

## THE TRANSIENT BLOCKING PROBABILITIES IN $M/M/N$ LOSS SYSTEMS VIA LARGE DEVIATIONS

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### Abstract

By using large deviations theory, we give asymptotic formulas for the transient blocking probabilities of  $M/M/N/N$  and  $M$  (with finite Poissonian sources)  $M/N/N$  queues.

LARGE DEVIATIONS; LOSS SYSTEM

AMS 1991 SUBJECT CLASSIFICATION: PRIMARY 60K25

### 1. Introduction and motivation

This paper follows the short communication [7], based on [3], in which the author gives an intuitive method for the derivation of the transient blocking probability in a  $M[\lambda N]/M[\mu]/N/N$  loss system, where  $\lambda N$  and  $\mu$  represent the parameters of the exponential interarrival and service distributions. In this paper we denote this system by  $\Sigma_1$ . In the references mentioned, the probability  $P_N(t, N)$  that all the  $N$  servers are busy at time  $t$  was approximated by the following formula:

$$(1) \quad P_N(t, N) \approx C[P_i(t, 1)]^N = C[1 - \exp(-(\lambda + \mu)t)]^N,$$

where  $P_i(t, 1)$  is the blocking probability of an  $M[\lambda]/M[\mu]/1/1$  system at time  $t$ , supposed to be initially free. We prove here that this probability (1) is rather related to the transient blocking probability of a  $M[\lambda(N - Q(t))]/M[\mu]/N/N$  queue, where  $\lambda(N - Q(t))$  means that the interarrival time between two successive customers entering the system has an exponential distribution with parameter  $\lambda(N - Q(t))$ , when the number of busy servers just before the arrival of the new customer is  $Q(t)$ . We denote this second system by  $\Sigma_2$ . We also give the corrected formula for the system  $M[\lambda N]/M[\mu]/N/N$ . The proofs are based on the principle of large deviations.

### 2. Main results

Let us denote by  $(Q^N(t))_{t \geq 0}$  the queue length process which is a pure jump Markov process for both systems  $\Sigma_1$  and  $\Sigma_2$ . We denote by  $1_E$  the indicator of event  $E$ ; it is equal to 1 if  $E$  is true and 0 otherwise. When  $Q^N(t) = q$ , the jumps  $e_+ = +1$  occur with the intensities  $\lambda^N(q) = N\lambda 1_{q \leq N}$  and  $\lambda^N(q) = \lambda(N - q)$  for  $\Sigma_1$  and  $\Sigma_2$  respectively, and the jumps  $e_- = -1$  occur with the intensity  $\mu^N(q) = \mu(q \wedge N)$  for both systems, where  $q \wedge N$  is the minimum of  $q$  and  $N$ . The sequence of processes  $(X^N(t)) = (Q^N(t)/N)$  satisfies the principle of large deviations (cf. [4], [5], [6]). Let  $A^N$  denote the infinitesimal generator of  $X^N$ . The instantaneous Laplace transform of  $(X^N(t))$  is defined by  $G^N(x, z) = (A^N f_z / f_z)(x)$  where

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Received 17 September 1990; revision received 16 July 1992.

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$f_z(x) = \exp(zx)$ . Direct computations give

$$(2) \quad G^N(x, z) = NG(x, z/N)$$

where

$$(3) \quad G(x, z) = \lambda(x)[e^z - 1] + \mu(x \wedge 1)[e^{-z} - 1]$$

with  $\lambda(x) = \lambda_{x \leq 1}$  for  $\Sigma_1$  and  $\lambda(x) = \lambda(1 - x)$  for  $\Sigma_2$ . Its Cramer–Legendre transform (cf. [5]) is defined by

$$(4) \quad H(r, r') = \sup_z (zr' - G(r, z)).$$

Let  $B_{0,T}$  be the set of piecewise differentiable right-continuous functions  $\phi$  defined on  $(0, T)$ , having left limits and such that  $\phi(0) = X_{\text{eq}}$  and  $\phi(T) = 1$ , where  $X_{\text{eq}}$  is the equilibrium point of  $X^\infty(t) = \lim_{N \rightarrow +\infty} X^N(t)$ . The action functional (cf. [2]) of  $B_{0,T}$  is  $S(B_{0,T}) = \inf_{\phi \in B_{0,T}} \int_0^T H(\phi(t), \phi'(t)) dt$ . By the principle of large deviations, we have

$$(5) \quad S(B_{0,T}) = \lim_{N \rightarrow +\infty} -\frac{1}{N} \log P((X^N(t))_{0 \leq t \leq T} \in B_{0,T}).$$

The Euler–Lagrange equation associated to the dynamic programming problem (cf. [1], [6])

$$(6) \quad S(B) = \inf_{0 \leq T} S(B_{0,T}) = \inf_{T \geq 0, \phi \in B_{0,T}} \int_0^T H(\phi(t), \phi'(t)) dt$$

is:

$$(7) \quad \frac{\partial H}{\partial t} - \frac{d}{dt} \left( \frac{\partial H}{\partial r'} \right) = 0$$

$$(8) \quad r(0) = X_{\text{eq}} \quad \text{and} \quad r(T) = 1.$$

An integration by parts gives

$$H(r, r') - r' \frac{\partial H}{\partial r'} = 0,$$

$$r(0) = X_{\text{eq}} \quad \text{and} \quad r(T) = 1.$$

Thus, for a solution  $r$  of (7, 8), we obtain

$$(9) \quad S(B) = \int_0^T r'(t) \frac{\partial H}{\partial r'} dt = \int_{r(0)}^{r(T)} \frac{\partial H}{\partial r'} dr.$$

From the definition (4) we get  $\partial H / \partial r' = z(r')$ , where  $z(r')$  maximizes  $zr' - G(r, z)$ . This, together with the Euler–Lagrange equation (7), gives  $G(r, z(r')) = 0$ ; from which we can solve  $z(r')$  as a function of  $r$  and get a tractable expression of  $\int_{r(0)}^{r(T)} (\partial H / \partial r') dr$ .

