



RESEARCH ARTICLE

Semisimple groups interpretable in various valued fields

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Abstract

We study infinite groups interpretable in power bounded T -convex, V -minimal or p -adically closed fields. We show that if G is an interpretable definably semisimple group (i.e., has no definable infinite normal abelian subgroups) then, up to a finite index subgroup, it is definably isogenous to a group $G_1 \times G_2$, where G_1 is a K -linear group and G_2 is a \mathbf{k} -linear group. The analysis is carried out by studying the interaction of G with four distinguished sorts: the valued field K , the residue field \mathbf{k} , the value group Γ , and the closed 0-balls K/\mathcal{O} .

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1. Introduction

We continue the study of groups interpretable in three classes of tame valued fields: p -adically closed fields (and their analytic expansions), power bounded T -convex expansions of o-minimal real closed fields, and V -minimal expansions of algebraically closed valued fields of equi-characteristic 0.

The tameness conditions in each of these classes have significant geometric implications on definable sets. For example, they imply a well behaved notion of dimension, generic differentiability of definable functions $f : K^n \rightarrow K$ with corresponding versions of Taylor's approximation theorem, and more (see,

for example, [6]). For definable groups, expanding on Pillay's work in the o-minimal context [25] (and see also [26]), this gives rise to a rudimentary Lie theory ([1]).

A group G is *interpretable* in a structure \mathcal{K} if its universe is the quotient of a definable set by a definable equivalence relation and multiplication is part of the induced structure. The powerful geometric tools described above are not directly available for the study of interpretable groups. Our general program aims, therefore, to exploit those tools (as well as tameness of the value group Γ , and the residue field \mathbf{k}) to give structure theorems for interpretable groups using groups that are better understood by virtue of being definable in a small collection of well studied sorts.

In our previous works, [13] and [12], we showed that any group G interpretable in \mathcal{K} has 'infinitesimal' type-definable subgroups definably isomorphic to groups that are (type)-definable in one of the four *distinguished* sorts: the valued field sort K , the value group, the residue field (when infinite) and the sort of closed 0-balls K/\mathcal{O} . Our strategy here is to understand interpretable groups using these type-definable groups and their construction.

In [12], we used this analysis to describe all interpretable fields in those families of structures. Here, we use it to study *definably semisimple groups* – namely, groups which contain no infinite definable normal abelian subgroups. Our main theorem (Theorem 10.3 below) is:

Theorem 1. *Let \mathcal{K} be either a power bounded T -convex field, a V -minimal field or a p -adically closed field. Let G be an interpretable definably semisimple group in \mathcal{K} . Then there exists a finite normal subgroup $N \trianglelefteq G$ and two normal subgroups $H_1, H_2 \trianglelefteq G/N$, such that*

- (1) $H_1 \cap H_2 = \{e\}$, H_1 and H_2 centralize each other and $H_1 \cdot H_2$ has finite index in G/N .
- (2) H_1 is definably isomorphic to a subgroup of $\mathrm{GL}_n(\mathbf{k})$.
- (3) H_2 is definably semisimple and definably isomorphic to a subgroup of $\mathrm{GL}_n(K)$.

It may be worth pointing out, with regard to the formulation of the above theorem, that in our setting, definable semisimplicity is preserved under finite quotients (Corollary 2.22). We make use of this several times in the proof of the theorem.

We have been informed by J. Gismatullin, I. Halupczok and D. Macpherson that in a recent unpublished work [10], they characterize simple groups *definable* in certain Henselian valued fields of characteristic 0 (covering the classes of fields discussed in the present paper). Their work seems to combine with the present one to characterize definably simple groups interpretable in our settings.

Our proof goes through a case-by-case reduction to one of the four distinguished sorts. This is based on [13], where we showed that after modding out by a finite subgroup, G is *locally strongly internal* to one of the distinguished sorts D ; namely, there exists an infinite definable set $X \subseteq G$ and a definable injection $f : X \rightarrow D^k$, for some k .

The main obstacle is to eliminate the cases when $D = \Gamma, K/\mathcal{O}$. In Proposition 6.1, we show that if G is locally strongly internal to Γ , then it contains a definable normal finite index subgroup whose center is infinite, which prohibits G from being definably semisimple. A more intricate result, Proposition 7.1, allows us to conclude that a definably semisimple group G cannot be locally strongly internal to K/\mathcal{O} .

When G is locally strongly internal to K , we use local differentiability of definable functions with respect to K , and basic Lie theory over K , to associate to G an adjoint representation over K . When $D = \mathbf{k}$, we either use similar methods, in the T -convex case, or use the theory of groups of finite Morley rank, in the V -minimal case, to complete the proof.

Though the statement of Theorem 1 and some of the auxiliary results often hold in all settings regardless of whether \mathcal{K} is p -adically closed, power bounded T -convex or V -minimal, some of the proofs depend on the specific context. For example, o-minimality of the value group plays a crucial role in our analysis of Γ -groups in the V -minimal and power bounded T -convex setting, and a rather different analysis – albeit with a similar conclusion – is needed for the p -adic case.

Remark 1.1. We note that a priori the notion of definable semisimplicity (more precisely, the existence of an infinite definable normal abelian subgroup) need not be elementary. Indeed, while the valued field sort in our settings is a geometric structure, so in particular has uniform finiteness (sometimes

called ‘elimination of \exists^∞ ’) for definable families of subsets of K^n , the same might not be true in \mathcal{K}^{eq} .

Johnson, [17], shows, in the V -minimal case, that \mathcal{K}^{eq} does eliminate \exists^∞ , and using his methods, we show the same for power bounded T -convex structures (see Section A.5). However, in the p -adically closed case, this fails in \mathcal{K}^{eq} , as neither Γ nor K/\mathcal{O} have uniform finiteness. Nevertheless, one of the consequences of the present work is that definable semisimplicity is indeed an elementary property in all cases.

Remark 1.2. In the power bounded T -convex case, our work makes use of results from James Tyne’s PhD thesis, [32], which as far as we know, have not been published elsewhere. These results, together with the work of van den Dries, [33], imply that every definable subset of K is a boolean combination of balls and intervals (first proven by Holly, [15], for real closed valued fields). In order to make the results available in print, we include in the appendix direct proofs.

Previous work We note recent work on interpretable groups in p -adically closed fields, by Johnson, [18], also together with Yao, [19], [20], and with Guerrero, [2]. Further work is needed in order to understand the relation between our methods and the model theoretic tools studied there, such as definable compactness, finitely satisfiable generics (fsg), definable f -generics (dfg), etc.

2. Preliminaries and notation

We set up some notation and terminology and review some of the basic facts concerning the main objects of interest in the present paper. Throughout, structures are denoted by calligraphic capital letters, \mathcal{M} , \mathcal{N} , \mathcal{K} etc., and their respective universes by the corresponding Latin letters, M , N and K .

Tuples from a structure \mathcal{M} are always assumed to be finite and are denoted by small Roman characters a, b, c, \dots . We apply the standard model theoretic abuse of notation writing $a \in M$ for $a \in M^{|a|}$. Variables will be denoted x, y, z, \dots with the same conventions as above. We do not distinguish notationally between tuples and variables belonging to different sort, unless some ambiguity can arise. Capital Roman letters A, B, C, \dots usually denote small subsets of parameters from \mathcal{M} . As is standard in model theory, we write Ab as a shorthand for $A \cup \{b\}$. In the context of definable groups, we will, whenever confusion can arise, distinguish between – for example, $Agh := A \cup \{g, h\}$ and $A g \cdot h := A \cup \{g \cdot h\}$.

By a partial type we mean a consistent collection of formulas. Two partial types ρ_1, ρ_2 are equal, denoted $\rho_1 = \rho_2$, if they are logically equivalent (i.e., if they have the same realizations in some sufficiently saturated elementary extension).

All the definable sets we shall consider here have finite dp-rank, whose properties (such as sub-additivity, invariance under finite-to-finite correspondences, invariance under automorphisms etc.) we use freely. See the preliminaries sections of [12],[13] for a more detailed discussion.

2.1. Valued fields

Throughout, \mathcal{K} denotes an expansion of a valued field of characteristic 0 in a language \mathcal{L} expanding the language of valued rings. We assume \mathcal{K} to be $(|\mathcal{L}| + 2^{\aleph_0})^+$ -saturated.

Unless specifically written otherwise, we will always work in \mathcal{K}^{eq} . **Henceforth, by ‘definable’ we mean ‘definable in \mathcal{K}^{eq} using parameters’, unless specifically mentioned otherwise.** In particular, we shall not use ‘interpretable’ anymore. A more detailed review of standard definitions and notation can be found in [13, §2].

For any valued field (K, v) , we let \mathcal{O} denote its valuation ring, \mathfrak{m} its maximal ideal and $\mathbf{k} := \mathcal{O}/\mathfrak{m}$ the residue field. The value group is denoted Γ . In case of possible ambiguity, we may, for the sake of clarity, add a subscript (e.g., \mathcal{O}_K) to the above notation.

A closed ball in K is a set of the form $B_{\geq \gamma}(a) := \{x \in K : v(x - a) \geq \gamma\}$, and similarly, $B_{> \gamma}(a)$ denotes the open ball of (valuative) radius γ around a . We will use the fact that v descends naturally

to $K/\mathcal{O} \setminus \{0\}$ (by $v(a + \mathcal{O}) := v(a)$ for any $a \notin \mathcal{O}$), and use the same notation $B_{>\gamma}(x)$ and $B_{\geq\gamma}(x)$ for $x \in K/\mathcal{O}$ in the obvious way. We will, however, reserve **the term ‘ball’ in K/\mathcal{O} , when \mathcal{K} is p -adically closed, only to such sets where $\gamma < \mathbb{Z}$** . For $a = (a_1, \dots, a_n) \in K$ (or in $(K/\mathcal{O})^n$), we set $v(a) = \min_i \{v(a_i)\}$. A ball in K^n (or in $(K/\mathcal{O})^n$) is an n -fold product of K -balls (or (K/\mathcal{O}) -balls) of **equal radii**.

When \mathcal{K} is p -adically closed, it is elementarily equivalent to some finite extension \mathbb{F} of \mathbb{Q}_p . By saturation, we may assume that (K, v) is an elementary extension of (\mathbb{F}, v) . Since its value group $\Gamma_{\mathbb{F}}$ is isomorphic to \mathbb{Z} , as ordered abelian groups, we identify $\Gamma_{\mathbb{F}}$ with \mathbb{Z} and view it as a prime (and minimal) model for Γ . We denote \mathbb{Z}_{Pres} the structure $(\mathbb{Z}, +, <)$.

2.2. The setting

Unless otherwise stated, \mathcal{K} is a saturated expansion of a valued field of one of three types (see [13] for definitions and more details):

- A V -minimal expansion of an algebraically closed valued field of residue characteristic 0.
- A T -convex expansion of a real closed valued field, for an o-minimal power bounded theory T .
- A p -adically closed field.

Remark 2.1. Our proof for the p -adically closed case works, as written, in the context of P -minimal 1-h-minimal fields with definable Skolem functions in the valued field sort. These include models of the theory of \mathbb{Q}_p^{an} , the expansion of \mathbb{Q}_p (or a finite extension thereof) by all convergent power series $f : \mathcal{O}^n \rightarrow \mathbb{Q}_p$ (any n). For the sake of clarity of exposition, we stick to the p -adically closed case.

There are important similarities between the three settings. For example, in all cases, the structure \mathcal{K} is dp-minimal – namely, $\text{dp-rk}(\mathcal{K}) = 1$ – so definable sets in \mathcal{K}^{eq} have finite dp-rank. Also, in all cases, the valued field sort is a geometric structure, carrying, moreover, the structure of an SW-uniformity. The latter introduced (without the name) by Simon and Walsberg, [31]:

Definition 2.2. A dp-minimal expansion of a topological group G is an *SW-uniformity* if it supports a definable group topology, with no isolated points and such that every infinite definable subset has nonempty interior.

In [31], the underlying setting is that of a definable uniformity inducing the topology. The existence of such a uniformity is automatic in the context of topological groups with a definable basis for the topology.

There are, however, also obvious differences between the three settings. For example, the residue field is stable in the V -minimal case, o-minimal in the T -convex case and finite in the p -adic case. Thus, while the main theorems can be stated uniformly in all settings, some of the proofs will require us to specialize to the particular cases.

2.3. The distinguished sorts

As in our previous work, the analysis of definable quotients is carried out via a reduction to four *distinguished sorts*, K, Γ, \mathbf{k} and K/\mathcal{O} . They are all dp-minimal, except the finite \mathbf{k} in the p -adic case. Note that in all cases, the sorts K, Γ and K/\mathcal{O} are partially ordered and therefore unstable. However, the residue field sort is unstable only in the T -convex case (in the V -minimal case it is a pure algebraically closed field, and in the p -adic case it is finite). Thus, when proofs mention the ‘unstable sorts’, they refer to the distinguished sorts in all three cases except for \mathbf{k} in the V -minimal and p -adically closed settings.

As noted above, in all settings, the sort K is an SW-uniformity, as is Γ in the V -minimal and T -convex cases (it is, in fact, an ordered vector spaces so o-minimal) and K/\mathcal{O} in the T -convex setting (it is weakly o-minimal). However, in all cases, K/\mathcal{O} is neither a geometric structure ($\text{acl}(\cdot)$ in K/\mathcal{O} does not satisfy the Steinitz Exchange Principle) nor is it stably embedded, leading to certain complications in some proofs.

Remark 2.3. In [13, §3], we study the structure of K/\mathcal{O} in p -adically closed fields. In this context, it was helpful to work in a saturated model, expanding the language by constants for all elements of (a copy of) \mathbb{F} .

Although the saturation assumption on \mathcal{K} plays an important role in many of our proofs here, the main theorems of the present paper do not assume saturation. Thus, a copy of \mathbb{F} cannot be expected to exist in all our models (let alone be named). Whenever needed, as part of the proof, we bridge this gap in the assumptions.

2.4. Some specialized terminology

We remind some terminology from [13] that is used throughout the paper:

Assume that S is definable in \mathcal{K} and D is one of the distinguished sorts. We say that S is *locally almost strongly internal to D* if in a **sufficiently saturated elementary extension** there is a definable infinite set $X \subseteq S$ and a definable m -to-one map $f : X \rightarrow D^n$, for some $m, n \in \mathbb{N}$. The set X is then called *almost strongly internal to D* . If we can find a definable injection $f : X \rightarrow D^n$, then S is *locally strongly internal to D* and X is *strongly internal to D* . We add ‘over A ’ to all the notions above if S, X and the map f are defined over a parameter set A .

The starting point of our analysis is the following ([13, Lemma 7.3, Lemma 7.6, Lemma 7.10]):

Fact 2.4. Every definable infinite set S in \mathcal{K} is locally almost strongly internal to K, \mathbf{k}, Γ or K/\mathcal{O} .

A *D -critical subset of S* is a definable $X \subseteq S$ of maximal dp-rank that is strongly internal to D . The *D -rank*¹ of S is the dp-rank of any D -critical $X \subseteq S$. The *almost D -rank* of S is the maximal dp-rank of a definable set $X \subseteq S$ almost strongly internal to D . A set $X \subseteq S$ is *almost D -critical* if $\text{dp-rk}(X)$ is the almost D -rank of S , and the size of the fibers of some function witnessing almost strong internality of X is minimal possible, among all sets of the same dp-rank.

The set S is *D -pure* if it is locally almost strongly internal to D but not to any other distinguished sort.

Definition 2.5. Let X be an A -definable set in \mathcal{K} , $a \in X$ and $B \supseteq A$ a set of parameters.

- (1) The point a is *B -generic in X* (or, *generic in X over B*) if $\text{dp-rk}(a/B) = \text{dp-rk}(X)$.
- (2) For an A -generic $a \in X$, a set $U \subseteq X$ is a *B -generic vicinity of a in X* if $a \in U$, U is B -definable, and $\text{dp-rk}(a/B) = \text{dp-rk}(X)$ (in particular, $\text{dp-rk}(U) = \text{dp-rk}(X)$).

In order to overcome the failure of additivity of dp-rank, we introduced in [13] the notion of a *D -group*. In the present paper, this notion can be used as a black box allowing us to seamlessly refer to results from [13]. However, for the sake of completeness, we give the definition: For D one of the unstable distinguished sorts, an A -definable group G is a *D -group* if it is locally strongly internal to D and for every $X_1, X_2 \subseteq G$ strongly internal to D , with X_2 D -critical in G , both defined over some $B \supseteq A$, and for every (g, h) B -generic in $X_1 \times X_2$, we have

$$\text{dp-rk}(g/B, g \cdot h) = \text{dp-rk}(g/B).$$

We stress that, by definition, the notion of a D -group refers only to unstable D – namely, all infinite sorts in our setting except \mathbf{k} in the V -minimal case. The following fact shows that a group G almost strongly internal to an unstable sort D is close to being a D -group.

Fact 2.6 [13, Fact 4.25, Proposition 4.35]. Let G be an infinite A -definable group in \mathcal{K} locally almost strongly internal to an unstable distinguished sort D . Then there is an A -definable finite normal abelian subgroup $H \trianglelefteq G$ such that G/H is a D -group. Moreover,

- (1) The almost D -rank and the D -rank of G/H are equal (and equal to the almost D -rank of G).
- (2) H is invariant under any definable automorphism of G and is contained in any definable finite index subgroup of G .

¹In [13] this was called the D -critical rank of S .

Recall that every definable group in \mathcal{K} is almost locally strongly internal to one of the distinguished sorts; hence, the above fact applies whenever that sort is unstable.

2.5. Vicinities and infinitesimal subgroups

In this section, we recall the notion of a vicinic set and that of an infinitesimal group from [13]. Before proceeding, we clarify the relation between several acl-related notions of dimension.

Definition 2.7. For D a definable set, a parameter set A , and $a \in D^n$, denote:

- (1) $\dim_{\text{acl}}(a/A)$ the minimal length of a sub-tuple $a' \subseteq a$ such that $\text{acl}(a'A) = \text{acl}(aA)$ and
- (2) $\dim_{\text{ind}}(a/A)$ the maximal size of a sub-tuple $a' \subseteq a$ which is acl-independent over A (namely, no $a_i \in a'$ is in $\text{acl}(A \cup a' \setminus \{a_i\})$).

If acl satisfies Exchange on D , it is well known and easy to see that $\dim_{\text{acl}} = \dim_{\text{ind}}$. In general, we only have $\dim_{\text{ind}}(a/A) \geq \dim_{\text{acl}}(a/A)$. In our setting, however, more is true:

Lemma 2.8. For D a dp-minimal definable set, the following are equivalent:

- (1) For every tuple $a \in D^n$ and set A , $\dim_{\text{acl}}(a/A) = \text{dp-rk}(a/A)$.
- (2) For every tuple $a \in D^n$ and set A , $\dim_{\text{ind}}(a/A) = \text{dp-rk}(a/A)$.

Proof. By dp-minimality and sub-additivity of dp-rank $\text{dp-rk}(a/A) \leq \dim_{\text{acl}}(a/A)$, proving (2) \Rightarrow (1). For the other direction, assume (1).

Let $a' \subseteq a$ be acl-independent over A of maximal length d – namely, $d = \dim_{\text{ind}}(a/A)$. Since a' is acl-independent over A , $\dim_{\text{acl}}(a'/A) = d$, which by assumption equals $\text{dp-rk}(a'/A)$. Thus, $\text{dp-rk}(a/A) \geq \text{dp-rk}(a'/A) = d = \dim_{\text{ind}}(a/A)$, and equality of dp-rk and \dim_{ind} follows. \square

Remark 2.9. In [13], we used a slightly different definition of \dim_{acl} , that we assumed throughout, to be equal to dp-rk. It follows immediately from the lemma that under this assumption, this notion of dimension is also equal to \dim_{acl} as defined here (and thus also to \dim_{ind}).

We recall the following from [13]:

Definition 2.10. A dp-minimal set D is *vicinic* if it satisfies the following axioms:

- (A1) $\dim_{\text{acl}} = \text{dp-rk}$; that is, for any tuple $a \in D^n$ and set A , $\dim_{\text{acl}}(a/A) = \text{dp-rk}(a/A)$.
- (A2) For any sets of parameters A and B , for every A -generic elements $b \in D^n$, $c \in D^m$ and any B -generic vicinity X of b in D^n , there exists $C \supseteq A$ and a C -generic vicinity of b in X such that $\text{dp-rk}(b, c/A) = \text{dp-rk}(b, c/C)$.

By [13, Fact 4.7], all the unstable distinguished sorts in our settings are vicinic. Throughout this subsection, unless specifically stated otherwise, we let D be one of them. Given a definable D -group G in \mathcal{K} , the main technical result of [13] is the construction of the infinitesimal type-definable subgroup ν_D . To achieve this, we introduce the notion of D -sets (in G). For completeness, we remind the somewhat technical definition. Note, however, that we do not give the original definition; we switch the original formulation of ‘minimal fibers’ with an equivalent one (see [13, Remark 4.12]). The fine details of the definition are unimportant for us here:

Definition 2.11 [13, Definition 4.16]. A definable set $X \subseteq G$ is a D -set over A in G if it is D -critical in G , witnessed by some A -definable function $f : X \rightarrow D^m$ and there exists a coordinate projection $\pi : f(X) \rightarrow D^n$, with $n = \text{dp-rk}(X)$, such that for every $B \supseteq A$ and B -generic $a \in f(X)$, all elements of $\pi^{-1}(\pi(f(a)))$ have the same type over $B\pi(f(a))$.

Remark 2.12.

- (1) If G is a definable group locally strongly internal to D , then it always contains a D -set. See [13, Remark 4.18].

- (2) Note the following special case: if X is D -critical, $f : X \rightarrow D^n$ a definable injection witnessing it, and $n = \text{dp-rk}(X)$, then X is a D -set. As we shall see, such an X can always be found when G is locally strongly internal to D . If D is an SW-uniformity, this follows from [31, Proposition 4.6], and in the p -adically closed case, this follows from Proposition 3.10 when $D = K/\mathcal{O}$ and cell decomposition when $D = \Gamma$. See Lemma 4.3 for more information.

Definition 2.13. Let G be a D -group, $Z \subseteq G$ a D -set over A and $d \in Z$ an A -generic point. The *infinitesimal vicinity of d in Z* , denoted $\nu_Z(d)$, is the partial type consisting of all B -generic vicinities of d in Z , as B varies over all small parameter subsets of \mathcal{K} .

By [13, Lemma 4.20], the type $\nu_Z(d)$ is a filter-base – namely, the intersection of any two generic vicinities of d contains another. It follows that $\text{dp-rk}(\nu_Z(d))$ equals the D -rank of G .

We think of $\nu_Z(d)$ (and the type definable group ν_D defined below) both as a collection of formulas over \mathcal{K} and a set of realization of the partial type in some monster model extending \mathcal{K} . We say that two such types are equal if they are logically equivalent. For a definable set X , we denote $\nu_Z(d) \vdash X$ if there is $Y \in \nu_Z(d)$ such that $Y \subseteq X$. By writing $\nu_Z(d) \vdash \nu_W(d')$, we mean that for all $X \in \nu_W(d')$, we have $\nu_Z(d) \vdash X$.

Fact 2.14 [13, Proposition 5.8]. Let D be an unstable distinguished sort and let G be a D -group.

- (1) Assume that $X \subseteq G$ is a D -set over A . Then for every A -generic $a, b \in X$, the set $\nu_X(a)a^{-1}$ is a (type-definable) subgroup of G and $\nu_X(a)a^{-1} = \nu_X(b)b^{-1} = a^{-1}\nu_X(a)$. We denote this group ν_X .
- (2) If $X, Y \subseteq G$ are D -sets over A , then $\nu_X = \nu_Y$, and we can call it $\nu_D(G)$, the *infinitesimal type-definable subgroup of G with respect to D* .
- (3) For every $g \in G(\mathcal{K})$, we have $g\nu_D(G)g^{-1} = \nu_D(G)$. In fact, ν_D is invariant under any \mathcal{M} -definable automorphism of G .

Whenever the group G is understood from the context and there is no ambiguity, we denote $\nu_D(G)$ by ν_D .

Remark 2.15. Note that if $X \subseteq G$ is a D -set which happens to be a subgroup, then $\nu_D \vdash X$.

Lemma 2.16. Let $H \leq G$ be two definable D -groups, locally strongly internal to an unstable distinguished sort D . Then

- (1) $\nu_D(H) \vdash \nu_D(G)$.
- (2) If H and G have the same D -rank, then $\nu_D(H) = \nu_D(G)$. In particular, this holds if H has finite index in G .

Proof. Let $H \leq G$ be any subgroup, as in the statement.

(1) Let $X_G \subseteq G$ be a D -set in G and $X_H \subseteq H$ a D -set in H , all definable over a parameter set A . Let $(g, h) \in X_G \times X_H$ be generic over A , so $\nu_D(G) = g^{-1}\nu_{X_G}(g)$ and $\nu_D(H) = h^{-1}\nu_{X_H}(h)$.

Let V be a generic vicinity of g and U a generic vicinity of h . By [13, Lemma 4.26], $U \cap hg^{-1}V$ is a generic vicinity of h , and hence,

$$\nu_D(H) \vdash h^{-1}(U \cap hg^{-1}V) = h^{-1}U \cap g^{-1}V \subseteq g^{-1}V.$$

(2) Assume that H and G have the same D -rank; hence, any D -set in H is automatically a D -set in G . It now follows by definition that $\nu_D(H) = \nu_D(G)$.

If H has finite index in G then it is easy to see that they have the same D -rank. □

The next lemma supports the intuition that the type-definable coset $g \cdot \nu_D(G)$ is an infinitesimal neighborhood of g , for g generic in a set locally strongly internal to D :

Lemma 2.17. Let G be a D -group, $X \subseteq G$ an A -definable set strongly internal to D over A , and $g \in X$ generic over A . Then $\text{dp-rk}(X \cap g \cdot \nu_D) = \text{dp-rk}(X)$.

