ABSOLUTE APPROXIMATE RETRACTS AND AR-SPACES

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1. Introduction. A subset A of a topological space X is an *approximate retract* of X if for every neighborhood U of A in X there is a retract R of X such that $A \subset R \subset U$. A compactum X is an *absolute approximate retract* (AAR-space) if whenever X is embedded as a subset of a compactum Z, then X is an approximate retract of Z. These concepts were first defined in [2] where it is shown that every AAR-space is a contractible Peano continuum. In [3] an example is given to show that there exists a contractible LC[∞] compactum which is not an AAR-space.

The purpose of this paper is to show that every AAR-space is locally contractible, and to give an example of a contractible and locally contractible compactum which is not an AAR-space.

2. Preliminaries. The terminology used in this paper may be found in [1]. In particular, Hilbert space will be denoted by E^{ω} and the diameter of a set M will be denoted by $\delta(M)$. The following two constructions will be used in the sequel.

(1) The cap over a compactum. Let X be a compact subset of E^{ω} and let S be a compact segment in E^{ω} which is disjoint from X. The construction of the cap of X and S, denoted by cap XS, may be found in [5, p. 42].

(2) A special plane continuum C. The infinite ray A, the 1-dimensional plane continuum B, and $C = A \cup B$ shall be as defined in [3, p. 491].

3. The results. In the proof of the following theorem, we make use of techniques which have been used in [3] and [4].

THEOREM 1. Every AAR-space is locally contractible.

Proof. Let X be an AAR-space and suppose that X is not locally contractible at a point p. Then there is a neighborhood U of p in X which contains a decreasing sequence $V_1, V_2, ...$ of compact neighborhoods of psuch that $\lim_{i\to\infty} \delta(V_i) = 0$ and no V_i is contractible in U. Consider a sequence of disjoint continua $Y_1, Y_2, ...$ with $\lim_{i\to\infty} \delta(Y_i) = 0$ obtained by first taking the disjoint union $\bigcup_{i=1}^{\infty} V_i$ and then letting $Y_i = \operatorname{cap} V_i A_i$

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for i = 1, 2, Let $Y = \bigcup_{i=1}^{\infty} Y_i$. Form the compactum M obtained by taking the disjoint union of X and Y, and then identifying V_i in Xwith $V_i \times \{0\}$ in Y for i = 1, 2, We now use the special continuum C defined in Section 2 to attach the infinite ray A to M. Since the construction used to attach A to M will subsequently be referred to in the paper, it shall be denoted by (*).

Let $g: B \to M$ be a homeomorphism into M such that

(1) $g(I) \subset Y$ and g(0) = p.

(2) $g(B_i) \subset Y_i$ and $g(A_i) = A_i$. (*)

Define Z_1 to be the continuum obtained by taking the disjoint union of C and M, and then identifying each point $z \in B$ with its image $g(z) \in M$.

Let W be a neighborhood of X in Z_1 such that $W \cap C$ consists of all the points in C whose distance from the x-axis is less than 1/6. Then Wcontains all but finitely many of the sets Y_i , and no connected subset of W containing X contains a point of A. Since X is an AAR-space, there is a retract R of Z_1 such that $X \subset R \subset W$. Then, since R is a retract of the connected space Z_1 , it follows that R is a connected subset of Wwhich contains X. Let $r: Z_1 \to R$ be a retraction of Z_1 onto R.

First we show that $A_1 \cap R = \emptyset$ for all i = 1, 2, ... To see this, suppose $A_j \cap R \neq \emptyset$ for some j. It then follows that R contains a nonlocally connected subcontinuum of Y_j which contains both V_j and A_j . Then r must map a subinterval of A onto a nonlocally connected subset of Y_j , which is impossible. Therefore $A_i \cap R = \emptyset$ for all i = 1, 2, ... and, hence,

$$R \subset Z_1 - \left(A \cup \bigcup_{i=1}^{\infty} A_i\right).$$

Define a retraction s: $R \rightarrow X$ by

$$s(y) = \begin{cases} y & \text{if } y \in R \cap X, \\ (x, 0) & \text{if } y = (x, t) \in R \cap \left(\bigcup_{i=1}^{\infty} Y_i\right). \end{cases}$$

Let $r_1 = sr$. Then $r_1: Z_1 \to X$ is a retraction such that $r_1(Y_i) \subset U$ for all but finitely many of the Y_i . To facilitate notation, we shall assume that $r_1(Y_i) \subset U$ for i = 1, 2, Since no V_j is contractible in U, it follows that $\delta(r_1(A_1)) \neq 0$ for i = 1, 2, Hence, we may assume that $\delta(r_1(A_i)) = \lambda_i$ where $\lambda_1, \lambda_2, ...$ is a sequence of positive numbers which converges to 0.

Let a_i denote the midpoint of A_i , and let $0 = t_{i,0} < t_{i,1} < ... < t_{i,j} < ... < t_{i,j}$ < ... be a sequence of numbers in $[0, \infty)$ such that

$$\lim_{j\to\infty} V_i \times \{t_{i,j}\} = a_i.$$

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Set $b_i = r_1(a_i)$, $B_{i,j} = r_1(V_i \times \{t_{i,j}\})$. Let $Y_{i,j} = \operatorname{cap}(B_{i,j}A_{i,j})$ denote a null sequence of caps satisfying the following properties.

