

Asymptotic K -Theory for Groups Acting on \tilde{A}_2 Buildings

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Abstract. Let Γ be a torsion free lattice in $G = \mathrm{PGL}(3, \mathbb{F})$ where \mathbb{F} is a nonarchimedean local field. Then Γ acts freely on the affine Bruhat-Tits building \mathcal{B} of G and there is an induced action on the boundary Ω of \mathcal{B} . The crossed product C^* -algebra $\mathcal{A}(\Gamma) = C(\Omega) \rtimes \Gamma$ depends only on Γ and is classified by its K -theory. This article shows how to compute the K -theory of $\mathcal{A}(\Gamma)$ and of the larger class of rank two Cuntz-Krieger algebras.

1 Introduction

Let \mathbb{F} be a nonarchimedean local field with residue field of order q . The Bruhat-Tits building \mathcal{B} of $G = \mathrm{PGL}(n+1, \mathbb{F})$ is a building of type \tilde{A}_n and there is a natural action of G on \mathcal{B} . The vertex set of \mathcal{B} may be identified with the homogeneous space G/K , where K is an open maximal compact subgroup of G . The boundary Ω of \mathcal{B} is the homogeneous space G/B , where B is the Borel subgroup of upper triangular matrices in G .

Let Γ be a torsion free lattice in $G = \mathrm{PGL}(n+1, \mathbb{F})$. Then Γ is automatically cocompact in G [Ser, Chapitre II.1.5, p. 116] and acts freely on \mathcal{B} . If $n = 1$, then Γ is a finitely generated free group [Ser], \mathcal{B} is a homogeneous tree, and the boundary Ω is the projective line $\mathbb{P}_1(\mathbb{F})$. If $n \geq 2$ then the group Γ and its action on Ω are not so well understood. In contrast to the rank one case, Γ has Kazhdan's property (T) and by the Strong Rigidity Theorem of Margulis [Mar, Theorem VII.7.1], the lattice Γ determines the ambient Lie group G . Since the Borel subgroup B of G is unique, up to conjugacy, it follows that the action of Γ on Ω is also unique, up to conjugacy. This action may be studied by means of the crossed product C^* -algebra $C(\Omega) \rtimes \Gamma$, which depends only on Γ and may conveniently be denoted by $\mathcal{A}(\Gamma)$.

Geometrically, a locally finite \tilde{A}_n building \mathcal{B} is an n -dimensional contractible simplicial complex in which each codimension one simplex lies on $q+1$ maximal simplices, where $q \geq 2$. If $n \geq 2$ then the number q is necessarily a prime power and is referred to as the order of the building. The building is the union of a distinguished family of n -dimensional subcomplexes, called *apartments*, and each apartment is a Coxeter complex of type \tilde{A}_n . If \mathcal{B} is a locally finite building of type \tilde{A}_n , where $n \geq 3$, then \mathcal{B} is the building of $\mathrm{PGL}(n+1, \mathbb{F})$ for some (possibly non commutative) local field \mathbb{F} [Ron, p. 137]. The case of \tilde{A}_2 buildings is somewhat different, because such a building might not be the Bruhat-Tits building of a linear group. In fact this is

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the case for the \tilde{A}_2 buildings of many of the groups constructed in [CMSZ]. The boundary Ω of \mathcal{B} is the set of chambers of the spherical building at infinity [Ron, Chapter 9], endowed with a natural totally disconnected compact Hausdorff topology [CMS], [Ca, Section 4].

Given an \tilde{A}_n building \mathcal{B} with vertex set \mathcal{B}^0 , there is a type map $\tau: \mathcal{B}^0 \rightarrow \mathbb{Z}/(n+1)\mathbb{Z}$ such that each maximal simplex (chamber) has exactly one vertex of each type. An automorphism α of Δ is said to be *type-rotating* if there exists $i \in \mathbb{Z}/(n+1)\mathbb{Z}$ such that $\tau(\alpha v) = \tau(v) + i$ for all vertices $v \in \mathcal{B}^0$. If \mathcal{B} is the Bruhat-Tits building of $G = \mathrm{PGL}(n+1, \mathbb{F})$ then the action of G on \mathcal{B} is type rotating [St].

Now let Γ be a group of type rotating automorphisms of an \tilde{A}_n building \mathcal{B} and suppose that Γ acts freely on the vertex set \mathcal{B}^0 with finitely many orbits. Then Γ acts on the boundary Ω and the rigidity results of [KL] imply that, as in the linear case above, the action is unique up to conjugacy and the crossed product C^* -algebra $\mathcal{A}(\Gamma) = C(\Omega) \rtimes \Gamma$ depends only on the group Γ .

The purpose of this paper is to compute the K -theory of the algebras $\mathcal{A}(\Gamma)$ in the case $n = 2$. This is done by using the fact that the algebras are higher rank Cuntz-Krieger algebras, whose structure theory was developed in [RS2]. In particular they are purely infinite, simple and nuclear. It was proved in [RS2] that a higher rank Cuntz-Krieger algebra is stably isomorphic to a crossed product of an AF algebra by a free abelian group. The computation of the K -groups is therefore in principle completely routine: no new K -theoretic or geometric ideas are needed. Actually organizing and performing the computations is another matter. This paper does this in the case $n = 2$. The most precise results are obtained in Section 7 for the algebra $\mathcal{A}(\Gamma)$ where Γ is an \tilde{A}_2 group; that is Γ acts freely *and* transitively on the vertices of an \tilde{A}_2 building. Such groups have been studied intensively in [CMSZ].

The detailed numerical results of our computations are available elsewhere, but we do present, in Example 7.3, the K -theory of $\mathcal{A}(\Gamma)$ for two torsion free lattices Γ in $\mathrm{PGL}(3, \mathbb{Q}_2)$. The non isomorphism of these two groups is seen in the K -theory of $\mathcal{A}(\Gamma)$ but not in the K -theory of the reduced group C^* -algebra $C_r^*(\Gamma)$.

The article concludes with some results on the order of the class of the identity in $K_0(\mathcal{A}(\Gamma))$.

2 Groups Acting on \tilde{A}_2 Buildings: Statement of the Main Result

Let \mathcal{B} be a finite dimensional simplicial complex, whose maximal simplices we shall call chambers. All chambers are assumed to have the same dimension and adjacent chambers have a common codimension one face. A gallery is a sequence of adjacent chambers. \mathcal{B} is a chamber complex if any two chambers can be connected by a gallery. \mathcal{B} is said to be *thin* if every codimension one simplex is a face of precisely two chambers. \mathcal{B} is said to be *thick* if every codimension one simplex is a face of at least three chambers. A chamber complex \mathcal{B} is called a *building* if it is the union of a family of subcomplexes, called *apartments*, satisfying the following axioms [Br3].

- (B0) Each apartment Σ is a thin chamber complex with $\dim \Sigma = \dim \mathcal{B}$.
- (B1) Any two simplices lie in an apartment.

- (B2) Given apartments Σ, Σ' there exists an isomorphism $\Sigma \rightarrow \Sigma'$ fixing $\Sigma \cap \Sigma'$ pointwise.
- (B3) \mathcal{B} is thick.

A building of type \tilde{A}_2 has apartments which are all Coxeter complexes of type \tilde{A}_2 . Such a building is therefore a union of two dimensional apartments, each of which may be realized as a tiling of the Euclidean plane by equilateral triangles.

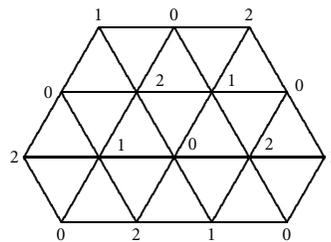


Figure 1: Part of an apartment in an \tilde{A}_2 building, showing vertex types.

From now on we shall consider only locally finite buildings of type \tilde{A}_2 . Each vertex v of \mathcal{B} is labeled with a type $\tau(v) \in \mathbb{Z}/3\mathbb{Z}$, and each chamber has exactly one vertex of each type. An automorphism α of \mathcal{B} is said to be *type rotating* if there exists $i \in \mathbb{Z}/3\mathbb{Z}$ such that $\tau(\alpha(v)) = \tau(v) + i$ for all vertices $v \in \mathcal{B}$.

A sector is a $\frac{\pi}{3}$ -angled sector made up of chambers in some apartment (Figure 2). Two sectors are equivalent if their intersection contains a sector.

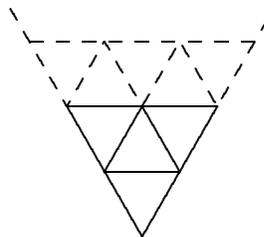


Figure 2: A sector in a building \mathcal{B} of type \tilde{A}_2 .

The boundary Ω of \mathcal{B} is defined to be the set of equivalence classes of sectors in \mathcal{B} . In \mathcal{B} fix some vertex O . For any $\omega \in \Omega$ there is a unique sector $[O, \omega)$ in the class ω having base vertex O [Ron, Theorem 9.6]. The boundary Ω is a totally disconnected compact Hausdorff space with a base for the topology given by sets of the form

$$\Omega(v) = \{\omega \in \Omega: [O, \omega) \text{ contains } v\}$$

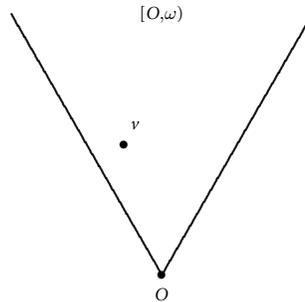


Figure 3: The sector $[O, \omega]$, where $\omega \in \Omega(v)$.

where v is a vertex of \mathcal{B} [CMS, Section 2]. If \mathcal{B} is the (type \tilde{A}_2) Bruhat-Tits building of $\text{PGL}(3, \mathbb{F})$ where \mathbb{F} is a nonarchimedean local field then this definition of the boundary coincides with that given in the introduction [St].

