# TWO REMARKS ON EXTREME FORMS 

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1. Introduction. The following remarks concern two different parts of the theory of extreme quadratic forms. In §2, I shall give a new proof for the theorem of Voronoi (4), which asserts that a form is extreme if and only if it is both perfect and eutactic. (For the definitions see, e.g., Coxeter (2) or the text below.) There is indeed a comparatively simple proof in Bachmann's Zahlentheorie, IV, 2. For two reasons, however, it may not be useless to communicate another proof here. First, I shall prove the necessity and the sufficiency in one step, and second, as a consequence, my proof requires a minimum of calculation. In $\S 3$, I shall add a new senary extreme form to Hofreiter's list (3) and Coxeter's paper (2). This form was found independently by Barnes (see the succeeding paper (1)). I therefore restrict myself to determining its group of automorphs, which is not done in Barnes's paper.
2. Voronoi's theorem. In this section, we denote: real symmetric ( $n \times n$ )-matrices by capital letters $A, B, \ldots$, the $\frac{1}{2} n(n+1)$-dimensional space of these matrices by $R$; vectors, considered as ( $n \times 1$ )-matrices, by small letters $x, y, \ldots$; the transposition of a matrix by a prime, and real numbers by Greek letters. Let $x^{\prime} A x$ be a positive definite quadratic form, and $\mu(A)$ the minimum of $x^{\prime} A x$ taken over all $x$ with integer coordinates not all 0 . This minimum is attained at a finite number of vectors, called minimal vectors; for these we shall reserve the letter $m$. The form $x^{\prime} A x$ is called extreme if the quotient

$$
\delta(B)=\mu(B) \operatorname{det}(B)^{-1 / n}
$$

has a local maximum at $B=A$, i.e., if $\delta(A+C) \leqslant \delta(A)$ for all matrices $C \in R$ whose elements are sufficiently small. Since $\delta(\lambda B)=\delta(B)$, we may restrict $C$ to a hyperplane through the origin not containing $A$, e.g. the hyperplane $H$ of $R$ defined by $\operatorname{tr}\left(A^{-1} C\right)=0$. Continuity shows that, for small $C, A+C$ is positive definite and the minimal vectors of $A+C$ are contained among those of $A$. Hence $\delta(A+C) \leqslant \delta(A)$ means that for at least one minimal vector $m$ of $A$, the inequality

$$
\begin{equation*}
m^{\prime}(A+C) m \cdot \operatorname{det}(A+C)^{-1 / n} \leqslant m^{\prime} A m \cdot \operatorname{det}(A)^{-1 / n} \tag{1}
\end{equation*}
$$

holds; or, what is the same, the union of the regions $K_{m}$ of $C$ 's such that $A+C$ is positive definite and (1) holds, contains a neighbourhood of the origin $O$ in $R$; or, finally
(a) $\mathrm{U}_{m} H \cap K_{m} \quad$ contains a neighbourhood of $O$ in $H$.

Now, the following lemma shows that $K_{m}$ is convex and $H \cap K_{m}$ is strictly convex.

Lemma. Let $m$ be a fixed vector and $\lambda>0$. The set $K$ of positive definite symmetric matrices $C$ satisfying the inequality $m^{\prime} C m \leqslant \lambda \operatorname{det}(C)^{1 / n}$ is a convex cone with its vertex at the origin $O$. If $H$ is a hyperplane not containing $O, H \cap K$ is strictly convex (i.e., if $C$ and $D$ are in $H \cap K$ and if $0<\tau<1$, then $\tau C+(1-\tau) D$ is an inner point of $H \cap K)$.

Proof. We have to show that if $C$ and $D$ are in $K$, so is $\tau C+(1-\tau) D$, and that the latter is an inner point unless $D=\kappa C$. Since $K$ obviously is a cone, we may replace $D$ by a scalar multiple and so may assume

$$
m^{\prime} C m=m^{\prime} D m=m^{\prime}(\tau C+(1-\tau) D) m
$$

It remains to prove that the inequalities

$$
\operatorname{det}(C)^{1 / n} \geqslant \mu=m^{\prime} C m \cdot \lambda^{-1}, \quad \operatorname{det}(D)^{1 / n} \geqslant \mu
$$

imply $\operatorname{det}(\tau C+(1-\tau) D)^{1 / n} \geqslant \mu$ with equality only if $D=C$. This is well known. It is proved by transforming $C$ and $D$ simultaneously to diagonal form and then applying the inequality

$$
\prod_{i=1}^{n}\left(\tau \gamma_{i}+(1-\tau) \delta_{i}\right)^{1 / n} \geqslant \tau \prod_{i=1}^{n} \gamma_{i}^{1 / n}+(1-\tau) \prod_{i=1}^{n} \delta_{i}^{1 / n}
$$

