A THEOREM FOR A FLUID SPHERE IN STOKES FLOW

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Abstract

A sphere theorem for non-axisymmetric Stokes flow of a viscous fluid of viscosity μ² past a fluid sphere of viscosity μ¹ is stated and proved. The existing sphere theorems in Stokes flow follow as special cases from the present theorem. It is observed that the expression for drag on the fluid sphere is a linear combination of rigid and shear-free drags.

1. Introduction

The study of the hydrodynamic forces on viscous drops moving in an ambient fluid has various applications to problems such as dispersion of one fluid in another.

The Stokes flow due to uniform translation of a spherical fluid particle in an unbounded fluid medium was treated by both Rybczynski [15] and Hadamard [6]. Using Lamb’s [10] general solution, Hetsroni and Haber [8] have found the solution for the flow fields, interior and exterior to a single spherical droplet submerged in an unbounded arbitrary Stokes flow. They have also obtained the expression for the drag on the droplet, which is a generalisation of Faxen’s law for a rigid spherical particle. This result for drag was also derived by Rallison [14] using the reciprocal theorem. Making use of Lamb’s [10] solution Fuentes et al. [3, 4] have studied the images of singularities such as Stokeslet and the higher order Stokes singularities near a viscous drop. As Lamb’s [10] solution is in the form of an infinite series, the algebra in [3, 4] is highly involved and

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the solution obtained is not in a closed form.

Shail [16] and Shail and Onslow [17] have proved sphere theorems for a class of non-axisymmetric flows within and past a rigid sphere respectively. They have employed a representation for velocity and pressure used in a paper by Hackborn et al. [5]. However, this analysis is restricted to the cases where the velocity dependence on the azimuthal angle, $\phi$, is linear in $\cos \phi$ and $\sin \phi$. Essentially, in this case, the problem reduces to an equivalent axisymmetric problem and the solution is readily obtained using Collin’s [2] theorem and Butler’s [1] theorem.

Recently, Palaniappan et al. [13] have given a general representation of the solution of Stokes equations in a closed form in terms of two scalar functions $A$ and $B$ which are biharmonic and harmonic respectively. It is also shown that this solution is equivalent to Lamb’s [10] general solution and a theorem for non-axisymmetric Stokes flow past a rigid sphere is proved. In [12] a sphere theorem for non-axisymmetric Stokes flow about a shear-free sphere is proved.

In this note, we prove a sphere theorem for a general non-axisymmetric Stokes flow in and around a fluid sphere, by using the velocity representation given in [13]. The flow fields interior and exterior to a fluid sphere are given in a closed form in terms of the two scalar functions $A$ and $B$. From this theorem the results of [13, 12] are deduced as special cases. The corresponding results for the axisymmetric case are presented as a corollary to the theorem. The expression for the drag on the fluid sphere is given and it is found to be a linear combination of rigid and shear-free drags. Several illustrative examples are presented to demonstrate the usefulness of our method and in each case the force acting on the fluid spherical particle is calculated.

2. The problem

We consider the steady flow of a viscous, incompressible fluid (viscosity $\mu^e$) past a viscous fluid sphere (viscosity $\mu^i$). The Stokes equations are as follows:

Exterior to the fluid sphere

\[
\begin{align*}
\mu^e \nabla^2 \mathbf{q}^e &= \text{grad } p^e, \\
\nabla \cdot \mathbf{q}^e &= 0;
\end{align*}
\]

In the fluid sphere

\[
\begin{align*}
\mu^i \nabla^2 \mathbf{q}^i &= \text{grad } p^i, \\
\nabla \cdot \mathbf{q}^i &= 0,
\end{align*}
\]
where \( \mathbf{q}^e \) and \( \mathbf{q}^i \) are the velocities outside and in the fluid sphere respectively, and \( p^e \) and \( p^i \) are the pressures. From \([13]\), the velocity and pressure fields are as follows: Outside the fluid sphere

\[
\mathbf{q}^e = \nabla \times (\nabla \times (rA^e)) + \nabla \times (rB^e), \quad (5)
\]
\[
p^e = p_0 + \mu^e \frac{\partial}{\partial r} (r \nabla^2 A^e), \quad (6)
\]

where

\[
\nabla^4 A^e = 0, \quad (7a)
\]
\[
\nabla^2 B^e = 0. \quad (7b)
\]