Let \mathcal{B} be a locally finite affine building of type \tilde{A}_2 . Let Γ be a group of type rotating automorphisms of \mathcal{B} that acts freely on the vertex set with finitely many orbits. Let t be a model tile for \mathcal{B} consisting of two chambers with a common edge and with vertices coordinatized as shown in Figure 4. For definiteness, assume that the vertex (j, k) has type $\tau(j, k) = j - k \pmod{2} \in \{0, 1, 2\}$. Let \mathfrak{T} denote the set of type rotating isometries $i: t \rightarrow \mathcal{B}$, and let $A = \Gamma \setminus \mathfrak{T}$. Take A as an alphabet. Informally we think of elements of A as labeling the tiles of the building according to Γ -orbits.

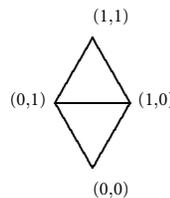


Figure 4: The model tile t

Two matrices M_1, M_2 with entries in $\{0, 1\}$ are defined as follows. If $a, b \in A$, say that $M_1(b, a) = 1$ if and only if there are representative isometries i_a, i_b in \mathfrak{T} whose ranges lie as shown in the diagram on the right of Figure 5. In that diagram, the tiles $i_a(t), i_b(t)$ have base vertices $i_a(0, 0), i_b(0, 0)$ respectively and $i_b(0, 0) = i_a(1, 0)$. A similar definition applies for $M_2(c, a) = 1$.

In Section 5 below the following result is proved. It expresses the K -theory of $\mathcal{A}(\Gamma)$ in terms of the cokernel of the homomorphism $\mathbb{Z}^A \oplus \mathbb{Z}^A \rightarrow \mathbb{Z}^A$ defined by $(I - M_1, I - M_2)$.

Theorem 2.1 *Let Γ be a group of type rotating automorphisms of a building \mathcal{B} of type \tilde{A}_2 which acts freely on the set of vertices of \mathcal{B} with finitely many orbits. Let Ω be the boundary of the building and let $\mathcal{A}(\Gamma) = C(\Omega) \rtimes \Gamma$. Denote by M_1, M_2 the*

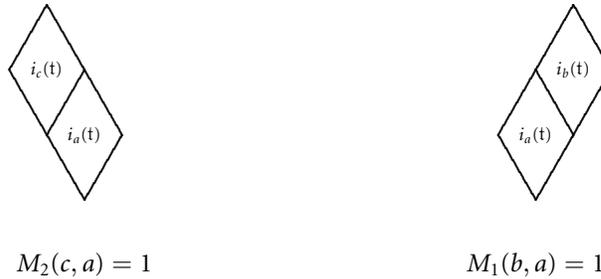


Figure 5: Definition of the transition matrices.

associated transition matrices, as defined above. Let r be the rank, and T the torsion part, of the finitely generated abelian group $\text{coker}(I-M_1, I-M_2)$. Thus $\text{coker}(I-M_1, I-M_2) = \mathbb{Z}^r \oplus T$. Then

$$K_0(\mathcal{A}(\Gamma)) = K_1(\mathcal{A}(\Gamma)) = \mathbb{Z}^{2r} \oplus T$$

Remark 2.2 The group Γ in Theorem 2.1 need not necessarily be torsion free. It may have 3-torsion and stabilize a chamber of the building.

3 Rank 2 Cuntz-Krieger Algebras

In [RS2], the authors introduced a class of C^* -algebras which are higher rank analogues of the Cuntz-Krieger algebras [CK]. We shall refer to the original algebras of [CK] as rank one Cuntz-Krieger algebras. The rank 2 case includes the algebras $\mathcal{A}(\Gamma)$ arising from discrete group actions on the boundary of an \tilde{A}_2 building as described in Section 2. In this section we shall compute the K -theory of a general rank 2 Cuntz-Krieger algebra \mathcal{A} .

We first outline how the algebra \mathcal{A} is defined. For our present investigation of the rank two case the assumptions in [RS2] can be somewhat simplified. Fix a finite set A , which is the ‘‘alphabet’’. Start with a pair of nonzero matrices M_1, M_2 with entries $M_j(b, a) \in \{0, 1\}$ for $a, b \in A$. For an algebra of the form $\mathcal{A}(\Gamma)$, the alphabet A and the matrices M_1, M_2 are defined in Section 2 above.

Let $[m, n]$ denote $\{m, m + 1, \dots, n\}$, where $m \leq n$ are integers. If $m, n \in \mathbb{Z}^2$, say that $m \leq n$ if $m_j \leq n_j$ for $j = 1, 2$, and when $m \leq n$, let $[m, n] = [m_1, n_1] \times [m_2, n_2]$. In \mathbb{Z}^2 , let 0 denote the zero vector and let e_j denote the j -th standard unit basis vector. If $m \in \mathbb{Z}_+^2 = \{m \in \mathbb{Z}^2; m \geq 0\}$, let

$$W_m = \{w: [0, m] \rightarrow A; M_j(w(l + e_j), w(l)) = 1 \text{ whenever } l, l + e_j \in [0, m]\}$$

and call the elements of W_m words. Let $W = \bigcup_{m \in \mathbb{Z}_+^2} W_m$. We say that a word $w \in W_m$ has shape $\sigma(w) = m$, and we identify W_0 with A in the natural way via the map $w \mapsto w(0)$. Define the initial and final maps $o: W_m \rightarrow A$ and $t: W_m \rightarrow A$ by $o(w) = w(0)$ and $t(w) = w(m)$. We assume that the matrices M_1, M_2 satisfy the following conditions.

- (H0) Each M_i is a nonzero $\{0, 1\}$ -matrix.
- (H1a) $M_1M_2 = M_2M_1$.
- (H1b) M_1M_2 is a $\{0, 1\}$ -matrix.
- (H2) The directed graph with vertices $a \in A$ and directed edges (a, b) whenever $M_i(b, a) = 1$ for some i , is irreducible.
- (H3) For any nonzero $p \in \mathbb{Z}^2$, there exists a word $w \in W$ which is not p -periodic, i.e. there exists l so that $w(l)$ and $w(l + p)$ are both defined but not equal.

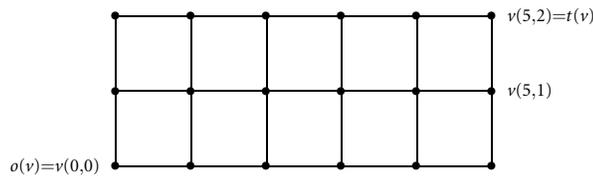


Figure 6: Representation of a two dimensional word v of shape $m = (5, 2)$.

If $v \in W_m$ and $w \in W_{e_j}$ with $t(v) = o(w)$ then there exists a unique word $vw \in W_{m+e_j}$ such that $vw|_{[0,m]} = v$ and $t(vw) = t(w)$ [RS2, Lemma 1.2]. The word vw is called the *product* of v and w .

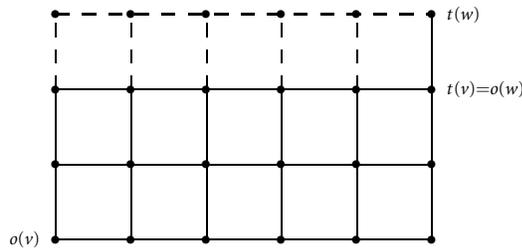


Figure 7: The product word vw , where $w \in W_{e_2}$.

The C^* -algebra \mathcal{A} is the universal C^* -algebra generated by a family of partial isometries $\{s_{u,v} ; u, v \in W \text{ and } t(u) = t(v)\}$ and satisfying the relations

$$(3.1a) \quad s_{u,v}^* = s_{v,u}$$

$$(3.1b) \quad s_{u,v}s_{v,w} = s_{u,w}$$

$$(3.1c) \quad s_{u,v} = \sum_{\substack{w \in W; \sigma(w) = e_j, \\ o(w) = t(u) = t(v)}} s_{uw,vw}$$

$$(3.1d) \quad s_{u,u}s_{v,v} = 0 \quad \text{for } u, v \in W_0, u \neq v.$$

It was shown in [RS2] that \mathcal{A} is simple, unital, nuclear and purely infinite, and that it is therefore classified by its K -theory. Moreover the algebra $\mathcal{A}(\Gamma)$ arising from a discrete group action on the boundary of an \tilde{A}_2 building is stably isomorphic to the corresponding algebra \mathcal{A} . See Section 5.

