## THE GEOMETRY OF FINITE MARKOV CHAINS

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The purpose of this paper is to present a geometric theorem which provides a proof of a fundamental theorem of finite Markov chains.

The theorem, stated in matrix theoretic terms, concerns the asymptotic behaviour of the powers of an n by n stochastic matrix, that is, a matrix of non-negative entries each of whose row sums is 1. The matrix might arise from a repeated physical process which goes from one of n possible states to another at each iteration and whose probability of going to a state depends only on the state it is in at present and not on its more distant history. The entry  $a_{ij}$  of the matrix A (called the one step transition matrix) is the probability that the process goes from state i to state j in one step. The ij-th entry in  $A^{m}$ , which is denoted by  $a_{ij}^{(m)}$ , is the probability of going from i to j in m steps. For example the process might consist of shuffling a deck of n cards by means of a machine which puts the i-th card from the top into the j-th from the top with probability  $a_{ij}$ . Then  $a_{ij}^{(m)}$  is the probability of finding the i-th card in the j-th position at the m-th shuffle.

For each m > 0, we say that <u>i leads to j in m steps</u> iff  $a_{ij}^{(m)} > 0$ . We write i  $\sim j$  iff i leads to j in m steps for some m.

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It is easy to see that  $\sim$  is an equivalence relation on the set of those states on which  $\sim$  is symmetric, i.e. on  $E = \bigcap_{j=1}^{n} \{i : i \sim j \text{ implies } j \sim i\}$ . E is called the set of ergodic states. E is partitioned by  $\sim$  into  $\nu$  equivalence classes  $E_1, E_2, \dots, E_{\nu}$  called <u>ergodic</u> classes. The states not in E are called transient.

Theorems I and II below are respectively probabilistic and matrix theoretic statements of the fundamental theorem of finite Markov chains. We shall provide a geometric proof at the conclusion of the paper. For probabilistic proofs we refer the reader to [1], [2], [3], and [4]. An algebraic proof can be found in [5].

THEOREM I. If  $A = (a_{ij})$  is the one step transition matrix of a Markov chain with n states then:

(Ia)  $\lim_{m\to\infty} a_{ij}^{(m)} = 0$  whenever j is transient.

There is a partition of each  $\sim$  equivalence class  $E_r$  into  $c_r$ non-empty subsets (called cyclically moving classes)  $E_{r0}$ ,  $E_{r1}$ , ...,  $E_{rc_r-1}$  with the following properties:

(Ib) If  $i \in E_{rs}$  and i leads to j in one step then  $j \in E_{r, s+1}$  (the second subscript is read modulo  $c_{r}$ ).

(Ic) To each  $E_{rs}$  corresponds an n-tuple  $k_{rs}$  of nonnegative numbers whose sum is 1 for which the j-th component,  $k_{j}^{(r,s)}$ , is zero iff  $j \notin E_{rs}$  and such that:

 $\lim_{\substack{r \to \infty}} a_{ij} = k_{j}^{(r,s')} \quad \text{for all } j$ 

and all  $t = 0, 1, \ldots, c_r - 1$  whenever  $i \in E_{rs}$  and s'  $\equiv s + t \pmod{c_r}$ .

THEOREM II. If  $A = (a_{ij})$  is an n by n stochastic matrix then there is a permutation matrix P (i.e. a matrix of zeroes and ones which has only one non-zero entry in each row and each column) such that:

$$PAP^{-1} = \begin{vmatrix} A_{1} & 0 & A_{2} & A_{0} & A_{0} & A_{0,\nu-1} & A_{0} \\ 0 & A_{1} & 0 & A_{0} & A_{0,\nu-1} & A_{0} \\ 0 & A_{1} & 0 & A_{1} & 0 & A_{1} & A_{1} & A_{1} \\ 0 & 0 & 0 & A_{1} & A_{1} & A_{2} & A_{1} & A_{1} & A_{1} \\ 0 & 0 & 0 & A_{1} & A_{1} & A_{2} & A_{2} & A_{2} & A_{2} \\ 0 & A_{2} & A_{1} & A_{2} & A_{2} & A_{2} & A_{2} & A_{2} \\ 0 & A_{2} \\ 0 & A_{2} \\ 0 & A_{2} &$$

$$A_{r} = \begin{vmatrix} 0 & A_{r1} & 0 & 0 & \dots & 0 & 0 \\ 0 & 0 & A_{r2} & 0 & \dots & 0 & 0 \\ \vdots & & & & & & \\ 0 & 0 & 0 & 0 & \dots & A_{rs} & \dots & 0 \\ \vdots & & & & & & \\ 0 & 0 & 0 & 0 & \dots & 0 & A_{rc_{r}-1} \\ A_{r0} & 0 & 0 & 0 & \dots & 0 & 0 \end{vmatrix}$$

where the  $A_{r}$  and  $A_{00}$  are square matrices and:

