# OSCILLATION OF SECOND ORDER NEUTRAL DIFFERENTIAL EQUATIONS

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Some new sufficient conditions are obtained for the oscillation of the neutral differential equation

$$[r(t)(y(t)-cy(t-\tau))']'+p(t)y^{\alpha}(t-\sigma(t))=0$$

where r(t) > 0, 0 < c < 1,  $p(t) \ge 0$ ,  $\sigma(t) > \tau > 0$  and  $\alpha = 1$  or  $0 < \alpha < 1$ .

## I. INTRODUCTION

In the past several years the oscillation problem for second order neutral differential equations of the form

(1.1) 
$$(y(t) + cy(t-\tau))'' + py(t-\sigma) = 0 \text{ where } \tau > 0 \text{ and } \sigma > 0$$

has been considered by a number of authors [1, 2, 4-8]. Most of these papers treat the case where c > 0. In [6, 7] the case c < 0 was also studied for Equation (1.1) with constant coefficients and constant delay.

In this paper we consider second order linear and sublinear neutral delay differential equations of the form

(1.2) 
$$[r(t)(y(t) - cy(t - \tau))']' + p(t)y^{\alpha}(t - \sigma(t)) = 0$$

where r, p,  $\sigma$  are continuous, r(t) > 0, 0 < c < 1,  $0 < \alpha \leq 1$  is a quotient of odd integers  $\sigma(t) > \tau > 0$ ,  $\sigma'(t) \leq 1$ ,  $\lim_{t \to \infty} (t - \sigma(t)) = \infty$  and  $p(t) \ge 0$ .

As mentioned in [6] there are many important applications for neutral differential equations of the form (1.2).

As usual, a solution of Equation (1.2) is said to be oscillatory if it has arbitrarily large zeros and nonoscillatory if it is eventually positive or eventually negative.

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#### **II. LINEAR EQUATIONS**

The following Lemmas will be used to prove the main results.

LEMMA 2.1. Assume 0 < g(t) < t for t > 0,  $\lim_{t \to \infty} g(t) = \infty$ ,  $g \in C(\mathbb{R}^+, \mathbb{R}^+)$ ,  $r(t) \in C(\mathbb{R}^+, \mathbb{R}^+)$  and assume r(t) is either nonincreasing (in brief n.i.) or nondecreasing (in brief n.d.). Let  $y \in C(\mathbb{R}^+, \mathbb{R})$  be such that  $r(t)y'(t) \in C^1(\mathbb{R}^+, \mathbb{R})$  and y(t) > 0, y'(t) > 0 and  $(r(t)y'(t))' \leq 0$  for  $t \geq T$ .

Then for each 0 < k < 1 there is a  $T_k \ge T$  such that either

(2.1) 
$$y(g(t)) \ge \frac{kr(t)g(t)}{tr(T)}y(t)$$
, for  $t \ge T_k \ge T$  and  $r \in n.i$ .

or

(2.2) 
$$y(g(t)) \ge \frac{kg(t)}{t}y(t)$$
, for  $t \ge T_k \ge T$  and  $r \in n.d$ .

Lemma 2.1 is a generalisation of Erbe's Lemma [3]. The proof of this Lemma can be given by the same argument as used in [3] so we omit it here.

LEMMA 2.2. We consider the delay differential inequality

(2.3) 
$$(r(t)z'(t))' - \frac{p(t)}{c}z(t-\sigma(t)+\tau) \leq 0$$

where r, p,  $\sigma$ , c and  $\tau$  satisfy the assumptions for (1.2) in Section 1. Further assume that either

$$\limsup_{t\to\infty}\frac{1}{r(t-\sigma(t)+\tau)}\int_{t-\sigma(t)+\tau}^t [u-(t-\sigma(t)+\tau)]p(u)du>c \text{ for } r\in n.i.$$

or

$$\limsup_{t\to\infty}\frac{1}{r(t)}\int_{t-\sigma(t)+\tau}^t [u-(t-\sigma(t)+\tau)]p(u)du > c \text{ for } r \in n.d.$$

Then (2.3) has no negative increasing solution.