Proof. Let Z' be any D -set, definable over some parameter set B' . Find an element $g' \equiv_A g$ such that $\text{dp-rk}(g'/AB') = \text{dp-rk}(g/A)$. Applying an automorphism over A , we can move g' to g and B' to some B . The image, Z , of Z' under this automorphism, is definable over B and $\text{dp-rk}(g/AB) = \text{dp-rk}(g/A)$. Renaming, we assume from now on, that $A = AB$.

Fix an A -generic $h \in Z$ with $\text{dp-rk}(g, h/A) = \text{dp-rk}(X) + \text{dp-rk}(Z)$. Thus, as $v_D = h^{-1}v_Z(h)$, we have to show that $\text{dp-rk}(X \cap gh^{-1}v_Z(h)) = \text{dp-rk}(X)$.

Let $Y \subseteq Z$ be some B -generic vicinity of h (i.e., $Y \in v_Z(h)$), for some B ; so it will suffice to prove that $\text{dp-rk}(X \cap gh^{-1}Y) = \text{dp-rk}(X)$.

By [13, Lemma 4.13], there exists $C \supseteq A$ and a C -generic vicinity $Y' \subseteq Y$ of h such that $\text{dp-rk}(g, h/A) = \text{dp-rk}(g, h/C)$. So (g, h) is C -generic in $X \times Y'$. It will be sufficient to prove that $\text{dp-rk}(X \cap gh^{-1}Y') = \text{dp-rk}(X)$; this is exactly [13, Lemma 4.26]. \square

Lemma 2.18. *Let G be a definable group in \mathcal{K} , H a finite normal subgroup and $f : G \rightarrow G/H$ the quotient map. Let D be any of the distinguished sorts.*

(1) *The almost D -ranks of G and G/H are equal.*

For the following, assume that D is not K/\mathcal{O} in the p -adically closed case.

(2) *The D -rank of G is at most the D -rank of G/H .*

(3) *If, furthermore, G is D -group (so D is unstable), then so is G/H , and then $f(v_D(G)) = v_D(G/H)$.*

(4) *If the D -critical rank and the almost D -critical ranks of G coincide, then the same is true for G/H .*

Proof. For (1) and (2), we first note that for any (almost) D -critical set $X \subseteq G$, there exists an (almost) D -critical $Y \subseteq f(X)$ (with respect to G/H), with $\text{dp-rk}(Y) = \text{dp-rk}(X)$. Indeed, if D is an SW-uniformity, then this is [13, Lemma 2.9], and if $D = \mathbf{k}$ in the V -minimal case, then it is [13, Lemma 4.3]. This implies (1) and (2) for D other than K/\mathcal{O} in the p -adically closed case. For (1) in that latter case, use [13, Lemma 3.9].

We now assume that D is not K/\mathcal{O} in the p -adically closed case.

(3) If G is a D -group, then G/H is also locally strongly internal to D by (2). Combined with (the proof of) [13, Fact 4.25], it follows that G/H is also a D -group.

To show that $f(v_D(G)) = v_D(G/H)$, let $X_0 \subseteq G$ be a D -set. By the above, we may find a D -critical subset $Y_0 \subseteq f(X_0)$. By [13, Remark 4.18], there exists a D -set $Y \subseteq Y_0 \subseteq G/H$. Setting $X = f^{-1}(Y) \subseteq X_0$, and since X_0 is a D -set, so is X_0 . We are now in the situation where X and $Y = f(X)$ are both D -sets, with respect to G and G/H , respectively. Assume everything is defined over some parameters set A .

Let $a \in X$ be an A -generic in X , so $f(a)$ is an A -generic in Y . It suffices to prove that $f(v_X(a)) = v_X(f(a))$.

For this, first note that if $U \subseteq X$ is a B -generic vicinity of a , for some $B \supseteq A$, then $f(U)$ is a B -generic vicinity of $f(a)$ since $f(a) \in \text{dcl}(Aa)$ and $\text{dp-rk}(U) = \text{dp-rk}(f(U))$ as f is finite-to-one.

To show the other direction, let V be a B -generic vicinity of $f(a)$ for some $B \supseteq A$. Then $f^{-1}(V)$ is a B -generic vicinity of a since $a \in \text{acl}(Af(a))$ and $f(f^{-1}(V)) = V$ because f is surjective.

(4) Follows directly from (1) and (2), \square

2.6. Some basic group theoretic facts in our setting

Before the next corollary, we note the following application of Baldwin-Saxl ([28, Lemma 1.3]).

Fact 2.19. Let G be a group definable in a sufficiently saturated NIP structure and $\{H_i : i \in T\}$ a definable family of finite index subgroups of G . Then $\bigcap_{i \in T} H_i$ is a definable subgroup of finite index.

Proof. By Baldwin-Saxl, there is a finite bound on the index of finite intersections of the H_i . \square

Corollary 2.20. Let G be a definable group in a sufficiently saturated NIP structure, $\{\lambda_t : t \in T\}$ a definable family of group automorphisms of G , and $X \subseteq G$, all definable over a parameter set A . Assume that for every $a \in X$, $C_G(a)$ has finite index in G . Then there exists an A -definable subgroup $G_1 \subseteq C_G(X)$ of finite index in G that is invariant under λ_t , for all $t \in T$.

Proof. By Fact 2.19, $C_G(X)$ has finite index in G . Applying this fact again to the intersection of the family $\{\lambda_t(C_G(X)) : t \in T\}$ gives the desired conclusion. \square

We need a couple of group theoretic observations on definable groups in our setting. We note for future reference that Lemma 2.21 and Corollary 2.22 below do not require saturation of \mathcal{K} .

Lemma 2.21. *Let N be a definable group in \mathcal{K} and $H \trianglelefteq N$ a definable normal subgroup, such that N/H is abelian. For $k \in \mathbb{N}$, let $N^k = \{g^k : g \in N\}$. Then*

- (1) *For every $k \in \mathbb{N}$, $N^k H$ is a normal subgroup of N and $N/N^k H$ is finite.*
- (2) *If H is finite and central in N , and $k = |H|$, then the set N^k is contained in $Z(N)$ and $Z(N)$ has finite index in N .*

Proof. (1) Since N/H is abelian, for every $a, b \in N$, $ab = bah$ for some $h \in H$. Because H is normal, for all $g \in G$ and $h \in H$, there is $h' \in H$ such that $hg = gh'$. It follows that $a^2 b^2 = (ab)^2 h_1$, for $h_1 \in H$, and by induction, $a^k b^k = (ab)^k h_0$, for some $h_0 \in H$. Thus, $N^k H$ is a subgroup, clearly normal in N .

The order of every $g \in N/N^k H$ is at most k ; thus, $N/N^k H$ has bounded exponent. The group $N/N^k H$ is clearly also definable in \mathcal{K} , and by [13, Theorem 7.4, Theorem 7.7 and Theorem 7.11], a definable group of bounded exponent must be finite. Thus, $N/N^k H$ must be finite.

(2) Assume now that $k = |H|$ and H is central. Since G/H is abelian, for every $g, x \in N$, we have $g^{-1}xg = xh$ for some $h \in H$, and hence, since H is central, $g^{-1}x^k g = (xh)^k = x^k h^k = x^k$. Thus, $N^k \subseteq Z(N)$. It follows that $N^k H \subseteq Z(N)$, so by (1), $Z(N)$ has finite index in N . \square

The proof of the next corollary is simpler when H is central, but we need the more general statement:

Corollary 2.22. *Let G be a definable group in \mathcal{K} and H a finite normal subgroup of G , both defined over a parameter set A . Let $\{\lambda_t : t \in T\}$ be a definable family of group automorphisms of G fixing H setwise.*

If for some $B \supseteq A$ the group G/H contains a B -definable normal abelian subgroup of dp-rank k invariant under all the λ_t , then so does G . In particular, if G is definably semisimple, then so is G/H .

Proof. For simplicity, let us call a set invariant under all the λ_t Λ -invariant. By Lemma 2.20, there exists a definable Λ -invariant $G_1 \trianglelefteq G$ of finite index such that $G_1 \subseteq C_G(H)$. In particular, $G_1 \cap H$ is central in G_1 . We fix such G_1 .

Assume that G/H has an infinite Λ -invariant definable abelian normal subgroup of the form N/H for $N \trianglelefteq G$. It follows that N is Λ -invariant. Let $N_1 := N \cap G_1$, an infinite normal subgroup of G of finite index in N and $H_1 := H \cap N_1$, a central subgroup of N_1 . The quotient N_1/H_1 is isomorphic to $N_1 H/H \subseteq N/H$ and so is abelian. Note that N_1 is also Λ -invariant.

By Lemma 2.21 (2), $Z(N_1)$ has finite index in N_1 , and therefore, $\text{dp-rk}(Z(N_1)) = \text{dp-rk}(N_1) = \text{dp-rk}(N) = \text{dp-rk}(N/H)$. Because N_1 is Λ -invariant and normal in G , so is $Z(N_1)$. Hence, $Z(N_1)$ is a Λ -invariant definable normal abelian subgroup of G of the same rank as N_1/H . Clearly, if N/H is B -definable for some $B \supseteq A$, then so are N_1 and $Z(N_1)$. \square

3. Definable subgroups of $((K/\mathcal{O})^n, +)$

Let \mathcal{K} be one of our valued fields. The purpose of this section is to describe the definable subgroups of $(K/\mathcal{O})^n$. When \mathcal{K} is either power bounded T -convex or V -minimal, those turn out to be definably isomorphic to a product of balls in K/\mathcal{O} . In this case, we can also describe all their definable endomorphisms. When \mathcal{K} is p -adically closed, the existence of finite subgroups creates obstructions (see Example 3.2); nonetheless, we will show that definable subgroups project injectively onto subgroups of full dp-rank.

3.1. \mathcal{K} power-bounded T -convex or V -minimal

We assume that \mathcal{K} is either power bounded T -convex or V -minimal. Recall that for $a \in K \setminus \mathcal{O}$, $v(a + \mathcal{O})$ is well-defined, allowing us to refer to definable balls in K/\mathcal{O} . Below, we use the term *trivial ball* to refer to either K (or K/\mathcal{O}) or $\{0\}$.

We start with the following basic observation.

Lemma 3.1. *Every definable subgroup G of $(K, +)$ is a ball, possibly trivial. As a result, every definable subgroup of K/\mathcal{O} is a (possibly trivial) ball.*

Proof. Since $\pi : K \rightarrow K/\mathcal{O}$ is a group homomorphism, and the image of a ball (centered at 0) under π is again a ball, it suffices to show that the claim is true for definable subgroups of $(K, +)$. So let G be a subgroup of $(K, +)$. Since $(K, +)$ is torsion-free, if G is finite, it is trivial. So we may assume G is infinite. Let B be the union of all sub-balls of G containing 0. If $B = K$, then $G = K$, and we are done, so assume $B \neq K$. Because Γ is definably complete, B is a ball itself, possibly $\{0\}$. Since every infinite definable subset of K has an interior, and G is a group $B \neq \{0\}$. We will show that $G = B$.

Assume for contradiction that $G \neq B$. In our settings, B is a divisible group (indeed, the maps $x \mapsto nx$ send B onto itself for all nonzero $n \in \mathbb{N}$), and since $(K, +)$ is torsion-free, it must be that $[G : B] = \infty$. This means that G contains infinitely many disjoint maximal balls, cosets of B .

Assume that B is a closed ball. By the so-called (Cballs) property introduced in [12], which holds in our settings [12, Proposition 5.6, Lemma 5.10], only finitely many translates of B intersect G , so G contains only finitely many cosets of B , contradiction.

Assume then that B is open. After re-scaling G , we may assume that $B = \mathbf{m}$. Again, by (Cballs), G intersects only finitely many closed 0-balls. Consequently, $\mathcal{O} \cap G$ is an additive subgroup of K containing infinitely many cosets of \mathbf{m} . The image of $\mathcal{O} \cap G$ is, therefore, an infinite definable subgroup of $(\mathbf{k}, +)$. However, under our assumptions, \mathbf{k} has no infinite definable proper subgroups, and thus, $G \cap \mathcal{O} = \mathcal{O}$ contradicting the maximality of the ball $B = \mathbf{m}$. Thus, $G = B$, with the desired conclusion. \square

Example 3.2. The lemma above does not hold in the p -adically closed case. For example, consider a finite residual extension K of \mathbb{Q}_p . Let H be a nontrivial finite proper subgroup of $(\mathbf{k}_K, +)$. Then $G = \{g \in K : \text{res}(g) \in H\}$ is a subgroup of K that is not a ball.

The following computation should be well known.

Fact 3.3. Let $B_1, B_2 \subseteq K$ be balls (possibly the whole of K).

- (1) Every ball containing 1 but not 0 is a multiplicative subgroup of K^\times .
- (2) The point-set product $B_1 \cdot B_2$ is also a ball.
- (3) If $0 \notin B_2$, then their point-set quotient $B_1 \cdot (B_2)^{-1}$ is also a ball.

Proof. We assume both B_1 and B_2 are not equal to K . The proof can be easily adapted to include this case as well.

(1) Well known.

(2) Let B_1 and B_2 be balls. It will suffice to show that cB_1B_2 is a ball for some $c \neq 0$. So, as we proceed, we may freely replace B_i with cB_i for any such constant c .

Assume, first, that $0 \in B_1$ but $0 \notin B_2$; thus, $B_1B_2 = \bigcup \{B_1b : b \in B_2\}$ is a chain of balls centered at 0. After multiplying by a suitable element, we may assume that $v(b) = 0$ for all $b \in B_2$ and so $B_1b = B_1$ for all $b \in B_2$, which gives $B_1B_2 = B_1$. If $0 \in B_1 \cap B_2$, then after multiplying by suitable elements, we may assume that $B_1, B_2 \in \{\mathcal{O}, \mathbf{m}\}$; in any of these cases, B_1B_2 is obviously a ball.

Assume, now, that $0 \neq B_1 \cup B_2$. By multiplying by appropriate elements, we may assume that $1 \in B_1 \cap B_2$, so both are multiplicative subgroups of K^\times . Without loss of generality, $B_1 \subseteq B_2$. Then $B_2 \subseteq B_1B_2 \subseteq B_2B_2 = B_2$.

(3) If $0 \notin B_2$, then after possibly multiplying by an appropriate element, we get that B_2 is a multiplicative subgroup of K^\times . Thus, $B_2^{-1} = B_2$ and (2) applies. \square

Lemma 3.4. *Let $I, J, H \subseteq K$ be definable subgroups, $I \subseteq H \cap J$, and let $T : H/I \rightarrow K/J$ be a definable homomorphism. Then there is $d \in K$ such that, $d \cdot I \subseteq J$, and for every $x \in H$, $T(x+I) = d \cdot (x+I) + J$.*

Proof. Since I, J, H are definable subgroups of K , they are balls and so are their cosets, and because T is a group homomorphism, the image under T of a coset of I is also a coset of a subgroup, so viewed as

a subset of K , it is a ball. Given $x \in H \setminus I$, let

$$S_x = \{w/z \in K : z \in x + I \wedge w \in T(x + I)\}.$$

As a quotient of two balls, S_x is a ball, too (note that $0 \notin x + I$ so Fact 3.3 applies). For $d \in K$, let

$$H_d = I \cup \{x \in H \setminus I : d \in S_x\}.$$

We claim that each H_d is a subgroup of K (and when $I = 0$, possibly a singleton). To see this, let $H'_d = \{x \in H \setminus I : d \in S_x\}$; by definition, $H'_d \cap I = \emptyset$. It follows directly from the definition of H'_d that if $x_1 \in I$ and $x_2 \in H'_d$, then $x_1 \pm x_2 \in H'_d$. So it remains to show that if $x_1, x_2 \in H'_d$, then $x_1 - x_2 \in H_d$. By assumption, $d \in S_{x_1} \cap S_{x_2}$, so we can write, $d = w_1/z_1 = w_2/z_2$ with $w_i \in T(x_i + I)$ and $z_i \in x_i + I$. So $d(z_1 - z_2) = w_1 - w_2$. If $z_1 - z_2 \in I$, then $x_1 + I = x_2 + I$, so obviously, $x_1 - x_2 \in H_d$. Otherwise, $d = (w_1 - w_2)/(z_1 - z_2)$, $z_1 - z_2 \in x_1 - x_2 + I$ and $w_1 - w_2 \in T(x_1 + I) - T(x_2 + I) = T(x_1 - x_2 + I)$.

Hence, by Lemma 3.1, H_d is a ball around 0. We use this fact now to show that the family $\{S_x : x \in K\}$ forms a chain of balls with respect to inclusion. Namely, we show that for $x_1, x_2 \in H \setminus I$, if $v(x_1) \leq v(x_2)$, then $S_{x_1} \subseteq S_{x_2}$. Let $d \in S_{x_1}$. Since H_d is a ball and $v(x_1) \leq v(x_2)$, then $x_1 \in H_d$ implies that $x_2 \in H_d$ (i.e., $d \in S_{x_2}$).

Since V -minimal and power bounded T -convex valued fields are 1-h-minimal (see [6, Section 6]), they are definably spherically complete ([6, Lemma 2.7.1] – namely, the intersection of a definable chain of nonempty balls is nonempty. Thus, $\bigcap_{x \in H \setminus I} S_x \neq \emptyset$, and we let d be an element in the intersection.

Let $\hat{H}_d = \{z \in H : d \cdot z \in T(z + I)\}$. Since $T : H/I \rightarrow K/J$ is a homomorphism, \hat{H}_d is a subgroup of $(K, +)$. By definition, $H'_d \subseteq \hat{H}_d$ and as both \hat{H}_d and I are balls, either $I \subseteq \hat{H}_d$ or $\hat{H}_d \subseteq I$. Since $H'_d \cap I = \emptyset$ necessarily, $I \subseteq \hat{H}_d$, and thus, $H_d \subseteq \hat{H}_d$. However, by the choice of d , for all $x \in H \setminus I$, $d \in S_x$, so $H = H_d = \hat{H}_d$.

Finally, as $I \subseteq \hat{H}_d$, $d \cdot I \subseteq T(I) = J$. Thus, $T(x + I) = d \cdot (x + I) + J$ for any $x \in H$. \square

We are now ready to describe all definable subgroups of K^n and the associated homomorphisms.

Lemma 3.5. *The following holds for all n :*

(1)_n If $H \subseteq K^n$ is a definable subgroup of K^n , then there is $g \in \text{GL}_n(\mathcal{O})$ such that $g(H)$ is a cartesian product of balls, possibly trivial.

(2)_n If $H \subseteq K^n$ and $J \subseteq K$ are definable subgroups and $T : H \rightarrow K/J$ is a definable homomorphism, then there are elements $\alpha_1, \dots, \alpha_n \in K$ such that for all $x = (x_1, \dots, x_n) \in H$,

$$T(x_1, \dots, x_n) = \alpha_1 x_1 + \dots + \alpha_n x_n + J.$$

Proof. (1)₁ By Lemma 3.1, every definable subgroup of K is a ball, possibly trivial.

(2)₁ This is Lemma 3.4 for $I = \{0\}$.

We now proceed with the induction step, assuming (1) _{$n-1$} , (2) _{$n-1$} and prove (1) _{n} :

Let $\pi : K^n \rightarrow K^{n-1}$ be the projection onto the first $n - 1$ coordinates. By (1) _{$n-1$} , we may assume that $\pi(H) = H_1 \times \dots \times H_{n-1}$, for balls $H_i \subseteq K$. Also, write $\ker(\pi) = H \cap (\{0\}^{n-1} \times K)$ as $\{0\}^{n-1} \times J$, for a definable subgroup $J \subseteq K$.

Notice that for every $(a, b), (a, c) \in H \subseteq K^{n-1} \times K$, we have $b - c \in J$, and hence, H can be viewed as the graph of a function $T : \pi(H) \rightarrow K/J$, mapping a to $b + J$; that is,

$$H = \{(a, b) \in K^n : a \in \pi(H) \wedge b \in T(a)\}.$$

By (2) _{$n-1$} , there are $\alpha_1, \dots, \alpha_{n-1} \in K$, such that $T(x) = \sum_{i=1}^{n-1} \alpha_i x_i + J$.

Hence,

$$H = \left\{ (x_1, \dots, x_n) \in K^n : (x_1, \dots, x_{n-1}) \in \pi(H) \wedge x_n - \sum_{i=1}^{n-1} \alpha_i x_i \in J \right\}.$$

The groups J and $\alpha_i H_i$, for $i = 1, \dots, n-1$, are subgroups of $(K, +)$, and hence, they are balls. Thus, for every $i = 1, \dots, n-1$, either $J \subseteq \alpha_i H_i$ or $\alpha_i H_i \subseteq J$. Note that if $\alpha_{i_0} H_{i_0} \subseteq J$ for some i_0 and $(x_1, \dots, x_{n-1}) \in \pi(H)$, then $x_n - \sum_{i \neq i_0} \alpha_i x_i \in J$ iff $x_n - \sum_i \alpha_i x_i \in J$. So there is no harm assuming that $\alpha_i = 0$ whenever $J \supseteq \alpha_i H_i$ and that $J \subseteq \alpha_i H_i$ whenever $\alpha_i \neq 0$. Also, we may assume that for some i , $\alpha_i \neq 0$, for otherwise, $H = \pi(H) \times J$, and we are done.

Fix $\alpha_1, \dots, \alpha_{n-1}$ as above. Permuting the coordinates, if needed, we may assume that $v(\alpha_1) \leq v(\alpha_j)$, for all $j = 2, \dots, n-1$. Thus, we can write

$$H = \left\{ (x_1, \dots, x_n) : (x_1, \dots, x_{n-1}) \in \pi(H) \wedge \frac{1}{\alpha_1} x_n - (x_1 + \sum_{i=2}^{n-1} \frac{\alpha_i}{\alpha_1} x_i) \in \frac{1}{\alpha_1} J \right\}.$$

Let $S(x_2, \dots, x_n) = \frac{1}{\alpha_1} x_n - \sum_{i=2}^{n-1} \frac{\alpha_i}{\alpha_1} x_i$. Then $S : K^{n-1} \rightarrow K$ is a linear map defined over \mathcal{O} , and we have

$$H = \left\{ (x_1, \dots, x_n) : (x_1, \dots, x_{n-1}) \in \pi(H) \wedge x_1 - S(x_2, \dots, x_n) \in \frac{1}{\alpha_1} J \right\}. \quad (1)$$

Let $\hat{\pi}(x_1, x_2, \dots, x_n) = (x_2, \dots, x_n)$ be the projection onto the last $n-1$ coordinates.

Claim 3.5.1. For every $\hat{x} = (x_2, \dots, x_n) \in \hat{\pi}(H)$, we have $(S(\hat{x}), \hat{x}) \in H$.

Proof. Let $\hat{x} = (x_2, \dots, x_n) \in \hat{\pi}(H)$ and let $x_1 = S(\hat{x})$. Then clearly, $x_1 - S(\hat{x}) = 0 \in \frac{1}{\alpha_1} J$, so by (1), it is sufficient to see that $(x_1, x_2, \dots, x_{n-1}) \in \pi(H)$. Since $\hat{x} \in \hat{\pi}(H)$, there exists x'_1 such that $(x'_1, x_2, \dots, x_n) \in H$. In particular, $x_2 \in H_2, \dots, x_{n-1} \in H_{n-1}$, so for (x_1, \dots, x_{n-1}) to be in $\pi(H)$, we only need to verify that $x_1 = S(\hat{x}) \in H_1$. By assumption, $(x'_1, x_2, \dots, x_{n-1}, x_n) \in H$, so by (1), $x'_1 \in H_1$ and $x'_1 - S(\hat{x}) \in \frac{1}{\alpha_1} J$, so $S(\hat{x}) \in \frac{1}{\alpha_1} J + x'_1$. However, we assumed that $J \subseteq \alpha_1 H_1$ so $\frac{1}{\alpha_1} J \subseteq H_1$, and therefore $S(\hat{x}) \in H_1$; hence, $(S(\hat{x}), \hat{x}) \in H$. \square

We get that

$$H = \left\{ (x_1, x_2, \dots, x_n) : (x_2, \dots, x_n) \in \hat{\pi}(H) \wedge x_1 - S(x_2, \dots, x_n) \in \frac{1}{\alpha_1} J \right\}.$$

So $H \cap (K \times \{0\}^{n-1}) = \frac{1}{\alpha_1} J \times \{0\}^{n-1}$ and, in particular, the map $(x_1, \dots, x_n) \mapsto x_1 - S(x_2, \dots, x_n)$ from H to $\frac{1}{\alpha_1} J$ is surjective. We now define $F : K^n \rightarrow K^n$ by

$$F(x_1, x_2, \dots, x_n) = (x_1 - S(x_2, \dots, x_n), x_2, \dots, x_n).$$

Then F is over \mathcal{O} , and by a direct computation, one sees that it has determinant 1; hence, $F \in \mathrm{GL}_n(\mathcal{O})$. It follows from the definition of F and the observation above that the restriction $F \upharpoonright H$ is definable, injective and onto $\frac{1}{\alpha_1} J \times \hat{\pi}(H)$.

By induction, there is $h \in \mathrm{GL}_{n-1}(\mathcal{O})$ such that $h(\hat{\pi}(H))$ is a product of balls. Hence, there is $g \in \mathrm{GL}_n(\mathcal{O})$ sending H to a product of balls. This ends the proof of (1)_n.