- (1) $Y_{i,j} \cap X = B_{i,j}$.
- (2) $Y_{i,j} \cap Y_{i,k} \subset X$ if $j \neq k$.
- (3) $\lim_{j\to\infty} Y_{i,j} = b_i.$

Let $M_i = X \cup \bigcup_{i=1}^{\infty} Y_{i,j}$ and, as in (*), obtain a continuum $Z_{2,i}$ by attaching an infinite ray to M_i . Then, using arguments similar to previous arguments, there is a sequence of retractions $r_{2,i}: Z_{2,i} \to X$, i = 1, 2, ..., each of which maps infinitely many sets of the form $Y_{i,j}$ into U. The process can be continued so that in the n^{th} stage we obtain retractions

 $r_{n,i_1,\ldots,i_{n-1}}: Z_{n,i_1,\ldots,i_{n-1}} \to X,$

each of which maps infinitely many of the sets of the form $Y_{i_1, i_2, ..., i_n}$ into U. Consequently, there is a sequence

 $V_{j_1} = B_{j_1,0}, B_{j_1,j_2}, B_{j_1,j_2,j_3}, \dots, B_{j_1,j_2,\dots,j_n}, \dots$

of sets lying in U, a point $q \in U$, and a sequence of homotopies $\{F_n\}_{n=1}^{\infty}$ with values in U such that the following properties are satisfied.

(1) $\lim_{n\to\infty} B_{j_1,j_2,\ldots,j_n} = \{q\}.$

(2) F_1 is a homotopy which deforms V_{j_1} onto B_{j_1,j_2} and, for n > 1, F_n deforms B_{j_1,j_2,\ldots,j_n} onto $B_{j_1,j_2,\ldots,j_n,j_{n+1}}$.

(3) $\lim_{n\to\infty}\delta(\operatorname{Im} F_n) = 0.$

It is possible to construct a homotopy F with values in U which deforms V_{j_1} to the point q. This contradiction shows that X must be locally contractible and the proof is complete.

Proposition 1 in [2, p. 410] together with the above theorem shows that every AAR-space is contractible and locally contractible. Thus every finite dimensional AAR-space is an AR-space [1, p. 122]. Since every AR-space is an AAR-space, we have the following theorem.

THEOREM 2. A finite dimensional compactum X is an AAR-space if and only if X is an AR-space.

Since a retract of an AR-space is an AR-space [1, p. 101], the following result would be a consequence of Theorem 2 for the finite dimensional case.

PROPOSITION. Every retract of an AAR-space is an AAR-space.

Proof. Let X be a retract of an AAR-space Y and let $r: Y \to X$ be a retraction of Y onto X. Let Z be a compactum and suppose $e: X \to Z$ is an embedding of X into Z. Form the identification space M obtained by taking the disjoint union of Y and Z, and then identifying each point

 $x \in X$ with $e(x) \in Z$. Let U be a neighborhood of X in Z. Then $Y \cup U$ is a neighborhood of Y in M. Thus there is a retract Q of M such that $Y \subset Q \subset Y \cup U$. Let $R = Q \cap Z$. Then $X \subset R \subset U$. Define a retraction $f: Q \to R$ from Q onto R by

$$f(x) = \begin{cases} x & \text{if } x \in Q \cap Z, \\ r(x) & \text{if } x \in Y. \end{cases}$$

Let $g: M \to Q$ be a retraction of M onto Q and let h = fg|Z. Then it is easy to check that $h: Z \to R$ is a retraction of Z onto R. Thus X is an approximate retract of Z and, hence, X is an AAR-space.

An example of a contractible LC^{∞} compactum which is not an AARspace is given in [3]. We now mention that a well-known example due to Borsuk [1, p. 126] is in fact an example of a contractible and locally contractible compactum which is not an AAR-space.

Example. Consider the following subsets of the Hilbert cube Q^{ω} (for notation see [1, p. 10]):

$$X_0 = \{x = \{x_i\} | x_1 = 0\},\$$

$$B_k = \{x = \{x_i\} | 1/(k+1) \le x_1 \le 1/k \text{ and}\$$

$$x_i = 0 \text{ for } i > k\} \text{ for } k = 1, 2, \dots.$$

The boundary Bd B_k of B_k is a (k-1)-sphere which we shall denote by X_k for k = 1, 2, ... Let $X = X_0 \cup \bigcup_{k=1}^{\infty} X_k$. Then, if Y denotes the cone over X with vertex p, Y is a contractible and locally contractible compactum which is not an ANR-space [1, p. 126]. We now show that Y is not an AAR-space by constructing a compactum Z containing Y such that Y is not an approximate retract of Z. Since the proof is analogous to that found in [3, p. 491], we omit the details.

Let $C_k = \operatorname{cap} X_k A_k$, k = 1, 2, ..., denote a sequence of caps in Hilbert space E^{ω} such that the following properties are satisfied.

- (1) $C_k \cap Y = X_k \times \{0\} = X_k$ for k = 1, 2, ...
- (2) $C_i \cap C_j = X_i \cap X_j$ for i, j = 1, 2, ...
- (3) $\lim_{k\to\infty}C_k = X_0.$

Define $M = Y \cup \bigcup_{k=1}^{\infty} C_k$. Let Z denote the continuum obtained by using (*) to attach an infinite ray A to M. Let U denote the neighborhood of Y in Z which consists of all the points in Z whose distance from Y is less than 1/6. Suppose R is a retract of Z such that $Y \subset R \subset U$. Then the following facts may be easily verified.

(1) C_k cannot be retracted onto $X_k = X_k \times \{0\}$ for k = 1, 2, ...

(2) Only finitely many of the sets C_k , k = 1, 2, ..., can be retracted into Y.

(3) R is a connected subset which contains a set of the form C_j , but R contains no point of A.

(4) Any retraction of Z onto R must map a subinterval of A onto a nonlocally connected subset of C_j , which is a contradiction.

In view of the fact that the class of AAR-spaces is properly contained in the class of contractible and locally contractible compacta, it is appropriate to ask the following question:

Question. Does the class of AAR-spaces coincide with the class of AR-spaces?

References

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