**PROOF:** Suppose the contrary and let z(t) be a negative increasing solution of (2.3).

Integrating (2.3) we have, for t > s

(2.5) 
$$r(t)z'(t)-r(s)z'(s)-\frac{1}{c}\int_s^t p(u)z(u-\sigma(u)+\tau)du \leq 0.$$

Integrating (2.5) in s from  $t - \sigma(t) + \tau$  to t, we have

$$r(t)z'(t)(\sigma(t)-\tau) - \int_{t-\sigma(t)+\tau}^{t} f(s)dz(s) \\ - \frac{1}{c}\int_{t-\sigma(t)+\tau}^{t} [u-(t-\sigma(t)+\tau)]p(u)z(u-\sigma(u)+\tau)du \leq 0.$$

We note that z'(t) > 0 so integrating the first integral by parts we have

$$-r(t)z(t) = r(t-\sigma(t)+\tau)z(t-\sigma(t)+\tau) + \int_{t-\sigma(t)+\tau}^{t} z(s)dr(s)$$
$$-\frac{1}{c}\int_{t-\sigma(t)+\tau}^{t} [u-(t-\sigma(t)+\tau)]p(u)z(u-\sigma(u)+\tau)du \leq 0.$$

For  $r \in n.d.$ , we have

(2.7) 
$$\int_{t-\sigma(t)+\tau}^{t} z(s)dr(s) \ge z(t-\sigma(t)+\tau)[r(t)-r(t-\sigma(t)+\tau)].$$

Combining (2.6) and (2.7) we have

$$r(t)[z(t-\sigma(t)+\tau)-z(t)] - \frac{1}{c}\int_{t-\sigma(t)+\tau}^{t} [u-(t-\sigma(t)+\tau)]p(u)z(u-\sigma(u)+\tau)du \leq 0.$$

Dividing the above inequality by  $r(t)z(t - \sigma(t) + \tau)$  and noting the negativity of this term, we have

$$1 - \frac{z(t)}{z(t-\sigma(t)+\tau)} - \frac{1}{cz(t-\sigma(t)+\tau)r(t)} \int_{t-\sigma(t)+\tau}^{t} [u-(t-\sigma(t)+\tau)]p(u)du \ge 0.$$

Since z(t) < 0 and z'(t) > 0, we have

$$1-\frac{z(t)}{z(t-\sigma(t)+\tau)}-\frac{1}{cr(t)}\int_{t-\sigma(t)+\tau}^t [u-(t-\sigma(t)+\tau)]p(u)du \ge 0.$$

Hence

$$\frac{1}{cr(t)}\int_{t-\sigma(t)+\tau}^t [u-(t-\sigma(t)+\tau)]p(u)du \leq 1$$

which contradicts (2.4).

The case that  $r \in n.i$ . may be proved in a similar way. We omit the details.

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**Remark 2.1.** If  $p(t) \ge p_0 > 0$  and  $p_0$  is a constant,  $r(t) \equiv 1$ ,  $\sigma(t) \equiv \sigma > \tau$ , then (2.3) becomes

(2.8) 
$$z''(t) - \frac{1}{c}(p_0 + p(t) - p_0)z(t - \sigma + \tau) \leq 0.$$

By a known result [9, Theorem 5.3.9], if

(2.9) 
$$\left(\frac{p_0}{c}\right)^{1/2}\frac{\sigma-\tau}{2} > \frac{1}{e}$$

then (2.8) has no negative increasing solution.

LEMMA 2.3. In addition to the assumptions for (1.2) in Section 1, further assume that  $\sigma(t)$  is nondecreasing and

(2.10) 
$$\liminf_{t\to\infty}\frac{1}{c}\int_{t-\sigma_1(t)}^t\frac{1}{r(s)}\int_s^{s+\frac{\sigma(s)-r}{2}}p(u)duds>\frac{1}{e}$$

where  $\sigma_1(t) = \sigma\left(t + \frac{\sigma(t) - \tau}{2}\right) - \frac{\sigma(t)}{2} - \frac{\tau}{2}$ . Then

(2.11) 
$$z'(t) + \frac{1}{cr(t)} \int_t^\infty p(u) z(u - \sigma(u) + \tau) du \ge 0$$

has no negative increasing solution.

