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# COBOUNDARY EQUATIONS OF EVENTUALLY EXPANDING TRANSFORMATIONS

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Let T be an eventually expansive transformation on the unit interval satisfying the Markov condition. Then T is an ergodic transformation on  $(X, \mathcal{B}, \mu)$  where X = [0, 1),  $\mathcal{B}$  is the Borel  $\sigma$ -algebra on the unit interval and  $\mu$  is the T invariant absolutely continuous measure. Let G be a finite subgroup of the circle group or the whole circle group and  $\phi : X \to G$  be a measurable function with finite discontinuity points. We investigate ergodicity of skew product transformations  $T_{\phi}$  on  $X \times G$  by showing the solvability of the coboundary equation  $\phi(x)g(Tx) = \lambda g(x), |\lambda| = 1$ . Its relation with the uniform distribution mod M is also shown.

### 1. INTRODUCTION

Let  $(X, \mathcal{B}, \mu)$  be a probability space and T be a measure preserving transformation on X. A transformation T on X is called ergodic if the constant function is the only T-invariant function and it is called weakly mixing if the constant function is the only eigenfunction with respect to T. A measure preserving transformation T is called exact if  $\bigcap_{n=0}^{\infty} T^{-n}\mathcal{B}$  is the trivial  $\sigma$ -algebra consisting of empty set and whole set modulo measure zero sets. So exact transformation are as far from being invertible as possible. Recall that if a transformation is exact then that transformation is weakly mixing ([11]).

A piecewise differentiable transformation  $T : [0,1) \rightarrow [0,1)$  is said to be eventually expansive if some iterate of T has its derivative bounded away from 1 in modulus, that is,  $|(T^n)'| > 1$  everywhere for some n. Let  $\{\Delta_i\}$  be a countable (or finite) partition of the unit interval [0,1) by subintervals. Suppose that an eventually expansive map T on the interval [0,1) satisfies

- (i)  $T|_{\text{Int}\,\Delta_i}$  has a  $C^2$ -extension to the closure of  $\Delta_i$ ,
- (ii)  $T|_{Int \Delta_i}$  is strictly monotone,
- (iii)  $\overline{T(\Delta_i)} = [0, 1]$ , and in the case that the number of subintervals in the partition is infinite
- (iv)  $\sup_{i} \left\{ \sup_{x_1 \in \operatorname{Int} \Delta_i} \left| T''(x_1) \right| / \inf_{x_2 \in \operatorname{Int} \Delta_i} \left| T'(x_2) \right|^2 \right\} < \infty.$

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Then it is well known that there exists a measure  $\mu$  which is (a) *T*-invariant, (b) exact, and (c) finite and of the form  $d\mu = \rho(x) dx$  where  $\rho$  is continuous and  $1/C < \rho < C$  for some C > 0 ([1, 3, 4]).

The conditions of the above fact can be modified in several ways. One modification is called the Markov condition, when the number of sets in the partition is finite and  $\overline{T(\Delta_i)}$  is a union of  $\overline{\Delta_j}$ . In this paper, let  $\mathbb{T}$  be the unit circle in the complex plane,  $\mathbb{T} = \{z \in \mathbb{C} : |z| = 1\}.$ 

In [9], Siboni consider the skew product transformation  $T_{2,a,\omega}$  on the torus,  $[0,1) \times [0,1)$  defined by

$$(x, y) \mapsto (2x, y + ax + \omega) \pmod{1}.$$

He proved a criterion for the ergodicity of the transformation by accurate estimation of correlations of characteristic functions.

Let T be an eventually expansive transformation on the unit interval satisfying the Markov conditions. Then T is an exact transformation on  $(X, \mathcal{B}, \mu)$  where X = [0, 1),  $\mathcal{B}$  is Borel  $\sigma$ -algebra on the unit interval and  $\mu$  is the T invariant absolutely continuous measure. Let G be a finite subgroup of the circle group or the whole circle group  $\mathbb{T}$  and  $\phi : X \to G$  a measurable function with finite discontinuity points. In this paper we investigate ergodicity of skew product transformations  $T_{\phi}$  on  $X \times G$  by showing the solvability of the coboundary equation  $\phi(x)g(Tx) = \lambda g(x), |\lambda| = 1$  and we give a simple proof and generalisations of Siboni's results, see Proposition 3.

Let  $X = \{x : 0 \le x < 1\}$  be the compact group of real numbers modulo 1, and let  $\theta \in X$  be irrational. The numbers  $j\theta$ ,  $j = 0, \pm 1, \ldots$ , comprise a dense subgroup of X. For each interval  $I \subset X$  and n > 0 define  $S_n = S_n(\theta, I)$  to be the number of integers  $j, 0 \le j \le n-1$ , such that  $j\theta \in I$ . By the Kronecker-Weyl theorem  $\lim_{n\to\infty} S_n/n = \mu(I)$ , where  $\mu$  is Lebesgue measure on X ([6]). Veech [10] was interested in the behaviour of the sequence  $\{d_n\}$  of parities of  $\{S_n\}$ , that is,  $d_n$  is 0 or 1 as  $S_n$  is even or odd. He investigated the existence of the limit

$$\mu_{\theta}(I) = \lim_{N \to \infty} \frac{1}{N} \sum_{n=1}^{N} d_n,$$

and he showed that a necessary and sufficient condition for  $\mu_{\theta}(I)$  to exist for every interval  $I \subset X$  is that  $\theta$  has bounded partial quotients. He also showed that  $d_n$  is evenly distributed if the length of the interval is not an integral multiple of  $\theta$  modulo 1.

