

A THEOREM ON ANALYTIC MAPPINGS OF COMPLEX MANIFOLDS

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Dedicated to late professor TADASI NAKAYAMA

We prove in this paper a theorem on analytic mappings of the complex space C_n into the complex projective space P_n . The theorem is closely related to that of S. S. Chern in [1], and the main idea of the proof is the same with the latter, though the calculations are rather different. The background of our calculation is the normal contact metric structure which was found by S. Sasaki and Y. Hatakeyama [4].

Our purpose is to find a criterion for an analytic mapping f of C_n into P_n in order that $f(C_n)$ covers almost every part of P_n . We take cartesian coordinates z^1, \dots, z^n in C_n and then the metric is given by

$$d\Sigma^2 = \sum_{j=1}^n dz^j d\bar{z}^j. \quad (0.1)$$

As for the elliptic metric of P_n we have

$$dT^2 = (1 + |w|^2)^{-2} \left(\sum_{j=1}^n dw^j d\bar{w}^j + \sum_{j < k} |dw^j w^k - dw^k w^j|^2 \right) \quad (0.2)$$

in complex coordinates w^1, \dots, w^n , where we have put $|w| = (\sum w^j \bar{w}^j)^{1/2}$. An analytic mapping $f: C_n \rightarrow P_n$ can be represented by

$$w^j = f_j(z^1, \dots, z^n) \quad (j = 1, \dots, n), \quad (0.3)$$

where $f_j(z^1, \dots, z^n)$ are analytic functions. We put

$$f^*(dT^2) = \sum_{jk} a_{jk} dz^j d\bar{z}^k. \quad (0.4)$$

(a_{jk}) is a hermitian tensor on C_n which is determined by the mapping f . We denote the eigenvalues of (a_{jk}) by $\lambda_1, \dots, \lambda_n$ and put

$$B = \sum_{j=1}^n \lambda_1 \lambda_2 \cdots \lambda_{j-1} \lambda_{j+1} \cdots \lambda_n. \quad (0.5)$$

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We use the notations

D_r : the sphere $|z| \leq r$ in C_n , $S_r = \partial D_r$, $D(r_0, r) = D_r - D_{r_0}$

Ω : the volume element in P_n determined by the metric dT^2 .

We define $v(D_r)$ and $T_k(r)$ by

$$v(D_r) = \int_{D_r} f^* \Omega, \quad T_k(r) = \int_{r_0}^r \frac{v(D_r)}{r^k} dr, \tag{0.6}$$

where r_0 is a constant smaller than r . We denote by Θ an element of the solid angle about the origin of C_n and then the volume element in C_n can be given by

$$\Pi = r^{2n-1} dr \wedge \Theta, \tag{0.7}$$

where $|z| = r$. We put moreover

$$U(r) = \int_{D(r_0, r)} \frac{B}{r^{2n}} \Pi, \quad Y(r) = \frac{1}{I_{2n-1}} \int_{S_r} B r^{2n-2} \Theta, \tag{0.8}$$

where I_{2n-1} is the surface area of a unit sphere in C_n .

Now S. S. Chern's theorem in [1] is in our version

THEOREM A. *We assume that for $r \rightarrow \infty$ we have*

$$T_{2n-1}(r) \rightarrow \infty \quad \text{and} \quad U(r) = O(T_{2n-1}(r)).$$

Then the complement of $f(C_n)$ is of measure zero.

On the other hand our theorem is

THEOREM B. *We denote the measure of the complement of $f(D_r)$ by b , and the total measure of P_n by c ($= \pi^n/n!$). Then we have an inequality*

$$\frac{b}{c} \leq a \frac{Y(r)}{T_1(r)}.$$

where $a = \frac{1}{4} \left(1 + \frac{1}{2} + \dots + \frac{1}{n} \right)$.

Hence if

$$\lim_{r \rightarrow \infty} \frac{Y(r)}{T_1(r)} = 0,$$

the complement of $f(C_n)$ is of measure zero.

Theorem A lacks an example and even for the most simple mapping

$$w^j = z^j \quad (j = 1, 2, \dots, n) \tag{0.9}$$

the assumptions do not hold good, because $T_{2n-1}(r)$ and $U(r)$ are finite for $r \rightarrow \infty$ as we shall show afterwards. On the other hand we have

$$T_1(r) = O(\log r), \quad Y(r) \rightarrow 1$$

for $r \rightarrow \infty$ and (0.9) is an example of theorem B. We will prove theorem B and also give formulas to calculate $T_k(r)$, $Y(r)$ and $U(r)$. Hereafter we omit the summation symbol \sum for double indices and we assume throughout that the indices run as follows

