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CORRIGENDUM

# Reinforcement learning-adaptive fault-tolerant IGC method for a class of aircraft with non-affine characteristics and multiple uncertainties – CORRIGENDUM

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The authors apologise that an authorial affiliation was not given correctly in the originally published piece:

"[4]Research Center for Unmanned System Strategy Development, Northwestern Polytechnical University, Xi'an, Shaanxi, China" should be "[4]Unmanned System Research Institute, Northwestern Polytechnical University, Xi'an, Shaanxi, China." This affiliation has now been corrected in the original article.

## Reference

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