For $(2)_n$, we start with $T : H \rightarrow K/J$. with $H \subseteq K^n$. By $(1)_n$, we may assume that $H = V_1 \times \cdots \times V_n$, for definable subgroups $V_i \subseteq K$. Thus,

$$T(x_1, \dots, x_n) = T(x_1, 0, \dots, 0) + \cdots + T(0, \dots, 0, x_n),$$

with all elements still in H . The result follows from the case $n = 1$. \square

Remark 3.6. Lemma 3.5(1) is inspired by the work of Hrushovski-Haskell-Macpherson on definable \mathcal{O} -submodules of K^n in algebraically closed valued fields, [14, Lemma 2.2.4]. In that work, the authors prove that up to an automorphism in $\text{GL}_n(K)$ every definable \mathcal{O} -submodule is a finite cartesian product of K , \mathcal{O} , \mathfrak{m} and $\{0\}$.

In our setting, if $G \subseteq K^n$ is a definable subgroup, then it is an \mathcal{O} -submodule (the converse is clearly true), since $\{d \in \mathcal{O} : dG \subseteq G\}$ is a definable subgroup of $(K, +)$ containing 1, so by Lemma 3.1, it must be the whole of \mathcal{O} .

Thus, Lemma 3.5 (1) can be seen as a strengthening of [14, Lemma 2.2.4] even in the $\text{ACVF}_{0,0}$ setting.

We may now conclude:

Lemma 3.7. Let $H \subseteq (K/\mathcal{O})^n$ be a definable subgroup.

(1) There is a definable automorphism T of $(K/\mathcal{O})^n$ such that $T(H) = H_1 \times \cdots \times H_n$, where each H_i is a, possibly trivial, ball.

(2) If $T : H \rightarrow K/\mathcal{O}$ is a definable homomorphism, then there are scalars $d_1, \dots, d_n \in \mathcal{O}$ such that for all $x = (x_1 + \mathcal{O}, \dots, x_n + \mathcal{O}) \in H$,

$$T(x_1 + \mathcal{O}, \dots, x_n + \mathcal{O}) = d_1 x_1 + \cdots + d_n x_n + \mathcal{O}.$$

Proof. (1) Consider $\hat{H} \subseteq K^n$ the preimage of H in K^n . By Lemma 3.5, there is $g \in \text{GL}_n(\mathcal{O})$ such that $g(\hat{H})$ is a product of (possibly trivial) balls in K . Since $g \in \text{GL}_n(\mathcal{O})$, it descends to an automorphism of $(K/\mathcal{O})^n$ sending H to a product of balls in (K/\mathcal{O}) (possibly trivial ones).

For (2), we may assume that $H = V_1 \times \cdots \times V_n$ for $V_i \subseteq K/\mathcal{O}$ and then

$$T(x_1 + \mathcal{O}, \dots, x_n + \mathcal{O}) = T(x_1 + \mathcal{O}, 0, \dots, 0) + \cdots + T(0, \dots, 0, x_n + \mathcal{O}),$$

with each element on the right inside H . We apply Lemma 3.4 with $I = J = \mathcal{O}$, so there are $d_1, \dots, d_n \in \mathcal{O}$ (because $d_i \mathcal{O} \subseteq \mathcal{O}$), such that $T(x_1 + \mathcal{O}, \dots, x_n + \mathcal{O}) = d \cdot x_1 + \cdots + d_n \cdot x_n + \mathcal{O}$. \square

Finally, we want the following:

Lemma 3.8. Let $H \subseteq (K/\mathcal{O})^n$ be a definable group and $T : H \rightarrow (K/\mathcal{O})^n$ a definable homomorphism. Then T can be extended definably to an endomorphism of $(K/\mathcal{O})^n$.

In addition, if T is injective, then we can choose the extension to be an automorphism of $(K/\mathcal{O})^n$.

Proof. For the first part, we may think of T in coordinates and apply Lemma 3.5(2)_n to each coordinate map, obtaining $L \in \text{End}((K/\mathcal{O})^n)$ extending T .

Assume now that T is injective, and we shall see that so is L . By Lemma 3.7(1)_n, after composing with a definable automorphism of $(K/\mathcal{O})^n$, we may assume that $H = B_1 \times \cdots \times B_n$, where each $B_i \subseteq K/\mathcal{O}$ is a ball around 0 (possibly trivial).

Assume first that, for all i , B_i is not the zero ball. If L , the extension of T provided above, were not injective, then, after permutation of the coordinates, we may assume the projection of $\ker(L)$ into B_1 is infinite. But then, $\ker(L) \cap B_1 \times \{0_{n-1}\}$ is nontrivial, contradicting the injectivity of T .

So without loss of generality, we assume that $H = B_1 \times \cdots \times B_m \times \{0\}^{n-m}$ and that B_i is nontrivial for $i \leq m$. Since T is injective, $\text{dp-rk}(T(H)) = m = \text{dp-rk}(H)$, and hence, after a definable automorphism of $(K/\mathcal{O})^n$ (the range), we may assume that $T(H) = C_1 \times \cdots \times C_m \times \{0\}^{n-m}$, where the $C_i \subseteq K/\mathcal{O}$ are balls with $r(C_i) < 0$ (possibly $C_i = K/\mathcal{O}$). Setting $H_1 = B_1 \times \cdots \times B_m$ and $H_2 = C_1 \times \cdots \times C_m$, the

map T thus induces an injective isomorphism of H_1 and H_2 that, by what we have already noted, can be extended to a definable automorphism L_1 of $(K/\mathcal{O})^m$.

Now, for $(x, y) \in (K/\mathcal{O})^m \times (K/\mathcal{O})^{n-m}$, let $S(x, y) = (L_1(x), y)$. This is an extension of T to an automorphism of $(K/\mathcal{O})^n$. \square

As a corollary, we obtain the following:

Corollary 3.9. *Assume that $f : (K/\mathcal{O})^n \rightarrow (K/\mathcal{O})^n$ is a definable group automorphism. Then there is $g \in \mathrm{GL}_n(\mathcal{O})$ such that for all $x \in K^n$, $f(x + \mathcal{O}^n) = gx + \mathcal{O}^n$. In particular, T preserves the valuation.*

Proof. By Lemma 3.7(2), there exist $L_1, L_2 \in M_n(\mathcal{O})$ such that for every $x \in K^n$,

$$f(x + \mathcal{O}^n) = L_1(x) + \mathcal{O}^n, \quad f^{-1}(x + \mathcal{O}^n) = L_2(x) + \mathcal{O}^n.$$

It follows that for all $x \in K^n$, we have $L_1 \circ L_2(x) - x \in \mathcal{O}^n$. It is easy to see that this forces the K -linear map $L_1 \circ L_2(x) - x$ to be 0. Thus, $L_2 = L_1^{-1}$ and both belong to $\mathrm{GL}_n(\mathcal{O})$. \square

3.2. $\mathcal{K}p$ -adically closed

In the present subsection, we assume that \mathcal{K} is p -adically closed. As we have already seen, definable subgroups of K/\mathcal{O} need not be balls, so the analysis of definable subgroups of $(K/\mathcal{O})^n$ is more subtle than in the V -minimal and the power-bounded T -convex settings. Our aim in this section is to prove the result below, a weak version of Lemma 3.7(1) that will suffice for our needs. Recall that balls in \mathcal{K}/\mathcal{O} are by definition infinite, and we call \mathcal{K} a *trivial ball*.

Proposition 3.10. *For any infinite definable subgroup $H \leq (K/\mathcal{O})^n$, there exist $k \in \mathbb{N}$ and a coordinate projection $\pi_0 : (K/\mathcal{O})^n \rightarrow (K/\mathcal{O})^m$, with $m = \mathrm{dp}\text{-rk}(H)$, such that $\pi_0 \upharpoonright p^k H$ is injective.*

Remark 3.11. For any natural number k , since $H/p^k H$ is an interpretable group in \mathcal{K} with bounded exponent, it must be finite, [13, Theorem 7.12(4b)].

Let us fix some notation for the rest of Section 3.2. Let $J \supseteq \mathcal{O}$ be a subgroup of $(K/\mathcal{O}, +)$ with J/\mathcal{O} finite and $\rho : K \rightarrow K/\mathcal{O}$ the quotient map. Let B_J be the smallest closed ball around 0 containing J .

Recall that since \mathcal{K} has definable Skolem functions, each (partial) definable function $\hat{f} : K/\mathcal{O} \rightarrow K/J$ lifts to a (partial) definable function $\hat{f} : K \rightarrow K$. Namely, $\mathrm{dom}(\hat{f}) + \mathcal{O} = \mathrm{dom}(\hat{f})$, and for every $a \in \mathrm{dom}(\hat{f})$, $\hat{f}(a) + J = f(\rho(a))$. In particular, for $a, b \in \mathrm{dom}(\hat{f})$, if $a - b \in \mathcal{O}$, then $\hat{f}(a) - \hat{f}(b) \in J$.

We break the proof into several lemmas. The first is an adaptation of [13, Proposition 3.21], so we may be terse at times.

Lemma 3.12. *Let $H, J \leq K$ be definable subgroups containing \mathcal{O} with J/\mathcal{O} finite and H/\mathcal{O} a ball in K/\mathcal{O} . Let $\hat{T} : H \rightarrow K$ be a definable function lifting a definable homomorphism $T : H/\mathcal{O} \rightarrow K/J$. Then there exists a nontrivial ball U in K , $0 \in U \leq H$, and $c \in B_J$ such that $\hat{T}(x) - cx \in J$ for all $x \in U$.*

Proof. Assume everything is defined over some parameter set A and let p be a complete type over A which is concentrated on H/\mathcal{O} with $\mathrm{dp}\text{-rk}(p) = 1$. As in [13, Section 3.2], there exists a unique complete type \hat{p} over A concentrated on H such that $\rho_* \hat{p} = p$. In particular, for any $a \models \hat{p}$, also $a + \mathcal{O} \models \hat{p}$.

By generic differentiability, \hat{T} and \hat{T}' are both differentiable on \hat{p} (see [13, Lemma 3.17(1)]). A similar proof to that of [13, Lemma 3.17(2)] gives, for any $b \models \hat{p}$, that $\hat{T}'(b) \in B_J$.

Claim 3.12.1. For every $a \models \hat{p}$, there exists a $\hat{\mathcal{K}}$ -definable ball $B \ni a$ contained in $\hat{p}(\hat{\mathcal{K}})$ of valuative radius $r(B) < \mathbb{Z}$ such that for all $b \in B$, $v(\hat{T}''(b)) + 2r(B) > 0$.

Proof. The proof mimics [13, Lemma 3.17(3)]. Since there is one delicate adjustment toward the end, we give the whole argument. The reader may refer to [13, Section 3.2] for the relevant definitions and notions.

By saturation of \mathcal{K} and the definition of \hat{p} , there exists a ball $B_0 \subseteq \hat{p}(\mathcal{K})$ around a with $r(B_0) < \mathbb{Z}$ (see [13, Section 3.2]) and let $r_0 := r(B_0)$. Note that $B_{>r_0+m}(a) \subseteq \hat{p}(\mathcal{K})$ for any natural number m .

By [13, Fact 3.13] applied to the function \widehat{T}' , there are an A -definable finite set C and $m \in \mathbb{N}$ such that $\forall x \in B_{>r_0+m}(a)$, $v(\widehat{T}''(x))$ is constant on that ball. By definition, the ball $B_{>r_0+m}(a)$ is contained in a ball m -next to C , so after possibly shrinking B_0 , we may assume that $v(\widehat{T}''(x))$ is constant on B_0 and that (\dagger) holds on B_0 (see also [13, Lemma 3.14]).

If $\widehat{T}''(t) \equiv 0$, the claim holds trivially. Otherwise, by [13, Fact 3.13], $\widehat{T}'(B_{>r'}(a))$ is an open ball of radius $v(\widehat{T}''(a)) + r'$ for any $r' \geq r_0$. As $B_{>r_0}(a) \subseteq \widehat{p}(\widehat{K})$, we have $\widehat{T}'(B_{>r_0}(a)) \subseteq B_J$. Since J/\mathcal{O} is finite, we deduce that $v(\widehat{T}''(a)) + r_0$ is either positive or a finite negative integer. Either way, for any $r' \in \mathbb{Z}$ satisfying that for any $n \in \mathbb{Z}$, $r' - n > r_0$, we get that $\widehat{T}'(B_{>r'}(a))$ is an open ball of radius $v(\widehat{T}''(a)) + r' > 0$. So let r be such an element. Since $r/2$ also satisfies the same requirements, we deduce that $\widehat{T}'(B_{>r/2}(a))$ is an open ball of radius $v(\widehat{T}''(a)) + r/2 > v(\widehat{T}''(a)) + r > 0$. We conclude that for any $b \in B := B_{>r/2}(a)$, $v(\widehat{T}''(b)) + r > 0$. \square

Now, the proof of [13, Lemma 3.18] is applicable word-for-word, and we get that for every $a \models \widehat{p}$, there is a ball B , $a \in B \subseteq \widehat{p}(\widehat{K})$, such that for all $y \in B$,

$$v(\widehat{T}(y) - \widehat{T}(a) - \widehat{T}'(a)(y - a)) > 0.$$

Setting $c := \widehat{T}'(a) \in B_J$, we get that for all $y \in B$, $\widehat{T}(y) - \widehat{T}(a) - c(y - a) \in \mathfrak{m} \subseteq J$.

Let $U = B - a$; it is a subgroup of H . Let $x = y - a$ be an element of U (so $y \in B$). Since \widehat{T} is a lift of a homomorphism, $\widehat{T}(x) + J = \widehat{T}(y) - \widehat{T}(a) + J = c(y - a) + J = cx + J$. \square

We note that for groups definable in K/\mathcal{O} , injectivity of definable homomorphisms can be detected locally:

Lemma 3.13.

- (1) Let $N \leq (K/\mathcal{O})^n$ be a nontrivial definable subgroup and $B \ni 0$ a ball in $(K/\mathcal{O})^n$. Then $N \cap B$ is nontrivial.
- (2) Let $H \subseteq (K/\mathcal{O})^n$ be a definable group, $f : H \rightarrow (K/\mathcal{O})^m$ a definable homomorphism and $B \ni 0$ ball in $(K/\mathcal{O})^n$. Then f is injective if and only if $f \upharpoonright (B \cap H)$ is injective.

Proof. (1) By [13, Lemmas 3.1(3), 3.10 (1)], the ball B contains all torsions points in $(K/\mathcal{O})^n$. By [13, Lemma 3.10 (2)], N has nontrivial torsion. Thus, $N \cap B$ contains a nontrivial torsion point.

(2) Apply (1) to $N = \ker(f)$. \square

The following is the technical core of the proof:

Lemma 3.14. Let $J \supseteq \mathcal{O}$ be a group with J/\mathcal{O} finite, $T : B \rightarrow (K/\mathcal{O})/J$ be a group homomorphism and let $H \subseteq (K/\mathcal{O})^n$ be a definable subgroup of the form

$$\{(h_1, \dots, h_n) \in (K/\mathcal{O})^n : (h_1, \dots, h_{n-1}) \in N \wedge h_n + J = T(h_1, \dots, h_{n-1})\},$$

where $N \leq (K/\mathcal{O})^{n-1}$ is some subgroup of $\text{dp-rk } n - 1$.

Then there exists a natural number k such that the projection of $p^k H$ on some $n - 1$ coordinates is injective.

Proof. Since $\text{dp-rk}(N) = n - 1$, there exists a ball $B \subseteq N$ around 0. If there exists a coordinate projection π and a natural number k for which $\pi \upharpoonright p^k(H \cap (B \times K/\mathcal{O}))$ is injective, then as $p^k(H \cap (B \times K/\mathcal{O})) = p^k H \cap (p^k B \times K/\mathcal{O})$, we may apply Lemma 3.13 (2) and deduce that it is injective on $p^k H$ as well. Consequently, we may assume that $N = B = H_1 \times \dots \times H_{n-1}$ is a product of balls.

Recall that $\rho : K \rightarrow K/\mathcal{O}$ is the quotient map. Since

$$T(x_1, \dots, x_{n-1}) = T(x_1, 0, \dots, 0) + \dots + T(0, \dots, 0, x_{n-1}),$$

and denoting \widehat{T}_i for a lift of $T(0, \dots, x_i, \dots, 0)$ to a partial map from K to K , we obtain

$$\rho^{-1}(H) = \left\{ (a_1, \dots, a_{n-1}, a_n) \in K^n : (a_1, \dots, a_{n-1}) \in \rho^{-1}(B) \wedge a_n + J = \sum_{i=1}^{n-1} \widehat{T}_i(a_i) + J \right\}.$$

Applying Lemma 3.12 to the \widehat{T}_i , for each i , we find $c_i \in K$ and sub-balls $H'_i \leq H_i$ such that $\widehat{T}_i(x) - c_i x \in J$ for elements of H'_i . Letting $B' = H'_1 \times \dots \times H'_{n-1}$, we may, as above, replace B by B' and H by $H \cap (B' \times K/\mathcal{O})$. So we may assume that

$$\rho^{-1}(H) = \left\{ (a_1, \dots, a_{n-1}, a_n) \in K^n : (a_1, \dots, a_{n-1}) \in \rho^{-1}(B) \wedge a_n + J = \sum_{i=1}^{n-1} c_i \cdot a_i + J \right\}.$$

If $c_i = 0$ for all $1 \leq i \leq n-1$, then H is equal to a product of $n-1$ balls together with J/\mathcal{O} . If we choose p^k large enough so that $p^k J \subseteq \mathcal{O}$, then $p^k H \subseteq (K/\mathcal{O})^{n-1} \times \{0\}$, and so projects injectively into the first $n-1$ coordinates.

We thus assume that $c_i \neq 0$ for some i . Setting $c_n = 1$, assume, without loss of generality, that $v(c_1) = \min_{1 \leq i \leq n} \{v(c_i)\}$.

Claim 3.14.1. $\rho^{-1}(H)$ is equal to

$$X := \left\{ (a_1, \dots, a_n) \in K^n : (a_2, \dots, a_n) \in P \wedge a_n + J = \sum_{i=1}^{n-1} c_i \cdot a_i + J \right\},$$

where P is the projection of \widehat{E} on the last $n-1$ coordinates.

Proof. Obviously, \widehat{E} is contained in X , so we show the reverse inclusion. Let $(a_1, \dots, a_n) \in X$. As $(a_2, \dots, a_n) \in P$, there exists t such that $(t, a_2, \dots, a_n) \in \widehat{E}$ so $a_n - c_1 t - \sum_{i=2}^{n-1} c_i a_i \in J$. However, $(a_1, \dots, a_n) \in X$, so $a_n - \sum_{i=1}^n c_i a_i \in J$ implying that $c_1 t - c_1 a_1 \in J$. So in order to show that $(a_1, \dots, a_n) \in \rho^{-1}(H)$, we only have to verify that if $t \in \rho^{-1}(H_1)$, then also $a_1 \in \rho^{-1}(H_1)$. But $a_1 - t \in c_1^{-1} J$, which is a finite subgroup of K/\mathcal{O} . As $\rho^{-1}(H_1)$ is a ball, it contains all torsion elements ([13, Fact 3.1, Lemma 3.10]), so it contains $a_1 - t$ as well, and the conclusion follows. \square

We get

$$\rho^{-1}(H) = \left\{ (a_1, \dots, a_n) \in K^n : (a_2, \dots, a_n) \in P \wedge a_1 - \sum_{i=2}^n e_i a_i \in c_1^{-1} J \right\},$$

for some $e_i \in \mathcal{O}$.

As $c_1^{-1} J/\mathcal{O}$ is finite as well, we can find some $k \in \mathbb{N}$ large enough so that $p^k(c_1^{-1} J) \subseteq \mathcal{O}$. We claim that for any $(h_1, \dots, h_n) \in p^k H$, h_1 is uniquely determined by (h_2, \dots, h_n) . We will show that for a tuple in $\rho^{-1}(p^k H)$, the first coordinate is determined, up to \mathcal{O} -equivalence, by the last $n-1$ coordinates.

To simplify the notation, we give the argument for $n = 2$, the general case is similar. Let $(a, b), (c, d) \in \rho^{-1}(p^k H)$, with $b - d \in \mathcal{O}$. We want to prove that $a - c \in \mathcal{O}$. As $\rho^{-1}(p^k H) = p^k \widehat{H} + \mathcal{O}$, we can write $(a, b) = (p^k a' + o_1, p^k b' + o_2)$ and $(c, d) = (p^k c' + o_3, p^k d' + o_4)$, with $(a', b'), (c', d') \in \rho^{-1}(H)$.

We thus have $a' - e_2(b' + o_2), c' - e_2(d' + o_4) \in c_1^{-1} J$. Since $p^k(c_1^{-1} J) \subseteq \mathcal{O}$, we get that

$$p^k(a' - c') - p^k(e_2(b' - d')) = p^k(a' - c') - e_2 p^k(b' - d') \in \mathcal{O}.$$

By our assumption that $b - d \in \mathcal{O}$ (and since $p^k(b' - d') + \mathcal{O} = (b - d) + \mathcal{O}$), it follows that $p^k(b' - d') \in \mathcal{O}$, and since e_2 is assumed to be in \mathcal{O} , it follows from the above that $p^k(a' - c') \in \mathcal{O}$. By our assumptions, $p^k(a' - c') + \mathcal{O} = (a - c) + \mathcal{O}$, and therefore, $a - c \in \mathcal{O}$, as claimed. \square

We can finally prove Proposition 3.10.

Proof of Proposition 3.10. We proceed by induction. The case $n = 1$ is trivially true (take $k = 0$ and $\pi_0 = \text{Id}$).

Let $\pi : (K/\mathcal{O})^n \rightarrow (K/\mathcal{O})^{n-1}$ be the projection onto the first $n - 1$ coordinates. We may assume that the kernel of this projection is finite: Indeed, let $H^i := \ker(\pi^i \upharpoonright H)$ for π^i the projection dropping the i -th coordinate. If all H^i were infinite, then since $H \supseteq H^1 \times \cdots \times H^n$, we would conclude that $\text{dp-rk}(H) = n$, and there is nothing to prove. Thus, we may assume that one of the H^i is finite, and after permuting coordinates, assume that $i = n$.

Write $\ker(\pi \upharpoonright H)$ as $\{0\}^{n-1} \times J$, for a finite subgroup $J \subseteq K/\mathcal{O}$. Since $\pi \upharpoonright H$ is finite-to-one, $\text{dp-rk}(H) = \text{dp-rk}(\pi(H))$. Notice that for every $(a, b), (a, c) \in H \subseteq (K/\mathcal{O})^{n-1} \times K/\mathcal{O}$, we have $b - c \in J$, and hence, H can be viewed as the graph of a function $T : \pi(H) \rightarrow (K/\mathcal{O})/J$, mapping a to $b + J$; that is,

$$H = \{(a, b) \in (K/\mathcal{O})^n : a \in \pi(H) \wedge b + J = T(a)\}.$$

By the induction hypothesis applied to $\pi(H) \subseteq (K/\mathcal{O})^{n-1}$, there exists $\ell \in \mathbb{N}$, and a coordinate projection $\pi_1 : (K/\mathcal{O})^{n-1} \rightarrow (K/\mathcal{O})^m$ such that $\pi_1 \upharpoonright p^\ell \pi(H)$ is injective and $m = \text{dp-rk}(\pi(H))$. Without loss of generality, assume that π_1 is the projection onto the last m -coordinates $n - m, \dots, n - 1$. Let

$$H_2 = \{(a_1, \dots, a_{n-1}, a_n) \in (K/\mathcal{O})^n : (a_1, \dots, a_{n-1}) \in p^\ell \pi(H) \wedge a_n + J = T(a_1, \dots, a_{n-1})\},$$

and note that $p^\ell H \subseteq H_2$.

By assumption, H_2 is definably isomorphic via (π_1, id) to

$$H_3 = \{(a_{n-m}, \dots, a_{n-1}, a_n) \in (K/\mathcal{O})^{m+1} : (a_{n-m}, \dots, a_{n-1}) \in \pi_1(p^\ell \pi(H)) \\ \wedge a_n + J = S(a_{n-m}, \dots, a_{n-1})\},$$

for $S = T \circ (\pi_1 \upharpoonright p^\ell \pi(H))^{-1}$.

Since $\text{dp-rk}(\pi_1(p^\ell \pi(H))) = m$, we may apply Lemma 3.14 to H_3 and find $r \in \mathbb{N}$ and a coordinate projection $\pi_2 : (K/\mathcal{O})^{m+1} \rightarrow (K/\mathcal{O})^m$ (on some m coordinates) such that $\pi_2 \upharpoonright p^r H_3$ is injective. As H_2 is isomorphic to H_3 via (π_1, id) , by composing the coordinate projections, we get that $\pi_0 = \pi_2 \circ (\pi_1, \text{id})$ is injective on $p^r H_2$. Hence, it is also injective on $p^{r+\ell} H \subseteq p^r H_2$. \square

4. Topology and dimension

If D is a distinguished sort which is an SW-uniformity, it follows from [13] (see below for details) that definable D -groups inherit a group topology, τ_D , from ν_D . However, since \mathcal{K} is geometric, \mathcal{K}^{eq} inherits a notion of dimension (that turns out to be nontrivial for K -groups). In the present section, we first recall the basic properties of the dimension induced from K to \mathcal{K}^{eq} , and then study its relation with the topology τ_G in K -groups.

4.1. Geometric dimension and equivalence relations

A sufficiently saturated (one sorted) structure is *geometric* if $\text{acl}(\cdot)$ satisfies Steinitz Exchange and the quantifier \exists^∞ can be eliminated. Elimination of \exists^∞ , sometimes referred to as *uniform finiteness*, means that in definable families, there is a uniform bound on the size of finite sets.

