# MULTIPLE SOLUTIONS FOR A CLASS OF QUASILINEAR ELLIPTIC PROBLEMS 

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Abstract We deal with a class of $p$-Laplacian Dirichlet boundary-value problems where the combined effects of 'sublinear' and 'superlinear' growths allow us to establish the existence of at least two positive solutions.

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## 1. Introduction

The objective of this paper is to establish the existence of two radial solutions for the quasilinear boundary-value problem

$$
\left.\begin{array}{rl}
-\Delta_{p} u=f(u) & \text { in } \Omega  \tag{1.1}\\
u>0 & \text { in } \Omega \\
u=0 & \text { on } \partial \Omega,
\end{array}\right\}
$$

where $\Omega \subset \mathbb{R}^{N}$ is a ball of radius $b$, and where $\Delta_{p} u=\operatorname{div}\left(|\nabla u|^{p-2} \nabla u\right)$ is the $p$-Laplacian with $1<p<N$. We will assume that the function $f:[0,+\infty) \rightarrow[0,+\infty)$ is a given continuous function satisfying $f(0)=0$ and the following two conditions:
$\left(\mathrm{H}_{1}\right) \lim _{t \rightarrow 0} f(t) / t^{p-1}=+\infty$, and
$\left(\mathrm{H}_{2}\right) \lim _{t \rightarrow+\infty} f(t) / t^{p-1}=+\infty$.
It follows from assumptions $\left(\mathrm{H}_{1}\right)$ and $\left(\mathrm{H}_{2}\right)$ that there exists $R>0$ such that

$$
\frac{f(R)}{R^{p-1}}=\min _{t>0} \frac{f(t)}{t^{p-1}}
$$

Let $\bar{R}$ be a point where $f$ attains its maximum on the interval $(0, R]$. We will assume the following two further conditions:
$\left(\mathrm{H}_{3}\right) f(\bar{R}) / \bar{R}^{p-1}<\eta=(p /(p-1))^{p-1} N / b^{p}$, and
$\left(\mathrm{H}_{4}\right)$ there exist increasing functions $g_{1}, g_{2} \in C([0,+\infty),[0,+\infty))$ and positive constants $\delta, \eta$, with $\delta \in(0,1)$, such that for all $t>0$,

$$
\begin{aligned}
& g_{2}(t) \leqslant \eta g_{1}(\delta t) \\
& g_{1}(t) \leqslant f(t) \leqslant g_{2}(t)
\end{aligned}
$$

Our main result is Theorem 1.1, which will be proved in $\S 3$ using fixed-point techniques.
Theorem 1.1. Under the assumptions $\left(\mathrm{H}_{1}\right)-\left(\mathrm{H}_{4}\right)$, problem (1.1) has at least two radial solutions.

Our study was motivated by some recent work on elliptic problems with concaveconvex nonlinearities (see $[\mathbf{1}-\mathbf{3}, \mathbf{9}, \mathbf{1 1}, \mathbf{1 2}]$ ). Ambrosetti et al. [1] study the second-order elliptic problem

$$
\left.\begin{array}{cl}
-\Delta u=\lambda u^{s}+u^{r} & \text { in } \Omega  \tag{1.2}\\
u>0 & \text { in } \Omega \\
u=0 & \text { on } \partial \Omega,
\end{array}\right\}
$$

where $\Omega$ is a bounded domain in $\mathbb{R}^{N}$ (for $N \geqslant 3$ ) with smooth boundary $\partial \Omega, \Delta$ is the Laplace operator, $\lambda$ is a positive real parameter, and $0<s<1<r$. They prove that there exists a positive real constant $\Lambda$ such that, for all $0<\lambda<\Lambda$, the problem (1.2) has a solution, which is found using subsolution as well as supersolution methods. Here the essential term is $u^{s}$, while the exponent $r$ may be arbitrary. Using variational methods, a second solution of (1.2) is found. In this case, the term $u^{r}$ plays a fundamental role, where $r$ must satisfy $r \leqslant(N+2) /(N-2)$. Among others, the following question is left open. Suppose that $r>(N+2) /(N-2)$ and that $\Omega$ is a ball. Does the problem (1.2) have two positive solutions for $\lambda$ small enough? In [12], it is proved that the assertion is true.

