1 INTRODUCTION

The mechanical properties of glacier beds, hereafter called basal mechanics, are a fundamental component of glacier dynamics. The importance of basal mechanics is most pronounced in areas of fast-flowing ice, where much of the ice flow is likely to be accommodated by slip along or deformation within the bed and where resistive basal shear traction can be appreciably less than gravitational driving stress (e.g. Raymond, 1996; Tulaczyk and others, 2000b; Morlighem and others, 2013). The mechanical properties of glacier beds are not fully understood, and this has clear implications for the veracity of models of future glacier states. Using synoptic-scale observations of glacier motion in different seasons to constrain numerical ice flow models, we study the mechanics of the bed beneath Hofsjökull, a land-terminating ice cap in central Iceland. Our results indicate that the bed deforms plastically and weakens following incipient summertime surface melt. Combining the inferred basal shear traction fields with a Coulomb-plastic bed model, we estimate the spatially distributed effective basal water pressure and show that changes in basal water pressure and glacier accelerations are non-local and non-linear. These results motivate an idealized physical model relating mean basal water pressure and basal slip rate wherein the sensitivity of glacier flow to changes in basal water pressure is inversely related to the ice surface slope.

KEYWORDS: Glaciology, surface velocity, basal mechanics, basal plasticity, basal hydrology

Plastic bed beneath Hofsjökull Ice Cap, central Iceland, and the sensitivity of ice flow to surface meltwater flux

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ABSTRACT. The mechanical properties of glacier beds play a fundamental role in regulating the sensitivity of glaciers to environmental forcing across a wide range of timescales. Glaciers are commonly underlain by deformable till whose mechanical properties and influence on ice flow are not well understood but are critical for reliable projections of future glacier states. Using synoptic-scale observations of glacier motion in different seasons to constrain numerical ice flow models, we study the mechanics of the bed beneath Hofsjökull, a land-terminating ice cap in central Iceland. Our results indicate that the bed deforms plastically and weakens following incipient summertime surface melt. Combining the inferred basal shear traction fields with a Coulomb-plastic bed model, we estimate the spatially distributed effective basal water pressure and show that changes in basal water pressure and glacier accelerations are non-local and non-linear. These results motivate an idealized physical model relating mean basal water pressure and basal slip rate wherein the sensitivity of glacier flow to changes in basal water pressure is inversely related to the ice surface slope.

ABSTRACT. The mechanical properties of glacier beds play a fundamental role in regulating the sensitivity of glaciers to environmental forcing across a wide range of timescales. Glaciers are commonly underlain by deformable till whose mechanical properties and influence on ice flow are not well understood but are critical for reliable projections of future glacier states. Using synoptic-scale observations of glacier motion in different seasons to constrain numerical ice flow models, we study the mechanics of the bed beneath Hofsjökull, a land-terminating ice cap in central Iceland. Our results indicate that the bed deforms plastically and weakens following incipient summertime surface melt. Combining the inferred basal shear traction fields with a Coulomb-plastic bed model, we estimate the spatially distributed effective basal water pressure and show that changes in basal water pressure and glacier accelerations are non-local and non-linear. These results motivate an idealized physical model relating mean basal water pressure and basal slip rate wherein the sensitivity of glacier flow to changes in basal water pressure is inversely related to the ice surface slope.
Evolution of the basal hydrological system complicates the response of glacier flow to surface meltwater flux, leading some authors to suggest that increased meltwater flux can enhance dynamic mass loss (Parizek and Alley, 2004). Increasing the frequency and duration of these accelerations results in dynamic glacier thinning (Parizek and Alley, 2004). Evolution of the basal hydrological system complicates the response of glacier flow to surface meltwater flux, leading some authors to suggest that increased meltwater flux can enhance dynamic mass loss (Parizek and Alley, 2004).

To better understand the fundamental mechanics of glacier beds and the response of glacier flow to surface meltwater flux, we consider Hofsjökull, a relatively small ice cap in central Iceland (Fig. 1). Hofsjökull experiences seasonal melt and contains multiple land-terminating outlet glaciers. Land-termination isolates the influence of basal water pressure on glacier flow by eliminating ocean tidal forcing and seasonal accelerations attributable to displacement of calving fronts (Joughin and others, 2008). Hofsjökull’s small size (diameter ~40 km), gentle surface slopes and dome-like shape (Fig. 1b) allow all outlet glaciers to experience roughly the same climate, thereby helping to elucidate the spatially heterogeneous response of individual outlet glaciers to comparable environmental forcing. Hofsjökull, which blankets a dormant volcanic caldera, is known to be underlain by till (Björnsson and others, 2003; Björnsson and Pálsson, 2008), which we show deforms plastically. While observations indicate that plastically deforming beds are well-represented in nature (Boulton, 1979; Iverson and others, 1998; Tulaczyk and others, 2000a), most models of basal mechanics and the influence of basal water pressure on ice flow dynamics focus on rigid-bedded glaciers. Therefore, while our observations focus solely on Hofsjökull, our physical model and conclusions have implications for understanding glacier systems worldwide.