In this paper, we are interested in the uniform distribution of the sequence  $d_n \in \{0, ..., M-1\}$  defined by

$$d_n(x) \equiv \sum_{k=0}^{n-1} \mathbf{1}_E(T^k x) \pmod{M}$$

Coboundary equations

for eventually expanding transformations, particularly for generalised *L*-covering maps (which will be defined in section 3) and for Gauss transformation on the interval. Here  $\mathbf{1}_{E}(x)$  denotes the indicator function of  $E \subset X$ .

To investigate the sequence  $\{d_n(x)\}$ , we consider the behaviour of the sequence  $\exp((2\pi i/M)d_n(x))$  and check whether this sequence is uniformly distributed on the finite group G generated by  $\exp((2\pi i)/M)$ . Weyl's criterion for uniform distribution says that the sequence  $\exp((2\pi i/M)d_n(x))$  is uniformly distributed if and only if  $\lim_{N\to\infty}\sum_{n=1}^{N}/N\exp^k((2\pi i/M)d_n(x)) = 0$  for all  $1 \le k \le M-1$  ([6]). We investigate this problem from the viewpoint of spectral theory. Let  $(X, \mu)$  be a probability space and T be an ergodic measure preserving transformation on X, which is not necessarily invertible. Let  $\phi(x)$  be a G-valued function defined by  $\phi(x) = \exp((2\pi i/M)\mathbf{1}_E(x))$ . Consider the skew product transformation  $T_{\phi}$  on  $X \times G$  defined by  $T_{\phi}(x,g) = (Tx,\phi(x)g)$ . Then

$$\lim_{N \to \infty} \frac{1}{N} \sum_{n=1}^{N} \exp^k \left( \frac{2\pi i}{M} d_n(x) \right) \cdot z^k = \lim_{N \to \infty} \frac{1}{N} \sum_{n=1}^{N} U_{T_{\phi}} f(x, z)$$

where  $U_{T_{\phi}}$  is an isometry on  $L^{2}(X \times G)$  induced by  $T_{\phi}$  and  $f(x, z) = z^{k}$ . If  $T_{\phi}$  is ergodic, we may apply Birkhoff's Ergodic Theorem to f to deduce that  $\lim_{N \to \infty} 1/N \sum_{n=1}^{N} \exp^{k}((2\pi i/M)d_{n}(x)) = 0$ , Recall that the dual group of G consists of the  $\gamma_{k}(z) = z^{k}$  for  $0 \leq k \leq M - 1$ . Hence  $L^{2}(X \times G) = \bigoplus_{k=0}^{M-1} L^{2}(X) \cdot z^{k}$  and each  $L^{2}(X) \cdot z^{k}$  is an invariant subspace of  $U_{T_{\phi}}$ . If  $f(x, z) \in L^{2}(X, G)$  then  $f(x, z) = \sum_{k=0}^{M-1} f_{k}(x)z^{k}$ , and

$$U_{T_{\phi}}f(x,z) = \sum_{k=0}^{M-1} \phi^k(x)f_k(Tx) \cdot z^k.$$

Hence, if f is an eigenfunction with eigenvalue  $\lambda$  we have  $\phi^k(x)f_k(Tx) = \lambda f_k(x)$  for all k. Recall that a nonconstant function h(x) is called a *coboundary* if  $h(x) = \overline{q(Tx)}q(x)$ , |q(x)| = 1 almost everyway on X.

In [2], Ahn and Choe considered the case when T is an (1/L, ..., 1/L)-Bernoulli transformation and show and that if E is a cylinder set with the same missing initial digit and M = 2, then the sequence  $\{d_n\}$  is evenly distributed. In this paper, we show that for all generalised *L*-covering maps and Gauss transformation on the unit interval, the sequence  $\{d_n\}$  is uniformly distributed and that compact group extension by  $\phi(x)$  is exact.

# 2. COBOUNDARY EQUATIONS

Let  $(Y, \mathcal{C}, \mu)$  be a probability space,  $f \in L^1(Y, \mathcal{C}, \mu)$  and  $\mathcal{B} \subset \mathcal{C}$  a sub  $\sigma$ -algebra. We denote by  $E(f \mid \mathcal{B})$  the conditional expectation of f with respect to  $\mathcal{B}$ . Recall that this

is a  $\mathcal{B}$ -measurable function g with the property that  $\int_{\mathcal{B}} f d\mu = \int_{\mathcal{B}} g d\mu$  for all  $\mathcal{B} \in \mathcal{B}$ . Let S be a transformation defined on Y and  $\mathcal{B}$  be *exhaustive* that is,  $S^{-1}\mathcal{B} \subset \mathcal{B}$  and  $S^{n}\mathcal{B} \uparrow \mathcal{C}$  as  $n \to +\infty$ . The Martingale Convergence Theorem says that  $E(f \mid S^{n}\mathcal{B})$  converges to f almost everywhere and in  $L^{1}(Y, \mathcal{C}, \mu)$  as  $n \to +\infty$  for  $f \in L^{1}(Y, \mathcal{C}, \mu)$ 

**LEMMA 1.** Let S be a measure preserving transformation on  $(Y, C, \mu)$ , and B be an exhaustive  $\sigma$ -algebra  $\mathcal{B} \subset C$ , and let  $\phi: Y \to \mathbb{T}$  be a B-measurable map to the circle group  $\mathbb{T}$ . If  $q: Y \to \mathbb{T}$  is a C-measurable solution to the equation  $\phi \cdot q \circ S = q$ , then q is B-measurable.

