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# Sharpness Results and Knapp's Homogeneity Argument

Alex Iosevich and Guozhen Lu

*Abstract.* We prove that the  $L^2$  restriction theorem, and  $L^p \to L^{p'}$ ,  $\frac{1}{p} + \frac{1}{p'} = 1$ , boundedness of the surface averages imply certain geometric restrictions on the underlying hypersurface. We deduce that these bounds imply that a certain number of principal curvatures do not vanish.

#### 1 Introduction

Let *S* be a smooth compact hypersurface in  $\mathbb{R}^n$ . Let

(1) 
$$F_{S}(\xi) = \int_{S} e^{i \langle x, \xi \rangle} \, d\sigma(x)$$

denote the Fourier transform of the surface measure carried by S.

Let  $\Re f = \hat{f}|_{S}$ , the restriction operator. It is well known (see [6], [2], [4]) that if

(2) 
$$|F_S(\xi)| \le C(1+|\xi|)^{-r}, \quad r > 0.$$

then

(3) 
$$\|\Re f\|_2 \le C_p \|f\|_p, \quad f \in S(\mathbb{R}^n), \quad \text{for } p \le p_0 = \frac{2(r+1)}{r+2},$$

where  $S(\mathbb{R}^n)$  is the standard Schwartz class.

However, it is not in general known whether this result is sharp. More precisely, it is natural to ask the following.

**Question A** Does the estimate (3) imply the estimate (2)?

Let

(4) 
$$Tf(x,x_n) = \int f(x-y,x_n-\Phi(y))\psi(y)\,dy,$$

where  $x, y \in \mathbb{R}^{n-1}$ ,  $\psi$  is a smooth cutoff function,  $\Phi$  is smooth,  $\Phi(0, \ldots, 0) = 0$ , and  $\nabla \Phi(0, \ldots, 0) = (0, \ldots, 0)$ .

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It is well known (see [5]) that if the estimate (2) holds, then

(5) 
$$||Tf||_{p'} \le C_p ||f||_p$$
, where  $\frac{1}{p} - \frac{1}{2} \le \frac{r}{2(r+1)}$ ,

where p' denotes the conjugate exponent of p.

The key estimate here is

(6) 
$$\|Tf\|_{2(r+1)} \le C \|f\|_{\frac{2(r+1)}{2r+1}};$$

the rest follows by interpolation. It is then natural to ask the following.

**Question B** Does the estimate (5) imply the estimate (2)?

The purpose of this paper is to answer questions A and B affirmatively in the case of the optimal exponents. We shall employ a multiparameter version of Knapp's homogeneity argument. (See *e.g.* [1] for a similar argument).

More precisely, we will show that if the the estimate (3) holds with  $p = \frac{2(n+1)}{n+3}$ , then the hypersurface has everywhere non-vanishing Gaussian curvature. Similarly, we will show that if the estimate (5) holds with  $p = \frac{n+1}{n}$ , then the hypersurface has non-vanishing Gaussian curvature.

We remark here, on the other hand, that non-vanishing Gaussian curvature implies that the estimate (2) holds with  $r = \frac{n-1}{2}$  (see *e.g.* [4]). Thus Question A is answered affirmatively in the case  $r = \frac{n-1}{2}$ . Since the estimate (2) with  $r = \frac{n-1}{2}$  implies the estimate (3) with  $p = \frac{2(n+1)}{n+3}$ , Theorem 2 below shows that the optimal decay of the Fourier transform (*i.e.*,  $r = \frac{n-1}{2}$ ) implies that the hypersurface has non-vanishing Gaussian curvature.

We will also see that if a hypersurface has  $\leq k$  non-vanishing principal curvatures at each point, then the exponent p in the estimate (3) can never exceed  $\frac{2n+k-2}{6}$ . Consequently, the estimate (3) with  $p \geq \frac{2n+k-2}{6}$  implies that at least k principal curvatures are non-zero at each point. (See Theorem 3 below). Similarly, we will show that if the estimate (5) holds with  $p \geq \frac{2n+k+4}{2n+k+1}$ , then at least k principal curvatures are non-zero at each point.