2 DATA AND METHODS

2.1 Surface velocity observations

We capture temporal flow variability in multiple outlet glaciers during the early melt season by inferring complete velocity fields over Hofsjökull using repeat-pass interferometric synthetic aperture radar (InSAR) data (Fig. 2). Airborne InSAR data were collected with NASA’s Uninhabited Aerial Vehicle Synthetic Aperture Radar (UAVSAR) (Hensley and others, 2009) in June 2012, beginning ~2 weeks after the onset of seasonal melt on Hofsjökull (Fig. 3), and in February 2014, the middle of winter (Minchew and others, 2015). We expect basal water pressure during winter to be at or near

![Fig. 1.](https://doi.org/10.1017/jog.2016.26 Published online by Cambridge University Press)
annual minimum pressure due to the lack of surface melt, so we take the February data as the reference velocity field (Fig. 2a). Because InSAR measures the component of displacement occurring in the time between two radar acquisitions along the (oblique) radar line-of-sight (LOS) vector (Rosen and others, 2000), we designed the UAVSAR data collection to observe all of Hofsjökull from at least three unique LOS directions with approximately equal azimuthal spacing. For each azimuth heading, three flight tracks were needed to cover all of the ice cap, yielding a total of nine different flight tracks (Minchew and others, 2015). UAVSAR was flown aboard a NASA Gulfstream III aircraft that cruises at \( \sim 12.5 \) km altitude, providing an incidence angle range of \( 22^\circ \text{ to } 65^\circ \). We incorporated all InSAR data collected on given dates to estimate the horizontal velocity fields using a Bayesian approach (Minchew and others, 2015). The resulting velocity fields have \( \sim 200 \text{ m} \) resolution with typical errors \( < 1 \text{ cm d}^{-1} \) (Figs 2g–i).

2.2 Basal mechanics

To infer the basal shear traction and slip rate, we use the observed velocity fields to constrain finite-element ice flow models. Employing the Ice Sheet Systems Model (ISSM) (Morlighem and others, 2010), we constructed the geometry of Hofsjökull using basal topography derived from ice-penetrating radar surveys (Björnsson, 1986) and lidar-derived surface topography (Jóhannesson and others, 2013) (Figs 1b–e). In ISSM the basal boundary condition uses a Weertman-type sliding law whose scalar form is defined as:

\[
\tau_b = C u_b^{1/m}
\]

where \( \tau_b \) is the basal shear traction, \( u_b \) is the basal slip rate, \( m \geq 1 \), and coupling between ice and the bed is indicated by the non-negative scalar \( C \) (e.g. Weertman, 1957; Gudmundsson and Raymond, 2008). Using a higher-order ice flow model to estimate viscous deformation in the ice (Blatter, 1995; Pattyn, 2003; Morlighem and others, 2013), we solved for the optimal values of \( C \) at each mesh node such that \( \tau_b \) satisfies global stress balance and \( u_b \) minimizes the residual between modeled and observed surface velocities. Ice is treated as an incompressible viscous fluid whose constitutive relation is \( \tau_{e} = 2\eta\dot{\varepsilon}_e \), where \( \dot{\varepsilon}_e \) and \( \varepsilon_e \) are components of the strain rate and deviatoric stress tensors, respectively. \( \eta = A\varepsilon_e^{(1-n)/n} / \dot{\varepsilon}_e \) is the effective dynamic viscosity, and \( \varepsilon_e \) is effective strain rate (calculated from the second invariant of the strain rate tensor). Hofsjökull is temperate and damage in the ice is predominantly restricted to areas that are not of interest in this study (Björnsson and others, 2003), so we take \( A \) and \( n \) to be spatially and temporally constant, assigning

Fig. 2. Seasonal ice flow variability. (a) Horizontal surface speeds on Hofsjökull recorded 1–3 February 2014. Black contours indicate ice surface elevation in \( 150 \text{ m} \) increments (maximum contour at 1650 m). (b) and (c) Horizontal surface speed relative to (a) recorded 3–4 June 2012 and 13–14 June 2012, respectively. (d) Horizontal surface speed on 13–14 June 2012 relative to 3–4 June 2012. (e) and (f) Transsects of horizontal surface speed along A’-A’ and B’-B’, respectively. (g)–(i) Formal errors in InSAR-derived estimates of the horizontal velocity fields, derived from the method in Minchew and others (2013), for data collected (g) 1–3 February 2014, (h) 3–4 June 2012 and (i) 13–14 June 2012. Ice divides and labels in (b) are the same as in Figure 1b.

