# LINEAR ISOMETRIES OF SPACES OF ABSOLUTELY CONTINUOUS FUNGTIONS 

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1. Let $X$ be an arbitrary compact subset of the real line $\mathbf{R}$ which has at least two points. For each finite complex valued function $f$ on $X$ we denote by $V(f ; X)$ (and call it the weak variation of $f$ on $X$ ) the least upper bound of the numbers $\sum_{i}\left|f\left(b_{i}\right)-f\left(a_{i}\right)\right|$ where $\left\{\left[a_{i}, b_{i}\right]\right\}$ is any sequence of non-overlapping intervals whose end points belong to $X$. A function $f$ is said to be of bounded variation (BV) on $X$ if $V(f ; X)<\infty$. A function $f$ is said to be absolutely continuous (AC) on $X$, if given any $\epsilon>0$ there exists an $\eta>0$ such that for every sequence of non-overlapping intervals $\left\{\left[a_{i}, b_{i}\right]\right\}$ whose end points belong to $X$, the inequality

$$
\sum_{i}\left(b_{i}-a_{i}\right)<\eta
$$

implies that

$$
\sum_{i}\left|f\left(b_{i}\right)-f\left(a_{i}\right)\right|<\epsilon
$$

([7], p. 221, 223).
We denote by $\mathrm{AC}(X)$ the linear space of all absolutely continuous complex valued functions on $X$ and define a norm on it by

$$
\begin{equation*}
\|f\|=\|f\|_{\infty}+V(f ; X), \quad f \in \mathrm{AC}(X) \tag{1}
\end{equation*}
$$

where $\|f\|_{\infty}$ is the usual uniform norm.
Now let $a$ and $b$ be the greatest lower bound and the least upper bound of $X$, respectively. Since $X$ is compact, $a$ and $b$ belong to $X$ and hence $[a, b] \backslash X$ is an open subset of the real line $\mathbf{R}$. Clearly then $[a, b] \backslash X$ is the union of a countable number of disjoint open intervals. In order to show that $\mathrm{AC}(X)$ is a Banach space we first prove the following lemma.

Lemma 1.1. Let $f \in \mathrm{AC}(X)$. Then there is a unique function $F$ on $[a, b]$ such that
(i) $\left.F\right|_{X} \equiv f$
(ii) $F$ is linear on the closure of each component of $[a, b] \backslash X$. We have $F \in \mathrm{AC}[a, b]$ and
(iii) $V(f ; X)=V(F ;[a, b])$.

Proof. The existence and uniqueness of a continuous function $F$ on $[a, b]$ with properties (i) and (ii) is obvious. It is easy to see that (iii) holds.

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To show that $F \in \mathrm{AC}[a, b]$ it is enough to show that the real and imaginary parts of $F$ belong to AC $[a, b]$. From (iii) it follows that $F$ is of BV on $[a, b]$ and hence $\operatorname{Re} F$ and $\operatorname{Im} F$ are of BV on $[a, b]$. Clearly, Re $F$ and Im $F$ are absolutely continuous and hence $N$-functions ([7], p. 224) on $X$ as well as on each component of $[a, b] \backslash X$. Since $[a, b] \backslash X$ has only a countable number of components $\operatorname{Re} F$ and $\operatorname{Im} F$ are $N$-functions on $[a, b]$. The result now follows from ([3], p. 288, Theorem 18.25).

Let $S_{X}=\{G \mid G \in \mathrm{AC}[a, b]$ and $G$ is linear on the closure of each component of $[a, b] \backslash X\}$.

$$
\|G\|=\|G\|_{\infty}+\int_{a}^{b}\left|G^{\prime}(t)\right| d t
$$

where $\|G\|_{\infty}$ is the usual uniform norm. It is well known that $\mathrm{AC}[a, b]$ with this norm is a Banach space.

Proposition 1.2. $S_{X}$ is a closed subspace of $\mathrm{AC}[a, b]$ and $\mathrm{AC}(X)$ with the norm given by (1) is a Banach space which is isometrically ısomorphic to $S_{X}$.