**PROOF:** If not, let z(t) be a negative increasing solution of (2.11), then

$$z'(t)+\frac{1}{cr(t)}\int_t^{t+\frac{(\sigma-\tau)}{2}}p(u)z(u-\sigma(u)+\tau)du\geq 0.$$

By the monotonicity of z we have

$$(2.12) z'(t) + \left(\frac{1}{cr(t)}\int_1^{t+\frac{\sigma-\tau}{2}}p(u)du\right)z\left(t+\frac{\sigma-\tau}{2}-\sigma\left(t+\frac{\sigma-\tau}{2}\right)+\tau\right) \ge 0.$$

By a known result, [9, Theorem 2.1.1], (2.12) has no negative solution under the assumption (2.10). This contradiction proves the Lemma.

In this section we shall henceforth always assume that  $\alpha = 1$  in (1.2).

THEOREM2.1. In addition to the assumption for (1.2) in the first section we assume that  $\int_T^{\infty} \frac{dt}{r(t)} = \infty$  and either the second order ODE

(2.13) 
$$(r(t)y'(t))' + \frac{\lambda p(t)r(t)(t-\sigma(t))}{tr(T)}y(t) = 0$$

is oscillatory for some  $0 < \lambda < 1$  and  $r \in n.i.$  or

(2.14) 
$$(r(t)y'(t))' + \lambda p(t)\frac{t-\sigma(t)}{t}y(t) = 0$$

is oscillatory for some  $0 < \lambda < 1$  and  $r \in n.d.$ . Then every solution of (1.2) is either oscillatory or tends to zero as  $t \to \infty$ .

**PROOF:** Without loss of generality let y(t) be an eventually positive solution of (1.2) and define

(2.15) 
$$z(t) = y(t) - cy(t - \tau).$$

From (1.2) we know that

(2.16)  $(r(t)z'(t))' \leq 0 \text{ for } t \geq T.$ 

We shall show that

$$(2.17) r(t)z'(t) > 0 \text{ for } t \ge T.$$

In fact, if

r(t)z'(t) < 0 for  $t \ge T_1 \ge T$ .

Then

 $p(t)z'(t) \leq -\ell < 0$  for  $t \geq T_1$ .

Hence

$$z(t) \rightarrow -\infty$$
 as  $t \rightarrow \infty$ ,

since  $\int_T^\infty \frac{dt}{r(t)} = \infty$ .

On the other hand, if

z(t) < 0

we have

$$0 < y(t) < cy(t-\tau) < \ldots < c^n y(t-n\tau)$$

Hence  $y(t) \to 0$  as  $t \to \infty$ , since 0 < c < 1. Consequently  $z(t) \to 0$  as  $t \to \infty$  which contradicts the fact that  $z(t) \to -\infty$ . Therefore (2.17) is true.

There are two possible cases for z(t):

- (a) z(t) > 0 for  $t \ge T_2 \ge T_1$ ,
- (b) z(t) < 0 for  $t \ge T_1$ .

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Let us consider the case (a). In this case the assumptions of Lemma 2.1 are satisfied. Therefore for each 0 < k < 1 there is a  $T_k \ge T_2$  such that

$$z(t-\sigma(t)) \geqslant rac{kr(t)(t-\sigma(t))}{r(T)t} z(t), \ t \geqslant T_k, \ r \in n.i.$$

and

$$z(t-\sigma(t)) \ge \frac{k(t-\sigma(t))}{t} z(t), \ t \ge T_k, \ r \in n.d.$$

Since 0 < z(t) < y(t), from (1.2) we have

(2.18) 
$$(r(t)z'(t)) + \frac{kp(t)r(t)(t-\sigma(t))}{tr(T)}z(t) \leq 0 \text{ for } \lambda < k < 1, r \in n.i.; \\ (r(t)z'(t)) + kp(t)\frac{(t-\sigma(t))}{t}z(t) \leq 0 \text{ for } \lambda < k < 1, r \in n.d.,$$

which imply, respectively that (2.13) and (2.14) are nonoscillatory [3]. This contradicts the assumption.

The second possibility is that z(t) < 0 for  $t \ge T$ . As before, this time the corresponding solution y(t) must tend to zero as  $t \to \infty$ .

THEOREM 2.2. In addition to the assumptions of Theorem 2.1 assume further that (2.4) holds. Then every solution of (1.2) oscillates.