By [RS2, Section 6], the stabilized algebra $\mathcal{A} \otimes \mathcal{K}$ can be constructed as a crossed product by \mathbb{Z}^2 . The details are as follows. Let $\mathcal{C} = \bigoplus_{a \in A} \mathcal{K}(\mathcal{H}_a)$, where \mathcal{H}_a is a separable infinite dimensional Hilbert space. For each $l \in \mathbb{Z}_+^2$ there is an endomorphism $\alpha_l: \mathcal{C} \rightarrow \mathcal{C}$ defined by the equation

$$(3.2) \quad \alpha_l(x) = \sum_{w \in W_l} \nu_w x \nu_w^*$$

where ν_w is a partial isometry with initial space $\mathcal{H}_{o(w)}$ and final space lying inside $\mathcal{H}_{t(w)}$. For the precise definition we refer to [RS2], where ν_w is denoted $\psi(s'_{w,o(w)})$. For each $m \in \mathbb{Z}^2$ let $\mathcal{C}^{(m)}$ be an isomorphic copy of \mathcal{C} , and for each $l \in \mathbb{Z}_+^2$, let

$$\alpha_l^{(m)}: \mathcal{C}^{(m)} \rightarrow \mathcal{C}^{(m+l)}$$

be a copy of α_l . Let $\mathcal{F} = \varinjlim \mathcal{C}^{(m)}$ be the direct limit of the category of C^* -algebras with objects $\mathcal{C}^{(m)}$ and morphisms α_l . Then \mathcal{F} is an AF-algebra. Since α_l is an endomorphism, we may identify $\mathcal{C}^{(m)}$ with its image in \mathcal{F} ([KR, Proposition 11.4.1]). If $x \in \mathcal{C}$, let $x^{(m)}$ be the corresponding element of $\mathcal{C}^{(m)}$. Now $\mathcal{A} \otimes \mathcal{K} \cong \mathcal{F} \rtimes \mathbb{Z}^2$, so that $K_*(\mathcal{A}) = K_*(\mathcal{F} \rtimes \mathbb{Z}^2)$. The action of \mathbb{Z}^2 on \mathcal{F} is defined by two commuting generators T_1, T_2 , where $T_j(x^{(m)}) = x^{(m-e_j)}$, $j = 1, 2$. We have $K_0(\mathcal{F}) = \varinjlim K_0(\mathcal{C}^{(m)})$. The maps T_j induce maps $(T_j)_*: K_0(\mathcal{F}) \rightarrow K_0(\mathcal{F})$, $j = 1, 2$.

Remark 3.1 Note that in [RS2] we considered a more general algebra denoted \mathcal{A}_D , where D is a nonempty countable set (called the set of “decorations”) and there is an associated map $\delta: D \rightarrow A$. The algebra \mathcal{A} described above is simply the algebra \mathcal{A}_A where $D = A$ and δ is the identity map on A . It was shown in [RS2, Lemma 4.13, Corollary 4.16] that for any set D of decorations there exists an isomorphism $\mathcal{A}_D \otimes \mathcal{K} \cong \mathcal{A} \otimes \mathcal{K}$. The algebra \mathcal{A}_D therefore has the same K -theory as \mathcal{A} , namely the K -theory of the algebra $\mathcal{F} \rtimes \mathbb{Z}^2$.

4 K -Theory for Rank 2 Cuntz-Krieger Algebras

Consider the chain complex

$$(4.1) \quad 0 \longleftarrow K_0(\mathcal{F}) \xleftarrow{(1-T_{2*}, T_{1*}-1)} K_0(\mathcal{F}) \oplus K_0(\mathcal{F}) \xleftarrow{\begin{pmatrix} 1-T_{1*} \\ 1-T_{2*} \end{pmatrix}} K_0(\mathcal{F}) \longleftarrow 0$$

For $j \in \{0, 1, 2\}$, denote by \mathfrak{H}_j the j -th homology group of the complex (4.1). In particular $\mathfrak{H}_0 = \text{coker}(1 - T_{2*}, T_{1*} - 1)$ and $\mathfrak{H}_2 = \ker \begin{pmatrix} 1-T_{1*} \\ 1-T_{2*} \end{pmatrix}$.

Proposition 4.1 *If the group \mathfrak{H}_2 is free abelian then*

$$K_0(\mathcal{A}) \cong \mathfrak{H}_0 \oplus \mathfrak{H}_2,$$

$$K_1(\mathcal{A}) \cong \mathfrak{H}_1.$$

Proof As observed in the introduction, $K_*(\mathcal{A}) = K_*(\mathcal{F} \rtimes \mathbb{Z}^2)$. It is known that the Baum-Connes Conjecture with coefficients in an arbitrary C^* -algebra is true for the group \mathbb{Z}^2 (and much more generally: [BBV] [Tu] [BCH, Section 9]). This implies that $K_*(\mathcal{F} \rtimes \mathbb{Z}^2)$ coincides with its “ γ -part”, and $K_*(\mathcal{F} \rtimes \mathbb{Z}^2)$ may be computed as the limit of a Kasparov spectral sequence [Ka, p. 199, Theorem]. The initial terms of the spectral sequence are $E_{p,q}^2 = H_p(\mathbb{Z}^2, K_q(\mathcal{F}))$, the p -th homology of the group \mathbb{Z}^2 with coefficients in the module $K_q(\mathcal{F})$. (See [W, Chapter 5] for an explanation of spectral sequences and their convergence.) Noting that $K_q(\mathcal{F}) = 0$ for q odd (since the algebra \mathcal{F} is AF), it follows that $E_{p,q}^2 = 0$ for q odd. Also $E_{p,q}^2 = 0$ for $p \notin \{0, 1, 2\}$, and the differential d_2 is zero. Thus

$$E_{p,q}^\infty = E_{p,q}^2 = \begin{cases} H_p(\mathbb{Z}^2, K_q(\mathcal{F})) & \text{if } p \in \{0, 1, 2\} \text{ and } q \text{ is even,} \\ 0 & \text{otherwise.} \end{cases}$$

To clarify notation, write $G = \mathbb{Z}^2 = \langle s, t \mid st = ts \rangle$. We have a free resolution F of \mathbb{Z} over $\mathbb{Z}G$ given by

$$0 \longleftarrow \mathbb{Z} \longleftarrow \mathbb{Z}G \xleftarrow{(1-t, s-1)} \mathbb{Z}G \oplus \mathbb{Z}G \xleftarrow{\begin{pmatrix} 1-s \\ 1-t \end{pmatrix}} \mathbb{Z}G \longleftarrow 0$$

It follows [Br1, Chapter III.1] that $H_*(G, K_0(\mathcal{F})) = H_*(F \otimes_G K_0(\mathcal{F}))$ is the homology of the complex (4.1). Therefore

$$E_{p,q}^\infty = \begin{cases} \mathfrak{H}_p & \text{if } p \in \{0, 1, 2\} \text{ and } q \text{ is even,} \\ 0 & \text{otherwise.} \end{cases}$$

Convergence of the spectral sequence to $K_*(\mathcal{F} \rtimes \mathbb{Z}^2)$ (see [W, Section 5.2]) means that

$$(4.2) \quad K_1(\mathcal{F} \rtimes \mathbb{Z}^2) = \mathfrak{H}_1$$

and that there is a short exact sequence

$$(4.3) \quad 0 \longrightarrow \mathfrak{H}_0 \longrightarrow K_0(\mathcal{F} \rtimes \mathbb{Z}^2) \longrightarrow \mathfrak{H}_2 \longrightarrow 0$$

The group \mathfrak{H}_2 is free abelian. Therefore the exact sequence (4.3) splits. This proves the result ■

Remark 4.2 Writing $\mathcal{A} \otimes \mathcal{K} = \mathcal{F} \rtimes \mathbb{Z}^2 = (\mathcal{F} \rtimes \mathbb{Z}) \rtimes \mathbb{Z}$ and applying the PV-sequence of M. Pimsner and D. Voiculescu one obtains (4.3) without using the Kasparov spectral sequence. See [WO, Remarks 9.9.3] for a description of the PV-sequence and [WO, Exercise 9.K] for an outline of the proof.

$$\begin{array}{ccc}
 K_0(\mathcal{F}) & \longrightarrow & K_0(\mathcal{F} \rtimes \mathbb{Z}^2) \\
 \downarrow & & \nearrow \text{---} \\
 \mathfrak{K}_0 & &
 \end{array}$$

Figure 8

Remark 4.3 From (4.1) one notes that \mathfrak{K}_0 is none other than the \mathbb{Z}^2 -coinvariants of $K_0(\mathcal{F})$. Hence the functorial map $K_0(\mathcal{F}) \rightarrow K_0(\mathcal{F} \rtimes \mathbb{Z}^2)$ factors through \mathfrak{K}_0 (Figure 8).

It follows from the double application of the PV-sequence (Remark 4.2) that the maps $\mathfrak{K}_0 \rightarrow K_0(\mathcal{F} \rtimes \mathbb{Z}^2)$ of equation (4.3) and Figure 8 coincide. In particular, the map in Figure 8 is injective.

Remark 4.4 Double application of the PV-sequence is not sufficient to prove the formula (4.2). However if one generalizes [WO, Exercise 9.K] from \mathbb{Z} to \mathbb{Z}^2 one obtains a proof of (4.2) at a (relatively) low level of K -sophistication.

Choose for each $a \in A$, a minimal projection $P_a \in \mathcal{K}(\mathcal{H}_a)$, and let $[P_a]$ denote the corresponding class in $K_0(\mathcal{K}(\mathcal{H}_a))$. Then $K_0(\mathcal{K}(\mathcal{H}_a)) \cong \mathbb{Z}$, with generator $[P_a]$. Identify \mathbb{Z}^A with $K_0(\mathbb{C}) = \bigoplus_a K_0(\mathcal{K}(\mathcal{H}_a))$ via the map $(n_a)_{a \in A} \mapsto \sum_{a \in A} n_a [P_a]$. The endomorphism α_l induces a map $(\alpha_l)_*$ on K_0 . The following lemma is crucial for the calculations which follow.

Lemma 4.5 *The map $(\alpha_{e_j})_* : K_0(\mathbb{C}) \rightarrow K_0(\mathbb{C})$ is given by the matrix $M_j : \mathbb{Z}^A \mapsto \mathbb{Z}^A$, $j = 1, 2$.*

Proof Note that $(\alpha_{e_j})_*([P_a]) = [\alpha_{e_j}(P_a)]$. Now

$$\alpha_{e_j}(P_a) = \sum_{w \in W_{e_j}} v_w P_a v_w^* = \sum_{w \in W_{e_j}; \sigma(w)=a} v_w P_a v_w^*.$$

If $t(w) = b$ then $v_w P_a v_w^*$ is a minimal projection in $\mathcal{K}(\mathcal{H}_b)$, and so its class in $K_0(\mathcal{K}(\mathcal{H}_b))$ equals $[P_b]$. Therefore

$$(\alpha_{e_j})_*([P_a]) = \sum_{w \in W_{e_j}; \sigma(w)=a} [v_w P_a v_w^*] = \sum_{b; M_j(b,a)=1} [P_b].$$

Consequently

$$(\alpha_{e_j})_* \left(\sum_a n_a [P_a] \right) = \sum_a n_a \sum_b M_j(b, a) [P_b] = \sum_b \left(\sum_a M_j(b, a) n_a \right) [P_b].$$

This proves the result. ■

Recall that M_1 and M_2 commute. If $l = (l_1, l_2) \in \mathbb{Z}_+^2$ then we write $(M_1, M_2)^l = M_1^{l_1} M_2^{l_2}$.