In [9], Gagelman shows that for geometric structures, the dimension associated with the $\text{acl}(\cdot)$ -pregeometry can be extended naturally to imaginary sorts. In the present section, we review this extension

of dimension and exploit it to show that in \mathcal{K} , the K -rank and the almost K -rank of definable sets coincide (compare with [18, Corollary 4.37]).

Given a geometric structure \mathcal{M} , we remind Gagelman's extension of \dim_{acl} to \mathcal{M}^{eq} : Given a definable equivalence relation E on M^n set, and $A \subseteq \mathcal{M}^{eq}$,

$$\dim^{eq}(a_E/A) = \max\{\dim(b/A) - \dim[a] : b \in [a]\},$$

where $\dim := \dim_{\text{acl}}$, the E -equivalence class of a is $[a] \subseteq K^n$, $a_E := a/E \in M^n/E$. For $Y \subseteq X/E$ defined over A , we define

$$\dim^{eq}(Y) = \max\{\dim^{eq}(a_E/A) : a_E \in Y\}.$$

For a concise summary of the properties of \dim^{eq} , we refer to [18, §2]. In the present text, we will mostly use additivity of \dim^{eq} : For $a, b \in \mathcal{M}^{eq}$,

$$\dim^{eq}(a, b/A) = \dim^{eq}(a/Ab) + \dim^{eq}(b/A).$$

Note that \dim^{eq} coincides with \dim_{acl} on definable subsets of M^n , and on tuples in M , over parameters from M . There is, therefore, no ambiguity in extending the notation \dim (instead of \dim^{eq}) to imaginary elements and definable sets. Note, however, that in this notation for a definable set Y , $\dim(Y) = 0$ does not imply that Y is finite, unless $Y \subseteq M^n$. For example, $\dim(K/\mathcal{O}) = \dim(\Gamma) = 0$.

Whenever \mathcal{M} is in addition dp-minimal, dp-rank coincides with dimension on definable subsets of M^n ([30, Theorem 0.3]), a fact that we use without further mention. In our setting, as \mathcal{K} is a geometric structure, this implies directly from the definitions that $\dim(X) \leq \text{dp-rk}(X)$ for any definable set X in \mathcal{K}^{eq} .

Since dimension is preserved under definable finite-to-one functions, and infinite definable subsets of K^n have positive dimension, it follows that if X is locally almost strongly internal to K , then $\dim(X) > 0$.

The above observation allows us to show that, in our setting, the K -critical and the almost K -critical ranks coincide. We start with the following result [24, Lemma 3.8].

Fact 4.1. Let \mathcal{M} be a geometric structure and let E be a definable equivalence relation on M^n . Then there exists a definable $S \subseteq M^n$ such that for every $x \in S$, $[x] \cap S$ is finite and $\dim(S) = \dim(S/E) = \dim(M^n/E)$.

In the setting where $\mathcal{M} = \mathcal{K}$, we can conclude the following:

Corollary 4.2. Let Y be a definable set in \mathcal{K} (so possibly in \mathcal{K}^{eq}). If $Y_0 \subseteq Y$ is almost strongly internal to K , then there exists a definable subset $Y' \subseteq Y_0$ with $\text{dp-rk}(Y') = \text{dp-rk}(Y_0)$ that is strongly internal to K . Moreover, the following are equal:

- (1) $\dim(Y)$
- (2) The K -rank of Y
- (3) The almost K -rank of Y .

Proof. We use the fact that, in our setting, the sort K is a geometric SW-uniformity. The proof relies on the following claim.

Claim 4.2.1. For any $Z \subseteq Y$, there exists $Z_0 \subseteq Z$ strongly internal to K with $\text{dp-rk}(Z_0) = \dim(Z)$.

Proof. Assume that $Z = X'/E$ for some X' . Let $S \subseteq X'$ be a definable set, as provided by Fact 4.1. That is, $\dim(S) = \dim(Z)$, and S intersects every E -class in a finite (possibly empty) set. Let $\pi : S \rightarrow S/E$ be the finite-to-one projection map; note that $S/E \subseteq Z$ and by [30, Theorem 0.3(1)], $\text{dp-rk}(S/E) = \text{dp-rk}(S) = \dim(S) = \dim(X'/E)$.

By [13, Lemma 2.6(1)], as K is an SW-uniformity, there exists a definable subset $Z_0 \subseteq S/E \subseteq Z$ strongly internal to M and satisfying $\text{dp-rk}(Z_0) = \text{dp-rk}(S/E) = \dim(Z)$. \square

We now apply this claim to prove the statements of the corollary. First, let Y_0 be as in the statement; applying the claim for $Z = Y_0$, we get $Y' \subseteq Y_0$ strongly internal to K with $\text{dp-rk}(Y') = \dim(Y_0)$. But since Y_0 is almost strongly internal to K , dp-rk and \dim also coincide on Y_0 so $\text{dp-rk}(Y') = \dim(Y_0) = \text{dp-rk}(Y_0)$.

This result assures that the K -rank and the almost K -rank of Y are equal. To conclude, note that, since $\dim(Y)$ is obviously bounded below by the K -rank of Y , we only need to verify the other inequality. This is immediate by applying the claim to $Z = Y$. \square

4.2. Topology

Let G be a definable group in \mathcal{K} , locally strongly internal to a fixed definable SW-uniformity D (for example, $D = K$). In particular, D admits a definable basis for a topology. In this section, we review results from [13] on how to topologize G using the D -topology. For p -adically closed fields, this was done using different techniques in [18] for the case $D = K$.

The group G is automatically a D -group by [13, Fact 4.25(1)]. By [13, Proposition 5.8], there is a type-definable subgroup $\nu_D := \nu_D(G)$ of G definably isomorphic to an infinitesimal type-definable group in D . Specifically, given any D -critical set $X \subseteq G$, any definable injection $f : X \rightarrow D^n$ (for $n = \text{dp-rk}(X)$) and any $c \in X$ generic over all the data, we have (recalling that we identify partial types with collections of definable sets):

$$\nu_D = \{f^{-1}(U)c^{-1} : U \subseteq D^n \text{ definable open containing } f(c)\}. \quad (2)$$

Before proceeding with the description of ν_D , we give the proof of the statement in Remark 2.12(2), assuring that such an X can always be found.

Lemma 4.3. *Let D be an unstable distinguished sort in \mathcal{K} and G a \mathcal{K} -definable D -group. Then there exists a D -critical subset $X \subseteq G$ and a definable injection $f : X \rightarrow D^m$ for $m = \text{dp-rk}(X)$. In particular, X is a D -set.*

Proof. If D is an SW-uniformity, this follows from [31, Proposition 4.6], so we may assume that \mathcal{K} is p -adically closed and D is either Γ or K/\mathcal{O} . If $D = \Gamma$, this follows from cell-decomposition in Presburger arithmetic (as referred to in the proof of Fact 5.4). If $D = K/\mathcal{O}$ then by [13, Theorem 7.11(3)], there exists a definable subgroup $H \subseteq G$ with $\text{dp-rk}(H) = n$, the K/\mathcal{O} -rank of G , definably isomorphic to a subgroup of $((K/\mathcal{O})^r, +)$ for some $r > 0$. By Proposition 3.10, we may assume, replacing H with a subgroup of the same dp-rk , that $r = n$. \square

We now return to the assumption that D is an SW uniformity. Note that ν_D is given as a definable collection of sets $\{U_t : t \in T\}$ which forms a filter-base: for every $t_1, t_2 \in T$, there is $t_3 \in T$ such that $U_{t_3} \subseteq U_{t_1} \cap U_{t_2}$. By [13, Corollary 5.14], G has a definable basis for a topology $\tau_D = \tau_D(G)$, making G a non-discrete Hausdorff topological group. **For the rest of this section, all topological notions in G refer to τ_D .**

A definable subset $X \subseteq G$ is open in this topology if and only if for all $a \in Xa \cdot \nu_D \subseteq X$. In particular, $\text{dp-rk}(X) \geq \text{dp-rk}(\nu_D)$ (i.e., the dp-rk of any open definable subset of G is at least the D -rank of G). Of course, it could be, for example, that $\text{dp-rk}(G) > \text{dp-rk}(\nu_D)$, so that definable open subsets need not all have the same dp-rk (but they all have the same D -rank).

The next lemma shows that the topology G inherits from D shares some of its good properties. Toward that end, recall that the D -rank of a set Z is the maximal dp-rk of a definable subset strongly internal to D . We let $\text{Fr}(X)$, the frontier of X , denote $\text{cl}(X) \setminus X$.

Lemma 4.4. *If $X \subseteq G$ is definable, then the D -rank of $\text{Fr}(X)$ is strictly smaller than the D -rank of X .*

Proof. Let d denote the D -rank of $\text{Fr}(X)$ and let $X_1 \subseteq \text{Fr}(X)$ be D -critical over A . Fix an A -generic $g \in X_1$ and $Y \ni g$ a definable basic open set. In particular, we can choose Y to be strongly internal to D .

By definition of $\text{Fr}(X)$, it follows that $\text{Fr}(X) \cap Y = \text{Fr}(X \cap Y)$. By Lemma 2.17, $\text{dp-rk}(X_1 \cap Y) = \text{dp-rk}(X_1)$. By the properties of SW-uniformities, ([31, Proposition 4.3, Lemma 2.3]), and since $X \cap Y$ can be identified with a subset of some D^n , $\text{dp-rk}(\text{Fr}(X \cap Y)) < \text{dp-rk}(X \cap Y)$. Thus, as $X_1 \cap Y \subseteq \text{Fr}(X \cap Y)$,

$$d = \text{dp-rk}(X_1) \leq \text{dp-rk}(\text{Fr}(X \cap Y)) < \text{dp-rk}(X \cap Y).$$

Since $X \cap Y$ is strongly internal to D (as Y was), its dp-rank is at most the D -rank of X , as needed. \square

Lemma 4.5. *If H is a definable subgroup of G , then H is closed in G and the following are equivalent:*

- (1) H is open,
- (2) the D -ranks of H and G are equal,
- (3) $\nu_D \vdash H$.

Proof. Because G is a topological group, and a basis for the topology is definable, the closure of H , call it H_1 , is also a definable subgroup. Therefore, if $H_1 \setminus H \neq \emptyset$, then H_1 must contain a coset of H ; thus, the D -rank of $H_1 \setminus H$ is at least that of H contradicting Lemma 4.4. So H is closed in G .

Now, assume that the D -ranks of H and G are equal. This implies (by definition of ν_D) that $\nu_D \vdash H$. Since ν_D is open, and H is a group, this implies that H is open. Finally, as we have seen, if H is open, then it contains ν_D as a subgroup, and therefore, they have the same D -rank (since the D -rank of ν_D is maximal in G). \square

Definition 4.6. For G locally strongly internal to D , we let the *centralizer of the type ν_D* , denoted by $C_G(\nu_D)$, be the set of all $g \in G$ such that for some definable Y with $\nu_D \vdash Y$, g commutes with all elements of Y .

Since, as we noted, ν_D is given as a definable collection of sets $\{U_t : t \in T\}$, it follows that $C_G(\nu_D)$ is definable: $g \in C_G(\nu_D)$ if there exists $t \in T$ such that $g \in C_G(U_t)$. Moreover, by the filter-base property of the family, it is a subgroup of G .

Remark 4.7. Let us note that, despite its name, if $\mathcal{K} < \hat{\mathcal{K}}$, and $g \in C_G(\nu_D)(\hat{\mathcal{K}})$, then g does not necessarily centralize the set $\nu_D(\hat{\mathcal{K}})$. What we know is that there exists $t \in T(\hat{\mathcal{K}})$ such that g centralizes $U_t(\hat{\mathcal{K}})$ with possibly $U_t \vdash \nu_D(\mathcal{K})$.

Recall that definable sets in o-minimal structures can be decomposed into finitely many definably connected sets (i.e., sets containing no non-trivial definable clopen sets). Thus, the same is true if $X \subseteq G$ is strongly internal to an o-minimal sort D . The result below will be useful in the sequel.

Lemma 4.8. *Assume that D is one of the o-minimal distinguished sorts. Assume that $X \subseteq G$ is definable, strongly internal to D and $e \in X$. If X is definably connected, then every $g \in C_G(\nu_D)$ centralizes X .*

Proof. Let $g \in C_G(\nu_D)$. By definition, $\nu_D \vdash C_G(g)$, so by Lemma 4.5, $C_G(g)$ is a clopen subgroup of G . Now, $C_G(g) \cap X \neq \emptyset$ (as e is in the intersection), so definable connectedness of X implies $X \subseteq C_G(g)$. \square

For the rest of this section, we focus our attention on the case $D = K$ (so, in particular, it is an SW-uniformity), and the topology we discuss below is the one coming from K .

We start with an immediate corollary of Lemma 4.5 and Corollary 4.2.

Corollary 4.9. *Let G be a definable group and H a definable subgroup. Then H is open in G if and only if $\dim(G) = \dim(H)$.*

As the distinguished sorts, Γ , \mathbf{k} and K/\mathcal{O} , are 0-dimensional, we get the following:

Lemma 4.10. *A definable set S is K -pure if and only if every definable 0-dimensional $X \subseteq S$ is finite.*

Proof. Assume that $X \subseteq S$ is infinite and 0-dimensional. By Fact 2.4, X (and hence also S) is locally almost strongly internal to some distinguished sort D . Namely, there is a definable infinite $X_1 \subseteq X$ and a definable finite to one function $f : X_1 \rightarrow f(X_1) \subseteq D^n$. Since $\dim(X_1) \geq \dim(f(X_1))$, necessarily $\dim(f(X_1)) = 0$ with $f(X_1)$ infinite. Hence, $D \neq K$, so S is not K -pure.

For the converse, assume that S is not K -pure, witnessed by a definable infinite $X \subseteq S$ and a definable finite to one function $f : X \rightarrow D^n$ for some $D \neq K$. Since $\dim(D) = 0$ for $D \neq K$, it follows that $\dim(f(X)) = 0$, and hence, $\dim(X) = 0$. So, X is infinite and 0-dimensional. \square

For the sake of completeness, we note that the τ_K -topology on G is *locally Euclidean*, in the following sense: for every $g \in G$, there exists a definable open $U \ni g$, which is definably homeomorphic to an open subset of $K^{\dim(G)}$. Moreover, it is the unique such group topology on G .

We prove:

Lemma 4.11. *The τ_K -topology on G (taken to be discrete if $\dim G = 0$) is locally Euclidean, and if τ is any other locally Euclidean group topology on G , then $\tau = \tau_K$.*

In particular, if K is a p -adically closed field, τ_K equals Johnson's admissible topology from [18].

Proof. A non-discrete locally Euclidean topological group is, by definition, a K -group, so (by Corollary 4.2) $\dim(G) > 0$, and since discrete groups are trivially locally Euclidean, we assume $\dim(G) > 0$. Since the topology is invariant under translations, it is sufficient to find a single $g \in G$ at which the topology is locally Euclidean. If $n = \dim(G) > 0$, then, by Lemma 4.2, there exists a definable $X \subseteq G$, $\dim(X) = \dim(G)$, such that X is strongly internal to K , over some A , and $\dim(G)$ is the K -rank of G . Given g_1 generic in X over A , it follows from Equation (2) at the beginning of Section 4.2 that there exists a definable τ_K -open set U , $g_1 \in U \subseteq X$, which is definably homeomorphic to an open set in K^n .

Now, assume that τ_1, τ_2 are two locally Euclidean group topologies on G . Then for $g \in G$, there are definable $U_1, U_2 \ni g$, U_i a τ_i -open set, and definable $f_i : U_i \rightarrow V_i \subseteq K^n$, such that each f_i is a homeomorphism between U_i with the τ_i -topology and open V_i with the K^n -topology.

The map $f_2 f_1^{-1} : f_1(U_1 \cap U_2) \rightarrow V_2$, is a definable injection. However, in SW-uniformities, definable bijections are homeomorphisms at generic points, [31, Corollary 3.8]. Thus, there is some $g_1 \in U_1 \cap U_2$ such that on τ_1, τ_2 open neighborhood of g_1 , the two topologies agree. Thus, $\tau_1 = \tau_2$.

Since Johnson's admissible topology is locally Euclidean, the two topologies are the same. \square

Using the exact same proof as above, one can show that for any distinguished sort D which is an SW-uniformity, if G is locally strongly internal to D , then every $g \in G$ has a τ_D -open neighborhood which is definably homeomorphic to an open set in D^m , where m is the D -rank of G .

5. The infinitesimal group ν_D and local (differentiable) groups

In Section 2.5, we gave an abstract description of $\nu_D(G)$ for an infinite definable D -group G and an unstable distinguished sort D . In the present section, we collect – for later use – more specific information on the construction of $\nu_D(G)$, as D ranges over the various distinguished sorts in the different settings we are interested in. Throughout, we fix an infinite group G definable in \mathcal{K} .

5.1. The sort of closed 0-balls K/\mathcal{O}

Let G be an infinite definable K/\mathcal{O} -group. In each of our three settings, there exists a definable subgroup $H \subseteq G$ definably isomorphic to a subgroup of $((K/\mathcal{O})^m, +)$ for some $m > 0$, such that $\text{dp-rk}(H)$ is the K/\mathcal{O} -rank of G [13, Theorems 7.4(4), 7.7(4), 7.11(3)]. By Lemma 3.5 (if \mathcal{K} is V -minimal or power-bounded T -convex), or by Proposition 3.10 (if \mathcal{K} is p -adically closed), we can, after possibly shrinking H but not its dp-rk , choose $m = \text{dp-rk}(H)$.

Recall that the valuation descends to K/\mathcal{O} and $(K/\mathcal{O})^n$, and hence, so does the notion of a ball. However, we reserve the term ‘ball’ for an infinite set; thus, in the p -adically closed case, we require the valuative radius to be infinitely negative (i.e., smaller than n for all $n \in \mathbb{Z}$).

We may now further assume that H is definably isomorphic to a definable ball (of the same rank) centered at 0:

Fact 5.1. For any A -definable set $X \subseteq (K/\mathcal{O})^n$ with $\text{dp-rk}(X) = n$ and any A -generic $a \in X$, there exists a ball $B \subseteq X$ with $a \in B$.

Proof. If \mathcal{K} is power-bounded T -convex or V -minimal, then this is [31, Corollary 2.7], and if \mathcal{K} is p -adically closed, this is [13, Lemma 3.6]. \square

We can now give, keeping the above notation and assumptions, a more specific description of the construction of $\nu_{K/\mathcal{O}}$:

Lemma 5.2. *Let $f : H \rightarrow (K/\mathcal{O})^n$ be an A -definable injective homomorphism, $\text{dp-rk}(H) = n$ the K/\mathcal{O} -rank of G . Then*

$$\nu_{K/\mathcal{O}} = \{f^{-1}(U) : U \subseteq (K/\mathcal{O})^n \text{ is an open ball in } (K/\mathcal{O})^n \text{ centered at } 0\}.$$

Proof. Let $\nu_1 := \{f^{-1}(U) : U \subseteq (K/\mathcal{O})^n \text{ is an open ball in } (K/\mathcal{O})^n \text{ centered at } 0\}$.

By definition, $\nu_{K/\mathcal{O}} = \nu_H(c)c^{-1}$ for any A -generic $c \in H$. Let $H_1 := f(H) \leq (K/\mathcal{O})^n$. Since $\text{dp-rk}(H_1) = n$, by Fact 5.1, we may assume, shrinking H (but not its rank) if needed, that H_1 is a ball in $(K/\mathcal{O})^n$.

We first show that $\nu_{K/\mathcal{O}} \vdash \nu_1$. Let $U \subseteq H_1$ be an open ball, $0 \in U$. By [12, Proposition 3.12] (if \mathcal{K} is power-bounded T -convex or V -minimal) or [13, Proposition 3.8] (if \mathcal{K} is p -adically closed), there exists a ball $Y \subseteq U + f(c)$, $f(c) \in Y$, definable over some $B \supseteq A$ such that $\text{dp-rk}(f(c)/B) = n$. Since H_1 is a subgroup, we have $Y \subseteq H_1$. Now, as f is a group homomorphism, $f^{-1}(Y - f(c)) = f^{-1}(Y)c^{-1} \subseteq f^{-1}(U)$, $c \in f^{-1}(Y)$, and $\text{dp-rk}(c/B) = n$. Thus, by the definition of $\nu_{K/\mathcal{O}}$, we have $\nu_{K/\mathcal{O}} \vdash f^{-1}(U)$, so $\nu_{K/\mathcal{O}} \vdash \nu_1$.

Similarly, $f(\nu_1)c \vdash \nu_{H_1}(c)$, so we conclude that $\nu_1 \vdash \nu_{K/\mathcal{O}}$. \square

5.2. The valuation group Γ .

When \mathcal{K} is either power bounded T -convex or V -minimal, the valuation group Γ is o-minimal; when it is p -adically closed, it is a model of Presburger arithmetic. In order to get a uniform treatment (and formulation of results), we make the following definition:

Definition 5.3. A subset $B \subseteq \Gamma^n$ is called a Γ -box (around $a = (a_1, \dots, a_n)$) if it is of the following form:

- (1) (In the non p -adic case) $\prod_{i=1}^n (b_i, c_i)$ for some $b_i < a_i < c_i$ in Γ .
- (2) (In the p -adic case) A cartesian product of n -many sets of the form $(b_i, c_i) \cap \{x_i : x_i - a_i \in P_{m_i}\}$ where both intervals (b_i, a_i) and (a_i, c_i) are infinite and P_{m_i} is the predicate for m_i -divisibility.

Fact 5.4. Let $Y \subseteq \Gamma^m$ be a definable set with $\text{dp-rk}(Y) = n \leq m$. Then there exists a definable $Z \subseteq Y$ with $\text{dp-rk}(Z) = n$ projecting injectively onto a Γ -box in Γ^n .

Proof. If \mathcal{K} is power-bounded T -convex or V -minimal, Γ is o-minimal and the result follows by cell-decomposition.

If \mathcal{K} is p -adically closed, then Γ is a model of Presburger arithmetic. It also admits a cell-decomposition [5] (see also [21, Fact 2.4] for a more explicit formulation), and thus, the result follows from the fact that dimension coincides with dp-rank ([30, Theorem 0.3]). \square

Using Fact 5.4 and [13, Lemma 4.2] repeatedly (as in the proof of Lemma 5.2 above), we get the following.

Lemma 5.5. *Let G be a definable Γ -group and $g : Y \rightarrow \Gamma^n$ be a definable injection with $\text{dp-rk}(Y) = n$ the Γ -rank of G . Assume everything is defined over some parameter set A , and $c \in Y$ is A -generic. Then*

$$\nu_Y(c) = \{g^{-1}(U) : U \subseteq \Gamma^n \text{ a } \Gamma\text{-box around } g(c)\}.$$

We can now conclude:

Lemma 5.6. *Let G be a definable Γ -group. There exists $X \subseteq G$, a Γ -critical set with $\nu_\Gamma \vdash X$, and $f : X \rightarrow \Gamma^n$ a definable injection satisfying:*

- (1) $f(X)$ is a Γ -box around 0,
- (2) $f(xy^{\pm 1}) = f(x) \pm f(y)$ for any $x, y \in X$ with $xy^{\pm 1} \in X$ and
- (3) $v_{\Gamma} = \{f^{-1}(U) : U \subseteq \Gamma^n \text{ a } \Gamma\text{-box around } 0\}$.

Proof. By [13, Theorems 7.4(3), 7.7(3), 7.11(2)], v_{Γ} is definably isomorphic (as groups) to a type-definable subgroup of $(\Gamma^r, +)$ for some $r > 0$, and using Fact 5.4, we may further assume that $r = n$. As this isomorphism is witnessed by an isomorphism of groups, the result follows by compactness and Lemma 5.5. \square

5.3. The valued field and the residue field

For this section, D is either the valued field K or the residue field \mathbf{k} when \mathcal{K} is power bounded T -convex. We first describe the infinitesimal group v_D and then show how in these situations, the type-definable group v_D gives rise to a definable, differentiable local group with respect to either K or \mathbf{k} .

5.3.1. Local differential groups

Let \mathcal{F} be an expansion of either a real closed field or a valued field with valuation v . Let us recall some standard definitions. We later apply them for when $\mathcal{F} = D$.

Definition 5.7. Given $U \subseteq \mathcal{F}^n$ open, a map $f : U \rightarrow \mathcal{F}^m$ is *differentiable* at $x_0 \in U$ if there exists a linear map $D_{x_0}f : \mathcal{F}^n \rightarrow \mathcal{F}^m$ such that

In the ordered case,

$$\lim_{x \rightarrow x_0} \frac{|f(x) - f(x_0) - (D_{x_0}f) \cdot (x - x_0)|}{|x - x_0|} = 0,$$

and in the valued case,

$$\lim_{x \rightarrow x_0} [v(f(x) - f(x_0) - (D_{x_0}f) \cdot (x - x_0)) - v(x - x_0)] = \infty.$$

Also, in the valued setting, f is called *strictly differentiable* at x_0 if there exists a linear map $D_{x_0}f$ which satisfies: for all $\epsilon \in \Gamma$, there exists $\delta \in \Gamma$, such that for all $x_1, x_2 \in B_{>\delta}(x_0)$,

$$v(f(x_1) - f(x_2) - (D_{x_0}f) \cdot (x_1 - x_2)) - v(x_1 - x_2) > \epsilon.$$

We are going to work extensively with the notion of a *local group*, so we first recall some additional definitions:

Definition 5.8. A *local group with respect to \mathcal{F}* is a tuple $\mathcal{G} = (X, m, \iota, e)$ such that

- X is a topological space, and there exists a homeomorphism $\varphi : U \rightarrow V$ between an open neighborhood of e in X and an open $V \subseteq \mathcal{F}^n$, for some n .
- the maps $m : X \times X \dashrightarrow X$ and $\iota : X \dashrightarrow X$ are continuous *partial* functions, with open domains containing (e, e) and e , respectively.

such that the following equalities hold **whenever both sides of the equations are defined**:

- (1) For any $x \in X$, $x = m(x, e) = m(e, x)$
- (2) For any $x \in X$, $e = m(x, \iota(x)) = m(\iota(x), x)$.
- (3) For all $x, y, z \in X$, $m(x, m(y, z)) = m(m(x, y), z)$.

