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# NONOSCILLATORY SOLUTIONS OF NEUTRAL DELAY DIFFERENTIAL EQUATIONS 

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Consider the following neutral delay differential equation

$$
\begin{equation*}
\frac{d}{d t}[x(t)+p x(t-\tau)]+Q(t) x(t-\delta)=0, t \geqslant t_{0} \tag{*}
\end{equation*}
$$

where $p \in R, \tau \in(0, \infty), \delta \in R^{+}=[0, \infty)$ and $Q \in C\left(\left[t_{0}, \infty\right), R\right)$. We show that if

$$
\int_{0}^{\infty}|Q(s)| d s<\infty
$$

then Equation (*) has a nonoscillatory solution when $p \neq-1$. We also deal in detail with a conjecture of Chuanxi, Kulenovic and Ladas, and Györi and Ladas.

## 1. Introduction

Consider the following neutral delay differential equation

$$
\begin{equation*}
\frac{d}{d t}[x(t)+p x(t-\tau)]+Q(t) x(t-\delta)=0, t \geqslant t_{0} \tag{1}
\end{equation*}
$$

where

$$
\begin{equation*}
p \in R, \tau \in(0, \infty), \delta \in R^{+}=[0, \infty) \text { and } Q \in C\left(\left[t_{0}, \infty\right), R\right) \tag{2}
\end{equation*}
$$

Recently, the oscillation and asymptotic behaviour of Equation (1) have been investigated by many authors, see for example $[1,2,3,5,6,7,8]$. For a recent survey, see [4]. All the papers mentioned above, however, assume that $Q(t)$ is nonnegative. Considerably less is known about the behaviour of the solutions of Equation (1) when the coefficient $Q(t)$ is oscillatory. In particular, by combining the result in [5, 7, and 8] we know that if

$$
\begin{equation*}
Q(t) \geqslant 0 \text { and } \int_{t_{0}}^{\infty} Q(s) d s<\infty \tag{3}
\end{equation*}
$$

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then Equation (1) has a nonoscillatory solution when $p \neq-1$. For the critical case $p=-1, Y u$, Wang and Qian [5] found a sufficient condition for the oscillation of all solutions of Equation (1) under the assumption (3). One of our aims in this paper is to study the existence of a nonoscillatory solution of Equation (1) when $Q(t)$ is oscillatory. In section 2 , we show that

$$
\begin{equation*}
\int_{0}^{\infty}|Q(s)| d s<\infty \tag{4}
\end{equation*}
$$

implies that Equation (1) has a nonoscillatory solution when $p \neq-1$.
In addition, the following result on the asymptotic behaviour of a nonoscillatory solution of Equation (1) has been established by Chuanxi, Kulenovic and Ladas [2], see also [4].

Theorem A. [2] Assume that (2) holds and that

$$
\begin{equation*}
Q(t) \geqslant 0 \text { and } \int_{t_{0}}^{\infty} Q(s) d s=\infty \tag{5}
\end{equation*}
$$

Let $x(t)$ be nonoscillatory solution of Equation (1). Then the following statements hold:
(a) If $p<-1$, then $\lim _{t \rightarrow \infty}|x(t)|=\infty$
(b) If $p>-1$, and $p \neq 1$, then $\lim _{t \rightarrow \infty} x(t)=0$.

Remark 1. As was shown in [1] and [2], the assumption tht $p=-1$, as well as (2) and (5) hold, implies that every solution of Equation (1) oscillates. Thus the assumption in the above Theorem A that $p \neq-1$ is harmless. But, the case $p=1$ has not yet been handled. Therefore, Chuanxi, Kulenovic and Ladas [2] posed the following conjecture. See also [4, Problem 6.12.9 (Conjecture)].

Conjecture B. [2, 4] Assume that (2) and (5) hold. Let $x(t)$ be a nonoscillatory solution of the neutral differential equation

$$
\begin{equation*}
\frac{d}{d t}[x(t)+x(t-\tau)]+Q(t) x(t-\delta)=0, t \geqslant t_{0} \tag{6}
\end{equation*}
$$

Then

$$
\begin{equation*}
\lim _{t \rightarrow \infty} x(t)=0 \tag{7}
\end{equation*}
$$

The second aim in this paper is to answer in detail the above Conjecture B. In section 3, we first give an existence result of a nonoscillatory solution not satisfying (7) of Equation (6), and then by using this result we answer Conjecture $B$ in the negative.

Finally, we also show that, under appropriate additional hypothesis on $Q(t)$, Conjecture $B$ is also true.