In the fluid sphere

\[
\mathbf{q}^i = \nabla \times (\nabla \times (rA^i)) + \nabla \times (rB^i), \quad (8)
\]
\[
p^i = p_0 + \mu^i \frac{\partial}{\partial r} (r \nabla^2 A^i), \quad (9)
\]

where

\[
\nabla^4 A^i = 0, \quad (10a)
\]
\[
\nabla^2 B^i = 0. \quad (10b)
\]

From (5) the components of \( \mathbf{q}^e \) in the directions of \( r, \theta, \phi \) are respectively

\[
q^e_r = -\frac{1}{r} (\cot \theta A^e_\theta + A^e_\theta + \csc^2 \theta A^e_\phi), \quad (11a)
\]
\[
q^e_\theta = \frac{1}{r} \frac{\partial}{\partial \theta} (A^e_r + r A^e_\theta) + \csc \theta B^e_\phi, \quad (11b)
\]
\[
q^e_\phi = \frac{1}{r \sin \theta} \frac{\partial}{\partial \phi} (A^e_r + r A^e_\phi) - B^e_\phi. \quad (11c)
\]

The components of \( \mathbf{q}^i \) can be written down by replacing the superscript \( e \) by \( i \) in (11a,b,c). The boundary conditions are

(I): the normal velocity vanishes at the surface of the sphere, i.e.,

\[
q^e_r = q^i_r = 0 \quad \text{on} \quad r = a.
\]

(II): the tangential velocity components are continuous at the interface i.e.,

\[
q^e_\theta = q^i_\theta, \quad q^e_\phi = q^i_\phi \quad \text{on} \quad r = a.
\]
(III): the tangential stress components are continuous across the boundary i.e.,

\[ T_{r\theta}^e = T_{r\theta}^i, \quad T_{r\phi}^e = T_{r\phi}^i \quad \text{on} \quad r = a, \]

where

\[
T_{r\theta}^e = \frac{\mu^e}{r^2} \frac{\partial}{\partial \theta} \left[ r q_r^e + r^2 \frac{\partial^2 A^e}{\partial r^2} - 2A^e \right] + \mu^e r \csc \theta \frac{\partial}{\partial \phi} \left[ \frac{\partial}{\partial r} \left( \frac{B^e}{r} \right) \right],
\]

\[
T_{r\phi}^e = \frac{\mu^e}{r^2 \sin \theta} \frac{\partial}{\partial \phi} \left[ r q_r^e + r^2 \frac{\partial^2 A^e}{\partial r^2} - 2A^e \right] - \mu^e r \frac{\partial}{\partial \theta} \left[ \frac{\partial}{\partial r} \left( \frac{B^e}{r} \right) \right].
\]

\[ T_{r\theta}^i \quad \text{and} \quad T_{r\phi}^i \quad \text{can be obtained similarly by replacing 'e' by 'i'.} \]

The above conditions are satisfied if, on \( r = a \), we have

\[
A^e = A^i = 0, \quad A_r^e = A_r^i, \quad B^e = B^i, \quad \mu^e A_{rr}^e = \mu^i A_{rr}^i, \quad \mu^e \frac{\partial}{\partial r} \left( \frac{B^e}{r} \right) = \mu^i \frac{\partial}{\partial r} \left( \frac{B^i}{r} \right). \quad (12a,b, 13a,b, 14a,b)
\]

3. The theorem

**Theorem.** Let the flow of a viscous, incompressible fluid (with viscosity \( \mu^e \)) in the absence of any boundary be characterized by a biharmonic \( A_0(r, \theta, \phi) \) and a harmonic \( B_0(r, \theta, \phi) \). Let the singularities (We extend the term 'singularity' to include flows non-vanishing at infinity and regular everywhere else, such as uniform flow, quadratic flow etc.) of these functions be at a distance greater than 'a' from the origin. If \( A_0 \sim o(r) \) and \( B_0 \sim o(1) \) at the origin and if now a fluid (with viscosity \( \mu^i \)) sphere \( r = a \) be introduced in the flow field with \( q_r^e = q_r^i = 0, \ q_{\theta}^e = q_{\theta}^i, \ q_{\phi}^e = q_{\phi}^i, \ T_{r\theta}^e = T_{r\theta}^i \) and \( T_{r\phi}^e = T_{r\phi}^i \) on the boundary \( r = a \), then the solution for \( r > a \) is

