of $\mu_{\mathbf{p}}$ for all $\beta > 1$ and any \mathbf{p} in [Suz19]. Since the random β -transformation satisfies assumptions (A1)–(A5) for any probability vector $\mathbf{p} = (p_0, p_1)$, we can also obtain the invariant density from Theorem 4.1. To illustrate our method we calculate the density for $\beta \in (1, 2)$ and $p_0 = p_1 = \frac{1}{2}$.

Let $\Omega = \{0, 1\}$, $N = 3$ and set

$$I_1 = [z_0, z_1), \quad I_2 = [z_1, z_2], \quad I_3 = (z_2, z_3].$$

Define the left and right limits at each point of discontinuity:

$$\begin{aligned} a_{1,0} &= 1, & b_{1,0} &= 1, & a_{2,0} &= \frac{1}{\beta - 1}, & b_{2,0} &= \frac{2 - \beta}{\beta - 1}, \\ a_{1,1} &= 1, & b_{1,1} &= 0, & a_{2,1} &= \frac{2 - \beta}{\beta - 1}, & b_{2,1} &= \frac{2 - \beta}{\beta - 1}. \end{aligned}$$

As pointed out in Remark 4.5, to determine γ it would suffice to compute only one row of M , but for the sake of completeness we give M below. Let $KI_n(1) = c_n$. By the symmetry of the system, for each $x \in [z_0, z_3]$ and all $(i, j) \in \{1, 2, 3\} \times \{0, 1\}$,

$$T_{i,j}(z_3 - x) = z_3 - T_{4-i,1-j}(x). \tag{38}$$

If for any $\omega = \omega_1 \cdots \omega_t \in \{0, 1\}^*$, we let $\bar{\omega} \in \{0, 1\}^*$ denote the string $\bar{\omega} = (1 - \omega_1) \cdots (1 - \omega_t)$, then (38) implies that $T_\omega(1) \in I_n$ if and only if $T_{\bar{\omega}}((2 - \beta)/(\beta - 1)) \in I_{4-n}$ and so $\text{KI}_n((2 - \beta)/(\beta - 1)) = c_{4-n}$. We obtain

$$M = \begin{pmatrix} \frac{1}{\beta} + \frac{1}{2\beta} \left(c_1 - \frac{1}{\beta - 1} \right) & -\frac{1}{2\beta} c_3 \\ -\frac{1}{\beta} + \frac{1}{2\beta} c_2 & \frac{1}{\beta} - \frac{1}{2\beta} c_2 \\ \frac{1}{2\beta} c_3 & -\frac{1}{\beta} - \frac{1}{2\beta} \left(c_1 - \frac{1}{\beta - 1} \right) \end{pmatrix}.$$

The null space consists of all vectors of the form

$$s(1 \ 1)^T, \quad s \in \mathbb{R}.$$

From Theorem 5.3 we then know that the system T has a unique invariant density. We obtain

$$h_\gamma = \frac{c}{2\beta} \sum_{t \geq 0} \sum_{\omega \in \{0,1\}^t} \left(\frac{1}{2\beta} \right)^t (\mathbf{1}_{[0, T_\omega(1)]} + \mathbf{1}_{[T_\omega((2-\beta)/(\beta-1)), 1/(\beta-1)]}),$$

for some normalizing constant c . This matches the density found in [Kem14, Theorem 2.1] except for possibly countably many points.

If we set $p_0 \neq \frac{1}{2}$, the computations are less straightforward. Nevertheless, we can obtain a nice closed formula for the density in specific instances. Let $p_0 = p \in [0, 1]$ be arbitrary and consider $\beta = (1 + \sqrt{5})/2$, the golden mean. Then β satisfies $\beta^2 - \beta - 1 = 0$ and the system has the nice property that $T_{2,0}(z_1) = z_2$ and $T_{2,1}(z_2) = z_1$ for $z_1 = 1/\beta$ and $z_2 = 1$. Also note that $1/(\beta - 1) = \beta$. This specific case has also been studied in [DdV07, Example 1]. The resulting matrix M is given by

$$M = \frac{\beta}{\beta^2 - p(1 - p)} \begin{pmatrix} p^2 & -p(1 - p) \\ -p & (1 - p) \\ (1 - p)p & -(1 - p)^2 \end{pmatrix},$$

and its null space consists of all vectors of the form

$$s(1 - p \ p)^T, \quad s \in \mathbb{R}.$$

For the functions L_γ we obtain $L_0 = 0, L_\beta = \beta^2$ and

$$L_{1/\beta} = \frac{p^2 \beta^2}{\beta^2 - p(1 - p)} + \frac{\beta^2}{\beta^2 - p(1 - p)} \mathbf{1}_{[0, 1/\beta]} + \frac{p\beta}{\beta^2 - p(1 - p)} \mathbf{1}_{[0, 1]},$$

$$L_1 = \frac{p\beta^3}{\beta^2 - p(1 - p)} + \frac{(1 - p)\beta}{\beta^2 - p(1 - p)} \mathbf{1}_{[0, 1/\beta]} + \frac{\beta^2}{\beta^2 - p(1 - p)} \mathbf{1}_{[0, 1]}.$$