Difficulties arise while extending the study of the problem (1.2) to the $p$-Laplacian operator. Many known techniques and results for the Laplacian no longer apply for the $p$-Laplacian due to its nonlinear nature. Using a radial setting, a priori estimates and topological arguments, Ambrosetti et al. [2] obtained a global multiplicity result for elliptic problems of the form

$$
\left.\begin{array}{rlrl}
-\Delta_{p} u & =\lambda u^{s}+u^{r} & & \text { in } \Omega  \tag{1.3}\\
u>0 & & \text { in } \Omega \\
u & =0 & & \text { on } \partial \Omega .
\end{array}\right\}
$$

More precisely, they prove that there is $\Lambda>0$ such that there exist at least two positive solutions of the problem (1.3) in the interval $(0, \Lambda)$, where $\Omega$ is a ball and $0<s<$ $p-1<r<p^{*}=N p /(N-p)$, with $p<N$. In [3], the critical case considering the
following restrictive assumptions on $p$ is studied: $2 N /(N+2)<p<3$ or $p \geqslant 3$ and $p-1>s>\left(p^{*}+1\right)-2 /(p-1)$. Related results may be found in $[\mathbf{4}, \boldsymbol{8}]$. For global multiplicity results on a general bounded domain in the subcritical case, see [9]. When $1 \leqslant s<p-1<r \leqslant p^{*}-1$, which includes the critical case, see [11].

Observe that we improve those results for the $p$-Laplacian operator which involve concave and convex nonlinearities because we impose restrictions neither on $p \in(1, N)$ nor on the growth of the nonlinearities, which may be subcritical, critical or supercritical. Note that the nonlinearities we consider are sublinear at 0 and superlinear at $+\infty$, and hence they contain the concave and convex nonlinearities above. We point out that our result is an improvement even in the case studied in [12] because we consider more general nonlinearities. For instance, let $g_{1}(t)=a_{1} t^{s}+b_{1} t^{r} \leqslant g_{2}(t)=a_{2} t^{s}+b_{2} t^{r}$, where $0<s<p-1<r$, and where $a_{1}, b_{1}, a_{2}$ and $b_{2}$ are positive constants. Assume that $g_{1}(t)=a_{1} t^{s}+b_{1} t^{r} \leqslant f(t) \leqslant g_{2}(t)=a_{2} t^{s}+b_{2} t^{r}$. It is easy to see that $f$ satisfies the hypotheses of Theorem 1.1. Finally, note that, in [6], De Figueiredo and Lions studied the Laplacian operator with subcritical nonlinearities that satisfy a sublinearity condition at 0 and a superlinearity condition at $+\infty$.

The paper is organized as follows: $\S 2$ contains preliminary results and $\S 3$ is devoted to proving our main result, Theorem 1.1.

## 2. Preliminary results

We will establish radial solutions of the problem (1.1). In fact, we will obtain solutions $u=u(r)$ of the ordinary equation

$$
\left.\begin{array}{rlrl}
-\left(r^{N-1} \phi\left(u^{\prime}\right)\right)^{\prime} & =r^{N-1} f(u) & & \text { in }(0, b),  \tag{2.1}\\
u & >0 & & \text { in }(0, b), \\
u(b) & =u^{\prime}(0)=0, & &
\end{array}\right\}
$$

where $\phi(t)=|t|^{p-2} t$. Performing the change of variable $t=a(r)$, define $z(t)=u(r(t))$, where $a:[0, b) \rightarrow[0,+\infty)$ is given by

$$
a(r)=\frac{p-1}{N-p}\left[r^{(p-N) /(p-1)}-b^{(p-N) /(N-1)}\right]
$$

Thus (2.1) can be rewritten as

$$
\left.\begin{array}{rlrl}
-\left(\phi\left(z^{\prime}(t)\right)\right)^{\prime} & =r^{(N-1) p /(p-1)}(t) f(z(t)) & & \text { in }(0,+\infty)  \tag{2.2}\\
z & >0 & & \text { in }(0,+\infty), \\
z(0) & =z^{\prime}(+\infty)=0 . & &
\end{array}\right\}
$$