Let $t_{1} \geqslant t_{0}$ and let $\phi \in C\left(\left[t_{1}-m\right], R\right)$, where $m=\max \{\tau, \delta\}$. By a solution of Equation (1) with initial function $\phi$ at $t_{1}$ we mean a function $x \in C\left(\left[t_{1}-m\right], \infty, R\right)$ such that $x(t)=\phi(t)$ for $t \in\left[t_{1}-m, t_{1}\right], x(t)+p x(t-\tau)$ is continuously differentiable for $t \geqslant t_{1}$ and $x(t)$ satisfies Equation (1) for all $t \geqslant t_{1}$.

As usual, a solution of Equation (1) is called nonoscillatory if it is eventually positive or eventually negative and oscillatory if it has arbitrarily large zeros.

## 2. Nonoscillatory solutions of equation (1)

In this section we study the existence of a nonoscillatory solution of Equation (1) with $p \neq-1$. The main result in this section is the following theorem.

Theorem 1. Assume that (2) and (4) hold with $p \neq-1$. Then Equation (1) has a nonoscillatory solution.

Proof: The proof of this theorem is rather long and will be divided into five claims. Let $X$ be the set of all continuous and bounded functions on $\left[t_{0}, \infty\right)$ with the sup-norm. Then $X$ is a Banach space.

Claim 1. For the case $-1<p \leqslant 0$, choose a $t_{1}>t_{0}$ sufficiently large such that $t_{1}-\tau \geqslant t_{0}, t_{1}-\delta \geqslant t_{0}$ and

$$
\int_{t_{1}}^{\infty}|Q(s)| d s \leqslant \frac{1+p}{4}
$$

Define a bounded, closed and convex subset of $X$ as follows

$$
A=\left\{x \in X ; \frac{2(1+p)}{3} \leqslant x(t) \leqslant \frac{4}{3} \text { for } t \geqslant t_{0}\right\}
$$

Now we define a mapping $T: A \rightarrow X$ as follows

$$
(T x)(t)= \begin{cases}1+p-p x(t-\tau)+\int_{t}^{\infty} Q(s) x(s-\delta) d s, & t \geqslant t_{1} \\ (T x)\left(t_{1}\right), & t_{0} \leqslant t \leqslant t_{1}\end{cases}
$$

Clearly, $T$ is continuous. For every $x \in A$ and $t \geqslant t_{1}$, we see that
and

$$
\begin{aligned}
& (T x)(t) \leqslant 1+p-\frac{4}{3} p+\frac{4}{3} \frac{1+p}{4}=\frac{4}{3} \\
& (T x)(t) \geqslant 1+p-\frac{4}{3} \frac{1+p}{4}=\frac{2(1+p)}{3}
\end{aligned}
$$

Hence, $(2(1+p)) / 3 \leqslant(T x)(t) \leqslant 4 / 3$ for $t \geqslant t_{0}$ and so $T A \subset A$.
Now we shall shows that $T$ is a contraction mapping on $A$. In fact, for any $x_{1}, x_{2} \in A$ and $t \geqslant t_{1}$ we have

$$
\begin{aligned}
\left|\left(T x_{1}\right)(t)-\left(T x_{2}\right)(t)\right| \leqslant & -p\left|x_{1}(t-\tau)-x_{2}(t-\tau)\right| \\
& \quad+\int_{t}^{\infty}|Q(s)|\left|x_{1}(s-\delta)-x_{2}(s-\delta)\right| d s \\
\leqslant & \frac{1-3 p}{4}\left\|x_{1}-x_{2}\right\|
\end{aligned}
$$

Then it follows that

$$
\left\|T x_{1}-T x_{2}\right\| \leqslant \frac{1-3 p}{4}\left\|x_{1}-x_{2}\right\|
$$

Since $0<(1-3 p) / 4<1$, we see that $T$ is a contraction. Therefore, by the Banach contraction principle, $T$ has a fixed point $x \in A$, that is, $T x=x$. Clearly, $x(t)$ is a positive solution of Equation (1) on $\left[t_{1}, \infty\right)$ and so the proof of Claim 1 is complete.