**PROOF:** To prove this theorem it is sufficient to show that in the proof of Theorem 2.1 z(t) < 0, for  $t \ge T$  is impossible under assumptions (2.4). Suppose that  $(rz')' \le 0$ , rz' > 0 and z(t) < 0 for  $t \ge T$ . By (2.15) we have

$$(2.19) z(t-\sigma(t)+\tau) > -cy(t-\sigma(t)).$$

This together with (1.2) gives

(2.20) 
$$(r(t)z'(t))' - \frac{p(t)}{c}z(t-\sigma(t)+\tau) \leq 0.$$

By Lemma 2.2 (2.20) has no negative increasing solutions which proves the theorem.

THEOREM 2.3. In addition to the assumptions of Theorem 2.1 assume further that  $\sigma(t)$  is nondecreasing and (2.10) holds. Then every solution of (1.2) oscillates.

**PROOF:** As mentioned earlier we continue the proof of Theorem 2.1 and consider the possible case that  $(rz')' \leq 0$ , rz' > 0 and z(t) < 0 for  $t \geq T$ . From this we have

$$r(t)z'(t)\to d\geqslant 0$$

exists. If d > 0 it follows that  $z(t) \to \infty$  as  $t \to \infty$  which contradicts the negativity of z(t). Therefore  $r(t)z'(t) \to 0$  as  $t \to \infty$ .

Integrating (1.2) from t to infinity we have

$$r(t)z'(t) = \int_t^\infty p(s)y(s-\sigma(s))ds,$$

which, together with (2.19), yields

$$r(t)z'(t) \ge -rac{1}{c}\int_t^\infty p(s)z(s-\sigma(s)+ au)ds.$$

This is a contradiction, by Lemma 2.3. The proof is completed.

**Remark 2.2.** We consider a special case of (1.2) as follows:

(2.21) 
$$(y(t) - cy(t - \tau))'' + p(t)y(t - \sigma) = 0$$

where 0 < c < 1,  $\sigma > \tau > 0$  are constants and  $p(t) \ge p_0 > 0$ . It is obvious (2.13) holds for (2.21). By Remark 2.1 if (2.9) holds then every solution of (2.21) oscillates. Therefore Theorem 8 in [6] becomes a special case of Theorem 2.2.

Example. Consider

$$(2.22) (y(t) - cy(t - \pi))'' + (1 + c)y(t - 2\pi) = 0$$

where 0 < c < 1. Every solution of (2.22) oscillates by Remark 2.2. In fact  $y = \sin t$  is a solution of (2.22).

## **III. SUBLINEAR EQUATIONS**

We now consider Equations (1.2) in the sublinear case, that is,  $0 < \alpha < 1$ .

THEOREM 3.1. Assume that:

- (i) the assumptions for (1.2) in Section 1 hold;
- (ii)  $R(t) = \int_{t_0}^t \frac{ds}{r(s)}$  and  $R(t) \to \infty$  as  $t \to \infty$ ;
- (iii) every solution of the second order ordinary differential equation

(3.1) 
$$(r(t)z'(t))' + p(t)\left(\frac{\lambda r(t)(t-\sigma(t))}{r(T)t}\right)^{\alpha} z^{\alpha}(t) = 0, \text{ if } r \in n.i.$$

or

(3.2) 
$$(r(t)z'(t))' + p(t)\left(\frac{\lambda(t-\sigma(t))}{t}\right)^{\alpha}z^{\alpha}(t) = 0, \text{ if } r \in n.d.$$

is oscillatory, where  $0 < \lambda < 1$  is a constant. Then every solution of (1.2) is either oscillatory or tends to zero as  $t \to \infty$ .

**PROOF:** Suppose the contrary and let y(t) be an eventually positive solution. As in the proof of Theorem 2.1 we have  $(rz')' \leq 0$  and rz' > 0 for  $t \geq T$ . For the case that z(t) > 0 for  $t \geq T$ , by Lemma 2.1 and (1.2), we get differential inequalities: either

(3.3) 
$$(r(t)z'(t))' + p(t)\left(\frac{kr(t)(t-\sigma(t))}{r(T)t}\right)^{\alpha} z^{\alpha}(t) \leq 0$$

for  $t \ge T_k$   $r \in n.i.$  and 0 < k < 1 or

(3.4) 
$$(t(t)z'(t))' + p(t)\left(\frac{k(t-\sigma(t))}{t}\right)^{\alpha}z^{\alpha}(t) \leq 0.$$

By the comparison method we know that (3.3) and (3.4) imply that (3.1) and (3.2) have a nonoscillatory solution [3, p.52], which contradicts assumption (iii). For the case that z(t) < 0 for  $t \ge T$ , as in the proof of Theorem 2.1 the corresponding solution y(t)tends to zero as  $t \to \infty$ . The proof is completed.