Integrating (2.2) and using the boundary conditions we obtain

$$
\phi\left(z^{\prime}(t)\right)=\int_{t}^{+\infty} r^{(N-1) p /(p-1)}(\tau) f(z(\tau)) \mathrm{d} \tau
$$

which is equivalent to

$$
z^{\prime}(t)=\left[\int_{t}^{+\infty} r^{(N-1) p /(p-1)}(\tau) f(z(\tau)) \mathrm{d} \tau\right]^{1 /(p-1)}
$$

Integrating once again we obtain

$$
\begin{equation*}
z(t)=\int_{0}^{t}\left[\int_{s}^{+\infty} G(\tau) f(z(\tau)) \mathrm{d} \tau\right]^{1 /(p-1)} \mathrm{d} s \tag{2.3}
\end{equation*}
$$

where

$$
\begin{equation*}
G(\tau)=\left(b^{(p-N) /(p-1)}+\tau \frac{N-p}{p-1}\right)^{p(1-N) /(N-p)} \tag{2.4}
\end{equation*}
$$

Consequently, we will solve (2.1) using fixed-point techniques. For this, we state the following well-known abstract result without proof (cf. [5, 7, 10]).

Lemma 2.1. Let $X$ be a Banach space with norm $|\cdot|$, and let $K \subset X$ be a cone in $X$. For $r>0$, define $K_{r}=K \cap B[0, r]$, where $B[0, r]=\{x \in X:|x| \leqslant r\}$ is the closed ball of radius $r$ centred at the origin of $X$. Assume that $F: K_{r} \rightarrow K$ is a compact map such that $F x \neq x$, for all $x \in \partial K_{r}=\{x \in K:|x|=r\}$.

Then the following assertions hold.
(1) If $|x| \leqslant|F x|$ for all $x \in \partial K_{r}$, then $\imath\left(F, K_{r}, K\right)=0$.
(2) If $|x| \geqslant|F x|$ for all $x \in \partial K_{r}$, then $\imath\left(F, K_{r}, K\right)=1$.

Now we consider the space

$$
X=\{z:[0,+\infty) \rightarrow \mathbb{R}: z \text { is a bounded, continuous function }\}
$$

endowed with the norm $|z|_{\infty}=\sup \{|z(t)|: t \in[0,+\infty)\}$. Let $A: K_{1} \rightarrow X$ be the operator defined by

$$
\begin{equation*}
(A z)(t)=\int_{0}^{t}\left[\int_{s}^{+\infty} G(\tau) f(z(\tau)) \mathrm{d} \tau\right]^{1 /(p-1)} \mathrm{d} s \tag{2.5}
\end{equation*}
$$

where $K_{1}$ is the cone defined by

$$
K_{1}=\{z \in X: z \text { is non-negative, concave and } z(0)=0\}
$$

Note that the elements of $K_{1}$ are increasing functions.
Lemma 2.2. $A$ is well defined, $A\left(K_{1}\right) \subset K_{1}$, and $A$ is a completely continuous operator.

Proof. For all $s \geqslant 0$, note that

$$
\int_{s}^{+\infty} G(\tau) \mathrm{d} \tau=\frac{1}{N} G(s)^{N(p-1) / p(N-1)}
$$

and that

$$
\int_{0}^{+\infty}\left[\int_{s}^{+\infty} G(\tau) \mathrm{d} \tau\right]^{1 /(p-1)} \mathrm{d} s=\eta^{1 /(1-p)}
$$

Hence $A$ is well defined.
Also, note that the function $(A z)(t)$ is of class $C^{2}$, whose derivatives are given by

$$
\begin{aligned}
\frac{\mathrm{d}}{\mathrm{~d} t}(A z)(t) & =\left[\int_{t}^{+\infty} G(\tau) f(z(\tau)) \mathrm{d} \tau\right]^{1 /(p-1)} \\
\frac{\mathrm{d}^{2}}{\mathrm{~d} t^{2}}(A z)(t) & =\frac{1}{1-p} G(t)\left[\frac{\mathrm{d}}{\mathrm{~d} t}(A z)(t)\right]^{p-2} f(z(t))
\end{aligned}
$$