$$j, k = 1, 2, \dots, n \quad a, b = 2, 3, \dots, n.$$

1. Decomposition of Kaehlerian metrics of C_n and P_n

A Kaehlerian metric on an n -dimensional complex analytic manifold M is a real analytic positive definite Riemannian metric which can locally be represented as

$$d\Sigma^2 = g_{jk}(z, \bar{z}) dz^j d\bar{z}^k \quad (g_{jk} = \bar{g}_{kj})$$

satisfying the relation $d(g_{jk} dz^j \wedge d\bar{z}^k) = 0$. When we take suitable local coframes

$$\sigma^j = p^j_k(z, \bar{z}) d\bar{z}^k \quad (j = 1, 2, \dots, n),$$

we have

$$d\Sigma^2 = \sigma^j \bar{\sigma}^j, \quad d(\sigma^j \wedge \bar{\sigma}^j) = 0.$$

Kaehlerian metric of C_n

This is given by

$$d\Sigma^2 = (dz, dz) = dz^j d\bar{z}^j. \tag{1.1}$$

We put

$$r = |z| = (z, z)^{1/2}, \quad r^{-1}z = (u^1, \dots, u^n)$$

and we get

$$d\Sigma^2 = dr^2 + r^2(du, du). \tag{1.2}$$

We take vectors $u_a = (u_a^1, u_a^2, \dots, u_a^n)$ ($a = 2, 3, \dots, n$) which constitute a unitary base together with $u = (u^1, \dots, u^n)$ and put

$$\theta = -i(du, u), \quad \mu^a = (du, u_a). \tag{1.3}$$

θ is a real form and we have

$$d\theta = i\mu^a \wedge \bar{\mu}^a. \tag{1.4}$$

The metric reduces to

$$(du, du) = \theta^2 + \mu^a \bar{\mu}^a \tag{1.5}$$

on a unit sphere $|u| = 1$. We have by (1.2) (1.5)

$$d\Sigma^2 = dr^2 + r^2\theta^2 + r^2\mu^a \bar{\mu}^a. \tag{1.6}$$

When we put

$$\mu^a = \theta^a + i\theta^{a+n} \quad (\theta^a, \theta^{a+n} \text{ are real forms}), \tag{1.7}$$

we get

$$d\Sigma^2 = dr^2 + r^2\theta^2 + r^2(\theta^a\theta^a + \theta^{a+n}\theta^{a+n}) \tag{1.8}$$

and the volume element of C_n is given by

$$H = dr \wedge r\theta \wedge r\theta^2 \wedge \dots \wedge r\theta^n \wedge r\theta^{n+2} \wedge \dots \wedge r\theta^{2n}.$$

We take an orientation of C_n in such a way that this form is positive. We put

$$\Theta_0 = \theta^2 \wedge \dots \wedge \theta^n \wedge \theta^{n+2} \wedge \dots \wedge \theta^{2n}, \quad \Theta = \theta \wedge \Theta_0 \tag{1.9}$$

and we get

$$H = r^{2n-1} dr \wedge \Theta. \tag{1.10}$$

The element of the area on the sphere $r = \text{const.}$ is $r^{2n-1}\theta$ and hence Θ is an element of a solid angle about the origin. Next we put

$$\sigma^1 = dr + ir\theta, \quad \sigma^a = r\mu^a. \tag{1.11}$$

Then we have

$$\sigma^1 = r^{-1}(dz, z), \quad \sigma^a = (dz, u_a) \tag{1.12}$$

and these do not contain $d\bar{z}^1, \dots, d\bar{z}^n$. Thus

$$d\Sigma^2 = \sigma^1 \bar{\sigma}^1 + \sigma^a \bar{\sigma}^a = \sigma^j \bar{\sigma}^j, \tag{1.13}$$

where the sum with respect to j ranges from 1 to n . When we represent Θ_0 by μ^a we get

$$\Theta_0 = (-1)^{n(n-1)/2} (2i)^{-n+1} \mu^2 \wedge \dots \wedge \mu^n \wedge \bar{\mu}^2 \wedge \dots \wedge \bar{\mu}^n. \tag{1.14}$$

