# Dihedral Groups of Order $2 p$ of Automorphisms of Compact Riemann Surfaces of Genus $p-1$ 

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Abstract. In this paper we prove that there is only one conjugacy class of dihedral group of order $2 p$ in the $2(p-1) \times 2(p-1)$ integral symplectic group that can be realized by an analytic automorphism group of compact connected Riemann surfaces of genus $p-1$. A pair of representative generators of the realizable class is also given.

## 1 Introduction

The problem we consider in this paper is the realizability of dihedral groups $D_{2 p}$ of order $2 p$, where $p$ is an odd prime, in $S P_{2(p-1)}(\mathbb{Z})$, the $2(p-1) \times 2(p-1)$ symplectic group over the ring of integers $\mathbb{Z}$, by analytic automorphisms of compact connected Riemann surfaces of genus $p-1$. This is a special case of a more general problem.

Let $S$ be a connected compact Riemann surface of genus $g(g \geq 2)$ without boundary and let $G$ be a subgroup of $\operatorname{Aut}(S)$, the group of analytic automorphisms of $S$. Then $G$ induces a faithful group action on $H_{1}(S)=H_{1}(S, \mathbb{Z})$, the first homology group of $S$,

$$
G_{*}: H_{1}(S) \longrightarrow H_{1}(S) .
$$

Let $a_{1}, a_{2}, \ldots, a_{g}, b_{1}, b_{2}, \ldots, b_{g}$ be a canonical basis of $H_{1}(S)$, that is, a basis for which the intersection matrix is

$$
J=\left(\begin{array}{cc}
0 & I_{g} \\
-I_{g} & 0
\end{array}\right)
$$

where $I_{g}$ is the identity matrix of degree $g$. For any element $\sigma_{*}$ in $G_{*}$, let $X$ be the matrix of $\sigma_{*}$ with respect to this basis. Since $\sigma_{*}$ preserves the intersection numbers, $X^{\prime} J X=J$, where $X^{\prime}$ is the transpose of $X$.

Definition 1.1 The set of $2 n \times 2 n$ unimodular matrices $X$ in $M_{2 n}(\mathbb{Z})$ such that

$$
X^{\prime} J X=J
$$

is called the symplectic group of genus $n$ over $\mathbb{Z}$ and is denoted by $S P_{2 n}(\mathbb{Z})$. Two symplectic matrices $X, Y$ of $S P_{2 n}(\mathbb{Z})$ are said to be conjugate or similar, denoted by $X \sim Y$, if there is a matrix $Q \in S P_{2 n}(\mathbb{Z})$ such that $Y=Q^{-1} X Q$. Two subgroups $G, H$ of

[^0]$S P_{2 n}(\mathbb{Z})$ are said to be conjugate or similar, denoted by $G \sim H$, if there is a matrix $Q \in S P_{2 n}(\mathbb{Z})$ such that $H=Q^{-1} G Q=\left\{Q^{-1} X Q \mid X \in G\right\}$.

If we fix a canonical basis of $H_{1}(S)$, there is a natural group monomorphism

$$
\Psi: \operatorname{Aut}(S) \rightarrow S P_{2 g}(\mathbb{Z}) ;
$$

see Farkas and Kra [3, p. 286]. Clearly, for any given subgroup $G$ of $\operatorname{Aut}(S)$, the groups $\Psi(G)$ with respect to different canonical basis are conjugate in $S P_{2 g}(\mathbb{Z})$.

Definition 1.2 A subgroup $H$ of $S P_{2 g}(\mathbb{Z})$ is said to be realizable if there is subgroup $G$ of Aut ( $S$ ) for some Riemann surface $S$ of genus $g$ such that $\Psi(G)=H$ with respect to some canonical basis of $H_{1}(S)$.

A question that naturally arises is "Which subgroups $H$ of $S P_{2 g}(\mathbb{Z})$ can be realized?"

Note that $\operatorname{Aut}(S)$ is finite, so we only need to consider finite subgroups of $S P_{2 g}(\mathbb{Z})$. The case of cyclic groups of order $p$ of $S P_{p-1}(\mathbb{Z})$, where $p \geq 5$ is an odd prime, was solved by Sjerve and Yang. They gave a complete list of realizable conjugacy classes of $p$-torsion in $S P_{p-1}(\mathbb{Z})$; see [11]. We have solved the problem for cyclic subgroups of $S P_{4}(\mathbb{Z})$, see [13]. In this paper we address the question of which classes of dihedral subgroups of order $2 p$ of $S P_{2(p-1)}(\mathbb{Z})$ can be realized by a dihedral group action on some Riemann surface of genus $p-1$.