The local group \mathcal{G} is *differentiable* if $\varphi(m(\varphi^{-1}(x), \varphi^{-1}(y)))$ and $\varphi(\iota(\varphi^{-1}(x)))$ are differentiable. *Strictly differentiable* local groups are defined analogously.

The local group \mathcal{G} is *definable* in \mathcal{F} , if X, m, ι and φ are definable.

For G a definable group, a *definable local subgroup with respect to \mathcal{F}* is a local subgroup with respect to \mathcal{F} whose universe is a definable subset of G and whose multiplication agrees with G -multiplication.

Definition 5.9. Let $\mathcal{G} = (X, m, e, \iota)$ and $\mathcal{G}' = (X', m', e', \iota')$ be local groups. A *homomorphism* of local groups $f : \mathcal{G} \rightarrow \mathcal{G}'$ is a continuous function $f : U \rightarrow X'$, where $U \subseteq X$ is an open neighborhood of e , such that $f(e) = e'$ and $f(m(x, y)) = m'(f(x), f(y))$ in a neighborhood of e . Such an f is a *local isomorphism* if, in addition, it is a homeomorphism onto its image. If $\mathcal{G}, \mathcal{G}'$ are (strictly) differentiable local groups, then such an f is (strictly) *differentiable* if $\varphi' \circ f \circ \varphi^{-1}$ is (strictly) differentiable.

For G a definable group, a local subgroup \mathcal{G} is called *normal in G* if for every $g \in G$, the map $x \mapsto x^g$ restricts to a local automorphism of \mathcal{G} . In particular – in the notation of local subgroups – for any definable open neighborhood $U \subseteq X$ of e , there exists an open neighborhood $V \subseteq X$ of e such that $x \mapsto x^g$ maps V into U .

Assume further that every definable function in \mathcal{F} is (strictly) *generically differentiable* (i.e., for every definable open $U \subseteq \mathcal{F}^n$, and definable $f : U \rightarrow \mathcal{F}$, the set of points $x \in U$ such that f is not (strictly) differentiable at x has empty interior). See [12, Section 4.3] for more information.

Now, if $\mathcal{G}, \mathcal{G}'$ as above are (strictly) differentiable local groups and $f : \mathcal{G} \rightarrow \mathcal{G}'$ is a definable homomorphism of local groups, then f is also (strictly) differentiable. Indeed, since definable functions are generically (strictly) differentiable with respect to \mathcal{F} , the corresponding map $\varphi' \circ f \circ \varphi$ is \mathcal{F} -(strictly) differentiable at a generic point, and then, using the local group structure, it is (strictly) differentiable on an open neighborhood of e .

Definition 5.10. Let G be a definable group in \mathcal{M} and let $\mathcal{G} = (X, \cdot, {}^{-1})$ be a differentiable normal local subgroup of G with respect to \mathcal{F} , witnessed by a map $\varphi : X \rightarrow \mathcal{F}^n$. The *Adjoint map with respect to \mathcal{F}* is the map $\text{Ad}_{\mathcal{F}}^{\mathcal{G}} : G \rightarrow \text{GL}_n(\mathcal{F})$, which assigns to every $g \in G$ the Jacobian matrix of the map $D_e(\varphi \circ \tau_g \circ \varphi^{-1})$.

By the chain rule in \mathcal{F} , $\text{Ad}_{\mathcal{F}}^{\mathcal{G}}$ is a group homomorphism.

Note that while the matrix $D_e(\tau_g)$ may depend on the choice of φ (up to conjugation), the definable group $\ker(\text{Ad}_{\mathcal{F}}^{\mathcal{G}})$ does not.

5.3.2. The infinitesimal group

Under the assumptions of this section, the sort D is an SW-uniformity expanding a field. Therefore, if $X \subseteq D^k$ is definable, $f : X \rightarrow D^m$ is a definable injection, then by possibly shrinking X , but not its rank, we may compose f with a projection $\pi : X \rightarrow D^{\text{dp-rk}(X)}$ such that $\pi \circ f(X)$ is a basic open set.

Furthermore, every definable function in D is generically differentiable with respect to D in the o-minimal case and generically strictly differentiable in the valued case. Indeed, if $D = \mathbf{k}$ in the power bounded T -convex case, then \mathbf{k} is a o-minimal, so every definable function is generically differentiable. In the other cases, it follows from 1- h -minimality ([1, Proposition 3.12]).

Fact 5.11. Let G be a definable D -group, locally strongly internal to D over A , witnessed by the definable injection $f : X \rightarrow D^n$, with $\text{dp-rk}(X) = n$, the D -rank of G . Given $c \in X$, generic over A ,

$$\nu_D(G) = \{f^{-1}(U)c^{-1} : U \subseteq D^n \text{ open containing } f(c)\}.$$

Proof. By [13, Proposition 5.6], for $c \in X$, A -generic $\nu_X(c) = f^{-1}(\mu(f(c)))$, where $\mu(f(c))$ is the infinitesimal neighborhood of $f(c)$ in the topology on D . The result now follows. \square

Lemma 5.12. Let G be a definable D -group locally strongly internal to D .

Then there exists a definable differentiable local normal subgroup $\mathcal{G} = (X, \cdot, {}^{-1}, e)$ with respect to the field D , with $\nu_D(G) \vdash X$. When $D = K$ the local group is strictly differentiable.

If G is definable over some $K_0 < K$, then the local group and the map $\varphi : X \rightarrow D^n$ witnessing it can be found definable over K_0 .

Proof. Let $\nu_D = \nu_D(G)$. By Fact 5.11, $\nu_D \vdash X$, for some definable ν_D -open set $X \subseteq G$, and there exists a definable injection $\varphi : X \rightarrow D^n$, with $\varphi(X)$ a definable open subset of D^n and n the D -rank of G (indeed, in the notation of the above Fact, replace Xc^{-1} by X).

Let $\widehat{\mathcal{K}} > \mathcal{K}$ be a $|\mathcal{K}|^+$ saturated elementary extension. By [13, Theorem 7.4(1,2), Theorem 7.7(1), Theorem 7.11(1)], $\nu_D(\widehat{\mathcal{K}})$ is a (differentiable) Lie group with respect to the structure induced by φ . Furthermore, since every definable function in the valued field case is generically strictly differentiable, a similar proof shows in this case that $\nu_D(\widehat{\mathcal{K}})$ is a strictly differentiable Lie group. Furthermore, $g\nu_D g^{-1} = \nu_D$ for any $g \in G(\mathcal{K})$ (Fact 2.14).

Using compactness, we can endow X with the structure of a (strictly) differentiable local normal subgroup of G with respect to the field D .

Lastly, if G is definable over \mathcal{K}_0 , then since the existence of X and φ with the desired properties is first order, such can be found over \mathcal{K}_0 as well. \square

Combining the last lemma with Definition 5.10, we can find a definable group representation $\text{Ad}_D^{\mathcal{G}} : G \rightarrow \text{GL}_n(D)$, for n the D -rank of G . As noted after Definition 5.10, the map $\text{Ad}_D^{\mathcal{G}}$ depends on \mathcal{G} (i.e., on X and φ), only up to a change of coordinates. In particular, the group $\ker(\text{Ad}_D^{\mathcal{G}})$ does not depend on the choice of \mathcal{G} , and the image $\text{Ad}_D^{\mathcal{G}}(G)$ is independent of \mathcal{G} , up to conjugation. As for the latter, since we do not care about the particular embedding in $\text{GL}_n(D)$, the choice of \mathcal{G} is unimportant, and **we will write, from now on, $\text{Ad}_D(G)$ without specifying any choice of local subgroup \mathcal{G} .**

For future reference, we single out the following corollary of Lemma 5.12 and the above discussion:

Remark 5.13. Given a D -group G defined over a model \mathcal{K}_0 , the subgroup $\ker(\text{Ad}_D(G))$ is definable over \mathcal{K}_0 .

6. Groups locally strongly internal to Γ

As above, \mathcal{K} denotes a saturated model of one of our valued fields, Γ its valued group. Since Γ^n and $(K/\mathcal{O})^n$ are commutative, so are their (local) subgroups. In the present and the next section, we show that this is reflected in a strong sense in definable Γ -groups or K/\mathcal{O} -groups. For Γ -groups, we get a clean result: definable Γ -groups contain infinite definable normal abelian subgroups. We prove (keeping the notation and conventions of the previous sections):

Proposition 6.1. *Assume that G is a definable group locally strongly internal to Γ . Then G contains a definable normal subgroup G_1 of finite index, defined over the same parameters as G , such that $\nu_{\Gamma} \vdash Z(G_1)$. In particular, G contains a definable (over the same parameter set) infinite normal abelian subgroup.*

The proof splits between the p -adic case (where Γ is discrete) and the remaining cases (where Γ is dense and \mathcal{O} -minimal).

6.1. $\mathcal{K}p$ -adically closed

We assume that \mathcal{K} is p -adically closed, and thus, Γ is a model of Presburger arithmetic. Let \mathbb{Z} be a prime (and minimal) model for Γ . We denote by \mathbb{Z}_{Pres} the structure $(\mathbb{Z}, +, <)$.

Before proceeding to the proof of Proposition 6.1 in this setting, we need some preparatory results:

Lemma 6.2. *For any definable family, $\{X_t\}_{t \in T}$, of subsets of Γ^n the family $\{X_t \cap \mathbb{Z}^n\}_{t \in T}$ is definable in \mathbb{Z}_{Pres} .*

Proof. Because \mathcal{K} is p -adically closed, Γ is stably embedded, so we may assume that $T \subseteq \Gamma^k$ for some k . Since in Presburger arithmetic types over \mathbb{Z} are (uniformly) definable, the family $\{X_t \cap \mathbb{Z}^n : t \in T\}$ is definable in \mathbb{Z}_{Pres} . See [7, Theorem 0.7] (and also [8]). \square

Lemma 6.3. *Let $\{X_t : t \in T\}$ be a definable family of subsets of Γ^n and assume that for all $t \in T$, $X_t \cap \mathbb{Z}^n$ contains a subgroup of \mathbb{Z}^n of finite index. Then there is a uniform upper bound on $l(t)$, the minimal $l \in \mathbb{N}$ such that $X_t \cap \mathbb{Z}^n$ contains a subgroup \mathbb{Z}^n of index l .*

Proof. Assume toward a contradiction that there is no bound on $l(t)$ for $t \in T$. So the following type is consistent:

$$\rho(t) := \{D \not\subseteq X_t : D \subseteq \mathbb{Z}^n \text{ finite, generating a definable subgroup of finite index}\},$$

contradicting the assumption. \square

Lemma 6.4.

- (1) Let $Y \subseteq \Gamma^n$ be a definable set. If $Y \cap \mathbb{Z}^n$ contains a subgroup of \mathbb{Z}^n of finite index, then $\text{dp-rk}(Y) = n$.
- (2) Every finite index subgroup $H \leq \Gamma^n$ is definable.

Proof. By Fact 6.2, $Y \cap \mathbb{Z}^n$ is definable in \mathbb{Z}_{Pres} , as a subset of \mathbb{Z}^n . Since it contains a finite index subgroup, it has dp-rank n . Thus, we have $\mathbb{Z}_{Pres} < \Gamma$ and $\text{dp-rk}(Y \cap \mathbb{Z}^n) = n$. It follows by [12, Lemma 3.10] that $\text{dp-rk}(Y) = n$. For Clause (2), let $H \leq G$ be a definable subgroup of finite index, and note that since H has finite index, there is $k \in \mathbb{N}$ such that the map $x \mapsto kx$ sends Γ^n into H . Because $k\Gamma^n$ has finite index in Γ^n , it follows that H is a union of finitely many cosets of $k\Gamma^n$, H is definable. \square

Recall Definition 5.3 of a Γ -box.

Lemma 6.5. Let $Y \subseteq \Gamma^n$ be a definable set such that $Y \cap \mathbb{Z}^n$ contains a subgroup H of \mathbb{Z}^n of finite index. Assume that $\{f_t\}_{t \in T}$ is a definable family of definable functions $f_t : Y \rightarrow Y$ such that for all $a, b \in Y$ with $a + b \in Y$, we have $f_t(a + b) = f_t(a) + f_t(b)$. Then

- (1) For every $t \in T$, $f_t(H) \subseteq \mathbb{Z}^n$.
- (2) The family $\{f_t \upharpoonright H : t \in T\}$ is uniformly definable in \mathbb{Z}_{Pres} and therefore finite.

Proof. Assume everything is definable over some parameter set A . By stable embeddedness of Γ , the family $\{f_t : t \in T\}$ is uniformly definable in Γ , so we may assume that $T \subseteq \Gamma^k$. Since H is a subgroup of finite index of \mathbb{Z}^n , it is generated by some finite set $\{m_1, \dots, m_s\} \subseteq \mathbb{Z}^n$.

(1) Fix some $t \in T$. It suffices to prove that each coordinate function of f_t sends H into \mathbb{Z} . So we may assume $f_t : Y \rightarrow \Gamma$. Let $c \in Y$ be A -generic in Y .

Since $\text{dp-rk}(Y) = n$, it follows from cell decomposition, [5, Theorem 1] and [21, Lemma 3.4] that there is an A -definable n -dimensional Γ -box, $B = \prod_i J_i \subseteq Y$, centered at $c = (c_1, \dots, c_n) \in B$, such that

$$(f_t \upharpoonright B)(x) = \sum_i s_i \left(\frac{x - t_i}{k_i} \right) + \gamma,$$

with $\gamma \in \Gamma^n$, $s_i, t_i, k_i \in \mathbb{N}$ and $J_i = I_i \cap \{x - t_i \in P_{k_i}\}$, for some infinite interval I_i .

By shrinking B , if needed (over the same parameters), we may assume that B is a product of boxes of the form $I_i \cap P_k(x_i - t_i)$ (i.e., that $k_i = k$ for all i).

Note that for every $\bar{r} \in \mathbb{Z}^n$, we have by the above description of f_t that $f_t(c + k\bar{r}) - f_t(c) \in \mathbb{Z}$. In particular, if m_i , $1 \leq i \leq s$, is any of the generators of H we fixed earlier, then we have $c, c + km_i$ and km_i all in Y , so by the additivity assumptions,

$$f_t(km_i) = f_t(c + k\bar{r}) - f_t(c) \in \mathbb{Z}.$$

However, since $f_t(km_i) = kf_t(m_i)$, this implies that $f_t(m_i) \in \mathbb{Z}$ and, as this is true of a set of generators of H , we see that $f_t(H) \subseteq \mathbb{Z}$, as claimed.

(2) The first part of the claim is a consequence of Fact 6.2 using Lemma 6.4. The second part follows from quantifier elimination in Presburger arithmetic, by noting that any definable family of group homomorphisms is finite (see also [21, Fact 2.10]). \square

We can now give the proof of Proposition 6.1 in p -adic case.

Proof of Proposition 6.1 in the p -adic case. We assume that G is locally strongly internal to Γ . By Lemma 5.6, there are a definable $X \subseteq G$, with $v_\Gamma \vdash X$, and a definable function, $f : X \rightarrow \Gamma^n$, with $\text{dp-rk}(X) = n$ for n the Γ -rank of G . For simplicity of notation, identify X with its image in Γ^n and e_G with 0_{Γ^n} . We may further assume that, restricted to X , G -multiplication coincides with addition and the same for the inverse. By Lemma 5.6, we may further assume that v_Γ is the intersection of Γ -boxes around 0. We fix one such Γ -box $B \subseteq X \subseteq \Gamma^n$, $v_\Gamma \vdash B$.

By [13, Proposition 5.8], $gv_\Gamma g^{-1} = v_\Gamma$ for every $g \in G$, and thus, $v_\Gamma \vdash B^g \cap B$. By compactness, for every $g \in G$, there exists a Γ -box $B_0 \subseteq B \cap B^g$ around 0. By Lemma 6.5(1), $B \cap \mathbb{Z}^n$ is a subgroup of \mathbb{Z}^n of finite index (though B^g need not be contained in Γ^n).

By Lemma 6.3, there is some natural number k such that for any $g \in G$, $B^g \cap B$ contains a box B_g with $B_g \cap \mathbb{Z}^n$ a subgroup of index at most k in \mathbb{Z}^n . Consequently, there exists some subgroup $H \subseteq \mathbb{Z}^n$ of finite index such that $H \subseteq B \cap B^g \cap \mathbb{Z}^n$ for all g .

Let $Y = \bigcap_{g \in G} B^g$. It is a definable set, contained in $B \subseteq \Gamma^n$, invariant under conjugation by all elements of G and containing H . Let $Y_0 := Y \cap \mathbb{Z}^n$ (note that $H \subseteq Y_0$), and for every $g \in G$ let $\tau_g : Y \rightarrow Y$, denote the restriction of conjugation by g to Y . By Lemma 6.5(1), $\tau_g(H) \subseteq \mathbb{Z}^n$. By Lemma 6.5(2), $\{\tau_g \upharpoonright H\}_{g \in G}$ is a family of group homomorphisms uniformly definable in \mathbb{Z} , so it is finite. We may now replace H by the (finite) intersection of all $\tau_g(H)$, and obtain another subgroup of \mathbb{Z}^n of finite index. Thus, we may assume that H is invariant under all τ_g .

Let R be a finite set of generators for H and let $E(g, h)$ be the definable equivalence relation on G given by $d^g = d^h$ for all $d \in R$. Since addition on H coincides with Γ -multiplication, and for all $g, h \in G$, both $\tau_g \upharpoonright H$ and $\tau_h \upharpoonright H$ are homomorphisms preserving H , it follows that $E(g, h)$ holds if and only if $\tau_g \upharpoonright H = \tau_h \upharpoonright H$. The definable quotient G/E can be identified with a finite subgroup of $\text{Aut}(H)$, and the map $\sigma : G \rightarrow G/E$ is a definable group homomorphism. Its kernel, call it G_1 , is a definable normal subgroup of G of finite index, that – by definition – centralizes H , and hence, $H \subseteq Z(G_1)$. We claim that $v_\Gamma \vdash Z(G_1)$.

By Lemma 6.4(2), H is definable in \mathbb{Z}_{Pres} and $Z(G_1)$ contains all finite boxes of the form $[-a, a]^n \cap H$, for $a \in \mathbb{N}$. Since H is definable, $Z(G_1)$ must contain a set of the form $I^n \cap H(K)$, for an infinite interval $I \subseteq \Gamma$, so in particular, it contains a Γ -box. It follows that $v_\Gamma \vdash Z(G_1)$, and therefore, $Z(G_1)$ is a definable infinite normal subgroup of G . \square

We postpone the proof that G_1 can be taken to be definable over the same parameters as G to the next section (since the proof is similar).

6.2. \mathcal{K} is power bounded T -convex or V -minimal

We now assume that \mathcal{K} is either power bounded T -convex or V -minimal, so that Γ is an (o-minimal) ordered vector space. Recall Definition 5.3 of a Γ -box.

Proof of Proposition 6.1 for o-minimal Γ . By the description of v_Γ (Lemma 5.6), there exists a definable subset $X \subseteq G$, with $v \vdash X$, definably isomorphic to a Γ -box (around 0) in Γ^n . Identifying X with its image, we assume (by compactness) that for every $x, y \in X$ with $xy^{\pm 1} \in X$, we have $xy^{\pm 1} = x \pm y$. \square

Because Γ is o-minimal, and X is identified with a Γ -box in Γ^n , there is a definable neighborhood base, $\{W_t : t \in T\}$, of 0 in X .

For every $g \in G$, let τ_g denote the map $x \mapsto x^g$, and for $g, h \in G$, write $g \sim h$ if τ_g and τ_h have the same germ at 0; namely, there exists an open neighborhood $U \subseteq \Gamma^n$ of 0, such that $\tau_g|_U = \tau_h|_U$. By the above, this is a definable equivalence relation. Let σ be the definable function mapping $g \in G$ to $[g]_{\sim}$. It is a homomorphism of groups, with the group operation on the set of equivalence classes given by composition of germs.

We know that for every $g \in G$, $v^g = v$ (as types), and thus, there is some $W_t \subseteq X$ such that $W_t^g \subseteq X$ is also a neighborhood of 0. So $\sigma(G)$ can be viewed as a definable family of definable germs on X . Since Γ is a pure ordered vector space over a field F (the field of exponents in the o-minimal T), it follows that

$\sigma(G)$ is finite. Indeed, by [34, §1.7 Corollary 7.6], each germ is the restriction of some $T \in \mathrm{GL}_n(F)$ to an open neighborhood of 0. Since each such T is \emptyset -definable, a definable family of such germs must be finite.

Hence, the definable group $G_1 := \ker(\sigma)$ has finite index in G .

By definition, for every $g \in G_1$, there exists a τ_Γ -open neighborhood of 0, on which $x^g = x$. Thus, $G_1 \subseteq C_G(\nu_\Gamma)$ (recall Definition 4.6). Since $X \subseteq \Gamma^n$ is a Γ -box, it is definably connected, so we may apply Lemma 4.8 and conclude that $X \subseteq C_G(\nu_\Gamma)$.

By Lemma 2.16, $\nu_\Gamma \vdash G_1$. Thus, $\nu_\Gamma \vdash X \cap G_1 \subseteq Z(G_1)$, as claimed. Since G_1 is normal in G , it follows that $Z(G_1)$ is a definable infinite abelian normal subgroup of G .

Finally, let us verify that in both the current case, and in the p -adically closed case, we can replace G_1 with a subgroup defined over the same parameters as G . Without loss of generality, assume that G is \emptyset -definable and let $\{G_s : s \in S\}$ be a \emptyset -definable family of normal subgroups of G whose index in G is $[G : G_1]$, and such that $G_1 = G_s$ for some $s \in S$. We may further assume that for each $s \in S$, $Z(G_s)$ has a definable subset which is in definable bijection with a Γ -box (in Γ^n) around 0. By Lemma 5.5, $\nu_\Gamma \vdash Z(G_s)$. By Fact 2.19, $\bigcap_s G_s$ has finite index in G . It is \emptyset -definable, and its center contains ν_Γ .

We have thus finished the proof of Proposition 6.1 in all cases.

7. Groups locally strongly internal to K/\mathcal{O} .

We still assume \mathcal{K} is a saturated model in one of our cases. In the present section, we extend the results of the previous section from Γ -groups to K/\mathcal{O} -groups. The result we get is somewhat weaker. Explicitly, we prove the following:

Proposition 7.1. *Let $\mathcal{K}_0 < \mathcal{K}$ be an elementary substructure, G a \mathcal{K}_0 -definable K/\mathcal{O} -group not locally strongly internal to \mathbf{k} . Let $\mathcal{A} = \{\lambda_s : s \in S\}$ be a \mathcal{K}_0 -definable family of automorphisms of G , fixing the partial type $\nu_{K/\mathcal{O}}$. Then there is a \mathcal{K}_0 -definable normal abelian subgroup $N \leq G$ which is stabilized under all of the λ_g such that $\nu_{K/\mathcal{O}} \vdash N$. In particular, $\mathrm{dp}\text{-rk}(N)$ is at least the K/\mathcal{O} -rank of G .*

Remark 7.2. For convenience of presentation, we chose in Proposition 7.1 a uniform statement for all cases. However, in fact, the results are slightly stronger in each case. For p -adically closed fields, the assumption that G is not locally strongly internal to \mathbf{k} is vacuous, while in the remaining cases, we obtain a group invariant under all definable automorphisms of G (without the need to fix a family in advance).

We say that a subgroup $H \leq G$ is \mathcal{A} -invariant if for every $s \in S$, $\lambda_s(H) = H$. Since the proposition does not make any assumptions on \mathcal{A} , we may assume that \mathcal{A} contains the family of all conjugations by elements of G , and thus, an \mathcal{A} -invariant subgroup will be in particular normal in G .

As in Section 6.2, the proof splits between the p -adically closed case and the remaining cases.

7.1. \mathcal{K} is p -adically closed

Since \mathcal{K} is P -minimal and saturated, there is a finite extension, \mathbb{F} of \mathbb{Q}_p embedding elementarily (as a valued field) into K . We identify the image of some fixed such embedding with a valued subfield of K .

Since the value group $\Gamma_{\mathbb{F}}$ is isomorphic to \mathbb{Z} , as ordered abelian groups, we identify $\Gamma_{\mathbb{F}}$ with \mathbb{Z} and view it as a prime (and minimal) model for Γ . We denote \mathbb{Z}_{Pres} the structure $(\mathbb{Z}, +, <)$.

The following fact is an easy consequence of the results of [13]:

Fact 7.3. Let $\mathcal{K}_0 \equiv \mathcal{K}$, \mathcal{K}_0 not necessarily saturated, with \mathcal{O}_0 its valuation ring. Let $\mathrm{Tor}(K_0/\mathcal{O}_0)$ denote the torsion subgroup. Then

- (1) $\mathrm{Tor}(K_0/\mathcal{O}_0) = \{a \in K_0/\mathcal{O}_0 : v(a) \in \mathbb{Z}\}$.
- (2) $\mathrm{Tor}(K_0/\mathcal{O}_0)$ is a finite direct sum of Prüfer p -groups and is isomorphic to $\mathbb{F}/\mathcal{O}_{\mathbb{F}}$. In particular, $\mathrm{Tor}(K_0/\mathcal{O}_0)$ is a p -group.
- (3) Every ball in $(K_0/\mathcal{O}_0)^n$ centered at 0 contains $\mathrm{Tor}(K_0/\mathcal{O}_0)^n$ and the p^k -torsion points are exactly the points $b \in (K/\mathcal{O})^n$ with $v(b) \geq -k$.

