# OSCILLATION OF SECOND ORDER NEUTRAL DIFFERENTIAL EQUATIONS 

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$$
\begin{aligned}
& \text { Some new sufficient conditions are obtained for the oscillation of the neutral differential } \\
& \text { equation } \\
& \qquad\left[r(t)(y(t)-c y(t-\tau))^{\prime}\right]^{\prime}+p(t) y^{\alpha}(t-\sigma(t))=0 \\
& \text { where } r(t)>0,0<c<1, p(t) \geqslant 0, \sigma(t)>\tau>0 \text { and } \alpha=1 \text { or } 0<\alpha<1
\end{aligned}
$$

## I. Introduction

In the past several years the oscillation problem for second order neutral differential equations of the form

$$
\begin{equation*}
(y(t)+c y(t-\tau))^{\prime \prime}+p y(t-\sigma)=0 \text { where } \tau>0 \text { and } \sigma>0 \tag{1.1}
\end{equation*}
$$

has been considered by a number of authors $[1,2,4-8]$. Most of these papers treat the case where $c>0$. In [6, 7] the case $c<0$ was also studied for Equation (1.1) with constant coefficients and constant delay.

In this paper we consider second order linear and sublinear neutral delay differential equations of the form

$$
\begin{equation*}
\left[r(t)(y(t)-c y(t-\tau))^{\prime}\right]^{\prime}+p(t) y^{\alpha}(t-\sigma(t))=0 \tag{1.2}
\end{equation*}
$$

where $r, p, \sigma$ are continuous, $r(t)>0,0<c<1,0<\alpha \leqslant 1$ is a quotient of odd integers $\sigma(t)>\tau>0, \sigma^{\prime}(t) \leqslant 1, \lim _{1 \rightarrow \infty}(t-\sigma(t))=\infty$ and $p(t) \geqslant 0$.

As mentioned in [6] there are many important applications for neutral differential equations of the form (1.2).

As usual, a solution of Equation (1.2) is said to be oscillatory if it has arbitrarily large zeros and nonoscillatory if it is eventually positive or eventually negative.

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## II. Linear equations

The following Lemmas will be used to prove the main results.
Lemma 2.1. Assume $0<g(t)<t$ for $t>0, \lim _{t \rightarrow \infty} g(t)=\infty, g \in C\left(\mathbf{R}^{+}, \mathbf{R}^{+}\right)$, $r(t) \in C\left(\mathbf{R}^{+}, \mathbf{R}^{+}\right)$and assume $r(t)$ is either nonincreasing (in brief $\left.n . i.\right)$ or nondecreasing (in brief n.d.). Let $y \in C\left(\mathbf{R}^{+}, \mathbf{R}\right)$ be such that $r(t) y^{\prime}(t) \in C^{1}\left(\mathbf{R}^{+}, \mathbf{R}\right)$ and $y(t)>0$, $y^{\prime}(t)>0$ and $\left(r(t) y^{\prime}(t)\right)^{\prime} \leqslant 0$ for $t \geqslant T$.

Then for each $0<k<1$ there is a $T_{k} \geqslant T$ such that either

$$
\begin{equation*}
y(g(t)) \geqslant \frac{k r(t) g(t)}{\operatorname{tr}(T)} y(t), \text { for } t \geqslant T_{k} \geqslant T \text { and } r \in n . i . \tag{2.1}
\end{equation*}
$$

or

$$
\begin{equation*}
y(g(t)) \geqslant \frac{k g(t)}{t} y(t), \text { for } t \geqslant T_{k} \geqslant T \text { and } r \in n . d . \tag{2.2}
\end{equation*}
$$

Lemma 2.1 is a generalisation of Erbe's Lemma [3]. The proof of this Lemma can be given by the same argument as used in [3] so we omit it here.