Let $D_{2 p}$ be the dihedral group of $2 p$ elements and let $T, R \in D_{2 p}$ be two fixed generators of order $p$ and 2. Let

$$
C=\left(\begin{array}{ccccc}
0 & & & & -1 \\
1 & 0 & & & -1 \\
& 1 & \ddots & & \vdots \\
& & \ddots & 0 & -1 \\
& & & 1 & -1
\end{array}\right), \quad U=\left(\begin{array}{cccc} 
& & & 1 \\
& . & & \\
1 & & &
\end{array}\right)
$$

be two ( $p-1) \times(p-1)$ matrices, where $C$ is the companion matrix for $\Phi_{p}(x)$, the cyclotomic polynomial of $p$-th unit roots, and $U$ is an anti-diagonal matrix whose anti-diagonal entries are 1 . Then $C^{p}=U^{2}=(C U)^{2}=I$. Let $X$ and $Y$,

$$
X=\left(\begin{array}{cc}
C & \\
& C^{\prime-1}
\end{array}\right), \quad Y=\left(\begin{array}{cc}
U & \\
& U
\end{array}\right)
$$

be two $2(p-1) \times 2(p-1)$ matrices. It is easy to verify that $X$ and $Y$ are integral symplectic matrices and satisfy the relations $X^{p}=Y^{2}=(X Y)^{2}=I$. Therefore, the group $\langle X, Y\rangle$ generated by $X$ and $Y$ is a dihedral subgroup of order $2 p$ of $S P_{2(p-1)}(\mathbb{Z})$.

Main Theorem Let dihedral group $D_{2 p}$ act on a Riemann surface $S$ of genus $p-1$. There is a canonical basis $a_{1}, a_{2}, \ldots, a_{p-1}, b_{1}, b_{2}, \ldots, b_{p-1}$ of $H_{1}(S)$ such that $\Psi\left(D_{2 p}\right)=\langle X, Y\rangle$ with $\Psi(T)=X$ and $\Psi(R)=Y$.

Note that $p-1$ is the minimal genus larger than or equal to two for a Riemann surface that has $D_{2 p}$ as its group of automorphisms; see Breuer [1], Michael [5], or Yang [12].

## 2 Preliminaries

In this section we collect some preliminary material on Riemann surfaces. First we describe how all group actions on Riemann surfaces occur, and then we specialize to the case of the dihedral group of order $2 p$.

If $G$ is a finite group acting topologically on a surface $S$ by orientation preserving homeomorphisms, then the positive solution of the Nielsen Realization Problem guarantees that there exists a complex analytic structure on $S$ for which the action of $G$ is by analytic automorphisms (see $[2,4,8,10]$ ). Thus there is no loss of generality in assuming that the action of $G$ is complex analytic to begin with, and we will tacitly do so.

The orbit space $\bar{S}=S / G$ of the action of $G$ is also a Riemann surface, and the orbit map $p: S \rightarrow \bar{S}$ is a branched covering, with all ramifications occurring at fixed points of the action. If $x \in \bar{S}$ is a branch point, then each point in $p^{-1}(x)$ has a non-trivial stabilizer subgroup in $G$.

It is known that there is a one-to-one correspondence between analytic conjugacy classes of $D_{2 p}$ actions on compact connected Riemann surface $S$ of genus $p-1$ and short exact sequences

$$
1 \longrightarrow \Pi \longrightarrow \Gamma \stackrel{\theta}{\longrightarrow} D_{2 p} \longrightarrow 1
$$

where $\Gamma$ is a Fuchsian group of signature $(0 ; p, p, 2,2)$ and the kernel $\Pi$ is a torsion free subgroup of $\Gamma$. The short exact sequence corresponds to the induced action of $D_{2 p}$ on $S=\mathbb{H} / \Pi$, where $\mathbb{H}$ denotes the upper half plane.

As an abstract group $\Gamma$ has the presentation:

$$
\Gamma=\Gamma(0 ; p, p, 2,2)=\left\langle A_{1}, A_{2}, B_{1}, B_{2} \mid A_{1}^{p}=A_{2}^{p}=B_{1}^{2}=B_{2}^{2}=A_{1} A_{2} B_{1} B_{2}=1\right\rangle
$$

see Jones and Singerman[7, p. 262] or Harvey [6]. The epimorphism $\theta: \Gamma \rightarrow D_{2 p}$ is determined by the images of the generators. The relations in $\Gamma$ must be preserved and the kernel of $\theta$ must be torsion free. Let $T=\theta\left(A_{1}\right)$ and $R=\theta\left(B_{2}\right)$. Then

$$
\theta: A_{1} \mapsto T, \quad A_{2} \mapsto T^{p-u}, \quad B_{1} \mapsto T^{u-1} R, \quad B_{2} \mapsto R
$$

where $u=1,2, \ldots, p-1$, is a fixed integer determined by $\theta$.
The main tool we will use is the fundamental domain. We choose a particular embedding of $\Gamma$ in $\operatorname{Aut}(H H)$, namely, $\Gamma$ is the subgroup generated by $A_{1}, A_{2}, B_{1}, B_{2}$, where $A_{1}, A_{2}$ are rotations by $2 \pi / p$ and $B_{1}, B_{2}$ are rotations by $\pi$ about the vertices $v_{1}, v_{2}, v_{3}, v_{4}$ of a quadrilateral $P$ whose angles are $\pi / p, \pi / p, \pi / 2, \pi / 2$, respectively, ordered in the counterclockwise sense. A particular fundamental domain of $\Gamma$ is given by $P \cup R(P)$, where $R(P)$ is a reflection of $P$ in its side $v_{1} v_{4}$. Then fundamental domain of $\Pi$ consists of $2 p$ copies of the fundamental domain of $\Gamma$ that can be chosen as the union

$$
\bigcup_{i=0}^{p-1} A_{1}^{i}\left(P \cup R(P) \cup B_{2}(P \cup R(P))\right)
$$

which is a hyperbolic polygon with $4 p$ sides. Figure 1 illustrates a fundamental domain of $\Pi$ for a particular embedding when $p=5$. Label these sides $e_{1}, f_{1}, g_{1}$, $h_{1}, \ldots, e_{p}, f_{p}, g_{p}, h_{p}$, and orient them as indicated in Figure 1. In the following, the subscripts will be in the set $\mathbb{Z}_{p}=\{1,2, \ldots, p\}$. For example, we write $e_{j}=e_{i}$ if $j-i=k p$ for some integer $k$.