**PROOF:** We follow an idea of Parry in [8]. Applying the conditional expectation operator  $E(\cdot | B)$  to the equation

$$(*) \qquad \qquad \phi \cdot q \circ S = q$$

we obtain  $\phi \cdot E(q \circ S \mid \mathcal{B}) = E(q \mid \mathcal{B})$  or  $\phi \cdot E(q \mid S\mathcal{B}) \circ S = E(q \mid \mathcal{B})$ . Multiplying this with the inverse of (\*) we have  $\overline{q(y)} \cdot E(q \mid \mathcal{B})(y) = \overline{q(Sy)} \cdot E(q \mid S\mathcal{B}) \circ S(y)$  almost everywhere so that  $\int_Y \overline{q} \cdot E(q \mid \mathcal{B}) d\mu = \int_Y \overline{q} \cdot E(q \mid S\mathcal{B}) d\mu$ . By exactly the same argument, using  $S^n\mathcal{B}$ in place of  $\mathcal{B}$ , we have  $\int_Y \overline{q} \cdot E(q \mid S^n\mathcal{B}) d\mu = \int_Y \overline{q} \cdot E(q \mid S^{n+1}\mathcal{B}) d\mu$  so that  $\int_Y \overline{q} \cdot E(q \mid \mathcal{B}) d\mu = \int_Y \overline{q} \cdot E(q \mid S^n\mathcal{B}) d\mu$ . Taking limits, we get  $\int_Y \overline{q} \cdot E(q \mid \mathcal{B}) d\mu = \int_Y |q|^2 d\mu$ . Thus  $E(q \mid \mathcal{B}) = q$  almost everywhere, and q is  $\mathcal{B}$ -measurable.

**PROPOSITION 1.** Let  $Y = \prod_{-\infty}^{\infty} \{0, 1, \dots, L-1\}$  where  $L \leq \infty$  and let  $\sigma$  be the shift map on Y with  $\sigma$ -invariant measure  $\mu$ . Let  $\mathcal{P}$  denote the state partition  $\{P_k : P_k = \{x : x_0 = k\}$  for  $0 \leq k \leq L-1\}$ , and let  $\mathcal{B}_l^m = \bigvee_{\substack{i=l \ i=l}}^m \sigma^{-i}\mathcal{P}$  for  $l \leq m$ . Assume that  $\phi(x)$  is a T-valued  $\mathcal{B}_l^m$  measurable function. If g(x) is a T-valued solution of the equation,  $\phi(x)g(\sigma x) = g(x)$  then g(x) is also a  $\mathcal{B}_l^m$  measurable function.

PROOF: Let  $\mathcal{B} = \bigvee_{i=l}^{\infty} \sigma^{-i} \mathcal{P}$ . Then  $\phi(x)$  is  $\mathcal{B}$  measurable and  $\mathcal{B}$  is exhaustive with respect to  $\sigma$ . Since  $\phi(x)g(\sigma x) = g(x)$ , g(x) is also  $\mathcal{B}$ -measurable by the above Lemma. Now let  $\mathcal{A} = \bigvee_{i=-m}^{\infty} \sigma^{i} \mathcal{P}$ . Then  $\phi(\sigma^{-1}x)$  is  $\mathcal{A}$  measurable and  $\mathcal{A}$  is exhaustive with respect to  $\sigma^{-1}$ . Since  $\phi(x)g(\sigma x) = g(x)$  can be rewritten as  $\phi(\sigma^{-1}x)g(x) = g(\sigma^{-1}x)$ , that is,  $\phi(\sigma^{-1}x)\overline{g(\sigma^{-1}x)} = \overline{g(x)}$ , g(x) is also  $\mathcal{A}$  measurable by applying the above Lemma to the map  $\sigma^{-1}$ . Hence the conclusion follows.

#### 3. The interval maps and symbolic dynamics

In this section we apply the previous result to Markov maps. Consider the behaviour of the iterates of a map  $\tau$  of the unit interval to itself. We also assume that  $\tau$  is noninvertible and piecewise continuous. Here are several well-known examples:

(a) 
$$\tau(x) = 2x \pmod{1};$$

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- (b)  $\tau(x) = \beta x \pmod{1}, \ \beta = (1 + \sqrt{5})/2;$
- (c) Gauss transform  $\tau(x) = 1/x \pmod{1}$ .