Claim 2. For the case $p<-1$, let $t_{1}>t_{0}$ be such that $t_{1}+\tau-\delta \geqslant t_{0}$ and

Set

$$
\begin{gathered}
\int_{t+\tau}^{\infty}|Q(s)| d s \leqslant-\frac{1+p}{4} \\
A=\left\{x \in X ;-\frac{p}{2} \leqslant x(t) \leqslant-2 p \text { for } t \geqslant t_{0}\right\}
\end{gathered}
$$

Then $A$ is a bounded, closed and convex subset of $X$. Define a mapping $T: A \rightarrow X$ as follows

$$
(T x)(t)= \begin{cases}-p-1-\frac{1}{p} x(t+\tau)+\frac{1}{p} \int_{t+\tau}^{\infty} Q(s) x(s-\delta) d s, & t \geqslant t_{1} \\ (T x)\left(t_{1}\right), & t_{0} \leqslant t \leqslant t_{1}\end{cases}
$$

In is easy to show that $T$ maps $A$ into itself, and by a fashion similar to that in the proof of Claim 1 we see that for any $x_{1}, x_{2} \in A$

$$
\left\|T x_{1}-T x_{2}\right\| \leqslant \frac{p-3}{4 p}\left\|x_{1}-x_{2}\right\|
$$

This means that $T$ is a contraction, since $0<(p-3) /(4 p)<1$. Therefore, by the Banach contraction principle, $T$ has a fixed point $x \in A$. It is easy to see that this $x$ is a positive solution of Equation (1) and the proof of Claim 2 is finished.

CLaIm 3. For the case $0<p<1$, let $t_{1}>t_{0}$ be such that $t_{1}-\tau \geqslant t_{0}, t_{1}-\delta \geqslant t_{0}$ and

Set

$$
\begin{gathered}
\int_{t_{1}}^{\infty}|Q(s)| d s \leqslant \frac{1-p}{4} \\
A=\left\{x \in X: 2(1-p) \leqslant x(t) \leqslant 4 \text { for } t \geqslant t_{0}\right\}
\end{gathered}
$$

which is a bounded, closed and convex subset of $X$. Define $T: A \rightarrow X$ as follows:

$$
(T x)(t)= \begin{cases}3+p-p x(t-\tau)+\int_{t}^{\infty} Q(s) x(s-\delta) d s, & t \geqslant t_{1} \\ (T x)\left(t_{1}\right), & t_{0} \leqslant t \leqslant t_{1}\end{cases}
$$

It is easy to show that $T$ maps $A$ into $A$ and for any $x_{1}, x_{2} \in A$,

$$
\left\|T x_{1}-T x_{2}\right\| \leqslant \frac{1+3 p}{4}\left\|x_{1}-x_{2}\right\|
$$

As $0<(1+3 p) / 4<1$, the Banach contraction principle can be applied to obtain a fixed point $x \in A$. We can see easily that this $x$ is a positive solution of Equation (1). This completes the proof of Claim 3.

Claim 4. For the case $p=1$, let $t_{1}>t_{0}$ be such that $t_{1}+\tau-\delta \geqslant t_{0}$ and

$$
\int_{t_{1}+\tau}^{\infty}|Q(s)| d s \leqslant \frac{1}{4}
$$

Clearly, the set

$$
A=\left\{x \in X: 2 \leqslant x(t) \leqslant 4, \text { for } t \geqslant t_{0}\right\}
$$

is a bounded, closed and convex subset of $X$. Define a mapping $T$ on $A$ as follows

$$
(T x)(t)= \begin{cases}3+\sum_{i=1}^{\infty} \int_{t+(2 i-1) \tau}^{t+2 i \tau} Q(s) x(s-\delta) d s, & t \geqslant t_{1} \\ (T x)\left(t_{1}\right), & t_{0} \leqslant t \leqslant t_{1}\end{cases}
$$

Clearly $T$ is continuous. It is easy to show that $T$ maps $A$ into $A$ and for any $x_{1}, x_{2} \in A$,

$$
\left\|T x_{1}-T x_{2}\right\| \leqslant \frac{1}{4}\left\|x_{1}-x_{2}\right\|
$$

Thus, by the Banach contraction principle, $T$ has a fixed point $x \in A$, that is,

$$
x(t)= \begin{cases}3+\sum_{i=1}^{\infty} \int_{t+(2 i-1) \tau}^{t+2 i \tau} Q(s) x(s-\delta) d s, & t \geqslant t_{1} \\ x\left(t_{1}\right), & t_{0} \leqslant t \leqslant t_{1}\end{cases}
$$

It follows that $x(t)+x(t-\tau)=6+\int_{t}^{\infty} Q(s) x(s-\delta) d x, t \geqslant t_{1}+\tau$.
From this we see that $x(t)$ is a positive solution of Equation (1) with $p=1$ on $\left[t_{1}+\tau, \infty\right)$ and so the proof for the case $p=1$ is complete.