Kaehlerian metric of P_n

We take a unit vector $p = (p^0, p^1, \dots, p^n)$ in C_{n+1} . We construct the n -dimensional projective complex space P_n in a usual way. The elliptic metric on P_n is given by

$$dT^2 = (dp, dp) - (dp, p)(p, dp) \tag{1.15}$$

and when we put

$$w^j = p^j/p^0 \quad (j = 1, 2, \dots, n), \tag{1.16}$$

we get (0.2). We take a unitary base e_0, e_1, \dots, e_n in C_{n+1} and for any unit vector p in C_{n+1} we define t by $\cos t = (e_0, p)$ ($0 \leq t \leq \frac{\pi}{2}$) and decompose p as $p = ae_0 + bv_1$ where $(e_0, v_1) = 0$ and $|v_1| = 1$. Then $|a| = \cos t, |a|^2 + |b|^2 = 1$. We take suitable real numbers α, β and put $e^{i\beta}v_1 = v$. Then we get $e^{i\alpha}p = \cos t \cdot e_0 + \sin t \cdot v$, where $(e_0, v) = 0, |v| = 1$. When we use $e^{i\alpha}p$ instead of p in (1.15), dT^2 is the same. We put

$$p = \cos t \cdot e_0 + \sin t \cdot v \tag{1.17}$$

into (1.15) and we get

$$dT^2 = dt^2 + \sin^2 t \cos^2 t \cdot \varphi^2 + \sin^2 t \cdot \nu^a \bar{\nu}^a, \tag{1.18}$$

where we have put

$$\varphi = -i(dv, v), \quad \nu^a = (dv, v_a), \tag{1.19}$$

v_a ($a = 2, 3, \dots, n$) being vectors which constitute a unitary base together with v in the complex hyperplane orthogonal to e_0 . We put moreover

$$\nu^a = \varphi^a + i\varphi^{a+n} \quad (\varphi^a, \varphi^{a+n} \text{ are real forms}) \tag{1.20}$$

and then

$$dT^2 = dt^2 + \sin^2 t \cos^2 t \cdot \varphi^2 + \sin^2 t (\varphi^a \varphi^a + \varphi^{a+n} \varphi^{a+n}) \tag{1.21}$$

and the volume element of P_n is

$$\Omega = dt \wedge \sin t \cos t \varphi \wedge \sin t \cdot \varphi^2 \wedge \dots \wedge \sin t \cdot \varphi^n \wedge \sin t \cdot \varphi^{n+2} \wedge \dots \wedge \sin t \cdot \varphi^{2n}.$$

We take an orientation of P_n in such a way that this form is positive definite.

We put

$$\Phi_0 = \varphi^2 \wedge \dots \wedge \varphi^n \wedge \varphi^{n+2} \wedge \dots \wedge \varphi^{2n}, \quad \Phi = \varphi \wedge \Phi_0, \tag{1.22}$$

then we get

$$\Omega = \sin^{2n-1} t \cos t dt \wedge \Phi. \tag{1.23}$$

The element of area on a sphere $t = \text{const.}$ is $\sin^{2n-1} t \cos t \cdot \Phi$. Hence Φ , which is the limit of $\sin^{2n-1} t \cos t \cdot \Phi / t^{2n-1}$ for $t \rightarrow 0$, is an element of a solid angle about the origin. We have

$$d\theta = 0. \quad (1.24)$$

We have by virtue of (1.16) (1.17) and $|p| = 1$

$$\cos t = p^0 = (1 + |w|^2)^{-1/2}. \quad (1.25)$$

As $\sin t \cdot v = (0, p^1, \dots, p^n) = (0, p^0 w^1, \dots, p^0 w^n)$, we have

$$v = (0, w^1/|w|, \dots, w^n/|w|).$$

We put

$$\tau^0 = dt + i \sin t \cos t \cdot \varphi, \quad \tau^a = \sin t \cdot \nu^a. \quad (1.26)$$

We get by (1.19) (1.25) (1.18)

$$\tau^1 = (dw, v)(1 + |w|^2)^{-1}, \quad \tau^a = (dw, v_a)(1 + |w|^2)^{-1/2}, \quad (1.27)$$

$$dT^2 = \tau^1 \bar{\tau}^1 + \tau^a \bar{\tau}^a = \tau^j \bar{\tau}^j. \quad (1.28)$$

When we represent θ_0 by ν^a , we get

$$\theta_0 = (-1)^{n(n+1)/2} (2i)^{-n+1} \nu^2 \wedge \dots \wedge \nu^n \wedge \bar{\nu}^2 \wedge \dots \wedge \bar{\nu}^n. \quad (1.29)$$

As $\nu^a \bar{\nu}^a$ is an elliptic metric on P_{n-1} (cf. [3] p. 314), we have

$$d\theta_0 = 0. \quad (1.30)$$

2. The first main theorem

The following formulation of the first main theorem of differentiable mapping is due to S. S. Chern. (cf. [2]) Let M be an m -dimensional differentiable manifold and N be a compact orientable Riemannian manifold of the same dimension. We consider a differentiable mapping $M \rightarrow N$. We denote the surface area of an m -dimensional unit sphere by I_{m-1} , the volume element of N by Ω and the total measure of N by c . We take a point a in N . Then there exists a function $u = u(x)$ on N satisfying the following conditions.

$$(i) \quad -\frac{1}{I_{m-1}} d(*du) = \frac{1}{c} \Omega$$

(ii) on a certain neighborhood of the point a we have

$$*du = (1 + \epsilon) \theta_a,$$

where θ_a is an element of a solid angle at a and $\epsilon \rightarrow 0$ as x tends to a .