Proof. Since, by the basic properties of Prüfer groups the p^n -torsion is finite for all n , it will suffice to prove the claim in \mathcal{K} :

(1): If $v(a) = n \in \mathbb{Z}_{<0}$, then $p^n a \in \mathcal{O}$, so $a + \mathcal{O} \in \text{Tor}(\mathcal{K}/\mathcal{O})$. The reverse inclusion follows from [13, Lemma 3.1](3).

(2): By [13, Lemma 3.1](3), every torsion element of $(K/\mathcal{O})^n$ is in $(\mathbb{F}/\mathcal{O}_{\mathbb{F}})^n$, and with the previous clause (2) follows for \mathcal{K} since $\mathbb{F}/\mathcal{O}_{\mathbb{F}}$ is isomorphic to a of Prüfer p -groups.

(3) follows from the structure of the Prüfer group. \square

Lemma 7.4. *Let G be a definable K/\mathcal{O} -group. Let $H_1, H_2 \leq G$ be definable subgroups, and $f_i : H_i \rightarrow (K/\mathcal{O})^n$ ($i = 1, 2$) definable group embeddings whose respective images are open balls in $(K/\mathcal{O})^n$, where n is the K/\mathcal{O} -rank of G . Then $\text{dp-rk}(H_1 \cap H_2) = n$ and*

$$\text{Tor}(H_1) = f_1^{-1}(\mathbb{F}/\mathcal{O}_{\mathbb{F}}) = \text{Tor}(H_2) = f_2^{-1}(\mathbb{F}/\mathcal{O}_{\mathbb{F}}).$$

In particular, all definable subgroups of G of dp-rank n that can be definably embedded into $(K/\mathcal{O})^n$ share the same torsion subgroup.

Proof. The assumptions and the conclusions are invariant under naming new constants, so we may assume that \mathbb{F} is named in \mathcal{K} , and so we may apply the results from [13].

By the construction of $v_{K/\mathcal{O}}$ (see Lemma 5.2 and Remark 2.15), we have $v_{K/\mathcal{O}} \vdash H_i$, $i = 1, 2$, and hence, $v_{K/\mathcal{O}} \vdash H_1 \cap H_2$. By Lemma 5.2, this implies that $\text{dp-rk}(H_1 \cap H_2) = n$.

Since $f_i(H_i)$ is an open ball, for $i = 1, 2$, it follows from Fact 7.3 that $\text{Tor}(H_i) = f_i^{-1}((\mathbb{F}/\mathcal{O}_{\mathbb{F}})^n)$. As $\text{dp-rk}(H_1 \cap H_2) = n$, also $\text{dp-rk}(f_i(H_1 \cap H_2)) = n$ for $i = 1, 2$, so by [13, Lemma 3.6] $f_i(H_1 \cap H_2)$ has nonempty interior, and thus contains a sub-ball of $(K/\mathcal{O})^n$. Therefore, (since it is a group) it also contains a ball centered at 0. Thus, $(\mathbb{F}/\mathcal{O}_{\mathbb{F}})^n \subseteq f_i(H_1 \cap H_2)$, and hence, $f_i^{-1}((\mathbb{F}/\mathcal{O}_{\mathbb{F}})^n) \subseteq H_1 \cap H_2$. We conclude

$$\text{Tor}(H_1) = f_1^{-1}((\mathbb{F}/\mathcal{O}_{\mathbb{F}})^n) = f_2^{-1}((\mathbb{F}/\mathcal{O}_{\mathbb{F}})^n) = \text{Tor}(H_2),$$

as needed. \square

We can now prove Proposition 7.1 in the p -adic case.

Proof of proposition 7.1 in the p -adic case. Recall that $\mathcal{A} = \{\lambda_s : s \in S\}$ is a definable family of automorphisms of G . First, we show that some infinite \mathcal{A} -invariant abelian subgroup of G is definable in \mathcal{K} , and then we construct one that is definable over K_0 as needed.

By Section 5.1, we can find a definable subgroup H_0 , $v_{K/\mathcal{O}} \vdash H_0 \leq G$, that is definably isomorphic to an open ball in $(K/\mathcal{O})^n$ centered at 0, where n is the K/\mathcal{O} -rank of G . Let $f : H_0 \rightarrow (K/\mathcal{O})^n$ be a group embedding witnessing this (note that H_0 and f are not claimed to be \mathcal{K}_0 -definable).

Let $H = \bigcap_{s \in S} H_0^{\lambda_s}$, where $H_0^{\lambda_s} = \lambda_s(H_0)$. It is a definable \mathcal{A} -invariant abelian subgroup, and by the previous lemma, it is infinite, as claimed. We shall now replace H by a group defined over K_0 .

By Lemma 7.4, $\text{Tor}(H_0^{\lambda_s}) = f^{-1}((\mathbb{F}/\mathcal{O}_{\mathbb{F}})^n)$, for every $s \in S$. It follows, using compactness and saturation, that there is $r < \mathbb{Z}$ such that $B_{>r}(0) \subseteq f(H)$. Let r_0 be the minimal such r .

Assume that H and f are definable over some $t_0 \in \mathcal{K}$ and let $\{(H_t, f_t) : t \in T\}$ be the corresponding K_0 -definable family of subgroups of G and definable group embeddings $f_t : H_t \rightarrow (K/\mathcal{O})^n$, such that $(H, f) = (H_{t_0}, f_{t_0})$. Note that the statement that H_{t_0} is \mathcal{A} -invariant is a first-order property of t_0 , defined over K_0 .

Thus, we may assume that each H_t is \mathcal{A} -invariant.

Define $\eta : T \rightarrow \Gamma$ by

$$\eta(t) = \min\{r \in \Gamma : B_{>r}(0) \subseteq f_t(H_t)\}.$$

In particular, $\eta(t_0) \leq r_0$, and by Lemma 7.4, if $\eta(t) < \mathbb{Z}$, then $\hat{H} := f_{t_0}^{-1}((\mathbb{F}/\mathcal{O}_{\mathbb{F}})^n) \subseteq H_t$.

Given $r \in \Gamma_{<0}$, let

$$G(r) := \bigcap \{H_t : \eta(t) \leq r\}.$$

Because each H_t is \mathcal{A} -invariant, so is $G(r)$, and as noted above, $\hat{H} \subseteq G(r)$ for every $r \in \Gamma_{<0}$.

The map f_{t_0} restricts to an injective homomorphism from $G(r_0)$ into $(K/\mathcal{O})^n$, and since $\hat{H} \subseteq G(r_0)$, the set $\{r \in \Gamma : f_{t_0}^{-1}(B_{>r}(0)) \subseteq G(r_0)\}$ contains \mathbb{Z} . It follows that there exists $r < \mathbb{Z}$ such that $f_{t_0}^{-1}(B_{>r}(0)) \subseteq G(r_0)$, and therefore, $v_{K/\mathcal{O}} \vdash G(r_0)$ (by Lemma 5.2).

The family $\{G(r) : r \in \Gamma\}$ is definable over K_0 and, by its definition, it is increasing as r tends to $-\infty$. Hence, the directed union

$$N := \bigcup_{r \in \Gamma_{<0}} G(r)$$

is an abelian subgroup defined over K_0 , \mathcal{A} -invariant and $v_{K/\mathcal{O}} \vdash N$. It follows that $\text{dp-rk}(N)$ is at least the K/\mathcal{O} -rank of G (note, however, that we do not claim that N is strongly internal to K/\mathcal{O}).

This concludes the proof of Proposition 7.1 in the p -adic case. \square

We now proceed to the remaining cases.

7.2. \mathcal{K} is power bounded T -convex or V -minimal

We assume that \mathcal{K} is either power bounded T -convex or V -minimal. In both cases, K/\mathcal{O} is an SW-uniformity and \mathcal{K} has residue characteristic 0.

Since $(K/\mathcal{O})^n$ is torsion-free, we cannot use torsion elements as in the p -adic case, so we adopt a different approach. The key to our argument is the characterization of definable groups and endomorphisms of $(K/\mathcal{O})^n$ from Section 3.1.

The conclusion of Proposition 7.1, in our case, will follow from the next proposition (recall that a ball containing 0 in $K/\mathcal{O})^n$ is of the form B^n for B a ball in K/\mathcal{O}):

Proposition 7.5. *Let G be a definable group in \mathcal{K} and let $H \subseteq G$ be an infinite definable subgroup, definably isomorphic to a ball in $(K/\mathcal{O})^n$. Let σ be a definable automorphism of G and let $H^\sigma := \sigma(H)$. Then $H^\sigma \cdot H \subseteq G$ is in definable bijection with a set of the form*

$$H \times \prod B_i \times \prod C_i,$$

where each B_i is a ball in K/\mathcal{O} and each C_i is a ball in K/\mathfrak{m} .

Furthermore,

- (1) If the k -rank of G is 0, then there are no C_i in the above description, so $H^\sigma \cdot H$ is strongly internal to K/\mathcal{O} .
- (2) If $H^\sigma \neq H$, then $\text{dp-rk}(H^\sigma \cdot H) > \text{dp-rk}(H)$.

Proof. We identify H with its image in $(K/\mathcal{O})^n$ (but still write the group operations multiplicatively) and let $H_3 = \{(a, b) \in H \times H : a^\sigma b = e\}$.

Claim 7.5.1. H_3 is a subgroup of $H \times H$ and $(H \times H)/H_3$ is in definable bijection with $H^\sigma \cdot H$.

Proof. Note that if $a^\sigma b = e$, then a^σ and b are in $H_0 := H \cap H^\sigma$, so they commute. To see that H_3 is a subgroup, assume that $a_1^\sigma b_1 = a_2^\sigma b_2 = e$. Then $(a_2^{-1})^\sigma a_1^\sigma b_1 b_2^{-1} = (a_1 a_2^{-1})^\sigma (b_1 b_2^{-1}) = e$, so $(a_1 a_2^{-1}, b_1 b_2^{-1}) \in H_3$.

We claim that for $a, b \in H$, $a_1^\sigma b_1 = a_2^\sigma b_2$ if and only if $(a_1, b_1)H_3 = (a_2, b_2)H_3$, and therefore, the map $(a, b) \mapsto a^\sigma b$ induces a well-defined bijection between $(H \times H)/H_3$ and $H^\sigma \cdot H$. Indeed, using the commutativity of H^σ ,

$$a_1^\sigma b_1 = a_2^\sigma b_2 \Leftrightarrow (a_2^\sigma)^{-1} a_1^\sigma b_1 b_2^{-1} = e \Leftrightarrow a_1^\sigma (a_2^\sigma)^{-1} b_1 b_2^{-1} = e \Leftrightarrow (a_1, b_1)H_3 = (a_2, b_2)H_3. \quad \square$$

The claim implies, in particular, that in order to compute $\text{dp-rk}((H^\sigma \cdot H))$, it will suffice to compute $\text{dp-rk}((H \times H)/H_3)$, to which we now turn our attention.

By definition, H_3 is the graph of a definable injective partial function $T : H^\sigma \cap H \dashrightarrow H^\sigma \cap H$, $x \mapsto (x^\sigma)^{-1}$; in particular, $\text{dom}(T)$ is a definable group. We want to study the map T . To do that, we may work solely inside $(K/\mathcal{O})^n \times (K/\mathcal{O})^n \supseteq H \times H$, so we switch to additive notation.

By Lemma 3.8, there is a definable automorphism $f : (K/\mathcal{O})^n \rightarrow (K/\mathcal{O})^n$ extending T . By Corollary 3.9, f preserves the valuation, and as H is a ball, we get that $f(H) = H$. Let us replace f by $f \upharpoonright H$. As H is abelian, $x \mapsto -f(x)$ is again an automorphism.

Consider the definable map $F : H \times H \rightarrow H \times H$: $F(x, y) = (x, y - f(x))$. Because f is an endomorphism of H , F is an automorphism of $H \times H$. It maps H_3 onto a group of the form $H_1 \times \{e\}$, where $H_1 = \text{dom}(T)$. Hence,

$$(H \times H)/H_3 \cong (H \times H)/(H_1 \times \{e_H\}) \cong (H/H_1) \times H.$$

By Lemma 3.7, there is a definable automorphism of $(K/\mathcal{O})^n$ mapping H_1 to a direct product of closed and open balls in K/\mathcal{O} (or K/\mathcal{O} or $\{0\}$). Since H of the form B^n , for $B \subseteq K/\mathcal{O}$, this automorphism preserves H (Corollary 3.9). Consequently, we may assume that

$$H_1 = \prod B_i \times \prod C_i \times \prod \{0\},$$

where B_i are closed balls and C_i are open balls. Therefore, H/H_1 is definably isomorphic to

$$\prod B/B_i \times \prod B/C_i \times \prod B.$$

Each B/B_i is definably isomorphic to a ball in K/\mathcal{O} (so strongly internal in K/\mathcal{O}), and each B/C_i is definably isomorphic to ball in K/\mathfrak{m} (so strongly internal to K/\mathfrak{m} . This gives the desired form.

For (1), if The \mathbf{k} -rank of G is 0, then there are no open C_i in the above description; so $H^\sigma \cdot H$ is strongly internal to K/\mathcal{O} .

For (2), if $H^\sigma \neq H$, then $H^\sigma \cap H \subsetneq H$, and in particular, $H_1 \subsetneq H$. Since Γ is dense, $[H : H_1] = \infty$ so $\text{dp-rk}(H/H_1) > 0$, and thus, $\text{dp-rk}(H^\sigma \cdot H) > \text{dp-rk}(H)$. \square

We can now complete the proof of Proposition 7.1 when \mathcal{K} is either power bounded or V-minimal. Let G be an infinite \mathcal{K}_0 -definable group whose \mathbf{k} -rank is 0. By Section 5.1 we can find a definable subgroup $H \subseteq G$ definably isomorphic to an open ball in $(K/\mathcal{O})^n$ centered at 0, where n is the K/\mathcal{O} -rank of G . It follows from Proposition 7.5 and the choice of H that H is invariant under every definable automorphism of G . Indeed, assume toward contradiction that $H^\sigma \neq H$. Then by (1) of the proposition, $H^\sigma \cdot H$ is strongly internal to K/\mathcal{O} and by (2) $\text{dp-rk}(H^\sigma \cdot H) > \text{dp-rk}(H)$, contradicting the fact that $\text{dp-rk}(H)$ is the K/\mathcal{O} -rank of G .

Thus, H is infinite, normal and abelian. Since any nonzero subgroup of $(K/\mathcal{O})^n$ is infinite, the existence of such a subgroup H is an elementary property, which implies that such a group exists already in \mathcal{K}_0 , as claimed.

We end this section with an example illustrating that in Proposition 7.1, the assumption that the \mathbf{k} -rank of G is 0 is essential.

Example 7.6. We produce an example of a group G of dp-rank 2 that is locally strongly internal to both K/\mathcal{O} and \mathbf{k} but has no infinite definable normal abelian subgroup which is locally strongly internal to K/\mathcal{O} .

Let \mathcal{K} be either a V -minimal valued field or a power-bounded T -convex valued field, and let $\gamma > 0$ be some element of Γ . Let $B_{\geq \gamma}$ and $B_{> \gamma}$ be the closed balls of respective radii γ and $-\gamma$ around 0.

Pick any $\delta \in \Gamma$ with $2\delta > \gamma > \delta > 0$. Then $H = (1 + B_{> \delta})/(1 + B_{\geq \gamma})$ is a definable multiplicative group definably isomorphic (because of our choice of δ) to the additive group $B_{> \delta}/B_{\geq \gamma}$ (via the map $a + B_{\geq \gamma} \mapsto (1 + a)(1 + B_{\geq \gamma})$). This latter group is obviously definably isomorphic to a subgroup of K/\mathcal{O} . Let $N = B_{> -\gamma}/\mathfrak{m}$ (which is strongly internal to \mathbf{k}).

Set $G = N \rtimes H$, where H acts on N by multiplication (it is well-defined) and the latter is a normal subgroup of G . We identify both of these groups with their obvious images in G ; namely, we identify $g = \bar{g} + \mathfrak{m} \in N$ with $(\bar{g} + \mathfrak{m}, 1 + B_{\geq \gamma})$, and $a = \bar{a}(1 + B_{\geq \gamma}) \in H$ with $(\mathfrak{m}, \bar{a}(1 + B_{\geq \gamma}))$.

A direct computation gives that if $a \in H$ and $g \in N$ as above,

$$a^g = g^{-1}ag = (\bar{g}(\bar{a} - 1) + \mathfrak{m}, \bar{a}(1 + B_{\geq \gamma})).$$

Assume now that L is a definable, normal subgroup of G which is locally strongly internal to K/\mathcal{O} . We will show that L is not abelian. By assumption, $\nu_{\mathcal{K}/\mathcal{O}} \vdash L$, so $L \cap H$ is infinite and in particular contains a non-identity element of the form $a = \bar{a}(1 + B_{\geq \gamma})$, with $\gamma > \nu(\bar{a} - 1) = \delta_1 > \delta$. We claim that for a suitable choice of $g \in G$, $a^g a \neq aa^g$, implying that L is not abelian.

Indeed, choose $g = \bar{g} + \mathfrak{m} \in N$, so that $\nu(\bar{g}) + \delta_1 < 0$ (we can do that since $-\gamma + \delta_1 < 0$), and then, by the above computation,

$$a^g a = (\bar{g}(a - 1) + \bar{a}\bar{g} + \mathfrak{m}, \bar{a}(1 + B_{\geq \gamma})), \quad aa^g = (\bar{g} + \bar{g}(a - 1) + \mathfrak{m}, \bar{a}(1 + B_{\geq \gamma})).$$

In order to see that $a^g a \neq aa^g$, it is enough to see that $\bar{g}(a - 1) + \bar{a}\bar{g} - (\bar{g} + \bar{g}(a - 1)) + \mathfrak{m} \neq \mathfrak{m}$ — namely, that $\bar{g}(\bar{a} - 1) \notin \mathfrak{m}$. This follows directly from our choice of g , since $\nu(\bar{g}) + \nu(\bar{a} - 1) < 0$.

We end with noting that similar computations give

$$H^g \cdot H = \{(\bar{a}(1 - \bar{g}) + \mathfrak{m}, \bar{b}(1 + B_{\geq \gamma})) : \bar{a}, \bar{b} \in 1 + B_{> \delta}\},$$

and thus, it is not hard to see that $H^g \cdot H = B_{> \delta + \nu(g)}/\mathfrak{m} \times H$ which is line with the Proposition 7.5(1).

8. Groups locally strongly internal to the residue field

The results of the previous sections imply, in particular, that there are no definably semisimple groups locally strongly internal to Γ (and in the p -adic case, nor to K/\mathcal{O}). This is clearly not the situation for groups locally strongly internal to the valued field or to the residue field. So our aim in the present and in the next section is to study such groups. We begin with the study of groups locally strongly internal to \mathbf{k} , where \mathcal{K} is either power-bounded T -convex or V -minimal.

For the statement of the main result of this section, we need a weakening of definable semisimplicity:

Definition 8.1. Let G be a definable group. A definable normal subgroup $H \trianglelefteq G$ is *G-semisimple* if H has no infinite abelian definable subgroups normal in G .

Note that, in the above notation, if either G or H are definably semisimple, then H is G -semisimple. We prove the following:

Proposition 8.2. Let G be a definably semisimple group locally almost strongly internal to \mathbf{k} . Then there exists a finite normal subgroup $N \trianglelefteq G$ and two normal subgroups $G_1, G_2 \trianglelefteq G/N$, all defined over any model over which G is defined, such that

- (1) $G_1 \cap G_2 = \{e\}$, G_1, G_2 centralize each other, and $G_1 \cdot G_2$ has finite index in G/N .
- (2) The almost \mathbf{k} -rank of G_1 is 0, and it is G/N -semisimple,
- (3) G_2 is definably semisimple, and it is definably isomorphic to a subgroup of $\mathrm{GL}_n(\mathbf{k})$.

Recall that a group G is a *definably connected* if it has no definable subgroups of finite index. Note that for G an arbitrary definable group, if there exists a definably connected subgroup of finite index,

then it is necessarily unique and denoted by G^0 . Clearly, if G^0 exists, then it is *definably characteristic* in G – namely, invariant under all definable automorphisms of G .

Fact 8.3 [24, Fact 2.11]. Let G be a definably connected group definable in some structure \mathcal{M} .

- (1) If N is a finite normal subgroup, then $N \subseteq Z(G)$.
- (2) If $Z(G)$ is finite, then $G/Z(G)$ is centerless.

The proof of Proposition 8.2 splits into two cases.

8.1. k is o-minimal

In this subsection, we assume that \mathcal{K} is power bounded T -convex, and thus, \mathbf{k} is an o-minimal expansion of a real closed field [33, Theorem A]. We first need a lemma allowing us, under suitable assumptions, to transfer definable semisimplicity under definable group homomorphisms:

Lemma 8.4. Assume that G is a definable group in \mathcal{K} , $B \subseteq \mathbf{k}^n$ is a definable group, and $f : G \rightarrow B$ a definable surjective homomorphism. Let $H \trianglelefteq G$ be a normal definable subgroup with $\ker(f \upharpoonright H)$ finite. Then

- (1) H^0 exists.
- (2) If H is G -definably semisimple, then H^0 and $f(H^0)$ are definably semisimple.

Proof. (1) $f(H)$ is a definable group in the o-minimal structure \mathbf{k} , so $f(H)^0$ exists. Since $\ker(f \upharpoonright H)$ is finite, H^0 exists as well. Indeed, if not, then there exists an infinite descending chain of finite index subgroups in H , which would give rise to a proper finite index subgroup of $f(H)^0$, contradiction.

(2) Assume that H is G -definably semisimple. Let $N = f(H^0)$; it is a definably connected component. If N is definably semisimple, then so is H^0 , so it suffices to show that N is definably semisimple. Assume toward a contradiction that N contains an infinite definable abelian normal subgroup A .

Recall that the *definable solvable radical* of N is the subgroup of N generated by all definably connected solvable normal subgroups of G . It is itself definable because of dimension considerations, and clearly definably characteristic in N . Let R be the definable solvable radical of N . The group A^0 is contained in R , so R is infinite. By [3, Corollary 5.6], R contains an infinite abelian definable definably connected subgroup R_0 that is definably characteristic in N .

Let A_1 be the connected component of $f^{-1}(R_0) \cap H^0$. Since R_0 is a definably connected group, $f(A_1) = R_0$. We claim that $Z(A_1)$ is infinite. Indeed, if it were finite then, by Fact 8.3, the group $A_1/Z(A_1)$ is centerless. However, because $\ker(f \upharpoonright A_1)$ is finite, it follows from the same fact that $\ker(f \upharpoonright A_1) \subseteq Z(A_1)$. Thus, $A_1/Z(A_1)$ can also be written as a quotient of $f(A_1) = R_0$, and so must be abelian, a contradiction.

Since R_0 is a characteristic subgroup of $N = f(H^0)$ and H^0 is normal in G , the group $f^{-1}(R_0) \cap H^0$ is invariant under conjugation by elements of G ; thus, so are A_1 and $Z(A_1)$. Thus, $Z(A_1)$ is an infinite abelian definable subgroup of H and normal in G , contradicting the definable G -semisimplicity of H . \square

Assume that G is locally strongly internal to \mathbf{k} . Let $\text{Ad}_{\mathbf{k}} : G \rightarrow \text{GL}_n(\mathbf{k})$ be the adjoint map, as discussed at the end of Section 5.

Lemma 8.5. Let G be locally strongly internal to \mathbf{k} . Then,

- (1) $\ker(\text{Ad}_{\mathbf{k}}) = C_G(v_{\mathbf{k}})$
- (2) $v_{\mathbf{k}} \vdash C_G(\ker(\text{Ad}_{\mathbf{k}}))$

Proof. Let $v = v_{\mathbf{k}}$.

(1) Let $g \in \ker(\text{Ad}_{\mathbf{k}})$. By [22, Lemma 3.2(ii)], for any group H definable in \mathbf{k} , two definable automorphisms H with the same differential at e_H coincide on an open neighborhood of e_H in H . While the proof is stated for groups, the analysis holds for local groups as well. Hence, if $g \in \ker(\text{Ad}_{\mathbf{k}})$, then $\tau_g(x) = x$ on some $\tau_{\mathbf{k}}$ -open neighborhood of e , so by definition, $g \in C_G(v)$. The reverse inclusion is immediate from the definitions.

(2) Since ν is the intersection of definable sets strongly internal to \mathbf{k} , we may choose $\nu \vdash X \subseteq G$ that we can identify with a definable subset of \mathbf{k}^n . By cell decomposition in o-minimal structures, we may further assume that X is definably connected. By Lemma 4.8, $X \subseteq C_G(C_G(\nu)) = C_G(\ker(\text{Ad}_{\mathbf{k}}))$, and thus, $\nu \vdash C_G(\ker(\text{Ad}_{\mathbf{k}}))$. \square

Proposition 8.6. *Let G be a definably semisimple group in \mathcal{K} , locally strongly internal to \mathbf{k} . Let $H_1 = \ker(\text{Ad}_{\mathbf{k}})$ and $H_2 = C_G(H_1)$. Then*

- (1) H_1 and H_2 are normal subgroups, H_2^0 is definably semisimple, $H_1 \cap H_2$ is finite and H_1 and H_2 centralize each other.
- (2) $H_1 \cdot H_2$ has finite index in G .
- (3) If the \mathbf{k} -rank of G equals the almost \mathbf{k} -rank, then $\text{dp-rk}(H_2)$ equals the \mathbf{k} -rank of G .

Proof. Let $\nu = \nu_{\mathbf{k}}$.

