# APPROXIMATE DUAL AND <br> APPROXIMATE VECTOR VARIATIONAL INEQUALITY FOR MULTIOBJECTIVE OPTIMIZATION 

G.-Y. CHEN and B. D. CRAVEN

(Received 12 April 1988; revised 4 July 1988)


#### Abstract

An approximate dual is proposed for a multiobjective optimization problem. The approximate dual has a finite feasible set, and is constructed without using a perturbation. An approximate weak duality theorem and an approximate strong duality theorem are obtained, and also an approximate variational inequality condition for efficient multiobjective solutions.


1980 Mathematics subject classification (Amer. Math. Soc.) (1985 Revision): 90 C 31.

## I. Introduction

Consider the finite dimensional linear space $\mathbf{R}^{p}$, equipped with a partial ordering $\geq_{s}$, defined by a closed pointed convex cone $S$, with interior int $S \neq \varnothing$.

Definition 1 (see [3]). For a given $e \in S$, a point $c \in A \subset \mathbf{R}^{p}$ is said to be an $e$-[weak] minimum of $A$ if there exists no $x \in A$ satisfying $0 \neq c-x-e \in S$ [ $\in \operatorname{int} S$ ]. A point $c \in A$ is said to be an $e$-[weak] maximum if there exists no $x \in A$ such that $0 \neq x-c-d \in S[\in \operatorname{int} S]$. When $e=0$, an $e$-[weak] minimum ( $e$-[weak] maximum) is said to be a [weak] minimum ([weak] maximum). A set $W$ is said to e-upper dominate a set $V$ if

$$
(\forall v \in V)(\exists w \in W) w+e-v \in S
$$

A set $W$ is said to $e$-strongly upper dominate a set $V$ if

$$
(\forall v \in V)(\exists w \in W) w+e-v \in \operatorname{int} S
$$

[^0]The order-interval $[-e, e]:=\left\{x \in \mathbf{R}^{p}: e \geq_{s} x \geq_{s}-e\right\}$. Denote its interior by $(-e, e)$. Denote by $\mathbf{R}^{p \times m}$ the space of all $p \times m$ real matrices $\Lambda$, and by $\|\Lambda\|$ the norm of $\Lambda$ in this space. Let $D \subset \mathbf{R}^{m}$ be a closed convex cone. Let $M:=\left\{\Lambda \in \mathbf{R}^{p \times m}:\|\Lambda\|=1, \Lambda(D) \subset S\right\}$. Then $M$ is compact.

A function $h: C \rightarrow \mathbf{R}^{p}$ is $S$-convex if $C \subset \mathbf{R}^{n}$ is convex, and

$$
(\forall x, y \in C, \forall \alpha \in(0,1)) \quad h(\alpha x+(1-\alpha) y) \leq_{s} \alpha h(x)+(1-\alpha) h(y)
$$

Consider a nonlinear multiobjective optimization problem:

$$
\begin{equation*}
\text { WMin } f(x) \text { subject to } x \in X:=\{x \in E,-g(x) \in D\} \tag{P}
\end{equation*}
$$

where $f: \mathbf{R}^{n} \rightarrow \mathbf{R}^{p}, g: \mathbf{R}^{n} \rightarrow \mathbf{R}^{m}$ are vector functions, $E \subset \mathbf{R}^{n}$, and weak minimum (WMin; and WMax later) are as in Definition 1.

Definition 2. A vector valued Lagrangian for (P) is $L(x, \Lambda):=f(x)+$ $\Lambda g(x)$.

Following Sawaragi, Nakayama and Tanino [1], it will be assumed that
(i) $E$ is nonempty compact,
(ii) $f$ is continuous, and
(iii) $g$ is continuous.

Under these assumptions, it is readily shown that $X$ and $f(X)$ are compact.
Definition 3. The dual map $\boldsymbol{\Phi}: M \rightarrow \mathbf{R}^{p}$ is defined by

$$
\Phi(\Lambda):=\mathbf{W M i n} L(E, \Lambda)
$$

for each $\Lambda \in M$. A dual problem [1] to ( P ) is
( $\mathrm{D}_{\mathrm{TS}}$ )
WMax $\bigcup_{\Lambda \in M} \Phi(\Lambda)$.