(IIa)  $\lim_{m \to \infty} A_{00}^m = 0$ ,

(IIb) the entries of  $A_r$  which are in no  $A_r$  are zero, rs

(IIc) for each  $r = 1, 2, ..., \nu$  there are stochastic matrices  $\Pi_{r0}, \Pi_{r1}, ..., \Pi_{rs}, ..., \Pi_{r,c_r-1}$  such that for each  $t = 0, 1, ..., c_r-1$ :

The entries in this matrix are zero if and only if they are in no  $\Pi_{rs}$ , there are as many rows in  $\Pi_{rs}$  as there are rows in  $\Lambda_{r,s-t+1}$  (second subscript modulo c<sub>r</sub>), and all of the rows of  $\Pi_{rs}$  are the same vector  $\pi^{(r,s)}$ .

The method we shall use to prove the fundamental theorem and related theorems is briefly this: we identify the n by n stochastic matrix A with a linear operator f on the simplex, S, spanned by the basis vectors of Euclidean n-space. The intersection, K, of all the images  $f^{m}(S)$  is a simplex whose vertices are permuted by f. The position of K in S and this permutation determine the behaviour of the  $a_{ij}^{(m)}$  for large m and also locate the vertices of the simplex of its stochastic eigenvectors.

Before going further we shall state a few definitions and preliminary remarks for the reader's convenience.

A convex polytope P is the convex hull of finitely many points  $t_1, t_2, \ldots, t_m$  in some Euclidean n-space. The point  $t_i$  is a vertex of P iff the convex hull of the others doesn't contain it. The convex hull of any subset of the vertices of P is called a <u>sub-polytope</u> of P. A linear function f mapping P into P is called a linear operator on P. A convex polytope P is a <u>simplex</u> iff none of its vertices is in the flat determined by the remaining vertices. If S is a simplex, each subpolytope is called a <u>subsimplex</u>. The subsimplices of S are themselves simplices. If A is a subset of the convex polytope P, <u>a car-</u> rier of A in P is a subpolytope with fewest vertices, containing A. If P is a simplex then each non empty subset has a unique carrier in P.

Three direct consequences of these definitions which we shall refer to in the sequel are:

(1) subsimplices without vertices in common are disjoint;

(2) if the carriers of m points in a simplex S are disjoint then the convex hull of these points is a simplex;

(3) if f is a linear operator on a simplex S, then the image of the carrier of a subset X of S is contained in the carrier of f(X).

The method we use is based on a lemma which we couldn't find in the literature:

LEMMA 1. The intersection K, of a nested sequence of convex polytopes  $\{P_{\alpha}\}$  each of which has n vertices is a convex polytope.

<u>Proof.</u> It is possible to choose a subsequence,  $\{P_{\alpha\beta}\}$ and a vertex  $v_{\beta}$  of  $Q_{\beta} = P_{\alpha\beta}$  such that  $\{v_{\beta}\}$  converges, to  $k_{1}$  say. Next choose a subsequence  $\{Q_{\beta\gamma}\}$  of  $\{Q_{\beta}\}$  and a sequence of vertices  $w_{\gamma}$  of  $R_{\gamma} = Q_{\beta\gamma}$  with  $w_{\gamma} \neq v_{\beta\gamma}$  such that

w converges, to  $k_2$  say. And so on, getting  $k_1, k_2, \ldots, k_n$ . This process must halt in n steps because the  $P_{\alpha}$  have only n vertices apiece. Let T be the convex hull of the  $k_i$ . Clearly TCK. Suppose  $x \in K \sim T$ . Let h be a hyperplane separating x from T. Let  $\varepsilon$  be the distance from h to T. For each i there are infinitely many  $\alpha$  for which a vertex of  $P_{\alpha}$  is in the sphere of radius  $\varepsilon/2$  about  $k_i$ . There is therefore a member of  $\{P_{\alpha}\}$  on the side of h opposite x hence  $\bigcap P_{\alpha}$ and  $\{x\}$  are disjoint. Thus  $K \sim T = \emptyset$  and hence K = T.