The unique invariant density turns out to be

$$h_\gamma = \frac{\beta^2}{1 + \beta^2} ((1 - p)\beta \cdot \mathbf{1}_{[0, \beta-1]} + \mathbf{1}_{(\beta-1, 1)} + p\beta \cdot \mathbf{1}_{[1, \beta]}),$$

which for $p = \frac{1}{2}$ corresponds to

$$h_\gamma = \frac{\beta^2}{2(1 + \beta^2)}(\beta \cdot \mathbf{1}_{[0, \beta-1]} + 2 \cdot \mathbf{1}_{(\beta-1, 1)} + \beta \cdot \mathbf{1}_{[1, \beta]}).$$

6.4. *The random (α, β) -transformation.* As an example of a system that is not everywhere expanding, but is expanding on average, we consider a random combination of the greedy β -transformation and the non-expanding (α, β) -transformation introduced in [DHK09]. More specifically, let $0 < \alpha < 1$ and $1 < \beta < 2$ be given and

$$z_0 = 0, \quad z_1 = 1/\beta, \quad z_2 = 1.$$

Define the (α, β) -transformation T_0 on the interval $[0, 1]$ by

$$T_0(x) = \begin{cases} \beta x & \text{if } x \in [0, z_1), \\ \frac{\alpha}{\beta}(\beta x - 1) & \text{if } x \in [z_1, z_2]. \end{cases}$$

Let $T_1 : [0, 1] \rightarrow [0, 1]$ be the greedy β -transformation again, given by $T_1(x) = \beta x \pmod{1}$. For any $0 < p < (\alpha(\beta - 1))/(\beta - \alpha)$ the random system T with probability vector $\mathbf{p} = (p, 1 - p)$ satisfies conditions (A1), (A2), (A3) and (A5). The assumptions on the boundary points from (A4) do not hold, but this is easily solved by adding an extra interval $(z_2, z_3]$ for $z_3 = 1/(\beta - 1)$ and extending T_0 and T_1 to it by setting $T_0(x) = T_1(x) = \beta x - 1$.

This random system T does not satisfy the conditions of Theorem 5.3 and we cannot therefore conclude directly that Theorem 4.1 produces all invariant densities for T . However, the set $\Omega = \{0, 1\}$ is finite and the map T_1 is expanding with $T_1'(x) = \beta > 1$ for all x and therefore T satisfies the conditions from [Pel84, Corollary 7] on the number of ergodic components of the pseudo skew-product R . Since the greedy β -transformation T_1 has a unique absolutely continuous invariant measure, this corollary implies that also the random system T has a unique invariant density. We use Theorem 4.1 to obtain this density.

Let $0 < p < (\alpha(\beta - 1))/(\beta - \alpha)$ be arbitrary and set

$$I_1 = [z_0, z_1), \quad I_2 = [z_1, z_2], \quad I_3 = (z_2, z_3].$$

The left and right limits at each point of discontinuity are given by

$$\begin{aligned} a_{1,0} &= 1, & b_{1,0} &= 0, & a_{2,0} &= \alpha - \alpha/\beta, & b_{2,0} &= \beta - 1, \\ a_{1,1} &= 1, & b_{1,1} &= 0, & a_{2,1} &= \beta - 1, & b_{2,1} &= \beta - 1. \end{aligned}$$