Remark 4.6 The direct limit $K_0(\mathcal{F})$ may be constructed explicitly as follows. Consider the set \mathcal{S} consisting of all elements $(s_n)_{n \in \mathbb{Z}^2} \in \bigoplus_n K_0(\mathcal{C}^{(n)})$ such that there exists $l \in \mathbb{Z}^2$, for which $s_{n+e_j} = M_j s_n$ for all $n \geq l, j = 1, 2$. Say that two elements $(s_n)_{n \in \mathbb{Z}^2}, (t_n)_{n \in \mathbb{Z}^2}$ of \mathcal{S} are equivalent if there exists $l \in \mathbb{Z}^2$, for which $s_n = t_n$ for all $n \geq l$. Then $K_0(\mathcal{F}) = \varinjlim K_0(\mathcal{C}^{(n)})$ may be identified with \mathcal{S} modulo this equivalence relation. We refer to [Fu, Section 11] for more information about direct limits.

For $c \in K_0(\mathcal{C}) = \mathbb{Z}^A$ let $c^{(m)} \in K_0(\mathcal{C}^{(m)})$ be the corresponding element in $K_0(\mathcal{F})$, defined as follows.

$$c^{(m)} = (s_n)_{n \in \mathbb{Z}^2} \quad \text{where } s_n = \begin{cases} (M_1, M_2)^{(n-m)} c & \text{if } n \geq m, \\ 0 & \text{otherwise.} \end{cases}$$

In particular we identify $c^{(m)}$ with $((\alpha_l)_*(c))^{(m+l)}$ for $l \in \mathbb{Z}_+^2$.

Define $\gamma_m: K_0(\mathcal{C}) \rightarrow K_0(\mathcal{F})$ by $\gamma_m(c) = c^{(m)} \in K_0(\mathcal{F})$.

Remark 4.7 It follows immediately from the definitions that

1. $T_j^* \gamma_m = \gamma_{m-e_j}$.
2. $\gamma_m(c) = \gamma_{m+l}((M_1, M_2)^l c)$ for $l \in \mathbb{Z}_+^2$.

Lemma 4.8 *The following assertions hold.*

1. Any element in $K_0(\mathcal{F})$ can be written as $\gamma_m(c)$ for some $m \in \mathbb{Z}_+^2$ and $c \in K_0(\mathcal{C})$.
2. If $c \in K_0(\mathcal{C})$ and $m \in \mathbb{Z}^2$ then $\gamma_m(c) = 0$ if and only if $(M_1, M_2)^l c = 0$ for some $l \in \mathbb{Z}_+^2$.
3. $T_j^* \gamma_m(c) = \gamma_m(M_j c)$ for $j = 1, 2$.

Proof Statements (1) and (2) follow from the definitions. To prove (3) note that $((T_j)_* \gamma_m)(c) = (T_j)_*(c^{(m)}) = c^{(m-e_j)} = (M_j c)^{(m)} = (\gamma_m M_j)(c)$. ■

Lemma 4.9 *For $j = 1, 2$ the map induced on the following complex by M_j acts as the identity on the homology groups.*

$$(4.4) \quad 0 \longleftarrow K_0(\mathcal{C}) \xleftarrow{(I-M_2, M_1-I)} K_0(\mathcal{C}) \oplus K_0(\mathcal{C}) \xleftarrow{\begin{pmatrix} I-M_1 \\ I-M_2 \end{pmatrix}} K_0(\mathcal{C}) \longleftarrow 0$$

Proof Denote by $[\cdot]$ the equivalence classes in the relevant homology groups.

0-homology If $c \in K_0(\mathcal{C})$, then $[c] - [M_j c] = [(I - M_j)c] = 0$, the zero element in the 0-homology group.

1-homology Let $c_1, c_2 \in K_0(\mathcal{C})$ with $(I - M_2)c_1 = (I - M_1)c_2$. Then $[(c_1, c_2)] - [(M_1 c_1, M_1 c_2)] = [((I - M_1)c_1, (I - M_2)c_1)] = 0$ in the 1-homology group. Likewise for M_2 .

2-homology Let $c \in K_0(\mathcal{C})$ with $c = M_1 c = M_2 c$. Then $[c] = [M_j c]$ in the 2-homology group. ■

Lemma 4.10

$$\varinjlim (K_0(\mathcal{C}^{(m)}) \xrightarrow{M_j} K_0(\mathcal{C}^{(m+1)})) = K_0(\mathcal{F}) \xrightarrow{T_{j*}} K_0(\mathcal{F})$$

Proof The direct limit of maps makes sense because the diagram

$$\begin{array}{ccc} K_0(\mathcal{C}^{(m)}) & \xrightarrow{(M_1, M_2)^!} & K_0(\mathcal{C}^{(m+1)}) \\ M_j \uparrow & & \uparrow M_j \\ K_0(\mathcal{C}^{(m)}) & \xrightarrow{(M_1, M_2)^!} & K_0(\mathcal{C}^{(m+1)}) \end{array}$$

commutes. The diagram

$$\begin{array}{ccc} K_0(\mathcal{C}^{(m)}) & \longrightarrow & K_0(\mathcal{F}) \\ M_j \uparrow & & \uparrow T_{j*} \\ K_0(\mathcal{C}^{(m)}) & \longrightarrow & K_0(\mathcal{F}) \end{array}$$

commutes by Lemma 4.8. Since $K_0(\mathcal{F}) = \varinjlim K_0(\mathcal{C}^{(m)})$ the result follows from the uniqueness assertion in the universal property of direct limits [Fu, Theorem 11.2]. ■

By Lemma 4.10 we have

$$\begin{aligned} 0 \longleftarrow K_0(\mathcal{F}) &\xleftarrow{(1-T_{2*}, T_{1*}-1)} K_0(\mathcal{F}) \oplus K_0(\mathcal{F}) \xleftarrow{\begin{pmatrix} I-T_{1*} \\ I-T_{2*} \end{pmatrix}} K_0(\mathcal{F}) \longleftarrow 0 \\ &= \varinjlim (0 \longleftarrow K_0(\mathcal{C}^{(m)}) \longleftarrow K_0(\mathcal{C}^{(m)}) \oplus K_0(\mathcal{C}^{(m)}) \longleftarrow K_0(\mathcal{C}^{(m)}) \longleftarrow 0) \end{aligned}$$

where the map $K_0(\mathcal{C}^{(m)}) \rightarrow K_0(\mathcal{C}^{(m+1)})$ is given by $(M_1, M_2)^!$. Now homology is continuous with respect to direct limits [Sp, Theorems 5.19, 4.17]. Therefore it follows from Lemma 4.9 that

$$\begin{aligned} &\text{Hom} \left(\varinjlim (0 \longleftarrow K_0(\mathcal{C}^{(m)}) \longleftarrow K_0(\mathcal{C}^{(m)}) \oplus K_0(\mathcal{C}^{(m)}) \longleftarrow K_0(\mathcal{C}^{(m)}) \longleftarrow 0) \right) \\ &= \varinjlim \left(\text{Hom} (0 \longleftarrow K_0(\mathcal{C}^{(m)}) \longleftarrow K_0(\mathcal{C}^{(m)}) \oplus K_0(\mathcal{C}^{(m)}) \longleftarrow K_0(\mathcal{C}^{(m)}) \longleftarrow 0) \right) \\ &= \text{Hom} (0 \longleftarrow K_0(\mathcal{C}) \longleftarrow K_0(\mathcal{C}) \oplus K_0(\mathcal{C}) \longleftarrow K_0(\mathcal{C}) \longleftarrow 0) \end{aligned}$$

where Hom denotes the homology of the complex. We have proved

Lemma 4.11 *The map of complexes in Figure 9 induces isomorphisms of the homology groups.*

$$\begin{array}{ccccccc}
 0 & \longleftarrow & K_0(\mathcal{F}) & \xleftarrow{(1-T_2^*, T_1^*-2)} & K_0(\mathcal{F}) \oplus K_0(\mathcal{F}) & \xleftarrow{\begin{pmatrix} 1-T_1^* \\ 1-T_2^* \end{pmatrix}} & K_0(\mathcal{F}) & \longleftarrow & 0 \\
 & & \gamma_0 \uparrow & & \begin{pmatrix} \gamma_0 & 0 \\ 0 & \gamma_0 \end{pmatrix} \uparrow & & \gamma_0 \uparrow & & \\
 0 & \longleftarrow & K_0\mathcal{C} & \xleftarrow{(I-M_2, M_1-I)} & K_0\mathcal{C} \oplus K_0(\mathcal{C}) & \xleftarrow{\begin{pmatrix} I-M_1 \\ I-M_2 \end{pmatrix}} & K_0(\mathcal{C}) & \longleftarrow & 0
 \end{array}$$

Figure 9

Recall that \mathfrak{S}_j denotes the j -th homology group of the complex (4.1). Lemma 4.11 shows that \mathfrak{S}_j is the j -th homology group of (4.4), i.e. the j -th homology group of the complex

$$(4.5) \quad 0 \longleftarrow \mathbb{Z}^A \xleftarrow{(I-M_2, M_1-I)} \mathbb{Z}^A \oplus \mathbb{Z}^A \xleftarrow{\begin{pmatrix} I-M_1 \\ I-M_2 \end{pmatrix}} \mathbb{Z}^A \longleftarrow 0$$

Remark 4.12 In particular, \mathfrak{S}_2 is a free abelian group, and so Proposition 4.1 applies.