\[
A^e(r, \theta, \phi) = A_0(r, \theta, \phi) + (1 - \lambda) \left[ -\frac{r}{a} A_0 \left( \frac{a^2}{r}, \theta, \phi \right) \right] + \lambda \left[ \frac{(r^2 + a^2)^2}{2ar} A_0 \left( \frac{a^2}{r}, \theta, \phi \right) + \frac{(r^2 - a^2)}{a} \frac{\partial}{\partial r} A_0 \left( \frac{a^2}{r}, \theta, \phi \right) \right] - \frac{r^2(r^2 - a^2)^2}{4a^3} \nabla^2 \left( r^{-1} A_0 \left( \frac{a^2}{r}, \theta, \phi \right) \right), \quad (15)
\]
A theorem for a fluid sphere in Stokes flow

\[ B^e(r, \theta, \phi) = B_0(r, \theta, \phi) + \lambda \left[ -\frac{a}{r} B_0 \left( \frac{a^2}{r}, \theta, \phi \right) \right] + (1 - \lambda) \left[ \frac{a}{r} B_0 \left( \frac{a^2}{r}, \theta, \phi \right) - \frac{3r}{a^3} \int_0^{a^2/r} R B_0(R, \theta, \phi) dR \right] + 3(1 - \lambda) \frac{r}{a^3} \left[ \int_0^{a^2/r} R B_0(R, \theta, \phi) dR \right] \]

and the solution for \( r < a \) is

\[ A^i(r, \theta, \phi) = (1 - \lambda) \left[ \frac{(a^2 - r^2)}{2a^2} A_0(r, \theta, \phi) + \frac{r(r^2 - a^2)}{a^2} \frac{\partial}{\partial r} A_0(r, \theta, \phi) - \frac{(r^2 - a^2)^2}{4a^2} \nabla^2 A_0(r, \theta, \phi) \right], \]

\[ B^i(r, \theta, \phi) = 2(1 - \lambda) B_0(r, \theta, \phi) - 3(1 - \lambda)(1 - 2\lambda) r^{3\lambda - 2} \int_0^r R^{1 - 3\lambda} B_0(R, \theta, \phi) dR, \]

where \( \lambda = \mu^i / (\mu^e + \mu^i) \).

**Proof.** By a direct verification, it can be shown that the expressions given in (15)-(18) satisfy (7a,b) and (10a,b) together with the boundary conditions (12a,b) - (14a,b). It is noted that \( A^e \) and \( B^e \) ((15) and (16)) can be written as

\[ A^e(r, \theta, \phi) = A_0(r, \theta, \phi) + (1 - \lambda) A^*_S(r, \theta, \phi) + \lambda A^*_K(r, \theta, \phi) \]

\[ B^e(r, \theta, \phi) = B_0(r, \theta, \phi) + (1 - \lambda) B^*_S(r, \theta, \phi) + \lambda B^*_K(r, \theta, \phi) + 3(1 - \lambda) \frac{r}{a^3} \left[ \int_0^{a^2/r} R B_0(R, \theta, \phi) dR \right] \]

\[ - (1 - 2\lambda) \frac{a^{6\lambda}}{r^{3\lambda}} \int_0^{a^2/r} R^{1 - 3\lambda} B_0(R, \theta, \phi) dR \],

where

\[ A^*_S(r, \theta, \phi) = -\frac{r}{a} A_0 \left( \frac{a^2}{r}, \theta, \phi \right), \]
\[ A^*_h(r, \theta, \phi) = -\frac{(r^2 + a^2)}{2ar} A_0 \left( \frac{a^2}{r}, \theta, \phi \right) \]
\[ -\frac{(r^2 - a^2)}{4a^3} \nabla^2 \left( r^{-1} A_0 \left( \frac{a^2}{r}, \theta, \phi \right) \right), \]
\[ B^*_S(r, \theta, \phi) = \frac{a}{r} B_0 \left( \frac{a^2}{r}, \theta, \phi \right) - \frac{3r}{a^3} \int_0^{a/r} R B_0(R, \theta, \phi) dR, \]
\[ B^*_R(r, \theta, \phi) = -\frac{a}{r} B_0 \left( \frac{a^2}{r}, \theta, \phi \right), \]

are the perturbed terms due to shear-free (suffix $S_F$) and rigid (suffix $R$) spheres [13, 12] respectively.

