M. Rao and J. Sokołowski Nagoya Math. J. Vol. 130 (1993), 101–110

POLYHEDRICITY OF CONVEX SETS IN SOBOLEV SPACE $H_0^2(\Omega)$

MURALI RAO AND JAN SOKOŁOWSKI

1. Introduction

We provide results on differential stability of metric projection in Sobolev space $H_0^2(\Omega)$ onto convex set

(1.1)
$$K = \{ f \in H_0^2(\Omega) \mid f(x) \ge \psi(x), x \in \Omega \}$$

where $\Omega \subset R^d$ is open, bounded domain.

We derive the form of tangent cone $T_K(f)$ for any element $f \in K$ -see Theorem 1. The same argument can be used for convex set

$$K = \{ f \in H_0^m(\Omega) \mid f \ge \phi \}, \ m = 2, 3, \dots$$

where $\psi \in H^m(\Omega)$, $\psi < 0$ on $\partial \Omega$.

In section 3 we provide necessary and sufficient conditions under which set K is polyhedric [5], [8] at a given point $f \in K$. The question of polyhedricity is addressed here since it implies directional differentiability of metric projection onto K with the explicit form of the differential [5], [8]. We refer the reader to [5], [8] for related results in the Sobolev space $H_0^1(\Omega)$. Some applications of the differential stability of metric projection onto convex sets in Sobolev spaces are presented in [6], [9]-[18].

We recall some properties of the Sobolev spaces and the notion of capacity [19]. The Sobolev spaces $H_0^1(\Omega)$ and $H_0^2(\Omega)$ are the closures of $C_0^{\infty}(\Omega)$ with norms

$$\| \varphi \|_{H^{1}_{0}(\Omega)}^{2} = \int_{\Omega} | \nabla \varphi |^{2} dx$$
$$\| \varphi \|_{H^{2}_{0}(\Omega)}^{2} = \int_{\Omega} | \nabla \varphi |^{2} dx$$

Received March 4, 1991.

respectively. If $\varphi \in H_0^2(\Omega)$, from the definition $D^{\alpha}\varphi \in H_0^1(\Omega)$ for each α with $|\alpha| = 1$. Functions in $H_0^1(\Omega)$ are defined quasi everywhere and are quasi continuous. These notions are made precise below.

The C_1 -capacity of a compact set F is defined as

$$C_1(F) = \inf \left\{ \int |\nabla \varphi|^2 dx : \varphi \ge 1 \text{ on } F, \ 0 \le \varphi \in C_0^{\infty}(\mathbb{R}^d) \right\}$$

similarly C_2 -capacity

$$C_2(F) = \inf \left\{ \int |\Delta \varphi|^2 dx : \varphi \ge 1 \text{ on } F, \ 0 \le \varphi \in C_0^{\infty}(\mathbb{R}^d) \right\}.$$

The capacity of a Borel set is then defined as the supremum of capacities of its compact subsets. A statement holds C_{i} -q.e., i = 1,2, if it holds except for a set of C_{i} -capacity zero. With this definition we have the following results:

- 1. Let $\varphi \in H_0^1(\Omega)$, and $\{\varphi_n\} \subset C_0^{\infty}(\Omega)$ converge to φ in $H_0^1(\Omega)$. Then a subsequence of $\{\varphi_n\}$ converge C_1 -q.e. and this is a representative of φ .
- 2. Let $\varphi \in H_0^1(\Omega)$. Then φ has a quasicontinuous representative: There is a representative $\overline{\varphi}$ such that given $\varepsilon > 0$, there is an open set $U(\varepsilon)$ of C_1 -capacity less than ε such that the restriction of $\overline{\varphi}$ to the complement of $U(\varepsilon)$ is continuous.
- 3. Any two quasi continuous representatives of $\varphi \in H_0^1(\Omega)$ agree C_1 -q.e.
- 4. Every set of positive Lebesque measure has positive C_1 -capacity.

We use standard notation throughout the paper [1], [19].