Fig. 3. (a) Cumulative seasonal melt inferred from meteorological data collected at \( \sim 1100 \text{ m} \) elevation on nearby Langjökull glacier (red triangle in Fig. 1). Data include incoming and outgoing solar and thermal radiation, relative humidity and wind speed and temperature at \( \sim 3 \text{ m} \) above the ice surface. (b) Ambient temperature is from the same meteorological data. Red dashed lines indicate the times when UAVSAR data were collected.
general, $C$ versus basal slip rate for 13 values to represent the sensitivity of inferred basal shear traction for each value of $m$. We expect results from the shallow-shelf model and large mesh grids. The higher-order and shallow-shelf models (MacAyeal, 1989) to infer basal conditions using ISSM and the same yield the same basal shear traction for any value of $m$. We infer $C$ using multiple values of $m$, such that $1 \leq m \leq 50$. The higher-order ice flow model is computationally expensive to implement so we applied the 2-D shallow-shelf model (e.g. MacAyeal, 1989) to infer basal conditions using ISSM and the same mesh grids. The higher-order and shallow-shelf models yield the same basal shear traction for $m = 1, 3$, and 5, so we expect results from the shallow-shelf model and large $m$ values to represent the sensitivity of inferred $C$ to large $m$. For all tested $m$ values, we retrieve basal shear traction fields that are within a few percent of one another because $C \propto u_b^{-1/m}$ for any $m$ in all observed data (Fig. 4). We will exploit this behavior to interpret inferred basal shear tractions in the context of sliding laws that differ from Eqn (1).

3 RESULTS
3.1. Surface velocity observations

Comparing winter and summer surface speeds, we find that early summer acceleration is evident in most outlet glaciers (Figs 2a–f). The only named glacier in our dataset that does not appear to accelerate is Kviðlajökull (Fig. 1b), which partially drains ice collected in the central caldera through a notch in the caldera rim, causing the observed surface speeds to be dominated by viscous deformation (Minchew and others, 2015). In other glaciers, typical increases in velocity are approximately double wintertime velocities, meaning that faster flowing areas tend to experience higher acceleration than slower moving areas. Highest accelerations are more evident at intermediate elevations (Figs 2e and f), with ice flow in higher- and lower-elevations indicating lower rates of acceleration, likely due to limited surface meltwater supply and the existence of a relatively efficient basal hydrological system, respectively. These observations are consistent with an influx of surface meltwater to, and subsequent pressurization of, a distributed hydrological system along much of the length of the outlet glaciers during the early melt season.

Between 3–4 June and 13–14 June the meteorological data indicate 4 days of little-to-no melt followed by 6 days of higher melt rates (Fig. 3) and UAVSAR data show notable changes in the relative surface velocities of the outlet glaciers. Glaciers that previously accelerated slowed except Sátújökull (transect A–A'; Fig. 2a) and Illvíðrajökull, suggesting that during the 10-day interim the capacity of the hydrological system beneath the other glaciers increased through a combination of enhanced efficiency, connectivity and the opening of cavities leeward of bumps in the bed (Figs 2b and 2c) (e.g. Schoof, 2010; Hoffman and Price, 2014; Andrews and others, 2014). While they likely have similar bed properties to the rest of Hofsjökull (Björnsson and others, 2003), Sátújökull and Illvíðrajökull have relatively small water catchment areas feeding their hydrological systems (Björnsson, 1988), which can delay evolution of the subglacial hydrological system (Schoof, 2010). Glaciers in the southwest quadrant slowed to near wintertime

Fig. 4. (a)–(c) Basal slipperiness versus basal slip rate inferred using a linear viscous sliding law ($m = 1$ in Eqn (1)) for horizontal surface speeds recorded (a) 1–3 February 2014, (b) 3–4 June 2012 and (c) 13–14 June 2012. Blue lines are the best-fit linear trends. (d) Basal slipperiness versus basal slip rate for 13–14 June inferred with $m = 1, 3$ and 5 (Eqn (1)). The solid black line is the best linear fit and indicates that, in general, $C \propto u_b^{-1/m}$ for any $m$, implying that $C$ is independent of $u_b$ and the bed deforms plastically.
velocities, while other outlet glaciers only partially slowed, consistent with differential evolution of the basal hydrological systems (Iken and Bindschadler, 1986; Sugiyama and Gudmundsson, 2004; Bartholomew and others, 2010). Múlajökull (transect B-B′; Fig. 2a) slowed considerably, losing approximately half of its early melt season acceleration, but maintained elevated flow speeds. Pjórsárljúkull generally experienced slowdown between 3–4 June and 13–14 June, though its southern-most portion accelerated slightly over the same time. There are no indications that any outlet glaciers slowed to below wintertime flow rates except in upstream areas with slightly reduced flow rates located at elevations that experienced little or no surface melt (Fig. 3). Given their overall minor changes and general association with relatively strong beds (next section), we do not consider areas that experience higher wintertime ice speeds to be germane to this study.

