

New in Robotics from Cambridge University Press

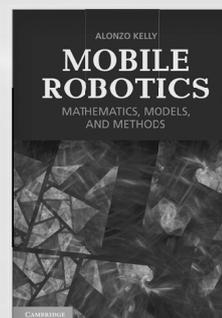
Mobile Robotics

Mathematics, Models, and Methods

Alonzo Kelly

Mobile Robotics offers comprehensive coverage of the essentials of the field suitable for both students and practitioners. Adapted from Alonzo Kelly's graduate and undergraduate courses, the content of the book reflects current approaches to developing effective mobile robots. Professor Kelly adapts principles and techniques from the fields of mathematics, physics, and numerical methods to present a consistent framework in a notation that facilitates learning and highlights relationships between topics. This text was developed specifically to be accessible to senior level undergraduates in engineering and computer science, and includes supporting exercises to reinforce the lessons of each section. Practitioners will value Kelly's perspectives on practical applications of these principles. Complex subjects are reduced to implementable algorithms extracted from real systems wherever possible, to enhance the real-world relevance of the text.

\$99.00: Hardback: 978-1-107-03115-9: 808 pp.

**Social Media Intelligence**

Wendy W. Moe and David A. Schweidel

As consumers, we turn to the public arena of social media to share our opinions and learn about the opinions of others. Fortune 500 companies, political campaigns, government agencies and many other organizations constantly monitor social media to gauge public opinion. This book explains how opinions are formed, what affects the opinions posted online and how organizations can use social media to inform their strategies.

\$50.00: Hardback: 978-1-107-03120-3: 200 pp.

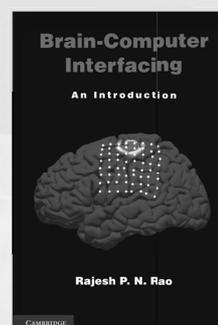
**Brain-Computer Interfacing**

An Introduction

Rajesh P. N. Rao

This introduction to the field of brain-computer interfacing is designed as a textbook for upper-level undergraduate and first-year graduate courses in neural engineering or brain-computer interfacing for students from a wide range of disciplines. It can also be used as a reference by neuroscientists, computer scientists, engineers, and medical practitioners.

\$80.00: Hardback: 978-0-521-76941-9: 356 pp.

**Methods of Argumentation**

Douglas Walton

Argumentation, which can be abstractly defined as the interaction of different arguments for and against some conclusion, is an important skill for everyday life, law, science, politics, and business. This book, written by a leading expert, and based on the latest research, shows how to apply methods of argumentation to a range of interesting examples. Written in a nontechnical style, the book explains what you most need to know by applying the methods to many real examples of arguments found in everyday conversational exchanges and legal argumentation.

\$95.00: Hardback: 978-1-107-03930-8: 322 pp.

\$32.99: Paperback: 978-1-107-67733-3



Prices subject to change.

www.cambridge.org/computerscience

800.872.7423

 @cambUP_maths



CAMBRIDGE
UNIVERSITY PRESS

CAMBRIDGE

JOURNALS

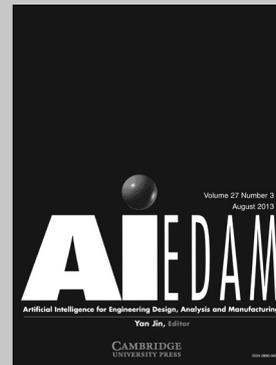
AI EDAM

Artificial Intelligence for Engineering Design, Analysis and Manufacturing

Editor

Yan Jin, *University of Southern California, USA*

AI EDAM is a journal for engineers and designers who see AI technologies as powerful means for solving difficult engineering problems; and for researchers in AI and computer science who are interested in applications of AI and in the theoretical issues that arise from such applications. The journal publishes original articles about significant theory and applications based on the most up-to-date research in all branches and phases of engineering. Suitable topics include: analysis and evaluation; selection; configuration and design; manufacturing and assembly; and concurrent engineering.



AI EDAM

is available online at:
<http://journals.cambridge.org/aie>

To subscribe contact Customer Services

in Cambridge:

Phone +44 (0)1223 326070
Fax +44 (0)1223 325150
Email journals@cambridge.org

in New York:

Phone +1 (845) 353 7500
Fax +1 (845) 353 4141
Email
subscriptions_newyork@cambridge.org