**Corollary.** Assuming \( A^e(r, \theta, \phi) = A^e(r, \theta), A^i(r, \theta, \phi) = A^i(r, \theta), B^e(r, \theta, \phi) = B^e(r, \theta, \phi) = 0 \) in (15)-(18) and differentiating with respect to \( \theta \), and setting \( \partial A^e/\partial \theta = \psi^e/r \sin \theta, \partial A^i/\partial \theta = \psi^i/r \sin \theta, \partial A_0/\partial \theta = \psi_0/r \sin \theta \) we obtain the theorem for axisymmetric Stokes flow past a fluid sphere in terms of the Stokes stream function \( \psi(r, \theta) \). The corresponding solution for the motion exterior to the fluid sphere is given by

\[ \psi^e(r, \theta) = \psi_0(r, \theta) + (1 - \lambda) \left[ \frac{r^3}{a^3} \psi_0 \left( \frac{a^2}{r}, \theta \right) \right] \]
\[ + \lambda \left[ \frac{r(r^2 - 3a^2)}{2a^3} \psi_0 \left( \frac{a^2}{r}, \theta \right) + \frac{r^2(r^2 - a^2)}{a^3} \frac{\partial}{\partial r} \psi_0 \left( \frac{a^2}{r}, \theta \right) \right. \]
\[ \left. - \frac{r^2(r^2 - a^2)^2}{4a^5} D^2 \left( r \psi_0 \left( \frac{a^2}{r}, \theta \right) \right) \right] \]

and for the motion interior to the fluid sphere

\[ \psi^i(r, \theta) = (1 - \lambda) \left[ \frac{3(a^2 - r^2)}{2a^2} \psi_0(r, \theta) + \frac{r(r^2 - a^2)}{a^2} \frac{\partial}{\partial r} \psi_0(r, \theta) \right. \]
\[ \left. - \frac{(r^2 - a^2)^2}{4a^2} D^2 \psi_0(r, \theta) \right], \]

where \( \psi(r, \theta) \) satisfies \( D^4 \psi = 0 \) with

\[ D^2 = \frac{\partial^2}{\partial r^2} + \frac{\sin \theta}{r^2} \frac{\partial}{\partial \theta} \frac{1}{\sin \theta} \frac{\partial}{\partial \theta}. \]
4. Deductions

**Rigid sphere** Setting $\lambda = 1$ in (15) and (16) and noting that $A^i = B^i = 0$ we obtain the theorem for non-axisymmetric Stokes flow past a rigid sphere [13]. Similarly, by setting $\lambda = 1$ in (21) we recover Collins’ [2] sphere theorem for axisymmetric flow.

**Shear-free sphere** Setting $\lambda = a$ in (15) and (16) we get the theorem for non-axisymmetric Stokes flow past a shear-free sphere [12], and setting $\lambda = 0$ in (21) we obtain Harper’s theorem [7].

5. Drag on the fluid sphere

The expression for the drag on the fluid sphere is [8]

$$F = 2\pi \mu^e a (2 + \lambda) [V_0]_0 + \pi \mu^e a^3 \lambda [\nabla^2 V_0]_0,$$

(23)

where $V_0$ is the velocity due to the undisturbed flow and the subscript $o$ indicates evaluation of the quantities inside the square brackets at the centre of the sphere. The equation (23) can be written as

$$F = (1 - \lambda) F_{SF} + \lambda F_R,$$

(24)

where

$$F_{SF} = 4\pi \mu^e a [V_0]_0, \quad F_R = 6\pi \mu^e a [V_0]_0 + \pi \mu^e a^3 [\nabla^2 V_0]_0$$

are the forces on the shear-free and rigid spheres respectively. When $\lambda = 1$, we get the force acting on a rigid spherical particle placed in an arbitrary Stokes flow (Faxen’s law) and when $\lambda = 0$, we recover the force acting on a shear-free sphere. Note that the torque on the fluid sphere is zero. This is due to the continuity of tangential stresses across the surface of the liquid drop.

6. Examples

6.1. Stokeslet outside the liquid sphere, perpendicular to the radius vector:
Consider a Stokeslet exerting a force $(F_1, 0, 0)$ at the point $(0, 0, c)$, $c > a$. The corresponding expressions for $A_0$ and $B_0$ due to this Stokeslet in an unbounded fluid are [13]
where \( R_1^2 = r^2 - 2rc \cos \theta + c^2 \).