### 3.2 Basal mechanics

Modeled surface speeds match observed surface speeds to within 10% (20%) over more than 50% (70%) of areas where observed flow speeds exceed 4 cm d⁻¹ (Fig. 5). Notable misfits include the midstream region of Múlajökull, lower extent of Blöndujökull, and high-velocity region of Kvíslajökull (all in green dashed circle and respectively labeled A, B and C; Fig. 5a). In all three cases the modeled viscous flow component of surface speed exceeds the observed surface flow speed. Three likely causes for the misfits in these areas are: (1) ice thickness overestimation, (2) excessive surface slope estimates and (3) failure of the underlying assumptions in the higher-order ice flow model. Viscous flow in areas with low basal slip rates approximately scales as $c^2 h^n$, where $c$ is the surface slope (radians) and $h$ is ice thickness, so small errors in ice thickness and surface slope are amplified in the viscous flow estimates. In all three glaciers in question, surface crevassing led to gaps in the bedrock topography observations, which were filled by interpolation (Björnsson, 1986). Modeling errors on Kvíslajökull could be exacerbated by a large increase in local surface slope that is not properly accounted for in the surface elevation measurements, which were collected at a different time than the InSAR data. The upper extent of Kvíslajökull is coincident with a significant slope break at the lip of the underlying caldera and, therefore, may be especially prone to errors in surface slope. Where high horizontal normal stresses are present, the assumption of hydrostatic normal pressure at the bed breaks down and the use of the higher-order model incurs larger errors (Schoof and Hindmarsh, 2010). However, for this study, our interest is in areas with relatively high and seasonally variable basal slip rates, all of which are well fit by the modeled ice flow and have flow characteristics that support the underlying assumptions in the higher-order model (Blatter, 1995; Pattyn, 2003; Schoof and Hindmarsh, 2010). Therefore, we disregard the aforementioned and other areas containing high misfits between modeled and observed ice flow (magenta and cyan colored regions in Fig. 5a) and analyze basal shear traction and basal slip rates in the remaining areas.

Inferred basal shear traction and basal slip rate fields indicate that the bed beneath Hofsjökull deforms plastically. Inferred basal shear tractions typically are between 100 and 150 kPa in areas where basal slip rate is non-zero (Figs 6a–h and 7a–f) and are within a factor of two of the gravitational driving stress, $\tau_g = \rho g h a$, where $\rho$ is the mean density of ice, $g$ is gravitational acceleration, and $a$ is taken to be small such that $\sin (a) \approx a$ (Figs 7g–i). Basal shear tractions generally increase linearly with basal slip rate for slow basal slip ($u_b \leq 5$ cm d⁻¹) and are independent of basal slip rate and observed surface speed in areas of faster slip, behavior that is consistent with a plastically deforming bed. This conclusion is supported by laboratory tests of plastically deforming subglacial till (Kamb, 1991; Tulaczyk and others, 2000a). The existence of plastically deforming till beneath Hofsjökull is bolstered by direct observations of the bed of nearby Breiðamerkurjökull (blue triangle in Fig. 1a) (Boulton, 1979), the known bed composition of

![Fig. 5](https://doi.org/10.1017/jog.2016.26) Published online by Cambridge University Press
Hofsjökull (Björnsson and others, 2003; Björnsson and Pálsson, 2008) and the presence of an active drumlin field at the Mulajökull (transect B-B’ in Fig. 2a) terminus (Johnson and others, 2010). The existence of an active drumlin field is particularly salient given that drumlins are thought to be primarily depositional, rather than erosional, features that arise due to the behavior of plastically deforming till (Fowler, 2000, 2001; Schoof, 2007b). This suite of observations diminishes the applicability of rigid-bed sliding laws to our study site (e.g. Lliboutry, 1968; Fowler, 1987; Schoof, 2005) and supports limiting our focus to models that account for deformation within a finite till layer. Though the thickness of the till remains unknown, as do the mechanisms for maintaining a till layer (Iverson, 2010), we note that till layers only need to be centimeters thick to facilitate plastic deformation. The mechanical properties of till layers depend on pore water pressure (Tulaczyk and others, 2000a), represented herein by mean basal water pressure.