The sharpness of the estimate (3) is known in some cases. For example, if the hypersurface has non-vanishing Gaussian curvature, Knapp's homogeneity argument can be used to show that the exponent  $p = \frac{2(n+1)}{n+3}$  is the best possible. Indeed, non-vanishing Gaussian curvature implies that the hypersurface has contact of order two with its tangent plane at every point. Let  $f_{\delta}(x) = g(\delta^{-1}x, \delta^{-2}x_n)$ , where  $x = (x_1, \dots, x_{n-1})$ , and g is the characteristic function of the rectangle with sides  $(1, \dots, 1, C)$ , C large, with the long side normal to the hypersurface.

It is not hard to check that  $||f_{\delta}||_p \approx \delta^{(1-\frac{1}{p})(n+1)}$ , whereas  $||\Re f_{\delta}||_2 \approx \delta^{\frac{n-1}{2}}$ . The comparison yields  $p \leq \frac{2(n+1)}{n+3}$ . It should be noted that the above example does not verify even a special case of ques-

It should be noted that the above example does not verify even a special case of question A. For example, the above argument does not prove that if the estimate (3) holds with  $p = \frac{2(n+1)}{n+3}$ , then the estimate (2) holds with  $r = \frac{n-1}{2}$ . We will show (see Theorem 2 below) that this is indeed the case.

The sharpness of the estimate (5) can also be verified in some cases. By testing *T* against a characteristic function of a small ball it is not hard to check that if *T* is bounded from  $L^p(\mathbb{R}^n)$  to  $L^q(\mathbb{R}^n)$ , then  $(\frac{1}{p}, \frac{1}{q})$  must be contained in the triangle with the endpoints (0,0),

(1, 1), and  $(\frac{n}{n+1}, \frac{1}{n+1})$ . However, as before this does not prove that if the estimate (5) holds with  $p = \frac{n+1}{n}$ , then the estimate (2) holds with  $r = \frac{n-1}{2}$ . We will show (see Theorem 5 below) that this is indeed the case.

#### 2 Statement of Results

**Theorem 1** Let  $S = \{(x, x_n) \in \mathbb{R}^n : x_n = \Phi(x)\}$ , where  $x = (x_1, \ldots, x_{n-1})$ ,  $\Phi$  is a smooth function which does not vanish on a set of positive measure,  $\Phi(0, \ldots, 0) = 0$ , and  $\nabla \Phi(0, \ldots, 0) = (0, \ldots, 0)$ . Suppose that the estimate (3) holds. Let G be any continuous function which does not vanish on a set of positive measure satisfying  $G(0, \ldots, 0) = 0$ . Then

(7) 
$$(|G(\delta)|)^r \ge CR(\delta)^{r+1} |\delta_1 \delta_2 \cdots \delta_{n-1}|,$$

where  $R(\delta) = |\{x \in [-1,1]^{n-1} : |\Phi(\delta_1 x_1, \dots, \delta_{n-1} x_{n-1})| \le C|G(\delta)|\}|.$ 

**Remark** If  $G(\delta)$  is chosen to be  $\Phi(\delta)$ , and  $\Phi$  is increasing in each variable separately, Theorem 1 says that the estimate (3) implies that  $(|\Phi(\delta)|)^r \ge C\delta_1\delta_2\cdots\delta_{n-1}$ . The same estimate would be true, of course, if we just assume that  $R(\delta)$  is bounded below, which is a much weaker assumption. To prove Theorem 2, Theorem 3, Theorem 5, and Theorem 6 below we shall use Theorem 1 with

(8) 
$$G(\delta) = \sup_{\{x \in [-1,1]^{n-1}\}} |\Phi(x_1\delta_1, \dots, x_{n-1}\delta_{n-1})|.$$

**Theorem 2** Suppose that the estimate (3) holds with  $p = \frac{2(n+1)}{n+3}$ . Then the hypersurface S has everywhere non-vanishing Gaussian curvature.

**Theorem 3** Suppose that the estimate (3) holds with  $p \ge \frac{2n+k-2}{6}$ . Then the hypersurface S has at least k non-vanishing principal curvatures at each point.

**Remark** The conclusion of Theorem 3 can be motivated as follows. If the hypersurface has exactly *k* non-vanishing principal curvatures at a point, then after perhaps applying a rotation we can write it as a graph of the function  $x_1^2 + \cdots + x_k^2 + A(x)$ , where *A* is a higher order remainder. It is not hard to believe that the best possible estimate (2) is obtained if  $A(x) = |x''|^3$ , where  $x'' = (x_{k+1}, \dots, x_{n-1})$ . This gives us the estimate (2) with  $r = \frac{k}{2} + \frac{n-1-k}{3}$ . The conclusion of Theorem 3 is the consequence of the fact that  $\frac{2(r+1)}{r+2} = \frac{2n+k-2}{6}$ .