Proof. Clearly, $S_{X}$ is a closed subspace of $\mathrm{AC}[a, b]$ and hence it is complete. Now define a map $\psi_{X}: \mathrm{AC}(X) \rightarrow S_{X}$ by $f \rightarrow F$ where $F$ is the unique extension of $f$ as defined in Lemma 1.1. Clearly, $\psi_{X}$ is well defined and is an isomorphism of $\mathrm{AC}(X)$ onto $S_{X}$. Now,

$$
\begin{aligned}
\|f\|=\|f\|_{\infty}+V(f ; X)= & \|f\|_{\infty}+V(F ;[a, b]) \\
& =\|F\|_{\infty}+\int_{a}^{b}\left|F^{\prime}(t)\right| d t=\|F\|=\left\|\psi_{X}(f)\right\| .
\end{aligned}
$$

Therefore, $\psi_{X}$ is an isometry. This implies that $\mathrm{AC}(X)$ is complete. Thus $\mathrm{AC}(X)$ is a Banach space which is isometrically isomorphic to $S_{X}$.
2. By an isometry of a Banach space $B_{1}$ onto a Banach space $B_{2}$ we will mean a linear norm preserving map of $B_{1}$ onto $B_{2}$. The isometries of $\mathrm{AC}[0,1]$ were investigated in $[\mathbf{1}]$ and in $[\mathbf{6}]$. In this article, we show that the techniques of [1], in fact, can be employed to prove that if $X$ and $Y$ are compact subspaces of $\mathbf{R}$, then the existence of an isometry $T$ of $\mathrm{AC}(X)$ onto $\mathrm{AC}(Y)$ implies that there exists an absolutely continuous homeomorphism $\tau$ of $Y$ onto $X$. Moreover $T$ can be described via $\tau$.

Let $V$ denote the closed unit ball of the space $L^{\infty}([a, b])$ provided with the weak-star topology and let $W_{X}$ denote the compact space $X \times V$. Corresponding to each $f \in \mathrm{AC}(X)$ we define $\tilde{f} \in \mathrm{C}\left(W_{X}\right)$ by

$$
\tilde{f}(x, \alpha)=f(x)+\int_{a}^{b} F^{\prime}(t) \bar{\alpha}(t) d t, \quad(x, \alpha) \in W_{X}
$$

where $F$ is the unique extension of $f$ as defined in Lemma 1.1. It is easy to see that the following lemma holds.

Lemma 2.1. The mapping $f \rightarrow \tilde{f}$ establishes an isometry between $\mathrm{AC}(X)$ and the closed subspace $\widetilde{S}_{X}$ of $\mathrm{C}\left(W_{X}\right)$ where $\widetilde{S}_{X}=\{\tilde{f} \mid f \in \mathrm{AC}(X)\}$.

Next, for $(x, \alpha) \in W_{X}$ we define the continuous linear functional $L_{x, \alpha}$ on $\mathrm{AC}(X)$ by

$$
L_{x, \alpha}(f)=\tilde{f}(x, \alpha), \quad f \in \mathrm{AC}(X)
$$

It follows from ([2], p. 441) that the extreme points of the unit ball $U_{X}{ }^{*}$ of $\mathrm{AC}^{*}(X)$ constitute a subset of
$\left\{\gamma L_{x, \alpha} \mid \quad \gamma\right.$ is a complex number with $\left.|\gamma|=1,(x, \alpha) \in W_{X}\right\}$.
Moreover, it is clear that if $L_{x, \alpha}$ is extreme in $U_{X}{ }^{*}$, then $\alpha$ must be extreme in the unit ball of $L^{\infty}([a, b])$, i.e., $|\alpha|=1$ almost everywhere on $[a, b]$ ([4], p. 138).

For a given $x$ in $X$ we denote by $\alpha_{x}$ the $L^{\infty}$ function which takes the value 1 on $[a, x)$ (if $[a, x) \neq \emptyset$ ) and takes the value -1 on $(x, b]$ (if $(x, b]$ $\neq \emptyset)$. Let $S$ be the set of all complex numbers with modulus one and having positive real part.

Lemma 2.2. For all $x \in X$ and $\gamma \in S$ the functional $L_{x, \gamma \alpha_{x}}$ is an extreme point of the unit ball in $\mathrm{AC}^{*}(X)$.