Let f be a differentiable mapping $M \rightarrow N$ and D be a domain on M . We assume that for a point a of $f(M)$ the set $f^{-1}(a) \cap D$ consists of a finite number

of points p_1, \dots, p_k , which are interior points of D , and $f^{-1}(a) \cap \partial D$ is empty. We denote by $n(a)$, or more precisely $n(a, D)$, the degree of the mapping f about the point a . This is the sum of the degree of the mappings of small neighborhoods of each points p_1, \dots, p_k . We take functions above stated and put

$$\lambda = - \frac{1}{I_{m-1}} f^*(*du). \tag{2.1}$$

Then $n(a)$ can be represented as

$$n(a) = \frac{1}{c} \int_D f^* \Omega - \int_{\partial D} \lambda. \tag{2.2}$$

This is the first main theorem. The proof can be given by applying the Stokes' theorem to the form λ and the domain $D - \sum_{j=1}^k D_j(\epsilon)$ and making ϵ tend to 0, where $D_j(\epsilon)$ is a sphere of radius ϵ with respect to local coordinates about the point p_j .

The function u on P_n .

The function u which satisfies (i) and (ii) is determined uniquely up to an additive constant. We will find the one for P_n . We take the point a at $t=0$ and put $u = u(t)$, we have $du = u'dt$ ($u' = du/dt$) and by (1.21)

$$\begin{aligned} *du &= u'(\sin t \cos t \cdot \varphi) \wedge \sin^{2n-2} t \cdot \varphi^2 \wedge \dots \wedge \varphi^n \wedge \varphi^{n+2} \wedge \dots \wedge \varphi^{2n}. \\ &= u' \sin^{2n-1} t \cos t \cdot \Phi \\ d(*du) &= (u' \sin^{2n-1} t \cos t)' dt \wedge \Phi. \end{aligned}$$

As $\Omega = \sin^{2n-1} t \cos t \cdot dt \wedge \Phi$ by (1.23) in our case, we get

$$(u' \sin^{2n-1} t \cos t)' = -2n \sin^{2n-1} t \cos t.$$

Hence by (ii) $u' \sin^{2n-1} t \cos t = 1 - \sin^{2n} t$

$$*du = (1 - \sin^{2n} t) \Phi \tag{2.3}$$

and also

$$u = \log \sin t - \sum_{k=1}^{n-1} \frac{1}{2k \sin^{2k} t}. \tag{2.4}$$

3. Integrated form of the first main theorem

We take a sphere $D_r : |z| \leq r$ in C_n and put $\partial D_r = S_r$, and apply the first main theorem to the mapping $f : C_n \rightarrow P_n$. Then we have by (2.2)

$$n(a, D_r) = \frac{1}{c} \int_{D_r} f^* \Omega - \int_{S_r} \lambda.$$

We divide by r^k (k const.) and integrate from r_0 to r with respect to r . Putting

$$N_k(a, D_r) = \int_{r_0}^r \frac{n(a, D_r)}{r^k} dr \tag{3.1}$$

and taking (0.6) into consideration we get

$$N(a, D_r) = \frac{1}{c} T_k(r) + \frac{1}{I_{2n-1}} J_k, \tag{3.2}$$

where

$$J_k = -I_{2n-1} \int_{D(r_0, r)} A \tag{3.3}$$

with

$$\begin{aligned} A &= -I_{2n-1} r^{-k} dr \wedge \lambda = r^{-k} dr \wedge f^*(* du) \\ &= r^{-k} dr \wedge f^*((1 - \sin^2 t)\Phi). \end{aligned} \tag{3.4}$$

Estimation of J_k

We take coframes in C_n and P_n as in (1.13) and (1.28). We can put

$$f^* \tau^j = p_k^j \sigma^k \tag{3.5}$$

by virtue of (0.3) (1.12) (1.27). Hence

$$f^*(d\Sigma^2) = a_{jk} \sigma^j \bar{\sigma}^k \quad (a_{jk} = p_j^h \bar{p}_k^h). \tag{3.6}$$

Hereafter we often omit conventionally such notation f^* as in (3.4) (3.5) (3.6).