Given a plastic bed, it is straightforward to estimate mean basal water pressure using inferred basal shear tractions. We assume that basal slip is facilitated solely by plastic bed deformation (Tulaczyk and others, 2000b), thereby ignoring any linear relationship between basal shear traction and basal slip rate at low basal slip rates (Figs 7a–c). We define the bed yield stress using the Mohr-Coulomb criteria (Iverson and others, 1998; Kamb, 1991; Tulaczyk and others, 2000a):

$$\tau_y = \left(\frac{\rho g h - \rho_w}{C_0}\right) f_c$$

where $\rho_w$ is the mean basal water pressure, $f_c$ is the internal friction parameter for till and we have assumed negligible till cohesion (Iverson, 2010). For a plastic bed, $\tau_b = \tau_y$ wherever basal slip occurs ($u_b > 0$) and $\tau_b < \tau_y$ where there is no basal slip ($u_b = 0$). By setting $\tau_b = \tau_y$ and taking the unknown $f_c$ to be the median of published values ($f_c = 0.4$; Iverson, 2010), we can solve for estimates of water pressure (Figs 6i–p). In areas with little or no basal slip (Fig. 6a), the estimated water pressure is the upper bound (indicated by subdued colors in Figs 6i and 6m).

The accuracy of estimated water pressure is relatively insensitive to the chosen value of $f_c$. The error in estimated

Fig. 6. Inferred (a)–(d) basal slip rates, (e)–(h) basal shear tractions, (i)–(l) basal water pressures and (m)–(p) normalized basal water pressure $\rho'_w = \rho_w / (\rho g h)$ for $\rho = 9000$ kg m$^{-3}$. The left column contains properties inferred from data collected 1–3 February 2014 while the two center columns contain inferred properties for 3–4 June 2012 and 13–14 June 2012, relative to the left column. The right column shows 13–14 June 2012 relative to 3–4 June 2012. Bright areas in (i)–(p) indicate regions where $u_b = \tau_y$, allowing for direct estimates of basal water pressure, while water pressures in subdued regions (i.e. areas of lower color intensity that tend to appear gray) are an upper bound on the absolute estimates in (i) and (m) or at least one estimate in the differences in (j)–(l) and (n)–(p). Ice divides and labels in (a) are the same as in Figure 1b.
water pressure arising from incorrect values of \( f_c \) is given as:

\[
\delta p_w = \frac{\partial p_w}{\partial f_c} \delta f_c \quad \text{(3)}
\]

Taking \( f_c = 0.4 \) and \( \delta f_c = 0.2 \) \citep{Iverson2010}, Eqn (3) gives \( \delta p_w = 1.25 \tau_y \). Given that \( \rho_w \) is generally more than an order of magnitude larger than \( \tau_y \), the range of ice thicknesses corresponds to the mean and standard deviation in rapidly-flowing areas. Eqn (3) gives \( \delta p_w = 1.25 \tau_y \). Given that \( \rho_w \) is generally more than an order of magnitude larger than \( \tau_y \), the range of ice thicknesses corresponds to the mean and standard deviation in rapidly-flowing areas.

We infer higher basal water pressure in areas where observed glacier flow is faster during the early melt season (Figs 6i–p). The relationship between temporal changes in surface speed and the corresponding inferred changes in basal water pressure is non-local (Figs 2a–d and 6) because perturbations in basal shear traction can affect ice flow over larger spatial scales \citep{Raymond1996}. On Sátujökull and Illviðrajökull, we note that elevated basal water pressure is present under much of the outlet glaciers, whereas basal water pressure variations are less spatially extensive beneath other outlet glaciers. Sustained elevated water pressure beneath Sátujökull and Illviðrajökull supports our previous postulate that the respective basal hydrological systems did not channelize during the timespan of our data collection. Overall, estimates of basal water pressure show that water pressure and flow speed are nonlinearly related, with small changes in water pressure (\( \lesssim 2\% \)) producing more substantial (\( \gtrsim 100\% \)) changes in surface speed (Figs 6i–p and 2a–d, respectively). This nonlinearity, which has been previously noted on an Alaskan glacier \citep{Jay-Allemand2011}, combined with the plasticity of the bed motivates an idealized physical model for the influence of basal hydrology on ice flow.

4 DISCUSSION

When the bed is perfectly plastic, the Weertman-type sliding law (Eqn (1)), which is predicated on the assumption of a rough, rigid bed \citep{Weertman1957, Kamb1970, Nye1970}, does not provide insight into the coupling between basal shear traction and ice flow because the exponent \( 1/m \approx 0 \) \citep{Iverson1998}. In deriving an alternative
basal slip model, we consider an idealized case in which basal slip along a smooth, horizontal bed arises solely from an imbalance between basal shear traction and gravitational driving stress (Figs 7g–i). In areas where basal slip is a significant fraction of the total surface velocity, slip along or within the glacier margins is negligible, and speed varies gradually along flowlines, we can consider ice flow to be controlled primarily by basal shear traction and lateral shearing in the glacier side walls. Sidewall shearing tends to concentrate near glacier margins, because ice is a non-Newtonian viscous fluid, so we further simplify the model by considering only the central trunk of a symmetric glacier, of width $2w$, where lateral shearing is locally negligible (e.g. Joughin and others, 2004). Under these assumptions, the normalized basal slip rate $u_b' = u_b/u_{b\text{O}} = \left[1 - t_b/\tau_0\right]^n$ where $n$ is the stress exponent in the constitutive relation for ice and the maximum basal slip rate, $u_{b\text{O}} = 2\pi C_0 C_3 (w/h)^3 w/(n + 1)$, corresponds to $t_b = 0$ (Raymond, 1996). Maximum basal slip rate is a function of glacier geometry and ice viscosity, parameters that vary over annual or longer timescales, meaning that $u_b'$ captures all of the sub-annual-timescale variability in the idealized model. The dependence of basal slip rate on the stress ratio $t_b/\tau_b$ is consistent with the inferred basal properties discussed above where the stress ratio decreases with increasing basal slip rate, reaching a minimum in the early melt season of $t_b/\tau_b \approx 0.75$ (Figs 7g–i).