By construction, none of the points in $[0, 1]$ will ever enter the interval I_3 , therefore $\text{KI}_3(y) = 0$ for all $y \in [0, 1]$. As a consequence, the last row of the 3×2 fundamental matrix M is given by $\mu_{3,1} = 0$ and $\mu_{3,2} = -1/\beta$. This fact, together with the fact that we know from Lemma 3.4 that the null space of M is non-trivial, forces the first column of M to be zero, that is, $\mu_{1,1} = \mu_{2,1} = \mu_{3,1} = 0$. Hence, the null space of M consists of all vectors of the form

$$s \begin{pmatrix} 1 & 0 \end{pmatrix}^\top, \quad s \in \mathbb{R},$$

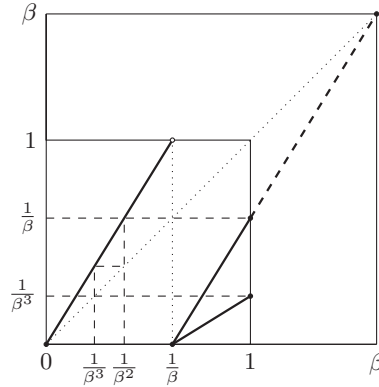


FIGURE 6. The random (α, β) -transformation for $\beta = (1 + \sqrt{5})/2$ and $\alpha = 1/\beta$.

and the unique invariant density of the system T is

$$h_\gamma = \frac{c}{\beta} L_1 = \frac{c}{\beta} \sum_{t \geq 0} \sum_{\omega \in \Omega^t} \delta_\omega(1, t) \mathbf{1}_{[0, T_\omega(1)]},$$

for some normalizing constant c . For our choice of $\beta = (1 + \sqrt{5})/2$ and $\alpha = 1/\beta$ as in Figure 6, we can compute further to get

$$h_\gamma = \frac{\beta^2}{\beta^2 + 1 + 2p} \left(p\beta \mathbf{1}_{[0, 1/\beta^3]} + p \mathbf{1}_{[0, 1/\beta^2]} + \frac{1}{\beta} \mathbf{1}_{[0, 1/\beta]} + \mathbf{1}_{[0, 1]} \right).$$

7. The random Lüroth map with bounded digits

In 1883 Lüroth introduced in [Lür83] a representation of real numbers of the unit interval, as a generalization of the decimal expansion. The standard Lüroth map on $[0, 1]$ is defined by $T_L(0) = 0$ and

$$T_L(x) := n(n - 1)x - (n - 1) \quad \text{if } x \in \left(\frac{1}{n}, \frac{1}{n - 1} \right], n \geq 2.$$

From T_L we can obtain the Lüroth expansion of any number $x \in (0, 1]$ by assigning to it a sequence of positive integers $(l_n)_{n \geq 1}$, where l_n is the unique integer such that $T_L^{n-1}(x) \in ((1/l_n), 1/(l_n - 1)]$. The Lüroth expansion of x is then the expression

$$x = \sum_{n=1}^{\infty} \left((l_n - 1) \prod_{k=1}^n \frac{1}{l_k(l_k - 1)} \right).$$

The map T_L was later generalized in various different ways. In [KKK90] the alternating Lüroth map was introduced as

$$T_A(x) := 1 - T_L(x).$$

This map is essentially a piecewise linear version of the Gauss map $x \mapsto 1/x \pmod{1}$, which can be used to obtain regular continued fraction expansions. This yields for each

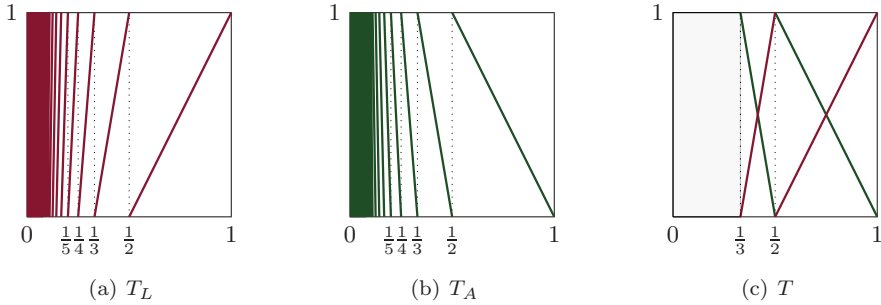


FIGURE 7. In (a) we see the Lüroth map and in (b) the alternating Lüroth map. (c) shows the open random system T consisting of random combinations of T_L and T_A restricted to the interval $[\frac{1}{3}, 1]$.

$x \in [0, 1]$ that is not a pre-image of 0 the alternating Lüroth expansion given by

$$x = \sum_{n=1}^{\infty} \left((-1)^{n+1} a_n \prod_{k=1}^n \frac{1}{a_k(a_k - 1)} \right),$$

where a_n is the unique integer such that $T_A^{n-1}(x) \in (1/a_n, 1/(a_n - 1)]$. Further generalizations and ergodic properties of such maps were studied in [Sal68, JdV69, BBDK94] for example. In [BBDK94] it was shown among other things that among a whole family of Lüroth-type maps, the alternating Lüroth map is the one with the best approximation properties.