By Lemma 8.5, $H_1 = C_G(\nu)$ and $\nu \vdash H_2$. By definition, H_1 is a definable normal subgroup, and thus, so is H_2 . By the semisimplicity of G , the intersection of any definable normal subgroup H with its centralizer is finite (otherwise, $Z(H)$ is infinite and normal in G). Thus, $H_1 \cap H_2$ is finite, and by definition, H_1 and H_2 centralize each other. By Lemma 8.4, H_2^0 is definably semisimple, completing the proof of (1).

(2) Note that

$$G/(H_1 \cdot H_2) \cong \frac{G/H_1}{(H_1 \cdot H_2)/H_1} \cong \frac{G/H_1}{H_2/(H_1 \cap H_2)} \cong \text{Ad}_{\mathbf{k}}(G)/\text{Ad}_{\mathbf{k}}(H_2),$$

where $\text{Ad}_{\mathbf{k}}(G)$ is the image of $\text{Ad}_{\mathbf{k}}$ and $\text{Ad}_{\mathbf{k}}(H_2)$ is the image of $\text{Ad}_{\mathbf{k}} \upharpoonright H_2$.

Thus, we need to see that $\text{Ad}_{\mathbf{k}}(G)/\text{Ad}_{\mathbf{k}}(H_2)$ is finite. Since both images are subgroups of $\text{GL}_n(\mathbf{k})$, we may freely use properties of groups definable in o-minimal expansions of fields. By o-minimality, showing that $\text{Ad}_{\mathbf{k}}(G)/\text{Ad}_{\mathbf{k}}(H_2)$ is finite amounts to showing that $\dim_{\mathbf{k}}(\text{Ad}_{\mathbf{k}}(G)) = \dim_{\mathbf{k}}(\text{Ad}_{\mathbf{k}}(H_2))$ (we use $\dim_{\mathbf{k}}$ for the o-minimal dimension in \mathbf{k}). So, it is sufficient to show that $\dim_{\mathbf{k}}(\text{Ad}_{\mathbf{k}}(G)) \leq \dim_{\mathbf{k}}(\text{Ad}_{\mathbf{k}}(H_2))$.

As G is definably semisimple, H_2 is G -definably semisimple. Since, by (1), $\ker(\text{Ad}_{\mathbf{k}} \upharpoonright H_2)$ is finite, H_2^0 and $\text{Ad}_{\mathbf{k}}(H_2^0)$ are definably semisimple by Lemma 8.4. Let \mathfrak{h} be the Lie algebra (in the sense of [23]) of the definably connected group $\text{Ad}_{\mathbf{k}}(H_2^0)$ with its \mathbf{k} -differential structure. By [23, Theorem 2.34], \mathfrak{h} is a semisimple Lie algebra. Thus, by [23, Claim 2.8], $\dim(\mathfrak{h}) = \dim_{\mathbf{k}}(\text{Aut}(\mathfrak{h}))$ (we use the \mathbf{k} -vector space dimension on the left and the fact that $\text{Aut}(\mathfrak{h})$ is definable in \mathbf{k}).

The group $\text{Ad}_{\mathbf{k}}(G)$ acts on $\text{Ad}_{\mathbf{k}}(H_2^0)$ by conjugation and thus also on \mathfrak{h} . We claim that the kernel of this action is trivial.

Indeed, assume that for some $g \in G$, the action of $\text{Ad}_{\mathbf{k}}(g)$ on \mathfrak{h} is the identity. By [22, Lemma 3.2(ii)], it follows that for all $x \in \text{Ad}_{\mathbf{k}}(H_2^0)$, $\text{Ad}_{\mathbf{k}}(g^{-1}xg) = \text{Ad}_{\mathbf{k}}(x)$, and hence, for all $x \in H_2^0$, $g^{-1}xgx^{-1} \in \ker(\text{Ad}_{\mathbf{k}} \upharpoonright H_2^0)$. Since $\ker(\text{Ad}_{\mathbf{k}} \upharpoonright H_2^0)$ is finite, and H_2^0 is definably connected, it follows that for all $x \in H_2^0$, $g^{-1}xg = x$, and hence, $g \in C_G(H_2^0)$. Because $\nu \vdash H_2$, then $g \in C_G(\nu)$, so by Lemma 8.5, $g \in \ker(\text{Ad}_{\mathbf{k}})$, and hence, $\text{Ad}_{\mathbf{k}}(g) = e$.

We can therefore conclude that $\text{Ad}_{\mathbf{k}}(G)$ can be definably embedded into $\text{Aut}(\mathfrak{h})$; hence, we get that $\dim(\text{Ad}_{\mathbf{k}}(G)) \leq \dim(\text{Aut}(\mathfrak{h})) = \dim(\mathfrak{h}) = \dim(\text{Ad}_{\mathbf{k}}(H_2^0))$, so $\text{dp-rk}(\text{Ad}_{\mathbf{k}}(G)) = \text{dp-rk}(\text{Ad}_{\mathbf{k}}(H_2^0)) = \text{dp-rk}(\text{Ad}_{\mathbf{k}}(H_2))$, as required.

(3) Because $\ker(\text{Ad}_{\mathbf{k}}) \cap H_2$ is finite, H_2 is almost strongly internal to \mathbf{k} . Thus, the almost \mathbf{k} -rank of G is at least that of H_2 . However, $\nu \vdash H_2$, so $\text{dp-rk}(H_2)$ is at least the \mathbf{k} -rank of G . Because of the rank assumptions, we must have that $\text{dp-rk}(H_2)$ is the \mathbf{k} -rank of G . \square

Remark 8.7. As was noted in Remark 5.13, the groups H_1 and H_2 appearing in the statement of Proposition 8.6 are definable over the same parameters as G .

We isolate the following direct consequences:

Corollary 8.8. *Let G be locally strongly internal to \mathbf{k} .*

- (1) *If $\ker(\text{Ad}_{\mathbf{k}}) = G$ then $\nu_{\mathbf{k}} \vdash Z(G)$. In particular, if $Z(G)$ is finite, then $\ker(\text{Ad}_{\mathbf{k}})$ is a proper subgroup of G .*
- (2) *If G is definably simple (namely non-abelian and has no nontrivial definable normal subgroup), then G is definably isomorphic to a definable subgroup of $\text{GL}_n(\mathbf{k})$.*

Proof. (1) If $G = \ker(\text{Ad}_{\mathbf{k}})$, then by Lemma 8.5(2), $\nu_{\mathbf{k}} \vdash C_G(G) = Z(G)$. (2) Since G is definably simple, either $\ker(\text{Ad}_{\mathbf{k}}) = G$ or $\ker(\text{Ad}_{\mathbf{k}}) = \{e\}$. Since G is non-abelian, it follows from (1) that $\ker(\text{Ad}_{\mathbf{k}})$ must be equal to $\{e\}$. \square

The proof of Proposition 8.2 when \mathbf{k} is o-minimal reduces to collecting what we have done so far:

Proof of Proposition 8.2 for o-minimal \mathbf{k} . Fix G a definably semisimple group locally almost strongly internal to \mathbf{k} .

To prove (1), we need to find a finite normal $N \trianglelefteq G$ and definable $G_1, G_2 \trianglelefteq G/N$ centralizing each other with $G_1 \cap G_2 = \{e\}$. By Fact 2.6, there exists a finite normal subgroup $N_1 \trianglelefteq G$ such that G/N_1 is a \mathbf{k} -group and the almost \mathbf{k} -rank and the \mathbf{k} -rank agree in G/N_1 . Furthermore, N_1 is definable over any model over which G is defined. By Corollary 2.22, G/N_1 is definably semisimple, so – in order to keep notation simpler – we denote G/N_1 by G . By Lemma 5.12, G contains a definable normal differentiable local subgroup \mathcal{G} with respect to \mathbf{k} , with $\nu_{\mathbf{k}} \vdash \mathcal{G}$.

Then Proposition 8.6 provides us with two definable normal subgroups H_1, H_2 satisfying (1) of the proposition. By Remark 5.13, H_1 and H_2 are both definable over any model over which G is defined. The group $N = H_1 \cap H_2$ is a finite normal subgroup of G . Replace G by G/N and set $G_i := H_i/N$. Then G_1 and G_2 satisfy (1) of the proposition.

For (3), we need to show that G_2 is definably semisimple, and definably isomorphic to a \mathbf{k} -linear group. The latter is clear, since $\text{Ad}_{\mathbf{k}}(G)$ is \mathbf{k} -linear. For the first part, note that since H_2^0 is definably semisimple (by Proposition 8.6), so is H_2 , and thus, so is G_2 by Lemma 2.22.

It remains to prove (2) (i.e., that the almost \mathbf{k} -rank of G_1 is 0 and that G_1 is G/N -semisimple).

The latter part follows from the fact that G_1 is normal in the definably semisimple group G . So we only need to compute its almost \mathbf{k} -rank.

Assume toward a contradiction that G_1 is locally almost strongly internal to \mathbf{k} . By applying Fact 2.6 to G_1 , we get a finite normal subgroup $H \trianglelefteq G_1$ such that G_1/H is locally strongly internal to \mathbf{k} . Note that H is normal in $G_1 \cdot G_2$ as well.

By Lemma 8.5, $\nu_{\mathbf{k}}(G) \vdash G_2$. Since $G_1 \cdot G_2$ has finite index in G , by Lemma 2.16(2) $\nu_{\mathbf{k}}(G_1 \cdot G_2) = \nu_{\mathbf{k}}(G)$, so $\nu_{\mathbf{k}}(G_1 \cdot G_2) \vdash G_2$, and thus, $\nu_{\mathbf{k}}(G_1 \cdot G_2)/H \vdash G_2/H$. By Lemma 2.18(3), $\nu_{\mathbf{k}}(G_1 \cdot G_2/H) \vdash G_2/H$, and by Lemma 2.16(1) $\nu_{\mathbf{k}}(G_1/H) \vdash \nu_{\mathbf{k}}(G_1 \cdot G_2/H) \vdash G_2/H$. However, obviously, $\nu_{\mathbf{k}}(G_1/H) \vdash G_1/H$; thus, $(G_1 \cap G_2)/H$ must be infinite, a contradiction. \square

8.2. Proof of Proposition 8.2 for \mathbf{k} an algebraically closed field.

Throughout this subsection, \mathcal{K} is assumed V -minimal, and hence, \mathbf{k} is a stably embedded pure algebraically closed field. In particular, \mathbf{k} is strongly minimal. Fix a \mathcal{K} -definable, definably semisimple group G which is locally almost strongly internal to \mathbf{k} . By [13, Proposition 6.2], there exist definable subgroups $H_0 \trianglelefteq H \trianglelefteq G$, with H definably connected and H_0 finite normal in G such that H/H_0 is strongly internal to \mathbf{k} .

Fix $H_0 \trianglelefteq G$ and H as above and consider $H_1 = H/H_0$. By [4, Theorem 1], it is a \mathbf{k} -connected algebraic group. By a classical theorem of Rosenlicht [29, Theorem 13], as H_1 is a connected algebraic group, $H_1/Z(H_1)$ is a \mathbf{k} -linear group. As G/H_0 is definably semisimple (Corollary 2.22) and H_1 is normal in G/H_0 , $Z(H_1)$ is finite. Since H_1 is connected, $H_1/Z(H_1)$ is centerless (Fact 8.3).

We now fix a finite $N \trianglelefteq G$, $H_0 \subseteq N$, such that H/N is a connected centerless \mathbf{k} -linear group. Note that G/N is still definably semisimple by Corollary 2.22. Below, we work in G/N , and to simplify

notation, we still use H for H/N . Note that, since \mathbf{k} has definable Morley Rank, the statement ‘ H is a normal subgroup of G strongly internal to \mathbf{k} whose Morley Rank equals the \mathbf{k} -rank of G ’ is definable in families, and we can choose H to be definable over any model in which G is defined.

Claim 8.8.1. H has no infinite normal abelian subgroups; hence, it is a semisimple algebraic group.

Proof. Assume toward contradiction that such a normal subgroup existed. Then its Zariski closure is an infinite normal abelian algebraic subgroup. Its (algebraic) connected component is contained in the solvable radical R of H which is therefore infinite as well. This radical contains an infinite abelian algebraic subgroup that is definably characteristic in H , and therefore is normal in G , contradicting our assumption. \square

Claim 8.8.2. The group $C_G(H) \cdot H$ has finite index in G .

Proof. The group G acts on H by conjugation, and because \mathbf{k} is stably embedded, each action is \mathbf{k} -algebraic, so the map $f : g \mapsto \tau_g \upharpoonright H$ sends G into $\text{Aut}(H)$ the group of all algebraic automorphisms of H (recall that $\tau_g : (x \mapsto x^g)$). The kernel of the map is $C_G(H)$.

Applying [16, Theorem 27.4], using the fact that \mathbf{k} is algebraically closed, we see that $\text{Aut}(H)$ is the semi-direct product of $\text{Int}(H)$, the inner automorphisms of H , and a finite group (we use here the fact that H is assumed centerless). Since $f(H) = \text{Int}(H)$, it follows that $f(G)$ has finite index in $\text{Aut}(H)$, so $C_G(H) \cdot H$ must have finite index in G . \square

We now let $G_1 = C_G(H)$ and $G_2 = H$. Since G_1 and G_2 centralize each other and G_2 is centerless, $G_1 \cap G_2 = \{e\}$. This ends the proof of (1).

By construction, G_2 is a linear \mathbf{k} -group. Assume toward a contradiction that G_1 is locally almost strongly internal to \mathbf{k} as well. By [13, Proposition 6.2], there exists a finite definable normal subgroup $N' \trianglelefteq G_1$ such that G_1/N' has a definable normal subgroup $B_1 \trianglelefteq G_1/N'$ strongly internal to \mathbf{k} . Since G_1 and G_2 intersect trivially, we may identify G_2 with G_2/N' . Moreover, the \mathbf{k} -rank of $G_1 \cdot G_2$, which equals that of G (since it has finite index in it), is at most that of $(G_1 \cdot G_2)/N'$, by Lemma 2.18; so $G_2 = H$ is still \mathbf{k} -critical in $(G_1 \cdot G_2)/N'$. But then $B_1 \cdot G_2 \cong B_1 \times G_2$ is strongly internal to \mathbf{k} , with $\text{dp-rk}(B_1 \cdot G_2) > \text{dp-rk}(G_2)$, contradicting the fact that $H = G_2$ was \mathbf{k} -critical in $(G_1 \cdot G_2)/N'$.

Finally, we already saw that G_2 is definably semisimple. The fact that G_1 is G/N -semisimple is immediate since G/N is definably semisimple.

This finishes the proof of Proposition 8.2 in the V-minimal case, and thus, the proof of the proposition is now complete.

9. K -groups

In the notation of Section 5.3, for a K -group G , there exists an infinitesimal type-definable subgroup $\nu_K(G)$ inducing a definable homomorphism $\text{Ad}_K : G \rightarrow \text{GL}_n(K)$, for n the K -rank of G .

Recall that a definable group G is K -pure if G is locally strongly internal to K but not locally almost strongly internal to Γ , to \mathbf{k} or to K/\mathcal{O} . In the present section, we collect some basic facts concerning K -pure groups, as those appear naturally in our later analysis.

For the following result, we observe that all the valued fields we consider are 1-h-minimal. The exact definition is immaterial here. See [6] and [12, Section 4.5].

Fact 9.1 [1, Theorem 2]. Let \mathcal{K} be a 1-h-minimal field, $\mathcal{G} = (X, \cdot, {}^{-1})$ a definable strictly differentiable local group with respect to \mathcal{K} and $f : \mathcal{G} \rightarrow \mathcal{G}$ a definable strictly differentiable homomorphism of local groups. If $D_e(f) = \text{Id}$, then $\{y \in \text{dom}(f) : f(y) = y\}$ contains a definable open neighborhood of e .

Proof. This is a theorem of Acosta and the second author, [1, Theorem 2], implying that $\text{dp-rk}\{y \in \text{dom}(f) : f(y) = y\} = \text{dp-rk dom}(f)$, and so contains a definable open subset; the result follows. \square

We still use \dim to denote the acl-dimension in K and the induced dimension on K^{eq} and τ_K for the topology on G .

Proposition 9.2. *Let G be a definable group in \mathcal{K} , locally strongly internal to K . If $g \in \ker(\text{Ad}_K)$, then $\dim C_G(g) = \dim G$.*

Proof. Let $\mathcal{G} = (X, \cdot, {}^{-1})$ be the definable strictly differentiable local group as provided by Lemma 5.12. If $g \in \ker(\text{Ad}_K)$, then by Fact 9.1, the set $W := \{x \in X : x^g = x\} \subseteq C_G(g)$ is open in X . Since $\dim(X)$ is the K -rank of G (Corollary 4.2), we get that

$$\dim(G) = \dim(X) = \dim(W) \leq \dim C_G(g) \leq \dim(G). \quad \square$$

The following is based on an analogous result of [10]:

Corollary 9.3. *Let G be a definable group, locally strongly internal to K and let $g \in G$. If G is K -pure and $\dim(C_G(g)) = \dim(G)$, then $[G : C_G(g)] < \infty$. In particular, $[G : C_G(g)] < \infty$ for every $g \in \ker(\text{Ad}_K)$.*

Proof. The conjugacy class g^G is in definable bijection with the imaginary sort $G/C_G(g)$. By additivity of dimension, we get that $\dim(g^G) = \dim(G) - \dim(C_G(g))$. If $\dim(C_G(g)) = \dim(G)$, then $\dim(g^G) = 0$. By Lemma 4.10, g^G is finite, and hence, $[G : C_G(g)]$ is finite. \square

10. Definably semisimple groups

We can finally prove the main results of the paper. Recall, first, that a definable group is *definably simple* if it is non-abelian and has no definable normal subgroups, and it is *definably semisimple* if it has no definable infinite normal abelian subgroups.

We point out that definable semisimplicity is not, a priori, an elementary property of groups definable in \mathcal{K}^{eq} , as \mathcal{K}^{eq} may not eliminate the quantifier \exists^∞ . As we will see below, one of the corollaries of the present work is that in our setting, definable semisimplicity, is, in fact, elementary. That is, if $\mathcal{K}_0 < \mathcal{K}$ and G is a \mathcal{K}_0 -definable group, such that G is definably semisimple in \mathcal{K}_0 , then it remains so in \mathcal{K} .

As before, $\mathcal{K} = \mathcal{K}^{eq}$ is a sufficiently saturated valued field, either power-bounded T -convex, V -minimal or p -adically closed. Throughout the previous sections, we were working under the assumption that our definable group G is a D -group (for some distinguished sort D). As shown in [13], this need not be the case as G might not be locally strongly internal to any distinguished sort. The best we can obtain, in general, that if G is locally *almost* strongly internal to D and then there is a finite normal subgroup H such that G/H is a D -group (so in particular, locally strongly internal to D), Fact 2.6. Fortunately, in our setting, Corollary 2.22 assures that definable semisimplicity is preserved under finite quotients and under finite extensions.

Before stating the first of the results, recall from [18, §9.3] that a topological group G is *locally abelian* if there exists $W \ni e$, an open neighborhood of e in G , such that $xy = yx$ for all $x, y \in W$.

The next theorem gives conditions under which a definable, infinite, abelian normal subgroup must exist in G . Recall that if $\dim(G) > 0$, then by Corollary 4.2, it is locally strongly internal to K .

Theorem 10.1. *Let G be an infinite group definable over some $\mathcal{K}_0 < \mathcal{K}$.*

- (1) *If G is K -pure (so locally strongly internal to K) and locally abelian with respect to τ_K , then there exists a definable abelian subgroup $G_1 \trianglelefteq G$ of finite index, defined over \mathcal{K}_0 . In particular, G_1 is open.*
- (2) (a) *If G is locally almost strongly internal to Γ , then there exists a \mathcal{K}_0 -definable infinite normal abelian subgroup $N \trianglelefteq G$, whose dp -rank is at least the almost Γ -rank of G .*
(b) *If G is locally almost strongly internal to K/\mathcal{O} but not to k , then there exists a \mathcal{K}_0 -definable infinite normal abelian subgroup $N \trianglelefteq G$ whose dp -rank is at least the K/\mathcal{O} -rank of G .*

Proof. (1) Since G is locally strongly internal to K , it is a topological group with respect to the τ_K -topology. All topological notions below refer to τ_K .

Assume that G is locally abelian. By Lemma 5.12, there exists a local differentiable abelian subgroup $\mathcal{G} = (U, \cdot, {}^{-1})$ of G . Let τ_g denote conjugation by g . As $\tau_g \upharpoonright U = \text{Id}$ for all $g \in U$, we get that $U \subseteq \ker(\text{Ad}_K)$. This gives $\dim(\ker(\text{Ad}_K)) = \dim(G)$.

The proof that G is abelian-by-finite is an adaptation of [27, Proposition 2.3]. By Corollary 9.3, since G is K -pure, $[G : C_G(a)] < \infty$ for all $a \in U$. By Fact 2.20, there is a definable normal subgroup of finite index $H_0 \leq G$ such that $H_0 \leq C_G(U)$.

For every $h \in H_0$, $U \subseteq C_G(h)$; hence, $\dim C_G(h) = \dim G$ (e.g., by Corollary 4.9). Therefore, by Corollary 9.3 and K -purity, we have $[G : C_G(h)] < \infty$ for every $h \in H_0$. Thus, applying Fact 2.20 again, we see that $C_G(H_0)$ has finite index in G , so in particular, $G_1 = C_G(H_0) \cap H_0$ has finite index in G and is commutative. It follows that G_1 is open by Corollary 4.9. The fact that G_1 is a definable, open, normal abelian, subgroup of index k (some $k \in \mathbb{N}$), is first order, so we can find such G_1 defined over \mathcal{K}_0 .

(2) Assume now that G is locally almost strongly internal to D , where $D = \Gamma$ or $D = K/\mathcal{O}$. By Fact 2.6, there exists $H \trianglelefteq G$ a finite normal subgroup such that G/H is locally strongly internal to D and a D -group. Moreover, the D -rank of G/H is the almost D -rank of G , and H is \mathcal{K}_0 -definable. Also, if G was not almost strongly internal to \mathbf{k} , then neither is G/H .

Assume that $D = \Gamma$. By Proposition 6.1, we have $v_\Gamma(G/H) \vdash Z(G/H)$. In particular, G/H contains a normal abelian subgroup whose dp-rank is at least the Γ -rank of G/H (equivalently, the almost Γ -rank of G). By Corollary 2.22, G contains a definable normal abelian subgroup of the same dp-rank.

Assume that G is locally almost strongly internal to K/\mathcal{O} but not to \mathbf{k} , so G/H is locally strongly internal to K/\mathcal{O} (but not to \mathbf{k}) and its K/\mathcal{O} -rank equals the almost K/\mathcal{O} -rank of G . By Proposition 7.1, as G and H are both \mathcal{K}_0 -definable, there exists a \mathcal{K}_0 -definable infinite normal abelian subgroup of G/H whose dp-rank is at least the almost Γ -rank of G/H . By Corollary 2.22, G contains a definable normal abelian group of the same rank. \square

The following example shows that the assumption of K -purity is needed in Theorem 10.1(1), in order for local commutativity to imply the existence of a definable open normal abelian subgroup:

Example 10.2. Let \mathcal{K} be a p -adically closed field. Let \mathcal{O}^\times denote the multiplicative group of \mathcal{O} . Consider the semi-direct product $G = \mathcal{O}^\times \ltimes K/\mathcal{O}$, where $(a, b + \mathcal{O}) \cdot (c, d + \mathcal{O}) = (ac, b + ad + \mathcal{O})$. Then $\dim(G) = 1$ and $\text{dp-rk}(G) = 2$. It is locally abelian, as witnessed by $\mathcal{O}^\times \times \{0\}$. We claim that G has no definable open normal abelian subgroup. Assume, toward a contradiction, that H is such, in particular by [18, Theorem 1.4(1)] $\dim(H) = \dim(G)$ so $\pi_1(H)$, the projection on the first coordinate, must be infinite.

Let $(t, 0) \in H$ for $t \neq 1$. Since the conjugation of $(t, 0)$ by $(1, b + \mathcal{O})$ is $(t, b - bt + \mathcal{O})$, by letting b vary, we conclude that $\pi_2(H)$, the projection on the second coordinate, is equal to K/\mathcal{O} . Thus, $H = U \ltimes K/\mathcal{O}$ for some infinite definable subgroup U of \mathcal{O}^\times . Every element of \mathcal{O}^\times acts nontrivially on K/\mathcal{O} ; thus, $U \ltimes K/\mathcal{O}$ is not abelian unless $U = \{1\}$, proving that H as required does not exist.

However, note that $\{1\} \times K/\mathcal{O}$ is an infinite definable normal abelian subgroup (that is not open).

Theorem 10.1 together with the above example answers a question of Johnson's [18, §9.3] on locally abelian groups in p -adically closed fields.

We can now prove the main result of this paper. Note that below, \mathcal{K}_0 is not assumed to be saturated.

Theorem 10.3. *Let \mathcal{K}_0 be either a power bounded T -convex field, a V -minimal field or a p -adically closed field. Let G be an infinite definable, definably semisimple group in \mathcal{K}_0 . Then there exists a finite normal subgroup $N \trianglelefteq G$ and two normal subgroups $H_1, H_2 \trianglelefteq G/N$, such that*

- (1) $H_1 \cap H_2 = \{e\}$, H_1 and H_2 centralize each other and H_2 is definably semisimple.
- (2) $H_1 \cdot H_2$ has finite index in G/N .
- (3) H_1 is definably isomorphic to a subgroup of $\text{GL}_n(\mathcal{K}_0)$
- (4) H_2 is definably isomorphic to a subgroup of $\text{GL}_n(\mathbf{k}_0)$.