2. Tangent cone

We shall consider the metric projection onto the following convex set

(2.1)
$$K = \{ f \in H_0^2(\Omega) \mid f(x) \ge \psi(x), x \in \Omega \}$$

with respect to the scalar product

(2.2)
$$(y, z) = \int_{\mathcal{Q}} \Delta y(x) \Delta z(x) dx.$$

We assume that $\psi \in H^2(\Omega)$, $\psi(x) < 0$ on $\partial\Omega$, therefore set (2.1) is nonempty. The metric projection $z = P_K y$, $y \in H_0^2(\Omega)$, is given by the unique solution of the following variational inequality

(2.3)
$$z \in K : \int_{\Omega} \Delta z(x) \Delta(\varphi - z)(x) dx \ge \int_{\Omega} \Delta y(x) \Delta(\varphi - z)(x) dx$$
$$\forall \varphi \in K.$$

We denote

(2.4)
$$C_{K}(z) = \{ \varphi \in H_{0}^{2}(\Omega) \mid \exists t > 0 \text{ such that } z + t\varphi \in K \}.$$

We derive the form of tangent cone $T_K(z) = clC_K(z)$ for any element z in convex set (2.1).

THEOREM 1. For any element $z \in K$, tangent cone $T_K(z)$ takes the form

(2.5)
$$T_{K}(z) = \{ \varphi \in H_{0}^{2}(\Omega) \mid \varphi(x) \geq 0, \ C_{2}\text{-}q.e. \ on \ E \}$$

where $\Xi = \{x \in \Omega \mid z(x) = \psi(x)\} \subset \Omega$.

Proof of Theorem 1. Note that $C_K(z)$ and hence also $T_K(z)$ is a convex cone containing all non-negative elements of $H_0^2(\Omega)$. Let an element $V \in H_0^2(\Omega)$ be given and suppose that $V \ge 0$ C_2 -q.e. on Ξ . There exists the unique element $\phi_0 \in T_K(z)$ such that

(2.6)
$$\| V - \phi_0 \|_{H^2_0(\Omega)}^2 = \inf\{ \| V - \phi_0 \|_{H^2_0(\Omega)}^2 | \phi \in C_K(z) \}.$$

It is easy to see that for any $H_0^2(\Omega) \ni \phi \ge 0$, $t \ge 0$, $\phi_0 + t \phi \in T_K(z)$. Using (2.6) and standard arguments it follows

(2.7)
$$(V - \phi_0, \phi)_{H^2_0(\Omega)} \le 0, \ 0 \le \phi \in H^2_0(\Omega)$$

hence there exists a non-negative Radon measure μ on ${\it Q}$ such that

(2.8)
$$(V - \phi_0, \phi)_{H^2_0(\Omega)} \leq -\int \phi d\mu, \ \phi \in C^{\infty}_0(\Omega).$$

This implies in particular that for $\phi \ge 0$

$$\int \phi d\mu = - (V - \phi_0, \phi)_{H^2_0(\Omega)} \le \| V - \phi_0 \|_{H^2_0(\Omega)} \| \phi \|_{H^2_0(\Omega)}.$$

So by definition of C_2 -capacity we see μ cannot charge sets of zero C_2 -capacity. Since the measure may be large near the boundary it is not clear that (2.8) holds for all $\phi \in H_0^2(\Omega)$. We can circumvent this difficulty by repeated use of a result of L. I. Hedberg: Theorem 3.1 in [7]. First we show that (2.8) holds for any bounded $\phi \in H_0^2(\Omega)$ which is non-negative and has compact support. Indeed for suitable mollifiers ρ_n , $\phi * \rho_n \in C_0^{\infty}(\Omega)$, have compact support, and tend boundedly pointwise C_2 -q.e. and in $H_0^2(\Omega)$ to ϕ . Since μ is Randon measure we may appeal to Lebesque dominated convergence to finish the claim. In the general case if $0 \leq \phi \in H_0^2(\Omega)$ by the above theorem of Hedberg, we can select $0 \leq w_k \leq 1$, $k = 1, 2, \ldots$ such that $w_k \phi$ has compact support and is in L^{∞} approximating ϕ in $H_0^2(\Omega)$. In particular $w_k \phi$ converges to ϕC_2 -q.e. By (2.8) we have

$$\int w_k \phi d\mu = - (V - \phi_0, w_k \phi)_{H^2_0(\Omega)}$$

is bounded, so by Fatou Lemma $\phi \in L^1(\mu)$. On the other hand $w_k \phi \leq \phi$ so domin ated convergence applies