We consider such a case that $\det(a_{jk}) \neq 0$, namely $\det(p_j^k) \neq 0$. Then we can put by (3.5)

$$\begin{aligned} \sigma^1 &= q_1^1 \tau^1 + q_a^1 \tau^a, & \sigma^a &= q_1^a \tau^1 + q_b^a \tau^b. \\ & & (a, b = 2, \dots, n) \end{aligned} \tag{3.7}$$

We have by (1.11) (1.26)

$$\begin{aligned} dr + i r \theta &\equiv q_1^1 (dt + i \sin t \cos t \cdot \varphi) \\ dr - i r \theta &\equiv \bar{q}_1^1 (dt - i \sin t \cos t \cdot \varphi). \\ & \pmod{\nu^2, \nu^3, \dots, \nu^n} \end{aligned} \tag{3.8}$$

Hence we get

$$\sin t \cos t dr \wedge \varphi \wedge \theta_0 = r dt \wedge \theta \wedge \theta_0. \tag{3.9}$$

This can be verified by solving (3.8) with respect to $dr, r\theta$ and putting dr

into the right side and $r\theta$ into the left side. Here we assumed $\det(p_j^k) \neq 0$. But (3.9) is an algebraic consequence of (3.5) and so (3.9) is true for the case $\det(p_j^k) = 0$, too.

As $\theta = \varphi \wedge \theta_0$, we get by (3.4) (3.9)

$$A = \frac{1 - \sin^{2n} t}{\sin t \cos t} r^{-k+1} dt \wedge \theta \wedge \theta_0. \tag{3.10}$$

We put

$$v = -\log \sin t + \frac{1}{2} \sum_{k=1}^{n-1} (-1)^{k-1} \frac{1}{k} \binom{n-1}{k} \cos^{2k} t. \tag{3.11}$$

The second term on the right side is one obtained by putting $s = \cos^2 t$ in the integral $\int_1^s \frac{1 - (1-s)^{n-1}}{s} ds$. Hence

$$v \geq 0 \quad \text{for} \quad \frac{\pi}{2} \geq t > 0. \tag{3.12}$$

We get by (3.11)

$$v' = \frac{dv}{dt} = -\frac{1 - \sin^{2n} t}{\sin t \cos t}. \tag{3.13}$$

Hence by the relation $d\theta_0 = 0$

$$A = -r^{k+1} dv \wedge \theta \wedge \theta_0 = d(-r^{k+1} v \theta \wedge \theta_0) + v d(r^{-k+1} \theta) \wedge \theta_0.$$

Hence we have

$$J_k = \int_{D(r_0, r)} A = -\int_{S_r} r^{-k+1} v \theta \theta_0 + \int_{S_{r_0}} r^{-k+1} v \theta \theta_0 + \int_{D(r_0, r)} v d(r^{-k+1} \theta) \cdot \theta_0. \tag{3.14}$$

By (1.11) (1.26) (3.5)

$$\begin{aligned} \sin t \cdot v^a &\equiv p_b^a r v^b. & (\text{mod } \sigma^1 = dr + ir\theta) \\ & & (a, b = 2, \dots, n) \end{aligned}$$

We put

$$\Delta = \det(p_b^a) \tag{3.15}$$

and we get by (1.9) (1.28)

$$\sin^{2n-2} t \cdot \theta_0 \equiv r^{2n-2} \Delta \bar{\Delta} \theta_0. \quad (\text{mod } dr, \theta) \tag{3.16}$$

As we have $dr = 0$ on S_r , we get

$$\sin^{2n-2} t \cdot \theta \wedge \theta_0 = r^{2n-2} \Delta \bar{\Delta} \theta \wedge \theta_0. \tag{3.17}$$

Hence taking $\theta = \theta \wedge \theta_0$ into consideration

$$r^{-k+1}v\theta \wedge \mathcal{O}_0 = v \sin^{-2n+2}t \cdot \Delta \bar{\Delta} r^{2n-k-1}\theta. \tag{3.18}$$

By (1.4) and (1.11) we have

$$d\theta = i\mu^a \wedge \bar{\mu}^a = ir^{-2}\sigma^a \wedge \bar{\sigma}^a, \quad \sigma^1 \wedge \bar{\sigma}^1 = -2ir dr \wedge \theta.$$

Hence we get

$$\begin{aligned} d(r^{-k+1}\theta) \wedge \mathcal{O}_0 &= r^{-k+1}d\theta \wedge \mathcal{O}_0 - (k-1)r^{-k}dr \wedge \theta \wedge \mathcal{O}_0 \\ &= ir^{-k-1}(\sigma^1 \wedge \bar{\sigma}^1 + \sigma^a \wedge \bar{\sigma}^a) \wedge \mathcal{O}_0 - (k+1)r^{-k}dr \wedge \theta \wedge \mathcal{O}_0 \\ &= ir^{-k-1}(\sigma^j \wedge \bar{\sigma}^j) \wedge \mathcal{O}_0 - (k+1)r^{-k}dr \wedge \theta \wedge \mathcal{O}_0. \end{aligned} \tag{3.19}$$