For each of these transformations explicit formulas are known for absolutely continuous invariant measures:

- (a) the Lebesgue measure dx;
- (b)  $d\mu = \beta dx, 0 \leq x < \beta^{-1}$ , and  $d\mu = dx, \beta^{-1} \leq x < 1$ ;
- (c) the Gauss measure  $d\mu = (1/\log 2) dx/(1+x)$ .

DEFINITION 1: Let  $\tau : [0,1) \to [0,1)$   $0 = a_0 < a_1 < \cdots < a_L = 1$ , and let  $\{I_j\}_{j=0}^{L-1}$  be a partition of [0,1) with  $I_j = [a_j, a_{j+1}), 0 \leq j \leq L-1 \leq \infty$ . Assume that  $\tau$  satisfies

- (1)  $\tau|_{\text{Int }I_i}$ , the restriction of  $\tau$  to interior points of  $I_i$ , has a  $C^2$ -extension to the closure of  $I_i$ ,
- (2)  $\tau|_{\text{Int }I_i}$  is strictly monotone,
- (3)  $\overline{\tau(I_i)} = [0, 1]$ , and, in the case where  $L = \infty$
- (4)  $\sup_{i} \left\{ \sup_{x_1 \in \operatorname{Int} I_i} \left| \tau''(x_1) \right| / \inf_{x_2 \in \operatorname{Int} I_i} \left| \tau'(x_2) \right|^2 \right\} < \infty.$

Suppose that for some n,  $|d\tau^n/dt| \ge \theta > 1$  for all t. If we regard the above map  $\tau$  as being defined on the unit circle, its winding number equals L. We call it a generalised *L*-covering map.

It is known that  $\tau$  has a finite ergodic measure  $\rho(x) dx$  where  $\rho(x)$  is piecewise continuous and  $1/D < \rho < D$  for some D > 0. See [1, 3].

Given a generalised L-covering map  $\tau$ , construct an one-sided shift space on L symbols as follows: To each  $t \in [0, 1)$  there corresponds a one-sided infinite sequence  $[a_0, a_1, \ldots, a_n, \ldots]$  such that  $\tau^n(t) \in I_{a_n}$ . For some  $t \in [0, 1)$ , we can find N such that its representation  $t = [a_0, a_1, \ldots, a_n, \ldots]$  satisfies the condition that  $a_n = 0$  for all  $n \ge N$ . We call such a t a generalised L-adic point. Let X be the set of all such sequences and  $\psi$  be the assignment of a sequence to a point. Since  $\tau$  has a finite absolutely continuous ergodic measure  $\rho(t) dt$ , we can define a shift invariant measure  $\nu$  on any cylinder set  $C \subset \prod_{0}^{\infty} \{0, 1, \ldots, L-1\}$  by  $\nu(C) = \int_{\psi^{-1}(C)} \rho(x) dx$ . Note that  $\psi^{-1}(C)$  is a union of intervals with generalised L-adic endpoints. The Kolmogorov Extension Theorem guarantes that  $\nu$  may be uniquely extended to the whole  $\sigma$ -algebra. We call the shift space X the L-adic symbolic system obtained from  $\tau$ . Recall that two measure preserving transformations  $T_1$  and  $T_2$  on  $X_1$  and  $X_2$  are said to be isomorphic if there exists a measure preserving transformation  $\psi : X_1 \to X_2$  which is one-to-one such that  $\psi \circ T_1 = T_2 \circ \psi$ on  $X_1$  modulo sets of measure zero. The mapping  $\phi$  introduced above is an isomorphism between  $((0, 1), \rho dt, \tau)$  and the one-sided shift space  $(X, d\nu, \sigma)$ .

Our construction also applies even if the condition (3) in Definition 1 does not hold. For example, the interval map  $x \mapsto \beta x \pmod{1}$ ,  $\beta = (1 + \sqrt{5})/2$  has the following special property: Put  $I_0 = [0, \beta^{-1})$ ,  $I_1 = [\beta^{-1}, 1)$ . If  $x \in I_1$ , then  $\tau x \in I_0$ . In other words, in

any sequence  $[x_0, x_1, \ldots, x_n, \ldots]$  the symbol 1 does not occur consecutively. Hence in this case X would not be the full shift  $\prod_{0}^{\infty} \{0,1\}$ . In fact, it is a shift of finite type with a forbidden block 11. See [1].

DEFINITION 2: An *L*-adic multi-index  $\vec{n}$  is a finite sequence of elements of  $\{0 \ 1 \ \dots, L-1\}$  and will denote by  $\vec{n} = \langle n_1, \dots, n_k \rangle$  Its length k is denoted by  $|\vec{n}|$ . If there is no danger of ambiguity we call it a multi-index. If  $|\vec{n}| = 1$ , then  $\vec{n} = \langle n_0 \rangle$  for some  $n_0$ , and we write  $\vec{n} = n_0$ .

Let  $\tau$  be a map as given in Definition 1. Define  $h_i : [0,1) \to [0,1)$  by letting  $h_i(t)$  be the unique element in the set  $\tau^{-1}(\{t\}) \cap I_i$ ,  $i = 0, 1, \ldots, L-1$ . Note that  $\tau^{-1}(\{t\}) = \{h_0(t), h_1(t), \ldots, h_{L-1}(t)\}$ . For a multi-index  $\vec{n} = \langle n_1, \ldots, n_k \rangle$ , define  $h_{\vec{n}} = h_{n_1} \circ \ldots \circ h_{n_k}$ .