LEMMA 2. If f is a continuous function mapping the compact set P into P and  $K = \bigcap_{m>1} f^{m}(P)$  then f(K) = K.

<u>Proof.</u> It is sufficient to show that  $K \subseteq f(K)$ . If  $x \in K$ then  $x \in f^{m}(P)$  for all m > 0 and hence  $x = f(x_{m-1})$  for some  $x_{m-1} \in f^{m-1}(P)$ . The  $x_{m}$  have a convergent subsequence  $\{x_{m}\}$  converging to a point y of P. If we can show that  $y \in K$  then we are through because  $x = \lim_{i \to \infty} f(x_{i}) = f(y)$ .  $i \to \infty$ 

If y were not in K then, for some N, y would not be in  $f^{N}(P)$ . The complement of  $f^{N}(P)$  contains no x for  $m_{i}$  is minimized by  $m_{i} > N$ . But the complement of  $f^{N}(P)$  is an open neighborhood of y. Therefore  $y \in K$ .

THEOREM 1. If f is a linear operator on a simplex S then

(i) the intersection, K, of the iterates  $f^{m}(S)$  is a simplex, and

(ii) the vertices of K are permuted by f and hence fall into  $\nu$  disjoint classes on each of which f is a cyclic permuta-

tion so that for  $r = 1, 2, ..., \nu$  and  $s = 0, 1, ..., c_r - 1$ , (where  $c_r$  is the number of elements in the r-th class) we have

(iii)  $f(k_{rs}) = k_{r, s+1}$  (the second subscript is read modulo  $c_r$ ).

If  $C_{rs}$  is the carrier of  $k_{rs}$  in S then

(iv) the C are disjoint,

(v) 
$$f^{t}(C_{rs}) \subseteq C_{r,s+1}$$
, and

(vi)  $\bigcap_{m \equiv t} f^m (C_{rs}) = k_{rs'}$  when  $s' \equiv t + s \pmod{c_r}$ .

If K is the subsimplex of K whose vertices are  $r_{r0}^{k}$ ,  $k_{r1}^{k}$ ,  $\ldots$ ,  $k_{r,c_{r}-1}^{k}$  then

(vii) the K are disjoint and

(viii) the set of all f-fixed points in S is a simplex whose vertices are the barycenters of the  $K_{r}$ .

## Proof.

(a) Lemmas 1 and 2 establish that K is a convex polytope and that f(K) = K.

(b) f permutes the vertices of K.

Let k be a vertex of K,  $X_k = [f^{-1}(k)] \cap K$  and  $C_K(X_k)$  denote a carrier of  $X_k$  in K. Then  $f(C_K(X_k)) = \{k\}$  by remark (3) and hence  $C_K(X_k) = X_k$ . Therefore there are as many  $C_K(X_k)$ as there are vertices of K, since the  $X_k$  are pairwise disjoint and hence each carrier  $C_{K}(X_{k})$  has only one vertex. Thus  $f^{-1}$  and hence f permute the vertices of K.

The family of sets,  $\{\bigcup_{\substack{m \ge 0}} \{f^m(k)\}: k \text{ is a vertex of } K\}$ , partition the vertices of K into  $\nu$  disjoint classes on each of which f is a cyclic permutation. Denote the convex hulls of these partitioning sets by  $K_1, K_2, \ldots, K_{\nu}$ . Let  $k_{r0}$  be any vertex of  $K_r$ ; let  $k_{rs} = f^s(k_{r0})$  for  $r = 1, 2, \ldots, \nu$  and  $s = 0, 1, 2, \ldots, c_r^{-1}$ . Let  $C_{rs}$  denote the carrier in S of  $k_{rs}^s$ .

(c) Each  $C_{rs}$  meets K in only one point, namely  $k_{rs}$ , and hence  $C_{rs} = C_{r's'}$  iff (r,s) = (r',s'). If not  $C_{rs}$  would contain two distinct points  $k_{rs}$  and k' of K. The line they determine would meet  $C_{rs}$  in a line segment contained in K neither of whose endpoints is  $k_{rs}$ , contradicting the assumption that  $k_{rs}$  is a vertex.

(d)  $f(C_{rs}) \subseteq C_{r,s+1}$  and hence  $f^{t}(C_{rs}) \subseteq C_{rs'}$  if s'  $\equiv t + s \pmod{c_r}$ ; because, by remark (3),  $f(C_{rs})$  is contained in the carrier in S of  $f(k_{rs})$  which is  $C_{r,s+1}$ by definition.