Thus $(A z)(t)$ is increasing and concave. Therefore, $A\left(K_{1}\right) \subset K_{1}$.
It remains to prove that $A$ is a completely continuous operator. Let $\left|z_{n}\right|_{\infty} \leqslant C_{0}$, and let $M_{1}=\max \left\{f(t): t \in\left[0, C_{0}\right]\right\}$. It follows that

$$
\begin{aligned}
\left|\left(A z_{n}\right)(t)\right| & \leqslant M_{1}^{1 /(p-1)} \int_{0}^{+\infty}\left[\int_{s}^{+\infty} G(\tau) \mathrm{d} \tau\right]^{1 /(p-1)} \mathrm{d} s \\
\left|\frac{\mathrm{~d}}{\mathrm{~d} t}\left(A z_{n}\right)(t)\right| & \leqslant\left[M_{1} \int_{0}^{+\infty} G(\tau) \mathrm{d} \tau\right]^{1 /(p-1)}
\end{aligned}
$$

By the Arzelá-Ascoli compactness criterion for uniform convergence, there exists a uniformly convergent subsequence $\left(A z_{n_{k}}\right) \subset\left(A z_{n}\right)$ on compact subsets of $[0,+\infty)$. To prove that there exists a uniformly convergent subsequence of $\left(A z_{n}\right)$ it suffices to recall that given $\epsilon>0$, there is $T=T(\epsilon)$ such that

$$
\int_{T}^{+\infty}\left[\int_{s}^{+\infty} G(\tau) \mathrm{d} \tau\right]^{1 /(p-1)} \mathrm{d} s<\epsilon
$$

We now verify that $A$ is continuous. Let $\left(z_{n}\right) \in X$ such that $\left|z_{n}-z_{0}\right|_{\infty} \rightarrow 0$ as $n \rightarrow \infty$. Thus

$$
\left|\left(A z_{n}\right)(t)-\left(A z_{0}\right)(t)\right| \leqslant \int_{0}^{+\infty}\left|\Gamma_{n}(s)-\Gamma_{0}(s)\right| \mathrm{d} s
$$

where

$$
\Gamma_{n}(s)=\int_{s}^{+\infty} G(\tau) f\left(z_{n}(\tau)\right) \mathrm{d} \tau \quad \text { and } \quad \Gamma_{0}(s)=\int_{s}^{+\infty} G(\tau) f\left(z_{0}(\tau)\right) \mathrm{d} \tau
$$

It follows from $\left|z_{n}-z_{0}\right|_{\infty} \rightarrow 0$ that $\Gamma_{n}(s) \rightarrow \Gamma_{0}(s)$ and that

$$
\Gamma_{n}(s) \leqslant \frac{C}{N G(s)^{N(p-1) / p(N-1)}}
$$

for all $s \in[0,+\infty)$. By the Lebesgue-dominated convergence theorem,

$$
\left|A z_{n}-A z_{0}\right|_{\infty} \rightarrow 0
$$

which implies that $A$ is continuous.

Given $\omega \in K_{1}$, there clearly exists a unique $\tau=\tau(\omega)$ such that $2 \omega(\tau)=|\omega|_{\infty}$.
Define

$$
\tau^{*}=\sup \left\{\tau(A(z)): z \in K_{1}\right\}
$$

and

$$
K=\left\{z \in K_{1}: 2 \inf _{t \geqslant \tau^{*}} z(t) \geqslant|z|_{\infty}\right\}
$$

Lemma 2.3. $\tau^{*}$ is a positive real number and $K$ is an invariant cone by $A$.
The proof is based on the following assertion.
Assertion 2.4. $\left\{\omega /|\omega|_{\infty}: \omega \in A\left(K_{1}\right) \backslash\{0\}\right\}$ is a relatively compact subset of $X$.
Proof. Since $\left\{A z /|A z|_{\infty}: z \in K_{1}\right.$ and $\left.A z \neq 0\right\}$ is a bounded subset of $X$, it suffices to prove that

$$
\left\{[A z]^{\prime} /|A z|_{\infty}: z \in K_{1} \text { and } A z \neq 0\right\}
$$