(2.9)
$$-\int \phi d\mu = (V - \phi_0, \phi)_{H^2_0(\Omega)}, \ 0 \le \phi \in H^2_0(\Omega).$$

Now let $\phi \in C_0^{\infty}(\Omega)$, $0 \le \phi \le 1$, then $\phi(z - \phi) \in H_0^2(\Omega)$. We show that

$$\phi_0 + t\phi(z-\psi) \in T_K(z), -1 \leq t \leq 1.$$

It is sufficient to show that for any $\varphi \in C_{\kappa}(z)$, it follows $\varphi + t\phi(z - \psi) \in C_{\kappa}(z)$. Now $\varepsilon \varphi + z - \psi \ge in \Omega$ for some $\varepsilon > 0$, hence for s > 0, $\frac{s}{1-s} < \varepsilon$ we have

$$s[\varphi + t\phi(z - \psi)] + z - \psi \ge 0$$
, in Ω

since $(1 + st\phi)(z - \psi) \ge (1 - s)(z - \psi)$. Using this in (2.6) with ϕ replaced by $\phi_0 + t\phi(z - \psi)$ we obtain

$$(V - \phi_0, \phi(z - \psi))_{H^2_0(\Omega)} = 0$$

which, because $\phi(z-\psi)$ has compact support and belongs to $H_0^2(\Omega)$ means

$$\int \phi(z-\psi)\,d\mu=0$$

hence

$$\mu(x:z>\phi)=0$$

i.e. μ is concentrated on Ξ . Our next step is to show that $\phi_0 = 0 \mu$ -a.e. To this end using the fact that $T_K(z)$ is a cone and taking $t\phi_0$ for ϕ in (2.6) we get

(2.10)
$$(V - \phi_0, \phi_0)_{H^2_s(Q)} = 0.$$

Now we use Hedberg's result once more. Choose w_k , $0 \le w_k \le 1$ such that $w_k \phi_0$ has compact support and converges to ϕ_0 in $H_0^2(\Omega)$. Since $\phi_0 \ge 0$ on Ξ and μ is concentrated on Ξ , $w_k \phi_0 \le \phi_0 \mu$ -a.e. So using the same argument as above we get

$$0 = (V - \phi_0, \phi_0)_{H_0^2(\Omega)} = -\int \phi_0 d\mu$$

i.e. that $\phi_0 = 0 \mu$ -a.e.

Finally since $\phi_{\rm 0}=0~\mu\text{-a.e}$ and $V\geq 0~C_{\rm 2}\text{-q.e.}$ on E we can repeat the above argument to get

$$(V-\phi_0, V-\phi_0)_{H^2_0(\Omega)} = -\int (V-\phi_0) d\mu = -\int V d\mu.$$

But the right hand side is ≤ 0 because $V \geq 0$, thus $V = \phi_0$.

Remark 1. For d = 1, 2, 3 proof of Theorem 1 simplifies since by Sobolev embedding theorem $H_0^2(\Omega) \subset C(\overline{\Omega})$. It is clear that

$$T_{K}(u) \subset \{\varphi \in H_{0}^{2}(\Omega) \mid \varphi(x) \geq 0, \text{ on } \Xi\}$$

therefore it is sufficient to show that any element $V(\cdot) \ge 0$ on Ξ actually belongs to $T_{\kappa}(u)$. Ξ is compact, hence there exists $0 \le \eta \in C_0^{\infty}(\Omega)$, $\eta \equiv 1$ on Ξ . Since by Sobolev embedding theorem $u, \psi, V \in C(\overline{\Omega})$ therefore for any $\varepsilon > 0$ there exists t > 0 such that

$$t(V+\varepsilon\eta)+u-\psi\geq 0$$
, in Ω .