Proof. Given $x \in X$, define $H_{x} \in S_{X}$ by $H_{x}(x)=b-a, H_{x}{ }^{\prime}=\alpha_{x}$ a.e. on $[a, b]$. Now let $\gamma \in S$. There is a real number $M$ such that

$$
\gamma(b-a+M i)=|b-a+M i|
$$

Set

$$
H_{x, \gamma}=\gamma\left(H_{x}+M i\right) \quad \text { and } \quad h_{x, \gamma}=\left.H_{x, \gamma}\right|_{x} .
$$

Then $h_{x, \gamma} \in \mathrm{AC}(X)$,

$$
\begin{aligned}
& L_{x, \gamma \alpha_{x}}\left(h_{x, \gamma}\right)=h_{x, \gamma}(x)+\bar{\gamma} \int_{a}^{b} \gamma H_{x}^{\prime}(t) \alpha_{x}(t) d t \\
&=\left\|h_{x, \gamma}\right\|_{\infty}+\int_{a}^{b}\left|H_{x, \gamma}^{\prime}(t)\right| d t=\left\|h_{x, \gamma}\right\|
\end{aligned}
$$

and

$$
\left|L_{t, \beta}\left(h_{x, \gamma}\right)\right|<\left\|h_{x, \gamma}\right\| \quad \text { for }(t, \beta) \in W_{X},(t, \beta) \neq\left(x, \gamma \alpha_{x}\right) .
$$

Now, a result of deLeeuw ([5], p. 61) shows that $L_{x, \gamma \alpha_{x}}$ is an extreme point of the unit ball in $\mathrm{AC}^{*}(X)$.

Now, let $Y$ be another arbitrary compact subset of $\mathbf{R}$ with $c$ and $d$ as its greatest lower bound and least upper bound respectively. Let $T$ be an isometry of $\mathrm{AC}(X)$ onto $\mathrm{AC}(Y)$. We denote by $\psi_{Y}$ (analogous to $\psi_{X}$ ) the
isometry of $\mathrm{AC}(Y)$ onto the closed subspace $S_{Y}$ (analogous to $S_{X}$ ) of $\mathrm{AC}[c, d]$. Then $\hat{T}=\psi_{Y} T \psi_{X}{ }^{-1}$ is an isometry of $S_{X}$ onto $S_{Y}$. Also the adjoint of $T$, namely $T^{*}$, is an isometry of $\mathrm{AC}(Y)^{*}$ onto $\mathrm{AC}(X)^{*}$ and hence maps the set of extreme points of $U_{Y}{ }^{*}$ onto the set of extreme points of $U_{X}{ }^{*}$.

The function which is identically equal to 1 on a set $Q$ will be denoted by 1 and it will be always clear from the context what $Q$ is meant.

Lemma 2.3. $T(1)$ is a constant function on $Y$.
Proof. Let $y \in Y, \gamma \in S$ and let $\alpha_{y}$ denote the function in $L^{\infty}([c, d])$ analogous to the function $\alpha_{x}$ in $L^{\infty}([a, b])$. The fact that $L_{y, \gamma \alpha_{y}}$ is an extreme point of $U_{Y}{ }^{*}$ implies that $T^{*} L_{y, \gamma \alpha_{y}}$ is a functional of the form $\delta L_{x, \beta}$, where $|\delta|=1$ and $(x, \beta) \in W_{X}$. Set $g=T(1)$ and $G=\hat{T}(1)$. Then

$$
\left|g(y)+\bar{\gamma} \int_{c}^{a} G^{\prime}(t) \alpha_{y}(t) d t\right|=\left|L_{y, \gamma \alpha_{y}}(g)\right|=\left|T^{*} L_{y, \gamma \alpha_{y}}(1)\right|=1 .
$$