is also a bounded subset of $X$.
Integrating by parts we have

$$
\begin{align*}
{\left[\frac{[A z]^{\prime}(t)}{|A z|_{\infty}}\right]^{p-1} } & =\frac{\int_{t}^{+\infty} G(\tau) f(z(\tau) \mathrm{d} \tau}{\left[\int_{0}^{+\infty}\left[\int_{s}^{+\infty} G(\tau) f(z(\tau)) \mathrm{d} \tau\right]^{1 /(p-1)} \mathrm{d} s\right]^{p-1}} \\
& =\frac{(p-1)^{p-1} \int_{t}^{+\infty} G(\tau) f(z(\tau)) \mathrm{d} \tau}{\left[\int_{0}^{+\infty}\left[\int_{s}^{+\infty} G(\tau) f(z(\tau)) \mathrm{d} \tau\right]^{(2-p) /(p-1)} s G(s) f(z(s)) \mathrm{d} s\right]^{p-1}} \tag{2.6}
\end{align*}
$$

We consider two cases.
Case $1(1<p<2)$. In this case, it follows from condition $\left(\mathrm{H}_{4}\right)$ that

$$
\begin{aligned}
{\left[\frac{[A z]^{\prime}(t)}{|A z|_{\infty}}\right]^{p-1} } & \leqslant \frac{(p-1)^{p-1} \int_{0}^{+\infty} G(\tau) g_{2}(z(\tau)) \mathrm{d} \tau}{\left[\int_{0}^{+\infty}\left[\int_{s}^{+\infty} G(\tau) g_{1}(z(\tau)) \mathrm{d} \tau\right]^{(2-p) /(p-1)} s G(s) g_{1}(z(s)) \mathrm{d} s\right]^{p-1}} \\
& \leqslant \frac{(p-1)^{p-1} \int_{0}^{+\infty} G(\tau) g_{2}(z(\tau)) \mathrm{d} \tau}{\left[\int_{0}^{+\infty}\left[\int_{s}^{+\infty} G(\tau) \mathrm{d} \tau\right]^{(2-p) /(p-1)} s G(s) g_{1}(z(s))^{1 /(p-1)} \mathrm{d} s\right]^{p-1}} \\
& \leqslant I_{1}+I_{2}
\end{aligned}
$$

where $I_{1}$ and $I_{2}$ are given by

$$
I_{1}=\frac{(p-1)^{p-1} \int_{0}^{1} G(\tau) g_{2}(z(\tau)) \mathrm{d} \tau}{\left[\int_{0}^{1}\left[\int_{s}^{+\infty} G(\tau) \mathrm{d} \tau\right]^{(2-p) /(p-1)} s G(s) g_{1}(z(s))^{1 /(p-1)} \mathrm{d} s\right]^{p-1}}
$$

and

$$
I_{2}=\frac{(p-1)^{p-1} \int_{1}^{+\infty} G(s) g_{2}(z(s)) \mathrm{d} s}{\left[\int_{1}^{+\infty}\left[\int_{s}^{+\infty} G(\tau) \mathrm{d} \tau\right]^{(2-p) /(p-1)} s G(s) g_{1}(z(s))^{1 /(p-1)} \mathrm{d} s\right]^{p-1}}
$$

We estimate each integral separately.

To estimate $I_{1}$, we use condition $\left(\mathrm{H}_{4}\right)$ to obtain

$$
\begin{aligned}
I_{1} & =\frac{(p-1)^{p-1} \int_{0}^{1} G(\tau) g_{2}(z(\tau)) \mathrm{d} \tau}{\left[\int_{0}^{1}\left[\int_{s}^{+\infty} G(\tau) \mathrm{d} \tau\right]^{(2-p) /(p-1)} s G(s) g_{1}(z(s))^{1 /(p-1)} \mathrm{d} s\right]^{p-1}} \\
& \leqslant \frac{(p-1)^{p-1} \int_{0}^{1} G(\tau) g_{2}(z(\tau)) \mathrm{d} \tau}{\left[\int_{\delta}^{1}\left[\int_{s}^{+\infty} G(\tau) \mathrm{d} \tau\right]^{(2-p) /(p-1)} s G(s) g_{1}(z(\delta))^{1 /(p-1)} \mathrm{d} s\right]^{p-1}} \\
& \leqslant \frac{(p-1)^{p-1} \int_{0}^{1} G(\tau) g_{2}(z(1)) \mathrm{d} \tau}{\left[\int_{\delta}^{1}\left[\int_{s}^{+\infty} G(\tau) \mathrm{d} \tau\right]^{(2-p) /(p-1)} s G(s) g_{1}(\delta z(1))^{1 /(p-1)} \mathrm{d} s\right]^{p-1}} \\
& \leqslant \frac{\eta(p-1)^{p-1} \int_{0}^{1} G(\tau) \mathrm{d} \tau}{\left[\int_{\delta}^{1}\left[\int_{s}^{+\infty} G(\tau) \mathrm{d} \tau\right]^{(2-p) /(p-1)} s G(s) \mathrm{d} s\right]^{p-1}}
\end{aligned}
$$