Thus

$$V+\varepsilon\eta\in C_{\kappa}(u), \ \forall \varepsilon>0$$

and

$$V + \varepsilon \eta \to V$$
 in $H_0^2(\Omega)$ strongly with $\varepsilon \downarrow 0$

hence $V \in \overline{C_K(u)} = T_K(u)$.

3. Differentiability of metric projection

We derive a result on the differentiability of metric projection P_K in the Hilbert space $H = H_0^2(\Omega)$ onto convex closed set $K \subseteq H$ of the form (2.1). Here we assume for the sake of simplicity that d = 1,2,3, hence by the Sobolev embedding

theorem it follows that $H^2(\Omega) \subset C(\overline{\Omega})$, the latter embedding is compact [1] for bounded domain Ω with smooth boundary $\partial \Omega$. We use the following notation. For any given element $u \in K$ we denote

(3.1)
$$C_K(u) = \{ \phi \in H \mid \exists t > 0 \text{ such that } u + t \phi \in K \}.$$

The tangent cone $T_{K}(u)$ to K at u is the closure of set (3.1)

(3.2)
$$T_{\kappa}(u) = \operatorname{cl}(C_{\kappa}(u))$$

Let us consider set K defined in section 1. We shall address the question of polyhedricity of K, see Definition 1 below. Let $T_K(f)$ be the tangent cone to K at $f \in K$. It is clear that $T_K(f)$ is the closure in the space $H_0^2(\Omega)$ of the convex cone

(3.3)
$$C_{K}(f) = \{v \in H_{0}^{2}(\Omega) \mid \exists t > 0 \text{ such that } f(x) + tv(x) \ge \psi(x) \text{ in } \Omega\}.$$

For a given element $g \in H_0^2(\Omega)$, such that $f = P_K(g)$ let us define the following convex cone in the space $H_0^2(\Omega)$

(3.4)
$$S = T_{K}(f) \cap [g - P_{K}(g)]^{\perp} = T_{K}(f) \cap [f - g]^{\perp}.$$

DEFINITION 1. The set $K \subset H_0^2(\Omega)$ is polyhedric at $f \in K$, if for any $g \in H_0^2(\Omega)$ such that $f = P_K g$ it follows

(3.5)
$$T_{K}(f) \cap [f-g]^{\perp} = \operatorname{cl}(C_{K}(f) \cap [f-g]^{\perp})$$

here cl stands for the closure.

Remark 2. Let us recall [5], [8] that if condition (3.5) is satisfied for given elements $(f, g) \in H_0^2(\Omega) \times H_0^2(\Omega)$, $f = P_K(g)$ then for all $h \in H_0^2(\Omega)$ and for t > 0 small enough

(3.6)
$$P_{K}(g+th) = P_{K}g + tP_{S}h + o(t).$$

In such a case the metric projection P_{κ} is conically differentiable, in the notation of [8], at $g \in H_0^2(\Omega)$. It turns out that condition (3.5) is satisfied if and only if the support of non-negative Radon measure defined below by (3.9) is admissible in the following way.

DEFINITION 2. Compact F is admissible if for any element $\varphi \in H_0^2(\Omega)$, $\varphi = 0$ on F implies $\varphi \in H_0^2(\Omega \setminus F)$.

We denote by B(x, r), $x \in \mathbb{R}^d$, r > 0 the ball of radius r and center x, |A| denotes the Lebesque measure of any set $A \subset \mathbb{R}^d$.

PROPOSITION 1. Let $F \subseteq \Omega$ be compact and assume that the following holds: for C_1 -quasi every $x \in F$,

$$|F \cap B(x, r)| > 0.$$

Then F is admissible.

Proof of Proposition 1. By Theorem 1.1 in [7] it is sufficient to show the following: let $\varphi \in H_0^2(\Omega)$ and $\varphi = 0$ C_2 -q.e. on F. Then $\nabla \varphi = 0$ C_1 -q.e. on F. Now $\varphi \in H_0^1(\Omega)$ so by a standard result, $\nabla \varphi = 0$ a.e. on F. Since $\varphi \in H_0^2(\Omega)$, each component of $\nabla \varphi$ belongs to $H_0^1(\Omega)$ and hence has a finely continuous version [19]. If for $x \in F$, $|\nabla \varphi|(x) > 0$ then in a fine neighborhood of x the same inequality will obtain. Since finely open sets have positive measure, and since $\nabla \varphi = 0$ a.e. on F, this violates our condition on F. Thus $\nabla \varphi = 0$ C_1 -q.e. on F.