Since $\gamma$ is an arbitrary element of $S$, we must have either $g(y)=0$ or $|g(y)|=1$. Since $\|g\|=1$, we have

$$
|g(y)|=1 \quad \text { and } \quad \int_{c}^{d} G^{\prime}(t) \alpha_{y}(t) d t=0
$$

for each $y \in Y$. Therefore

$$
0=G(y)-G(c)-G(d)+G(y), \quad G(y)=\frac{1}{2}(G(c)+G(d))
$$

for each $y \in Y$. Since $g=\left.G\right|_{Y}, g$ is a constant function on $Y$.
For $y \in Y$ and $\gamma \in S$, the functional $T^{*} L_{y, \gamma \alpha_{y}}$ must be of the form $\delta L_{x, \beta}$ where $\delta, x, \beta$, as such, will depend on $y$ and $\gamma$ but it is easy to see that $\delta$ is constant for all $y \in Y$ and $\gamma \in S$ and $\delta=T(1)$. In what follows we suppose that $T(1)=1$, for otherwise we may replace $T$ by $T / T(1)$. Hence for $y \in Y$ and $\gamma \in S$, the functional $T^{*} L_{y, \gamma \alpha_{y}}$ will be of the form $L_{x, \beta}$ for some $x \in X$ and $\beta \in L^{\infty}([a, b])$ such that $|\beta|=1$ a.e. on $[a, b]$. For each $y \in Y$ let $h_{y} \in \mathrm{AC}(Y)$ be defined by $h_{y}=\left.H_{y}\right|_{Y}$ where $H_{v} \in$ $\mathrm{AC}[c, d]$ is defined as $H_{y}(y)=d-c, H_{y}{ }^{\prime}=\alpha_{y}$ a.e. on $[c, d]$. Let $M$ be a real number such that

$$
\gamma(d-c+M i)=|d-c+M i|
$$

Let $H_{y, \gamma}=\gamma\left(H_{y}+M i\right)$ and let $h_{y, \gamma}=\left.H_{y, \gamma}\right|_{Y}$.
Lemma 2.4. Let $y \in Y, \gamma \in S, g \in A C(Y)$ and

$$
\left\|h_{y, \gamma}+g\right\|=\left\|h_{y, \gamma}\right\|+\|g\| .
$$

Then $\|g\|=L_{y, \gamma \alpha_{y}}(g)$.

Proof. It is easy to see that

$$
\left\|h_{y, \gamma}+g\right\|_{\infty}=\left\|h_{y, \gamma}\right\|_{\infty}+\|g\|_{\infty}
$$

and that

$$
\int_{c}^{a}\left|H_{y, \gamma^{\prime}}(t)+G^{\prime}(t)\right| d t=\int_{c}^{a}\left(\left|H_{y, \gamma^{\prime}}(t)\right|+\left|G^{\prime}(t)\right|\right) d t
$$

where $G=\psi_{Y}(g)$. It follows that $g(y)=\|g\|_{\infty}$ and that $G^{\prime} \geqq 0$ a.e. on $(c, y), G^{\prime} \leqq 0$ a.e. on $(y, d)$. This proves the lemma.
Lemma 2.5. Let $y \in Y, \gamma \in S$ and $T^{*} L_{y, \gamma \alpha_{y}}=L_{x, \beta}$. Let $k=T^{-1}\left(h_{y, \gamma}\right)$, $f \in \mathrm{AC}(X)$ and $\|k+f\|=\|k\|+\|f\|$. Then

$$
\|f\|=L_{x, \beta}(f) .
$$

Proof. We have

$$
\begin{aligned}
&\left\|h_{y, \gamma}\right\|+\|\mathrm{T}(f)\|=\|k\|+\|f\|=\|k+f\|=\|T(k+f)\| \\
&=\left\|h_{y, \gamma}+T(f)\right\| .
\end{aligned}
$$

Therefore by Lemma 2.4

$$
\|f\|=\|T(f)\|=L_{y, \gamma \alpha_{y}}(T(f))=T^{*} L_{y, \gamma \alpha_{y}}(f)=L_{x, \beta}(f) .
$$

For each $y \in Y$ and each $\gamma \in S$ let $A_{y, \gamma}$ be the set of all $g \in \operatorname{AC}(Y)$ such that $L_{y, \gamma \alpha_{y}}(g)=\|g\|$. Then, since $T^{-1}$ is an isometry, we have

$$
\begin{aligned}
& T^{-1}\left(A_{y, \gamma}\right)=\left\{T^{-1}(g) \mid \quad g \in A_{y, \gamma}\right\} \\
&=\left\{f \in \operatorname{AC}(X) \mid \quad T^{*} L_{y, \gamma \alpha_{y}}(f)=\|f\|\right\} .
\end{aligned}
$$