Let $\text{tor}(G)$ denote the torsion part of the finitely generated abelian group G , and let $\text{rank}(G)$ denote the rank of G ; that is the rank of the free abelian part of G (also sometimes called the torsion-free rank of G).

We have, by definition

1. $\mathfrak{S}_0 = \text{coker} (I-M_2, M_1-I)$,
2. $\mathfrak{S}_2 = \text{ker} \begin{pmatrix} I-M_1 \\ I-M_2 \end{pmatrix}$,
3. $\mathfrak{S}_1 = \text{ker} (I-M_2, M_1-I) / \text{im} \begin{pmatrix} I-M_1 \\ I-M_2 \end{pmatrix}$.

The next result determines the K -theory of the algebra \mathcal{A} in terms of the matrices M_1 and M_2 .

Proposition 4.13 *The following equalities hold.*

$$\begin{aligned}
 \text{rank}(K_0(\mathcal{A})) &= \text{rank}(K_1(\mathcal{A})) \\
 &= \text{rank}(\text{coker} (I-M_1, I-M_2)) + \text{rank}(\text{coker} (I-M_1^t, I-M_2^t)) \\
 \text{tor}(K_0(\mathcal{A})) &\cong \text{tor}(\text{coker} (I-M_1, I-M_2)) \\
 \text{tor}(K_1(\mathcal{A})) &\cong \text{tor}(\text{coker} (I-M_1^t, I-M_2^t)).
 \end{aligned}$$

In particular $K_0(\mathcal{A})$ and $K_1(\mathcal{A})$ have the same torsion free parts.

Proof We have $\text{rank ker} \begin{pmatrix} I-M_1 \\ I-M_2 \end{pmatrix} = \text{rank coker} (I-M_1^t, I-M_2^t)$. Hence, by Proposition 4.1 (and Remark 4.12),

$$\begin{aligned}
 \text{rank}(K_0(\mathcal{A})) &= \text{rank}(\mathfrak{S}_0) + \text{rank}(\mathfrak{S}_2) \\
 &= \text{rank}(\text{coker} (I-M_1, I-M_2)) + \text{rank}(\text{coker} (I-M_1^t, I-M_2^t)).
 \end{aligned}$$

Also

$$\begin{aligned} \text{rank}(K_1(\mathcal{A})) &= \text{rank}(\mathfrak{H}_1) \\ &= \text{rank}(\ker(I-M_2, M_1-I)) - \text{rank}(\text{im} \begin{pmatrix} I-M_1 \\ I-M_2 \end{pmatrix}) \\ &= 2n - \text{rank}(\text{im} \begin{pmatrix} I-M_1, I-M_2 \end{pmatrix}) - \text{rank}(\text{im} \begin{pmatrix} I-M_1' \\ I-M_2' \end{pmatrix}) \\ &= \text{rank}(\text{coker} \begin{pmatrix} I-M_1, I-M_2 \end{pmatrix}) + \text{rank}(\text{coker} \begin{pmatrix} I-M_1' \\ I-M_2' \end{pmatrix}). \end{aligned}$$

Since $\text{tor}(\mathfrak{H}_0) = \text{tor}(\text{coker} \begin{pmatrix} I-M_1, I-M_2 \end{pmatrix})$ and $\text{tor}(\mathfrak{H}_2) = 0$, it follows that

$$\text{tor}(K_0(\mathcal{A})) = \text{tor}(\text{coker} \begin{pmatrix} I-M_1, I-M_2 \end{pmatrix}).$$

Finally

$$\text{tor}(K_1(\mathcal{A})) = \text{tor}(\mathfrak{H}_1) = \text{tor}(\text{coker} \begin{pmatrix} I-M_1 \\ I-M_2 \end{pmatrix}) = \text{tor}(\text{coker} \begin{pmatrix} I-M_1' \\ I-M_2' \end{pmatrix})$$

where the last equality follows from the Smith normal form for integer matrices. ■

5 K-Theory for Boundary Algebras Associated With \tilde{A}_2 Buildings

Return now to the setup of Section 2. That is, let \mathcal{B} be a locally finite affine building of type \tilde{A}_2 . Let Γ be a group of type rotating automorphisms of \mathcal{B} that acts freely on the vertex set with finitely many orbits. Let A denote the associated finite alphabet and let M_1, M_2 be the transition matrices with entries indexed by elements of A .

It was shown in [RS2] that the conditions (H0), (H1a), (H1b) and (H3) of Section 3 are satisfied by the matrices M_1, M_2 . It was also proved in [RS2] that condition (H2) is satisfied if Γ is a lattice subgroup of $\text{PGL}_3(\mathbb{F})$, where \mathbb{F} is a local field of characteristic zero. The proof uses the Howe-Moore Ergodicity Theorem. In forthcoming work of T. Steger it is shown how to extend the methods of the proof of the Howe-Moore Theorem and so prove condition (H2) in the stated generality.

It follows from [RS2, Theorem 7.7] that the algebra $\mathcal{A}(\Gamma)$ is stably isomorphic to the algebra \mathcal{A} . Moreover if the group Γ also acts transitively on the vertices of \mathcal{B} (which is the case in the examples of Section 7) then $\mathcal{A}(\Gamma)$ is isomorphic to \mathcal{A} .

Lemma 5.1 *If M_1, M_2 are associated with an \tilde{A}_2 building as in Section 2, then there is a permutation matrix $S: \mathbb{Z}^A \rightarrow \mathbb{Z}^A$ such that $S^2 = I$ and $SM_1S = M_2', SM_2S = M_1'$. In particular $\text{coker} \begin{pmatrix} I-M_1, I-M_2 \end{pmatrix} = \text{coker} \begin{pmatrix} I-M_1' \\ I-M_2' \end{pmatrix}$*

Proof Define $s: \mathfrak{t} \rightarrow \mathfrak{t}$ by $s(i)(j, k) = i(1-k, 1-j)$ for $i \in \mathfrak{T}$ and $0 \leq j, k \leq 1$. Then s is the type preserving isometry of \mathfrak{t} given by reflection in the edge $[(0, 1), (1, 0)]$. (See Figure 9.) Now define a permutation $s: A \rightarrow A$ by $s(\Gamma i) = \Gamma s(i)$. If $a = \Gamma i_a, b = \Gamma i_b \in A$ then it is clear that $M_1(b, a) = 1 \Leftrightarrow M_2(s(a), s(b)) = 1$. The situation is illustrated, not too cryptically we hope, in Figure 10, where the tiles are located in the building \mathcal{B} and, for example, the tile labeled a is the range of a suitable isometry $i_a: \mathfrak{t} \rightarrow \mathcal{B}$ with $a = \Gamma i_a$. Let S be the permutation matrix corresponding to s . Then

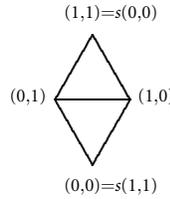


Figure 10: The reflection s of a tile t



Figure 11: Reversing transitions between tiles

$M_1(b, a) = 1 \Leftrightarrow SM_2S^{-1}(a, b) = 1$. Clearly $S^2 = I$. Therefore $M_1^t = SM_2S$. A similar argument proves the other equality. ■

The proof of Theorem 2.1 now follows immediately from Proposition 4.13 and Lemma 5.1. The next result identifies which of the algebras $\mathcal{A}(\Gamma)$ are rank one algebras.

Corollary 5.2 *Continue with the hypotheses of Theorem 2.1. The following are equivalent.*

1. *The algebra $\mathcal{A}(\Gamma)$ is isomorphic to a rank one Cuntz-Krieger algebra;*
2. *the algebra $\mathcal{A}(\Gamma)$ is stably isomorphic to a rank one Cuntz-Krieger algebra;*
3. *the group $K_0(\mathcal{A}(\Gamma))$ is torsion free.*

Proof The K -theory of a rank one Cuntz Krieger algebra \mathcal{O}_A can be characterized as follows (see [C1]):

$$K_0(\mathcal{O}_A) = (\text{finite group}) \oplus \mathbb{Z}^k ; K_1(\mathcal{O}_A) = \mathbb{Z}^k.$$

By Theorem 2.1, we have $K_0 = K_1$ for the algebra $\mathcal{A}(\Gamma)$. Since stably isomorphic algebras have the same K -theory, it follows that if $\mathcal{A}(\Gamma)$ is stably isomorphic to a rank one Cuntz-Krieger algebra then $K_0(\mathcal{A}(\Gamma))$ is torsion free.

On the other hand, suppose that $G_0 = K_0(\mathcal{A}(\Gamma))$ is torsion free. Let $g_0 = [1] \in G_0$ be the class in K_0 of the identity element of $\mathcal{A}(\Gamma)$. By a result of M. Rordam [Ror, Proposition 6.6], there exists a simple rank one Cuntz-Krieger algebra \mathcal{O}_A such that

$K_0(\mathcal{O}_A) = G_0$ with the class of the identity in \mathcal{O}_A being g_0 . Since G_0 is torsion free we necessarily have $K_1(\mathcal{O}_A) = G_0$ and by Theorem 2.1 we also have $K_1(\mathcal{A}(\Gamma)) = G_0$. Thus $K_*(\mathcal{A}(\Gamma)) = K_*(\mathcal{O}_A)$ and the identity elements of the two algebras have the same image in K_0 . Since the algebras $\mathcal{A}(\Gamma)$ and \mathcal{O}_A are purely infinite, simple, nuclear and satisfy the Universal Coefficient Theorem, it now follows from the Classification Theorem of [Kir, Ph] that they are isomorphic. ■

Remark 5.3 Corollary 5.2 can be used (see Remark 8.4) to verify that almost all the examples of rank 2 Cuntz-Krieger algebras described later are not stably isomorphic to ordinary (rank 1) Cuntz-Krieger algebras.