Figure 1: Fundamental Domain of $\Pi$.

The sides $e_{j}$ and $h_{j}, j=1, \ldots, p$, are identified in the Riemann surface $S=\mathbb{H} / \Pi$. This can be seen from the fact that $A_{1}^{j} B_{2} A_{1} B_{2} A_{1}^{1-j} \in \operatorname{Ker} \theta=\Pi$ and

$$
e_{j} \xrightarrow{A_{1}^{1-j}} e_{1} \xrightarrow{B_{2}} e_{p}^{\prime} \xrightarrow{A_{1}} e_{1}^{\prime} \xrightarrow{B_{2}} h_{p} \xrightarrow{A_{1}^{j}} h_{j} .
$$

Similarly, $A_{1}^{j-1} B_{2} B_{1} A_{1}^{u-j} \in \Pi$ and

$$
g_{j-u} \xrightarrow{A_{1}^{u-j}} g_{p} \xrightarrow{B_{1}}-g_{p} \xrightarrow{B_{2}} f_{1} \xrightarrow{A_{1}^{j-1}} f_{j} .
$$

Therefore, the sides $f_{j}$ and $g_{j-u}$ are identified in $S$, for $j=1, \ldots, p$.

Let $\alpha_{j}=f_{j}-g_{j}, \beta_{j}=e_{j}^{\prime}-e_{j-u}^{\prime}, \gamma_{j}=e_{j}-e_{j+u}, j=1, \ldots, p$. Then $\alpha_{1}, \ldots, \alpha_{p}$, $\beta_{1}, \ldots, \beta_{p}, \gamma_{i}, \ldots, \gamma_{p}$ are closed paths on $S$. It is clear that

$$
\sum_{i=1}^{p}\left[\alpha_{i}\right]=0, \quad \sum_{i=1}^{p}\left[\beta_{i}\right]=0, \quad \sum_{i=1}^{p}\left[\gamma_{i}\right] .=0
$$

Here we use the notation [ ] to denote homology classes in $H_{1}(S)$. We see that $\left[\beta_{1}\right], \ldots,\left[\beta_{p-1}\right],\left[\gamma_{1}\right], \ldots,\left[\gamma_{p-1}\right]$ forms a basis of $H_{1}(S)$; see Massey [9]. According to the Figure 1 , and $\left[f_{j+u}-g_{j}\right]=0$, we see that, for $j=1, \ldots, p$,

$$
\begin{aligned}
{\left[e_{j}-\right.} & \left.e_{j+u}\right]+\left[f_{j+1}-g_{j+1}\right]+\left[f_{j+2}-g_{j+2}\right]+\cdots+\left[f_{j+u-1}-g_{j+u-1}\right] \\
= & {\left[e_{j}-e_{j+1}\right]+\left[f_{j+1}-g_{j+1}\right]+\left[e_{j+1}-e_{j+2}\right]+\cdots } \\
& +\left[e_{j+u-2}-e_{j+u-1}\right]+\left[f_{j+u-1}-g_{j+u-1}\right]+\left[e_{j+u-1}-e_{j+u}\right] \\
= & -\left[f_{j+u}-g_{j}\right]+\left[e_{j}^{\prime}-e_{j+u}^{\prime}\right]=\left[e_{j}^{\prime}-e_{j+u}^{\prime}\right]
\end{aligned}
$$

Thus we have
or

$$
\begin{equation*}
\left[\beta_{j+u}\right]+\sum_{i=1}^{u-1}\left[\alpha_{j+i}\right]=\left[\alpha_{j+1}\right]+\cdots+\left[\alpha_{j+u-1}\right]+\left[\beta_{j+u}\right]=-\left[\gamma_{j}\right] \tag{2.1}
\end{equation*}
$$

or
where the sum $\sum_{i=1}^{u-1}$ is zero if $u=1$. Hence $\left[\alpha_{1}\right], \ldots,\left[\alpha_{p-1}\right],\left[\beta_{1}\right], \ldots,\left[\beta_{p-1}\right]$ forms a basis of $H_{1}(S)$.