If the almost \mathbf{k} -rank of G is 0 (e.g., in the p -adically closed case), then $H_1 = G/N$.

Proof. Let $\mathcal{K} > \mathcal{K}_0$ be a sufficiently saturated elementary extension. Throughout the proof below, we use G to denote $G(\mathcal{K})$. As a first approximation, we prove the existence of $N, H_1, H_2 \subseteq G$ as above, all defined over \mathcal{K}_0 , satisfying (1), (2) and (4), such that H_1 is K -pure. We shall later show that after modding out by another finite subgroup, H_1 becomes K -linear.

We divide the proof into two cases:

(a) \mathcal{K}_0 is V -minimal or power bounded T -convex.

In this case, either by [17, §3] in the V -minimal case, or by Proposition A.5 in the T -convex power bounded case, \mathcal{K}^{eq} eliminates \exists^∞ , and therefore, G is definably semisimple.

By Fact 2.6, there exists a K_0 -definable finite normal subgroup $N' \trianglelefteq G$ such that in G/N' , the almost K/\mathcal{O} -rank and the K/\mathcal{O} -rank agree (they may be zero); by Lemma 2.18(4), this still holds if we further quotient by finite normal subgroups. Replace G by G/N' (using Corollary 2.22 which says it is still definably semisimple).

Assume first that G is locally almost strongly internal to \mathbf{k} . By Proposition 8.2, there is a finite normal subgroup $N_0 \trianglelefteq G$ definable over K_0 , and K_0 -definable normal subgroups $H_1, H_2 \trianglelefteq G/N_0$ such that $H_1 \cap H_2 = \{e\}$, $H_1 \cdot H_2$ has finite index in G/N_0 and H_1, H_2 centralize each other. Furthermore, H_2 is K_0 -definably isomorphic to a \mathbf{k} -linear definably semisimple group and the almost \mathbf{k} -rank of H_1 is 0. Since G is definably semisimple, so is G/N_0 (Corollary 2.22). Replace G by G/N_0 .

If the almost \mathbf{k} -rank of G is 0, then we just take $H_1 = G$ and $H_2 = \{e\}$.

Claim 10.3.1. The almost K/\mathcal{O} -rank of H_1 is 0.

Proof. Assume toward contradiction that H_1 is almost locally strongly internal to K/\mathcal{O} . By Fact 2.6, there exists a finite $N_1 \trianglelefteq H_1$, invariant under conjugation in G (namely, normal in G), such that H_1/N_1 is locally strongly internal to K/\mathcal{O} . Notice that G acts on H_1/N_1 by $\sigma_g(hN_1) := h^g N_1$.

Since the almost \mathbf{k} -rank of H_1 is 0, so is the almost \mathbf{k} -rank of H_1/N_1 . We now apply Proposition 7.1 to H_1/N_1 and the definable family of automorphisms $\mathcal{A} = \{\sigma_g : g \in G\}$, and obtain a definable infinite normal abelian subgroup of H_1/N_1 which is \mathcal{A} -invariant. By Corollary 2.22, H_1 contains a definable infinite normal abelian subgroup which is invariant under conjugation in G – namely, normal in G . This contradicts the semisimplicity of G . \square

By Theorem 10.1(2a), the almost Γ -rank of G is 0, and therefore, the same is true for H_1 . So H_1 is K -pure, as claimed.

This completes the proof of our approximation to the theorem, when \mathcal{K} is either V -minimal or power bounded T -convex.

(b) Assume now that \mathcal{K} is p -adically closed.

In this case, we just need to show that G is K -pure (and then we take $H_1 = G$). However, since \mathcal{K} does not eliminate \exists^∞ , we cannot assume a priori that it is definably semisimple.

Again, by Theorem 10.1(2a), the almost Γ -rank of G is 0, for otherwise, G would have a K_0 -definable infinite normal abelian subgroup, whose K_0 -points would contradict the definable semisimplicity of $G(K_0)$.

Since the almost \mathbf{k} -rank of G is obviously 0, it follows from Theorem 10.1 2(b) that the almost K/\mathcal{O} -rank of G must be 0. Indeed, if not, then once again, G would contain an infinite K_0 -definable normal abelian subgroup whose K_0 -points would contradict the semisimplicity of $G(K_0)$.

We therefore showed, in the p -adically closed case, that G is K -pure. This ends the proof of the approximated statement in all cases.

We now proceed with the proof of Theorem 10.3. As we showed above, we have a finite $N \trianglelefteq G$, and $H_1, H_2 \trianglelefteq G/N$ all defined over K_0 , satisfying (1), (2), (4), with H_1 being K -pure (in particular, H_1 is locally strongly internal to K). In the p -adically closed case, we take $H_1 = G/N$ and $H_2 = \{e\}$.

By Corollary 2.22, G/N is still definably semisimple. For clarity of notation, we replace G by G/N .

Note that $\dim G = \dim H_1 + \dim H_2$, and since $\dim H_2 = 0$, we have $\dim G = \dim H_1$. By Lemma 2.16, $v_K(G) = v_K(H_1)$. By Lemma 5.12, G contains a definable, differentiable normal local subgroup, with respect to K , which – as $\dim(G) = \dim(H_1)$ – we may assume to be contained in H_1 . Thus, we have an associated K_0 -definable map $\text{Ad}_K : G \rightarrow \text{GL}_n(K)$, with $n = \dim H_1$. Let $\text{Ad}_K^{H_1} = \text{Ad}_K \upharpoonright H_1$.

Claim 10.3.2. $\ker(\text{Ad}_K^{H_1})$ is a finite normal subgroup of G .

Proof. Since H_1 is K -pure, by Corollary 9.3, for every $h \in \ker(\text{Ad}_K^{H_1})$, $C_G(h)$ has finite index in H_1 . By Corollary 2.20, there exists a \mathcal{K}_0 -definable subgroup $\tilde{H}_1 \trianglelefteq H_1$ of finite index, that is also normal in G , such that $\tilde{H}_1 \leq C_{H_1}(\ker \text{Ad}_K^{H_1})$, and thus, $\tilde{H}_1 \cap \ker(\text{Ad}_K^{H_1}) \subseteq Z(\tilde{H}_1)$. Since $\ker(\text{Ad}_K^{H_1}) = \ker(\text{Ad}_K) \cap H_1$, it is obviously normal in G .

Thus, $\tilde{H}_1 \cap \ker(\text{Ad}_K^{H_1})$ is a \mathcal{K}_0 -definable normal abelian subgroup of G , so it must be finite by semisimplicity of $G(\mathcal{K}_0)$.

Finally, since \tilde{H}_1 has finite index in H_1 , it follows that $\ker(\text{Ad}_K^{H_1})$ is finite, as claimed.² \square

Clearly, $H_1/\ker(\text{Ad}_K^{H_1})$ is definably isomorphic, over K_0 , to a subgroup of $\text{GL}_n(K)$, with $n = \dim H_1$. Since $\ker(\text{Ad}_K^{H_1}) \cap H_2 = \{e\}$, we can replace G by $G/\ker(\text{Ad}_K^{H_1})$ and obtain H_1, H_2 as needed.

Since all the groups and maps are defined over K_0 , the theorem now descends to $G(\mathcal{K}_0)$ as well. This ends the proof of Theorem 10.3. \square

Remark 10.4. In Theorem 10.3, it is not claimed that H_1 is definably semisimple, though we believe it is true. We expect a standard proof using the tools developed in the unpublished paper [10] (and [1, §6]). Note, however, that if G in the theorem is definably connected or has almost \mathbf{k} -rank 0, then it follows easily that H_1 is definably semisimple.

As a special case, we get the following:

Corollary 10.5. *Let \mathcal{K}_0 be as above. If a group G , definable in \mathcal{K}_0 , is definably simple, then it is definably isomorphic to either a K_0 -linear group or a \mathbf{k}_0 -linear H .*

We also have the following.

Corollary 10.6. *Let $\mathcal{K}_0 < \mathcal{K}$ be as above. Let G be a K_0 -definable group. Then $G(K_0)$ is definably semisimple if and only if $G(K)$ is.*

Proof. By Proposition A.5 and [17, §3], we may assume that \mathcal{K}_0 is p -adically closed.

If $G(K)$ is definably semisimple, then so is $G(K_0)$. So we assume that $G(K_0)$ is definably semisimple and show that so is $G(K)$.

By Theorem 10.1(2), G is K -pure; so by Theorem 10.3, there exists a finite normal subgroup $H_0 \trianglelefteq G$ with $G/H_0(\mathcal{K}_0)$ definably isomorphic to a K_0 -linear group. Note that $(G/H_0)(\mathcal{K}_0)$ is definably semisimple by Corollary 2.22. As \mathcal{K}_0 eliminates \exists^∞ , it follows that $(G/H_0)(\mathcal{K})$ is definably semisimple as well. However, since H_0 is finite, $G(\mathcal{K})$ is definably semisimple. \square

Appendix A. Auxiliary results on power-bounded T -convex valued fields

In this appendix, we prove two results on power bounded T -convex valued fields. The first, stating that definable subsets of K are finite boolean combinations of ball cuts, is due to Holly [15, Theorem 4.8] in the case of RCVF. In full generality, it was proved by Tyne, [32, Page 94], but never published. Tyne's proof builds on a deep result, dubbed the valuation property (also not published in the required generality). As a service to the community, we provide an alternative, more direct proof. The second result shows, using a theorem of Johnson's [17], uniform finiteness for all imaginary sorts.

From now on, \mathcal{K} denotes a power bounded T -convex valued field. We remind some standard notation.

A.1. Definable subsets of K

If $C \subseteq K$ is any convex set, by $x < C$ we mean that $x < y$ for all $y \in C$ and $x \leq C$ is defined similarly. For convex sets C_1, C_2 , we write $C_1 < C_2$ if $x < y$ for any $x \in C_1$ and $y \in C_2$, similarly $C_1 \leq C_2$.

²The argument given in the claim shows that for K -pure groups, the kernel of Ad has a (relatively) open normal abelian subgroup of finite index. This is true in particular for p -adic Lie groups definable in the p -adic field. Recently, [11], Glöckner constructed an example of a 1-dimensional p -adic Lie group G for which this fails. In fact, in his example, $\ker(\text{Ad}_K) = G$, but G contains no open normal abelian subgroup.

By a *definable cut* in K we mean a pair of disjoint definable convex sets $\mathcal{C} = (C_1, C_2)$, such that $C_1 < C_2$ and $C_1 \cup C_2 = K$. A cut \mathcal{C} is *realized* if either C_1 has a maximum or C_2 has minimum.

For a definable function f from C_1 (or some open interval containing it) to either K or Γ , we say that $\lim_{x \rightarrow \mathcal{C}^-} f(x) = t_0$, if for every $t_1 < t_0 < t_2$, there exists $x \in C_1$ such that for all $x' > x$ in C_1 , $t_1 < f(x') < t_2$ (and likewise, $\lim_{x \rightarrow \mathcal{C}^+}$).

Following [15], we define the following:

Definition A.1. A definable cut $\mathcal{C} = (C_1, C_2)$ in K is a *ball cut* if there is a ball B (possibly a point) such that either $C_1 = \{x \in K : x < B\}$ (and then $C_2 = \{x \in K : B \leq x\}$), or $C_2 = \{x \in K : B < x\}$ (and then $C_1 = \{x \in K : x \leq B\}$).

By o-minimality of Γ , for every definable set X , bounded above or below, and $x \in X$, there exists a maximal ball around x which is contained in X . We leave the following easy observation to the reader.

Lemma A.2. Let $C \subseteq K$ be a convex definable subset and let b_1, b_2, b_3 be maximal balls in C with $b_1 < b_2 < b_3$. Then b_2 is necessarily an open ball.

Proposition A.3. If $\mathcal{C} = (C_1, C_2)$ is definable cut with $C_1, C_2 \neq \emptyset$, then \mathcal{C} is a ball cut. As a corollary, every definable subset of K is a boolean combination of balls and intervals.

Proof. Since every definable subset of K is a finite union of convex sets [35, Corollary 3.14], it will suffice to prove the first clause of the statement. So assume that $\mathcal{C} = (C_1, C_2)$ as given is an unrealized cut (if realized then \mathcal{C} is a ball cut with a trivial ball). For every $x \in C_1$, let B_x denote the maximal ball in C_1 containing x (since $C_2 \neq \emptyset$ such a ball exists) and let $r(x) \in \Gamma$ be its radius. Note that $r(x)$ is (weakly) increasing with x . We start with the following.

Claim A.3.1. Keeping the above notation, if $r(x)$ stabilizes as $x \rightarrow \mathcal{C}^-$, then \mathcal{C} is a ball cut.

Proof. Notice that $r(x)$ is (possibly weakly) increasing. Assume that $r(x) = r_0$ for sufficiently large x in C_1 . After re-scaling, assume that $r_0 = 0$.

If B_x is the same ball for all sufficiently large $x \in C_1$, then \mathcal{C} is a ball cut, so assume that for every $x \in C_1$ there is some $x' > x$ in C_1 such that $B_x \neq B_{x'}$. By Lemma A.2, for all sufficiently large x , all the B_x are open. Thus, for any $x \in C_1$, the closed ball $B_{\geq 0}(x)$ intersects C_2 . As every ball is convex, we have $B_{\geq 0}(x_1) = B_{\geq 0}(x_2)$ for all sufficiently large elements of C_1 ; let B be this closed ball. After translating, we may assume that $B = \mathcal{O}$.

As a result, the map $x \mapsto x + \mathbf{m}$ maps $(B \cap C_1, B \cap C_2)$ into a cut in \mathbf{k} . By o-minimality of \mathbf{k} , this cut is realized; namely, either the left side has a maximum or the right side has a minimum. In the first case, C_1 has a right side ball, and in the second case, C_2 has a left side ball. \square

By the claim, we may assume that $r(x)$ does not stabilize, as x increases in C_1 .

Using definable Skolem functions, [33, Remark 2.7], we find a definable $h : C_1 \rightarrow K$ such that for all $x \in C_1$, $r(x) = v(h(x))$. Let $\mathcal{L}_{\text{omin}}$ be the language of the underlying o-minimal reduct (i.e., $\mathcal{L}_{\text{omin}} = \mathcal{L}(T)$). By [33, Corollary 2.8], there exists an $\mathcal{L}_{\text{omin}}$ -definable function $\hat{h} : I \rightarrow K$ such that $h = \hat{h}$ on an end segment of C_1^- , which we may assume equals to $I \cap C_1$. Since \mathcal{C} is an unrealized cut and I is an $\mathcal{L}_{\text{omin}}$ -definable interval containing an end segment of C_1 , then necessarily $I \cap C_2 \neq \emptyset$. Shrinking I (without losing the property that $I \cap C_i \neq \emptyset$ for $i = 1, 2$), we may assume that h is strictly monotone and continuous.

By replacing, if needed, h by $-h$ (and \hat{h} by $-\hat{h}$), we may assume that \hat{h} is strictly decreasing.

Case 1: $\lim_{x \rightarrow \mathcal{C}^-} r(x) = \infty$. In this case, $\lim_{x \rightarrow \mathcal{C}^-} \hat{h}(x) = 0$. Thus, the function \hat{h} , which is strictly decreasing and continuous, takes a convex set of the form $\{x \in C_1 : x > c\}$, for some $c \in C_1 \cap I$, onto an open interval $(0, d)$, with $d = \hat{h}(c)$.

Since \hat{h} is $\mathcal{L}_{\text{omin}}$ -definable, so is its inverse function $\hat{h}^{-1} \upharpoonright (0, d)$. By o-minimality, and since \hat{h}^{-1} is strictly decreasing and bounded, it takes the interval $(0, d)$ to an interval of the form (c, a) , for some $a \in K$, and therefore, a realizes the cut \mathcal{C} , contradicting our assumption.

Case 2: $\lim_{x \rightarrow C^-} r(x) = r_0 \in \Gamma$. Since $r(x)$ does not stabilize, then $r(x) = v(h(x)) < r_0$ for all $x \in C_1$.

After re-scaling, we may assume that $r_0 = 0$, so $v(\widehat{h}(x)) < 0$ for all $x \in C_1 \cap I$ and $\lim_{x \in C^-} v(\widehat{h}(x)) = 0$. Thus, for all $x \in C_2 \cap I$, we have $v(h_1(x)) \geq 0$, and by continuity, there must be an element $x \in C_2 \cap I$ with $v(\widehat{h}(x)) = 0$. Hence, there is some $x_2 \in C_2 \cap I$ such that for all $x \in C_2$, if $x < x_2$, then $v(\widehat{h}(x)) = 0$.

Consequently, $x \in C_2 \cap I \iff \widehat{h}(x) \in \mathcal{O}$. Let (C'_1, C'_2) be the ball cut $C'_1 = \{y \in K : y \leq \mathcal{O}\}$ and let $J = \widehat{h}(I)$. Then $J \cap C'_i \neq \emptyset$, for $i = 1, 2$, and \widehat{h}^{-1} is strictly decreasing (from J to I). For simplicity, let $g = \widehat{h}^{-1}$.

For any $y \in \mathcal{O} \cap J$, let $B_y \subseteq C_2$ be the maximal ball containing $g(y) \in C_2$, and denote its radius by $r'(y)$. We may assume that $y \mapsto B_y$ does not stabilize as $y \rightarrow (J \cap \mathcal{O})^+$ (otherwise, \mathcal{C} is a ball cut, and we are done) and thus, by Lemma A.2, the $B_y \subseteq C_2$ are open. By [33, Proposition 4.2], $r'(y)$ stabilizes for sufficiently large $y \in J$. Since g sends $\mathcal{O} \cap J$ to $C_2 \cap I$, it follows that for some $c \in C_2$, all maximal balls $B \subseteq C_2$, with $B < c$, have the same radius. We can now conclude that \mathcal{C} is a ball cut, using Claim A.3.1 (with the roles of C_1 and C_2 interchanged), thus finishing the proof of Proposition A.3. \square

The fact that \mathcal{K} is definably spherically complete is a consequence of 0-h-minimality of \mathcal{K} , [6, Lemma 2.7.1]. The proof there is not hard, though it implicitly uses Tyne's theorem. We give here a different proof using the previous proposition.

Corollary A.4. *\mathcal{K} is definably spherically complete.*

Proof. Let $\{B_t : t \in T\}$ be a definable chain of balls in K . Assume toward contradiction that $\bigcap_{t \in T} B_t = \emptyset$. Let $r(B_t) \in \Gamma$ be the valuative radius of B_t .

We define two definable convex sets C_1, C_2 by

$$C_1 = \{x \in K : \exists t \ x < B_t\} ; \ C_2 = \{x \in K : \exists t \ B_t < x\}.$$

Since balls are convex, our assumption implies that $\mathcal{C} = (C_1, C_2)$ is a definable, unrealized, cut. By Proposition A.3, this is a ball cut. For simplicity (the other cases are similar), we assume that $C_1 = \{x \in K : x \leq B\}$ for some ball B . Translating and re-scaling, we may assume that B is either \mathcal{O} or \mathfrak{m} .

Let $B_0 = \bigcup_{t \in T} B_t$. We define a function $r : B_0 \rightarrow \Gamma$ by $r(x) = \sup\{r(B_t) : x \in B_t\}$. Using definable Skolem functions, we find a definable function $h : B_0 \rightarrow K$, such that $v(h(x)) = r(x)$.

Assume that $B = \mathcal{O}$. By [33, Proposition 4.2], the function $v(h(x))$, restricted to \mathcal{O} , eventually stabilizes as $x \rightarrow C^-$. This implies that the chain of balls B_t has a minimal element (there is a bijection between the balls and their radii), contradicting our assumption that the intersection of the chain is empty.

Assume that $B = \mathfrak{m}$ and consider $h \upharpoonright C_2$. Let $\mathcal{C}' = (C'_1, C'_2)$, where $C'_1 = \{x \in K : x \leq \mathcal{O}\}$. As $x \rightarrow C^+$, we get that $x^{-1} \rightarrow C^-$, so applying [33, Proposition 4.2] to $h(x^{-1})$, we conclude that $v(h(x))$ must stabilize as $x \rightarrow C^+$, again reaching a contradiction. \square

A.2. Elimination of \exists^∞ in the T -convex power bounded case

We now show that \mathcal{K}^{eq} eliminates \exists^∞ ; the proof utilizes a criterion used by Johnson to prove a parallel result for C -minimal valued fields (see [17]).

Proposition A.5. *\mathcal{K}^{eq} eliminates \exists^∞ .*

Proof. We shall apply Johnson's criterion for eliminating \exists^∞ , [17]. By [17, Theorem 2.3], it suffices to prove that if X is a definable set in \mathcal{K}^{eq} such that there exists a definable set $S \subseteq X \times K$ with the function $a \mapsto S_a := \{b \in K : (a, b) \in S\}$ injective on X , then \exists^∞ is eliminated on X . Namely, if $\{Y_t : t \in T\}$ is a definable family of subsets of X , then there is a bound on the size of those Y_t that are finite.

Let X be such a definable set (with $S \subseteq X \times K$ as in the assumption). As \mathcal{K} is weakly o-minimal (and saturated), there exists $k \in \mathbb{N}$ such that each S_a is a finite union of at most k convex sets. By partitioning X , we may assume that each S_a consists of exactly k convex sets. Let $X' = X \times \{1, \dots, k\}$ and let $S' \subseteq X' \times K$ the set satisfying that $S'_{a,i}$ is the i -th convex component of S_a .

It is sufficient to prove that \exists^∞ is eliminated on X' : Indeed, if \exists^∞ is not eliminated on X , then there exists a definable family of subsets $\{Y_t : t \in T\}$ of X and a sequence $\{t_n\}$, such that $|Y_{t_n}|$ is finite and tends to ∞ . We then define a family of finite subsets of X' as follows: For $i = 1, \dots, k$, let

$$Y'_{t,i} = \{ \text{the } i\text{-th convex component of } S_a : a \in Y_t \}.$$

Since $|Y_{t_n}| \rightarrow \infty$, one of the $|Y'_{t_n,i}|$ must tend to ∞ , thus X' does not eliminate \exists^∞ .

We now replace X by X' and S by S' , so we may assume that each S_a is a convex subset of K . By Proposition A.3, every S_a is a boolean combination of intervals and balls; so by convexity, it must be of the form $B_1 \square_1 x \square_2 B_2$, where each B_i is either a point or a ball and $\square_i \in \{<, =, \leq\}$. Thus, every S_a is coded by a pair of balls (for simplicity, we consider singletons as balls), so it is sufficient to treat the case where each S_a is a ball; namely, we may assume that X is a set of balls. Let $\{Y_t : t \in T\}$ be a definable family of subsets of X . We claim that there is a bound on the size of the finite Y_t in the family. We reduce the problem to the bound, in families, on the number of convex components of subsets of K , as well as the o-minimality of Γ .

We conclude the proof as in [17, §3]. If a ball b belongs to a finite Y_t , then it contains a ball $b' \in Y_t$ which is minimal with respect to inclusion. Thus, we may assume that for every $t \in T$, every ball in Y_t contains a minimal ball in Y_t (the set of all such t is definable).

We first note that whenever Y_t is finite, each convex component of the definable set $\bigcup \{b \in Y_t : b \text{ minimal}\}$ consists of a single minimal ball in Y_t . Indeed, the union of finitely many (but more than one), necessarily pairwise disjoint, balls is not a convex set.

Thus, we may assume now that for each Y_t in the family, each convex component of the definable set $\bigcup \{b \in Y_t : b \text{ minimal}\}$ consists of a single minimal ball in Y_t (this is a definable property of t). By the bound on the number of convex components, it follows that there is a bound on the number of minimal balls in each Y_t .

Assume toward contradiction that the number of balls in those finite Y_t is not uniformly bounded. Then, by the bound on the number of minimal balls in Y_t , there are chains of balls in Y_t , as t varies, of unbounded size. This is impossible, as this would imply that the sets $\{r(B) : B \in Y_t\}$ (where $r(B)$ is the valuative radius of B) are finite of unbounded size (as t ranges over T). Since Γ is o-minimal and stably embedded, definable families of finite subsets of unbounded size do not exist. \square

Let us conclude with an example demonstrating that general weakly o-minimal expansions of groups do not necessarily eliminate \exists^∞ in the imaginary sorts:

Example A.6. Our goal is to construct an ordered \mathbb{Q} -vector space with a discretely ordered definable family of convex subgroups.

Let $\mathcal{R}_{\mathbb{Z}}$ be a real closed valued field R with value group \mathbb{Q} together with a predicate $Z \subseteq \mathbb{Q}$ for the set of integers. Let $z : \mathbb{Q} \rightarrow \mathbb{Z}$ be the upper integer value. Let \mathcal{M} be the 2-sorted structure reduct of $\mathcal{R}_{\mathbb{Z}}$ consisting of the ordered \mathbb{Q} -vector space $R^{\mathbb{Q}} = (R, <, +, \{\lambda_q\}_{q \in \mathbb{Q}})$, the sort $(\mathbb{Z}, <)$ and the function $\zeta : R \rightarrow \mathbb{Z}$ given by $z \circ v$.

It is not hard to check that, after adding the function symbols for the successor and predecessor on \mathbb{Z} , the structure \mathcal{M} has quantifier elimination. It follows that the induced structure on R is weakly o-minimal. It is also not hard to see that \mathcal{M} is inter-definable with the expansion of the 1-sorted structure $R^{\mathbb{Q}}$ by a binary relation B on R , defined by $B(x, y) \Leftrightarrow \zeta(x) \geq \zeta(y)$. Since $(\mathbb{Z}, <)$ is interpretable, then \exists^∞ cannot be eliminated in the imaginary sorts.

We expect that also weakly o-minimal expansions of fields do not necessarily eliminate \exists^∞ in their imaginary sorts (although T-convex structures, even if not power bounded, do eliminate \exists^∞).

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