6 Reduction of Order

Continue with the assumptions of Section 5. The following lemma will simplify the calculation of the K -groups, by reducing the order of the matrices involved.

Lemma 6.1 Suppose that M_1, M_2 are $\{0, 1\}$ -matrices acting on \mathbb{Z}^A .

- (i) Let \hat{A} be a set and let $\hat{\pi}: A \rightarrow \hat{A}$ be a surjection. Suppose that $M_j(b, a) = M_j(b, a')$ if $\hat{\pi}(a) = \hat{\pi}(a')$. Let the matrix \hat{M}_j acting on $\mathbb{Z}^{\hat{A}}$ be given by $\hat{M}_j(\hat{b}, \hat{a}) = \sum_{\hat{\pi}(b)=\hat{b}} M_j(b, a)$. Then the canonical map from \mathbb{Z}^A onto $\mathbb{Z}^{\hat{A}}$ which sends generators to generators induces an isomorphism from $\text{coker}(I - M_1, I - M_2)$ onto $\text{coker}(I - \hat{M}_1, I - \hat{M}_2)$.
- (ii) Let \check{A} be a set and let $\check{\pi}: A \rightarrow \check{A}$ be a surjection. Suppose that $M_j(b, a) = M_j(b', a)$ if $\check{\pi}(b) = \check{\pi}(b')$. Let the matrix \check{M}_j acting on $\mathbb{Z}^{\check{A}}$ be given by $\check{M}_j(\check{b}, \check{a}) = \sum_{\check{\pi}(a)=\check{a}} M_j(b, a)$. Then the canonical map from \mathbb{Z}^A onto $\mathbb{Z}^{\check{A}}$ which sends generators to generators induces an isomorphism from $\text{coker}(I - M_1, I - M_2)$ onto $\text{coker}(I - \check{M}_1, I - \check{M}_2)$.

Proof (i) Let $(e_a)_{a \in A}$ be the standard set of generators for the free abelian group \mathbb{Z}^A and $(e_{\hat{a}})_{\hat{a} \in \hat{A}}$ that of $\mathbb{Z}^{\hat{A}}$. Define the map $\pi: \mathbb{Z}^A \rightarrow \mathbb{Z}^{\hat{A}}$ by $\pi(e_a) = e_{\hat{\pi}(a)}$. Observe that the diagram

$$\begin{array}{ccc} \mathbb{Z}^A & \xrightarrow{M_j} & \mathbb{Z}^A \\ \pi \downarrow & & \downarrow \pi \\ \mathbb{Z}^{\hat{A}} & \xrightarrow{\hat{M}_j} & \mathbb{Z}^{\hat{A}} \end{array}$$

commutes. Therefore so does the diagram

$$\begin{array}{ccc} \mathbb{Z}^A \oplus \mathbb{Z}^A & \xrightarrow{(I - M_1, I - M_2)} & \mathbb{Z}^A \\ \pi \oplus \pi \downarrow & & \downarrow \pi \\ \mathbb{Z}^{\hat{A}} \oplus \mathbb{Z}^{\hat{A}} & \xrightarrow{(I - \hat{M}_1, I - \hat{M}_2)} & \mathbb{Z}^{\hat{A}} \end{array}$$

Hence there is a well defined map of cokernels, which is surjective because π is. The kernel of π is generated by $\{e_a - e_{a'} ; \hat{\pi}(a) = \hat{\pi}(a')\}$. Now if $\hat{\pi}(a) = \hat{\pi}(a')$ then according to the hypothesis of the lemma, $M_j e_a = M_j e_{a'}$ and so $(I - M_j)(e_a - e_{a'}) = e_a - e_{a'}$. Hence the kernel of π is contained in the image of the map $(I - M_1, I - M_2)$. It follows by diagram chasing that the map on cokernels is injective.

(ii) The argument in this case is a little harder but similar. Note that the vertical maps in the diagrams go up rather than down. ■

We now explain how Lemma 6.1 is used in our calculations to reduce calculations based on rhomboid tiles to calculations based on triangles. Let \hat{t} be the model triangle with vertices $\{(1, 1), (0, 1), (1, 0)\}$, which is the upper half of the model tile t . Let $\hat{\mathcal{T}}$ denote the set of type rotating isometries $i: \hat{t} \rightarrow \mathcal{B}$, and let $\hat{A} = \Gamma \setminus \hat{\mathcal{T}}$. We think of \hat{A} as labels for triangles in \mathcal{B} , just as A is thought of as labels for parallelograms. Each type rotating isometry $i: \hat{t} \rightarrow \mathcal{B}$ restricts to a type rotating isometry $\hat{i} = i|_{\hat{t}}: \hat{t} \rightarrow \mathcal{B}$. Define $\hat{\pi}: A \rightarrow \hat{A}$ by $\hat{\pi}(a) = \Gamma \hat{i}_a$ where $a = \Gamma i_a$. It is clear that $M_j(b, a) = M_j(b, a')$

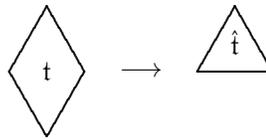


Figure 12: The restriction $t \rightarrow \hat{t}$

if $\hat{\pi}(a) = \hat{\pi}(a')$. This is illustrated in Figure 13 for the case $M_1(b, a) = 1$. Thus the hypotheses of Lemma 6.1(i) are satisfied.

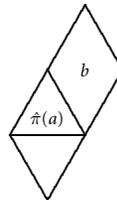


Figure 13: $M_1(b, a) = 1$

Each matrix \hat{M}_j has entries in $\{0, 1\}$. For example Figure 13 illustrates the configuration for $\hat{M}_1(\hat{b}, \hat{a}) = 1$.

Note that although the matrices \hat{M}_1 and \hat{M}_2 are used to simplify the final computation, they could not be used to define the algebra \mathcal{A} because their product $\hat{M}_1 \hat{M}_2$ need not have entries in $\{0, 1\}$. In fact in the gallery of Figure 14 the triangle labels \hat{a} and \hat{c} do not uniquely determine the triangle label \hat{b} . In other words there is more than one such two step transition from \hat{a} to \hat{c} .

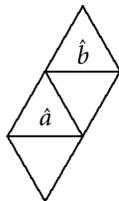


Figure 14: $\hat{M}_1(\hat{b}, \hat{a}) = 1$

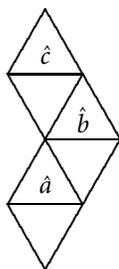


Figure 15: Non uniqueness of two-step transition

Similar arguments apply to the set \check{A} obtained by considering the model triangle \check{t} with vertices $\{(0, 0), (0, 1), (1, 0)\}$, which is the lower half of the model tile t (Figure 15).

The map $\tilde{\pi}: A \rightarrow \check{A}$ is induced by the restriction of Figure 15 and one applies Lemma 6.1(ii) to the resulting matrices \check{M}_1, \check{M}_2 . Figure 16 illustrates the configuration for $\check{M}_1(\check{b}, \check{a}) = 1$.

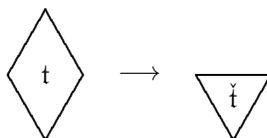


Figure 16: The restriction $t \rightarrow \check{t}$

The same argument as in Lemma 5.1 shows that there is an isomorphism $V: \mathbb{Z}^{\check{A}} \rightarrow \mathbb{Z}^A$ such that $\check{M}_1 = V^{-1}M_1V$ and vice versa.

We may summarize the preceding discussion as follows.

Corollary 6.2 *Assume the notation and hypotheses of Theorem 2.1. Let \hat{M}_j, \check{M}_j ($j =$*

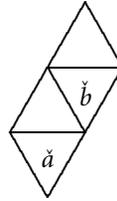


Figure 17: $\check{M}_1(\check{b}, \check{a}) = 1$

1, 2) be the matrices defined as above. Then

$$\begin{aligned} K_0(\mathcal{A}_D) &= K_1(\mathcal{A}_D) = \mathbb{Z}^{2r} \oplus \text{tor}(\text{coker}(I - \check{M}_1, I - \check{M}_2)) \\ &= \mathbb{Z}^{2r} \oplus \text{tor}(\text{coker}(I - \check{M}_1, I - \check{M}_2)) \end{aligned}$$

where $r = \text{rank}(\text{coker}(I - \check{M}_1, I - \check{M}_2)) = \text{rank}(\text{coker}(I - \check{M}_1, I - \check{M}_2))$.

7 K-Theory for the Boundary Algebra of an \check{A}_2 Group

Now suppose that Γ is an \check{A}_2 group. This means that Γ is a group of automorphisms of the \check{A}_2 building \mathcal{B} which acts freely and transitively in a type rotating manner on the vertex set of \mathcal{B} . If Ω is the boundary of \mathcal{B} then the algebra $\mathcal{A} = \mathcal{A}(\Gamma)$ was studied in [RS1], [RS2, Section 7]. Suppose that the building \mathcal{B} has order q . If $q = 2$ there are eight \check{A}_2 groups Γ , all of which embed as lattices in a linear group $\text{PGL}(3, \mathbb{F})$ over a local field \mathbb{F} . If $q = 3$ there are 89 possible \check{A}_2 groups, of which 65 do not embed naturally in linear groups.