After applying the Mohr-Coulomb criteria (Eqn (2)) by imposing $t_b = t_w$, we can write a single equation for normalized basal slip rate as a function of normalized basal water pressure, $\rho_w' = \rho_w/\rho gh$ (Fig. 8a):

$$u_b' = \left[H(\Theta)\Theta\right]^n; \quad \Theta = 1 - \mu(1 - \rho_w')$$

(4)

where $\mu = f_c/\alpha$ is the stress factor that represents the ratio of dry ($\rho_w = 0$) basal shear traction to gravitational driving stress. Over the timescales of interest, it is reasonable to think of $\mu$ as the static stress component and $(1 - \rho_w')$ as the dynamic component. That basal slip arises from unbalanced basal shear traction and driving stress requires the basal slip parameter, $\Theta$, to be positive for basal slip to occur. Because basal shear traction can be less than the bed yield stress, we apply $H(\Theta)$, the Heaviside step function ($H(\Theta) = 1$ for $\Theta > 0$ and $H(\Theta) = 0$ otherwise), in Eqn (4) to ensure $u_b'$ is everywhere non-negative and real for any $n$. This condition provides some insight as to when certain glaciers accelerate in response to variations in basal water pressure. Setting $\Theta = 0$ (i.e. $t_b = t_w$) yields the critical water pressure:

$$\rho_w' = \rho_0 h (1 - \mu^{-1}),$$

(5)

above which basal slip is non-zero. Only basal water pressure variations above the critical water pressure will lead to glacier flow variability.

Basal water pressure is equal to critical water pressure whenever gravitational driving stress is equal to the yield stress of the bed. During winter on Hofsjökull, inferred basal shear traction and driving stress are roughly balanced in areas with high basal slip rates (Fig. 7g). Consequently, inferred wintertime basal water pressure (Fig. 6i) and critical water pressure (Eqn (5)) should be approximately equal as well. Indeed we find good agreement between $\rho_w'$ and wintertime $\rho_w$ in areas with basal slip rates above 4 cm d$^{-1}$ (Fig. 8b). This agreement suggests that estimates of annually averaged, effective water pressures for broad spatial areas (several ice thicknesses) can be gleaned from surface slope and thickness measurements on glaciers that are at or near steady state.

For sub-annual water pressure variations, our basal slip model (Eqn (4)) shows that the sensitivity of basal slip rate to changes in mean basal water pressure is given as:

$$\psi = \frac{\partial u_b'}{\partial \rho_w'} = \mu n[H(\Theta)\Theta]^{n-1}$$

(6)

and scales as the inverse of the ice surface slope. Published values give $0.3 \le f_c \le 0.5$, with $f_c$ being approximately constant in time (Iverson, 2010), while observed surface slopes vary by up to two orders of magnitude, with minimum values $\sim 10^{-5}$, and may change on multi-annual timescales. Therefore, ice surface slope is the dominant factor in $\mu$ at seasonal and shorter timescales. Consequently, for a given $f_c$, glaciers with gentler surface slopes require higher mean basal water pressures to initiate slip but, once slip has commenced, these glaciers are highly sensitive to subsequent changes in water pressure. This behavior is due to the dependence of basal slip rate on the ratio $t_w/\tau_b$ for a given ice thickness, glaciers with gentle surface slopes have relatively low gravitational driving stress, $t_w$, requiring basal water pressure to approach ice overburden pressure (i.e. for
the glacier to approach floatation) for basal slip to commence. Once basal slip is underway, basal slip rates become increasingly sensitive to changes in water pressure as basal slip rates increase (Fig. 8a) because shearing in the glacier sidewalls is a fundamental control on ice flow in our model. A consequence of nonlinearity in μ is that for a given change in the absolute value of mean basal water pressure (∆|ρw|) the amplitude of increases in basal slip rate (∆|δρw| > 0) will exceed the amplitude of decreases in basal slip rate (i.e. |δρw| < 0) (<|δρw| > 0)). Furthermore, that μ scales as the inverse of ice surface slope helps explain some of the variable response to meltwater flux on Hofsjökull, where typical surface slopes are <0.2, with a median of 0.06, making 2 μ ≤ 12 for ℓ∞ = 0.4 (Fig. 9).