Lemma 1. Under the above assumptions, for each $\Lambda \in M$, the sets $L(E, \Lambda)$ and $\Phi(\Lambda)$ are compact.

Proof. Since $E$ is compact, and $f$ and $g$ are continuous, $L(E, \Lambda)$ is compact, for each $\Lambda \in M$. Hence $\Phi(\Lambda)$ is nonempty and bounded. Consider a sequence $\left\{y_{k}\right\} \subset \Phi(\Lambda),\left\{y_{k}\right\} \rightarrow y_{0}$. If $y_{0} \notin \Phi(\Lambda)$ then there exists $v \in L(E, \Lambda)$ such that $y_{0}-v \in \operatorname{int} S$. Since $\left\{y_{k}\right\} \rightarrow y_{0}$, there exists $k_{0} \in \mathcal{N}$ such that $y_{k}-v \in \operatorname{int} S$ when $k \geq k_{0}$, contradicting the weak minimum. So $\Phi(\Lambda)$ is closed, and therefore compact.

Lemma 2. The map $\Phi: M \rightarrow \boldsymbol{R}^{p}$ is upper semicontinuous, and $\Phi(M)$ is compact.

Proof. Let $\left\{\Lambda_{k}\right\} \rightarrow \Lambda_{0}$ in $M,\left\{v_{k}\right\} \rightarrow v_{0},(\forall k) v_{k} \in L\left(E, \Lambda_{k}\right)$. For each $k$, there exists $x_{k} \in E$ such that $v_{k}=L\left(x_{k}, \Lambda_{k}\right)$. Since $E$ is compact, there
is a subsequence $\left\{x_{k_{j}}\right\} \subset\left\{x_{k}\right\}$ such that $\left\{x_{k_{j}}\right\} \rightarrow x_{0} \in E$. Since $f$ and $g$ are continuous, $\left\{v_{k_{j}}\right\} \rightarrow L\left(x_{0}, \Lambda_{0}\right)=v_{0} \in L\left(E, \Lambda_{0}\right)$. Thus the mapping $L(E, \cdot)$ is upper semicontinuous on $M$. To show also lower semicontinuity, let $\left\{\Lambda_{k}\right\} \rightarrow \Lambda_{0}$ in $M$, and let $v_{0} \in L\left(E, \Lambda_{0}\right)$; thus $v_{0}=L\left(x_{0}, \Lambda_{0}\right)$ for some $x_{0} \in E$; then $\left\{v_{k}\right\}:=\left\{L\left(x_{0}, \Lambda_{k}\right)\right\} \rightarrow v_{0}$, and $(\forall k) v_{k} \in L\left(E, \Lambda_{k}\right)$.

Let $\left\{\Lambda_{k}\right\} \rightarrow \Lambda_{0}, \varphi_{k} \in \Phi\left(\Lambda_{k}\right)$ for each $k,\left\{\varphi_{k}\right\} \rightarrow \varphi_{0}$. If $\varphi_{0} \notin \Phi\left(\Lambda_{0}\right)$ then $\varphi_{0}-v_{0} \in \operatorname{int} S$ for some $v_{0} \in L\left(E, \Lambda_{0}\right)$. Since $\left\{\varphi_{k}\right\} \rightarrow \varphi_{0}$, there exists a $k_{0}>0$ such that for each $k \geq k_{0} \varphi_{k}-v_{0} \in$ int $S$. Since $L(E, \cdot)$ is continuous at $\Lambda_{0}$, for each $k$ there exists $v_{k} \in L\left(E_{k}\right)$ such that $\left\{v_{k}\right\} \rightarrow v_{0}$, thus $\varphi_{k}-v_{k} \in \operatorname{int} S$, and thus $\varphi_{k} \notin \mathrm{WMin} L\left(E, \Lambda_{k}\right)$. The contradiction shows that $\Phi$ is upper semicontinuous. Since $M$ is compact, $\Phi(M)$ is compact [6].