Denote by $\nu \geq 0$ the Radon measure defined as follows

(3.9)
$$\int \varphi d\nu = \int_{\mathcal{Q}} \Delta(g-f) \Delta \varphi dx, \ \forall \varphi \in C_0^{\infty}(\mathcal{Q}).$$

THEOREM 2. We have

(3.10)
$$\operatorname{cl}(C_{K}(f) \cap [f-g]^{\perp}) = \{\varphi \in H_{0}^{2}(\Omega \setminus F) \mid \varphi \geq 0 \text{ on } E \setminus \operatorname{spt} \nu\}$$

where spt $\nu \subset \Xi$ is compact, spt ν denotes the support of Radon measure ν .

Proof of Theorem 2. It is clear that

(3.11)
$$\operatorname{cl}(C_{K}(f) \cap [f-g]^{\perp}) \subset S = T_{K}(f) \cap [f-g]^{\perp}$$

and in view of Theorem 1

(3.12)
$$S = \{ \varphi \in H_0^2(\Omega) \mid \varphi = 0 \text{ on spt } \nu, \varphi \ge 0 \text{ on } E \setminus \operatorname{spt} \nu \}.$$

Let us observe that

(3.13)
$$H^2(\Omega) \ni f - \psi \ge 0$$
, and $f - \psi = 0$ on compact set Ξ

therefore it can be shown [20]

(3.14)
$$\nabla (f - \psi) = 0 C_1$$
-q.e. on Ξ .

Let $\varphi \in C_{\kappa}(f) \cap [f-g]^{\perp}$ then for some $t \geq 0$

(3.15)
$$t\varphi + f - \psi \ge 0 \text{ on } \Omega$$
, and $\varphi = 0$ q.e. on spt ν .

It follows that $\nabla [t\varphi + f - \phi] = 0$ C_1 -q.e. on spt ν i.e. that $\nabla \varphi = 0$ C_1 -q.e. on spt ν . Clearly the same conclusion obtains for any element in $\operatorname{cl}(C_K(f) \cap [f-g]^{\perp})$ therefore

(3.16)
$$\operatorname{cl}(C_{K}(f) \cap [f-g]^{\perp}) \subset H_{0}^{2}(\Omega \setminus \operatorname{spt} \nu).$$

Now we can use the same argument as in the proof of Theorem 1 to show that if V is an arbitrary element in set

(3.17)
$$\{\varphi \in H_0^2(\Omega \setminus \operatorname{spt} \nu) \mid \varphi \ge 0 \text{ on } \mathcal{E}\}$$

and φ_0 denotes the projection of V onto $\operatorname{cl}(C_{\kappa}(f) \cap [f-g]^{\perp})$ then $V = \varphi_0$. Thus (3.18) $\operatorname{cl}(C_{\kappa}(f) \cap [f-g]^{\perp}) = \{\varphi \in H_0^2(\Omega \setminus \operatorname{spt} \nu) \mid \varphi \ge 0 \text{ on spt } \nu\}.$

THEOREM 3. Set K is polyhedric at $f \in K$ if and only if $C_1(\Xi) = 0$, where $\Xi = \{x \in \Omega \mid f(x) = \psi(x)\}.$

Proof. We show that in (3.9) we can have any nonnegative Radon measure $\nu \in H^{-2}(\Omega)$ with spt $\nu \subset \Xi$. Let such $\nu \geq 0$ be given. Let $g \in H^{2}_{0}(\Omega)$ satisfy

(3.19)
$$\int_{\mathcal{Q}} \Delta g \Delta \varphi dx = \int_{\mathcal{Q}} \Delta f \Delta \varphi dx - \int \varphi d\nu, \ \forall \varphi \in H_0^2(\mathcal{Q}).$$