For example, consider the transformation  $\tau(x) = 2x \pmod{1}$  defined on the unit interval with the partition  $\left\{ \begin{bmatrix} 0, (1/2) \\ 0, (1/2) \end{bmatrix} \right\}$ . Since every  $t \in \begin{bmatrix} 0, 1 \end{bmatrix}$  can be represented as a binary expansion, say  $t = \begin{bmatrix} t_1, t_2, \ldots \end{bmatrix}$ ,  $h_0(t) = (1/2)t = \begin{bmatrix} 0, t_1, t_2, \ldots \end{bmatrix}$  and  $h_1(t)$  $= (1/2) + (1/2)t = \begin{bmatrix} 1, t_1, t_2, \ldots \end{bmatrix}$ . Hence  $h_i(t) = \begin{bmatrix} i, t_1, t_2, \ldots \end{bmatrix}$  for i= 0, 1. So  $h_{\vec{n}}(t) = \begin{bmatrix} n_1, \ldots, n_k, t_1, t_2, \ldots \end{bmatrix}$  where  $\vec{n} = \langle n_1, \ldots, n_k \rangle$ . In particular,  $h_{\vec{n}}(0) = \begin{bmatrix} n_1, \ldots, n_k \end{bmatrix} = \sum_{j=1}^k n_j 2^{-j}$ .

From Definitions 1 and 2 we easily obtain

**LEMMA 2.** Put  $\vec{n} = \langle n_1, \ldots, n_k \rangle$ . Let  $\tau$  and  $h_i$  be as given in Definitions 1 and 2. Then

(1)  $\tau^{-k}(\{t\}) = \{h_{\vec{n}}(t) : |\vec{n}| = k\},$ (2)  $\tau^{k}(h_{\vec{n}}(x)) = x$  where  $k = |\vec{n}|,$ (3)  $h_{\vec{n}}([a_{1}, a_{2}, \ldots]) = [n_{1}, \ldots, n_{k}, a_{1}, a_{2}, \ldots],$  and (4)  $\tau^{-k}(E) = \bigcup_{|\vec{n}|=k} h_{\vec{n}}(E)$  for any subset E.

For any fixed integer k > 0 let  $\mathcal{P}_0^k$  be the set of numbers of the form  $[a_1, \ldots, a_k]$ ,  $a_i = 0, 1, \ldots, L-1$  so that the points in  $\mathcal{P}_0^k$  partition the whole interval [0, 1) into  $L^k$ segments. Then (i)  $h_{\vec{n}}([0, 1))$  is one of the  $L^k$  intervals obtained by partitioning the unit interval by the points in  $\mathcal{P}_0^k$ ,  $k = |\vec{n}|$  and (ii) if  $x \in h_{\vec{n}}([0, 1))$ ,  $\vec{n} = \langle n_1, \ldots, n_k \rangle$ , then the coded sequence for x is  $[n_1, \ldots, n_k, \ldots]$ .

**PROPOSITION 2.** A complex valued step function  $\phi(x)$  with finite generalised L-adic discontinuity points  $a_1 \leq t_1 < \ldots < t_n < 1$ , is not a coboundary for any generalised L-covering map.

PROOF: Let  $(X, \sigma_X, \nu)$  be the one-sided shift space which is isomorphic to the given L-covering map. Let  $Y = \prod_{-\infty}^{\infty} \{0, 1, \dots, L-1\}, \sigma_Y$  the two-sided shift and  $\mu$  the unique measure on Y so that  $(Y, \sigma_Y, \mu)$  is the natural extension of  $(X, \sigma_Y, \mu)$ 

### Coboundary equations

Assume that  $\phi(x)h(\tau x) = h(x)$ . Since  $\phi(x)$  is step function with finite *L*-adic discontinuity points, we can regard  $\phi(x)$  is function on *Y* which is measurable, with respect to  $\mathcal{B}_0^m = \bigvee_{i=0}^m \sigma^{-i}\mathcal{P}$  for some  $m < \infty$  (Lemma 2). Hence h(x) is also  $\mathcal{B}_0^m$ -measurable by Proposition 1. Thus h(x) is also a step function with finite *L*-adic discontinuity points. Hence there exists  $0 < r \le a_1$  such that h(x) is constant on [0, r). Thus  $\phi(x)h(x) = h(x)$  on [0, r), that is,  $\phi(x) = 1$  on  $[0, t_1)$ . Since  $\phi(x)h(\tau x) = h(x)$ ,  $t_1 \ge a_1$  and  $\tau[0, a_1) = [0, 1)$ , h(x) is constant on [0, 1). Hence the conclusion follows.

EXAMPLE 1. For a transformation  $T : [0,1) \to [0,1)$  defined by  $x \mapsto 2x \pmod{1}$ , we consider the following. Let I = [(3/4),1),  $F = \bigcup_{k=0}^{\infty} (1/2^k)I$  and  $E = F \bigtriangleup T^{-1}F$ . Then  $\phi(x) = \exp(\pi i \mathbf{1}_E(x))$  is a coboundary even if the discontinuity points of  $\phi(x)$  are contained in [(1/2),1) where the cobounding function  $h(x) = \exp(\pi i \mathbf{1}_F(x))$ . Hence the assumption in Proposition 2 of finite discontinuity points cannot be dropped.