In this section we consider a random Lüroth map, using $T_0 := T_L$ and $T_1 := T_A$ as its base maps. See Figure 7 for the graphs of T_L , T_A and an example of a random Lüroth map T . Then for each realization of the random system $\omega \in \{0, 1\}^{\mathbb{N}}$ and each $x \in [0, 1]$ that is not a pre-image of 0 under the realization ω we obtain a random Lüroth expansion by setting, for each $k \geq 0$,

$$r_{k+1}(\omega, x) = n, \quad \text{if } T_{\omega_1^k}(x) \in \left(\frac{1}{n}, \frac{1}{n-1} \right].$$

Observe that

$$T_{\omega_1^k}(x) = (-1)^{\omega_k} r_k(r_k - 1)x + (-1)^{\omega_k - 1}(r_k + \omega_k - 1).$$

If we set $s_n = \sum_{k=1}^n \omega_k$ with $s_0 = 0$, then we obtain the following expression for x :

$$x = \sum_{n \geq 1} (-1)^{s_{n-1}} (r_n + \omega_n - 1) \prod_{k=1}^n \frac{1}{r_k(r_k - 1)}.$$

We call this expression a *random Lüroth expansion* of x .

Many people have considered digit properties of Lüroth expansions, such as digit frequencies and the sizes of sets of numbers for which the digit sequence $(l_n)_{n \geq 1}$ is bounded. See for example [BI09, FLMW10, SF11, MT13, GL16]. The set of points that have all Lüroth digits bounded by some integer a corresponds to the set of points that avoid the set $[0, 1/a]$ under all iterations of the map T_L . For a deterministic system, such

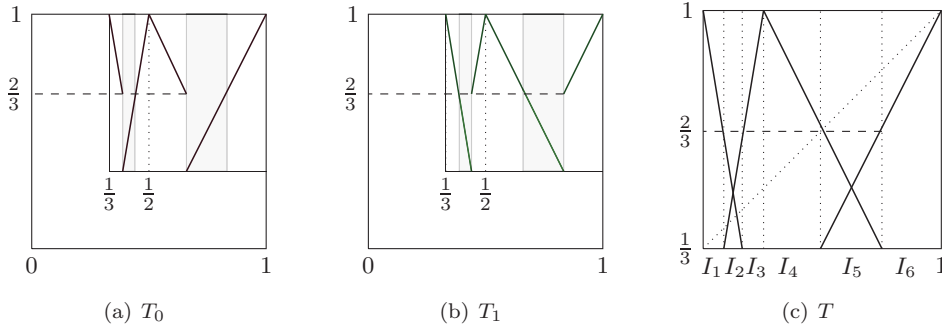


FIGURE 8. The systems T_0 , T_1 and T on the interval $I = [\frac{1}{3}, 1]$.

a set is usually a fractal no matter how large we take the upper bound a . In the random setting, the situation is drastically different. Fix, for example, $a = 3$. We show below that all $x \in [\frac{1}{3}, 1]$ have a random Lüroth expansion using only digits 2 and 3. Using the density given by Theorem 4.1, we can compute the frequency of each of these digits for any typical point $x \in [\frac{1}{3}, 1]$.

Partition the interval $[\frac{1}{3}, 1]$ by setting

$$I_1 = \left[\frac{1}{3}, \frac{7}{18}\right], I_2 = \left(\frac{7}{18}, \frac{4}{9}\right], I_3 = \left(\frac{4}{9}, \frac{1}{2}\right], I_4 = \left(\frac{1}{2}, \frac{2}{3}\right], I_5 = \left(\frac{2}{3}, \frac{5}{6}\right], I_6 = \left(\frac{5}{6}, 1\right].$$

Let

$$T_0(x) := \begin{cases} T_L(x) & \text{if } x \in I_2 \cup I_3 \cup I_5 \cup I_6, \\ T_A(x) & \text{if } x \in I_1 \cup I_4, \end{cases} \quad \text{and } T_1(x) := \begin{cases} T_A(x) & \text{if } x \in I_1 \cup I_2 \cup I_4 \cup I_5, \\ T_L(x) & \text{if } x \in I_3 \cup I_6. \end{cases}$$

For $0 \leq p \leq 1$ with $p \neq \frac{1}{2}$ let $p_0 := p$ and $p_1 := 1 - p$ and let T now be the *random Lüroth system with digits 2 and 3* defined on $[\frac{1}{3}, 1]$ by setting $T(x) = T_j(x)$ with probability p_j ; see Figure 8. Note that we have to exclude $p = \frac{1}{2}$, since condition (A5) is not satisfied in that case.