Moreover, $K_{m}$ possesses a tangent hyperplane at the origin. This will be shown by developing (1) into a power-series in the elements of $C$ and taking the linear terms only. In point of fact, write (1) in the form

$$
1+m^{\prime} C m \mu(A)^{-1} \leqslant \operatorname{det}\left(E+A^{-1} C\right)^{1 / n}
$$

For the half-space determined by the tangent hyperplane and containing $K_{m}$, we then obtain the linear inequality

$$
m^{\prime} C m \mu(A)^{-1} \leqslant \frac{1}{n} \operatorname{tr}\left(A^{-1} C\right)
$$

Restricting $C$ to $H$, we obtain

$$
l_{m}(C)=m^{\prime} C m \leqslant 0
$$

Next we show that (a) is equivalent to
(b) The half-spaces $l_{m}(C)<0$ cover the whole space $H$ except $O$.

First suppose (a) holds. Let $C \neq O$ be any point of $H$. It follows from (a) that there exist an $m$ and a $\lambda>0$ such that $\lambda C$ is in $L_{m}=H \cap K_{m}$. Since $L_{m}$ is strictly convex, $\mu C$ is an inner point of $L_{m}$ if $0<\mu<\lambda$, and thus

$$
l_{m}(C)=\mu^{-1} l_{m}(\mu C)<0
$$

which proves (b). Conversely, suppose (b) holds. Let $S$ be the unit sphere in $H$. For every $C \in S$ there is an $m$ with $l_{m}(C)<0$. Since $l_{m}=0$ is the tangent hyperplane of $L_{m}$ at $O$, there exists a $\lambda>0$ such that $\lambda C$ is an inner point of
$L_{m}$. Then there is a neighbourhood $U$ of $C$ on $S$ such that $\mu D \in L_{m}$ for every $D \in U$ and $0<\mu \leqslant \lambda$. As $S$ is compact, it is covered by a finite number of $U$ 's. Denote by $\lambda_{0}$ the minimum of the corresponding $\lambda$ 's. Then the solid sphere of radius $\lambda_{0}$ is contained in $\bigcup_{m} L_{m}$, which proves (a). Transforming (b) into a statement about the complementary half-spaces $l_{m}(C) \geqslant 0$, we get
(c) $O$ is the only point of $H$ common to all the half-spaces $l_{m}(C) \geqslant 0$.

Now, let $H^{\prime}$ be the space of linear forms on $H$, and $M \subset H^{\prime}$ the convex set generated by $O$ and the $l_{m}$. Since the elements $l$ of any hyperplane in $H^{\prime}$ passing through the origin satisfy an equation $l(C)=0$ with some fixed $C \neq O$, the statement (c) means that there is no hyperplane through $O$ in $H^{\prime}$ leaving $M$ on one side. Since $M$ is convex, a neighbourhood of $O$ in $H^{\prime}$ is contained in $M$. This assertion can be divided into two parts. First, $H^{\prime}$ is the linear space generated by $M$, i.e., $M$ is not contained in any hyperplane in $H^{\prime}$. This means that there is no hyperplane passing through $O$ and the $l_{m}$. Second, $O$ is an inner point of $M$ relative to the linear space generated by $M$, i.e., there are numbers $\rho_{0}, \rho_{m}>0$ with sum 1 , such that $O=\rho_{0} . O+\sum_{m} \rho_{m} l_{m}$. We may multiply this equation by an arbitrary positive number, and so the condition that the sum of the coefficients is 1 may be dropped. We have the following two statements which, together, are equivalent to (c).
(d) The equations $l_{m}(C)=0$ have no common solution $C \neq O$ in $H$.
(e) There exist positive numbers $\rho_{m}$ such that $\sum_{m} \rho_{m} l_{m}(C)=0$ for all $C$ in $H$.
Since $H$ is defined by $\operatorname{tr}\left(A^{-1} C\right)=0$, (e) is equivalent to

$$
\begin{equation*}
\sum_{m} \rho_{m} m^{\prime} C m=\sigma \operatorname{tr}\left(A^{-1} C\right) \quad \text { for all } C \text { in } R \tag{2}
\end{equation*}
$$

with some constant $\sigma$. Putting $C=A$ we get $\sigma>0$. If $C=x . x^{\prime}$ we obtain

$$
\begin{equation*}
\sum_{m} \rho_{m}\left(m^{\prime} x\right)^{2}=\sigma \operatorname{tr}\left(A^{-1} x x^{\prime}\right)=\sigma \operatorname{tr}\left(x^{\prime} A^{-1} x\right)=\sigma x^{\prime} A^{-1} x \tag{3}
\end{equation*}
$$

This means that $A$ is eutactic. Conversely (2) follows from (3), since every symmetric matrix $C$ is a linear combination of matrices of the type $x x^{\prime}$ (this is nothing else than the well-known theorem that every quadratic form is a linear combination of squares of linear forms). Finally, (d) and (e) also imply that the equations $m^{\prime} C m=0$ have no common solution in $R$, except $C=O$. For, if C is a solution, (2) implies $C \in H$ and then $C=O$ according to (d). This means that $A$ is perfect and so we have proved