By virtue of (3.16)

$$dr \wedge \theta \wedge \mathcal{O}_0 = r^{2n-2} \sin^{-2n+2}t \cdot \Delta \bar{\Delta} dr \wedge \theta \wedge \mathcal{O}_0 \tag{3.20}$$

and also

$$i(\sigma^j \wedge \bar{\sigma}^j) \wedge \mathcal{O}_0 = 2C_0 r^{2n-3} \sin^{-2n+2}t dr \wedge \theta \wedge \mathcal{O}_0. \tag{3.21}$$

Here

$$C_0 = \det(c_{ab}), \quad c_{ab} = p_j^a \bar{p}_j^b. \quad (a, b = 2, \dots, n) \tag{3.22}$$

(3.21) can be verified as follows. By (1.29) and (1.26)

$$\sin^{2n-2}t \cdot \mathcal{O}_0 = (-1)^{n(n-1)/2} (2i)^{-n+1} \tau^2 \wedge \dots \wedge \tau^n \wedge \bar{\tau}^2 \wedge \dots \wedge \bar{\tau}^n.$$

We put $\tau^a = p_j^a \sigma^j$ into the right side and multiply by $\sigma^j \wedge \bar{\sigma}^j$. When we put

$$P = \begin{pmatrix} p_1^1 & p_2^1 & \dots & p_n^1 \\ p_1^2 & p_2^2 & \dots & p_n^2 \\ \dots & \dots & \dots & \dots \\ p_1^n & p_2^n & \dots & p_n^n \end{pmatrix}, \quad P_1 = \begin{pmatrix} p_1^2 & p_2^2 & \dots & p_n^2 \\ \dots & \dots & \dots & \dots \\ p_1^n & p_2^n & \dots & p_n^n \end{pmatrix} \tag{3.23}$$

and denote by Δ_j the minor determinant corresponding to p_j^1 in P , we get

$$\begin{aligned} &\sigma^j \wedge \bar{\sigma}^j \wedge \tau^2 \wedge \dots \wedge \tau^n \wedge \bar{\tau}^2 \wedge \dots \wedge \bar{\tau}^n \\ &= \Delta_j \bar{\Delta}_j \sigma^1 \wedge \bar{\sigma}^1 \wedge \sigma^2 \wedge \bar{\sigma}^2 \wedge \dots \wedge \sigma^n \wedge \bar{\sigma}^n \wedge \sigma^3 \wedge \bar{\sigma}^3 \wedge \dots \wedge \bar{\sigma}^n \\ &= \det(P_1^t \bar{P}_1) (-2ir) dr \wedge \theta \wedge \sigma^2 \wedge \dots \wedge \sigma^n \wedge \bar{\sigma}^2 \wedge \dots \wedge \bar{\sigma}^n. \end{aligned}$$

As $C_0 = \det(P_1^t \bar{P}_1)$, we get the verification of (3.21) by virtue of (1.11) and (1.14).

By putting (3.20) (3.21) into (3.19) and taking $\theta = \theta \wedge \mathcal{O}_0$ into consideration we get

$$d(r^{-k+1}\theta) \wedge \mathcal{O}_0 = 2r^{2n-k-1} \sin^{-2n+2}t \left(C_0 - \frac{k+1}{2} \Delta \bar{\Delta} \right) dr \wedge \theta. \tag{3.24}$$

By (3.18) (3.24) we get from (3.14)

$$J_k = - \int_{S_r} v \sin^{-2n+2} t \cdot \Delta \bar{\Delta} r^{2n-k-1} \Theta + \int_{S_{r_0}} v \sin^{-2n+2} t \cdot \Delta \bar{\Delta} r^{2n-k-1} \Theta + \int_{D(r_0, r)} 2 v r^{2n-k-1} \sin^{-2n+2} t \left(C_0 - \frac{k+1}{2} \Delta \bar{\Delta} \right) dr \Theta. \quad (3.25)$$

C_0 determined by (3.22) is a minor determinant corresponding to c_{11} of the matrix $P^t \bar{P} = (c_{jk})$ ($j, k = 1, 2, \dots, n$) and $P^t \bar{P}$ is a hermitian matrix which is positive definite or semi-definite. Hence C_0 is not greater than the sum of principal determinants of $n - 1$ -th order of $P^t \bar{P}$, namely the sum of products of $n - 1$ numbers taken arbitrarily from n eigenvalues of $P^t \bar{P}$. On the other hand we have by (3.6)

$$(a_{jk}) = {}^t P \bar{P} = \bar{P}^{-1} (\overline{{}^t P \bar{P}}) \bar{P}$$

and so the eigenvalues of (a_{jk}) are the same with those of $\overline{{}^t P \bar{P}}$ namely of $P^t \bar{P}$. Hence by the definition of B in (0.5) we have

$$C_0 \leq B. \quad (3.26)$$

By taking (3.15) (3.23) into consideration we have

$$\Delta \bar{\Delta} \leq C_0 \leq B. \quad (3.27)$$

Hence by (3.12) (3.25) (3.27) we get for $k = 1$

$$J_1 \geq - \int_{S_r} v \sin^{-2n+2} t B r^{2n-2} \Theta. \quad (3.28)$$

This is the most important key to our proof of theorem B.