# 4. A CLASS OF SKEW PRODUCTS OF CIRCLE ENDOMORPHISMS

In this section, we investigate the dynamical properties of a class of skew products of circle endomorphisms.

DEFINITION 3: For a positive integer L, let  $T_{L,a,\omega}$  be the skew-product transformation on the torus,  $[0, 1) \times [0, 1)$  defined by

$$(x, y) \mapsto (Lx, y + ax + \omega) \pmod{1}$$
.

In [9], Siboni considered the skew product transformation  $T_{2,a,\omega}$  and proved a criterion of ergodicity of the transformation by the accurate estimation of correlations of characteristic functions. In this section, we shall give a simple proof and generalisation of his results.

For a fixed natural number L, let T be the transformation on X = [0, 1) defined by  $Tx = Lx \pmod{1}$ .

**LEMMA 3.** Let S and S' be transformations of the torus defined by

$$S(x,y) = (Lx, y + ax) \pmod{1} \text{ and}$$
  
$$S'(x,y) = \left(Lx, y + \sum_{k=0}^{L-1} \frac{ka}{L-1} \mathbf{1}_{\{(k/L), (k+1/L)\}}(x)\right) \pmod{1}$$

Then S and S' are isomorphic.

PROOF: We will use the *L*-adic expansion of x;  $x = (x_0/L) + (x_1/L^2) + \cdots$ . Let  $\phi(x, y) = (x, y + (a/L - 1)x) \pmod{1}$ . Then  $\phi^{-1}(x, y) = (x, y - (a/L - 1)x) \pmod{1}$ 

and

$$\phi^{-1}S\phi(x,y) = \phi^{-1}\left(Lx, y + ax + \frac{a}{L-1}x\right)$$
  
=  $\left(Lx, y + ax + \frac{a}{L-1}x - \frac{a}{L-1}(Lx-k)\right)$  if  $x_0 = k$   
=  $\left(Lx, y + \frac{ka}{L-1}\right)$  if  $x_0 = k$   
=  $S'(x, y)$ .

Hence to investigate the spectral type of S, we only need to study the spectral type of S'.

**PROPOSITION 3.**  $T_{L,a,\omega}$  is weakly mixing if and only if a is irrational. Further if a is rational then  $T_{L,a,\omega}$  is ergodic if and only if  $\omega$  is irrational.

PROOF: For convenience, let us denote the 2-torus by  $X \times \mathbb{T}$ . As before, we use the *L*-adic expansion of *x*. Recall that  $L^2(X \times \mathbb{T}) = \bigoplus_{n=-\infty}^{\infty} f(x) \cdot z^n$ .

Let  $\eta(x) = \exp(2\pi i(ax + \omega))$ ,  $\psi(x) = \exp(2\pi iax)$  and  $\phi(x) = \exp(2\pi ia(x_0/L - 1))$ . Then

 $U_{T_{\eta}}(f(x) \cdot z^n) = \exp(2\pi i n a x) \cdot \exp(2\pi i n \omega) \cdot f(Tx) \cdot z^n.$ 

We consider the operator

$$U(f(x)) = \exp(2\pi i n a x) \cdot \exp(2\pi i n \omega) \cdot f(Tx)$$

If n = 0, then U(f(x)) = f(Tx). Thus if  $f(Tx) = \lambda f(x)$  then f(x) is constant and  $\lambda = 1$  by the mixing property of T. Hence it remains to consider the case  $n \neq 0$ . Assume that  $U(f(x)) = \lambda f(x)$ . Then

$$\exp(2\pi i nax)\exp(2\pi i n\omega)f(Tx) = \lambda f(x)$$

and  $|\lambda| = 1$ . Without loss of generality we may assume that |f(x)| = 1 almost everywere. So  $\exp(2\pi i n a x) = \lambda' \overline{f(Tx)} f(x)$ , where  $\lambda' = \lambda \exp(-2\pi i n \omega)$ . By Lemma 3,  $U_{T_{\psi}}$  is spectrally equivalent to  $U_{T_{\phi}}$  and  $U_{T_{\phi}}$  also has an eigenfunction g(x) with eigenvalue  $\lambda'$ , that is,  $\overline{\lambda'} \exp\left(2\pi i n \sum_{k=0}^{L-1} (ka/L - 1) \mathbf{1}_{[(k/L),(k+1/L))}(x)\right) = \overline{g(Tx)}g(x)$ . If a is an irrational number, then there exists the only integer n for mention.

$$\overline{\lambda'} \exp\left(2\pi i n \sum_{k=0}^{L-1} \frac{ka}{L-1} \mathbf{1}_{[(k/L),(k+1/L))}(x)\right)$$

is constant is n = 0. Hence by Proposition 2, there exists no eigenfunction for  $U_{T_{\phi}}$ . If a is rational then there exists n such that  $\exp\left(2\pi i n \sum_{k=0}^{L-1} (ka/L-1) \mathbf{1}_{\left[(k/L),(k+1/L)\right]}(x)\right) = 1$ .