(e) 
$$\bigcap_{m \equiv t} f^{m}(C_{rs}) = \{k_{rs'}\} \text{ if } s' \equiv t + s \pmod{c_{r}}.$$

To see why this is so we observe first that if  $m \equiv t \pmod{c_r}$ , then  $k_{rs'} \in f^m(C_{rs})$  because  $f^m(k_{rs}) = k_{r,s+m} = k_{rs'}$ ; and secondly that  $(\bigcap_{m \equiv t} f^m(C_{rs})) \subseteq K$  so that  $\{k_{rs'}\} \subseteq \bigcap_{m \equiv t} f^m(C_{rs})$  $= K \cap \bigcap_{m \equiv t} f^m(C_{rs}) \subseteq \bigcap_{m \equiv t} K \cap f^m(C_{rs}) \subseteq \bigcap_{m \equiv t} K \cap C_{rs'}$ .

According to (c),  $K \cap C_{rs'} = \{k_{rs'}\}$  and hence  $\bigcap_{m \equiv t} f^m(C_{rs})$ =  $\{k_{rs'}\}$ . An immediate consequence of this is:

(f) The C are pairwise disjoint. Applying remarks
(2) and (1) we have:

(g) K is a simplex and the K are disjoint.

Evidently the set F of all fixed points is a convex subset of K. By linearity, the barycenter  $b_r = \frac{1}{c_r} \sum_{r=0}^{r-1} k_{rs}$  of K is fixed by f and hence F contains the convex hull of these barycenters. Conversely, if x is fixed, then, since  $x \in K$ ,  $v = c_r^{-1}$   $x = \sum \sum x k_r$  (where  $x \ge 0$  and  $\sum x r = 1$ ) r = 1 = s = 0  $v = c_r^{-1}$ and hence  $f(x) = \sum \sum x k_r$ , s + 1 = x. Therefore r = 1 = s = 0  $x_{rs} = x_{rs}$ , where  $s' \equiv s + 1 \pmod{c_r}$  and hence, given r, either  $x_{rs} = 0$  for each  $0 \le s < c_r$  or for all  $0 \le s < c_r : x_r = \frac{4}{c_r}$ . Consequently x is in the convex hull of the barycenters. Therefore F is a convex polytope spanned by the v barycenters of the K. The barycenters of the K are the vertices of F because the K are distinct. By applying remark (2) and (g)

we obtain:

(h) The set F of all f-fixed points is a simplex whose vertices are the barycenters of the  $K_{\mu}$ .

This completes the proof of the theorem.

We shall present a proof of the probabilistic form of the fundamental theorem (theorem I) after a few preliminary remarks showing the correspondence between the pertinant geometric and probabilistic ideas. Each state i = 1, 2, ..., n of the Markov chain whose one step transition matrix is  $A = (a_{ij})$  corresponds to the n-tuple  $v_i$  whose only non-zero component, 1, is its i-th component. Let f(x) = xA (i.e. the j-th component of f(x) is  $\sum_{i=1}^{n} \sum_{i=1}^{\infty} x_i a_{ij}$  for each x in the convex hull S, of the  $v_i$ . S is i=1a simplex and f is a linear operator on S. If  $X \subseteq S$  let C(X) denote the carrier of X in S. We then have:

(4)  $i \sim j$  iff  $v_j \in \bigcup_{m>0} C(f^m(v_i))$  because of the definitions of  $\sim$  and C.

We shall show that

(5) i is ergodic iff  $v_i$  is a vertex of C(K)

after we have established (5a) and (5b) below.

(5a) If  $E(K) = \{i : v \in C(K)\}$  then for each j there is an  $i \in E(K)$  such that  $j \sim i$ .

Proof of (5a). Let  $D = C(\{f^{m}(v_{j}):m > 0\})$  then, using (3), we have  $f(D) \subseteq D$  and hence  $\bigcap_{m>0} f^{m}(D)$  is a non-empty subset of both K and D. There is, therefore, a vertex  $v_{i}$ of C(K) which is also a vertex of D. But the vertices of D are also those of  $\bigcup_{m>0} C(f^{m}(v_{i}))$ . Consequently  $j \sim i \in E(K)$ .

(5b) If  $i \in E(K)$  and  $i \sim j$  then  $j \in E(K)$  and  $j \sim i$ .