For each measurable set $B \subset R$ let $|B|$ be its Lebesgue measure.
Lemma 2.6. Let $y \in Y, \gamma \in S$ and $T^{*} L_{y, \gamma \alpha_{y}}=L_{x, \beta}$. If $E$ is an open subset of $X$ which contains $x$, then there exists an $h \in \mathrm{AC}(X)$ such that

$$
L_{x, \beta}(h)=\|h\| \text { and } \max _{t \in(X \backslash E)}|h(t)|<|h(x)| .
$$

Proof. We first assume that $x$ is an interior point of $[a, b]$. Then there exists an open interval $(p, q)$ such that $x \in(p, q) \cap X \subset E$. We claim that $T^{-1}\left(A_{y, \gamma}\right)$ contains an element $f_{1}$ such that $\psi_{X}\left(f_{1}\right)$ is not constant on ( $p, x]$. To see this, one may take $f_{1}=T^{-1}\left(h_{y, \gamma}\right)$ if $\hat{T}^{-1}\left(H_{y, \gamma}\right)$ is not constant on $(p, x]$. Otherwise let $\chi$ be the characteristic function of $(p, x]$, $F_{1}(t)=\int_{a}{ }^{t} \chi(s) d s(t \in[a, b])$ and $f_{1}=\left.F_{1}\right|_{X}$. Further define $\beta_{1}(s)=\beta(s)$ on $[a, b] \backslash(p, x], \beta_{1}(s)=1$ on $(p, x]$. Then

$$
\begin{aligned}
&\left\|f_{1}\right\|+\left\|T^{-1}\left(h_{y, \gamma}\right)\right\|=\left\|f_{1}\right\|_{\infty}+\int_{a}^{b}\left|F_{1}^{\prime}(s)\right| d s+L_{x, \beta}\left(T^{-1}\left(h_{y, \gamma}\right)\right) \\
&= f_{1}(x)+\int_{p}^{x} \chi(s) d s+T^{-1}\left(h_{y, \gamma}\right)(x)+\int_{a}^{b}\left(\hat{T}^{-1}\left(H_{\nu, \gamma}\right)\right)^{\prime}(s) \bar{\beta}(s) d s \\
&=\left(f_{1}+T^{-1}\left(h_{y, \gamma}\right)\right)(x)+\int_{a}^{b}\left(F_{1}^{\prime}+\left(\hat{T}^{-1}\left(H_{y, \gamma}\right)\right)^{\prime}\right)(s) \bar{\beta}_{1}(s) d s \\
& \leqq\left\|f_{1}+T^{-1}\left(h_{y, \gamma}\right)\right\| .
\end{aligned}
$$

Lemma 2.5 now shows that $f_{1} \in T^{-1}\left(A_{y, \gamma}\right)$. Clearly, $F_{1}$ is not constant on $(p, x]$. Thus there exists an $f_{1} \in T^{-1}\left(A_{y, \gamma}\right)$ and a point $e_{1} \in(p, x)$ such that