Free email alerts

Keep up-to-date with new
material – sign up at
journals.cambridge.org/register

For free online content visit:
<http://journals.cambridge.org/aie>



CAMBRIDGE
UNIVERSITY PRESS

CAMBRIDGE

JOURNALS

Combinatorics, Probability & Computing

Editor-in-Chief

Béla Bollobás, *DPMMS, Cambridge, UK; University of Memphis, USA*

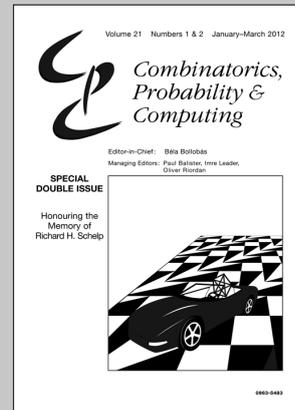
Published bimonthly, *Combinatorics, Probability & Computing* is devoted to the three areas of combinatorics, probability theory and theoretical computer science. Topics covered include classical and algebraic graph theory, extremal set theory, matroid theory, probabilistic methods and random combinatorial structures; combinatorial probability and limit theorems for random combinatorial structures; the theory of algorithms (including complexity theory), randomised algorithms, probabilistic analysis of algorithms, computational learning theory and optimisation.

Price information

is available at: <http://journals.cambridge.org/cpc>

Free email alerts

Keep up-to-date with new material – sign up at
<http://journals.cambridge.org/cpc-alerts>



Combinatorics, Probability & Computing

is available online at:

<http://journals.cambridge.org/cpc>

To subscribe contact Customer Services

in Cambridge:

Phone +44 (0)1223 326070

Fax +44 (0)1223 325150

Email journals@cambridge.org

in New York:

Phone +1 (845) 353 7500

Fax +1 (845) 353 4141

Email

subscriptions_newyork@cambridge.org

For free online content visit:
<http://journals.cambridge.org/cpc>



CAMBRIDGE
UNIVERSITY PRESS

CAMBRIDGE

JOURNALS

Journal of Functional Programming

Editors-in-Chief

Matthias Felleisen, *Northeastern University, USA*
Benjamin C. Pierce, *University of Pennsylvania, USA*

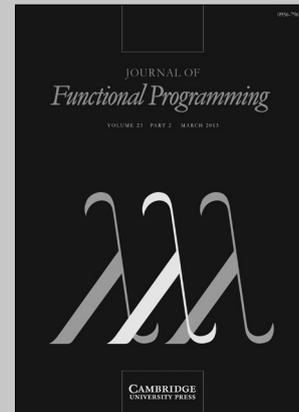
The *Journal of Functional Programming* is the only journal devoted solely to the design, implementation, and application of functional programming languages, spanning the range from mathematical theory to industrial practice. Topics covered include functional languages and extensions, implementation techniques, reasoning and proof, program transformation and synthesis, type systems, type theory, language-based security, memory management, parallelism and applications. The journal is of interest to computer scientists, software engineers, programming language researchers and mathematicians interested in the logical foundations of programming.

Price information

is available at: <http://journals.cambridge.org/jfp>

Free email alerts

Keep up-to-date with new material – sign up at
<http://journals.cambridge.org/jfp-alerts>



Journal of Functional Programming

is available online at:
<http://journals.cambridge.org/jfp>

To subscribe contact Customer Services

in Cambridge:
Phone +44 (0)1223 326070
Fax +44 (0)1223 325150
Email journals@cambridge.org

in New York:
Phone +1 (845) 353 7500
Fax +1 (845) 353 4141
Email
subscriptions_newyork@cambridge.org

For free online content visit:
<http://journals.cambridge.org/jfp>



CAMBRIDGE
UNIVERSITY PRESS

CAMBRIDGE

JOURNALS

The Knowledge Engineering Review

Editors-in-Chief

Peter McBurney, *University of Liverpool, UK*

Simon Parsons, *Brooklyn College, City University of New York, USA*

The Knowledge Engineering Review is committed to the development of the field of artificial intelligence and the clarification and dissemination of its methods and concepts. *KER* publishes analyses – high quality surveys providing balanced but critical presentations of the primary concepts in an area; technical tutorials – detailed introductions to an area; application and country surveys commentaries and debates; book reviews; and a popular ‘from the journals’ section, providing the contents of current journals in theoretical and applied artificial intelligence.

Price information

is available at: <http://journals.cambridge.org/ker>

Free email alerts

Keep up-to-date with new material – sign up at <http://journals.cambridge.org/ker-alerts>



The Knowledge Engineering Review

is available online at:
<http://journals.cambridge.org/ker>

To subscribe contact Customer Services

in Cambridge:

Phone +44 (0)1223 326070

Fax +44 (0)1223 325150

Email journals@cambridge.org

in New York:

Phone +1 (845) 353 7500

Fax +1 (845) 353 4141

Email

subscriptions_newyork@cambridge.org

For free online content visit:
<http://journals.cambridge.org/ker>



CAMBRIDGE
UNIVERSITY PRESS

CAMBRIDGE

JOURNALS

Mathematical Structures in Computer Science

Editor-in-Chief

G. Longo, *CNRS and Ecole Normale Supérieure, Paris, France*

Mathematical Structures in Computer Science is a journal of theoretical computer science which focuses on the application of ideas from the structural side of mathematics and mathematical logic to computer science. The journal aims to bridge the gap between theoretical contributions and software design, publishing original papers of a high standard and broad surveys with original perspectives in all areas of computing, provided that ideas or results from logic, algebra, geometry, category theory or other areas of logic and mathematics form a basis for the work.