## 3 Matrices of $T_{*}$ and $R_{*}$

Since

$$
A_{1}: e_{j} \mapsto e_{j+1}, \quad e_{j}^{\prime} \mapsto e_{j+1}^{\prime}, \quad f_{j} \mapsto f_{j+1}, \quad g_{j} \mapsto g_{j+1}
$$

and $\theta\left(A_{1}\right)=T$, we get that $T_{*}$ on $H_{1}(S)$ has the form

$$
T_{*}\left[\alpha_{j}\right]=\left[\alpha_{j+1}\right], \quad T_{*}\left[\beta_{j}\right]=\left[\beta_{j+1}\right], \quad T_{*}\left[\gamma_{j}\right]=\left[\gamma_{j+1}\right]
$$

Also, $\theta\left(A_{1}^{k} B_{2} A_{1}^{k}\right)=R$. We see that the induced action $R$ on $S$ has the form

$$
R: e_{j} \mapsto e_{p+1-j}^{\prime}, \quad e_{j}^{\prime} \mapsto e_{p+1-j}, \quad f_{j} \mapsto-g_{p+1-j}, \quad g_{i} \mapsto-f_{p+1-j}
$$

and then induced action $R_{*}$ on $H_{1}(S)$ is given by

$$
R_{*}\left[\alpha_{j}\right]=\left[\alpha_{p+1-j}\right], \quad R_{*}\left[\beta_{j}\right]=\left[\gamma_{p+1-j}\right], \quad R_{*}\left[\gamma_{j}\right]=\left[\beta_{p+1-j}\right]
$$

Let $B_{k}$ denote the $(p-1) \times(p-1)$ matrix $C^{k} U$, where $k$ is an integer. It is clear that $B_{0}=U, B_{k}^{2}=I$, and $B_{k}=B_{p+k}$.

Lemma 3.1 Let $T_{u}$ and $R_{u}$ denote the matrices of $T_{*}$ and $R_{*}$ with respect to the basis

$$
\alpha_{1}, \alpha_{2}, \ldots, \alpha_{p-1}, \beta_{1}, \beta_{2}, \ldots, \beta_{p-1}
$$

respectively. Then

$$
T_{u}=\left(\begin{array}{cc}
C & 0 \\
0 & C
\end{array}\right), \quad R_{u}=\left(\begin{array}{cc}
B_{1} & -\sum_{i=1}^{u-1} B_{i+1} \\
0 & -B_{u+1}
\end{array}\right)
$$

Proof Since $T_{*}\left[\alpha_{i}\right]=\left[\alpha_{i+1}\right]$ and $\left[\alpha_{p}\right]=-\left[\alpha_{1}\right]-\cdots-\left[\alpha_{p-1}\right]$, we have

$$
\begin{aligned}
T_{*}\left(\left[\alpha_{1}\right], \ldots,\left[\alpha_{p-2}\right],\left[\alpha_{p-1}\right]\right) & =\left(\left[\alpha_{2}\right], \ldots,\left[\alpha_{p-1}\right],\left[\alpha_{p}\right]\right) \\
& =\left(\left[\alpha_{2}\right], \ldots,\left[\alpha_{p-1}\right],-\left[\alpha_{1}\right]-\cdots-\left[\alpha_{p-1}\right]\right) \\
& =\left(\left[\alpha_{1}\right], \ldots,\left[\alpha_{p-2}\right],\left[\alpha_{p-1}\right]\right) C .
\end{aligned}
$$

Similarly, $T_{*}\left(\left[\beta_{1}\right], \ldots,\left[\beta_{p-2}\right],\left[\beta_{p-1}\right]\right)=\left(\left[\beta_{1}\right], \ldots,\left[\beta_{p-2}\right],\left[\beta_{p-1}\right]\right) C$. Therefore,

$$
T_{u}=\left(\begin{array}{cc}
C & 0 \\
0 & C
\end{array}\right)
$$

Note that $R_{*}\left[\alpha_{i}\right]=\left[\alpha_{p+1-i}\right]$, and

$$
\begin{aligned}
R_{*}\left(\left[\alpha_{1}\right], \ldots,\left[\alpha_{p-2}\right],\left[\alpha_{p-1}\right]\right) & =\left(\left[\alpha_{p}\right],\left[\alpha_{p-1}\right], \ldots,\left[\alpha_{3}\right],\left[\alpha_{2}\right]\right) \\
& =\left(\left[\alpha_{2}\right],\left[\alpha_{3}\right], \ldots,\left[\alpha_{p-1}\right],\left[\alpha_{p}\right]\right) U \\
& =\left(\left[\alpha_{1}\right], \ldots,\left[\alpha_{p-2}\right],\left[\alpha_{p-1}\right]\right) C U \\
& =\left(\left[\alpha_{1}\right], \ldots,\left[\alpha_{p-2}\right],\left[\alpha_{p-1}\right]\right) B_{1} .
\end{aligned}
$$

Also note that $R_{*}\left[\beta_{j}\right]=\left[\gamma_{p+1-j}\right]$. From (2.1), we have

$$
R_{*}\left[\beta_{j}\right]=-\sum_{i=1}^{u-1}\left[\alpha_{i+1-j}\right]-\left[\beta_{u+1-j}\right], \quad j=1,2, \ldots, p-1
$$