Remark. The conclusions of Lemma 1 and Lemma 2 still hold if $\Phi(\Lambda)$ is changed to $e-\operatorname{WMin} L(E, \Lambda)$.

## 2. Approximate dual

We now introduce an approximate dual for the multiobjective problem $(\mathrm{P})$. No perturbation map is required.

Lemma 3. Let $A \subset \mathbf{R}^{p}$ be compact, and $e \in \operatorname{int} S$. Then there exists a finite subset $K \subset A$ such that $K$ e-strongly upper dominates $A$.

Proof. The family of open order intervals $\{(a-e, a+e): a \in A\}$ covers $A$, so there exists a finite subfamily $\left\{\left(a_{i}-e, a_{i}+e\right): i=1,2, \ldots, k\right\}$ which covers $A$. Let $K=\left\{a_{1}, a_{2}, \ldots, a_{k}\right\}$. If $a \in A$, then $a \in\left(a_{i}-e, a_{i}+e\right)$ for some $i$, and $a_{i}+e-a \in \operatorname{int} S$; thus $K \varepsilon$-strongly upper dominates $A$.

Remark. Similar results hold with upper replaced by lower.
Since $f$ is continuous and $X$ is compact, $f(X)$ is compact. By Lemma 3, there exists a finite subset $U \subset f(X)$, such that $U e$-strongly lower dominates $f(X)$, and thus $(\forall v \in f(X))(\exists u \in U) u-e-v \in-\operatorname{int} S$. So a primal approximate problem may be defined as

WMin $U$.
For each $\Lambda \in M$, define $\Phi^{*}(\Lambda)$ to be the set of $e$-weak minima of $L(E, \Lambda)$. Then $\Phi^{*}(\Lambda) \neq \varnothing$. Set $Q:=\bigcup_{\Lambda \in M} \Phi^{*}(\Lambda)$. By Lemma 2 , the set $Q$ is compact. By Lemma 3, there exists a finite subset $W \subset Q$ such that $(\forall q \in Q)(\exists w \in W)$ $w-e-q \in-S$. So an approximate dual problem may be defined as
(D*) WMax $W$.
Two obvious corollaries follow.

Corollary 1. If $u_{0}$ is a weak minimum of $\left(\mathrm{P}^{*}\right)$, then $u_{0}$ is an e-weak minimum of $(\mathrm{P})$.

Proof. If not, then there exists $v \in f(X)$ such that $u_{0}-v-e \in \operatorname{int} S$. But, given $v \in f(X)$, there exists $u^{\prime} \in U$ with $u^{\prime}-v-e \in-$ int $S$. Combining these, $u_{0}-u^{\prime} \in$ int $S$, contradicting the weak minimum.

Corollary 2. If $w_{0}$ is a weak maximum of $\left(\mathrm{D}^{*}\right)$ then $w_{0}$ is an e-weak maximum of $\left(\mathrm{D}_{\mathrm{TS}}\right)$.

Proof. If not, then there exists $v \in \Phi^{*}(M)$ such that $v-\left(w_{0}+e\right)=\operatorname{int} S$. Given this $v$, there exists $w^{\prime} \in W$ such that $w^{\prime}+e-v \in \operatorname{int} S$. Combining these, we obtain $w^{\prime}-w_{0} \in$ int $S$, contradicting the weak maximum.

Theorem 1 (approximate weak duality). For each $u \in U$ and each $w \in W, w-u-e \notin S \backslash\{0\}$.

Proof. If $w \in W$, then $w \in \Phi^{*}(\Lambda)$ for some $\Lambda \in M$. Then

$$
(\forall x \in X) w-e-[f(x)+\Lambda g(x)] \in H:=\mathbf{R}^{p} \backslash \operatorname{int} S .
$$

Theorem 2 (approximate strong duality). Let $x^{*} \in X$ and $\Lambda^{*} \in M$ satisfying $w^{*}:=f\left(x^{*}\right) \in \Phi^{*}\left(\Lambda^{*}\right) \cap U \cap W$. Then $x^{*}$ is an $e$-weak minimum of $f(X)$, and $w^{*}$ is an $e$-weak maximum of $\Phi(M)$.