**Theorem 4** Let  $\delta y = (\delta_1 y_1, \dots, \delta_{n-1} y_{n-1})$  and  $g_{\delta}(s) = |\{y \in \operatorname{supp}(\psi) : |s - |\Phi(\delta y)/\Phi(\delta)|| \leq C\}|$ . Suppose that the estimate (5) holds. Then for  $|\delta|$  sufficiently small,

(9) 
$$\left(\left|\Phi(\delta)\right|\right)^{r} \ge CP_{\delta} \|g_{\delta}\|_{L^{p'}(ds)}.$$

**Theorem 5** Suppose that the estimate (5) holds with  $r = \frac{n-1}{2}$ . Let  $S = \{(x, x_n) : x \in \text{supp}(\psi), x_n = \Phi(x)\}$ . Then S has everywhere non-vanishing Gaussian curvature.

**Theorem 6** Suppose that the estimate (5) holds with  $p \ge \frac{2n+k+4}{2n+k+1}$ . Then the hypersurface has at least k non-vanishing principal curvatures at each point.

(See the remark after Theorem 3 for the motivation of the conclusion of Theorem 6).

## 3 Proof of Theorem 1

Let  $\delta x = (\delta_1 x_1, \dots, \delta_{n-1} x_{n-1})$ , and  $\delta^{-1} x = (\delta_1^{-1} x_1, \dots, \delta_{n-1}^{-1} x_{n-1})$ . Let  $\hat{f}_{\delta}(x, x_n) = g(\delta^{-1} x, \frac{x_n}{|G(\delta)|})$ , where *g* is the characteristic function of a rectangle with sides of length  $(1, 1, \dots, 1, C)$ . Let  $P_{\delta} = |\delta_1 \delta_2 \cdots \delta_{n-1}|$ . It is not hard to see that

(10) 
$$\|f_{\delta}\|_{p} \approx (P_{\delta}|G(\delta)|)^{(1-1/p)}.$$

On the other hand,

(11) 
$$\|\mathcal{R}f_{\delta}\|_{2}^{2} = \int \left|g\left(\delta^{-1}x, \frac{\Phi(x)}{|G(\delta)|}\right)\right|^{2} dx = P_{\delta} \int \left|g\left(x, \frac{\Phi(\delta x)}{|G(\delta)|}\right)\right|^{2} dx \approx CP_{\delta}R(\delta),$$

where  $R(\delta)$  is defined in the statement of the theorem.

Comparing the estimates (10) and (11) we see that (3) can hold only if

(12) 
$$(|G(\delta)|)^r \ge CP_{\delta}R^{r+1}(\delta),$$

for  $|\delta|$  sufficiently small. This completes the proof of Theorem 1.

## 4 Proof of Theorem 2

Let  $G(\delta) = \sup_{\{x \in [-1,1]^{n-1}\}} |\Phi(\delta_1 x_1, \dots, \delta_{n-1} x_{n-1})|$ . It follows that  $R(\delta) \equiv 1$ , and so

(13) 
$$(G(\delta))^r \ge CP_{\delta}$$

where  $r = \frac{n-1}{2}$  by assumption.

After perhaps applying a rotation, we can use Taylor's theorem to write

(14) 
$$\Phi(x) = a_1 x_1^2 + a_2 x_2^2 + \dots + a_k x_k^2 + A(x),$$

where A(x) is a higher order remainder term, and  $k \le n - 1$ . If k = n - 1, then in a sufficiently small neighborhood of the origin the determinant of the Hessian matrix of  $\Phi$  never vanishes, which would verify the claim of Theorem 2. We shall henceforth assume that k < n - 1.

It is not hard to check that

(15) 
$$(G(\delta))^{\frac{n-1}{2}} \le (a_1 \delta_1^2 + \dots + a_k \delta_k^2 + C |\delta|^3)^{\frac{n-1}{2}},$$

 $|\delta|$  small.