4. The final step of the proof

We denote the complement of $f(D_r)$ by K , whose measure b we will estimate. For any point a in K we have $n(a, D_r) = 0$ and so by (3.2) we get

$$\frac{1}{c} T_1(r) + \frac{1}{I_{2n-1}} J_1 = 0. \quad (4.1)$$

Hence we get by (3.28)

$$\frac{1}{c} I_{2n-1} T_1(r) \leq \int_{S_r} v \sin^{-2n+2} t \cdot B r^{2n-2} \Theta. \quad (4.2)$$

We multiply the both sides by the invariant volume element Ω of P_n with

respect to the point a and integrate on K . Then we have

$$\frac{b}{c} I_{2n-1} T_1(r) \leq \int_{S_r} \left(\int_K v \sin^{-2n+2} t \cdot \Omega \right) B r^{2n-2} \Phi. \tag{4.3}$$

In the first we fix a point p on S_r and estimate the integral in the bracket on the right side of (4.3). As t is a distance from the point a to the point p and Ω is the invariant measure, we get by (1.23)

$$\Omega = \sin^{2n-1} t \cos t \, dt \wedge \Phi,$$

when we take coordinates such that $t = 0$ for the point p . Hence we get

$$\int_K v \sin^{-2n+2} t \cdot \Omega \leq \int_{P_n} v \sin t \cos t \, dt \cdot \Phi.$$

Here we have $\int \Phi = I_{2n-1}$ and by (3.13)

$$\begin{aligned} \int_0^{\pi/2} v \sin t \cos t \, dt &= \left[v \frac{1}{2} \sin^2 t \right]_0^{\pi/2} - \int_0^{\pi/2} \frac{dv}{dt} \frac{1}{2} \sin^2 t \, dt \\ &= \frac{1}{2} \int_0^{\pi/2} (1 - \sin^{2n} t) \frac{\sin t}{\cos t} \, dt = \frac{1}{4} \int_0^1 \frac{1-s^{2n}}{1-s} \, ds \quad (s = \sin^2 t) \\ &= \frac{1}{4} \left(1 + \frac{1}{2} + \dots + \frac{1}{n} \right) = a. \end{aligned}$$

Thus by (4.3)

$$\frac{b}{c} I_{2n-1} T_1(r) \leq a \int_{S_r} B r^{2n-2} \Phi = a I_{2n-1} Y(r),$$

namely

$$\frac{b}{c} \leq a \frac{Y(r)}{T_1(r)}$$

This is theorem B .

5. Explicit calculations of $T_1(r)$, $T_{2n-1}(r)$, $Y(r)$ and $U(r)$

In the last we will show how to calculate these numbers for the mapping (0.3) and will actually calculate in the case (0.9). In this section we do not omit the symbol \sum representing the summation.

In the first we denote by P_j a matrix obtained from P by omitting the j -th row and by A_k^j the minor determinant of P corresponding to p_k^j . Then we have

$$B = \sum_j \det(P_j^t \bar{P}_j) = \sum_{j,k} A_k^j \bar{A}_k^j,$$

Now we put

$$T^j = \tau^1 \wedge \tau^2 \wedge \dots \wedge \tau^{j-1} \wedge \tau^{j+1} \wedge \dots \wedge \tau^n.$$

We have by (3.5) (0.5)

$$\left(\sum_j \sigma^j \wedge \bar{\sigma}^j\right) \wedge \left(\sum_k T^k \wedge \bar{T}^k\right) = (-1)^{n-1} B \sigma^1 \wedge \dots \wedge \sigma^n \wedge \bar{\sigma}^1 \wedge \dots \wedge \bar{\sigma}^n. \tag{5.1}$$

Taking (1.26) into consideration we put

$$\sigma^j = dz^j, \quad \tau^1 = (dw, v \cdot (1 + |w|^2)^{-1}), \quad \tau^a = (dw, v_a)(1 + |w|^2)^{-1/2}.$$