Lemma 2.2. We consider the delay differential inequality

$$
\begin{equation*}
\left(r(t) z^{\prime}(t)\right)^{\prime}-\frac{p(t)}{c} z(t-\sigma(t)+\tau) \leqslant 0 \tag{2.3}
\end{equation*}
$$

where $r, p, \sigma, c$ and $\tau$ satisfy the assumptions for (1.2) in Section 1. Further assume that either

$$
\begin{equation*}
\limsup _{t \rightarrow \infty} \frac{1}{r(t-\sigma(t)+\tau)} \int_{t-\sigma(t)+\tau}^{t}[u-(t-\sigma(t)+\tau)] p(u) d u>c \text { for } r \in n . i \tag{2.4}
\end{equation*}
$$

or

$$
\limsup _{t \rightarrow \infty} \frac{1}{r(t)} \int_{t-\sigma(t)+\tau}^{t}[u-(t-\sigma(t)+\tau)] p(u) d u>c \text { for } r \in \text { n.d. }
$$

Then (2.3) has no negative increasing solution.
Proof: Suppose the contrary and let $z(t)$ be a negative increasing solution of (2.3).

Integrating (2.3) we have, for $t>s$

$$
\begin{equation*}
r(t) z^{\prime}(t)-r(s) z^{\prime}(s)-\frac{1}{c} \int_{s}^{t} p(u) z(u-\sigma(u)+\tau) d u \leqslant 0 \tag{2.5}
\end{equation*}
$$

Integrating (2.5) in $s$ from $t-\sigma(t)+\tau$ to $t$, we have

$$
\begin{aligned}
r(t) z^{\prime}(t)(\sigma(t)-\tau) & -\int_{t-\sigma(t)+\tau}^{t} f(s) d z(s) \\
& -\frac{1}{c} \int_{t-\sigma(t)+\tau}^{t}[u-(t-\sigma(t)+\tau)] p(u) z(u-\sigma(u)+\tau) d u \leqslant 0
\end{aligned}
$$

We note that $z^{\prime}(t)>0$ so integrating the first integral by parts we have

$$
\begin{align*}
-r(t) z(t)=r( & t-\sigma(t)+\tau) z(t-\sigma(t)+\tau)+\int_{t-\sigma(t)+\tau}^{t} z(s) d r(s)  \tag{2.6}\\
& -\frac{1}{c} \int_{t-\sigma(t)+\tau}^{t}[u-(t-\sigma(t)+\tau)] p(u) z(u-\sigma(u)+\tau) d u \leqslant 0
\end{align*}
$$

For $r \in n . d$., we have

$$
\begin{equation*}
\int_{t-\sigma(t)+\tau}^{t} z(s) d r(s) \geqslant z(t-\sigma(t)+\tau)[r(t)-r(t-\sigma(t)+\tau)] . \tag{2.7}
\end{equation*}
$$

Combining (2.6) and (2.7) we have

$$
\begin{aligned}
r(t)[z(t-\sigma(t)+\tau)-z(t)]- & \frac{1}{c} \int_{t-\sigma(t)+\tau}^{t} \\
& {[u-(t-\sigma(t)+\tau)] p(u) z(u-\sigma(u)+\tau) d u \leqslant 0 . }
\end{aligned}
$$

Dividing the above inequality by $r(t) z(t-\sigma(t)+\tau)$ and noting the negativity of this term, we have

$$
\begin{aligned}
1-\frac{z(t)}{z(t-\sigma(t)+\tau)}-\frac{1}{c z(t-\sigma(t)+\tau) r(t)} & \int_{t-\sigma(t)+\tau}^{t} \\
& {[u-(t-\sigma(t)+\tau)] p(u) d u \geqslant 0 . }
\end{aligned}
$$

Since $z(t)<0$ and $z^{\prime}(t)>0$, we have

$$
1-\frac{z(t)}{z(t-\sigma(t)+\tau)}-\frac{1}{c r(t)} \int_{t-\sigma(t)+\tau}^{t}[u-(t-\sigma(t)+\tau)] p(u) d u \geqslant 0
$$

Hence

$$
\frac{1}{c r(t)} \int_{t-\sigma(t)+r}^{t}[u-(t-\sigma(t)+\tau)] p(u) d u \leqslant 1
$$

which contradicts (2.4).
The case that $r \in n . i$. may be proved in a similar way. We omit the details.