We must show that the estimate (13) cannot hold if k < n - 1. It suffices to show that the right hand side of (15) is not bounded below by  $CP_{\delta}$ . We may assume that A(x) is not

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identically 0, and that A(x) depends on  $x_{n-1}$ , for otherwise the contradiction is immediate. Let  $\delta_j = \delta_{n-1}^{\frac{3}{2}}$ . If the right hand side were bounded below by  $CP_{\delta}$ , we could use the fact that A(x) is a higher order remainder term to force an inequality

(16) 
$$|\delta_{n-1}|^{\frac{3(n-1)}{2}} \ge C|\delta_{n-1}|^{\frac{3n-4}{2}}$$

 $\delta_{n-1}$  small, which is not true. This shows that the estimate (8) cannot hold unless k = n-1. This implies that there exists a small neighborhood of the origin where *S* has non-vanishing Gaussian curvature. This completes the proof.

#### 5 Proof of Theorem 3

We must show that if  $\Phi$  is as in the estimate (14) above, with *k* denoting the number of non-vanishing principal curvatures, then the estimate

(17) 
$$(G(\delta))^r \ge CP_{\delta}$$

can only hold if  $r \leq \frac{k}{2} + \frac{n-1-k}{3} = \frac{2n+k-2}{6}$ . Let  $\delta = (\delta', \delta'')$ , where  $\delta' = (\delta_1, \dots, \delta_k)$ , and  $\delta'' = (\delta_{k+1}, \dots, \delta_{n-1})$ . Let  $\delta_j = |\delta''|^{\frac{3}{2}}$ . The estimate (16) cannot hold if the inequality

(18) 
$$|\delta''|^{3r} \ge C |\delta''|^{(\frac{3k}{2} + (n-1-k))}$$

is not satisfied. However, the estimate (17) can only hold if  $r \le \frac{k}{2} + \frac{n-1-k}{3} = \frac{2n+k-2}{6}$ . This completes the proof.

## 6 Proof of Theorem 4

Let  $\delta^{-1}y = (\delta_1^{-1}y_1, \dots, \delta_{n-1}^{-1}y_{n-1})$ . Let f denote the characteristic function of the rectangle with sides of length  $(1, 1, \dots, 1, C)$ , C large. Let  $\tau_{\delta}f(x, x_n) = f(\delta x, |\Phi(\delta)|x_n)$ , and  $\tau_{\delta}^{-1}f(x, x_n) = f(\delta^{-1}x, |\Phi(\delta)|^{-1}x_n)$ . Let  $f_{\delta}(x, x_n) = \tau_{\delta}^{-1}f(x, x_n)$ . Let

(19) 
$$T_{\delta}f(x,x_n) = \int f(x-y,x_n-\Phi(y))\psi(\delta^{-1}y)\,dy.$$

After making a change of variables we see that

(20) 
$$T_{\delta}f_{\delta}(x,x_n) = P_{\delta}\tau_{\delta}^{-1}T_{\delta}^*f(x,x_n),$$

where

(21) 
$$T_{\delta}^* f(x, x_n) = \int f(x - y, x_n - \Phi(\delta y) / |\Phi(\delta)|) \psi(y) \, dy.$$

It is not hard to see that

(22) 
$$\|f_{\delta}\|_{p} \approx P_{\delta}^{\frac{1}{p}} \left(|\Phi(\delta)|\right)^{\frac{1}{p}}.$$

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Also,

(23)

$$\|T_{\delta}f_{\delta}\|_{p'} = \|P_{\delta}\tau_{\delta}^{-1}T_{\delta}^{*}f\|_{p'} = P_{\delta}P_{\delta}^{\frac{1}{p'}} \left(|\Phi(\delta)|\right)^{\frac{1}{p'}} \|T_{\delta}^{*}f\|_{p'} \approx P_{\delta}P_{\delta}^{\frac{1}{p'}} \left(|\Phi(\delta)|\right)^{\frac{1}{p'}} \|g_{\delta}\|_{L^{p'}(ds)},$$

where  $g_{\delta}$  is defined above.

Comparing the estimates (22) and (23) yields the assertion of the theorem.

### 7 Proofs of Theorem 5 and Theorem 6

Let  $G(\delta) = \sup_{x \in [-1,1]^{n-1}} |\Phi(\delta x)|$ . The proof of Theorem 4 shows that if the estimate (5) holds then

(24) 
$$\left(G(\delta)\right)^r \ge CP_\delta$$

The proofs of Theorem 5 and Theorem 6 now follow in the same way as the proofs of Theorem 2 and Theorem 3.

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Department of Mathematics Georgetown University Washington, DC 20057 USA email: iosevich@math.georgetown.edu Department of Mathematics Wright State University Dayton, OH 45435 USA email: gzlu@math.wright.edu

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