As v_a ($a = 2, \dots, n$) constitute a unitary base with $v = w|w|^{-1}$ we get after some calculation

$$\begin{aligned} T^1 &= \tau^2 \wedge \dots \wedge \tau^n \\ &= \varepsilon(1 + |w|^2)^{-(n-1)/2} |w|^{-1} \sum_j (-1)^{j-1} \bar{w}^j dw^1 \wedge \dots \wedge \widehat{dw}^j \wedge \dots \wedge dw^n \\ T^a &= \tau^1 \wedge \dots \wedge \widehat{\tau}^a \wedge \dots \wedge \tau^n \\ &= (-1)^a \varepsilon(1 + |w|^2)^{-n/2} \sum_j (-1)^{j-1} v_a^j dw^1 \wedge \dots \wedge \widehat{dw}^j \wedge \dots \wedge dw^n, \end{aligned}$$

where \wedge means that the indicated term is absent in the product, and ε is a determinant formed by the components of v, v_2, \dots, v_n . We put these into the left side of (5.1) and get

$$B = (1 + |w|^2)^{-n} \left(\sum_j K_{jj} + \sum_{i,j} \bar{w}^i w^j K_{ij}\right), \tag{5.2}$$

where K_{ij} is a cofactor corresponding to k_{ij} of the matrix $K = (k_{ij})$ defined by

$$J = \begin{pmatrix} \frac{\partial w^1}{\partial z^1} & \dots & \frac{\partial w^1}{\partial z^n} \\ \dots & \dots & \dots \\ \frac{\partial w^n}{\partial z^1} & \dots & \frac{\partial w^n}{\partial z^n} \end{pmatrix}. \quad K = J^t J.$$

On the other hand we have

$$\tau^1 \wedge \tau^2 \wedge \dots \wedge \tau^n = (1 + |w|^2)^{-(n+1)/2} \varepsilon dw^1 \wedge dw^2 \wedge \dots \wedge dw^n.$$

and the volume element Ω of P_n is given by

$$\Omega = (1 + |w|^2)^{-(n+1)} \det K \cdot r^{2n-1} dr \wedge \theta.$$

For the special case $w^j = f_j(z^j)$ ($j = 1, 2, \dots, n$) we have

$$B = (1 + |w|^2)^{-n} \sum_j (1 + |f_j|^2) |f'_1 \dots \widehat{f'_j} \dots f'_n|^2.$$

For a simple mapping

$$w^j = z^j \quad (5.3)$$

we have

$$\Omega = \frac{r^{2n-1}}{(1+r^2)^{n+1}} dr \wedge \Theta, \quad B = \frac{n+r^2}{(1+r^2)^n} \quad (|z|=r)$$

Hence

$$\begin{aligned} v(D_r) &= \int_{D_r} \Omega = \frac{1}{2n} I_{2n-1} \left(\frac{r^2}{r^2+1} \right)^n \\ T_1(r) &= \int_{r_0}^r \frac{v(D_r)}{r} dr = \frac{1}{4n} I_{2n-1} \left[\log(r^2+1) + \sum_{k=1}^{n-1} (-1)^{k-1} \frac{1}{k} \binom{n-1}{k} \frac{1}{(r^2+1)^k} \right] \Big|_{r_0}^r \\ Y(r) &= \frac{1}{I_{2n-1}} \int_{s_r} B r^{2n-2} \Theta = \frac{r^{2n-2}(n+r^2)}{(1+r^2)^n} \end{aligned}$$

As $r \rightarrow \infty$, $T_1(r) = O(\log r)$, $Y(r) \rightarrow 1$ and (5.3) is an example of theorem B. On the other hand we have for $n > 1$

$$\begin{aligned} T_{2n-1}(r) &= \frac{I_{2n-1}}{2n} \int_{r_0}^r \frac{r dr}{(1+r^2)^n} = \left[-\frac{I_{2n-1}}{4n(n-1)} \cdot \frac{1}{(1+r^2)^{n-1}} \right]_{r_0}^r \\ U(r) &= \int_{D(r_0, r)} \frac{B}{r} dr \cdot \Theta = I_{2n-1} \int_{r_0}^r \frac{n+r^2}{r(1+r^2)^n} dr \end{aligned}$$

Hence $T_{2n-1}(r)$ and $U(r)$ is finite as $r \rightarrow \infty$ and (5.3) is not an example of theorem A.

In theorem A the case $k = 2n - 1$ is treated and the result can be got by omitting the terms

$$-\int_{s_r} v \sin^{-2n+2} t \cdot \Delta \bar{\Delta} \Theta, \quad -\int_{D(r_0, r)} 2n v r^{-1} \sin^{-2n+2} t \cdot \Delta \bar{\Delta} dr \Theta$$

in J_{2n-1} . For the simple mapping (5.3) these terms have the same order with the remaining terms, while we have omitted the term containing $C_0 - \frac{1}{2}(k+1) \Delta \bar{\Delta} = C_0 - \Delta \bar{\Delta}$ in theorem B, which is natural for the mapping (5.3).

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