Remark 2.1. If $p(t) \geqslant p_{0}>0$ and $p_{0}$ is a constant, $r(t) \equiv 1, \sigma(t) \equiv \sigma>\tau$, then (2.3) becomes

$$
\begin{equation*}
z^{\prime \prime}(t)-\frac{1}{c}\left(p_{0}+p(t)-p_{0}\right) z(t-\sigma+\tau) \leqslant 0 \tag{2.8}
\end{equation*}
$$

By a known result [9, Theorem 5.3.9], if

$$
\begin{equation*}
\left(\frac{p_{0}}{c}\right)^{1 / 2} \frac{\sigma-\tau}{2}>\frac{1}{e} \tag{2.9}
\end{equation*}
$$

then (2.8) has no negative increasing solution.
Lemma 2.3. In addition to the assumptions for (1.2) in Section 1, further assume that $\sigma(t)$ is nondecreasing and

$$
\begin{equation*}
\liminf _{t \rightarrow \infty} \frac{1}{c} \int_{t-\sigma_{1}(t)}^{t} \frac{1}{r(s)} \int_{0}^{s+\frac{\sigma(t)-\tau}{2}} p(u) d u d s>\frac{1}{e} \tag{2.10}
\end{equation*}
$$

where $\sigma_{1}(t)=\sigma\left(t+\frac{\sigma(t)-\tau}{2}\right)-\frac{\sigma(t)}{2}-\frac{\tau}{2}$.
Then

$$
\begin{equation*}
z^{\prime}(t)+\frac{1}{c r(t)} \int_{t}^{\infty} p(u) z(u-\sigma(u)+\tau) d u \geqslant 0 \tag{2.11}
\end{equation*}
$$

has no negative increasing solution.
Proof: If not, let $z(t)$ be a negative increasing solution of (2.11), then

$$
z^{\prime}(t)+\frac{1}{c r(t)} \int_{t}^{t+\frac{(\sigma-\tau)}{2}} p(u) z(u-\sigma(u)+\tau) d u \geqslant 0
$$

By the monotonicity of $z$ we have

$$
\begin{equation*}
z^{\prime}(t)+\left(\frac{1}{c r(t)} \int_{1}^{t+\frac{\sigma-\tau}{2}} p(u) d u\right) z\left(t+\frac{\sigma-\tau}{2}-\sigma\left(t+\frac{\sigma-\tau}{2}\right)+\tau\right) \geqslant 0 \tag{2.12}
\end{equation*}
$$

By a known result, [ $\boldsymbol{\theta}$, Theorem 2.1.1], (2.12) has no negative solution under the assumption (2.10). This contradiction proves the Lemma.

In this section we shall henceforth always assume that $\alpha=1$ in (1.2).

Theorem2.1. In addition to the assumption for (1.2) in the first section we assume that $\int_{T}^{\infty} \frac{d t}{r(t)}=\infty$ and either the second order $O D E$

$$
\begin{equation*}
\left(r(t) y^{\prime}(t)\right)^{\prime}+\frac{\lambda p(t) r(t)(t-\sigma(t))}{\operatorname{tr}(T)} y(t)=0 \tag{2.13}
\end{equation*}
$$

is oscillatory for some $0<\lambda<1$ and $r \in n . i$. or

$$
\begin{equation*}
\left(r(t) y^{\prime}(t)\right)^{\prime}+\lambda p(t) \frac{t-\sigma(t)}{t} y(t)=0 \tag{2.14}
\end{equation*}
$$

is oscillatory for some $0<\lambda<1$ and $r \in n . d$. Then every solution of (1.2) is either oscillatory or tends to zero as $t \rightarrow \infty$.

Proof: Without loss of generality let $y(t)$ be an eventually positive solution of (1.2) and define

$$
\begin{equation*}
z(t)=y(t)-c y(t-\tau) \tag{2.15}
\end{equation*}
$$

From (1.2) we know that

$$
\begin{equation*}
\left(r(t) z^{\prime}(t)\right)^{\prime} \leqslant 0 \text { for } t \geqslant T \tag{2.16}
\end{equation*}
$$

We shall show that

$$
\begin{equation*}
r(t) z^{\prime}(t)>0 \text { for } t \geqslant T \tag{2.17}
\end{equation*}
$$