**Remark 3.1.** There are many results for oscillation of second order sublinear ordinary differential equations (3.1) and (3.2). For example, if

(3.5) 
$$\int_{T}^{\infty} R^{\alpha}(t) p(t) \left(\frac{\lambda r(t)(t-\sigma(t))}{r(T)t}\right)^{\alpha} dt = \infty \text{ for } r \in n.i.$$

or

(3.6) 
$$\int_{T}^{\infty} R^{\alpha}(t) p(t) \left(\frac{\lambda(t-\sigma(t))}{t}\right)^{\alpha} dt = \infty \text{ for } t \in n.d.$$

then every solution of (3.1) or (3.2) respectively oscillates.

THEOREM 3.2. In addition to the assumptions of Theorem 3.1 assume further that

(3.7) 
$$\overline{\lim_{t\to\infty}\frac{1}{r(t-\sigma(t)+\tau)}}\int_{t-\sigma(t)+\tau}^t [u-(t-\sigma(t)+\tau)]p(u)du>0 \text{ for } r\in n.i.$$

or

(3.8) 
$$\overline{\lim_{t\to\infty}\frac{1}{r(t)}\int_{t-\sigma(t)+\tau}^t [u-(t-\sigma(t)+\tau)]p(u)du>0 \text{ for } r\in n.d.$$

then every solution of (1.2) oscillates.

**PROOF:** Let y(t) be an eventually positive solution. As in the proof of Theorem 3.1, we have  $(rz')' \leq 0$ , rz' > 0 and z(t) < 0 for  $t \geq T$ . From (2.19) and (1.2) we have

(3.9) 
$$(r(t)z'(t))' - \frac{p(t)}{c}z^{\alpha}(t-\sigma(t)+\tau) \leq 0.$$

By the same arguments as used in the proof of Lemma 2.2 we can prove that (3.9) has no negative increasing solution under assumptions (3.7) and (3.8). Hence we get a contradiction, which porves the theorem.

[8]

THEOREM 3.3. In addition to the assumptions of Theorem 3.1 assume further that  $\sigma(t)$  is nondecreasing and

(3.10) 
$$\int_{T}^{\infty} \frac{1}{r(s)} \int_{s}^{s + \frac{(\sigma - \tau)}{K}} P(u) du ds = \infty$$

where K > 1 is some constant. Then every solution of (1.2) oscillates.

**PROOF:** If not, it is sufficient to consider the case that  $(rz')' \leq 0$ , rz' > 0 and z(t) < 0 for  $t \ge T$ . As in the proof of Theorem 2.2, we have

$$(3.11)$$

$$r(t)z'(t) = \int_{t}^{\infty} p(s)y^{\alpha}(s - \sigma(s))ds$$

$$\geqslant -\frac{1}{c^{\alpha}} \int_{t}^{\infty} p(s)z^{\alpha}(s - \sigma(s) + \tau)ds$$

$$\geqslant -\frac{1}{c^{\alpha}} \int_{t}^{t + \frac{(\sigma - \tau)}{K}} p(s)z^{\alpha}(s - \sigma(s) + \tau)ds$$

$$\geqslant -\left(\frac{1}{c^{\alpha}} \int_{t}^{t + \frac{\sigma - \tau}{K}} p(s)ds\right)z^{\alpha}\left(t + \frac{(\sigma - \tau)}{K} - \sigma\left(t + \frac{\sigma - \tau}{K}\right) + \tau\right).$$

This is a first order sublinear delay differential inequality. From a known result [9, Theorem 3.3.2] (3.11) has no negative solution under assumption (3.10). This contradiction proves the theorem.

**Remark.** It would be interesting to obtain results similar to those presented here for the superlinear case  $\alpha > 1$  for equation (1.2).

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