The 1-skeleton of \mathcal{B} is the Cayley graph of the group Γ with respect to its canonical set P of $(q^2 + q + 1)$ generators. The set P is identified with the set of points of a finite projective plane (P, L) and the set of lines L is identified with $\{x^{-1} ; x \in P\}$. The relations satisfied by the elements of P are of the form $xyz = 1$. There is such a relation if and only if $y \in x^{-1}$, that is the point y is incident with the line x^{-1} in the projective plane (P, L) . See [CMSZ] for details.

Since Γ acts freely and transitively on the vertices of \mathcal{B} , each element $a \in A$ has a unique representative isometry $i_a: \mathfrak{t} \rightarrow \mathcal{B}$ such that $i_a(0, 0) = O$, the fixed base vertex of \mathcal{B} . We assume for definiteness that the vertex O has type 0. It then follows that the vertex $i_a(1, 0)$ has type 1, $i_a(0, 1)$ has type 2 and $i_a(1, 1)$ has type 0. The combinatorics of the finite projective plane (P, L) shows that there are precisely $q(q + 1)(q^2 + q + 1)$ possible choices for i_a . That is $\#(A) = q(q + 1)(q^2 + q + 1)$. Thinking of the 1-skeleton of \mathcal{B} as the Cayley graph of the group Γ with $O = e$, we shall identify elements of Γ with vertices of \mathcal{B} via $\gamma \mapsto \gamma(O)$.

We now examine the transition matrices M_1, M_2 in this situation. If $a, b \in A$, we have $M_1(b, a) = 1$ if and only if there are representative isometries in a and b respectively whose ranges are tiles which lie as shown in Figure 17. More precisely this means that the ranges $i_a(\mathfrak{t})$ and $i_a(1, 0)b(\mathfrak{t})$ lie in the building as shown in Figure 17, where they are labeled a and b respectively.

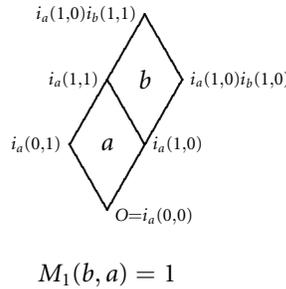


Figure 18: Transitions between tiles

Lemma 7.1 The $\{0, 1\}$ -matrices M_j ($j = 1, 2$) have order $\#(A) = q(q+1)(q^2+q+1)$ and each row or column has precisely q^2 nonzero entries.

Proof Suppose that $a \in A$ has been chosen. Refer to Figure 17. In the link of the vertex $i_a(1, 1)$, let the vertices of type 1 correspond to points in P and the vertices of type 2 correspond to lines in L . There are then $q + 1$ choices for a line incident with the point $i_a(0, 1)$; therefore there are q choices for $i_a(1, 0)i_b(1, 0)$. After choosing $i_a(1, 0)i_b(1, 0)$ there are q choices for the point $i_a(1, 0)i_b(1, 1)$. That choice determines b . There are therefore q^2 choices for b . This proves that for each $a \in A$, there are q^2 choices for $b \in A$ such that $M_1(b, a) = 1$. That is, each column of the matrix M_1 has precisely q^2 nonzero entries. A similar argument applies to rows. ■

In order to compute the K -theory of $\mathcal{A} = \mathcal{A}(\Gamma)$, it follows from Section 6 that we need only compute $\text{coker}(I - \hat{M}_1, I - \hat{M}_2)$ or equivalently $\text{coker}(I - \hat{M}_1, I - \hat{M}_2)$. For definiteness we deal in detail with the former. We shall see that this reduces the order of the matrices by a factor of q . Since Γ acts freely and transitively on the vertices of \mathcal{B} , each class $\hat{a} \in \hat{A}$ contains a unique representative isometry $\hat{i}_a: \mathfrak{t} \rightarrow \mathcal{B}$ such that $\hat{i}_a(1, 1) = O$, the fixed base vertex of \mathcal{B} . The isometry \hat{i}_a is completely determined by its range which is a triangle in \mathcal{B} whose edges are labeled by generators in P , according to the structure of the 1-skeleton of \mathcal{B} as a Cayley graph. In this way the element $\hat{a} \in \hat{A}$ may be identified with an ordered triple (a_0, a_1, a_2) , where $a_0, a_1, a_2 \in P$ and $a_0 a_1 a_2 = 1$. See Figure 18.

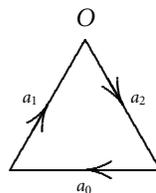


Figure 19: Representation of \hat{a}

Note that in this representation of \hat{a} there are $(q^2 + q + 1)$ choices for a_0 . Having chosen a_0 , there are $q + 1$ choices for a_1 , since a_1 is incident with a_0^{-1} . The element a_2 is then uniquely determined. This shows that $\#(\hat{A}) = (q + 1)(q^2 + q + 1)$.

Given $\hat{a} \in \hat{A}$, an element $\hat{b} \in \hat{A}$ satisfies $\hat{M}_1(\hat{b}, \hat{a}) = 1$ if and only if the 1-skeleton of \mathcal{B} contains a diagram of the form shown in Figure 19. In terms of the projective plane (P, L) , this diagram is possible if and only if $b_1 \notin a_1^{-1}$ (q^2 choices for b_1). Then b_0 is uniquely specified by $b_0^{-1} = b_1 \vee a_2$, the line containing the points b_1 and a_2 . This determines b_2 and hence \hat{b} . Thus \hat{M}_1 is a $\{0, 1\}$ -matrix of order $(q+1)(q^2+q+1)$, whose entries are specified by

$$(7.1) \quad \hat{M}_1(\hat{b}, \hat{a}) = 1 \Leftrightarrow b_1 \notin a_1^{-1}, \quad b_0^{-1} = b_1 \vee a_2.$$

In particular for a fixed $\hat{a} \in \hat{A}$ we have $\hat{M}_1(\hat{b}, \hat{a}) = 1$ for precisely q^2 choices of $\hat{b} \in \hat{A}$. That is, each column of the matrix \hat{M}_1 has precisely q^2 nonzero entries. Analogously, for a fixed $\hat{b} \in \hat{A}$ we have $\hat{M}_1(\hat{b}, \hat{a}) = 1$ for precisely q^2 choices of $\hat{a} \in \hat{A}$. Again refer to Figure 19. There are precisely q^2 choices of the line a_1^{-1} such that $b_1 \notin a_1^{-1}$. Then a_2 is specified by $a_2 = a_1^{-1} \wedge b_0^{-1}$ and this determines \hat{a} completely.

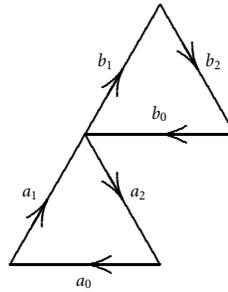


Figure 20: $\hat{M}_1(\hat{b}, \hat{a}) = 1$

A similar argument shows that the $\{0, 1\}$ -matrix \hat{M}_2 is specified by

$$(7.2) \quad \hat{M}_2(\hat{b}, \hat{a}) = 1 \Leftrightarrow a_2 \notin b_2^{-1}, \quad b_0 = a_1^{-1} \wedge b_2^{-1}.$$

Using the preceding discussion and the explicit triangle presentations for \tilde{A}_2 groups given in [CMSZ], we may now proceed to compute the K -theory of the algebra \mathcal{A} by means of Corollary 6.2, with “upward pointing” triangles. The authors have done extensive computations for more than 100 different groups with $2 \leq q \leq 11$, including all possible \tilde{A}_2 groups for $q = 2, 3$. The complete results are available at <http://maths.newcastle.edu.au/~guyan/Kcomp.ps.gz> or from either of the authors.

Everything above applies mutatis mutandis for “downward pointing” triangles. In an obvious notation, illustrated in Figure 20, we have

$$(7.3) \quad \check{M}_1(\check{b}, \check{a}) = 1 \Leftrightarrow b_2 \notin a_2^{-1}, \quad a_0 = b_1^{-1} \wedge a_2^{-1}.$$

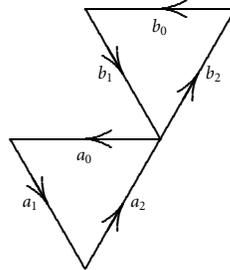


Figure 21: $\check{M}_1(\check{b}, \check{a}) = 1$

The accuracy of our computations was confirmed by repeating them with “downward pointing” triangles.

It is convenient to summarize the general structure of the matrices we are considering.

Lemma 7.2 *The $\{0, 1\}$ -matrices \check{M}_j , \check{M}'_j ($j = 1, 2$) have order $\#(\hat{A}) = (q + 1)(q^2 + q + 1)$ and each row or column has precisely q^2 nonzero entries.*

Example 7.3 Consider the following two \check{A}_2 groups, which are both torsion free lattices in $\text{PGL}(3, \mathbb{Q}_2)$, where \mathbb{Q}_2 is the field of 2-adic numbers [CMSZ].

The group B.2 of [CMSZ], which we shall denote $\Gamma_{B.2}$ has presentation

$$\langle x_i, 0 \leq i \leq 6 \mid x_0x_1x_4, x_0x_2x_1, x_0x_4x_2, x_1x_5x_5, x_2x_3x_3, x_3x_5x_6, x_4x_6x_6 \rangle.$$

The group C.1 of [CMSZ], which we shall denote $\Gamma_{C.1}$ has presentation

$$\langle x_i, 0 \leq i \leq 6 \mid x_0x_0x_6, x_0x_2x_3, x_1x_2x_6, x_1x_3x_5, x_1x_5x_4, x_2x_4x_5, x_3x_4x_6 \rangle.$$

These groups are not isomorphic. Indeed the MAGMA computer algebra package shows that $\Gamma_{B.2}$ has a subgroup of index 5, whereas $\Gamma_{C.1}$ does not. This non isomorphism is revealed by the K -theory of the boundary algebras. Performing the computations above shows that

$$K_0(\mathcal{A}(\Gamma_{B.2})) = K_1(\mathcal{A}(\Gamma_{B.2})) = (\mathbb{Z}/2\mathbb{Z})^2 \oplus \mathbb{Z}/3\mathbb{Z},$$

$$K_0(\mathcal{A}(\Gamma_{C.1})) = K_1(\mathcal{A}(\Gamma_{C.1})) = (\mathbb{Z}/2\mathbb{Z})^4 \oplus \mathbb{Z}/3\mathbb{Z}.$$

These examples are not typical in that K_* of a boundary algebra usually has a free abelian component. Note also that in both these cases $[1] = 0$ in $K_0(\mathcal{A}(\Gamma))$. See Remark 8.4.