Applying the theorem we obtain the exterior and interior flow fields as

\[
A_0(r, \theta, \phi) = \frac{F_1}{8\pi \mu} \left[ \left( \frac{(r \cos \theta - c)}{c} R_1 + \frac{R_1^2}{c} \right) \frac{\cos \phi}{r \sin \theta} \right], \quad (25)
\]

\[
B_0(r, \theta, \phi) = \frac{F_1}{4\pi \mu} \left( R_1 + r \cos \theta - c \right) \frac{\sin \phi}{r c \sin \theta}, \quad (26)
\]

\[
A^e(r, \theta, \phi) = \frac{F_1}{8\pi \mu} \left[ \left( \frac{(r \cos \theta - c)}{c} R_1 + \frac{R_1^2}{c} \right) \frac{\cos \phi}{r \sin \theta} \right]
+ \lambda \left\{ - \frac{(r^2 + a^2)c \cos \phi}{2a^3 r \sin \theta} \left( R_2^2 - \left( \frac{a^2}{c} \cos \theta \right) R_2 \right) \right\}
+ \lambda \left\{ \frac{(r^2 - a^2) \cos \phi}{a^3 r \sin \theta} \times \left( \frac{c}{r} \left( \frac{r^2 - a^4}{c^2} \right) - \frac{a^2}{r} R_2 \cos \theta - \frac{c(\frac{a^2}{c} \cos \theta)^2}{R_2} \right) \right\}
+ \lambda \left\{ \frac{(r^2 - a^2)^2 \cos \phi}{2ac R_2 r \sin \theta} \left( r - \frac{a^2}{c} \cos \theta - R_2 \right) \right\}
+ (1 - \lambda) \left\{ \frac{c \cos \phi}{a^3 \sin \theta} \left( \left( \frac{a^2}{c} \cos \theta \right) R_2 - R_2^2 \right) \right\}], \quad (27)
\]

\[
B^e(r, \theta, \phi) = \frac{F_1}{4\pi \mu} \left( R_1 + r \cos \theta - c \right) \frac{\sin \phi}{r c \sin \theta}
+ \lambda \left\{ - \frac{\sin \phi}{ar \sin \theta} \left( R_2 + \frac{a^2}{c} \cos \theta - r \right) \right\}
+ (1 - \lambda) \left\{ \frac{\sin \phi}{ar \sin \theta} \left( R_2 + \frac{a^2}{c} \cos \theta - r \right)
- \frac{3r \sin \phi}{a^3 c \sin \theta} \left( \frac{l}{2} + \frac{a^2}{r} \left[ \frac{a^2}{2r} \cos \theta - c \right] \right) \right\}
+ 3(1 - \lambda) \frac{r \sin \phi}{a^3 c \sin \theta} \left\{ \left( \frac{l}{2} + \frac{a^2}{r} \left[ \frac{a^2}{2r} \cos \theta - c \right] \right) \right\}
- (1 - 2\lambda) \frac{a^{6\lambda}}{r^{1-3\lambda}} \left[ \frac{a^2 \cos \theta}{r(2 - 3\lambda)} - \frac{c}{(1 - 3\lambda)} \right] \right\}] \right\}, \quad (28)
\]
where

\[ I = \left( \frac{a^2}{c} - r \cos \theta \right) \frac{c^2}{r^2} R_2 + c^2 \cos \theta \]

\[ + c^2 \sin^2 \theta \left[ \log \left( \frac{a^2}{r} - c \cos \theta + \frac{c}{r} R_2 \right) - \log c(1 - \cos \theta) \right], \quad (29) \]

\[ R_2^2 = r^2 - 2 \frac{a^2}{c} r \cos \theta + \frac{a^4}{c^2}, \quad (30) \]

\[ A^i(r, \theta, \phi) = \frac{F_1}{8 \Pi \mu} (1 - \lambda) \left( \frac{1}{\sin \theta} \right) \left[ \left( \frac{a^2 - r^2}{2a^2 r} \right) \left( \frac{r \cos \theta - c}{c} \right) R_1 + \frac{R_i^2}{c} \right] \cos \phi \]

\[ + \frac{r(r^2 - a^2)}{a^2} \frac{\partial}{\partial r} \left( \frac{r \cos \theta - c}{r c} \right) R_1 + \frac{R_i^2}{rc} \right) \cos \phi \]