Then

$$
\begin{aligned}
R_{*} & \left(\left[\beta_{1}\right], \ldots,\left[\beta_{p-2}\right],\left[\beta_{p-1}\right]\right) \\
& =-\sum_{i=1}^{u-1}\left(\left[\alpha_{i}\right],\left[\alpha_{i-1}\right], \ldots,\left[\alpha_{i-p+2}\right]\right)-\left(\left[\beta_{u}\right],\left[\beta_{u-1}\right], \ldots,\left[\beta_{u-p+2}\right]\right) \\
& =-\sum_{i=1}^{u-1}\left(\left[\alpha_{i-p+2}\right], \ldots,\left[\alpha_{i}\right]\right) U-\left(\left[\beta_{u-p+2}\right], \ldots,\left[\beta_{u}\right]\right) U \\
& =-\sum_{i=1}^{u-1}\left(\left[\alpha_{1}\right], \ldots,\left[\alpha_{p-1}\right]\right) C^{i+1} U-\left(\left[\beta_{1}\right], \ldots,\left[\beta_{p-1}\right]\right) C^{u+1} U \\
& =-\left(\left[\alpha_{1}\right], \ldots,\left[\alpha_{p-1}\right]\right) \sum_{i=1}^{u-1} C^{i+1} U-\left(\left[\beta_{1}\right], \ldots,\left[\beta_{p-1}\right]\right) C^{u+1} U \\
& =-\left(\left[\alpha_{1}\right], \ldots,\left[\alpha_{p-1}\right]\right) \sum_{i=1}^{u-1} B_{i+1}-\left(\left[\beta_{1}\right], \ldots,\left[\beta_{p-1}\right]\right) B_{u+1} .
\end{aligned}
$$

Hence,

$$
R_{u}=\left(\begin{array}{cc}
B_{1} & -\sum_{i=1}^{u-1} B_{i+1} \\
0 & -B_{u+1}
\end{array}\right)
$$

## 4 Intersection Matrix

It is easy to see that the intersection numbers of $\left[\alpha_{i}\right]$ and $\left[\alpha_{j}\right]$ are zero. But the other intersection numbers of $\left[\alpha_{1}\right], \ldots,\left[\alpha_{p}\right],\left[\beta_{1}\right], \ldots,\left[\beta_{p}\right]$ are somewhat complex.

Let $l_{i j}$ be the intersection number $\left[\alpha_{i}\right] \cdot\left[\beta_{j}\right]$ of $\left[\alpha_{i}\right]$ and $\left[\beta_{j}\right]$. We have the following lemma.

Lemma 4.1 We have that $l_{i j}=l_{i+1 j+1}, l_{1 j}=l_{p-j+2,1}=l_{p-1, j-2}$, and

$$
l_{1 j}= \begin{cases}1, & j=1  \tag{4.1}\\ -1, & j=u+1 \\ 0, & \text { otherwise }\end{cases}
$$

Proof $T_{*}$ preserves the intersection number of closed chains. By Lemma 3.1,

$$
l_{i j}=\left[\alpha_{i}\right] \cdot\left[\beta_{j}\right]=T_{*}\left(\left[\alpha_{i}\right]\right) \cdot T_{*}\left(\left[\beta_{j}\right]\right)=\left[\alpha_{i+1}\right] \cdot\left[\beta_{j+1}\right]=l_{i+1 j+1}
$$

Iterating this formula, we see that $l_{1 j}=l_{p-j+2,1}=l_{p-1, j-2}$.
If $j \neq 1$ and $j \neq u+1$, it is clear that $\alpha_{1}$ and $\beta_{j}$ do not intersect, so $l_{1 j}=0$. If $j=1$ or $j=u+1$, the intersection of $\alpha_{1}$ and $\beta_{j}$ is one point. The verification of (4.1) is easy.

Let $L_{k}, k=1, \ldots, p-1$, denote the $(p-1) \times(p-1)$ matrix

$$
L_{k}=\left(\begin{array}{cccccccc}
1 & \cdots & \cdots & 0 & -1 & 0 & \cdots & 0 \\
\vdots & \ddots & & & & \ddots & & \vdots \\
\vdots & & \ddots & & & & \ddots & 0 \\
\vdots & & & \ddots & & & & -1 \\
0 & & & & \ddots & & & 0 \\
-1 & & & & & \ddots & & \vdots \\
\vdots & \ddots & & & & & \ddots & \vdots \\
0 & \cdots & -1 & 0 & \cdots & \cdots & \cdots & 1
\end{array}\right)
$$

whose entries $x_{i j}^{(k)}$ are given by

$$
x_{i j}^{(k)}=\left\{\begin{array}{ll}
1, & i=j \\
-1, & j-i=k \\
0, & \text { otherwise }
\end{array} \quad \text { or } \quad i-j=p-k\right.
$$

According to Lemma 4.1, we have proved that the intersection matrix of

$$
\left[\alpha_{1}\right], \ldots,\left[\alpha_{p-1}\right] \text { and }\left[\beta_{1}\right], \ldots,\left[\beta_{p-1}\right]
$$

is $L_{u}$. That is

$$
\left(\left[\alpha_{1}\right], \ldots,\left[\alpha_{p-1}\right]\right)^{\prime} \cdot\left(\left[\beta_{1}\right], \ldots,\left[\beta_{p-1}\right]\right)=L_{u}
$$

Then

$$
\left(\left[\beta_{1}\right], \ldots,\left[\beta_{p-1}\right]\right)^{\prime} \cdot\left(\left[\alpha_{1}\right], \ldots,\left[\alpha_{p-1}\right]\right)=-L_{u}^{\prime} .
$$

It is clear that $L_{k}$ is a persymmetric matrix, and $L_{k} U=U L_{k}^{\prime}=U L_{p-k}$. Also, we have