On the other hand, using the results of V. Lafforgue [La], the K -theory of the reduced group C^* -algebras of these groups can easily be computed. The result is the same for these two groups:

$$K_0(C_r^*(\Gamma_{B.2})) = K_0(C_r^*(\Gamma_{C.1})) = \mathbb{Z},$$

$$K_1(C_r^*(\Gamma_{B.2})) = K_1(C_r^*(\Gamma_{C.1})) = (\mathbb{Z}/2\mathbb{Z})^2 \oplus \mathbb{Z}/3\mathbb{Z}.$$

8 The Class of the Identity in K -Theory

Continue with the assumptions of Section 7; that is Γ is an \bar{A}_2 group. Since the algebras $\mathcal{A}(\Gamma)$ are purely infinite, simple, nuclear and satisfy the Universal Coefficient Theorem [RS2, Remark 6.5], it follows from the Classification Theorem of [Kir, Ph] that they are classified by their K -groups together with the class $[\mathbf{1}]$ in K_0 of the identity element $\mathbf{1}$ of $\mathcal{A}(\Gamma)$. It is therefore important to identify this class. We prove that $[\mathbf{1}]$ is a torsion element of K_0 .

Let $i \in \mathfrak{T}$, that is, suppose that $i: \mathfrak{t} \rightarrow \mathcal{B}$ is a type rotating isometry. Let $\Omega(i)$ be the subset of Ω consisting of those boundary points represented by sectors which originate at $i(0, 0)$ and contain $i(\mathfrak{t})$. Clearly $\Omega(\gamma i) = \gamma\Omega(i)$ for $\gamma \in \Gamma$. For each $i \in \mathfrak{t}$ let $\mathbf{1}_i$ be the characteristic function of the set $\Omega(i)$.

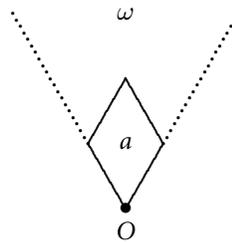


Figure 22: $\mathbf{1}_a(\omega) = 1$

Lemma 8.1 *If $i_1, i_2 \in \mathfrak{T}$ with $\Gamma i_1 = \Gamma i_2$ then $[\mathbf{1}_{i_1}] = [\mathbf{1}_{i_2}]$.*

Proof If $i_1 = \gamma i_2$ with $\gamma \in \Gamma$ then the covariance condition for the action of Γ on $C(\Omega)$ implies that $\mathbf{1}_{i_1} = \gamma \mathbf{1}_{i_2} \gamma^{-1}$. The result now follows because equivalent idempotents belong to the same class in K_0 . ■

For each $a \in A$ let $\mathbf{1}_a = \mathbf{1}_{i_a}$. See Figure 21. It follows from the discussion in [CMS, Section 2] that the identity function in $C(\Omega)$ may be expressed as $\mathbf{1} = \sum_{a \in A} \mathbf{1}_a$.

Proposition 8.2 *In the group $K_0(\mathcal{A}(\Gamma))$ we have $(q^2 - 1)[\mathbf{1}] = 0$.*

Proof Referring to Figure 17, we have for each $a \in A$, $\mathbf{1}_a = \sum \mathbf{1}_{i_a(1,0)i_b}$, where the sum is over all $b \in A$ such that $i_b(\mathfrak{t})$ lies as shown in Figure 17; that is the sum is over all $b \in A$ such that $M_1(b, a) = 1$. Now by Lemma 8.1, $[\mathbf{1}_{i_a(1,0)i_b}] = [\mathbf{1}_{i_b}] = [\mathbf{1}_b]$ and so

$$[\mathbf{1}_a] = \sum_{b \in A} M_1(b, a)[\mathbf{1}_b].$$

It follows that

$$[\mathbf{1}] = \sum_{a \in A} [\mathbf{1}_a] = \sum_{a \in A} \sum_{b \in A} M_1(b, a)[\mathbf{1}_b].$$

By Lemma 7.1, there are $q^3(q + 1)(q^2 + q + 1)$ nonzero terms in this double sum and each term $[1_b]$ occurs exactly q^2 times. Thus $[1] = q^2 \sum_{a \in A} [1_a] = q^2 [1]$, which proves the result. ■

Proposition 8.3 For $q \not\equiv 1 \pmod{3}$, $q - 1$ divides the order of $[1]$. For $q \equiv 1 \pmod{3}$, $(q - 1)/3$ divides the order of $[1]$.

Proof By [RS2, Theorem 7.7], the algebra $\mathcal{A}(\Gamma)$ is isomorphic to the algebra \mathcal{A} , which is in turn stably isomorphic to the algebra $\mathcal{F} \rtimes \mathbb{Z}^2$ [RS2, Theorem 6.2]. We refer to Section 1 for notation and terminology. Recall that $\mathcal{F} = \varinjlim \mathcal{C}^{(m)}$ where $\mathcal{C}^{(m)} \cong \bigoplus_{a \in A} \mathcal{K}(\mathcal{H}_a)$. The isomorphism $\mathcal{A}(\Gamma) \rightarrow \mathcal{A}$ has the effect $\mathbf{1}_a \mapsto s_{a,a}$ and the isomorphism $\mathcal{A} \otimes \mathcal{K} \rightarrow \mathcal{F} \rtimes \mathbb{Z}^2$ sends $s_{a,a} \otimes E_{1,1}$ to a minimal projection $P_a \in \mathcal{K}(\mathcal{H}_a) \subset \mathcal{C}^{(0)} \subset \mathcal{F}$.

As an abelian group in terms of generators and relations, we have

$$(8.1) \quad \text{coker} (I^{-M_1}, I^{-M_2}) = \left\langle e_a ; e_a = \sum_b M_j(b, a)e_b, j = 1, 2 \right\rangle.$$

By Lemma 4.11 $\text{coker} (I^{-M_1}, I^{-M_2})$ is isomorphic to $\mathfrak{H}_0 = \text{coker}(1 - T_{2*}, T_{1*} - 1)$. Under this identification, $\sum_{a \in A} e_a$ maps to the coset of $[1] \in K_0(\mathcal{F})$. By Remark 4.3 that coset maps to $[1] \in K_0(\mathcal{F} \rtimes \mathbb{Z}^2)$ under the injection of (4.3). Thus the order of $[1] \in K_0(\mathcal{F} \rtimes \mathbb{Z}^2)$ is equal to the order of $\sum_{a \in A} e_a$ in $\text{coker} (I^{-M_1}, I^{-M_2})$.

Each of the relations in the equation (8.1) expresses a generator e_a as the sum of exactly q^2 generators. It follows that there exists a homomorphism ψ from $\text{coker} (I^{-M_1}, I^{-M_2})$ to $\mathbb{Z}/(q^2 - 1)$ which sends each generator to $1 + (q^2 - 1)\mathbb{Z}$. As $\sum_{a \in A} e_a$ has $q(q + 1)(q^2 + q + 1)$ terms,

$$\psi \left(\sum_{a \in A} e_a \right) \equiv q(q + 1)(q^2 + q + 1) \equiv 3(q + 1) \pmod{q^2 - 1}$$

Consequently, the order of $\psi(\sum_{a \in A} e_a)$ is

$$\begin{aligned} \frac{q^2 - 1}{(q^2 - 1, 3(q + 1))} &= \frac{q^2 - 1}{(q + 1)(q - 1, 3)} = \frac{q - 1}{(q - 1, 3)} \\ &= \begin{cases} q - 1 & \text{if } q \not\equiv 1 \pmod{3}, \\ (q - 1)/3 & \text{if } q \equiv 1 \pmod{3}. \end{cases} \end{aligned}$$

The result follows since the order of $\sum_{a \in A} e_a$ is necessarily a multiple of the order of $\psi(\sum_{a \in A} e_a)$. ■

Remark 8.4 Propositions 8.2 and 8.3 give upper and lower bounds for the order of $[1]$ in K_0 . The authors have computed the K -groups for the boundary algebras associated with more than one hundred different \tilde{A}_2 groups, for $2 \leq q \leq 11$. These numerical results strongly suggest that if $q \not\equiv 1 \pmod{3}$ [respectively $q \equiv 1 \pmod{3}$] then the order of $[1]$ is precisely $q - 1$ [respectively $(q - 1)/3$]. Our computational

results are complete in two cases: if $q = 2$ the $[1] = 0$ and if $q = 3$ then $[1]$ has order 2.

Propositions 8.2 and 8.3 show that if $q \neq 2, 4$ then $[1]$ is a nonzero torsion element in $K_0(\mathcal{A}(\Gamma))$. It follows from Corollary 5.2 that for $q \neq 2, 4$ the corresponding algebras are not isomorphic to any rank one Cuntz-Krieger algebra. The only group Γ among the eight groups for $q = 2$, for which $K_0(\mathcal{A}(\Gamma))$ is torsion free is the group B.3. We do not know if such a group exists for $q = 4$.

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