\[ - \frac{(r^2 - a^2)^2}{4a^2} \nabla^2 \left( \frac{r \cos \theta - c}{r c} \right) R_1 + \frac{R_i^2}{rc} \right) \cos \phi \right], \quad (31) \]

\[ B^i(r, \theta, \phi) = \frac{F_1}{4 \Pi \mu} (1 - \lambda) \frac{\sin \phi}{c \sin \theta} \left[ \frac{2}{r} (R_1 + r \cos \theta - c) \right. \]

\[ - 3(1 - 2\lambda) r^{3\lambda - 2} \left( \int_0^r R^{-3\lambda} (R^2 - 2cR \cos \theta + c^2)^{1/2} dR \right. \]

\[ + r^{1 - 3\lambda} \left[ \frac{r \cos \theta}{2 - 3\lambda} - \frac{c}{1 - 3\lambda} \right] \right] \). \quad (32) \]

This problem was also discussed by Fuentes [4] by making use of Lamb’s solutions. However the above analysis is simpler and the solution is in a closed form. For this reason, the method proposed in Section 3 is more efficient. The corresponding axisymmetric case was also discussed by Fuentes [3]. It may be noted that these results can be easily obtained by using (21) and (22). The drag on the fluid sphere may be calculated as explained in [13] and is given by

\[ \mathbf{F} = \frac{F_1}{4} \left( \lambda \left( \frac{3a}{c} + \frac{a^3}{c^3} \right) + (1 - \lambda) \frac{2a}{c} \right) \hat{i}. \quad (33) \]

When \( \lambda = 1 \) in (33) we recover the expression for drag in the case of a rigid sphere. This agrees with the result of Higdon [9] who has used Oseen’s [11] image solution to model the motion of micro-organisms by flagellar propulsion.

6.2. Rotlet at \((0, 0, c), c > a\): Consider a rotlet of strength \((0, F_2, 0)\) located at \((0, 0, c)\). The corresponding expressions for \(A_0\) and \(B_0\) in an unbounded fluid
are

\[
A_0(r, \theta, \phi) = \frac{F_2}{8\pi\mu} \left[ -R_1 + c - r \cos \theta \right] \frac{\cos \phi}{r c \sin \theta}, \tag{34}
\]

\[
B_0(r, \theta, \phi) = \frac{F_2}{8\pi\mu} \left( \frac{c - r \cos \theta}{R_1} - 1 \right) \frac{\sin \phi}{r c \sin \theta}. \tag{35}
\]

From the theorem

\[
A^e(r, \theta, \phi) = \frac{F_2}{8\pi\mu} \left\{ \left[ -R_1 + c - r \cos \theta \right] \frac{\cos \phi}{r c \sin \theta} + (1 - \lambda) \left[ c R_2 - r c + a^2 \cos \theta \right] \frac{r \cos \phi}{c a^3 \sin \theta} \right. \\
\left. + \lambda \left( \frac{r^2 + a^2}{2r} \left[ c R_2 - r c + a^2 \cos \theta \right] - (r^2 - a^2) \frac{\partial}{\partial r} \left[ c R_2 - r c + a^2 \cos \theta \right] \right) \frac{\cos \phi}{c a^3 \sin \theta} \right\}, \tag{36}
\]

\[
B^e(r, \theta, \phi) = \frac{F_2}{8\pi\mu} \left[ \left( \frac{c - r \cos \theta}{R_1} - 1 \right) \frac{\sin \phi}{r c \sin \theta} - \lambda \left( \frac{r - a^2 c \cos \theta}{R_2} - 1 \right) \frac{\sin \phi}{a c \sin \theta} \right. \\
\left. + (1 - \lambda) \left( \frac{r - a^2 c \cos \theta}{R_2} + 2 - \frac{3r}{2a^2 c} \frac{\partial l}{\partial c} \right) \sin \phi \frac{\sin \phi}{a c \sin \theta} \right. \\
\left. + 3(1 - \lambda) \left( \frac{r}{2a^2 c} \frac{\partial l}{\partial c} - \frac{1}{c} \right) \sin \phi \frac{\sin \phi}{a \sin \theta} \right. \\
\left. - 3(1 - \lambda) (1 - 2\lambda) \frac{a^6 \lambda - 3}{\lambda^{3\lambda - 1}} \right. \\
\left. \times \left\{ \int_0^{a^2/r} \left[ \frac{(c - R \cos \theta)}{(R^2 - 2c R \cos \theta + c^2)^{1/2}} - 1 \right] R^{-3\lambda} \frac{dR}{c \sin \theta} \right\}, \tag{37}
\]