$$
F_{1}\left(e_{1}\right) \neq f_{1}(x)=\left\|f_{1}\right\|_{\infty}
$$

Similarly, there is an $F_{2} \in S_{X}$ and a point $e_{2} \in(x, q)$ such that

$$
\left.F_{2}\right|_{X} \in T^{-1}\left(A_{y, \gamma}\right)
$$

and that

$$
F_{2}\left(e_{2}\right) \neq F_{2}(x)=\left\|F_{2}\right\|_{\infty} .
$$

Define functions $H_{1}$ and $H_{2}$ as follows: If $e_{1}, e_{2} \in X$ then $H_{1}(t)=F_{1}\left(e_{1}\right)$ for $t \in\left[a_{1}, e_{1}\right], H_{1}(t)=F_{1}(t)$ for $t \in\left(e_{1}, b\right], H_{2}(t)=F_{2}(t)$ for $t \in\left[a, e_{2}\right)$, $H_{2}(t)=F_{2}\left(e_{2}\right)$ for $t \in\left[e_{2}, b\right]$. If $e_{1} \notin X$ then $e_{1}$ must belong to one of the components of $[a, b] \backslash X$ which must be an open interval say $\left(a_{1}, b_{1}\right) \subset$ $(a, b)$. Thus $e_{1} \in\left(a_{1}, b_{1}\right)$. Clearly then at least one of the $f_{1}\left(a_{1}\right)$ and $f_{1}\left(b_{1}\right)$ must be different from $f_{1}(x)$. Say for definiteness $f_{1}\left(a_{1}\right) \neq f_{1}(x)$. Then define $H_{1}(t)=F_{1}\left(a_{1}\right)$ for $t \in\left[a, a_{1}\right], H_{1}(t)=F_{1}(t)$ for $t \in\left(a_{1}, b\right]$.

If $e_{2} \notin X$, the definition of $H_{2}$ can be modified similarly. It is easy to see that $\left.H_{j}\right|_{X} \in T^{-1}\left(A_{y, \gamma}\right) \quad(j=1,2)$ and that the function $h=\left(H_{1}+H_{2}\right.$ $+1)\left.\right|_{x}$ has the required properties. A slight modification in the above arguments will prove the result in the case when $x=a$ or $x=b$.

Lemma 2.7. Let $y \in Y, D=\left\{t \in[a, b] \mid\left(T^{-1}\left(H_{y}\right)\right)^{\prime}(t)=0\right\}$. Then $|D|=0$.

Proof. Let $T^{*} L_{y, \alpha_{y}}=L_{x, \delta}$. Suppose that $|D|>0$. Then for some positive real number $\eta$ at least one of the two sets $D \cap[a, x-\eta], D \cap[x+\eta, b]$ has a nonzero measure. Choose such a set and denote it by $B$. By Lemma 2.6 there exists an $h \in T^{-1}\left(A_{y, 1}\right)$, and an $\epsilon>0$, such that

$$
\sup _{t \in B}|h(t)|<|h(x)|-\epsilon
$$

Next choose a measurable function $\alpha$ with $|\alpha|=1$ on $B, \alpha=0$ on $[a, b] \backslash B$, $\int_{a}{ }^{b} \alpha(s) d s=0$ and such that $\alpha \bar{\delta}$ has a nonzero imaginary part on some subset of $B$ with positive measure. Now define

$$
H=\psi_{X}(h), \quad F(t)=H(t)+\epsilon \int_{a}^{t} \alpha(s) d s \quad(a \leqq t \leqq b), \quad f=\left.F\right|_{X}
$$

It is easy to see that $\|f\|_{\infty}=f(x), F^{\prime}(t)=H^{\prime}(t)$ a.e. on $[a, b] \backslash B,\left|H^{\prime}(t)\right|$ $=H^{\prime}(t) \bar{\delta}(t)$ a.e. on $[a, b]$. We may choose $h$ so that $H^{\prime}(t)$ is either zero or one on $B$ from which it follows that $F^{\prime}(t) \neq 0$ a.e. on $B$.

Let $\delta_{1}(t)=F^{\prime}(t) /\left|F^{\prime}(t)\right|$ a.e. on $B, \delta_{1}(t)=\delta(t)$ on $[a, b] \backslash B$. We have

$$
\begin{aligned}
\|f\| & +\left\|T^{-1}\left(h_{y}\right)\right\|=\|f\|_{\infty}+\int_{a}^{b}\left|F^{\prime}(t)\right| d t+L_{x, \delta}\left(T^{-1}\left(h_{y}\right)\right) \\
& =f(x)+\int_{[a, b] \backslash B}\left|F^{\prime}(t)\right| d t+\int_{B}\left|F^{\prime}(t)\right| d t+\left(T^{-1}\left(h_{y}\right)\right)(x) \\
& +\int_{\{a, b \backslash \backslash B}\left(\hat{T}^{-1}\left(H_{y}\right)\right)^{\prime}(t) \bar{\delta}(t) d t=\left(f+T^{-1}\left(h_{y}\right)\right)(x) \\
& +\int_{\{a, b\rceil \backslash B}\left(F^{\prime}(t)+\left(\hat{T}^{-1}\left(H_{y}\right)\right)^{\prime}(t)\right) \bar{\delta}(t) d t+\int_{B}\left|F^{\prime}(t)\right| d t \\
& =\left(f+T^{-1}\left(h_{y}\right)\right)(x)+\int_{a}^{b}\left(F+\hat{T}^{-1}\left(H_{y}\right)\right)^{\prime}(t) \bar{\delta}_{1}(t) d t \\
& \leqq\left\|f+T^{-1}\left(h_{y}\right)\right\| .
\end{aligned}
$$