Claim 5. Finally we consider the last case when $p>1$. Let $t_{1}>t_{0}$ be such that $t_{1}+\tau-\delta \geqslant t_{0}$ and

$$
\int_{t+\tau}^{\infty}|Q(s)| d s \leqslant \frac{p-1}{4}
$$

Consider the bounded, closed and convex subset of $X$;

$$
A=\left\{x \in X: 2(p-1) \leqslant x(t) \leqslant 4 p \text { for } t \geqslant t_{0}\right\}
$$

and define a mapping $T$ on $A$ as follows:

$$
(T x)(t)= \begin{cases}3 p+1-\frac{1}{p} x(t+\tau)+\frac{1}{p} \int_{t+\tau}^{\infty} Q(s) x(s-\delta) d s, & t \geqslant t_{1} \\ (T x)\left(t_{1}\right), & t_{0} \leqslant t \leqslant t_{1}\end{cases}
$$

By an argument similar to that in the previous four cases, we can easily show that all assumptions of the Banach contraction principle are satisfied. Therefore, $T$ has a fixed point $x \in A$. It is easy to see that this $x$ is a positive solution of Equation (1) on $\left[t_{1}+\tau, \infty\right)$, and the proof of Theorem 1 is complete.

## 3. On the Conjecture B

Consider the neutral delay differential equation

$$
\begin{equation*}
\frac{d}{d t}[x(t)+x(t-\tau)]+Q(t) x(t-\delta)=0 \tag{8}
\end{equation*}
$$

where

$$
\begin{equation*}
\tau>0, \delta \geqslant 0 \text { and } Q \in C\left(\left[t_{0}, \infty\right),(0, \infty)\right) \tag{9}
\end{equation*}
$$

First we establish the following result on the existence of a nonoscillatory solution of Equation (8).

Theorem 2. Assume that (9) holds and there exists a nonnegative continuous function $B(t)$ on $\left[t_{0}, \infty\right)$ such that

$$
\begin{equation*}
B(t)+B(t-\tau)=\text { Constant, } t \geqslant t_{0}+\tau . \tag{10}
\end{equation*}
$$

Also suppose that there exists a positive number $\lambda$ such that

$$
\begin{equation*}
\lambda\left(1+e^{\lambda \tau}\right) \geqslant Q(t)\left[B(t-\delta) e^{\lambda t}+e^{\lambda \delta}\right], t \geqslant t_{0}+\delta \tag{11}
\end{equation*}
$$

Then Equation (8) has a positive solution $x(t)$ satisfying $x(t) \geqslant B(t)$ for $t \geqslant t_{0}+\tau+\delta$ and $x(t)-B(t) \rightarrow 0$ as $t \rightarrow \infty$.

Proof: Set

$$
y(t)=e^{-\lambda t}
$$

Then by (11) we have

$$
[y(t)+y(t-\tau)]^{\prime}+Q(t)[B(t-\delta)+y(t-\delta)] \leqslant 0, t \geqslant t_{0}+\delta .
$$

Also let

$$
Q^{*}(t)=-[y(t)+y(t-\tau)]^{\prime} /[B(t-\delta)+y(t-\delta)] .
$$

Then $Q^{*}(t) \geqslant Q(t)$ and $y(t)$ satisfies

$$
[y(t)+y(t-\tau)]^{\prime}+Q^{*}(t)[B(t-\delta)+y(t-\delta)]=0, t \geqslant t_{0}+\delta
$$

From this we have

$$
y(t)+y(t-\tau)=\int_{t}^{\infty} Q^{*}(t)[B(s-\delta)+y(s-\delta)] d s, t \geqslant t_{0}+\delta
$$

which yields

$$
\begin{equation*}
y(t)=\sum_{i=1}^{\infty} \int_{t+(2 i-1) \tau}^{t+2 i \tau} Q^{*}(s)[B(s-\delta)+y(s-\delta)] d s, t \geqslant t_{0}+\delta-\tau \tag{12}
\end{equation*}
$$

By a slight modification of Lemma 10.5 .2 in [4] we can easily see that the corresponding integral equation

$$
z(t)=\sum_{i=1}^{\infty} \int_{t+(2 i-1) \tau}^{t+2 i \tau} Q(s)[B(s-\delta)+z(s-\delta)] d s
$$

has a positive solution $z:\left[t_{0}+\delta-\tau, \infty\right) \rightarrow(0, \infty)$ and $0<z(t) \leqslant y(t)$. From (13) we have

$$
z(t)+z(t-\tau)=\int_{t}^{\infty} Q(s)[B(s-\delta)+z(s-\delta)] d s, t \geqslant t_{0}+\delta .
$$

That is

$$
[z(t)+z(t-\tau)]^{\prime}+Q(t)[B(t-\delta)+z(t-\delta)]=0, t \geqslant t_{0}+\delta
$$

which implies that $x(t)=B(t)+z(t)$ is a positive solution of Equation (8) satisfying $x(t)>B(t)$ and $x(t)-B(t) \rightarrow 0$ as $t \rightarrow \infty$. The proof of Theorem 2 is complete.