\[
A'(r, \theta, \phi) = \frac{F_2}{8\pi\mu} \left[ (1 - \lambda) \left\{ \left( \frac{a^2 - r^2}{2a^2 r} \right) [-R_1 + c - r \cos \theta] + \frac{r(r^2 - a^2)}{2a^2 r} \frac{\partial}{\partial r} \left( \frac{-R_1 + c - r \cos \theta}{r} \right) \right\} \cos \phi \frac{\sin \phi}{c \sin \theta}, \tag{38}
\]
A theorem for a fluid sphere in Stokes flow

\[ B^i(r, \theta, \phi) = \frac{F_2}{8\pi \mu} (1 - \lambda) \frac{\sin \phi}{c \sin \theta} \left\{ 2 \left( \frac{(c - r \cos \theta)}{r R_1} - 1 \right) - 3(1 - 2\lambda)r^{3\lambda - 2} \right\} x \int_0^r R^{-3\lambda} \left[ \frac{(c - r \cos \theta)}{(R^2 - 2cR \cos \theta + c^2)^{1/2}} - 1 \right] dR \right\}. \]  \tag{39}

The drag on the fluid sphere is found to be

\[ \mathbf{F} = \left( \frac{3}{4} \lambda + \frac{(1 - \lambda)}{2} \right) F_2 \frac{a}{c^2} \hat{\mathbf{i}}. \]  \tag{40}

To the best of the authors' knowledge, this result was not available in literature.

6.3. Potential doublet at (0, 0, c), c > a: Consider a potential-doublet of strength \((S_1, 0, 0)\) located at \((0, 0, c)\). The corresponding expressions for \(A_0\) and \(B_0\) are

\[ A_0 = \frac{S_1}{6\pi \mu} \left( \frac{c - r \cos \theta}{R_1} - 1 \right) \frac{\cos \phi}{r c \sin \theta}, \]  \tag{41}

\[ B_0 = 0. \]  \tag{42}

Applying the theorem we obtain

\[ A^i = \frac{S_1}{6\pi \mu} \frac{\cos \phi}{r c \sin \theta} \left\{ \frac{(c - r \cos \theta)}{R_1} - 1 \right\} - (1 - \lambda) \frac{r^3}{a^2} \left( \frac{r - \frac{a^2}{c} \cos \theta}{R_2} - 1 \right) \right\} \right\} \]  \tag{43}

\[ A^i = \frac{S_1}{6\pi \mu} (1 - \lambda) \frac{\cos \phi}{r c \sin \theta} \left\{ \frac{(a^2 - r^2)}{2a^2} \left( \frac{c - r \cos \theta}{R_1} - 1 \right) + \frac{r^2(r^2 - a^2)}{a^2} \frac{\partial}{\partial r} \left( \frac{c - r \cos \theta}{r R_1} - 1 \right) \right\}. \]  \tag{44}

The drag in this case is

\[ \mathbf{F} = -(3\lambda + 2(1 - \lambda))S_1 \frac{a}{3c^3} \hat{\mathbf{i}}. \]  \tag{45}

The authors believe that this is a new result.
6.4. Stokes-doublet at \((0, 0, c)\): The expressions for \(A_0\) and \(B_0\) for a Stokes-doublet of strength \(M\) in an unbounded fluid are (refer to (31) and (32) of [13])

\[
A_0(r, \theta, \phi) = \frac{M}{16\Pi\mu} \left[ \frac{2(r - c\cos\theta)}{rc^2 \sin^2 \theta} R_1 - \frac{r(r - c\cos\theta)}{c^2 R_1} \right. \\
\left. + \frac{2}{rc \sin^2 \theta} (r - c\cos\theta + r\cos^2 \theta) \right] \sin 2\phi,
\]

(46)

\[
B_0(r, \theta, \phi) = \frac{M}{8\Pi\mu} \left\{ \left[ \frac{-2\cos\theta}{rc^2 \sin^2 \theta} R_1 + \frac{1}{c R_1} - \frac{2\cos\theta}{rc \sin^2 \theta} \right] \cos 2\phi - \frac{1}{c R_1} \right\}.
\]

(47)

The exterior and interior flow fields can be obtained by applying the theorem (Section 3). It is found that the drag on the fluid sphere in this case is zero.

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References

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