In fact, if

$$
r(t) z^{\prime}(t)<0 \text { for } t \geqslant T_{1} \geqslant T
$$

Then

$$
p(t) z^{\prime}(t) \leqslant-\ell<0 \text { for } t \geqslant T_{1}
$$

Hence

$$
z(t) \rightarrow-\infty \text { as } t \rightarrow \infty,
$$

since $\int_{T}^{\infty} \frac{d t}{r(t)}=\infty$.
On the other hand, if

$$
z(t)<0
$$

we have

$$
0<y(t)<c y(t-\tau)<\ldots<c^{n} y(t-n \tau) .
$$

Hence $y(t) \rightarrow 0$ as $t \rightarrow \infty$, since $0<c<1$. Consequently $z(t) \rightarrow 0$ as $t \rightarrow \infty$ which contradicts the fact that $z(t) \rightarrow-\infty$. Therefore (2.17) is true.

There are two possible cases for $z(t)$ :
(a) $z(t)>0$ for $t \geqslant T_{2} \geqslant T_{1}$,
(b) $z(t)<0$ for $t \geqslant T_{1}$.

Let us consider the case (a). In this case the assumptions of Lemma 2.1 are satisfied. Therefore for each $0<k<1$ there is a $T_{k} \geqslant T_{2}$ such that

$$
z(t-\sigma(t)) \geqslant \frac{k r(t)(t-\sigma(t))}{r(T) t} z(t), t \geqslant T_{k}, r \in n . i .
$$

and

$$
z(t-\sigma(t)) \geqslant \frac{k(t-\sigma(t))}{t} z(t), t \geqslant T_{k}, r \in n . d . .
$$

Since $0<z(t)<y(t)$, from (1.2) we have

$$
\begin{align*}
& \left(r(t) z^{\prime}(t)\right)+\frac{k p(t) r(t)(t-\sigma(t))}{\operatorname{tr}(T)} z(t) \leqslant 0 \text { for } \lambda<k<1, r \in n . i . ;  \tag{2.18}\\
& \left(r(t) z^{\prime}(t)\right)+k p(t) \frac{(t-\sigma(t))}{t} z(t) \leqslant 0 \text { for } \lambda<k<1, r \in n . d .
\end{align*}
$$

which imply, respectively that (2.13) and (2.14) are nonoscillatory [3]. This contradicts the assumption.

The second possibility is that $z(t)<0$ for $t \geqslant T$. As before, this time the corresponding solution $y(t)$ must tend to zero as $t \rightarrow \infty$.

Theorem 2.2. In addition to the assumptions of Theorem 2.1 assume further that (2.4) holds. Then every solution of (1.2) oscillates.

Proof: To prove this theorem it is sufficient to show that in the proof of Theorem $2.1 z(t)<0$, for $t \geqslant T$ is impossible under assumptions (2.4). Suppose that $\left(r z^{\prime}\right)^{\prime} \leqslant 0$, $r z^{\prime}>0$ and $z(t)<0$ for $t \geqslant T$. By (2.15) we have

$$
\begin{equation*}
z(t-\sigma(t)+\tau)>-c y(t-\sigma(t)) \tag{2.19}
\end{equation*}
$$

This together with (1.2) gives

$$
\begin{equation*}
\left(r(t) z^{\prime}(t)\right)^{\prime}-\frac{p(t)}{c} z(t-\sigma(t)+\tau) \leqslant 0 \tag{2.20}
\end{equation*}
$$

By Lemma 2.2 (2.20) has no negative increasing solutions which proves the theorem.
Theorem 2.3. In addition to the assumptions of Theorem 2.1 assume further that $\sigma(t)$ is nondecreasing and (2.10) holds. Then every solution of (1.2) oscillates.

Proof: As mentioned earlier we continue the proof of Theorem 2.1 and consider the possible case that $\left(r z^{\prime}\right)^{\prime} \leqslant 0, r z^{\prime}>0$ and $z(t)<0$ for $t \geqslant T$. From this we have

$$
r(t) z^{\prime}(t) \rightarrow d \geqslant 0
$$

exists. If $d>0$ it follows that $z(t) \rightarrow \infty$ as $t \rightarrow \infty$ which contradicts the negativity of $z(t)$. Therefore $r(t) z^{\prime}(t) \rightarrow 0$ as $t \rightarrow \infty$.