To use Theorem 4.1, we need to determine the orbits of all the points $a_{n,j}$ and $b_{n,j}$, which in this case are $\frac{1}{3}, \frac{2}{3}$ and 1. One can easily check that all $KI_n(a_{i,j})$ and $KI_n(b_{i,j})$ are zero, except for

$$KI_1\left(\frac{1}{3}\right) = -\frac{1}{6}, \quad KI_6\left(\frac{1}{3}\right) = -\frac{1}{6}, \quad KI_6(1) = 1 \quad \text{and} \quad KI_4\left(\frac{2}{3}\right) = -\frac{1}{3}.$$

The fundamental matrix M of the system is therefore given by

$$M = \begin{pmatrix} \frac{p-6}{36} & \frac{1-p}{36} & 0 & \frac{p}{12} & \frac{1-p}{12} \\ \frac{1-2p}{6} & \frac{2p-1}{6} & 0 & 0 & 0 \\ 0 & -\frac{1}{6} & \frac{1}{6} & 0 & 0 \\ \frac{p}{18} & \frac{1-p}{18} & \frac{1}{2} & \frac{p-3}{6} & \frac{1-p}{6} \\ 0 & 0 & 0 & \frac{1-2p}{2} & \frac{2p-1}{2} \\ \frac{p}{36} & \frac{1-p}{36} & \frac{2}{3} & \frac{p}{12} & -\frac{p+5}{12} \end{pmatrix},$$

and its null space consists of all vectors of the form

$$s(3 \ 3 \ 3 \ 5 \ 5)^\top, \quad s \in \mathbb{R}.$$

Again this is a one-dimensional space, so, by Theorem 5.3, T has a unique invariant density. The corresponding measure $m_p \times \mu_p$ is necessarily ergodic for R . From

$$L_{1/3} = -\frac{1}{3}, \quad L_{2/3} = \frac{2}{3} \cdot \mathbf{1}_{[1/3, 2/3]} \quad \text{and} \quad L_1 = 2$$

we get the invariant density

$$h_\gamma = \frac{3}{8}(3 \cdot \mathbf{1}_{[1/3, 2/3]} + 5 \cdot \mathbf{1}_{(2/3, 1]}).$$

Let $R : \{0, 1\}^\mathbb{N} \times [\frac{1}{3}, 1] \rightarrow \{0, 1\}^\mathbb{N} \times [\frac{1}{3}, 1]$ be the pseudo skew-product associated to T . For any point $(\omega, x) \in \{0, 1\}^\mathbb{N} \times [\frac{1}{3}, 1]$ the frequency of the digit 2 in its random Lüroth expansion is given by

$$\lim_{n \rightarrow \infty} \frac{1}{n} \sum_{k=0}^{n-1} \mathbf{1}_{\{0,1\}^\mathbb{N} \times (1/2, 1]}(R^k(\omega, x)).$$

Since $m_p \times \mu_p$ is ergodic, by the ergodic theorem we have that for $m_p \times \mu_p$ -almost every $(\omega, x) \in \{0, 1\}^\mathbb{N} \times [\frac{1}{3}, 1]$ the frequency of 2 in the associated random Lüroth expansion is

$$\int_{(1/2, 1]} h_\gamma \, d\lambda = \frac{13}{16},$$

giving also that the frequency of the digit 3 is $3/16$.

Even though condition (A5) is not satisfied for $p = \frac{1}{2}$, the fundamental matrix M can still be computed and its null space is still given by $s(3 \ 3 \ 3 \ 5 \ 5)^\top$, $s \in \mathbb{R}$. Moreover, the function $h_\gamma = \frac{3}{8}(3 \cdot \mathbf{1}_{[1/3, 2/3]} + 5 \cdot \mathbf{1}_{(2/3, 1]})$ is still the unique invariant density. We believe that Theorems 4.1 and 5.3 should still hold without assumption (A5).

Remark 7.1. Note that our method is also capable of handling more general versions of restricted random Lüroth maps. If, instead of considering holes of the form $[0, \frac{1}{3})$, we

restricted the system $\{T_L, T_A\}$ to an interval $[\eta, 1]$ for some $0 < \eta < 1$, then by the same arguments as above, the restricted random Lüroth system would have a unique absolutely continuous invariant measure for which the density can be obtained from Theorem 4.1.

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