For  $\Sigma_1$ :

$$r(0) = X_{\text{eq}} = \frac{\lambda}{\mu},$$

$$z(r') = \log \frac{\mu r'}{\lambda}.$$

Thus,

$$S(B) = \log \left( \frac{\mu}{\lambda} \right) - \left( 1 - \frac{\lambda}{\mu} \right).$$

We can easily check that

$$\lim_{N \rightarrow +\infty} -\frac{1}{N} \log \left( B \left( N, \rho = \frac{\lambda}{\mu} \right) \right) = S(B)$$

where  $B(N, \rho)$  is the Erlang loss probability.

For  $\Sigma_2$ :

$$r(0) = X_{eq} = \frac{\lambda}{\mu + \lambda},$$

$$z(r') = \log \frac{\mu r}{\lambda(1-r)}.$$

Thus,

$$S(B) = \log \left( 1 + \frac{\mu}{\lambda} \right).$$

For finite  $T$ ,  $S(B_{0,T})$  is computed by using the optimal function  $(r(t))$  realizing the minimum of  $S(B)$ . The optimal function verifies

$$r'(t) = \mu(r(t)) - \lambda(r(t)) \tag{10}$$

$$r(T) = 1.$$

The initial condition  $r(0)$  depends on  $T$  and is computed by using the final condition  $r(T) = 1$ . Therefore,

$$(11) \quad S(B_{0,T}) = S(B) - \int_{X_{eq}}^{r(0)} z(r') dr = S(B) - I(T),$$

where

$$(12) \quad I(T) = \int_{X_{eq}}^{r(0)} z(r') dr.$$

The solution of the linear differential equation (10) added to the condition  $r(T) = 1$  give the initial value of  $r(t)$ . This yields for  $\Sigma_1$  and  $\Sigma_2$ , respectively:

$$(13) \quad r_{\Sigma_1}(0) = \left\{ 1 - \frac{\lambda}{\mu} [1 - \exp(\mu T)] \right\} \exp(-\mu T)$$

$$(14) \quad r_{\Sigma_2}(0) = \left\{ 1 - \frac{\lambda}{\mu + \lambda} [1 - \exp((\mu + \lambda)T)] \right\} \exp(-(\mu + \lambda)T).$$

Let us determine  $I(T)$  and compute its asymptotic value when  $T$  grows to infinity. By replacing, for  $\Sigma_1$ , expression (13) of  $r_{\Sigma_1}(0)$  into the definition of  $I(T)$ , we obtain

$$I(T) = \int_{\lambda/\mu}^{r_{\Sigma_1}(0)} z(r') dr$$

$$= \int_1^{\mu/\lambda r_{\Sigma_1}(0)} \log(r) dr$$

$$= \{r \log(r) - r\}_1^{[\mu/\lambda - (1 - \exp(\mu T))] \exp(-\mu T)} \exp(-\mu T).$$

Using the Maclaurin expansion of  $\log(1+y)$  for  $y = (\mu/\lambda - 1) \exp(-\mu T)$  and large values of  $T$ , we obtain that  $I(T)$  is equivalent (denoted by  $\sim$ ) to  $(\mu/\lambda - 1)^2 \exp(-2\mu T)$  when  $T$  grows to infinity. The expression of  $I(T)$  and its equivalent for  $\Sigma_2$  are derived in a similar way. These results are summarized as follows:

$$I_{\Sigma_1}(T) = (1+y) \log(1+y) - y - 1, \quad \text{where } y = ((\mu/\lambda) - 1) \exp(-\mu T),$$

$$I_{\Sigma_1}(T) \sim_{T \rightarrow \infty} \frac{1}{2} \left( \frac{\mu}{\lambda} - 1 \right)^2 \exp(-2\mu T),$$

$$(15) \quad I_{\Sigma_2}(T) = \alpha(1+y') \log(1+y') + [1 - \alpha(1+y')] \log \left( 1 - \frac{\alpha}{1-\alpha} y' \right),$$

where  $\alpha = \lambda/(\lambda + \mu)$  and  $y' = (\mu/\lambda) \exp(-(\lambda + \mu)T)$ ,

$$(16) \quad I_{\Sigma_2}(T) \sim_{T \rightarrow \infty} \frac{1}{2} \frac{\mu}{\lambda} \exp(-2(\lambda + \mu)T).$$

Remark that the asymptotic value of  $I_{\Sigma_1}(T)$  depends exponentially only on  $\mu$  while  $I_{\Sigma_2}(T)$  depends on  $\mu$  and  $\lambda$ . The coefficient of  $T$  in (15) and (16), which we call relaxation time, represents the convergence rate of  $X^N$ . It is larger for  $\Sigma_2$  than for  $\Sigma_1$  due to the dynamic of the customers' arrivals. The relaxation time  $(\lambda + \mu)$  of  $\Sigma_1$ , derived in [7] (formula 1) is, in fact, related to that of  $\Sigma_2$  given here by formula (16).

This method can be applied to more general queueing networks than  $M/M/N/N$  loss systems studied in this paper. Since this technique is based on large deviations theory, the time-transient behavior result is asymptotic when the network is large.

### Acknowledgement

The author thanks the referee for helpful comments.

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