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Task-priority motion planning of underactuated systems: an endogenous configuration space approach – ERRATUM
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Figures 2 and 5 were incorrectly reproduced in the above publication (Ratajczak et al. 2009). The figures are reproduced below in their correct form.

![Figure 2](image-url)

Fig. 2. Task-priority algorithm (both $S_1$ and $S_2$).

![Figure 5](image-url)

Fig. 5. Single-task algorithm (only $S_1$).

Reference

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