Also, since $\alpha \bar{\delta}$ has a nonzero imaginary part on some subset of $B$ with positive measure, $L_{x, \delta}(f) \neq\|f\|$ which contradicts Lemma 2.5.

Lemma 2.8. Let $y \in Y, \gamma \in S, T^{*} L_{y, \alpha_{y}}=L_{x, \delta}, T^{*} L_{y, \gamma \alpha_{y}}=L_{v, \beta}$. Then $\beta=\gamma \delta$ а.е.

Proof. Let $M$ be a real number such that

$$
\begin{aligned}
& \gamma(d-c+M i)=|d-c+M i|, \\
& F=\gamma\left(\hat{T}^{-1}\left(H_{y}\right)+M i\right), \\
& f=\left.F\right|_{x} .
\end{aligned}
$$

Then $H_{y, \gamma}=\gamma\left(H_{y}+M i\right), T(f)=h_{y, \gamma}$ and

$$
\|f\|=\left\|h_{y, \gamma}\right\|=L_{y, \gamma \alpha_{y}}\left(h_{y, \gamma}\right)=T^{*} L_{y, \gamma \alpha_{y}}(f)=f(v)+\int_{a}^{b} F^{\prime}(t) \bar{\beta}(t) d t
$$

Thus

$$
\begin{aligned}
\int_{a}^{b}\left|\left(\hat{T}^{-1}\left(H_{y}\right)\right)^{\prime}(t)\right| d t=\int_{a}^{b}\left|F^{\prime}(t)\right| d t= & \int_{a}^{b} F^{\prime}(t) \bar{\beta}(t) d t \\
& =\int_{a}^{b} \gamma\left(\hat{T}^{-1}\left(H_{y}\right)\right)^{\prime}(t) \bar{\beta}(t) d t
\end{aligned}
$$

and hence

$$
\gamma \bar{\beta}(t)\left(\hat{T}^{-1}\left(H_{y}\right)\right)^{\prime}(t)=\left|\left(\hat{T}^{-1}\left(H_{y}\right)\right)^{\prime}(t)\right| \text { a.e. on }[a, b] .
$$

Taking $\gamma=1$ we get

$$
\bar{\delta}(t)\left(\hat{T}^{-1}\left(H_{y}\right)\right)^{\prime}(t)=\left|\left(\hat{T}^{-1}\left(H_{y}\right)\right)^{\prime}(t)\right| \text { a.e. on }[a, b] .
$$

Therefore, by Lemma 2.7, $\beta=\gamma \delta$ a.e.

Let $y \in Y, T^{*} L_{y, \alpha_{y}}=L_{x, \delta},(x, \delta) \in W_{X}$. We see from Lemma 2.8 that for each $\gamma \in S$ there is a $v \in X$ such that
(2) $T^{*} L_{y, \gamma \alpha_{y}}=L_{v, \gamma \delta}$.

It is easy to see that there is a unique $v$ fulfilling (2). Define a function $\varphi$ on $S$ setting $\varphi(\gamma)=v$, where $v$ is obtained by (2).

Lemma 2.9. Let $y \in Y$ and let $\varphi$ be as above. Then $\varphi$ is constant.
Proof. We show first that $\varphi$ is continuous. Let $\gamma \in S$ and let $E$ be an open neighbourhood of $\varphi(\gamma)$ in $X$. By Lemma 2.6 there exists an $h$ in $\mathrm{AC}(X)$ such that $T^{*} L_{y, \gamma \alpha_{y}}(h)=\|h\|$ and

$$
\sup _{t \in X \backslash E}|h(t)|<|h(\varphi(\gamma))|-\epsilon \text { for some } \epsilon>0
$$

Then

$$
\|h\|=(T(h))(y)+\bar{\gamma} \int_{c}^{l}(\hat{T}(H))^{\prime}(t) \bar{\alpha}_{y}(t) d t
$$

So it is clear that for $z$ sufficiently close to $\gamma, \varphi(z) \in E$. Thus the mapping $\varphi$ is continuous and $\varphi(S)$ is connected.