Lemma 4.2 For $1 \leq i, k \leq p-1$,

$$
\left(C^{\prime}\right)^{-i} L_{k}=L_{k} C^{i}= \begin{cases}L_{k-i}-L_{p-i}, & i<k \\ -L_{p-k}, & i=k \\ L_{p+k-i}-L_{p-i}, & i>k\end{cases}
$$

Proof We only prove the case that $L_{k} C^{i}=L_{k-i}-L_{p-i}, 1 \leq i<k \leq p-1$. From the definition of $L_{k}$, we have

$$
L_{k} \varepsilon_{j}= \begin{cases}\varepsilon_{j}-\varepsilon_{p+j-k}, & 1 \leq j<k \\ \varepsilon_{k}, & j=k \\ \varepsilon_{j}-\varepsilon_{j-k}, & k<j \leq p-1\end{cases}
$$

where $\varepsilon_{j}, j=1, \ldots, p-1$, is the $j$-th basic unit vector whose $j$-th component is 1 and all other components are 0 . Therefore, $L_{k}\left(\varepsilon_{1}+\varepsilon_{2}+\cdots+\varepsilon_{p-1}\right)=\varepsilon_{p-k}$. Note that

$$
C \varepsilon_{j}= \begin{cases}\varepsilon_{j+1}, & 1 \leq j<p-1 \\ -\left(\varepsilon_{1}+\varepsilon_{2}+\cdots+\varepsilon_{p-1}\right), & j=p-1\end{cases}
$$

By mathematical induction, we have

$$
C^{i} \varepsilon_{j}= \begin{cases}\varepsilon_{i+j}, & 1 \leq j<p-i \\ -\left(\varepsilon_{1}+\varepsilon_{2}+\cdots+\varepsilon_{p-1}\right), & j=p-i \\ \varepsilon_{i+j-p}, & p-i<j \leq p-1\end{cases}
$$

Hence

$$
L_{k} C^{i} \varepsilon_{j}= \begin{cases}\varepsilon_{i+j}-\varepsilon_{p+i+j-k}, & 1 \leq j<k-i \\ \varepsilon_{k}, & j=k-i \\ \varepsilon_{i+j}-\varepsilon_{i+j-k}, & k-i<j<p-i \\ -\varepsilon_{p-k}, & j=p-i \\ \varepsilon_{i+j-p}-\varepsilon_{i+j-k}, & p-i<j \leq p-1\end{cases}
$$

When $1 \leq j \leq k-i-1$,

$$
\left(L_{k} C^{i}+L_{p-i}-L_{k-i}\right) \varepsilon_{j}=\left(\varepsilon_{i+j}-\varepsilon_{p+i+j-k}\right)+\left(\varepsilon_{j}-\varepsilon_{i+j}\right)-\left(\varepsilon_{j}-\varepsilon_{p+i+j-k}\right)=0
$$

When $j=k-i$,

$$
\left(L_{k} C^{i}+L_{p-i}-L_{k-i}\right) \varepsilon_{k-i}=\varepsilon_{k}+\left(\varepsilon_{k-i}-\varepsilon_{k}\right)-\varepsilon_{k-i}=0 .
$$

When $k-i+1 \leq j \leq p-i-1$,

$$
\left(L_{k} C^{i}+L_{p-i}-L_{k-i}\right) \varepsilon_{j}=\left(\varepsilon_{i+j}-\varepsilon_{i+j-k}\right)+\left(\varepsilon_{j}-\varepsilon_{i+j}\right)-\left(\varepsilon_{j}-\varepsilon_{i+j-k}\right)=0
$$

When $j=p-i$,

$$
\left(L_{k} C^{i}+L_{p-i}-L_{k-i}\right) \varepsilon_{p-i}=\varepsilon_{p-k}+\varepsilon_{p-i}-\left(\varepsilon_{p-i}-\varepsilon_{p-k}\right)=0 .
$$

When $p-i+1 \leq j \leq p-1$,

$$
\left(L_{k} C^{i}+L_{p-i}-L_{k-i}\right) \varepsilon_{j}=\left(\varepsilon_{i+j-p}-\varepsilon_{i+j-k}\right)+\left(\varepsilon_{j}-\varepsilon_{i+j-p}\right)-\left(\varepsilon_{j}-\varepsilon_{i+j-k}\right)=0
$$

Thus $L_{k} C^{i}+L_{p-i}-L_{k-i}=0$.
For other cases, the method is similar.

Now we compute the intersection matrix of $\left[\beta_{1}\right], \ldots,\left[\beta_{p-1}\right]$. From (2.2), we have

$$
\begin{aligned}
\left(\left[\beta_{1}\right], \ldots,\left[\beta_{p-1}\right]\right) & =-\sum_{i=1}^{u-1}\left(\left[\alpha_{1-u+i}\right], \ldots,\left[\alpha_{p-1-u+i}\right]\right)-\left(\left[\gamma_{1-u}\right], \ldots,\left[\gamma_{p-1-u}\right]\right) \\
& =-\sum_{i=1}^{u-1}\left(\left[\alpha_{1}\right], \ldots,\left[\alpha_{p-1}\right]\right) C^{i-u}-\left(\left[\gamma_{1-u}\right], \ldots,\left[\gamma_{p-1-u}\right]\right)
\end{aligned}
$$