To estimate $I_{2}$, we use again condition $\left(\mathrm{H}_{4}\right)$ to get

$$
\begin{aligned}
{\left[\int_{s}^{+\infty} G(\tau) \mathrm{d} \tau\right]^{(2-p) /(p-1)} s G(s) } & \left(g_{1}(z(s))\right)^{1 /(p-1)} \\
& \geqslant N^{(p-2) /(p-1)}\left[s G(s) g_{1}(z(s))\right]^{1 /(p-1)} \\
& \geqslant N^{(p-2) /(p-1)}\left[s G(s) g_{1}(\delta z(s))\right]^{1 /(p-1)} \\
& \geqslant \frac{N^{(p-2) /(p-1)}}{\eta^{1 /(p-1)}}\left[s G(s) g_{2}(z(s))\right]^{1 /(p-1)}
\end{aligned}
$$

which implies

$$
\begin{aligned}
I_{2} & =\frac{(p-1)^{p-1} \int_{1}^{+\infty} G(s) g_{2}(z(s)) \mathrm{d} s}{\left[\int_{1}^{+\infty}\left[\int_{s}^{+\infty} G(\tau) \mathrm{d} \tau\right]^{(2-p) /(p-1)} s G(s) g_{1}(z(s))^{1 /(p-1)} \mathrm{d} s\right]^{p-1}} \\
& \leqslant \frac{\eta(p-1)^{p-1} \int_{1}^{+\infty} G(s) g_{2}(z(s)) \mathrm{d} s}{N^{p-2}\left[\int_{1}^{+\infty}\left[s G(s) g_{2}(z(s))\right]^{1 /(p-1)} \mathrm{d} s\right]^{p-1}} \\
& =\frac{\eta(p-1)^{p-1} \int_{1}^{+\infty} s(1 / s) G(s) g_{2}(z(s)) \mathrm{d} s}{N^{p-2}\left[\int_{1}^{+\infty}\left[s G(s) g_{2}(z(s))\right]^{1 /(p-1)} \mathrm{d} s\right]^{p-1}} \\
& \leqslant \frac{\eta(p-1)^{p-1}\|1 / s\|_{L^{1 /(2-p)}[1,+\infty)}}{N^{p-2}}
\end{aligned}
$$

Case $2(\boldsymbol{p} \geqslant 2)$. In this case, in accordance with conditions (2.6) and $\left(\mathrm{H}_{4}\right)$ :

$$
\begin{aligned}
\frac{[A z]^{\prime}(t)}{|A z|_{\infty}} & \leqslant \frac{(p-1) \int_{0}^{+\infty} G(s) f(z(s)) \mathrm{d} s}{\int_{0}^{+\infty} G(s) s f(z(s)) \mathrm{d} s} \\
& \leqslant(p-1)\left[\frac{\int_{0}^{1} G(s) f(z(s)) \mathrm{d} s}{\int_{0}^{1} G(s) s f(z(s)) \mathrm{d} s}+1\right]
\end{aligned}
$$

$$
\begin{aligned}
& \leqslant(p-1)\left[\frac{\int_{0}^{1} G(s) g_{2}(z(s)) \mathrm{d} s}{\int_{0}^{1} G(s) s g_{1}(z(s)) \mathrm{d} s}+1\right] \\
& \leqslant(p-1)\left[\frac{\int_{0}^{1} G(s) g_{2}\left(z\left(s_{M}\right)\right) \mathrm{d} s}{\int_{\delta}^{1} s G(s) g_{1}\left(z\left(s_{m}\right)\right) \mathrm{d} s}+1\right]
\end{aligned}
$$