Price information

is available at: <http://journals.cambridge.org/msc>

Free email alerts

Keep up-to-date with new material – sign up at <http://journals.cambridge.org/msc-alerts>



Mathematical Structures in Computer Science is available online at: <http://journals.cambridge.org/msc>

To subscribe contact Customer Services

in Cambridge:

Phone +44 (0)1223 326070
Fax +44 (0)1223 325150
Email journals@cambridge.org

in New York:

Phone +1 (845) 353 7500
Fax +1 (845) 353 4141
Email subscriptions_newyork@cambridge.org

For free online content visit: <http://journals.cambridge.org/msc>



CAMBRIDGE
UNIVERSITY PRESS

Instructions for contributors

Robotica aims to be an outlet for publication of original papers of the highest quality in the field of Robotics and closely related areas. This includes: novel robotic mechanism and actuator design; robot kinematics, dynamics and control; computer vision; sensor fusion; teleoperation and haptic interfaces; robot motion planning; and artificial intelligence. In addition, papers that apply techniques from Robotics to other fields are also welcome. Examples include dynamics and control models applied to biological systems, the description of implementations of robots in factories, service and agricultural settings, and general mechatronic design. Works may be theoretical, computational or experimental, or some combination. Both short papers (rapid communications), and longer archival papers are welcome. Proposals for special issues on topics of current interest are welcome, and can be submitted via email to the editor.

Authors are urged to ensure that their papers are written clearly and attractively, in order that their work will be readily accessible to readers. Manuscripts must be written in English. *Robotica* employs a rigorous peer-review process whereby all submitted manuscripts are sent to recognized experts in their subjects for evaluation. The Editor's decision on the suitability of a manuscript for publication is final. Manuscripts, whether accepted or rejected, will not be returned to authors.

Submission of manuscripts

Manuscripts for consideration by *Robotica* should be submitted electronically, using the Manuscript Central System, via <http://mc.manuscriptcentral.com/cup/robotica>. This system will allow authors to benefit from faster review and earlier, online publication. The system will accept PDF files; most other file types will be automatically converted directly into PDF. Source files are required for any paper accepted for publication. Authors who are unable to submit online should contact the Editorial Office (gregc@jhu.edu) for assistance.

Submission of a paper is taken to imply that it has not been previously published and that it is not being considered for publication elsewhere. Upon acceptance of a paper, the author will be asked to transfer copyright to the publisher. Authors are responsible for obtaining written permission from the copyright owners to reprint any previously published material included in their article.

Layout of manuscripts

Text should be double spaced throughout, on one side of the paper, allowing generous margins on all sides of the paper. Please avoid footnotes if possible. Papers should begin with an abstract of not more than 100 words and should end with a brief concluding section. The title and section headings should be concise and descriptive. All measurements should be given in SI units. On acceptance of a manuscript, authors are asked to send the electronic source file of the final version together with a PDF copy produced using the same file. The publisher reserves the right to typeset material by conventional means if an author's file proves unsatisfactory.

Illustrations

Figures should be composed to occupy a single column (80mm) or two columns (166mm) after reduction. The preferred format for figure files is .eps or .tiff at resolution 1200 dpi for lines, 600 dpi for greyscale and 300 dpi for colour (which preferably should also be in CMYK – cyan magenta yellow black – format). However,

most standard image formats such as pct, ppm, png, psd, Word, ppt, CorelDraw, ChemDraw, AutoCAD can also be used, but not customized output of software not designed for publishing purposes such as Matlab, nor PDF. Figures to be printed in black and white must be submitted as black and white files.

Figures should be numbered consecutively, with Arabic numerals, have descriptive captions, and be mentioned in the text. A list of captions should be attached separately, and as far as possible, information relating to a figure should be placed in the caption rather than on the figure. Each figure should be clearly numbered. Photographs should be the same size as they will appear in the journal and should be selected to fit neatly into one column (80 mm) or two columns (166 mm). Photographs should be clearly identified and numbered as for line drawings.

Tables

Tables should be presented on separate sheets. A descriptive title should be given to each table. If possible, very wide tables should be avoided. Tables should be numbered consecutively in Roman numerals. Exceptionally lengthy tables may be summarized for publication with a note that fuller details can be obtained from the authors.

Equations

Mathematical equations should be typewritten, with subscripts and superscripts clearly indicated. All mathematical symbols will be set in italics unless otherwise indicated: symbols or letters to be set in Roman (upright) type should be marked clearly.