Since the paths $\beta_{j}$ and $\gamma_{k-u}$ have no intersection for any $j$ and $k$, the intersection matrix of $\left[\beta_{1}\right], \ldots,\left[\beta_{p-1}\right]$ is

$$
\begin{aligned}
& \left(\left[\beta_{1}\right], \ldots,\left[\beta_{p-1}\right]\right)^{\prime} \cdot\left(\left[\beta_{1}\right], \ldots,\left[\beta_{p-1}\right]\right) \\
& \quad=-\sum_{i=1}^{u-1}\left(C^{\prime}\right)^{i-u}\left(\left[\alpha_{1}\right], \ldots,\left[\alpha_{p-1}\right]\right)^{\prime} \cdot\left(\left[\beta_{1}\right], \ldots,\left[\beta_{p-1}\right]\right) \\
& \quad=-\sum_{i=1}^{u-1}\left(C^{\prime}\right)^{i-u} L_{u}=-\sum_{i=1}^{u-1}\left(L_{i}-L_{p+i-u}\right) \\
& \quad=-\sum_{i=1}^{u-1} L_{i}+\sum_{i=1}^{u-1} L_{u-i}^{\prime}=-\sum_{i=1}^{u-1} L_{i}+\sum_{i=1}^{u-1} L_{i}^{\prime} \\
& \quad=\sum_{i=1}^{u-1}\left(L_{i}^{\prime}-L_{i}\right) .
\end{aligned}
$$

Hence the intersection matrix of the basis $\left[\alpha_{1}\right], \ldots,\left[\alpha_{p-1}\right],\left[\beta_{1}\right], \ldots,\left[\beta_{p-1}\right]$ is

$$
M_{u}=\left(\begin{array}{cc}
0 & L_{u} \\
-L_{u}^{\prime} & \sum_{i=1}^{u-1}\left(L_{i}^{\prime}-L_{i}\right)
\end{array}\right) .
$$

We see that $\left[\alpha_{1}\right], \ldots,\left[\alpha_{p-1}\right],\left[\beta_{1}\right], \ldots,\left[\beta_{p-1}\right]$ is not a canonical basis.

## 5 Proof of Main Theorem

We need some more properties of $L_{k}$ and $B_{k}$ to prove the Main Theorem.
Lemma 5.1 For any $1 \leq k \leq p-1$,
(i) $C^{-i} B_{k} C^{i}=B_{k-2 i}$,
(ii) $L_{k} B_{k} L_{k}^{-1}=-U$,
(iii) $\left(C^{\prime}\right)^{i} L_{k} C^{i}=L_{k}$,
(iv) $B_{i}^{\prime} L_{k} B_{i}=L_{p-i}$.

Proof (i) By definition,

$$
C^{-i} B_{k} C^{i}=C^{-i} C^{k} U C^{i}=C^{-i} C^{k} C^{-i} U=C^{k-2 i} U=B_{k-2 i} .
$$

(ii) From Lemma 4.2, $L_{k} B_{k} L_{k}^{-1}=\left(L_{k} C^{k}\right)\left(U L_{k}^{-1}\right)=-L_{p-k}\left(L_{k}^{\prime}\right)^{-1} U=-U$.
(iii) This is the special case of Lemma 4.2.
(iv) $B_{i}^{\prime} L_{k} B_{i}=\left(C^{i} U\right)^{\prime} L_{k}^{\prime}\left(C^{i} U\right)=U C^{\prime i} L_{k} C^{i} U=U L_{k} U=L_{p-k}$.

Now we can prove the Main Theorem by showing that there is an invertible integral matrix $Q$ such that $Q^{-1} T_{u} Q=X, Q^{-1} R_{u} Q=Y$, and $Q^{\prime} M_{u} Q=J$.

Proof of Main Theorem By Lemma 5.1, we see that $C^{-(p+1) / 2} B_{k} C^{(p+1) / 2}=B_{k-1}$. Let

$$
Q_{1}=\left(\begin{array}{cc}
C^{(p+1) / 2} & \\
& C^{(p+1) / 2}
\end{array}\right)
$$

Then by Lemma 5.1, we have

$$
Q_{1}^{-1} T_{u} Q_{1}=T_{u}, \quad Q_{1}^{-1} R_{u} Q_{1}=\left(\begin{array}{cc}
U & -\sum_{i=1}^{u-1} B_{i} \\
0 & -B_{u}
\end{array}\right), \quad Q_{1}^{\prime} M_{u} Q_{1}=M_{u}
$$