The sensitivity of basal slip rate to changes in basal water pressure can be understood in a Mohr’s circle framework (Fig. 10), which considers the relationship between shear stress and effective normal stress (Malvern, 1969). In the idealized model, effective normal stress is equal to effective pressure N, where N = p − ρw and p = ghw. For basal slip, we consider the gravitational driving stress and the basal shear traction, which form the radii of the concentric half-circles labeled D, for driving stress (green), and B, for basal shear traction (red). We delineate the Mohr-Coulomb criteria (Eqn 2) using the line labeled ‘yield criteria’, which slopes at an angle φ = tan −1(ℓ∞). The value of ψ dictates the maximum size of the half-circles because the Mohr-Coulomb criteria, along with the existence of non-zero stresses within the ice, requires B to be smaller than D at all times. Over the timescales of interest, ψ is constant and N is bounded by the bed yield stress. Thus half-circle D can enter the gray-shaded region but half-circle B cannot and B intersects the yield line at ρw = ρwinst. Disparity between driving stress and basal shear traction in their response to yieldings informs the sensitivity of basal slip rate changes in basal water pressure. When ℓ∞ < ℓγ, both circles have approximately the same radius. Decreasing ψ reduces ψ*, shrinking half-circle D. If we hold ℓ∞ constant, then glaciers with smaller α will have greater freedom to traverse along the x-axis (effective normal stress) without their stress circles intersecting the yield line, meaning that ρwinst is large, as expected from Eqn (5). Once the bed beneath a shallow-sloping glacier begins to yield, there is less space between N at yielding and the origin where uψ = umax, meaning that ψ must be large. Conversely, increasing α enlarges half-circle D causing the Mohr circles to intersect the yielding criteria at higher values of N (lower ρwinst) than for shallower-sloping glaciers, requiring relatively large subsequent increases in ρw to achieve uψ = umax (i.e. ψ is small). We can achieve the same effect by increasing (decreasing) ℓ∞ instead of decreasing (increasing) α. Hence the sensitivity of basal slip rate to changes in basal water pressure scales as μ.

Together, spatial variability in μ (Fig. 9) and inferred basal water pressure (Figs 6i–p) more closely represent patterns in seasonal velocity (Figs 2a–c) than either individually. Outlet glaciers on Hofsjökull that show the greatest decrease in speed during the early melt season have the lowest μ values due to steep ice surface slopes. Outlet glaciers that experience nearly complete cessation of the observed acceleration within 10 days have μ ≤ 5 (Fig. 9) and show sharp reductions in basal water pressure (Figs 6i–k and n–o). Conversely, outlet glaciers that maintained elevated ice flow between early and mid-June 2012 have relatively high μ values due to gradual surface slopes, except for Illúvriðrajökull, whose basal hydrological system likely did not become channelized. Glaciers in the southeast quadrant, which have relatively high μ values, sustain increased speeds during the period of observation despite modestly elevated basal water pressures.

These observations indicate that the stress factor, μ, is a useful parameter in establishing a glacier’s dynamic response to basal water flux. Glaciers accelerate in response to rapid changes in melting or precipitation so long as basal water pressure exceeds the critical water pressure (Eqn 5), a function of ice overburden pressure and μ. Initial melt-season accelerations may be ephemeral owing to evolving hydrological systems but diurnal melt cycles and periodic rain events can continue to episodically overwhelm and pressurize the system throughout the melt season. Ice flow responds readily to these continual, short-term water pressure fluctuations (Shepherd and others, 2009; Schoof, 2010) and this response will be amplified on glaciers with gentle surface slopes. Longer melt seasons, increasing diurnal temperature variations and more frequent rain

Fig. 9. Stress factor μ for Hofsjökull calculated assuming ℓ∞ = 0.4 and with surface slopes averaged over ~10 ice thicknesses. Blue contours delineate the bright regions in Figures 6i–p, indicating that basal slip occurs in these areas.
events (e.g. Schuenemann and Cassano, 2010) brought on by a warming climate will potentially bolster total melt-season mass flux in gently sloping glaciers, while glaciers with steep surface slopes will be less susceptible to these prolonged cyclical basal water pressure variations. Given the prevalence of till-covered glacier beds, these findings should help reconcile observations of the influence of basal hydrology and surface meltwater flux on glacier flow (Zwally and others, 2002; Joughin and others, 2008; Shepherd and others, 2009; Bartholomew and others, 2010; Moon and others, 2014; Tedstone and others, 2013, 2015). In particular, it may be useful to classify glaciers by μ to facilitate mechanistically consistent comparisons of the response of different glaciers with surface meltwater flux and enhance our understanding of basal processes.