References

In the text, references are indicated by superior Arabic numbers (without brackets), and should be confined to published work that is directly pertinent. References should be listed at the end of the paper in numerical order. Authors' initials should precede their names: cited article titles should be quoted in full, enclosed in quotation marks; and abbreviations of journal names should follow the style of Chemical Abstracts or Physical Abstracts, and be underlined for italics:

P.W. Anderson, "More is different" *Science* **177**, 393-399 (1972);
C.V. Negoita, *Fuzzy Systems* (Abacus Press, Tunbridge Wells, UK, 1980).

Citations such as 'personal communication', 'unpublished work', etc., are not acceptable as numbered references but can be included in parenthesis in the text. Do not use summaries as references.

Proof Reading

The corresponding author will receive PDF copies of page proofs for final proofreading. Only typographical or factual errors may be changed at proof stage. The publisher reserves the right to charge authors for correction of non-typographical errors. Authors are requested to return proofs within 48 hours by airmail. No page charge is made.

Offprints

No paper offprints are provided, but the corresponding author will be sent the pdf of the published article. Print offprints may be purchased at extra cost at proof stage.

© CAMBRIDGE UNIVERSITY PRESS 2013

Cambridge University Press
The Edinburgh Building, Cambridge CB2 8RU, United Kingdom
32 Avenue of the Americas, New York, NY 10013-2473, USA
477 Williamstown Road, Port Melbourne, VIC 3207, Australia
Ruiz de Alarcón 13, 28014, Madrid, Spain
Dock House, The Waterfront, Cape Town 8001, South Africa

Printed in the UK by Bell & Bain Ltd, Glasgow

ROBOTICA

Volume 31 Part 8 December 2013

- Randomized path planning with preferences in highly complex dynamic environments, **Khaled Belghith, Froduald Kabanza and Leo Hartman** 1195
- Multibody modeling and vibration testing of 3R planar manipulators: effects of flexible installation frames, **Emiliano Mucchi, Stefano Fiorati, Raffaele Di Gregorio and Giorgio Dalpiaz** 1209
- A passive dynamic walking model with Coulomb friction at the hip joint, **Wenhao Guo, Tianshu Wang and Qi Wang** 1221
- Regressor-free prescribed performance robot tracking, **Y. Karayiannidis and Z. Doulgeri** 1229
- Faulty robot rescue by multi-robot cooperation, **Gyuhoo Eoh, Jeong S. Choi and Beom H. Lee** 1239
- A finger skill transfer system using a multi-fingered haptic interface robot and a hand motion image, **Takahiro Endo, Mana Kobayashi and Haruhisa Kawasaki** 1251
- Artificial moment method using attractive points for the local path planning of a single robot in complicated dynamic environments, **Wang-bao Xu, Jie Zhao, Xue-bo Chen and Ying Zhang** 1263
- Active control of flexible one-link manipulators using wavelet networks, **V. I. Gervini, E. M. Hemerly and S. C. P. Gomes** 1275
- Path planning for simple wheeled robots: sub-Riemannian and elastic curves on $SE(2)$, **Craig Maclean and James D. Biggs** 1285
- A globally converging algorithm for adaptive manipulation and trajectory following for mobile robots with serial redundant arms, **Paul Moubarak and Pinhas Ben-Tzvi** 1299
- Effect of compliance location in series elastic actuators, **Jonathon W. Sensinger, Lawrence E. Burkart, Gill A. Pratt, and Richard F. ff. Weir** 1313
- Design and operation of a 2-DOF leg-wheel hybrid robot, **Erika Ottaviano and Pierluigi Rea** 1319
- A real-time motion planning algorithm for a hyper-redundant set of mechanisms, **Nir Shvalb, Boaz Ben Moshe and Oded Medina** 1327
- A rat-like robot for interacting with real rats, **Qing Shi, Hiroyuki Ishii, Shinichi Kinoshita, Shinichiro Konno, Atsuo Takanishi, Satoshi Okabayashi, Naritoshi Iida and Hiroshi Kimura** 1337
- Leader-follower-based dynamic trajectory planning for multirobot formation, **Shuang Liu and Dong Sun** 1351
- Orientation-singularity analysis and orientationability evaluation of a special class of the Stewart-Gough parallel manipulators, **Yi Cao, Clément Gosselin, Hui Zhou, Ping Ren and Weixi Ji** 1361

Robotica now accepts submissions via Manuscript Central
Go to <http://mc.manuscriptcentral.com/cup/robotica>

Cambridge Journals Online
For further information about this journal
please go to the journal website at:
journals.cambridge.org/rob



MIX
Paper from
responsible sources
FSC® C007785

CAMBRIDGE
UNIVERSITY PRESS