Note that $L_{k} B_{k} L_{k}^{-1}=-U$. Let $Q_{2}=\left(\begin{array}{c} \\ L_{u}^{-1}\end{array}\right)$. Then

$$
Q_{2}^{-1} T_{u} Q_{2}=X, \quad Q_{2}^{-1}\left(\begin{array}{cc}
U & -\sum_{i=1}^{u-1} B_{i} \\
0 & -B_{u}
\end{array}\right) Q_{2}=\left(\begin{array}{cc}
U & -\left(\sum_{i=1}^{u-1} B_{i}\right) L_{u}^{-1} \\
0 & U
\end{array}\right)
$$

and

$$
Q_{2}^{\prime} M_{u} Q_{2}=Q_{2}^{\prime}\left(\begin{array}{cc}
0 & L_{u} \\
-L_{u}^{\prime} & \sum_{i=1}^{u-1}\left(L_{i}^{\prime}-L_{i}\right)
\end{array}\right) Q_{2}=\left(\begin{array}{cc}
0 & I \\
-I & A^{\prime}-A
\end{array}\right)
$$

where $A=L_{u}^{\prime-1}\left(\sum_{i=1}^{u-1} L_{i}\right) L_{u}^{-1}$. Let $Q_{3}=\left(\begin{array}{cc}I & -A \\ 0 & I\end{array}\right)$. Then $Q_{3}^{-1}=\left(\begin{array}{cc}I & A \\ 0 & I\end{array}\right)$ and

$$
\begin{aligned}
Q_{3}^{-1}\left(\begin{array}{ll}
C & \\
& C^{\prime-1}
\end{array}\right) Q_{3} & =\left(\begin{array}{cc}
C & A C^{\prime-1}-C A \\
0 & C^{\prime-1}
\end{array}\right), \\
Q_{3}^{-1}\left(\begin{array}{cc}
U & -\left(\sum_{i=1}^{u-1} B_{i}\right) L_{u}^{-1} \\
0 & U^{2}
\end{array}\right) Q_{3} & =\left(\begin{array}{cc}
U & A U-U A-\left(\sum_{i=1}^{u-1} B_{i}\right) L_{u}^{-1} \\
0 & U
\end{array}\right), \\
Q_{3}^{\prime}\left(\begin{array}{cc}
0 & I \\
-I & A^{\prime}-A
\end{array}\right) Q_{3} & =J .
\end{aligned}
$$

Using Lemma 5.1 again, we have

$$
\begin{aligned}
A C^{\prime-1}-C A & =L_{u}^{\prime-1}\left(\sum_{i=1}^{u-1} L_{i}\right) L_{u}^{-1} C^{\prime-1}-C L_{u}^{\prime-1}\left(\sum_{i=1}^{u-1} L_{i}\right) L_{u}^{-1} \\
& =L_{u}^{\prime-1}\left(\sum_{i=1}^{u-1} L_{i}\right) C L_{u}^{-1}-L_{u}^{\prime-1} C^{\prime-1}\left(\sum_{i=1}^{u-1} L_{i}\right) L_{u}^{-1} \\
& =L_{u}^{\prime-1}\left(\sum_{i=1}^{u-1}\left(L_{i} C-C^{\prime-1} L_{i}\right)\right) L_{u}^{-1}=0
\end{aligned}
$$

and

$$
\begin{aligned}
A U & -U A-\left(\sum_{i=1}^{u-1} B_{i}\right) L_{u}^{-1} \\
& =L_{u}^{\prime-1}\left(\sum_{i=1}^{u-1} L_{i}\right) L_{u}^{-1} U-U L_{u}^{\prime-1}\left(\sum_{i=1}^{u-1} L_{i}\right) L_{u}^{-1}-\left(\sum_{i=1}^{u-1} B_{i}\right) L_{u}^{-1} \\
& =L_{u}^{\prime-1}\left[\left(\sum_{i=1}^{u-1} L_{i}\right) L_{u}^{-1} U L_{u}-L_{u}^{\prime} U L_{u}^{\prime-1}\left(\sum_{i=1}^{u-1} L_{i}\right)-L_{u}^{\prime}\left(\sum_{i=1}^{u-1} B_{i}\right)\right] L_{u}^{-1} \\
& =L_{u}^{\prime-1}\left[-\left(\sum_{i=1}^{u-1} L_{i}\right) B_{u}+B_{u}^{\prime}\left(\sum_{i=1}^{u-1} L_{i}\right)-L_{p-u}\left(\sum_{i=1}^{u-1} B_{i}\right)\right] L_{u}^{-1}
\end{aligned}
$$

$$
\begin{aligned}
& =L_{u}^{\prime-1}\left[-\left(\sum_{i=1}^{u-1} L_{i}\right)+B_{u}^{\prime}\left(\sum_{i=1}^{u-1} L_{i}\right) B_{u}-\left(\sum_{i=1}^{u-1} L_{p-u} B_{i}\right) B_{u}\right] B_{u} L_{u}^{-1} \\
& =L_{u}^{\prime-1}\left[-\sum_{i=1}^{u-1} L_{i}+\sum_{i=1}^{u-1} L_{p-i}-\sum_{i=1}^{u-1} L_{p-u} C^{p+i-u}\right] B_{u} L_{u}^{-1} \\
& =L_{u}^{\prime-1}\left[-\sum_{i=1}^{u-1} L_{i}+\sum_{i=1}^{u-1} L_{p-i}-\sum_{i=1}^{u-1}\left(L_{p-i}-L_{u-i}\right)\right] B_{u} L_{u}^{-1}=0 .
\end{aligned}
$$

Here we also use Lemma 4.2 for $L_{p-u} C^{p+i-u}$. If we let $Q=Q_{1} Q_{2} Q_{3}$, then

$$
Q^{-1} T_{u} Q=X, \quad Q^{-1} R_{u} Q=Y, \quad Q^{\prime} M_{u} Q=J
$$

This concludes the proof.
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