Now we prove that $\varphi(S)$ is a singleton. We proceed as follows: Suppose that $\varphi(S)$ has more points than one. Let $T^{*} L_{y, \alpha_{y}}=L_{x, \delta}$. We may choose a function $p \in \mathrm{AC}(X)$, an interval $I \subset \varphi(S)$ and a point $z \in S$ such that $p=0$ on $I, p(\varphi(z)) \neq 0$ and

$$
\int_{a}^{b}\left(\psi_{x}(p)\right)^{\prime}(t) \bar{\delta}(t) d t=0
$$

If $\varphi(\gamma) \in I$, then

$$
L_{y, \gamma \alpha_{y}}(T(p))=L_{\varphi(\gamma), \gamma \delta}(p)=p(\varphi(\gamma))=0
$$

Since there are infinitely many such numbers $\gamma$, we have

$$
L_{y, \gamma \alpha_{y}}(T(p))=0 \quad \text { for each } \gamma \in S
$$

However,

$$
L_{y, z \alpha_{y}}(T(p))=L_{\varphi(z), z \delta}(p)=p(\varphi(z)) \neq 0
$$

which is a contradiction.
We now define a mapping $\tau$ : Y into $X$ setting $\tau(y)$ to be the value of the function $\varphi$ defined above. Thus

$$
T^{*} L_{y, \alpha_{y}}=L_{\tau(y), \delta}
$$

Consideration of $T^{-1}$ will show that $\tau$ is onto and one-to-one. It will then follow from the following theorem that $\tau$ is an absolutely continuous homeomorphism from $Y$ onto $X$.

Theorem 2.10. Let $T$ be an isometry of $\mathrm{AC}(X)$ onto $\mathrm{AC}(Y)$ with $T(1)=1$. Let $f_{0}$ be the identity mapping of $X$ onto itself and let $\tau=T\left(f_{0}\right)$. Then for each $f \in \mathrm{AC}(X)$ and each $y \in Y$

$$
(T(f))(y)=f(\tau(y)) .
$$

Proof. Let $y \in Y$. We first suppose that $g \in \operatorname{AC}(Y)$ with $g(y)=0$. Then for all $\gamma \in S$

$$
\begin{array}{r}
\int_{c}^{a} G^{\prime}(t) \bar{\alpha}_{y}(t) d t=\gamma L_{y, \gamma \alpha_{y}}(g)=\gamma T^{*} L_{y, \gamma \alpha_{y}}\left(T^{-1}(g)\right)=\gamma L_{\tau(y), \gamma \delta}\left(T^{-1}(g)\right) \\
=\gamma\left(T^{-1}(g)\right)(\tau(y))+\int_{a}^{b}\left(\hat{T}^{-1}(G)\right)^{\prime}(t) \bar{\delta}(t) d t .
\end{array}
$$

Therefore $\left(T^{-1}(g)\right)(\tau(y))=0$.
For arbitrary $g \in \mathrm{AC}(Y)$, define $g_{1}$ by

$$
g_{1}(t)=g(t)-g(y), \quad t \in Y
$$

Then

$$
\begin{aligned}
0=\left(T^{-1}\left(g_{1}\right)\right)(\tau(y))=\left(T^{-1}(g)\right)(\tau(y)) & -g(y)\left(T^{-1}(1)\right)(\tau(y)) \\
& =\left(T^{-1}(g)\right)(\tau(y))-g(y) .
\end{aligned}
$$

Replacing $g$ by $T(f)$, we have for $y \in Y$ and $f \in \operatorname{AC}(X)$,

$$
(T(f))(y)=f(\tau(y)) .
$$

If $f_{0}$ is the identity mapping of $X$ onto itself, we have

$$
\tau(y)=\left(T\left(f_{0}\right)\right)(y)
$$

and the theorem is proved.
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