Proof. If $x^{*}$ is not an $e$-weak minimum of $f(X)$, then there exists $x \in X$ such that $f\left(x^{*}\right)-e-f(x) \in \operatorname{int} S$. Since $f\left(x^{*}\right) \in W$ and $\Lambda^{*} g\left(x^{*}\right) \in-S$, it follows that $f\left(x^{*}\right)-e-\left[f(x)+\Lambda^{*} g(x)\right] \in \operatorname{int} S$, contradicting $f\left(x^{*}\right) \in$ $\Phi^{*}\left(\Lambda^{*}\right)$.

If $w^{*}=f\left(x^{*}\right)$ is not an $e$-weak maximum of $\Phi(M)$, there is $w \in \bigcup_{\Lambda \in M} \Phi(\Lambda)$ such that $w-f\left(x^{*}\right)-e \in \operatorname{int} S$. Now $w=\Phi(\Lambda)$ for some $\Lambda \in M$. Since $\Lambda g\left(x^{*}\right) \in-S, w-\left[f\left(x^{*}\right)+\Lambda g\left(x^{*}\right)+e\right] \in \operatorname{int} S$, and hence $w$ is not an $e$-weak maximum of $L(E, \Lambda)$.

## 3. Approximate vector variational inequality

Let $C \in \mathbf{R}^{n}$ be a nonempty convex set, $S \subset \mathbf{R}^{p}$ a closed convex cone with int $S \neq \varnothing$, and $f: C \rightarrow \mathbf{R}^{p}$ a vector valued function. Denote by $\mathrm{L}\left(\mathbf{R}^{n}, \mathbf{R}^{p}\right)$ the space of all linear mappings from $\mathbf{R}^{n}$ into $\mathbf{R}^{n}$. Let $G: C \rightarrow \mathbf{L}\left(\mathbf{R}^{n}, \mathbf{R}^{p}\right)$ be a mapping. A generalized vector variational inequality is the problem of finding $x_{0} \in C$ and $A \in G\left(x_{0}\right)$ such that

$$
(\forall x \in C) A\left(x-x_{0}\right) \notin-\operatorname{int} S
$$

Theorem 3. Let $C \subset \mathbf{R}^{n}$ be compact convex; let $S \subset \mathbf{R}^{p}$ be a closed convex pointed cone with int $S \neq \varnothing$; let $f: C \rightarrow \mathbf{R}^{p}$ be $S$-convex, (Fréchet) continuously differentiable at $x_{0} \in C$, and differentiable on $C$; let $x_{0}$ be a weak minimum of $f(x)$ subject to $x \in C$. Then, for each $e \in$ int $S$, there exists a finite subset $W \subset C$ such that $(\forall w \in W) f^{\prime}\left(x_{0}\right)\left(w-x_{0}\right)+e \notin-i n t S$.

Proof. Since $C$ is a compact convex, and $f^{\prime}\left(x_{0}\right)$ is a continuous linear mapping, $K:=f^{\prime}\left(x_{0}\right)\left(C-x_{0}\right)$ is compact convex. By Lemma 3, for each $e \in$ int $S$, there exists a finite subset $W^{\prime} \subset C$ such that, for each $x \in C$, there is $w_{x} \in W^{\prime}$ such that $\left[f^{\prime}\left(x_{0}\right)\left(w_{x}-x_{0}\right)+e\right]-f^{\prime}\left(x_{0}\right)\left(x-x_{0}\right) \in S$. Denote by $W$ the finite subset $\left\{w_{x} \in W^{\prime}: x \in C\right\}$. From [2, Theorem 4], since $f$ is $S$-convex, $(\forall x \in C) f^{\prime}\left(x_{0}\right)\left(x-x_{0}\right) \notin$-int $S$. Let $Q:=\mathbf{R}^{p} \backslash(-$ int $S)$. Then $f^{\prime}\left(x_{0}\right)\left(w_{x}-x\right)+e \in S+Q \subset Q$. Hence $(\forall w \in W) f^{\prime}\left(x_{0}\right)\left(w-x_{0}\right)+e \notin$-int $S$.