where $z\left(s_{M}\right)=\max \{z(s): s \in[0,1]\}$ and $z\left(s_{m}\right)=\min \{z(s): s \in[\delta, 1]\}$. It now follows from the fact that $z\left(s_{m}\right) \geqslant \delta z\left(s_{M}\right)$ and condition $\left(\mathrm{H}_{4}\right)$ that

$$
\frac{[A z]^{\prime}(t)}{|A z|_{\infty}} \leqslant(p-1)\left[\eta \frac{\int_{0}^{1} G(s) \mathrm{d} s}{\int_{\delta}^{1} s G(s) \mathrm{d} s}+1\right]
$$

The result follows by the Arzelá-Ascoli compactness criterion.
Proof of Lemma 2.3. We first show that $\tau^{*}$ is a positive real number. Suppose on the contrary that $\tau^{*}=+\infty$. Then there must exist a sequence $\left(z_{n}\right) \subset K_{1} \backslash\{0\}$ such that $\left(\tau\left(z_{n} /\left|z_{n}\right|_{\infty}\right)\right)$ is a strictly increasing sequence of positive real numbers converging to $+\infty$. By Assertion 2.4, there exists a subsequence of $\left(z_{n} /\left|z_{n}\right|_{\infty}\right)$, which is denoted by the same index, such that $\left(z_{n} /\left|z_{n}\right|_{\infty}\right)$ converges to some $\omega_{0}$ in $X$. Hence $\left|\omega_{0}\right|_{\infty}=1$ and, for large $n$, we must have

$$
\tau\left(z_{n} /\left|z_{n}\right|\right)>\tau\left(\omega_{0}\right)
$$

Note that $\omega_{0}(t) \leqslant \frac{1}{2}$, for all $t \in\left[0, \tau\left(\omega_{0}\right)\right]$. On the other hand, given $t>\tau\left(\omega_{0}\right)$, we have $t<\tau\left(z_{n} /\left|z_{n}\right|\right)$ for large $n$. It follows that

$$
\omega_{0}(t)=\lim _{n \rightarrow+\infty} z_{n}(t) /\left|z_{n}\right|_{\infty} \leqslant \frac{1}{2}, \quad \text { for } t>\tau\left(\omega_{0}\right)
$$

We conclude that $\omega_{0}(t) \leqslant \frac{1}{2}$, for all $t \geqslant 0$. But this is impossible, since $\left|\omega_{0}\right|_{\infty}=1$.
That $K$ is an invariant cone by $A$ is clear. The proof of the lemma is now complete.
Lemma 2.5. We have $\imath\left(A, K_{R}, K\right)=1$.
Proof. According to condition $\left(\mathrm{H}_{3}\right)$, for $z \in \partial K_{R}$,

$$
\begin{aligned}
|A z|_{\infty} & =\max _{t \geqslant 0} \int_{0}^{t}\left[\int_{s}^{+\infty} G(\tau) f(z(\tau)) \mathrm{d} \tau\right]^{1 /(p-1)} \mathrm{d} s \\
& \leqslant \int_{0}^{+\infty}\left[\int_{s}^{+\infty} G(\tau) f(\bar{R}) \mathrm{d} \tau\right]^{1 /(p-1)} \mathrm{d} s \\
& =\frac{f(\bar{R})^{1 /(p-1)}(p-1) b^{p /(p-1)}}{p N^{1 /(p-1)}} \\
& <\bar{R}
\end{aligned}
$$

Since $\bar{R} \leqslant R$, we have $|A z|_{\infty}<R=|z|_{\infty}$. The result now follows from Lemma 2.1 (2).
Lemma 2.6. There is $r_{1} \in(0, R)$ such that $\imath\left(A, K_{r_{1}}, K\right)=0$.