Our model has some limitations in its immediate applicability to understanding the response of soft-bedded glaciers to surface meltwater flux. The primary limitation is that not all glaciers closely adhere to the idealized assumptions employed in the model derivation. More robust testing with numerical models and further observations on other glacier systems are needed to support the model and lend credence to μ as a viable mechanistic parameter. Another limitation is the need to decouple the dependence of ψ and the evolution of the basal hydrological system on the ice surface slope in observations (e.g. Schoof, 2010). These mechanical and hydrological dependencies work together, with gentler surface slopes potentially resisting channelization of the hydrological system by increasing the critical meltwater flux needed to facilitate the switch from an inefficient distributed system to an efficient channelized system. This resistance to channelization increases the likelihood that an inefficient distributed hydrological system will persist later in the melt season on shallower-sloping glaciers, resulting in higher basal water pressure variability (Schoof, 2010) in a system with higher dynamical sensitivity to such variability (Eqn (6)). Because it may not be possible to know the state of the basal hydrological system during the early melt season, collecting observations aimed at understanding ψ is challenging. In this work, we avoid the complexities of evolving basal hydrological systems by estimating the effective basal water pressure directly from observations of surface velocity and the inferred basal shear traction fields. Our approach isolates the mechanical basal properties from the hydrological properties, providing insight into the mechanics of deformable glacier beds.

Improved understanding of basal mechanics is a key component of the physical foundation on which we can build predictive models to explore a range of plausible future glacier states in a warming climate. One outstanding problem currently prohibiting reliable predictive models is an incomplete understanding of how changes in water flux at the bed of glaciers, arising from surface meltwater flux, transmission of tidal loads (e.g. Thompson and others, 2014) or subglacial lake drainage (e.g. Magnússon and others, 2007, 2010; Fricker and Scambos, 2009), influences multi-annual-timescale ice flow. Solving this problem requires defining the sensitivity of basal slip rate to changes in ψ, the water flux through the basal hydrological system, given as:

$$\frac{\partial \psi}{\partial t} = \frac{\partial \psi}{\partial t} \frac{\partial \rho_w}{\partial \psi} \frac{\partial \psi}{\partial \rho_w}.$$  (7)

The second term on the right hand side of Eqn (7) (\(\partial \rho_w/\partial \psi\)) is a function of the time-varying state of the basal hydrological system and is the subject of numerous studies (e.g. Libboury, 1968; Röthlisberger, 1972; Nye, 1976; Kamb, 1987; Schoof, 2010). With this study, we define the first term on the right hand side of Eqn (7), simply the dimensional form of Eqn (6) in which both sides are multiplied by \(u_{b,\text{mag}}/(\rho gh)\), in an idealized framework for glaciers with deformable beds.

5 CONCLUSION

We use InSAR-derived measurements of ice surface velocity combined with a numerical ice-flow model to study the response of several outlet glaciers on Hofsjökull ice cap to surface melt during the early melt season. Observations indicate that the outlet glaciers respond differently to similar environmental forcing with some glaciers maintaining fast ice flow relative to winter while other glaciers appear to accelerate then slow to wintertime speeds over the same time period. This spatial heterogeneity in the response of ice flow to surface melt is at least partially explained by differential evolution of the basal hydrological systems of the outlet glaciers, which influences how surface meltwater flux can alter basal shear traction and consequently ice flow. We infer basal shear tractions using the observed velocities and note that the bed beneath Hofsjökull deforms plastically, allowing for a straightforward means of estimating absolute and seasonally variable basal water pressures. The resulting water pressure estimates indicate that changes in basal water pressure and surface velocity are non-local and non-linearly related. These findings motivate an idealized model of basal slip rate wherein the response of glaciers with plastically deforming beds is largely determined by the relationship between the intrinsic mechanical properties of the deforming bed and glacier geometry. This relationship is quantified by the stress factor, μ, defined as the ratio of the internal friction parameter for the bed to the ice surface slope.

In plastic-bedded glaciers, μ helps determine the critical basal water pressure, \(p_{\text{c}}\), at which basal slip commences and the sensitivity of basal slip rate to changes in basal water pressure. Given the ranges of plausible values for internal friction in till and ice surface slopes, both the critical water pressure and sensitivity of basal slip rate to changes in basal water pressure are driven primarily by the ice surface slope. Glaciers with shallower ice surface slopes require higher basal water pressure (relative to overburden pressure) for incipient basal slip, but basal slip rate is then more sensitive to basal water pressure variations than in steeper sloping glaciers. Our observations support this conclusion by showing that outlet glaciers that maintained elevated ice flow between early and mid-June, despite evidence that the respective hydrological systems evolved toward being channelized, have relatively high μ values, arising from gentle surface slopes. Conversely, outlet glaciers that experienced the greatest slowdowns over the same time period have relatively low μ values, or steep surface slopes.

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