Since $f^{\prime}(x)(C-x)$ is compact convex, for each $x \in C$, Lemma 3 shows that, for each $x \in C$ and each $e \in$ int $S$, there exists a finite subset $M(x) \subset$ $f^{\prime}(x)(C-x)$ such that $\left(\forall m \in f^{\prime}(x)(C-x)\right)\left(\exists m^{\prime} \in M(x)\right) m-\left[m^{\prime}-e\right] \in S$. For each $x \in C$ and each $m^{\prime} \in M(x)$, let $u \equiv u\left(x, m^{\prime}\right)$ be an element of $C$ such that $f^{\prime}(x)(u-x) \in M(x)$; denote by $U(x)$ the finite set $\left\{u\left(x, m^{\prime}\right): m^{\prime} \in\right.$ $M(x)\}$.

Consider now the generalized inequality system, for $x \in C$ :

$$
\begin{equation*}
(\forall u \in U(x)) f^{\prime}(x)(u-x)-e \notin-\operatorname{int} S . \tag{GI}
\end{equation*}
$$

Theorem 4. Let $f: C \rightarrow \mathbf{R}^{p}$ be $S$-convex and continuously differentiable on $C$, where $C \subset \mathbf{R}^{n}$ is a compact convex set; let $e \in \operatorname{int} S$. If $x_{0}$ is a solution (GI), then $x_{0}$ is a weak minimum of $f(x)$ subject to $x \in C$.

Proof. Since $f$ is $S$-convex and differentiable, $(\forall x \in C) f(x)-f\left(x_{0}\right)-$ $f^{\prime}\left(x_{0}\right)\left(x-x_{0}\right) \in S$. Since $f^{\prime}(x)(C-x)$ is compact, Lemma 3 shows that, for each $x \in C$, there exists $u \in U\left(x_{0}\right)$ such that

$$
f^{\prime}\left(x_{0}\right)\left(x-x_{0}\right)-\left[f^{\prime}\left(x_{0}\right)\left(u-x_{0}\right)-e\right] \in S .
$$

Since $x_{0}$ is a solution of $(\mathrm{GI}), f^{\prime}\left(x_{0}\right)\left(u-x_{0}\right) \in Q$, where $Q:=\mathbf{R}^{p} \backslash(-$ int $S)$. Adding these inclusions, $f(x)-f\left(x_{0}\right) \in S+S+Q \subset Q$. Thus $x_{0}$ is a weak minimum of $f(x)$ subject to $x \in C$.

## Acknowledgement

The authors thank a referee for careful checking and useful comments.

## References

[1] Y. Sawaragi, H. Nakayama and T. Tanino, Theory of Multiobjective Optimization, (Math. Sci. Engrg., vol. 176, Academic Press, New York, 1985, 137-138).
[2] G.-Y. Chen and B. D. Craven, 'A vector variational inequality and optimization over an efficient set' Z. Oper. Res. (to appear).
[3] P. Loridan, ' $\varepsilon$-solutions in vector minimization problems', J. Optim. Theory Appl. 43 (1984), 265-276.
[4] J. Vályi, 'Approximate saddle-point theorems in vector optimization', J. Optim. Theory Appl. 55 (1987), 436-448.
[5] P. L. Yu, 'Cone convexity, cone extreme points, and nondominated solutions in decision problems with multiobjectives', J. Optim. Theory Appl. 14 (1974), 318-323.
[6] C. Berge, Topological Spaces, (Macmillan, New York, 1963).

Academia Sinica
Institute of Systems Science
Beijing 100080
China

Mathematics Department
University of Melbourne Parkville, Victoria 3052

Australia


[^0]:    (c) 1989 Australian Mathematical Society $0263-6115 / 89 \$ A 2.00+0.00$