We have $f = P_K g$. To see it let us observe that

(3.20)
$$\int \varphi d\nu \ge 0, \ \forall \varphi \in T_{\kappa}(f)$$

since $\eta - f \in T_K(f)$, $\forall \eta \in K$ it follows

(3.21)
$$\int (\eta - f) d\nu \ge 0, \ \forall \eta \in K$$

hence

(3.22)
$$\int (\eta - f) d\nu = \int_{\mathcal{Q}} \Delta(f - g) \Delta(\eta - f) dx \ge 0, \ \forall \eta \in K$$

which shows that $f = P_{\kappa}g$. Therefore condition (3.5) can be satisfied if and only if

 $C_1(\Xi) = 0.$

COROLLARY 1. Assume that $F = \operatorname{spt} \nu$ is admissible then (3.5) and (3.6) hold, where cone S is defined by (3.12).

REFERENCES

- [1] Adams, R. A., Sobolev Spaces, Academic Press, New York (1975).
- [2] Ancona, A., Une propriete des espaces de Sobolev, C. R. Acad. Sc. Paris, t. 292, Serie I. 477-480.
- [3] Brezis, H. and Browder, F., Some properties of higher order Sobolev spaces, J. Math. Pures Appl., 61 (1982), 245-259.
- [4] Coffman, C. V. and Grover, C. L., Obtuse cones in Hilbert spaces and applications to partial differential equations, J. Funct. Anal., 35 (1980), 369-396.
- [5] Haraux, A., How to differentiate the projection on a convex set in Hilbert space, Some applications to variational inequalities, J. Math. Soc. Japan, 29 (1977), 615-631.
- [6] Haug, E. J. and Cea, J. (EDS.), Optimization of Distributed Parameter Structures, Sijthoff and Noordhoff, Alpen aan den Rijn, The Netherlands, (1981).
- [7] Hedberg, L. I., Spectral synthesis in Sobolev spaces, and uniqueness of solutions of Dirichlet problem, Acta Math., **147** (1981), 237–264.
- [8] Mignot, F., Controle dans les inequations variationelles elliptiques, J. Funct. Anal., 22 (1976), 25-39.
- [9] Rao, M. and Sokołowski, J., Sensitivity of unilateral problems in $H_0^2(\Omega)$ and applications, to appear.
- [10] —, Shape sensitivity analysis of state constrained optimal control problems for distributed parameter systems, Lecture Notes in Control and Information Sciences, Vol. 114, Springer Verlag, (1989), 236–245.
- [11] ——, Differential stability of solutions to parametric optimization problems, to appear.
- [12] Sokołowski, J., Differential stability of solutions to constrained optimization problems, Appl. Math. Optim., 13 (1985), 97-115.
- [13] —, Sensitivity analysis of control constrained optimal control problems for distributed parameter systems, SIAM J. Control Optim., 25 (1987), 1542–1556.
- [14] —, Shape sensitivity analysis of boundary optimal control problems for parabolic systems, SIAM J. Control Optim., 26 (1988), 763–787.
- [15] —, Stability of solutions to shape optimization problems. to appear.
- [16] Sokołowski, J. and Zolesio, J. P., Shape sensitivity analysis of unilateral problems. SIAM J. Math. Anal., 18 (1987), 1416–1437.
- [17] , Introduction to Shape Optimization. Shape sensitivity analysis, to appear.
- [18] Zarantonello, F. H., Projections on convex sets in Hilbert space and spectral theory, In: Contributions to Nonlinear Functional Analysis, Publ. No. 27, Math. Res. Center. Univ. Wisconsin, Madison, Academic Press, New York, (1971), 237-424.

- [19] Ziemer, P. W., Weakly Differentiable Functions, Springer Verlag, New York, 1989.
- [20] —, Private communication.

Murali Rao Department of Mathematics University of Florida 201 Walker Hall, Gainesville, FL 32611 USA

Jan Sokolowski Systems Research Institute Polish Academy of Sciences ul. Newelska 6, 01–447 Warszawa Poland