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Task-priority motion planning of underactuated systems: an endogenous configuration space approach – ERRATUM
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Figures 2 and 5 were incorrectly reproduced in the above publication (Ratajczak et al. 2009). The figures are reproduced below in their correct form.

![Fig. 2. Task-priority algorithm (both S₁ and S₂).](image1)

![Fig. 5. Single-task algorithm (only S₁).](image2)

Reference