Integrating (1.2) from $t$ to infinity we have

$$
r(t) z^{\prime}(t)=\int_{t}^{\infty} p(s) y(s-\sigma(s)) d s
$$

which, together with (2.19), yields

$$
r(t) z^{\prime}(t) \geqslant-\frac{1}{c} \int_{t}^{\infty} p(s) z(s-\sigma(s)+\tau) d s
$$

This is a contradiction, by Lemma 2.3. The proof is completed.
Remark 2.2. We consider a special case of (1.2) as follows:

$$
\begin{equation*}
(y(t)-c y(t-\tau))^{\prime \prime}+p(t) y(t-\sigma)=0 \tag{2.21}
\end{equation*}
$$

where $0<c<1, \sigma>\tau>0$ are constants and $p(t) \geqslant p_{0}>0$. It is obvious (2.13) holds for (2.21). By Remark 2.1 if (2.9) holds then every solution of (2.21) oscillates. Therefore Theorem 8 in [6] becomes a special case of Theorem 2.2.

Example. Consider

$$
\begin{equation*}
(y(t)-c y(t-\pi))^{\prime \prime}+(1+c) y(t-2 \pi)=0 \tag{2.22}
\end{equation*}
$$

where $0<c<1$. Every solution of (2.22) oscillates by Remark 2.2. In fact $y=\sin t$ is a solution of (2.22).

## III. Sublinear equations

We now consider Equations (1.2) in the sublinear case, that is, $0<\alpha<1$.
Theorem 3.1. Assume that:
(i) the assumptions for (1.2) in Section 1 hold;
(ii) $R(t)=\int_{t_{0}}^{t} \frac{d s}{r(s)}$ and $R(t) \rightarrow \infty$ as $t \rightarrow \infty$;
(iii) every solution of the second order ordinary differential equation

$$
\begin{equation*}
\left(r(t) z^{\prime}(t)\right)^{\prime}+p(t)\left(\frac{\lambda r(t)(t-\sigma(t))}{r(T) t}\right)^{\alpha} z^{\alpha}(t)=0, \quad \text { if } r \in n . i \tag{3.1}
\end{equation*}
$$

or

$$
\begin{equation*}
\left(r(t) z^{\prime}(t)\right)^{\prime}+p(t)\left(\frac{\lambda(t-\sigma(t))}{t}\right)^{\alpha} z^{\alpha}(t)=0, \text { if } r \in n . d . \tag{3.2}
\end{equation*}
$$

is oscillatory, where $0<\lambda<1$ is a constant. Then every solution of (1.2) is either oscillatory or tends to zero as $t \rightarrow \infty$.

Proof: Suppose the contrary and let $y(t)$ be an eventually positive solution. As in the proof of Theorem 2.1 we have $\left(r z^{\prime}\right)^{\prime} \leqslant 0$ and $r z^{\prime}>0$ for $t \geqslant T$. For the case that $z(t)>0$ for $t \geqslant T$, by Lemma 2.1 and (1.2), we get differential inequalities: either

$$
\begin{equation*}
\left(r(t) z^{\prime}(t)\right)^{\prime}+p(t)\left(\frac{k r(t)(t-\sigma(t))}{r(T) t}\right)^{\alpha} z^{\alpha}(t) \leqslant 0 \tag{3.3}
\end{equation*}
$$

for $t \geqslant T_{k} \quad r \in n . i$. and $0<k<1$ or

$$
\begin{equation*}
\left(t(t) z^{\prime}(t)\right)^{\prime}+p(t)\left(\frac{k(t-\sigma(t))}{t}\right)^{\alpha} z^{\alpha}(t) \leqslant 0 \tag{3.4}
\end{equation*}
$$