Note that by using Theorem 2, we can easily construct many examples which show that the answer to Conjective $B$ is negative. In fact for any constant $c>0$, we define

$$
B(t)= \begin{cases}0, & t \in\left[2 i \tau,\left(2 i+\frac{1}{2}\right) \tau\right] \\ \frac{2 c}{\tau}\left[t-\left(2 i+\frac{1}{2}\right) \tau\right], & t \in\left[\left(2 i+\frac{1}{2}\right) \tau,(2 i+1) \tau\right] \\ c, & t \in\left[(2 i+1) \tau,\left(2 i+\frac{3}{2}\right) \tau\right] \\ \frac{2 c}{\tau}[-t+(2 i+1) \tau], & t \in\left[\left(2 i+\frac{3}{2}\right) \tau, 2(i+1) \tau\right]\end{cases}
$$

where $i=0,1,2,3, \ldots$ Clearly

$$
B(t)+B(t-\tau)=c \text { for } t \geqslant \tau
$$

and $B(t)$ is a nonnegative continuous function on $[0, \infty)$. Thus, if $Q(t)$ satisfies for some $\lambda>0$

$$
\frac{\lambda\left(1+e^{\lambda \tau}\right)}{2\left(e^{\lambda \delta}+B(t-\delta) e^{\lambda t}\right)} \leqslant Q(t) \leqslant \frac{\lambda\left(1+e^{\lambda \tau}\right)}{e^{\lambda \delta}+B(t-\delta) e^{\lambda t}}, \text { for } t \geqslant \delta,
$$

then (5) is satisfied and by Theorem 2 Equation (8) has a positive solution $x(t)$ satisfying $x(t)-B(t) \rightarrow 0$ as $t \rightarrow \infty$. But $x(t) \nrightarrow 0$ as $t \rightarrow \infty$, since $\limsup _{t \rightarrow \infty} B(t)=c$.

The above example indeed shows that Conjecture B is not true. But, on the other hand, the following theorem shows that, under appropriate additional hypothesis on $Q(t)$, Conjecture B is true.

Theorem 3. Assume that all the assumptions of Conjecture B hold. Further assume that there exists a positive constant $\beta$ such that $\beta \neq 1$, and

$$
\begin{equation*}
Q(t) \leqslant \beta Q(t-\tau), \text { for } t \geqslant t_{0}+\tau \tag{14}
\end{equation*}
$$

Then every nonoscillatory solution of Equation (6) goes to zero as $t \rightarrow \infty$.
Proof: Let $x(t)$ be a nonoscillatory solution of Equation (6). As $-x(t)$ is also a solution of Equation (6), we may assume that $x(t)$ is eventually positive. Thus there exists a $t_{1} \geqslant t_{0}+r$ such that $x(t-r)>0, x(t-\delta)>0$ for $t \geqslant t_{1}$. Set

$$
y(t)=x(t)+x(t-\tau)
$$

Then by (6) we have

$$
y^{\prime}(t) \leqslant 0, y(t)>0 \text { for } t \geqslant t_{1}
$$

and

$$
\begin{aligned}
y^{\prime}(t) & =-Q(t) x(t-\delta)=-Q(t) y(t-\delta)+Q(t) x(t-\tau-\delta) \\
& \leqslant-Q(t) y(t-\delta)+\beta Q(t-\tau) x(t-\tau-\delta) \\
& =-Q(t) y(t-\delta)-\beta y^{\prime}(t-\tau) . \\
& y^{\prime}(t)+\beta y^{\prime}(t-\tau)+Q(t) y(t-\delta) \leqslant 0 \text { for } t \geqslant t_{1} .
\end{aligned}
$$

That is
It follows by (5) that

$$
\begin{aligned}
& \lim _{t \rightarrow \infty} y(t)=0 . \\
& \lim _{t \rightarrow \infty} x(t)=0 .
\end{aligned}
$$

Consequently,

The proof of Theorem 3 is complete.

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