Voronoi's Theorem. A positive definite quadratic form is extreme if and only if it is both perfect and eutactic.
3. The new senary extreme form. The senary form

$$
x^{\prime} A x=\sum_{i=1}^{3}\left(x_{i}^{2}-x_{i} x_{i+3}+x_{i+3}^{2}\right)+\left(\sum_{i=1}^{6} x_{i}\right)^{2}
$$

with the matrix

$$
A=\left(\begin{array}{llllll}
2 & 1 & 1 & \frac{1}{2} & 1 & 1 \\
1 & 2 & 1 & 1 & \frac{1}{2} & 1 \\
1 & 1 & 2 & 1 & 1 & \frac{1}{2} \\
\frac{1}{2} & 1 & 1 & 2 & 1 & 1 \\
1 & \frac{1}{2} & 1 & 1 & 2 & 1 \\
1 & 1 & \frac{1}{2} & 1 & 1 & 2
\end{array}\right)
$$

has determinant $2^{-6} .3^{3} .13$ and minimum 2. There are 21 pairs $\pm m_{i}$ of minimal vectors. First, the pairs $\pm m_{i}(i=1, \ldots, 6)$ of unit vectors with $i$ th coordinate $\pm 1$, all others 0 ; second, 12 pairs $\pm m_{i}(i=7, \ldots, 18)$ with $x_{k}=1, x_{i}=-1$ $(k \equiv l \bmod 3)$ and $x_{j}=0$ if $j \neq k, l$; third, three pairs $\pm m_{i}(i=19,20,21)$ with coordinates obtained from $x_{1}=x_{4}=1, x_{2}=x_{5}=-1, x_{3}=x_{6}=0$ by permuting the values $1,-1,0$. That $A$ is perfect is seen by an easy calculation. That it is eutactic follows from the identity

$$
\begin{equation*}
39 y^{\prime} A y=6 \sum_{i=1}^{6}\left(m_{i}^{\prime} A y\right)^{2}+5 \sum_{i=7}^{18}\left(m_{i}^{\prime} A y\right)^{2}+7 \sum_{i=19}^{21}\left(m_{i}^{\prime} A y\right)^{2} \tag{4}
\end{equation*}
$$

which, by the substitution $y=A^{-1} x$, yields a formula of type (3). The representation (4) of $y^{\prime} A y$ as a linear combination of the squares of the linear forms $m_{i}^{\prime} A y$ is unique. This fact is important for the determination of the group of automorphs of $A$, i.e., of those unimodular matrices $U$ which transform $A$ into itself: $U^{\prime} A U=A$. At the first glance there is a group $G$ of 48 automorphs, namely those permutations of the variables $x_{i}$, which change each pair $\left(x_{i}, x_{i+3}\right)$ into a pair of the same kind. We shall show that $G$ combined with $\pm E$ is the whole group of automorphs of $A$. Obviously every $U$ permutes the minimal vectors and preserves the scalar products $m_{i}^{\prime} A m_{k}$. Now $U$ transforms the representation (4) into another of the same kind, with $U m_{i}$ instead of $m_{i}$. Since (4) is unique and the first coefficient, 6 , is different from the two others, 5 and $7, U$ permutes the pairs $\pm m_{i}(i=1, \ldots, 6)$ amongst each other. This permutation is such that any quadruple $\pm m_{i}$, $\pm m_{i+3}$ changes into one of the same kind, because $m_{i}^{\prime} A m_{k}=1$ or $\neq 1$ according as $i \not \equiv k$ or $i \equiv k \bmod 3$. Hence we can write every automorph as a product of an element of $G$ by an automorph $V$ with $V m_{i}= \pm m_{i}(i=1, \ldots, 6)$. As $m_{i}^{\prime} A m_{k} \neq 0$, the sign must be the same for all $i$ and so $V= \pm E$. Therefore the total group of automorphs is the direct product of $G$ and the cyclic group $\pm E$ of order two.

As we have seen, the group of automorphs is not transitive on the minimal vectors, contrary to most other known extreme forms (2), nor is it irreducible. The irreducible subspaces are: One of dimension one, generated by

$$
\sum_{i=1}^{6} m_{i} ;
$$

one of dimension two, generated by $m_{19}, m_{20}, m_{21}$; one of dimension three, generated by $n_{1}=m_{1}-m_{4}, n_{2}=m_{2}-m_{5}, n_{3}=m_{3}-m_{6}$. The representation
of $G$ in the third subspace is isomorphic. $G$ induces all transformations of the form $n_{i} \rightarrow \pm n_{k}, i \rightarrow k$ being any permutation and $\pm$ any combination of signs. So $G$ is isomorphic to the extended octahedral group. This completes the determination of the structure of the group of automorphs.

## References

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