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So the problem is reduced to finding g(x) such that  $g(Tx) = \lambda'g(x)$ . By the mixing property of T we know that g(x) is constant and  $\lambda' = \lambda \exp(-2\pi i n\omega) = 1$  for each  $n \neq 0$ . So  $U_{T_{\phi}}$  has eigenfunction  $g(x, z) = z^n$  with eigenvalue  $\lambda = \exp(2\pi i n\omega)$ . Hence  $T_{L,a,\omega}$  is not weakly mixing. For the ergodicity, we need only consider the case  $\lambda = 1$ , that is,  $\exp(2\pi i n\omega) = 1$ . Hence if a is rational, then  $T_{L,a,\omega}$  is ergodic if and only if  $\omega$  is irrational.

REMARK 1. Indeed we have shown that if a is irrational then  $T_{L,a,\omega}$  is exact on the torus. In fact,  $T_{L,a,\omega}$  is strong mixing. To see this, let  $\mathcal{B}_1$  be the Borel  $\sigma$ -algebra on [0,1),  $\mathcal{B}_2$  be the Borel  $\sigma$ -algebra on  $\mathbb{T}$  and  $\mathcal{B}_{\infty} = \bigcap_{n=0}^{\infty} T_{L,a,\omega}^{-n}(\mathcal{B}_1 \times \mathcal{B}_2)$ . We only need to show that  $L^2(\mathcal{B}_{\infty})$  is the set of constant functions. We use the fact that  $T_{L,a,\omega}$  commutes with the circle action  $(x, z) \mapsto (x, z \cdot g)$  so that for every n the  $\sigma$ -algebra  $T_{L,a,\omega}^{-n}(\mathcal{B}_1 \times \mathcal{B}_2)$  is preserved by the circle action. Hence  $\mathcal{B}_{\infty}$  is invariant with respect to the circle action. If  $f \in L^2(\mathcal{B}_{\infty})$  then it has a representation

$$f(x,z) = \sum_{k} f_k(x) \cdot z^k$$

and  $f(x, z \cdot g) = \sum_{k} f_{k}(x) \cdot z^{k} \cdot g^{k}$  for all  $g \in \mathbb{T}$ . Hence  $f_{k}(x) \cdot z^{k} \in L^{2}(\mathcal{B}_{\infty})$ . So  $|f_{k}(x) \cdot z^{k}| = |f_{k}(x)|$  is also  $\mathcal{B}_{\infty}$  measurable. But  $|f_{k}(x)|$  depends only on x. Hence  $|f_{k}(x)|$  is constant by the exactness of T. By a similar argument  $\overline{f_{k}} \cdot f_{k} \circ T_{L,a,\omega}$  is also constant, that is,

$$\exp(2\pi i kax) \cdot \exp(2\pi i k\omega) \cdot f_k(Tx) \cdot z^k = \lambda f_k(x) \cdot z^k$$

where  $\lambda \in \mathbb{C}$ . Thus if  $T_{L,a,\omega}$  is weakly mixing then  $T_{L,a,\omega}$  is exact. For more information on this subject, see [5].

# 5. Mod M normality of L-covering maps

In this section, let G be the finite subgroup of T generated by  $\exp(2\pi i/M)$ .

**PROPOSITION 4.** Let T be an ergodic transformation on X and  $\phi(x)$  be a G-valued function. Let  $T_{\phi}$  be the skew product transformation defined by  $T_{\phi}(x,g) = (Tx, \phi(x) \cdot g)$  on  $X \times G$ . If  $\phi(x)h(Tx) = h(x)$ , then there exists a G-valued function q(x) such that the following diagram commutes

$$\begin{array}{ccc} X \times G & \stackrel{T_{\phi}}{\longrightarrow} & X \times G \\ q & & & \downarrow q \\ X \times G & \stackrel{S}{\longrightarrow} & X \times G \end{array}$$

where  $Q(x,g) = (x,q(x) \cdot g)$  and S(x,g) = (Tx,g). Hence  $T_{\phi}$  has M ergodic components.

**PROOF:** Since  $(\phi(x))^M = 1$ ,  $(\phi(x))^M (h(Tx))^M = (h(x))^M$  is equivalent to  $(h(Tx))^M = (h(x))^M$ . So we may assume that  $(h(x))^M = 1$  by the ergodicity of T. Hence there exist a G-valued function q(x) such that  $\phi(x)q(Tx) = q(x)$ . For q(x), of this for it is easy to see that the diagram commutes.

**LEMMA 4.** Let  $\tau$  be piecewise, twice continuously differentiable and such that  $\inf_{x \in J_1} |\tau'(x)| > 1$  where  $J_1 = \{x \in X : \tau'(x) \text{ exists}\}$ . If the number of discontinuity points of  $\tau$  of  $\tau'$  is finite, then there is a finite collection of sets  $L_1, \ldots, L_n$  and a set of invariant functions  $\{f_1, \ldots, f_n\}$  such that

- (1) each  $L_i(1 \leq i \leq n)$  is a finite union of closed intervals;
- (2)  $L_i \cap L_j$  contains at most a finite number of points when  $i \neq j$ ;
- (3)  $f_i(x) = 0$  for  $x \notin L_i, 1 \leq i \leq n$ , and  $f_i(x) > 0$  for almost everywhere x in  $L_i$ ;
- (4)  $\int_{L_i} f_i(x) dx = 1$  for  $1 \le i \le n$ ;
- (5) every  $\tau$  invariant function can be written as  $f = \sum_{i=1}^{n} a_i f_i$  with suitable chosen  $\{a_i\}$ .