By the comparison method we know that (3.3) and (3.4) imply that (3.1) and (3.2) have a nonoscillatory solution [3, p.52], which contradicts assumption (iii). For the case that $z(t)<0$ for $t \geqslant T$, as in the proof of Theorem 2.1 the corresponding solution $y(t)$ tends to zero as $t \rightarrow \infty$. The proof is completed.
Remark 3.1. There are many results for oscillation of second order sublinear ordinary differential equations (3.1) and (3.2). For example, if

$$
\begin{equation*}
\int_{T}^{\infty} R^{\alpha}(t) p(t)\left(\frac{\lambda r(t)(t-\sigma(t))}{r(T) t}\right)^{\alpha} d t=\infty \text { for } r \in n . i \tag{3.5}
\end{equation*}
$$

or

$$
\begin{equation*}
\int_{T}^{\infty} R^{\alpha}(t) p(t)\left(\frac{\lambda(t-\sigma(t))}{t}\right)^{\alpha} d t=\infty \text { for } t \in n . d . \tag{3.6}
\end{equation*}
$$

then every solution of (3.1) or (3.2) respectively oscillates.
Theorem 3.2. In addition to the assumptions of Theorem 3.1 assume further that

$$
\begin{equation*}
\varlimsup_{t \rightarrow \infty} \frac{1}{r(t-\sigma(t)+\tau)} \int_{t-\sigma(t)+\tau}^{t}[u-(t-\sigma(t)+\tau)] p(u) d u>0 \text { for } r \in n . i . \tag{3.7}
\end{equation*}
$$

or

$$
\begin{equation*}
\varlimsup_{t \rightarrow \infty} \frac{1}{r(t)} \int_{t-\sigma(t)+\tau}^{t}[u-(t-\sigma(t)+\tau)] p(u) d u>0 \text { for } r \in n . d . \tag{3.8}
\end{equation*}
$$

then every solution of (1.2) oscillates.
Proof: Let $y(t)$ be an eventually positive solution. As in the proof of Theorem 3.1, we have $\left(r z^{\prime}\right)^{\prime} \leqslant 0, r z^{\prime}>0$ and $z(t)<0$ for $t \geqslant T$. From (2.19) and (1.2) we have

$$
\begin{equation*}
\left(r(t) z^{\prime}(t)\right)^{\prime}-\frac{p(t)}{c} z^{\alpha}(t-\sigma(t)+\tau) \leqslant 0 \tag{3.9}
\end{equation*}
$$

By the same arguments as used in the proof of Lemma 2.2 we can prove that (3.9) has no negative increasing solution under assumptions (3.7) and (3.8). Hence we get a contradiction, which porves the theorem.

Theorem 3.3. In addition to the assumptions of Theorem 3.1 assume further that $\sigma(t)$ is nondecreasing and

$$
\begin{equation*}
\int_{T}^{\infty} \frac{1}{r(s)} \int_{0}^{a+\frac{(\sigma-T)}{K}} P(u) d u d s=\infty \tag{3.10}
\end{equation*}
$$

where $K>1$ is some constant. Then every solution of (1.2) oscillates.
Proof: If not, it is sufficient to consider the case that $\left(r z^{\prime}\right)^{\prime} \leqslant 0, r z^{\prime}>0$ and $z(t)<0$ for $t \geqslant T$. As in the proof of Theorem 2.2, we have

$$
\begin{align*}
r(t) z^{\prime}(t) & =\int_{t}^{\infty} p(s) y^{\alpha}(s-\sigma(s)) d s  \tag{3.11}\\
& \geqslant-\frac{1}{c^{\alpha}} \int_{t}^{\infty} p(s) z^{\alpha}(s-\sigma(s)+\tau) d s \\
& \geqslant-\frac{1}{c^{\alpha}} \int_{t}^{t+\frac{(\sigma-\tau)}{K}} p(s) z^{\alpha}(s-\sigma(s)+\tau) d s \\
& \geqslant-\left(\frac{1}{c^{\alpha}} \int_{t}^{t+\frac{\sigma-\tau}{K}} p(s) d s\right) z^{\alpha}\left(t+\frac{(\sigma-\tau)}{K}-\sigma\left(t+\frac{\sigma-\tau}{K}\right)+\tau\right)
\end{align*}
$$

This is a first order sublinear delay differential inequality. From a known result [ $\boldsymbol{\theta}$, Theorem 3.3.2] (3.11) has no negative solution under assumption (3.10). This contradiction proves the theorem.

Remark. It would be interesting to obtain results similar to those presented here for the superlinear case $\alpha>1$ for equation (1.2).

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