Proof. According to condition $\left(\mathrm{H}_{1}\right)$, given $M>0$ there exists $r_{1} \in(0, R)$ such that

$$
f(t) \geqslant M t^{p-1}, \quad \text { for all } t \in\left[0, r_{1}\right]
$$

Thus for $z \in \partial K_{r_{1}}$,

$$
\begin{aligned}
(A z)\left(\tau^{*}\right) & =\int_{0}^{\tau^{*}}\left[\int_{s}^{+\infty} G(\tau) f(z(\tau)) \mathrm{d} \tau\right]^{1 /(p-1)} \mathrm{d} s \\
& \geqslant \int_{0}^{\tau^{*}}\left[\int_{s}^{+\infty} G(\tau) M z(\tau)^{p-1} \mathrm{~d} \tau\right]^{1 /(p-1)} \mathrm{d} s \\
& \geqslant \int_{0}^{\tau^{*}}\left[\int_{\tau^{*}}^{+\infty} G(\tau) M z(\tau)^{p-1} \mathrm{~d} \tau\right]^{1 /(p-1)} \mathrm{d} s \\
& \geqslant\left[\int_{\tau^{*}}^{+\infty} G(\tau) \mathrm{d} \tau\right]^{1 /(p-1)} \frac{\tau^{*} M^{1 /(p-1)}}{2}|z|_{\infty}
\end{aligned}
$$

Choosing $M>0$ such that

$$
\begin{equation*}
\tau^{*} G\left(\tau^{*}\right)^{N / p(N-1)}\left[\frac{M}{N}\right]^{1 /(p-1)}>2 \tag{2.7}
\end{equation*}
$$

we have that $|A z|_{\infty}>|z|_{\infty}$, for all $z \in \partial K_{r_{1}}$. The result now follows from Lemma 2.1 (1).

Lemma 2.7. There is $r_{2}>R$ such that $\imath\left(A, K_{r_{2}}, K\right)=0$.
Proof. It follows from condition $\left(\mathrm{H}_{2}\right)$ that there exists $r_{3}>R$ such that

$$
f(t) \geqslant M t^{p-1}, \quad \text { for all } t \geqslant r_{3}
$$

Note that for $z \in \partial K_{2 r_{3}}$ we have

$$
2 \min _{t \geqslant \tau^{*}} z(t) \geqslant|z|_{\infty}=2 r_{3}
$$

which implies

$$
f(z(t)) \geqslant M z(t)^{p-1}, \quad \text { for all } t \geqslant \tau^{*}
$$

Thus

$$
\begin{aligned}
(A z)\left(\tau^{*}\right) & =\int_{0}^{\tau^{*}}\left[\int_{s}^{+\infty} G(\tau) f(z(\tau)) \mathrm{d} \tau\right]^{1 /(p-1)} \mathrm{d} s \\
& \geqslant \int_{0}^{\tau^{*}}\left[\int_{\tau^{*}}^{+\infty} G(\tau) f(z(\tau)) \mathrm{d} \tau\right]^{1 /(p-1)} \mathrm{d} s \\
& \geqslant \int_{0}^{\tau^{*}}\left[\int_{\tau^{*}}^{+\infty} G(\tau) M z(\tau)^{p-1} \mathrm{~d} \tau\right]^{1 /(p-1)} \mathrm{d} s \\
& \geqslant \tau^{*} G\left(\tau^{*}\right)^{N / p(N-1)}\left[\frac{M}{N}\right]^{1 /(p-1)} \frac{|z|_{\infty}}{2}
\end{aligned}
$$

Define the number $r_{2}=2 r_{3}$. By (2.7), we have $|A z|_{\infty}>|z|_{\infty}$, for $z \in \partial K_{r_{2}}$, and the result now follows from Lemma 2.1 (1).

## 3. Proof of the main result

Proof of Theorem 1.1. It follows from Lemmas 2.5-2.7 and the additivity of the fixed-point index that

$$
\imath\left(A, K_{R} \backslash K_{r_{1}}, K_{r_{1}}\right)=1
$$

and that

$$
\imath\left(A, K_{r_{2}} \backslash K_{R}, K_{R}\right)=-1
$$

Consequently, the operator $A$ has two fixed points, namely $z_{1}$ in $K_{R} \backslash K_{r_{1}}$ and $z_{2}$ in $K_{r_{2}} \backslash K_{R}$.

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