Proof of (5b).  $i \in E(K)$  and  $i \sim j$  imply that  $v_i$  is a vertex of some  $C_{rs}$  and  $v_j$  is a vertex of some  $C(f^t(v_i))$  by (4). Therefore  $f^t(v_i) \in f^t(C_{rs})$ . But  $f^t(C_{rs}) \subseteq C_{rs}$ , when  $s' \equiv s + t \pmod{c_s}$  according to Theorem 1 part (v) and hence

v<sub>j</sub> is a vertex of  $C_{rs'}$ . Consequently  $j \in E(K)$ .  $C(f^{m}(v_{j})) = C_{rs}$  for a sufficiently large  $m \equiv s - s' \pmod{c_{r}}$ by parts (v) and (vi) of theorem 1, but  $v_{i} \in C_{rs}$  and hence  $j \sim i$  by (4).

Proof of (5).  $E(K) \subseteq E$  by (5b) and the definition of E. If  $j \notin E(K)$  then  $j \sim i \in E(K)$  by (5a) and  $i \not \sim j$  by (5b). Consequently  $j \notin E$  and hence  $E \subseteq E(K)$ .

Proof of Theorem I.

(Ia) If i is any state let  $x^{(m)}$  be the point of C(K) closest to  $f^{m}(v_{i})$ . Because of the definition of K the sequence of distances  $d_{m}$  between  $f^{m}(v_{i})$  and  $x^{(m)}$  converges to zero. According to (5)  $x_{j}^{(m)} = 0$  for all transient j; therefore  $\lim_{m \to \infty} a_{ij}^{(m)} = 0$  because the j-th component of  $f^{m}(v_{i})$  is  $a_{ij}^{(m)}$ .

Let  $E_{rs} = \{i : v_i \in C_{rs}\}$ ; then, evidently,  $c_r - 1$   $E_r = \bigcup_{s=0}^{r} E_{rs}$ . The  $E_{rs}$  are pairwise disjoint and non-empty because of parts (iii) and (iv) of Theorem 1.

(Ib) If  $i \in E_{rs}$  and i leads to j in one step then  $v_i \in C_{rs}$  and  $v_j \in C(f(v_i))$ . But according to Theorem 1 part (v):  $f(v_i) \in C_{r,s+1}$  and hence  $v_j \in C_{r,s+1}$ .

Consequently  $j \in E_{r, s+1}$ .

(Ic)  $k_{rs}$  is an n-tuple of non-negative numbers summing to 1 because  $k_{rs} \in S$ . The j-th component,  $k_j^{(r,s)}$  of  $k_j$ is 0 iff  $j \notin E_{rs}$  because of the definitions of  $C_{rs}$  and  $E_{rs}$ .

$$\lim_{\substack{n \to \infty}} a_{ij} = k_{j}^{(r,s')} \quad \text{for all } j \text{ and all}$$

 $t = 0, 1, \ldots, c_r - 1$  whenever  $i \in E_{rs}$  and  $s' \equiv s + t \pmod{c_r}$ by (vi).

This completes the proof of theorem I.

Theorem II can be proven either directly from Theorem I (their statements are equivalent) or from Theorem 1.

To obtain a proof of Theorem II the latter way let c(r, s)be the number of vertices in C and let P be the permutation matrix which performs the change of basis mapping the first c basis vectors (vertices)  $v_1, v_2, \ldots, v_c$  onto each of the c vertices not in C(K), mapping the next c(1,1) basis vectors  $v_{c+1}, v_{c+2}, \ldots, v_{c+c(1,1)}$  onto the vertices of C 11; and so forth until all the last  $c(v, c_v - 1)$  basis vectors are mapped onto the vertices of C  $v, c_v - 1$ .

(IIa) is proven analogously to (Ia). (IIb) is a result of (v).

To prove (IIc), define  $\pi^{(r,s)}$  by letting  $\pi_j^{(r,s)}$  be the j-th component of  $k_{rs}$  for each j = 1, 2, ..., c(r,s); each  $s = 0, 1, ..., c_r - 1$  and each  $r = 1, 2, ..., \nu$ . (IIc) then follows from (vi).

We have extended the techniques used here to study inhomogeneous chains, that is, to study the asymptotic behaviour of products  $A_1 \cdot A_2 \cdot \ldots \cdot A_n \cdot \ldots$  of stochastic matrices  $A_n$  which are not necessarily the same matrix and all of which might be infinite. Some of these results are contained in a forthcoming paper on infinite products of substochastic matrices [7].

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