PROOF: For the proof, See [7].

**PROPOSITION 5.** If a G-valued function  $\phi(x)$  is a step function with finite discontinuity points  $a_1 \leq t_1 < \cdots < t_n < 1$ , then  $\phi(x)$  is not coboundary for any generalised L-covering map.

PROOF: Assume that  $\phi(x)h(Tx) = h(x)$ . Without loss of generality assume that X = [0, 1). Since  $X \times G = \bigcup_{k=0}^{M-1} \{X \times \exp((2k\pi i)/M)\}$ , we may identify  $\{X \times \exp((2k\pi i)/M)\}$  with the unit interval  $[k, k + 1), 0 \leq k < M$ . Since  $\phi(x)$  is a G-valued step function with finite discontinuity points, we can regard  $T_{\phi}$  as a piecewise continuous map on [0, M) satisfying the condition of Lemma 4. So we can say that h(x) is also a G-valued step function with finite discontinuity points by Lemma 4 and Proposition 4. Hence there exists  $0 < r \leq a_1$  such that h(x) is constant on [0, r). Thus  $\phi(x)h(x) = h(x)$  on [0, r). So h(x) is constant on [0, 1) by the argument of the proof of Proposition 2. The conclusion follows.

REMARK 2. In Proposition 5, we have not assumed that the discontinuity points are generalised L-adic points, but rather that the range of  $\phi(x)$  is contained in a finite subgroup of T. For generalised L-covering maps, mod M normality holds for finite unions of intervals, when the associated step function  $\phi(x)$  step satisfies the condition of Proposition 5. Indeed we may also show that the skew product transformation induced by  $\phi(x)$  is also exact on  $X \times G$ , as in fact strong mixing, using the similar arguments, to those in Remark 1.

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# 6. Mod M normality of Gauss transformation

Recall that the Gauss transformation T on [0, 1) is defined by

$$T(x) = \begin{cases} 0 & \text{if } x = 0 \\ \frac{1}{x} & \text{if } x \neq 0 \pmod{1}, \end{cases}$$

It is well known that T preserves the Gauss measure on [0, 1) given by

$$\mu(A) = \frac{1}{\log 2} \int_A \frac{1}{1+x} \, dx$$

Let  $\mathcal{P} = \{P_j\}$  be a partition on [0,1) defined by  $P_j = [(1/j+1), (1/j))$  for  $j \in \mathbb{N}$ .

**PROPOSITION 6.** Let  $\{B_i\}$  be a sequence of intervals of [0,1) with rational endpoints and  $\{b_i\}$  be a sequence of real numbers. Then a nonconstant function  $\phi(x) = \exp\left(2\pi i \sum_{i=1}^{n} b_i \mathbf{1}_{B_i}(x)\right)$  is not a coboundary for the Gauss transformation.

PROOF: Let  $Y = \prod_{-\infty}^{\infty} \{1, 2, ...\}$  and  $Y^+ = \prod_{0}^{\infty} \{1, 2, ...\}$ . Consider the following commutative diagram

$$\begin{array}{ccc} & [0,1) & \xrightarrow{T} & [0,1) \\ & \psi & & & \downarrow \psi \\ & & Y^+ & \xrightarrow{\sigma^+} & Y^+ \end{array}$$

where  $(\psi(x))_i = j$  if  $T^i x \in P_j$  for  $i \in \mathbb{N}$ . Then  $\psi$  is a an isomorphism between  $([0, 1), T, \mu)$ and  $(Y^+, \sigma^+, \nu^+)$  where  $\nu^+$  is the induced measure by  $\psi$  and  $\sigma^+$  is the one-sided shift map on  $Y^+$ . Let  $(Y, \sigma, \nu)$  be the natural extension of  $(Y^+, \sigma^+, \nu^+)$  where  $\sigma$  is the twosided shift map on Y. If  $\phi(x)g(Tx) = g(x)$  then g(x) is also step function with rational discontinuity points and there exist an interval I with rational end points such that g(x)is constant on I by the arguments of Proposition 1. Since  $T^n I = [0, 1)$  for some n,  $\phi(x)$  is a function with finite discontinuity points, and  $\phi(x)g(Tx) = g(x), g(x)$  is also a function with finite discontinuity points. Since  $\phi(x)g(Tx) = g(x)$  can be rewritten as  $\phi(x) = g(x)\overline{g(Tx)}, \phi(x)$  must be a function with infinite discontinuity points. this is a contradiction.

REMARK 3. By Proposition 6, mod M normality holds for finite union of intervals with rational end points on Gauss transformation. By the similar arguments as in Remark 1, the induced skew product transformation on  $X \times G$  is also exact.

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